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# LIMIT PROBLEMS IN OPTIMAL CONTROL THEORY

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## 1. INTRODUCTION

In this paper we deal with sequences of optimal control problems of the form

$$(P_h) \quad \min \left\{ \int_0^1 f_h(t, y, u) dt : y' = g_h(t, y, u), y(0) = y_h^0 \right\}$$

where the state variable  $y$  belong to the Sobolev space  $W^{1,1}(0,1; \mathbf{R}^n)$  and the control variable  $u$  is in  $L^1(0,1; \mathbf{R}^m)$ . We are interested in the asymptotic behaviour (as  $h \rightarrow +\infty$ ) of the optimal pairs  $(u_h, y_h)$  of  $(P_h)$ ; more precisely, we shall construct a new problem  $(P_\infty)$  such that

*if  $(u_h, y_h)$  is an optimal pair of  $(P_h)$  and if  $(u_h, y_h)$  tends to  $(u_\infty, y_\infty)$  in the topology  $wL^1(0,1; \mathbf{R}^m) \times L^\infty(0,1; \mathbf{R}^n)$ , then  $(u_\infty, y_\infty)$  is an optimal pair for  $(P_\infty)$ .*

The basic tool for treating the asymptotic problem above is the  $\Gamma$ -convergence theory which has been already used very fruitfully for many variational problems (see for instance [1],[2],[4],[5],[8],[9])

Here we use a more sophisticated version of the usual  $\Gamma$ -limits, because we shall consider our problems  $(P_h)$  as minimization problems on the product space  $U \times Y$  ( $U$  is the space of controls and  $Y$  the space of states) for the functionals

$$F_h(u, y) = \begin{cases} \int_0^1 f_h(t, y, u) dt & \text{if } y' = g_h(t, y, u), y(0) = y_h^0 \\ +\infty & \text{otherwise,} \end{cases}$$

and the spaces  $U$  and  $Y$  will play a different role with respect to  $\Gamma$ -convergence.

In Section 2 we develop the abstract theory we shall need in the following; in Section 3 we show the applications to problems  $(P_h)$  above, and we give an example showing that in some situations the domain of problem  $(P_\infty)$  is not given by a state equation  $y' = g_\infty(t, y, u)$  but coincides with the entire product space  $U \times Y$ .

## 2. THE ABSTRACT FRAMEWORK

Let us denote by  $U$  and  $Y$  two topological spaces and let  $F_h: U \times Y \rightarrow \overline{\mathbf{R}}$  be a sequence of functions; by  $Z(+)$  we shall denote the "sup" operator and by  $Z(-)$  the "inf" operator. For every  $u \in U$  and  $y \in Y$  we define

$$\Gamma_{\text{seq}}(N^\alpha, U^\beta, Y^\gamma) \lim_h F_h(u, y) = \begin{matrix} Z(\beta) & Z(\gamma) & Z(-\alpha) & Z(\alpha) \\ (u_h) \in S(u) & (y_h) \in S(y) & k \in N & h \geq k \end{matrix} F_h(u_h, y_h)$$

where  $\alpha, \beta, \gamma$  are the signs  $+$  or  $-$ , and  $S(u)$  and  $S(y)$  respectively denote the set of all sequences  $u_h \rightarrow u$  in  $U$  and  $y_h \rightarrow y$  in  $Y$ . For example we have

$$\Gamma_{\text{seq}}(N^+, U^-, Y^+) \lim_h F_h(u, y) = \inf_{u_h \rightarrow u} \sup_{y_h \rightarrow y} \limsup_{h \rightarrow \infty} F_h(u_h, y_h).$$

When a  $\Gamma$ -limit is independent of the sign  $+$  or  $-$  associated to one of the spaces  $N, U, Y$  this sign will be omitted. For example, if

$$\Gamma_{\text{seq}}(N^+, U^-, Y^+) \lim_h F_h(u, y) = \Gamma_{\text{seq}}(N^+, U^+, Y^+) \lim_h F_h(u, y),$$

then their common value will be indicated by  $\Gamma_{\text{seq}}(N^+, U, Y^+) \lim_h F_h(u, y)$ .

The following propositions are proved in [4].

**PROPOSITION 2.1.** *Let  $(u_h, y_h)$  be a minimum point for  $F_h$ , or simply a pair such that*

$$\lim_h F_h(u_h, y_h) = \lim_h \left[ \inf_{U \times Y} F_h \right].$$

*Assume that  $(u_h, y_h)$  converges to  $(u_\infty, y_\infty)$  in  $U \times Y$  and that there exist*

$$F_\infty = \Gamma_{\text{seq}}(N, U^-, Y^-) \lim_h F_h.$$

*Then we have*

- (i)  $(u_\infty, y_\infty)$  is a minimum point for  $F_\infty$  on  $U \times Y$ ;
- (ii)  $\lim_h \left[ \inf_{U \times Y} F_h \right] = \min_{U \times Y} F_\infty$ .

**PROPOSITION 2.2.** *Let  $\{F_h\}$  and  $\{G_h\}$  be two sequences of function from  $U \times Y$  into  $[0, +\infty]$ , and let  $(u, y) \in U \times Y$ . Assume there exist*

$$\Gamma_{\text{seq}}(N, U^-, Y) \lim_h F_h(u, y) \quad \text{and} \quad \Gamma_{\text{seq}}(N, U, Y^-) \lim_h G_h(u, y).$$

*Then we have*

$$\Gamma_{\text{seq}}(N, U^-, Y^-) \lim_h [F_h + G_h](u, y) = \Gamma_{\text{seq}}(N, U^-, Y) \lim_h F_h(u, y) + \Gamma_{\text{seq}}(N, U, Y^-) \lim_h G_h(u, y).$$

In many applications, the introduction of a new auxiliary variable can be helpful; the following proposition shows the behaviour of  $\Gamma$ -limits with respect to this operation.

**PROPOSITION 2.3.** *Let  $F_h: U \times Y \rightarrow \overline{\mathbb{R}}$  be a sequence of functions, let  $V$  be another topological space, and let  $\Xi_h: U \times Y \rightarrow \wp(V)$  be a sequence of multimappings. Assume that the following compactness condition is satisfied:*

*for every converging sequence  $(u_h, y_h)$  with  $F_h(u_h, y_h)$  bounded, there exist a sequence  $v_h \in \Xi_h(u_h, y_h)$  relatively compact in  $V$ .*

*Then setting*

$$\Phi_h(u,v,y) = \begin{cases} F_h(u,y) & \text{if } v \in \Xi_h(u,y) \\ +\infty & \text{otherwise,} \end{cases}$$

we have for every  $(u,y) \in U \times Y$

$$\begin{aligned} & \inf \left\{ \Gamma_{\text{seq}}(N^-, (U \times V)^-, Y^-) \lim_h \Phi_h(u,v,y) : v \in V \right\} \leq \\ & \leq \Gamma_{\text{seq}}(N^-, U^-, Y^-) \lim_h F_h(u,y) \leq \Gamma_{\text{seq}}(N^+, U^-, Y^-) \lim_h F_h(u,y) \leq \\ & \leq \inf \left\{ \Gamma_{\text{seq}}(N^+, (U \times V)^-, Y^-) \lim_h \Phi_h(u,v,y) : v \in V \right\}. \end{aligned}$$

Therefore, if for every  $(u,v,y) \in U \times V \times Y$  there exists

$$\Gamma_{\text{seq}}(N, (U \times V)^-, Y^-) \lim_h \Phi_h(u,v,y),$$

we have

$$\Gamma_{\text{seq}}(N, U^-, Y^-) \lim_h F_h(u,y) = \inf \left\{ \Gamma_{\text{seq}}(N, (U \times V)^-, Y^-) \lim_h \Phi_h(u,v,y) : v \in V \right\}.$$

**Proof.** It is enough to repeat, with just some slight modifications, the proof of Proposition 2.4 of [3]. ■

In the following, if  $A$  is a set we denote by  $\chi_A$  the function

$$\chi_A(x) = \begin{cases} 0 & \text{if } x \in A \\ +\infty & \text{otherwise.} \end{cases}$$

### 3. APPLICATIONS TO CONTROL PROBLEMS

Let  $k, m, n$  be positive integers and let  $p > 1$ . The space  $Y$  of states we consider is the Sobolev space  $W^{1,1}(0,1; \mathbb{R}^n)$  endowed with the  $L^\infty(0,1; \mathbb{R}^n)$  topology, and the space  $U$  of

controls is the space  $L^p(0,1;\mathbb{R}^n)$  endowed with its weak topology (weak\* if  $p=+\infty$ ). The cost functions are of the form

$$(3.1) \quad J_h(u,y) = \int_0^1 f_h(t,y,u) dt$$

where  $f_h:[0,1]\times\mathbb{R}^n\times\mathbb{R}^m\rightarrow[0,+\infty]$  are Borel functions. Finally, the state equations are

$$(3.2) \quad \begin{cases} y' \in a_h(t,y) + B_h(t,y) b_h(t,u) \\ y(0)=y_h^0 \end{cases}$$

where  $a_h:[0,1]\times\mathbb{R}^n\rightarrow\mathbb{R}^n$  and  $B_h:[0,1]\times\mathbb{R}^n\rightarrow\mathbb{R}^{nk}$  are Borel functions, and the multimappings  $b_h:[0,1]\times\mathbb{R}^m\rightarrow\varphi(\mathbb{R}^{nk})$  are Borel measurable (i.e. the sets  $\{(t,u,v)\in[0,1]\times\mathbb{R}^n\times\mathbb{R}^k : v\in b_h(t,u)\}$  are Borel sets).

Then the control problems we are concerned are

$$(P_h) \quad \inf \{ J_h(u,y) : (u,y)\in\Lambda_h \}$$

or equivalently

$$(P_h) \quad \inf \{ F_h(u,y) : (u,y)\in U\times Y \}$$

where

$$(3.3) \quad \Lambda_h = \{ (u,y)\in U\times Y : y' \in a_h(t,y) + B_h(t,y) b_h(t,u), y(0)=y_h^0 \}$$

$$(3.4) \quad F_h = J_h + \chi_{\Lambda_h}.$$

We introduce now an auxiliary variable  $v\in L^q(0,1;\mathbb{R}^k)$  with  $q>1$  and define a new sequence of functionals by setting

$$(3.5) \quad \Phi_h(u,v,y) = \begin{cases} F_h(u,y) & \text{if } v\in b_h(t,u) \\ +\infty & \text{otherwise.} \end{cases}$$

In this way the problems  $(P_h)$  take the form

$$\inf \left\{ \int_0^1 [f_h(t,y,u) + \chi_{\{v\in b_h(t,u)\}}] dt : y'=a_h(t,y) + B_h(t,y)v, y(0)=y_h^0 \right\}.$$

In order to apply the abstract theory presented in Section 2 (more precisely Proposition 2.1), we have to calculate the  $\Gamma_{\text{seq}}(N,U^-,Y^-)$  limit of the sequence  $F_h$ . To do this, we make

some hypotheses on  $f_h, a_h, B_h, b_h$ .

(3.6) For every  $t \in [0,1], r \geq 0, y \in \mathbb{R}^n$  with  $|y| \leq r$  we have (if  $1/q + 1/q' = 1$ )

$$\begin{aligned} |a_h(t,y)| \leq M_h(t,r) & \quad \text{with} \quad \|M_h(\cdot,r)\|_{L^1(0,1)} \leq M(r) < +\infty \\ |B_h(t,y)| \leq N_h(t,r) & \quad \text{with} \quad \|N_h(\cdot,r)\|_{L^{q'}(0,1)} \leq N(r) < +\infty . \end{aligned}$$

(3.7) For every  $t \in [0,1], r \geq 0, y_1, y_2 \in \mathbb{R}^n$  with  $|y_1|, |y_2| \leq r$  we have

$$\begin{aligned} |a_h(t,y_1) - a_h(t,y_2)| \leq \alpha_h(t,r) |y_1 - y_2| & \quad \text{with} \quad \|\alpha_h(\cdot,r)\|_{L^1(0,1)} \leq \alpha(r) < +\infty \\ |B_h(t,y_1) - B_h(t,y_2)| \leq \beta_h(t,r) |y_1 - y_2| & \quad \text{with} \quad \|\beta_h(\cdot,r)\|_{L^{q'}(0,1)} \leq \beta(r) < +\infty . \end{aligned}$$

(3.8) There exist  $\lambda > 0$  and  $a \in L^1(0,1)$  such that

$$\lambda(|u|^p + |v|^q) - a(t) \leq f_h(t,0,u) + \chi_{\{v \in b_h(t,u)\}}$$

for every  $t \in [0,1], u \in \mathbb{R}^m, v \in \mathbb{R}^k$ . When  $p = +\infty$  or  $q = +\infty$  the quantities  $|u|^p$  and  $|v|^q$  in the left-hand side have to be substituted by  $\chi_{\{u \in H\}}$  and  $\chi_{\{v \in K\}}$  respectively, where  $H \subset \mathbb{R}^m$  and  $K \subset \mathbb{R}^k$  are bounded sets.

(3.9) For every  $t \in [0,1], r \geq 0, u \in \mathbb{R}^m, y_1, y_2 \in \mathbb{R}^n$  with  $|y_1|, |y_2| \leq r$  we have

$$f_h(t, y_1, u) \leq f_h(t, y_2, u) + \rho_r(t, |y_1 - y_2|) + \sigma_r(t, |y_1 - y_2|) |f_h(t, y_2, u)|^{(\alpha-1)/\alpha}$$

for a suitable  $\alpha \in [1, +\infty[$  and functions  $\rho_r(t, s), \sigma_r(t, s)$  from  $[0,1] \times [0, +\infty[$  into  $[0, +\infty[$  measurable in  $t$ , increasing and continuous in  $s$ , with  $\rho_r(t, 0) = \sigma_r(t, 0) = 0$ , and such that  $z \rightarrow \rho_r(t, |z(t)|), z \rightarrow \sigma_r(t, |z(t)|)$  are continuous operators from  $Y$  into  $L^1(0,1), L^\alpha(0,1)$  respectively.

(3.10) There exist  $u_h \in L^p(0,1; \mathbb{R}^m)$  and  $v_h \in L^q(0,1; \mathbb{R}^k)$  such that  $v_h(t) \in b_h(t, u_h(t))$  for a.e.  $t \in (0,1)$ , and the sequence  $f_h(t, 0, u_h(t))$  is weakly compact in  $L^1(0,1)$ .

**LEMMA 3.1.** *Under the previous assumptions, the following compactness condition is satisfied: for every converging sequence  $(u_h, y_h)$  with  $F_h(u_h, y_h)$  bounded, there exists a sequence  $\{v_h\}$  relatively compact in  $V$  such that for a.e.  $t \in [0,1]$*

$$v_h(t) \in b_h(t, u_h(t)) \quad \text{and} \quad y_h'(t) = a_h(t, y_h(t)) + B_h(t, y_h(t)) v_h(t) .$$

**Proof.** Let  $(u_h, y_h)$  be converging in  $U \times Y$  with  $F_h(u_h, y_h)$  bounded; then we have  $(u_h, y_h) \in \Lambda_h$ , so that we can find measurable functions  $v_h(t)$  with

$$v_h(t) \in b_h(t, u_h(t)) \quad \text{and} \quad y'_h(t) = a_h(t, y_h(t)) + B_h(t, y_h(t)) v_h(t)$$

for a.e.  $t \in [0, 1]$ . It remains to prove that the sequence  $v_h$  is bounded in  $L^q(0, 1; \mathbb{R}^k)$ . Since  $y_h$  is uniformly bounded, by (3.8) and (3.9) we have for a suitable  $r > 0$

$$\begin{aligned} \lambda(|u_h|^p + |v_h|^q) - a(t) &\leq f_h(t, 0, u_h) \leq \\ &\leq f_h(t, y_h, u_h) + \rho_r(t, r) + \sigma_r(t, r) |f_h(t, y_h, u_h)|^{(\alpha-1)/\alpha} \leq \\ &\leq c f_h(t, y_h, u_h) + \gamma(t) \end{aligned}$$

where  $c > 0$  is a constant and  $\gamma \in L^1(0, 1)$ . Then, from the boundedness of  $J_h(u_h, y_h)$  we get that  $v_h$  is bounded in  $L^q(0, 1; \mathbb{R}^k)$ . ■

By Lemma 3.1, Proposition 2.3 applies, so that we have reduced our problem to the characterization of the  $\Gamma_{\text{seq}}(\mathbb{N}, (U \times Y)^-, Y^-)$  limit of the sequence  $\Phi_h(u, v, y)$  defined in (3.5). Set now

$$\begin{aligned} \bar{f}_h(t, y, u, v) &= f_h(t, y, u) + \chi_{\{v \in b_h(t, u)\}} \\ \bar{J}_h(u, v, y) &= \int_0^1 \bar{f}_h(t, y, u, v) dt \\ \bar{\Lambda}_h &= \left\{ (u, v, y) \in U \times V \times Y : y' = a_h(t, y) + B_h(t, y) v \text{ a.e. on } [0, 1], y(0) = y_h^0 \right\}. \end{aligned}$$

Therefore

$$\Phi_h = \bar{J}_h + \chi_{\bar{\Lambda}_h}^-$$

and, by Proposition 2.2 we may split the  $\Gamma_{\text{seq}}(\mathbb{N}, (U \times Y)^-, Y^-)$  limit of  $\Phi_h$  into the sum

$$(3.11) \quad \Gamma_{\text{seq}}(\mathbb{N}, (U \times V)^-, Y) \lim_h \bar{J}_h + \Gamma_{\text{seq}}(\mathbb{N}, U \times V, Y^-) \lim_h \chi_{\bar{\Lambda}_h}^-.$$

The two terms in the sum above can be computed by using Lemma 3.1 and Theorem 3.4 of [4].

More precisely we have



**PROPOSITION 3.2.** Assume that (3.8),(3.9),(3.10) hold and that for every  $y \in \mathbb{R}^n, \xi \in \mathbb{R}^n, \eta \in \mathbb{R}^k$

$$(3.12) \quad \bar{F}_h^*(\cdot, y, \xi, \eta) \rightarrow \varphi(\cdot, y, \xi, \eta) \quad \text{weakly in } L^1(0,1)$$

where  $\bar{F}_h^*$  are the polar functions of  $\bar{F}_h$  defined by

$$\bar{F}_h^*(t, y, \xi, \eta) = \sup \{ \xi u + \eta v - \bar{F}_h(t, y, u, v) : u \in \mathbb{R}^m, v \in \mathbb{R}^k \} .$$

Then, for every  $(u, v, y) \in U \times V \times Y$  we have

$$\Gamma_{\text{seq}}(N, (U \times V)^-, Y) \lim_h \bar{J}_h(u, v, y) = \int_0^1 \varphi^*(t, y, u, v) dt$$

where  $\varphi^*$  is the polar function of  $\varphi$ .

**PROPOSITION 3.3.** Assume that (3.6),(3.7) hold and that

$$(3.13) \quad \text{for every } y \in \mathbb{R}^n \quad a_h(\cdot, y) \rightarrow a(\cdot, y) \quad \text{weakly in } L^1(0,1; \mathbb{R}^n);$$

$$(3.14) \quad \text{for every } y \in \mathbb{R}^n \quad B_h(\cdot, y) \rightarrow B(\cdot, y) \quad \text{strongly in } L^1(0,1; \mathbb{R}^{nk});$$

$$(3.15) \quad y_h^0 \rightarrow y^0 \quad \text{in } \mathbb{R}^n .$$

Then we have

$$\Gamma_{\text{seq}}(N, U \times V, Y^-) \lim_h \chi_{\Lambda_h^-} = \chi_{\Lambda^-}$$

where

$$\Lambda^- = \{ (u, v, y) \in U \times V \times Y : y' = a(t, y) + B(t, y) v, y(0) = y^0 \} .$$

Finally, we are in a position to compute the  $\Gamma_{\text{seq}}(N, U^-, Y^-)$  limit of  $F_h$ . In fact, by Propositions 2.3, 3.2, and 3.3, and by (3.11) we get for every  $(u, y) \in U \times Y$

$$\begin{aligned} \Gamma_{\text{seq}}(N, U^-, Y^-) \lim_h F_h(u, y) &= \\ &= \inf \left\{ \int_0^1 \varphi^*(t, y, u, v) dt : y' = a(t, y) + B(t, y) v, y(0) = y^0 \right\} = \end{aligned}$$

$$= \int_0^1 f(t, y, u, y') dt + \chi_{\{y(0)=y^0\}}$$

where the function  $f$  is defined by

$$f(t, y, u, w) = \inf \{j(t, y, u, v) : w = a(t, y) + B(t, y) v\} .$$

We conclude with an example showing that in general the domain of the limit functional

$$F(u, y) = \int_0^1 f(t, y, u, y') dt + \chi_{\{y(0)=y^0\}}$$

is not given by a differential equation of the form  $y'=g(t, y, u)$  but may be the whole space  $U \times Y$ .

**EXAMPLE 3.4.** Consider the sequence of optimal control problems

$$(P_h) \quad \min \left\{ \int_0^1 [u^2 + |y - y_0(t)|^2] dt : y' = a_h(t) y + b_h(t) u, y(0) = \xi \right\}$$

where  $u$  varies in  $U=L^2(0,1)$ ,  $y$  varies in  $Y=W^{1,1}(0,1)$ , and  $y_0 \in L^2(0,1)$ ,  $\xi \in \mathbf{R}$  are given.

About the functions  $a_h$  and  $b_h$  we assume that

$$\begin{cases} a_h \rightarrow a & \text{weakly in } L^1(0,1) \\ b_h \rightarrow b & \text{weakly}^* \text{ in } L^\infty(0,1) \\ b_h^2 \rightarrow \beta^2 & \text{weakly}^* \text{ in } L^\infty(0,1) . \end{cases}$$

It is not difficult to check that all hypotheses (3.6),..., (3.10) and (3.12),..., (3.15) are satisfied, and after some standard calculations we find that the limit problem  $(P_\infty)$  has the form

$$(P_\infty) \quad \min \left\{ \int_0^1 \left[ u^2 + |y - y_0(t)|^2 + \frac{|y' - a(t) y - b(t) u|^2}{\beta^2(t) - b^2(t)} \right] dt : y(0) = \xi \right\} .$$

Note that it is  $\beta^2(t) \geq b^2(t)$  for a.e.  $t \in [0,1]$ , and

$$\beta^2 = b^2 \text{ a.e. on } [0,1] \Leftrightarrow b_h \rightarrow b \text{ a.e. on } [0,1] .$$

In this last situation, problem  $(P_\infty)$  takes the usual form

$$(P_\infty) \quad \min \left\{ \int_0^1 [u^2 + |y - y_0(t)|^2] dt : y' = a(t) y + b(t) u, y(0) = \xi \right\} ,$$

but this does not arrive in the general case. Take for instance

$$b_h(t) = \sin(ht)$$

and we get  $b=0$  and  $\beta^2=1/2$ , so that the limit problem is

$$\min \left\{ \int_0^1 [u^2 + |y - y_0(t)|^2 + 2|y' - a(t)y|^2] dt : y(0)=\xi \right\} .$$

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