

Maximal singular integrals

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Abstract. We prove the L_p boundedness of the maximal operators attached to the singular kernels introduced in [1]. These kernels are obtained by multiplying (pointwise) a classical convolution Calderon-Zygmund kernel with the perturbing factor $[a]_{x,y}$ (cf. below). The importance of these perturbations lies in potential theoretic applications (cf. [3, 7]).

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0. Introduction

0.1. Notation and statement of the theorem

In this note I shall examine maximal operators that are related to the singular integrals that were introduced in [1] (cf. also [7]). I shall preserve the notation of [1, 7] and denote $[a]_{x,y} = \int_0^1 a(x + t(y-x))dt$; $x, y \in \mathbb{R}^n$, $a \in C_0^\infty(\mathbb{R}^n)$. I shall also use the abbreviation $F([a]_{x,y}) = F([a_1]_{x,y}, \dots, [a_k]_{x,y})$ for $a_1, \dots, a_k \in C_0^\infty$ and where $F(z_1, \dots, z_k) \in C^N (N \geq 1)$ will denote throughout some sufficiently smooth function of k complex variables. We shall denote throughout by $\Omega \in L^r(\Sigma)$ ($r > 1$) where $\Sigma = \{x \in \mathbb{R}^n; |x| = 1\}$ is the unit sphere and where L^r or L_r denotes throughout the Lebesgue space on the appropriate measure space. The condition $\int \Omega = 0$ will be assumed throughout.

We shall be concerned in this paper with the following kernel and the corresponding principal value operator and the associated maximal function:

$$K(x, y) = \Omega \left(\frac{x-y}{|x-y|} \right) |x-y|^{-n} F([a]_{x,y}); \quad x, y \in \mathbb{R}^n, \quad (0.1)$$

$$f \mapsto K_{\epsilon, M} f(x) = \int_{\epsilon < |x-y| < M} K(x, y) f(y) dy, \quad (0.2)$$

$$K^* f(x) = \sup_{\epsilon, M} \left| K_{\epsilon, M} f(x) \right|; \quad f, a_j \in C_0^\infty, \quad 1 \leq j \leq k. \quad (0.3)$$

In [1] the authors consider kernels that are more general, but also smoother:

$$T(x, y) = L(x - y)F([a]_{x,y}), \tag{0.1}'$$

where L is a classical convolution Calderon-Zygmund kernel (i.e. $\widehat{L} \in L^\infty$, $|L(x)| \leq C|x|^{-n}$, and $|L(x+h) - L(x)| \leq C|h|^\epsilon|x|^{-n-\epsilon}$ for $2|h| \leq |x|$). It is then proved in [1] that the corresponding principal value operator $T_{\epsilon, M}$ is $L_p \rightarrow L_p$ bounded, uniformly in ϵ, M for $1 < p < \infty$, with bounds that only depend on $\|a\|_\infty$ and $\|F\|_{C^N}$ (for some $N \geq 1$). The formulation in [1] is slightly different, but equivalent: In [1] $F(z) = z^p$ ($p = 1, 2, \dots$) but the operator norms are then $O(p^N)$ for some $N > 0$.

The kernel T is not a standard kernel (cf. [1]) and therefore the general theory [6, Chapter I, 7.3] cannot be used to deduce the L^p boundedness of the corresponding maximal operator (defined as in (0.3)).

In the notation I shall preserve the letters c, C , possibly with indices, to indicate positive constants that may differ from place to place but are independent from the main parameters of the formulae.

Theorem 0.1. *Let Ω, F, n, N, r be as above and let $a_1, \dots, a_k \in C_0^\infty$ be such that $\|a_j\|_\infty \leq 1$. For every $1 < p < \infty$ there exists C depending on n, N, r, k, p , but not on the a_j 's, such that*

$$\|K^*f\|_p \leq C \|\Omega\|_r \|F\|_{C^N} \|f\|_p; \quad f \in C_0^\infty(\mathbb{R}^n). \tag{0.4}$$

$\|\cdot\|_p$ indicates throughout the corresponding L_p norm.

The estimate (0.4) with K^* replaced by $K_{\epsilon, M}$ (but uniform in ϵ, M) is in [7, Corollary, Section 1.3] (cf. [1] for the case $\Omega \in C^m$). As I already pointed out in [7] the integrability of Ω can be improved to $\Omega \in L(\log^+ L)^a$ for some $a \geq 1$. It is easy to see that the same $a \geq 1$ that works in [7] also works in the above Theorem. When Ω is odd (0.4) follows by the method of rotation.

The critical first part of the proof of the theorem for $p = 2$ only uses the uniform bound of $\|K_{\epsilon, M}\|_{2 \rightarrow 2}$ and the additional key estimate [7, (1.32)]. For the more general $1 < p < \infty$ some additional notions from [1, 7] will be needed, but none of the technical aspects of these papers. Some of these facts from [7] will be elaborated in the Appendix at the end of the paper. As a result familiarity with [1, 7] although desirable, is not essential for the understanding of the first part of the proof.

The weak L^1 boundedness of all the above operators, even in the smooth case in the setting of [1], remains an open (and interesting) problem.

0.2. Further notation and plan of the proof

We say that a function $A(x, h)$ on $\mathbb{R}_+^{n+1} = (x \in \mathbb{R}^n, h > 0)$ lies in D_p , ($0 < p < \infty$) if the non tangential maximal function A^* and S -function: $S(h \nabla A)(x) = \left(\iint_{\Gamma(x)} |h \nabla A|^2 \frac{dx dh}{h^{n+1}} \right)^{\frac{1}{2}}$ both lie in $L^p(\mathbb{R}^n)$ (Here $\Gamma(x) \subset \mathbb{R}_+^{n+1}$ denotes the conical

wedge with vertex at $x \in \mathbb{R}^n$). These spaces were introduced for the first time in [3]. Cf. [2, 7] for further elaborations and for the case $p = \infty$.

Let now $Q(x, y; h) \in L^1_{\text{loc}}(x, y \in \mathbb{R}^n, h > 0)$ and let us define the bilinear form: (cf. [7, Section 2.5])

$$B(A, f) = \int Q(x, y; h) f(x) A(y, h) \frac{dx dy dh}{h}; \quad A, f \in C_0^\infty. \quad (0.5)$$

A mapping $L : C_0^\infty(\mathbb{R}^{n+1}) \rightarrow \mathcal{D}'(\mathbb{R}^n)$ (= the space of distribution on \mathbb{R}^n) can then be defined by

$$(LA, \varphi) = B(A, \varphi); \quad \varphi \in C_0^\infty(\mathbb{R}^n). \quad (0.6)$$

The kernels Q that we shall consider in this paper (cf. [7, (1.19)]) are of the form:

$$Q(x, y; h) = Q_h(x - y) F(x, y; h) = \Omega \left(\frac{x - y}{|x - y|} \right) \theta_h(|x - y|) F(x, y; h), \quad (0.7)$$

where F is a perturbing factor and where in the convolution kernel $\Omega \in L'$ with $\int \Omega = 0$ is as in the theorem, and $\theta \in C_0^\infty$ with $\text{supp } \theta \subset [1, 2]$.

The standard notation $Q_h(x) = h^{-n} Q\left(\frac{x}{h}\right)$ ($h > 0$) as well as the notation $Q_h f(x) = \int Q_h(x - y) f(y) dy$ ($f \in C_0^\infty$) will also be used. I shall also use a notation that proved very convenient in [7]; this consists in reserving the letter \check{P} for the elements of $C_0^\infty(\mathbb{R}^n)$ and the letter \check{Q} for the elements of C_{00}^∞ , i.e. when in addition $\int \check{Q} = 0$. These \check{P}, \check{Q} differ from place to place. Furthermore in (0.7) we shall set $F = F([a]_{x,y})$ unless otherwise stated. We shall also denote $F_0 = c_0 + \sum_{i=1}^k c_i z_i$ the affine functions. Together with L in (0.6), (0.7) I shall define the maximal operator

$$L^* A(x) = \sup_{\substack{\epsilon, M \\ \epsilon < h < M}} \left| \int Q(x, y; h) A(y, h) \frac{dy dh}{h} \right|; \quad A \in C_0^\infty, \quad (0.8)$$

and the essential step in the proof of the theorem is the following.

Proposition 0.2. *With Q, p, a_j and F as in the theorem we have*

$$\| L^* A \|_p \leq C \| \Omega \|_r \| F \|_{C^N} \| A \|_{D_p}, \quad (0.9)$$

with $C = C(n, p, k, N, r)$.

$\| \cdot \|_{D_p}$ indicates the natural norm in the D_p -spaces. The proof of this proposition is given in Sections 1-3 below and it is the crucial part of the paper.

Modulo classical maximal functions on the other hand (cf. [7, (1.20) (1.21)]) the theorem is equivalent to the $L^p \rightarrow L^p$ boundedness of the operator

$$f \mapsto \sup_{\epsilon, M} \left| \int_{\epsilon < h < M} Q(x, y; h) f(y) \frac{dy dh}{h} \right|; \quad f \in C_0^\infty. \quad (0.10)$$

But for $f \in L^p$ we have $\check{P}_h f(y) \in D_p$, ($1 < p < \infty$, cf. [2, 6]) and Proposition 0.2 applies. For (0.10) it suffices therefore to examine the *correcting* maximal operator where in the integral we replace $f(y)$ by $f(y) - \check{P}_h f(y)$. This is done in the second part of the paper in Section 4-5 and uses a Cotlar analysis and some other ideas from [1]. The estimate of this correcting term follows very closely [7, Section 8-9]. Adapting the arguments of [7], is straightforward indeed for $p = 2$. For the general case $p \neq 2$ I shall go back and elaborate on the arguments of the last subsection of [7, Section 9] because not many details were given there. This second part of the proof will be difficult to read without a reasonable familiarity of [7, Section 8-9]. I should point out however that, although technical, this second part of the proof uses either classical tools, or ideas that have been borrowed from [1].

0.3. The smooth case

If we assume that $\Omega \in C^\alpha$ (some $\alpha > 0$) in (0.1) – this a special case of [1, (0.1)'] – a different, much shorter, proof of the Proposition 0.2 can be given. This proof avoids altogether the difficult estimate [7, (1.32)], but uses instead the vector valued (i.e. valued in ℓ^2) version of the generalized T1 theorem that I developed in [8].

Using that version of the T1 theorem we can prove the critical case of Proposition 0.2 when F is an affine function. More precisely this proof gives Proposition 1.1 for $p = \infty$ (with $L^p(\ell^2)$ interpreted as the ℓ^2 -valued BMO). The other values of p then follow by general considerations ([7, Section 2.5]).

This approach is simpler (because it avoids [7, (1.32)]) but it has the drawback that it needs the smoothness of Ω . I shall not give the details but the motivated reader, I am sure, will be able to adapt [8] to give this alternative proof of (1.6), below, in this special case. The starting point of this proof can be found in the remark at the end of Section 2.1 below.

1. The general strategy for Proposition 0.2

1.1. Notation and the vector valued operator

We shall fix once and for all $R \in C_0^\infty(\mathbb{R}^n)$ in such a way that the Fourier transform satisfies $|\widehat{R}(\xi) - 1| = O(|\xi|^{-a})$ for some large $a \geq 1$. Let us also define the operators

L_k, \tilde{L}_N with $L = L_k + \tilde{L}_{2^k}$ by truncating the definition (0.6):

$$\begin{aligned} (L_k A, f) &= \int_{h>2^k} Q(x, y; h) f(x) A(y, h) \frac{dx dy dh}{h}, \\ (\tilde{L}_N A, f) &= \int_{h<N} Q(x, y; h) f(x) A(y, h) \frac{dx dy dh}{h}; \quad f, A \in C_0^\infty. \end{aligned} \tag{1.1}$$

We shall then compose L, L_k, \tilde{L}_N with the convolution operator R where the notation used is for instance

$$R_{2^k} L(A)(x) = \int 2^{-nk} R\left(\frac{x-y}{2^k}\right) L A(y) dy. \tag{1.2}$$

With this notation and denoting by I the identity operator (*i.e.* convolution with δ) we can write

$$L_k = -R_{2^k} \tilde{L}_{2^k} + (I - R_{2^k}) L_k + R_{2^k} L = M_k^{(1)} + M_k^{(2)} + M_k^{(3)}, \tag{1.3}$$

$$L^{**} = \sup_k |L_k| \leq \sum_{i=1}^3 \sup_k |M_k^{(i)}| = \sum M^{(i)}, \tag{1.4}$$

and the three components of the above decomposition will be examined separately. We have $M^{(3)} \leq ML$ for the Hardy-Littlewood maximal function M . It follows that the $D_p \mapsto L_p$ norm of $M^{(3)}$ ($p > 1$) is dominated by the corresponding norm of L in [7, 8]. $M^{(1)}$ will be analyzed in Section 1.2 below.

To deal with $M^{(2)}$ we shall introduce $\mathcal{L}A(x) \in \ell^2$, ($A \in C_0^\infty(\mathbb{R}_+^{n+1})$, $x \in \mathbb{R}^n$) a vector valued operator defined by

$$\begin{aligned} (\mathcal{L}A, f) &= \sum_{k=-\infty}^{+\infty} ((I - R_{2^k}) L_k A, f_k); \quad f = (\dots f_{-1}, f_0, \dots), \\ f_j &\in C_0^\infty, \quad f_j = 0 \quad \text{for } |j| \text{ large enough.} \end{aligned} \tag{1.5}$$

We shall then prove the

Proposition 1.1. *Let the notation be as above and let Q, a_j be as in Proposition 0.2 and let us assume that in (0.7) $F = F_0 = c_0 + \sum c_j z_j$ is affine. For all $1 < p < \infty$ we then have:*

$$\| \mathcal{L}A \|_{L^p(\ell^2)} \leq C \| \Omega \|_r \| F_0 \| \| A \|_{D_p}; \quad A \in C_0^\infty, \tag{1.6}$$

with $C = C(n, r, k, N, p)$ and

$$\| F_0 \| = \sum |c_j|; \quad \| f \|_{L^p(\ell^2)}^p = \int \left(\sum_{-\infty}^{+\infty} |f_k(x)|^2 \right)^{p/2} dx. \tag{1.7}$$

In the next few lines I shall assume Proposition 1.1 and complete the proof of Proposition 0.2.

1.2. The pointwise estimate for $M^{(1)}$

We shall use the notation and the facts from [7, Section 2.1, 2.2]. We denote by $\tilde{A} = A^* + S(h\nabla A)$ for $A \in C_0^\infty(\mathbb{R}_+^{n+1})$ and we shall decompose $A = A_1 + A_2$ so that

$$\begin{aligned} \text{supp} A_1 \subset [|x| + h \leq C_1], \text{supp} A_2 \subset [|x| + h \geq C_2]; \\ \|A_1\|_{D_1} \leq C \|\tilde{A}\|_{L^1(|x| \leq C_3)} \leq CM\tilde{A}(0), \end{aligned} \tag{1.8}$$

where C_i are appropriate constants and M will denote throughout the Hardy-Littlewood function. We shall use (1.8) to deduce

$$|R\tilde{L}_1 A(0)| \leq CM\tilde{A}(0) + CMM_\Omega A^*(0), \tag{1.9}$$

where (cf. [6, II, Section 4])

$$M_\Omega f(x) = \sup_r r^{-n} \int_{|x-y| \leq r} |f(x-y)\bar{\Omega}(y/|y|)| dy; \bar{\Omega}(\sigma) = |\Omega(\sigma)| + 1, \sigma \in \Sigma. \tag{1.10}$$

Once (1.9) has been proved, by scaling and translation we obtain the pointwise control of $R_N \tilde{L}_N$, ($N \geq 0$) and of $M^{(1)}$ by $M\tilde{A}(x) + MM_\Omega A^*(x)$ as required.

Proof of (1.9). With $C > 0$ and C_2 large enough we have $\tilde{L}_1 A_2(x) = 0$ for $|x| \leq C$, and therefore

$$\tilde{L}_1 A(x) = \tilde{L}_1 A_1(x) = LA_1(x) - L_0 A_1(x); |x| \leq C. \tag{1.11}$$

But by (1.8) and the compactness of the support of $Q(x)$ in (0.7) we have $|L_0 A_1(x)| \leq CM_\Omega A^*(x)$, $|x| \leq C$. From the main Theorem of [7] and (1.8) we have on the other hand

$$\|LA_1\|_1 \leq C \|A_1\|_{D_1} \leq C \|\tilde{A}\|_1 \leq CM\tilde{A}(0). \tag{1.12}$$

These two estimates are inserted in (1.11) and then we convolve with R . (1.9) follows. □

1.3. Proof of Proposition 0.2

Reduction to the discrete parameter

Let Q be as in (0.7) we then have

$$\begin{aligned} \int_{2^k \leq h \leq 2^{k+1}} |Q(x, y; h)A(y, h)| \frac{dydh}{h} \leq CM_\Omega A^*(x); \\ k \in \mathbb{Z}, x \in \mathbb{R}^n, A \in C_0^\infty(\mathbb{R}^{n+1}), \end{aligned} \tag{1.13}$$

with the notation (1.10). This implies that for the Proposition 0.2 it suffices to prove (0.9) with L^* replaced by the L^{**} of (1.4). From the above, and Proposition 1.1, it follows therefore that Proposition 0.2 holds for affine functions $F = F_0$.

Reduction to the affine function

Once the Proposition 0.2 has been proved for an affine function F_0 and $p \geq p_0$ large enough then this proposition holds for all $F \in C^N$ and all $1 < p < \infty$.

The proof of this reduction is not trivial but it follows the same strategy as the reduction in [7, Section 7]. For the convenience of the reader I shall present this reduction in an essentially self contained manner in Section 3 below. A_1 -weights, Carleson measures, and non trivial facts from [5, 7] will be used in that reduction.

2. Proof of Proposition 1.1

2.1. The L^2 -estimates

Here R will be as in Section 1 but Q will be, a priori, an arbitrary $L^1(\mathbb{R}^n)$ function. We shall use furthermore the following notation

$$Q_h^k = (I - R_{2^k}) Q_h \mathbf{I}(h > 2^k),$$

$$B(f, A) = \sum_{k=-\infty}^{+\infty} \int f_k(x) Q_h^k(x - y) A(y, h) \frac{dy dx dh}{h}; \quad A, f \text{ as in (1.5)}, \tag{2.1}$$

where \mathbf{I} denotes the indicator function. We shall recall the notation $\| A \|_{T_2^2}^2 = \int |A(y, h)|^2 \frac{dy dh}{h}$ from [2] and we have:

Lemma 2.1.

$$|B(f, A)| \leq C \| f \|_{L^2(\ell^2)} \| A \|_{D_2}. \tag{2.2}$$

If the Fourier transform satisfies $\widehat{Q}(\xi) = O(|\xi|^{-\delta})$ for some $\delta > 0$ we have:

$$|B(f, A)| \leq C \| f \|_{L^2(\ell^2)} \| A \|_{T_2^2}. \tag{2.3}$$

We shall denote by $\widehat{A}(\xi, h)$ the partial Fourier transform of $A(\cdot, h)$ and denote by $S(\xi) = |1 - \widehat{R}(\xi)|^2$, $T(\xi) = |\xi|^{-1} |\widehat{Q}(\xi)|^2$ and

$$|||Q|||^2 = \sup_{\xi} \sum_k \int \frac{|\widehat{Q}_h^k(\xi)|^2}{h|\xi|} \frac{dh}{h} = \sup_{\xi} \sum_k \int_{h>2^k} S(2^k \xi) T(h\xi) \frac{dh}{h}. \tag{2.4}$$

By Plancherel and Hölder we have then

$$|B(f, A)|^2 \leq \| f \|_{L^2(\ell^2)}^2 \sum_k \int \left(\int |\widehat{Q}_h^k(\xi) \widehat{A}(\xi, h)| \frac{dh}{h} \right)^2 d\xi$$

$$\leq \| f \|_2^2 \int \left(\sum_k \int_0^\infty \frac{|\widehat{Q}_h^k(\xi)|^2}{h|\xi|} \frac{dh}{h} \right) \left(\int h|\xi| |\widehat{A}(\xi, h)|^2 \frac{dh}{h} \right) d\xi, \tag{2.5}$$

(with the notation (1.7)). By partial integration (as in [7, Section 2.9]) on the last factor of the right hand side of (2.5) we see that (2.2) is a consequence of the fact that $|||Q||| < +\infty$. This fact is easy to verify: We shall replace $S(\xi)$ by $|\xi|^a \wedge 1$ for some (arbitrary *cf.* Section 1) $a > 1$ and replace $T(\xi)$ by $|\xi|^{-1}$. After this substitution we shall replace the discrete summation in the definition (2.4) by the continuous integral so that

$$|||Q|||^2 \leq C \sup_{\xi} \iint_{h>\ell} (|\ell\xi|^a \wedge 1) |h\xi|^{-1} \frac{d\ell}{\ell} \frac{dh}{h}. \tag{2.6}$$

This is useful because it makes the scaling $|\xi|h = h'$, $|\xi|\ell = \ell'$ obvious and so, in proving that $|||Q||| < +\infty$, we can just take $|\xi| = 1$. We are thus just left with:

$$\sum_{k<j} (2^{ak} \wedge 1) 2^{-j} \approx \sum_{j\leq 0} 2^{(a-1)j} + \sum_{j\geq 0} j 2^{-j} \leq C. \tag{2.7}$$

We have in fact proved the more precise version of the lemma

$$|B(f, A)| \leq C |||Q||| \|f\|_2 \|A\|_{D_2}. \tag{2.2}'$$

For the estimate (2.3) we shall use Plancherel again and what has to be seen is that for each fixed ξ (but uniformly in ξ) the matrix $(a_k(h) = \widehat{Q}_h^k(\xi); k \in \mathbb{Z}, h > 0)$ defines an $\ell^2 \rightarrow L^2(\frac{dh}{h})$ bounded operator. We have $|a_k(h)| = S(2^k\xi)|\widehat{Q}(h\xi)|\mathbf{I}[2^k < h]$ and by Schur's Lemma this operator norm can be estimated by

$$\sup_k \int_0^\infty |a_k(h)| \frac{dh}{h} + \sup_h \sum_k |a_k(h)|. \tag{2.8}$$

Here we shall proceed as before and replace $S(\xi)$ by $|\xi|^a \wedge 1$ and $|\widehat{Q}(\xi)|$ by $1 \wedge |\xi|^{-\delta}$ and then use the analogue of the continuous time integration for (2.8) as in (2.6). This allows us to scale again and assume that $|\xi| = 1$. In (2.8) we are thus left with

$$\begin{aligned} \sup_k \left(2^{ak} \wedge 1 \right) \sum_{j>k} \left(2^{-\delta j} \wedge 1 \right) &\leq \sup_k \left(2^{ak} \wedge 1 \right) \left(2^{-\delta k} \wedge (|k| + 1) \right), \\ \sup_j \left(2^{-\delta j} \wedge 1 \right) \sum_{k<j} \left(2^{ak} \wedge 1 \right) &\leq \sup_j \left(2^{-\delta j} \wedge 1 \right) \left(2^{aj} \wedge (|j| + 1) \right), \end{aligned} \tag{2.9}$$

and both the above are $< +\infty$.

Remark 2.2.

- (i) If we use the space variable x , the convolution kernel of the above $\ell^2 \mapsto L^2(\frac{dh}{h})$ operator is given by the matrix $b_k(h) = (Q_h(x) - R_{2^k}Q_h(x))\mathbf{I}(h > 2^k)$. For **fixed** x this is a $2 \rightarrow 2$ bounded operator provided that Q is smooth. This is seen by Hardy's inequality and it gives the size estimate for the generalized T1 theorem of Section 0.3. We shall not pursue the matter further but an alternative proof of (2.3) can be given in these lines.

(ii) The condition $O(|\xi|^{-\delta})$ on the Fourier transform is verified for the kernel $Q(x) = \Omega\left(\frac{x}{|x|}\right)\theta(|x|)$ of (0.7) cf. [4], [6, VIII 5.22].

2.2. The scaled kernel

We shall here scale Q and consider $Q_s = s^{-n}Q\left(\frac{x}{s}\right)$ ($0 < s < 1$) and we shall also assume here that $\widehat{Q}(\xi) = O(|\xi|^\delta)$ for some $0 < \delta \leq 10^{-10}$. In terms of the integral (2.6) we can then estimate

$$\begin{aligned} |||Q_s|||^2 &\leq C \iint_{\ell < h} \frac{(\ell^a \wedge 1)((sh)^{2\delta} \wedge 1)}{h} \frac{dh}{h} \frac{d\ell}{\ell} \\ &\leq C \int (h^a \wedge (|\log h| + 1)) \left((sh)^{2\delta} \wedge 1 \right) \frac{dh}{h^2} \\ &\leq Cs^{2\delta} \int (h^a \wedge (|\log h| + 1)) h^{2\delta-2} dh = O(s^{2\delta}). \end{aligned} \tag{2.10}$$

Remark 2.3. In the applications that we have in mind in Section 2.4 (cf. (2.29)) it is not exactly the scaled Q_s in (2.1) that will be used but the variant $Q * \check{Q}_s$ that is involved in:

$$B_3^0(f, a) = \sum_{k=-\infty}^{\infty} \int \check{Q}_{sh} f_k(x) Q_h^k(x - y) A(y, h) \frac{dx dy dh}{h}. \tag{2.11}$$

Proceeding as in (2.10) we see that $|||Q * \check{Q}_s||| = O(s^\delta)$.

The modified form

We shall improve the estimate (2.3) for the modified form

$$\begin{aligned} B(f, A; s) &= \sum_{k=-\infty}^{+\infty} \int_{s^2h > 2^k} f_k(x) Q_{sh}^k(x - y) A(y, h) \frac{dy dx dh}{h}; \\ f, A &\in C_0^\infty, \quad 0 < s < 1. \end{aligned} \tag{2.12}$$

We shall need the estimate

$$|B(f, A; s)| \leq Cs^\epsilon \|f\|_{L^2} \|A\|_{T^2}; \quad 0 < s < 1, \tag{2.13}$$

for some $\epsilon > 0$. To see this we first reduce the corresponding Schur estimate to continuous time integration (as in (2.6)). We then use the scaling that allows us to normalize to $|\xi| = 1$. We then make the additional change of variables $h \mapsto sh, \ell \mapsto s\ell$ in that integration. Had we left the integration range in $[sh > 2^k]$ the

above transformations would not have changed the estimate (2.3). But the factor s^2 gives rise instead to a matrix

$$M_\sigma = \left((2^{ak} \wedge 1) \wedge (2^{-\delta j} \wedge 1) \mathbf{I}(k < j - \sigma) \right)_{k,j} ; \sigma = -\log s . \tag{2.14}$$

As before the $\| M_\sigma \|_{2 \rightarrow 2}$ can be estimated by the analogue of (2.9):

$$\begin{aligned} & \sup_k \left(2^{ak} \wedge 1 \right) \left(2^{-\delta(k+\sigma)} \wedge (|k| + \sigma + 1) \right) , \\ & \sup_j \left(2^{-\delta j} \wedge 1 \right) \left(2^{a(j-\sigma)} \wedge (|j| + \sigma + 1) \right) . \end{aligned} \tag{2.15}$$

(2.13) follows.

2.3. Proof of Proposition 1.1 for $p = 2$

For an affine function F_0 and Q , as in Proposition 1.1, and $\check{P} \in C_0^\infty$ s.t. $\int \check{P} = 1$, we define

$$\begin{aligned} B(f, A) &= \sum_{k=-\infty}^{+\infty} \int f_k(x) Q_h^k(x-y) F_0([a]_{x,y}) A(y, h) \frac{dx dy dh}{h} , \\ B_0(f, A) &= \sum_{k=-\infty}^{+\infty} \int f_k(x) Q_h^k(x-y) \check{P}_h a(y) A(y, h) \frac{dx dy dh}{h} . \end{aligned} \tag{2.16}$$

The estimate of the above B with $F_0 \equiv 1$ is given in (2.2) and this gives the proof of the Proposition 1.1 for $p = 2$ and $F_0 \equiv 1$. But the same estimate gives

$$|B_0(f, A)| \leq C \| f \|_{L^2(\ell^2)} \| A \|_{D_2} \| a \|_\infty . \tag{2.17}$$

This is because $\check{P}_h a(y) \in D_\infty$ and therefore this factor can be absorbed with $A(y, h)$ (Cf. [7, Section 2.2, 7] also [2]).

For the Proposition 1.1 we have to prove the estimate (2.17) for the form B in (2.16). From the above it follows that it suffices to prove the same estimate for the correcting form:

$$\begin{aligned} B_1(f, A) &= \sum_{k=-\infty}^{+\infty} \int f_k(x) Q_h^k(x-y) ([a]_{x,y} - \check{P}_h a(y)) A(y, h) \frac{dy dx dh}{h} ; \\ & a \in C_0^\infty, \| a \|_\infty \leq 1 . \end{aligned} \tag{2.18}$$

Towards that we shall modify B_1 further and define first $B_2(f, A)$ where in the integrand of (2.18) we smooth out and replace $f_k(x)$ by $\check{P}_h f_k(x)$ (with $\int \check{P} = 1$ and $I - \check{P}_h = \int_0^1 \check{Q}_{sh} \frac{ds}{s}$). Another modification of B_1 is $B_3(f, A; s)$, $0 < s < 1$, where

we replace f_k by $\check{Q}_{sh} f_k(x)$ and where in addition the summation in k is restricted to the range $[2^k \leq s^2 h]$. Finally we consider $B_4(f, A; s)$ with the same $\check{Q}_{sh} f_k(x)$ in the integrand but where the summation of the k 's extend to the complementary range $s^2 h < 2^k \leq h$.

We obtain thus the decomposition

$$\begin{aligned}
 B_1(f, A) &= B_2(f, A) + \int_0^1 B_3(f, A; s) \frac{ds}{s} + \int_0^1 B_4(f, A; s) \frac{ds}{s} \\
 &= X + Y + Z,
 \end{aligned}
 \tag{2.19}$$

and we shall estimate the three components separately.

Estimate of X

We assume that $f \in L^2(\ell^2)$, $A \in D_2$ and we have:

$$\begin{aligned}
 X &= \int U(x, h) V(x, h) \frac{dx dh}{h}; \\
 U(x, h) &= \sum_{2^k \leq h} \check{P}_h(I - R_{2^k}) f_k \in T_2^2 \text{ (cf. (2.3))}, \\
 V(x, h) &= \int Q_h(x - y) ([a]_{x,y} - \check{P}_h a(y)) A(y, h) dy,
 \end{aligned}
 \tag{2.20}$$

$$\begin{aligned}
 |V| &\leq \left(\int |Q_h(x - y)| |[a]_{x,y} - \check{P}_h a(y)|^2 dy \right)^{1/2} \left(\int |Q_h(x - y) A^2(y, h)| dy \right)^{1/2} \\
 &= V_1 V_2.
 \end{aligned}
 \tag{2.21}$$

With the notation of [2] we have $V_2 \in T_\infty^2$ cf. [7, Section 4.1] (i.e. the non tangential maximal function lies in L_2), $V_1 \in T_2^\infty$ cf. [7, Section 3.4] (i.e. Carleson measures as in [2]). Observe here that because of the compactness of the support of Q the localization in [7, (3.12), (3.13)] is symmetric in x and y . Therefore it does not matter that in [7, (3.4)] we define $\beta^2(x, h)$ with $\check{P}_h a(y)$ instead of $\check{P}_h a(x)$ and we still have the Carleson condition for $(\beta^2(x, h) \frac{dx dh}{h})$. Now it follows from [2] that $V \in T_\infty^2 T_2^\infty \subset T_2^2$ and this together with the expression of X in (2.20) gives the required estimate for X . More explicitly we can use the trivial fact that $T_2^2 T_\infty^2 \subset T_2^1$ and the (non trivial) duality between T_2^1 and T_2^∞ (as in [7, (4.13)]) to obtain the required

$$|X| \leq C \|f\|_2 \|A\|_{D_2}.
 \tag{2.22}$$

Estimates of Y

For B_2 we have exactly the same scalar product as in (2.20) but now U is replaced by $\int_0^1 U_s \frac{ds}{s}$ where

$$U_s(x, h) = \sum_{2^k \leq s^2 h} \check{Q}_{sh}(I - R_{2^k})f_k ; \| U_s \|_{T_2^2} \leq C s^\epsilon \| f \|_{L^2(\ell^2)} , \quad (2.23)$$

because of (2.13). The same argument as for (2.22) and integration in s gives therefore:

$$|B_3(f, A; s)| \leq C s^\epsilon \| f \|_{L^2(\ell^2)} \| A \|_{D_2} ; |Y| \leq C \| f \|_{L^2(\ell^2)} \| A \|_{D_2} . \quad (2.24)$$

Estimates of Z

This is deeper. The summation of the k 's that gives B_4 consists of $c|\log s| + c$ terms and the required estimate follows from the fact that each of these terms is

$$O \left(s^\epsilon \| f \|_{L^2(\ell^2)} \| A \|_{D_2} \right) ; \text{ some } \epsilon > 0 , \quad (2.25)$$

summing and integrating in s as in (2.19) gives the required estimate and completes the proof of Proposition 1.1.

The estimate (2.25) is not obvious. It is in fact the key estimate of [7, (1.32)] and the reader will have to read a good part of [7] to understand how this is proved. (The additional factor $(I - R_{2^k})$ gives no problem here because it can be absorbed with f_k , and the additional term $\check{P}_h a(y) \in D_\infty$ is absorbed with $A(y, h)$ as before.) This estimate (1.32) is on the other hand stated in the introduction of [7]. A quick glance at that introduction could perhaps satisfy the less demanding readers.

2.4. Proof for $1 < p < \infty$

Having proved that $\mathcal{L} : D_p \rightarrow L^p(\ell^2)$ is bounded for $p = 2$, it follows that the same thing holds for $0 < p \leq 1$. Here as in [7, Section 2.4, 2.5] it suffices to test on the atoms of D_p . Observe however that here we cannot reduce the test to unit atoms only, because a priori we cannot scale. But this makes no difference. On the other hand the operator \mathcal{L} is local in the sense that $\text{supp}(\mathcal{L}A) \subset \tilde{I}$ for all A with $\text{supp} A \subset T(I)$ ($I \subset \mathbb{R}^n$ is a cube, \tilde{I} is the concentric cube c -times as large and $T(I)$ is the tent above I [2, 6, 7]. Cf. also (3.3) below). It follows that for an atom $A \in D_p$ we do not have to worry about $\mathcal{L}A$ far out. Therefore no size estimate for Q is needed here.

Having proved the boundedness for \mathcal{L} for $p \leq 1$ and $p = 2$ we can interpolate and obtain all the values $0 < p \leq 2$ (cf. [7, Section 2.7, A.3.2])

As in [7], in the scalar case, the values $2 < p < \infty$ are much harder to handle and in particular we shall need to use concrete size and smoothness estimates for the

kernel of \mathcal{L} as [7, Section 2.5, 2.6]. We shall analyze these estimates again in more detail in the Appendix 2 below. Here I shall assume the results of the Appendix and complete the proof of the boundedness of \mathcal{L} for $2 \leq p < \infty$. I shall use the forms B_i , $0 \leq i \leq 4$ of Section 2.3 and (as in [7, (6.16)]) I shall first prove estimates for the Hardy space:

$$|B_i(f, A)| \leq C_i \|f\|_{H^1(\ell^2)} \|A\|_{D_\infty} \quad (2.26)$$

For $i = 2$ the form B_2 is smooth in the sense of [7, Section 2.6]. (Cf. Lemma (i) of the Appendix 2.) For C_2 we can therefore take a constant C . The $C_3, C_4 = C(s)$ will on the other hand depend on s but as in [7, Section 2.7] (cf. Lemma (ii) of the Appendix 2) we can assert that for any $\lambda > 0$ we have $C_3, C_4 \leq C_\lambda s^{-\lambda}$, $0 < s < 1$. The estimate (2.26) for $i = 3, 4$ can thus be interpolated with (2.24), (2.25). (This is the Lemma (iii) of the Appendix 2) and we deduce that

$$|B_i(f, A; s)| \leq C s^{\epsilon_p} \|f\|_{L^q(\ell^2)} \|A\|_{D_p}; \quad i = 3, 4, \quad 2 < p < \infty, \quad 1/p + 1/q = 1, \quad (2.27)$$

where C and $\epsilon_p > 0$ depend on p . The above inserted in (2.19) gives

$$|B_i(f, A)| \leq C \|f\|_{L^q(\ell^2)} \|A\|_{D_p}; \quad i = 1, \quad 1/p + 1/q = 1, \quad 2 \leq p < \infty. \quad (2.28)$$

Now I shall examine B_0 in (2.16) and decompose it

$$B_0(f, A) = B_2^0(f, A) + \int_0^1 B_3^0(f, A; s) \frac{ds}{s}, \quad (2.29)$$

where $B_2^0(f, A)$ is obtained from $B_0(f, A)$ by replacing in the integrand f_k by $\check{P}_h f_k$, and B_3^0 is obtained by replacing in the integrand f_k by $\check{Q}_{sh} f_k$. This is analogous to what we did in Section 2.3 for the decomposition (2.19) of B_1 (except that now we do not need to modify the summation range of k and we do not need to define the analogue of B_4). By the smoothness properties of these forms (cf. Appendix 2) we obtain as before

$$|B_i^0(f, A)| \leq C_i \|f\|_{H^1(\ell^2)} \|A\|_{D_\infty}; \quad i = 2, 3, \quad (2.30)$$

with $C_2 = C$ is a constant and $C_3 \leq C_\lambda s^{-\lambda}$ for any $\lambda > 0$. The estimate (2.30) can then be interpolated with (2.2)', (2.10), (2.11) and we obtain (cf. Appendix 3)

$$B_i^0(f, A) \leq C_i \|f\|_{L^q(\ell^2)} \|A\|_{D_p}; \quad 2 \leq p < \infty, \quad 1/p + 1/q = 1, \quad (2.31)$$

with $C_2 = C$ and $C_3 \leq C_\epsilon s^\epsilon$ (for some $\epsilon > 0$). If we insert (2.31) in (2.29) we obtain a proof of (2.28) for $i = 0$. Since $B = B_0 + B_1$ we have the proof of the Proposition 1.1 for $2 \leq p < +\infty$.

3. Reduction of Proposition 0.2 to affine functions

One says (cf. [6]) that $0 \leq \sigma \in A_\infty$ if there exists $r > 1, C > 0$ such that

$$\left(\frac{1}{|I|} \int_I \sigma^r dx \right)^{1/r} \leq C \frac{1}{|I|} \int_I \sigma dx ; I \text{ cube of } \mathbb{R}^n , \tag{3.1}$$

where $|I|$ denotes the Lebesgue measure of I . For the Properties 3.1 and 3.2 below the only thing that counts is this: For each $0 < \epsilon < 1$ and each $g \in L^1_{loc}$ such that the Hardy-Littlewood maximal function Mg is not identically $+\infty$ we have $(Mg)^\epsilon \in A_\infty$. (We even have $(Mg)^\epsilon \in A_1 \subset A_\infty$ but this here can be ignored).

We shall consider here sublinear local mappings L from functions A on \mathbb{R}^{n+1}_+ to $L(A)$ a function on \mathbb{R}^n . To wit:

$$|L(\lambda A)| = |\lambda| |L A| ; \lambda \in \mathbb{R} , |L(A_1 + A_2)| \leq |L A_1| + |L A_2| . \tag{3.2}$$

There exists $C_0 > 0$ such that for all cube $I \subset \mathbb{R}^n$ we have:

$$\begin{aligned} \text{supp } A \subset T(I) = [(x, h) ; h < c \text{ dist}(x, I^c)] &\Rightarrow \\ \Rightarrow \text{supp } L A \subset C_0 I = \text{the concentric cube } C_0 - \text{times as large.} \end{aligned} \tag{3.3}$$

Property 3.1. *Let us assume that L satisfies (3.2) and that for all $\sigma \in A_1$ the mapping*

$$L : D_1(\sigma) \longrightarrow L_1(\sigma) , \tag{3.4}$$

is bounded. Then

$$L : D_p \longrightarrow L_p , \tag{3.5}$$

bounded for all $1 \leq p < +\infty$.

Here $A \in D_1(\sigma)$ means that $\tilde{A} = A^* + S(h\nabla A) \in L_1(\sigma)$ (cf. [7, A.1] for more details on these weighted D_p -spaces). The above property is an immediate consequence of the property of A_1 weights that I stated above. Cf. [7, Section 2.8] for a two line proof of Property 3.1. Here we shall need to use this property for the vector valued spaces $L^p(\ell^2)$. The prototype of the Property 3.1 can be found in [5].

Property 3.2. *Let us assume that L satisfies (3.2) (3.3) let us assume that (3.5) bounded for all $1 \leq p < +\infty$ then (3.4) is bounded for all $\sigma \in A_\infty$.*

Once more the L_p -spaces are here vector valued. The local property (3.3) is now essential because we use here the atomic decomposition of $D_1(\sigma)$ (cf. [7, Section 2.8 and A.3.5.]

We shall consider now $\sigma \in A_\infty$ and $Q_h(x - y) = \Omega \left(\frac{x-y}{|x-y|} \right) \theta_h(|x - y|)$ as in (0.7) with $\Omega \in L^r(\Sigma)(r > 1)$ and $\theta \in C^\infty_0$. We shall assume that $\int \check{P} = 1$ and define as in [7, (3.15)]

$$\beta^2_\sigma(x, h) = \int |Q_h(x - y)| \left| [a]_{x,y} - \check{P}_h a(x) \right|^2 \sigma(y) dy . \tag{3.6}$$

Property 3.3.

$$\left| \int \beta_\sigma^2(x, h) A(x, h) \frac{dx dh}{h} \right| \leq C \|a\|_\infty^2 \int A^*(x) \sigma(x) dx ; A \geq 0. \quad (3.7)$$

where here $A^*(x)$ denotes the non tangential maximal function $\sup[|A(z)|; z \in \Gamma_\delta(x)]$.

It is easy to see that the right hand side of (3.7) is essentially independent of the aperture of the wedge $\delta > 0$ (cf. [7, A.1]). The proof of (3.7) is given in the Appendix 1.

Proof of the reduction of Section 1.3

We follow closely the strategy of [7, Section 7]. Let

$$L_X A(x) = \sup_{\epsilon, M} \left| \int_{\epsilon < h < M} Q_h(x - y) X(x, y; h) A(y, h) \frac{dy dh}{h} \right|. \quad (3.8)$$

When $X(x, y; h) = F_0([a]_{x,y}) = F_0$ for an affine $F_0 = c_0 + \sum_i c_i z_i$ I shall denote (3.8) by L_0 . By Proposition 1.1 and the above Property 3.2 we deduce the boundedness of

$$L_0 : D_1(\sigma) \longrightarrow L_1(\sigma) (\ell^2 \text{ valued } L^2), \quad (3.9)$$

for $\sigma \in A_\infty$. (3.9) also holds if in (3.8) we set $X = \Phi(\check{P}_h a(y)) = \Phi$ for some $\Phi \in C^N$, because then X is independent of x and $X \in D_\infty$ and can therefore be absorbed with A (cf. [7, Section 2.2]). The Property 3.2 applies thus again. The same thing clearly also holds for a product $X = F_0 \Phi$ as above. Let us consider the Taylor expansion of $F \in C^N$

$$F([a]_{x,y}) = F_0 \Phi + X(x, y; h) ; X = O(|[a]_{x,y} - \check{P}_h a(y)|^2) ; a \in C_0^\infty, \quad (3.10)$$

where F_0, Φ are as above. We shall then apply Property 3.3 to L_X (3.8) with the X as (3.10). This will give the boundedness of:

$$L_X : D_1(\sigma) \longrightarrow L_1(\sigma) ; \sigma \in A_\infty. \quad (3.11)$$

To see this we use duality with L^∞ (with respect to the weight σ) and use (3.7). But since L_X is bounded in (3.11) for any $\sigma \in A_\infty$ if $X = F_0 \Phi$, the boundedness of (3.11) with $X = F([a]_{x,y})$ follows. The Property 3.1 completes the proof of the reduction.

4. The Cotlar analysis – denouement

In this paragraph and in the next I shall estimate the correcting term in the control of (0.10).

4.1. Decomposition of the operators and notation

4.1.1. First set of notation

All the \check{P} will satisfy $\int \check{P} = 1$ and we can write $I - \check{P}_h = \int_0^1 \check{Q}_{sh} \frac{ds}{s}$ where I denotes throughout the identity operator. Furthermore when confusion does not arise I shall identify functions with convolution operators. R is as in Section 1, $F \in C^N$ as in Section 0 and $Q(x) = \Omega\left(\frac{x}{|x|}\right) \theta(|x|)$ is as in (0.7). If $K = K(x, y)$ ($x, y \in \mathbb{R}^n$) I shall denote by $\{K\}$ the operator whose kernel is $K(x, y)$. In the notation below a product of operators as above, denotes the composition of these operators.

The operators that give the correcting term in (0.10) are

$$T_k(h) = \int_0^1 (I - R_{2^k}) \{Q_h(x - y) F([a]_{x,y})\} \check{Q}_{s_1 h} \frac{ds_1}{s_1} [h > 2^k]; \quad k \in \mathbb{Z}, \quad (4.1)$$

with the abbreviation $[h > 2^k]$ for the indicator function $\mathbf{I}(h > 2^k)$ and where the a 's are as in the Theorem. The constants in the estimates below depend on $n, r, k, N, \|F\|_{C^N}$ but not on the a 's where we assume as before that $\|a\|_\infty \leq 1$. It is these operators that have to be analyzed.

4.1.2. Decomposition of (4.1)

We shall abbreviate and denote:

$$\begin{aligned} \{Q_h(x - y) F([a]_{x,y})\} &= \{\cdots |h\}; \\ \{Q_h(x - y) F([\check{P}_h a]_{x,y})\} &= \{1|h\}; \\ \{Q_h(x - y) F([\check{P}_{s_1 h} a]_{x,y}) [\check{Q}_{s_1 h} a]_{x,y}\} &= \{2|s, h\}. \end{aligned} \quad (4.2)$$

We have a first decomposition

$$\{\cdots |h\} = \{1|h\} + \int_0^1 \{2|s, h\} \frac{ds}{s}, \quad (4.3)$$

where $\{\cdots\}$ in the integrand is defined with the functions of ∇F .

A further decomposition is obtained by inserting the decomposition of the identity $I = \check{P}_h + (I - \check{P}_h)$:

$$(I - R_{2^k}) \{\cdots |h\} \check{Q}_{s_1 h} = (I - R_{2^k}) \check{P}_h \{\cdots |h\} \check{Q}_{s_1 h} + \int_0^1 (I - R_{2^k}) \check{Q}_{s_2 h} \{\cdots |h\} \check{Q}_{s_1 h} \frac{ds_2}{s_2}. \quad (4.4)$$

If we combine (4.3) and (4.4) and multiply by $[h > 2^k]$ we obtain a decomposition of $T_k(h)$ into four different operators.

4.1.3. An illustration and a further decomposition

One of the above four components of $T_k(h)$ is

$$\int_0^1 \int_0^1 \int_0^1 (I - R_{2^k}) \check{Q}_{s_1 h} \{2|s, h\} \check{Q}_{s_2 h} \frac{ds ds_1 ds_2}{s s_1 s_2} [h > 2^k]. \tag{4.5}$$

If we restrict the above integration to the range

$$2^{-i} < s_1 < 2^{-i+1}, \quad 2^{-j} < s_2 < 2^{-j+1}, \quad 2^{-\ell} < s < 2^{-\ell+1}; \quad 1 \leq i, j, \ell \in \mathbb{Z}, \tag{4.5}'$$

we obtain operators $T_k(h|i, j, \ell)$ and a further decomposition of (4.5) into $\sum_{i,j,\ell} T_k(h|i, j, \ell)$.

Analogous, but simpler decompositions (that involve only one or two summation indices) can be given for the other three components of $T_k(h)$ in (4.3)-(4.4).

4.1.4. The vector valued operator

Let

$$\mathbf{T}(h) : L^2 \longrightarrow L^2(\ell^2); \quad \mathbf{T}(h)g = (\dots T_{-1}(h)g, T_0(h)g, \dots). \tag{4.6}$$

Observe that

$$\mathbf{T}^*(h)\mathbf{T}(h') = \sum_{-\infty}^{+\infty} T_k^*(h)T_k(h'); \quad \mathbf{T}(h)\mathbf{T}^*(h') = (T_k(h)T_r^*(h'))_{k,r}, \tag{4.7}$$

where $(\cdot)_{k,r}$ indicates an operator entries (infinite) matrix that defines an operator in $\ell^2(L^2) \cong L^2(\ell^2)$.

4.1.5. The h -integration

For all the above operators we shall consider their integrated versions in dh/h :

$$T_k = \int_0^\infty T_k(h) \frac{dh}{h}, \quad \mathbf{T} = \int_0^\infty \mathbf{T}(h) \frac{dh}{h}, \quad \mathbf{T}_{i,j,\ell} = \int_0^\infty \mathbf{T}(h|i, j, \ell) \frac{dh}{h}, \dots$$

where $\mathbf{T}(h|i, j, \ell)$ is defined as in (4.6) from the operators $T_k(h|i, j, \ell)$.

4.2. The Cotlar estimates

The notation is as in Section 4.1. We shall prove that there exists $\epsilon > 0$ and $\delta > 0$ s.t.

$$\begin{aligned} & \| \mathbf{T}_{i,j,\ell}^*(h)\mathbf{T}_{i,j,\ell}(h') \|_{\text{op}}, \quad \| \mathbf{T}_{i,j,\ell}(h)\mathbf{T}_{i,j,\ell}^*(h') \|_{\text{op}} \\ & \leq C \exp(-\delta(i + j + \ell)) \left((h/h')^\epsilon \wedge (h'/h)^\epsilon \right); \quad i, j, \ell \geq 1. \end{aligned} \tag{4.8}$$

Here $\| \cdot \|_{\text{op}}$ denotes the corresponding $L^2 \longrightarrow L^2$ operator norm. Analogous estimates will be proved for the other components (that have one or two indices) of the decomposition Sections 4.1.2, 4.1.3.

The exponents ϵ

Throughout the $\epsilon > 0$ that appears as an exponent will denote some positive constant that may differ from place to place.

From (4.8) Cotlar’s Lemma applies (cf. [1, 6]) and we deduce:

$$\| \mathbf{T} \|_{\text{op}} \leq C ; \| \mathbf{T}_{i,j,\ell} \|_{\text{op}} \leq C \exp(-\delta(i + j + \ell)) , \tag{4.9}$$

for some $\delta > 0$.

The proof of (4.8) will be given below and is a straightforward adaptation of ideas of [7, Sections 8, 9] and of [1]. The only real difficulty in these proofs is to keep track of the notation which are unfortunately very involved.

4.3. Estimate of T^*T

The integrand of $\mathbf{T}_{i,j,\ell}^*(h)\mathbf{T}_{i,j,\ell}(h')$ that comes from (4.5) is:

$$\check{Q}_{s_1 h} \{2|s_2, h\} \check{Q}_{s_3 h} (I - R_{2^k})^2 \check{Q}_{s_4 h'} \{2|s_5, h'\} \check{Q}_{s_6 h'} [2^k < h \wedge h'] , \tag{4.10}$$

where we integrate in the range:

$$2^{-j} < s_1, s_6 < 2^{-j+1}, 2^{-i} < s_3, s_4 < 2^{-i+1}, 2^{-\ell} < s_2, s_5 < 2^{-\ell+1}; i, j, \ell \geq 1, \tag{4.11}$$

and sum in $k \in \mathbb{Z}$. The other components of the decomposition (4.3)-(4.4) give analogous (but simpler) expressions. If we integrate (4.10) in (4.11) we obtain $\mathbf{T}_{i,j,\ell}^*(h)\mathbf{T}_{i,j,\ell}(h')$. Finally in (4.10) and throughout, I abuse slightly the notation and use the same symbols $R, \{\cdot \cdot \cdot\}$ etc to indicate these operators and their adjoints. The functions that are used for these adjoints are of course different, but noting changes either in the notation or in the arguments that follow.

By taking adjoints if necessary we may assume that $h/h' = e^{-a}$, $a \geq 0$. We shall denote $s_i = e^{-\sigma_i}$ ($\sigma_i \geq 0$) and use throughout the convention that in the exponentials that appear below e.g. $\exp(-\sigma_1)$, $\exp(-\sigma_3 + \sigma_4 - a)$ etc. what is meant is $\exp(-c\sigma_1)$, $\exp(-c\sigma_3 + c\sigma_4 - ca)$ etc. In other words the positive constants c are omitted. Finally each of the factors in (4.10) has a bounded operator norm and the estimates given below are obtained by combining adjacent factors.

For the summation in k in (4.10) two different ranges will be considered:

Range 1: $2^k \leq s_3 h \wedge s_4 h'$.

Range 2: ($\mathbb{Z} \setminus$ Range 1), and we shall use the fact that:

$$\text{Cardinality of Range 2} \leq c + c|\log s_3| + c|\log s_4| . \tag{4.12}$$

Estimate 1

We shall estimate the L^1 norm of

$$\sum_k \check{Q}_{s_3h}(I - R_{2^k})^2 \check{Q}_{s_4h'}[2^k < h \wedge h'] , \tag{4.13}$$

which is one of the segments of (4.10).

At this point it is instructive to consider first the other component coming from the first term of the right hand side of (4.4). The corresponding segment simplifies and is

$$\sum_{2^k < h \wedge h'} \check{P}_h(I - R_{2^k})^2 \check{P}_{h'} = \sum_{2^k < h \wedge h'} \check{Q}_h^k \check{Q}_{h'}^k ; \quad \|\check{Q}_h^k\|_1 = O(2^k h^{-1}), \tag{4.14}$$

because $\check{Q}_h^k = (I - R_{2^k})\check{P}_h = ((I - R_{2^k h^{-1}})\check{P})_h$. The norm of each term, of (4.14) can also be estimated by $(h/h') \wedge (h'/h)$ because of the cancellation. This gives

$$\|\check{Q}_h^k \check{Q}_{h'}^k\|_1^2 \leq C [(h/h') \wedge (h'/h)] 2^k h^{-1} . \tag{4.15}$$

Summing up we see that we can estimate (4.14) by $(h/h')^\epsilon \wedge (h'/h)^\epsilon = e^{-a}$.

For the original (4.13) exactly the same argument applies for the summation of $k \in \text{Range } 1$, and this gives therefore an estimate $\left(\frac{s_3h}{s_4h'}\right)^\epsilon \wedge \left(\frac{s_4h'}{s_3h}\right)^\epsilon$ for the sum of the L^1 -norms. The same estimate holds for each individual term in the summation (4.13). In the range 2 we can thus use (4.12) to conclude

$$(4.13) \leq C(1 + \sigma_3)(1 + \sigma_4) \exp(-\sigma_3 + \sigma_4 - a) . \tag{4.16}$$

Estimate 2

Here we use [7, Section 8] (esp. (8.6) (8.7)) on each sub-product

$$\{2|s_2, h\} \check{Q}_{s_3h}(I - R_{2^k}) \text{ or } (I - R_{2^k}) \check{Q}_{s_4h'}\{2|s_5, h'\} , \tag{4.17}$$

in (4.10). Furthermore as before we can combine together the terms that come from $k \in \text{Range } 1$. We obtain therefore for the L^2 operator norm of (4.10) the estimate

$$(1 + |\log s_3| + |\log s_4|) \left(\frac{s_3^\epsilon}{s_2^\epsilon} \wedge \frac{s_4^\epsilon}{s_5^\epsilon} \right) \sim (1 + \sigma_3 + \sigma_4) (\exp(-\sigma_3 + \sigma_2) \wedge \exp(-\sigma_4 + \sigma_5)) , \tag{4.18}$$

where the logarithmic factor comes from (4.12). We shall omit the details. The key observation however, as in (4.14), is that with $k \in \text{Range } 1$ $(I - R_{2^k})\check{Q}_{s_3h} = 2^k s_3^{-1} h^{-1} \check{Q}_{s_3h}^{(k)}$ with the $\check{Q}^{(k)}$'s staying in a ‘‘bounded set’’ of functions of C_0^∞ . The additional scalar factor comes about because the integral of $I - R_r$ is 0 and the diameter of its support is r . Here $r = 2^k s_3^{-1} h^{-1}$.

It will be instructive at this point to switch to the two components of the decomposition Section 4.1.2 that come from $\{1|h\}$ in (4.3). I shall show how the above two estimates suffice to give the final control of these two components. Indeed the integrands in $\mathbf{T}^*(h)\mathbf{T}(h')$ that give these two components are respectively

$$\check{Q}_{s_1h}\{1|h\}\check{Q}_{s_3h}(I - R_{2^k})^2\check{Q}_{s_4h'}\{1|h'\}\check{Q}_{s_6h'}[2^k < h \wedge h'] , \tag{4.19}$$

$$\check{Q}_{s_1h}\{1|h\}\check{P}_h(I - R_{2^k})^2\check{P}_{h'}\{1|h'\}\check{Q}_{s_6h'}[2^k < h \wedge h'] . \tag{4.20}$$

For (4.19) if we use (4.16) on the middle three factors we obtain the estimate

$$\exp(-\sigma_3 + \sigma_4 - a) . \tag{4.21}$$

On the other hand in (4.19) from the four possible combinations of the type (4.17) (where now $s_2 = s_5 = 1$) we obtain for the summation in Range 1 the estimates

$$s_1^\epsilon \wedge s_3^\epsilon \wedge s_4^\epsilon \wedge s_6^\epsilon . \tag{4.22}$$

For this we observe that the summation of the middle three factors is also bounded by C and thus the first (respectively last) two factors give s_1^ϵ (respectively s_6^ϵ).

If we combine these with the logarithmic factor coming from the summation in k in Range 2 (4.12) we finally obtain for (4.19) the estimate

$$(1 + \sigma_3)(1 + \sigma_4) [e^{-\sigma_1} \wedge e^{-\sigma_3} \wedge e^{-\sigma_4} \wedge e^{-\sigma_6} \wedge \exp(-\sigma_3 + \sigma_4 - a)] .$$

That this suffices to give (4.9) is easy to see [cf. (4.24) below].

An analogous, but simpler estimate can be obtained for (4.20). To treat the term (4.10) we shall need the following additional:

Estimate 3 [7, Section 8], [1, Section 5.3]

$$\| \{2|s_2, h\} \|_{\text{op}} \leq C s_2^\epsilon ; \quad \| \{2|s_5, h'\} \|_{\text{op}} \leq C s_5^\epsilon .$$

With this new estimate and with the previous treatment of (4.19) adapted now to the case $0 < s_2, s_5 < 1$ we finally obtain for (4.10) the estimate

$$\begin{aligned} & (1 + \sigma_3)(1 + \sigma_4) \left[s_2^\epsilon \wedge s_5^\epsilon \wedge \left(\frac{s_1^\epsilon}{s_2^\epsilon} \wedge \frac{s_3^\epsilon}{s_2^\epsilon} \right) \wedge \left(\frac{s_4^\epsilon}{s_5^\epsilon} \wedge \frac{s_6^\epsilon}{s_5^\epsilon} \right) \wedge \left(\frac{s_3h}{s_4h'} \right)^\epsilon \right] \\ & \approx (1 + \sigma_3)(1 + \sigma_4) [e^{-\sigma_2} \wedge e^{-\sigma_5} \wedge \exp(-\sigma_1 + \sigma_2) \wedge \exp(-\sigma_3 + \sigma_2) \\ & \wedge \exp(-\sigma_4 + \sigma_5) \wedge \exp(-\sigma_6 + \sigma_5) \wedge \exp(-\sigma_3 + \sigma_4 - a)] . \end{aligned} \tag{4.23}$$

To obtain the estimate (4.9) for the component (4.10), as in [7, Section 9] we apply on (4.23) the barrycenter inequality

$$\text{Min}[x_1, \dots, x_m] \leq x_1^{\alpha_1} \dots x_m^{\alpha_m} ; \quad x_j \geq 0, \alpha_j \geq 0, (1 \leq j \leq m), \sum \alpha_j = 1 , \tag{4.24}$$

for an appropriate choice of the α_j 's, and where the x_j are the exponentials of (4.23). We then integrate each σ_r , $1 \leq r \leq 6$ in the corresponding interval $[i, i + 1], [j, j + 1], [\ell, \ell + 1]$ that is given by (4.11). (4.9) follows at once.

4.4. Estimate of TT^*

The integrand of $\mathbf{T}_{i,j,\ell}(h)\mathbf{T}_{i,j,\ell}^*(h')$ that comes from (4.5) is

$$(I - R_{2^k})\check{Q}_{s_1h}\{2|s_2, h\}\check{Q}_{s_3h}\check{Q}_{s_4h'}\{2|s_5, h'\}\check{Q}_{s_6h'}(I - R_{2^r})[2^k < h][2^r < h'], \tag{4.25}$$

where no summation in k or r is involved here and (4.25) represents the entry of the matrix $(\cdot)_{k,r}$ in (4.7). The other components of the decomposition (4.3)-(4.4) give analogous but simpler expressions.

If we integrate (4.25) in the range (4.11) we obtain

$$A_{k,r} = T_k(h|i, j, \ell)T_r^*(h'|i, j, \ell), \tag{4.26}$$

and we have

$$\|\mathbf{T}_{i,j,\ell}(h)\mathbf{T}_{i,j,\ell}^*(h')\|_{\text{op}} \leq \sum_{k,r} \|A_{k,r}\|_{\text{op}}. \tag{4.27}$$

We shall use the same method and the same notation as in Section 4.3 to estimate (4.27). As in Section 4.3 we distinguish in the summation (4.27) the four ranges obtained from the decompositions

$$[2^k \leq s_1h] \cup [s_1h \leq 2^k < h]; [2^r \leq s_6h'] \cup [s_6h' \leq 2^r \leq h']. \tag{4.28}$$

We shall in particular use the estimate 1-2-3 of Section 4.3 to estimate various segments of the product of operators appearing in (4.25). We shall then use the ranges (4.28) to sum in k, r . We shall omit the details. The estimate obtained is as before (4.23). We finally integrate in the same range for the $\sigma_r (1 \leq r \leq 6)$.

4.5. Denouement

The estimate that will be used is summarized in the following:

Lemma 4.1. *With our previous notation*

$$\int_{\epsilon}^M \mathbf{T}(h) \frac{dh}{h} : L^p \longrightarrow L^p(\ell^2); \quad 1 < p < \infty, \tag{4.29}$$

is bounded uniformly in $\epsilon, M > 0$.

In (4.9) I gave a proof of (4.29) for $p = 2$. The general $1 < p < \infty$ will be proved in Section 5 below. Here I shall assume the results of [7] and (4.29) and complete the proof of (0.10). This, as explained in Section 0.2, will finish the proof of the theorem. What is needed is the control of

$$f \mapsto \sup_N |\Lambda_N f|; \quad \Lambda_N f(x) = \iint_{h < N} Q_h(x - y) F([a]_{x,y})(I - \check{P}_h) f(y) \frac{dydh}{h}; \tag{4.30}$$

$$0 < N \leq \infty.$$

A consequence of the lemma is that

$$f \mapsto \sup_k |(I - R_{2^k})(\Lambda_\infty - \Lambda_{2^k})f(x)|, \tag{4.31}$$

is $L^p \rightarrow L^p$ bounded (because $\ell^2 \subset \ell^\infty$).

We shall prove that

$$f \mapsto \sup_N |R_N \Lambda_N f(x)|, \tag{4.32}$$

is $L^p \rightarrow L^p$ bounded. From (4.31) and (4.32) $f \mapsto \sup_k |\Lambda_{2^k} f|$ is seen to be L^p bounded, therefore by the argument of Section 1.3 the L^p boundedness (4.30) follows. Observe also that the full thrust of [7] is used together with the fact that $\check{P}_h f(x) \in D_p$ for $f \in L^p$ to guarantee the $p \rightarrow p$ boundedness of Λ_N . This finishes the proof.

To prove (4.32) it suffices to show that

$$|R_N \Lambda_N f(x)| \leq C(M|f|^p)^{1/p}(x); \quad 1 < p < \infty, \tag{4.33}$$

where M is the Hardy-Littlewood maximal function. But by translation and dilation we can assume in (4.33) that $x = 0, N = 1$. But then (4.33) is a consequence of the fact that Λ_1 is $L^p - L^p$ bounded. Indeed if we localize $f_c = f\chi_{[|x|<c]}$ we have $R_1 \Lambda_1 f(0) = R_1 \Lambda_1 f_c(0)$ because of the compactness of the support of Q . It follows that

$$|R_1 \Lambda_1 f(0)| = |R_1 \Lambda_1 f_c(0)| \leq C \| \Lambda_1 f_c \|_p \leq C \| f_c \|_p \leq C(M|f|^p)^{1/p}(0),$$

as needed.

From (4.33) it follows that (4.32) is $L^p \rightarrow L_{p,\infty}$ bounded $1 < p < \infty$ i.e. the weak p -boundedness. Interpolation gives the corresponding L^p -boundedness.

5. The Calderon-Zygmund estimates

5.1. Terminology and basic facts [1, 6]

Let $K(x, y) \in H = \ell^2, (x, y \in \mathbb{R}^n)$ be a vector valued kernel. We say that K satisfies the standard estimates if:

$$\text{Size estimate: } |K(x, y)| \leq C_1|x - y|^{-n}.$$

$$\text{Gradient estimate: } |\nabla K(x, y)| = |\nabla_x K| + |\nabla_y K| \leq C_2|x - y|^{-n-1}.$$

Let T, T^* be operators $L^2 \rightarrow L^2(H)$ and $L^2(H) \rightarrow L^2$ with $\| T \|_{2 \rightarrow 2} = C_3$ and let us assume that the kernel of T satisfies the standard estimates. In terms of

the constants C_1, C_2, C_3 and with the notation $L_{1,\infty}$ for the weak L_1 space (Lorentz notation), the “norm” of:

$$T : L^1 \longrightarrow L_{1,\infty}(H), \quad T^* : L_1(H) \longrightarrow L_{1,\infty}, \tag{5.1}$$

can then be bounded by

$$C_\theta(C_3 + C_1^{1-\theta}C_2^\theta); \quad 0 < \theta < 1, \tag{5.2}$$

where C_θ only depends on n and θ . (Cf. [1, 6] for this basic fact). Let us also consider the condition (cf. [6, I, Section 5])

$$\int_{|x-y|>2|x-x'|} (|K(x, y) - K(x', y)| + |K(y, x) - K(y, x')|) dy \leq C_4; \quad x, x' \in \mathbb{R}^n. \tag{5.3}$$

We obviously have $C_4 \leq C_\theta C_1^{1-\theta} C_2^\theta$, but we can also improve the above and we can estimate the norms of (5.1) by

$$C(C_3 + C_4). \tag{5.2}'$$

5.2. The scalar valued illustration [7, Section 9]

With the notation of Section 4.1 I considered in [7] the $L^2 \longrightarrow L^2$ operators

$$T_{i,j,\ell} = \int_0^\infty \frac{dh}{h} \iiint \check{Q}_{s_1 h} \{2|s, h\} \check{Q}_{s_2 h} \frac{ds ds_1 ds_2}{s s_1 s_2}, \tag{5.4}$$

where the s -integration is taken in

$$2^{-i} \leq s_1 \leq 2^{-i+1}, \quad 2^{-j} \leq s_2 \leq 2^{-j+1}, \quad 2^{-\ell} \leq s \leq 2^{-\ell+1}.$$

We also considered the sum $T = \sum_{i,j,\ell=1}^\infty T_{i,j,\ell}$. What was proved in [7, Section 9] was that

$$\| T_{i,j,\ell} \|_{2 \rightarrow 2} = O \left(e^{-c(i+j+\ell)} \right). \tag{5.5}$$

The proof of (5.5) in [7] served as prototype for the proofs of Section 4.2. But the situation in [7] was simpler.

Then in [7, Section 9] I used Section 5.1 to conclude

$$\| T_{i,j,\ell} \|_{p \rightarrow p} = O \left(e^{-c_p(i+j+\ell)} \right), \tag{5.6}$$

and therefore also that T is $L^p \rightarrow L^p$ bounded.

To see this let us denote by $Q(x, y; h) = Q(x, y; h|s_1, s_2, s)$ the integrand in (5.4). Here we identify the operator with its kernel *i.e.* with a function in $x, y \in \mathbb{R}^n$. It is easy to see that if $\Omega^* = M\Omega$ is the Hardy-Littlewood maximal function of Ω on the unit sphere, then for $h = 1$ we have

$$\begin{aligned} Q(x, y; 1) &\leq C \Omega^* \left(\frac{x - y}{|x - y|} \right) \mathbf{I}(|x - y| \leq C) ; |\nabla_x Q| + |\nabla_y Q|(x, y; 1) \\ &\leq Cs_1^{-c} s_2^{-c} \mathbf{I}(|x - y| \leq C) . \end{aligned}$$

We can scale the above and obtain the corresponding estimates for all $h > 0$. These estimates can be integrated in dh/h and we obtain

$$\begin{aligned} |K_{i,j,\ell}(x, y)| &\leq C \Omega^* \left(\frac{x - y}{|x - y|} \right) |x - y|^{-n} ; \\ |\nabla K_{i,j,\ell}(x, y)| &\leq Ce^{c(i+j)} |x - y|^{-n-1} , \end{aligned} \tag{5.7}$$

for the kernels of the operators $T_{i,j,\ell}$. When $\Omega \in L^\infty$ we can combine (5.2) with the above to conclude that the $L_1 \rightarrow L_{1,\infty}$ norm of $T_{i,j,\ell}, T_{i,j,\ell}^*$ are $O(e^{\delta(i+j)})$ for an arbitrary $\delta > 0$. This interpolated with (5.5) (and dualized) gives (5.6).

For the general case $\Omega \in L^r (r > 1)$ the previous argument still works because, with the above notation, in (5.3), (5.2)' we have

$$C_4 \leq Ce^{\delta(i+j)},$$

(for any $\delta > 0$ and where C only depends on n, δ and the constants of (5.7)).

To see this we can estimate the integrals (5.3) in the range $2^m|x - x'| \leq |x - y| \leq 2^{m+1}|x - x'|$ in the two different ways by using either the first or the second estimate in (5.7). We then take a geometric average.

5.3. Proof of Lemma 4.1

We shall apply the same strategy as in the previous section to the operators $\mathbf{T}_{i,j,\ell}$ of Section 4. Towards this let us denote

$$\mathbf{Q}(x, y; h|s_1, s_2, s) = \{(I - R_{2^k})\check{Q}_{s_2h}\{2|s, h\}\check{Q}_{s_1h}\{h > 2^k\}\}_{k \in \mathbb{Z}} \in \ell^2 , \tag{5.8}$$

where each coordinate of ℓ^2 in (5.8) denotes a scalar kernel as above. This after integration in the range (4.5)' gives the kernel of $\mathbf{T}(h|i, j, \ell)$. We aim to prove the following estimates

$$\begin{aligned} |\mathbf{Q}(x, y; 1|s_1, s_2, s)| &\leq C(1 + \sigma_1 + \sigma_2 + \sigma)^c \Omega^* \left(\frac{x - y}{|x - y|} \right) \mathbf{I}(|x - y| \leq C) ; \\ (|\nabla_x \mathbf{Q}| + |\nabla_y \mathbf{Q}|)(x, y; 1|s_1, s_2, s) &\leq Ce^{c(\sigma_1 + \sigma_2 + \sigma)} \mathbf{I}(|x - y| \leq C); \\ x, y \in \mathbb{R}^n, s_j &= e^{-\sigma_j} \text{ as in Section 4.3 } \sigma, \sigma_j > 0 , \end{aligned} \tag{5.9}$$

and where $\Omega^* = M\Omega$ is as in (5.7). Once (5.9) has been proved we proceed as in Section 5.2. More explicitly we first scale to obtain the analogous estimates for (5.8) with $h > 0$. We then integrate to obtain the analogue of the estimate (5.7) for $\mathbf{K}_{i,j,\ell}$ the kernel of $\mathbf{T}_{i,j,\ell}$:

$$\begin{aligned} |\mathbf{K}_{i,j,\ell}(x, y)| &\leq C(i + j + \ell)^c \Omega^* \left(\frac{x - y}{|x - y|} \right) |x - y|^{-n} ; \\ |\nabla \mathbf{K}_{i,j,\ell}(x, y)| &\leq C e^{c(i+j+\ell)} |x - y|^{-n-1} . \end{aligned} \tag{5.10}$$

We proceed as in Section 5.2 to obtain

$$\| \mathbf{T}_{i,j,\ell} \|_{p \rightarrow p} = O \left(e^{-c_p(i+j+\ell)} \right) . \tag{5.11}$$

Here the presence of the factor $(i + j + \ell)$ in the size estimate (5.10) is easily seen to make no difference. From (5.11) we obtain the boundedness of $\mathbf{T} : L^p \rightarrow L^p(\ell^2)$ for the component of \mathbf{T} in the decomposition Section 4.1 coming from (4.5). The other components of \mathbf{T} in the decomposition Section 4.1 are treated identically and they are simpler. This gives the proof of the lemma.

5.4. Proof of the estimates (5.9)

For both the size and the gradient estimate in (5.9) what has to be estimated is the square root of:

$$\sum_{2^k \leq 1} |(I - R_{2^k}) \check{Q}_{s_2} \{2|s, 1\} \check{Q}_{s_1}|^2 , \tag{5.12}$$

and for simplicity, and to illustrate the issue, assume first that $\Omega \in L^\infty$. Then, by the compactness of the support of Q , in (5.9) we just have to prove the uniform estimate in x, y .

Clearly (since $\{\dots\} \leq Q(x - y)$) each individual term in (5.12) is uniformly bounded. Observe however that for the gradient estimate an additional factor s_1^{-1} or s_2^{-1} will appear. Now to take the summation in k we decompose as we did in Section 4.3 in the two ranges $[2^k \leq s_2], [s_2 \leq 2^k \leq 1]$ and for the first range, as in Section 4.3, we can improve the above uniform estimate by the factor $\frac{2^k}{s_2}$. The estimate (5.12) as in (5.9) follow and the factor $|\log s_2| \sim |(k : 2^k \geq s_2)|$ comes from the second range.

For the general case $\Omega^* \in L^1$ the proof is essentially the same:

To estimate the uniform norm of $\check{Q}_{s_i} * Q$ we have to use $\| \Omega \|_1$ multiplied with the L^∞ -norms of $\check{Q}_{s_1}, \check{Q}_{s_2}$ (or at least of one of them!). This accounts for the $s_1^{-c} s_2^{-c}$ in the constant of the gradient estimate of (5.9).

To obtain the size estimate in (5.9) we do not use $\| \check{Q}_{s_1} \|_\infty$ but dominate each term of (4.12) by $\Omega^* \left(\frac{x-y}{|x-y|} \right)$ with the same convergence factor $\frac{2^k}{s_2}$ in the range $2^k \leq s_2$. This completes the proof of (5.9).

Appendix

A.1. (Carleson measures)

We recall the notation of [7, (3.15)] so that in (3.6) we have

$$G_h(x, y) = \left| [a]_{x,y} - \check{P}_h a(x) \right| ;$$

$$\beta_\sigma^2(x, h) = \int |Q_h(x - y)| G_h^2(x, y) \sigma(y) dy ;$$

$$a \in C_0^\infty, \sigma \geq 0 .$$

I pointed out in the remark of [7, Section 3.6] that with $G^2(y) = \int G_h^2(x, y) \frac{dx dh}{h}$ we have

$$\| G \|_{2r} \leq C \| a \|_{2r} ; r > 1 . \tag{A.1}$$

This was seen as follows. For $g \in C_0^\infty$ we have

$$\int G^2(y) g(y) dy \leq \iiint \beta_\sigma^2(x, h) \frac{dx dh}{h} \leq C \int |a(x)|^2 \sigma^{**}(x) dx , \tag{A.2}$$

where $\sigma = (Mg^{1+\epsilon})^{\frac{1}{1+\epsilon}}$ for some $\epsilon > 0$ with $\frac{q}{1+\epsilon} > 1$ and $\frac{1}{q} + \frac{1}{r} = 1$ as in [7, lemma, Section 3.5]. As for σ^{**} it was constructed in that lemma so that $\| \sigma^{**} \|_q \leq C \| g \|_q$ and such that (A.2) holds. (A.1) is a consequence of (A.2).

From this we obtain the following Carleson measure property:

$$\iint_{T(I)} \beta_\sigma^2(x, h) \frac{dx dh}{h} \leq C \sigma(I) \| a \|_\infty^2 ; \text{ for a cube } I \subset \mathbb{R}^n , \tag{A.3}$$

where $T(I)$ is the tent above I (cf. [6,7]) and $\sigma \in A_\infty$ is arbitrary. To see this, by the compactness of the support of Q in the left hand side of (A.3), we can localize a and replace it by $a_1 = \chi_{I_1} a$ for some larger concentric $I_1 \supset I$. It follows that the left hand side of (A.3) can be dominated by $\int G_1^2(y) \sigma(y) dy$ where G_1 is constructed exactly as G but where we use the localized a_1 . We then use (A.1) on G_1, a_1 and the reverse Hölder inequality (3.1) on σ , and we obtain (A.3). The Property 3.3 of Section 3 is a consequence of (A.3) and the general theory cf. [6].

[This is a good place to point out that there is an error in the statement, but not in the proof, of [7, lemma, Section 3.5]: $\sigma^{**} = (\sigma_\alpha)^{1/\alpha}$ and not $(\Omega^* \sigma^\alpha)^{1/\alpha}$. This error is purely notational and makes no difference either in [7] or here.]

A.2. (Kernels)

The scalar kernel

For the convenience of the reader I will start with rerunning the argument of [7, Section 2.6] for the kernel (0.7):

$$Q(x, y; h) = \Omega \left(\frac{x - y}{|x - y|} \right) \theta_h(|x - y|) F([a]_{x,y}). \tag{A.4}$$

We consider

$$\tilde{Q}(x, y; h) = \check{P}_h Q(x, y; h) = \int \check{P}_h(x - z) Q(z, y; h) dz,$$

and define analogously $Q_s(x, y; h) = \check{Q}_{sh} Q$ for $0 < s < 1$. What was needed and proved in [7] is the following:

Lemma. *Let the notation be as above. Then:*

- (i) *If we assume that $\tilde{Q} : D_2 \rightarrow L_2$ bounded then $\tilde{Q} : D_\infty \rightarrow BMO$ is bounded.*
- (ii) *If we assume that $Q_s : D_2 \rightarrow L_2$ bounded uniformly in s the $D_\infty \rightarrow BMO$ operator norm of Q_s is $O(s^{-\lambda})$ for any $\lambda > 0$.*
- (iii) *If we assume that the $D_2 \rightarrow L_2$ norm of Q_s is $O(s^\epsilon)$ for some $\epsilon > 0$ then the $D_p \rightarrow L_p$ norm of Q_s is $O(s^{\epsilon p})$ for some $\epsilon_p > 0$ ($1 < p < \infty$).*

Part (iii) for $2 \leq p < \infty$ is an immediate consequence of (ii) and interpolation, (cf. Appendix 3 below). For the case $1 \leq p \leq 2$ we interpolate between $p = 1$ and 2 and we do not need (ii). In the above lemma and throughout I abusively use the same notation for the kernel and the induced mapping (0.6).

The proof of (i) and of (ii) in the special case $\Omega \in L^\infty$ are easy: Indeed we have

$$\begin{aligned} |\tilde{Q}(x, y; h)|, |Q_s(x, y; h)| &\leq Ch^{-n} \mathbf{I}(|x - y| \leq ch), \\ |\nabla_x \tilde{Q}(x, y; h)| &\leq Ch^{-n-1} \mathbf{I}(|x - y| \leq ch), \\ |\nabla_x Q_{sh}(x, y; h)| &\leq Cs^{-1} h^{-n-1} \mathbf{I}(|x - y| \leq ch). \end{aligned} \tag{A.5}$$

In particular for all $0 < \lambda < 1$ it follows that:

$$|Q_{sh}(x, y; h) - Q_{sh}(x', y; h)| \leq Cs^{-\lambda} h^{-\lambda-n} \mathbf{I}(|y| \leq Ch); |x|, |x'| \leq 1, |y| + h \geq C,$$

and as a consequence:

$$\int_{|y|+h \geq C} |Q_{sh}(x, y; h) - Q_{sh}(x', y; h)| \frac{dy dh}{h} \leq Cs^{-\lambda}; \lambda > 0, |x|, |x'| \leq 1.$$

The analogous estimate for \tilde{Q} holds for $\lambda = 0$. If we now use the hypothesis of the lemma and the previous estimate, together with the cut off properties of [7, Section 2.1], we deduce the required BMO property for $\tilde{Q}A, Q_s A (A \in D_\infty)$ tested on the unit cube. The situation is clearly dilation and translation invariant and our result follows.

When $\Omega \in L^r$ with $r < +\infty$ nothing changes in the estimates for \tilde{Q} and for Q_s we have

$$|Q_s(x, y; h)| \leq Ch^{-n} \Omega^* \left(\frac{x-y}{|x-y|} \right) \mathbf{I}(|x-y| \leq ch), \tag{A.6}$$

$$|\nabla_x Q_s(x, y; h)| \leq Ch^{-n-1} s^{-a} \mathbf{I}(|x-y| \leq ch) ; a = a(n, r) > 0 ,$$

where $\Omega^* = M_\Sigma \Omega$ is the Hardy-Littlewood maximal function of Ω on Σ . We shall then proceed as before and denote by $f(x) = \int_{|y|+h>C} Q_s(x, y, h) A(y, h) \frac{dydh}{h}$ for some $A \in L^\infty$ with norm 1. For the BMO condition tested on the unit cube I it suffices therefore to estimate

$$\iint_{|x_i| \leq 1} |f(x_1) - f(x_2)| dx_1 dx_2 \leq \iiint_{\substack{(y,h) \in T \\ |x_i| \leq 1}} |Q_s(x_1, y; h) - Q_s(x_2, y; h)| \frac{dx_1 dx_2 dy dh}{h} , \tag{A.7}$$

$$T = \bigcup_{j \geq 100} T_j ; T_j = [2^j < h < 2^{j+1} ; |y| \leq C2^j] ; j \geq 1 .$$

The integration range T holds because of the compactness of the support of Q . Using the two estimates (A.6) separately on each T_j and taking a geometric mean and summing we see that we can estimate (A7) by $Cs^{-\lambda} \| A \|_\infty 0 < s < 1$ for any $\lambda > 0$. This completes the proof of the lemma.

The vector valued kernel

We shall examine now the vector valued kernel:

$$\tilde{Q}(x, y; h) = \{(I - R_{2^k})\tilde{Q}(x, y; h)\mathbf{I}(2^k < h)\}_k \in H = \ell^2 , \tag{A.8}$$

and the analogue Q_s where in $\{\cdot \cdot \cdot\}$ we replace \tilde{Q} by Q_s . The analogue of the estimates (A.5) for \tilde{Q} also hold and this is essentially trivial to verify by the smoothness of \check{P}_h and the geometric decay of the diameters of the supports of $I - R_{2^k}$. The analogue of (A.6) for Q_s is

$$|Q_s(x, y; h)|_H \leq Ch^{-n} (1 + |\log s|) \Omega^* \left(\frac{x-y}{|x-y|} \right) \mathbf{I}(|x-y| \leq ch) ;$$

$$|\nabla_x Q_s(x, y; h)|_H \leq Ch^{-n-1} s^{-a} \mathbf{I}(|x-y| \leq ch) .$$

The difference with \tilde{Q} lies simply in the fact that in the ℓ^2 -coordinates k of (A.8) we have to distinguish two ranges: range-1 = $[2^k < sh]$ and range 2 = $[sh < 2^k < h]$.

For the first range the same argument as for $\tilde{\mathbf{Q}}$ works and nothing changes. For range 2 we simply use the fact that the cardinality of range 2 is $\sim 1 + |\log s|$ and estimate separately each individual coordinate. We shall omit the details which are similar to what was done in Section 4.3 and Section 5.4.

It is clear now that in the proof of the lemma we have room to absorb the logarithms. The conclusion is therefore that the lemma holds verbatim for the vector valued kernels $\tilde{\mathbf{Q}}$ and \mathbf{Q}_s .

A.3. (Interpolation)

The interpolation that we used in the proof of Appendix 2 Lemma (iii) says this: Let T be a linear operator and assume that:

$$\begin{aligned} T : D_\infty &\longrightarrow BMO(\ell^2) \text{ with norm } \|T\|_{(\infty)} ; \\ T : D_2 &\longrightarrow L^2(\ell^2) \text{ with norm } \|T\|_{(2)} , \end{aligned} \tag{A.9}$$

then

$$\begin{aligned} T : D_p &\longrightarrow L^p(\ell^2) ; \frac{1}{p} = \frac{\theta}{2}, \quad 0 < \theta < 1 , \\ \text{with norm } \|T\|_{(p)} &\leq C_\theta \|T\|_{(2)}^\theta \|T\|_{(\infty)}^{1-\theta} . \end{aligned} \tag{A.10}$$

One way to see this is to use K -real interpolation and use the facts

$$D_p \subset [D_\infty, D_2]_{\theta,p} ; [BMO(\ell^2), L^2(\ell^2)]_{\theta,p} \subset L^p(\ell^2) . \tag{A.11}$$

The proof of the first fact in (A.11) has been spelled out in [7, Appendix]. This proof follows standard lines anyway.

For the second fact in (A.11) one can use duality and reduce it to vector valued Hardy spaces (cf. O. Blasco & Q. Xu: J. of Func. Analysis 102 (1991) pages 191-194) and prove the fact:

$$L^p(\ell^2) \subset [L^2(\ell^2), H^1(\ell^2)]_{p,\theta} . \tag{A.12}$$

For the proof of (A.12) we can use the same proof as for the scalar case:

P. Jones: The “Zygmund Conference” Wadworth 1981.

J. Peetre: Studia Math. T. LXI, 1979 pages 191–194.

The duality and the use of the H^1 -spaces has been avoided by J.-L. Journé (L.N.M. No. 994, Springer, page 40). Journé uses directly the sharp function in a very analogous context. With the same method we can deduce directly from (A.9) that $D_p \longrightarrow L_{p,\infty}(\ell^2)$ is bounded. From this a slightly weaker version of (A.10) follows. This is sufficient for Lemma (iii) in Appendix 2.

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