JUNCTION OF ELASTIC PLATES AND BEAMS

ANTONIO GAUDIELLO¹, RÉGIS MONNEAU², JACQUELINE MOSSINO³,
FRANÇOIS MURAT⁴ AND ALI SILI⁵

Abstract. We consider the linearized elasticity system in a multidomain of $\mathbb{R}^3$. This multidomain is the union of a horizontal plate with fixed cross section and small thickness $\varepsilon$, and of a vertical beam with fixed height and small cross section of radius $r^\varepsilon$. The lateral boundary of the plate and the top of the beam are assumed to be clamped. When $\varepsilon$ and $r^\varepsilon$ tend to zero simultaneously, with $r^\varepsilon \gg \varepsilon^2$, we identify the limit problem. This limit problem involves six junction conditions.

Mathematics Subject Classification. 35B40, 74B05, 74K30.

Received July 14, 2005.

1. Introduction

Let $\omega^a$ and $\omega^b$ (a for “above”, b for “below”) be two bounded regular domains in $\mathbb{R}^2$. In the whole paper, the origin and axes are chosen so that:

$$
\int_{\omega^a} x_1 \, dx_1 \, dx_2 = \int_{\omega^b} x_2 \, dx_1 \, dx_2 = \int_{\omega^a} x_1 x_2 \, dx_1 \, dx_2 = 0 \quad \text{and} \quad 0 \in \omega^b. \tag{1.1}
$$

Let $\varepsilon$ be a parameter taking values in a sequence of positive numbers converging to zero, and let $r^\varepsilon$ be another positive parameter tending to zero with $\varepsilon$. We introduce the thin multidomain $\Omega^\varepsilon = \Omega^a \cup J^\varepsilon \cup \Omega^b$, where $\Omega^a = r^\varepsilon \omega^a \times (0,1)$ represents a vertical beam with fixed height and small cross section, $\Omega^b = \omega^b \times (-\varepsilon,0)$ represents a horizontal plate with small thickness and fixed cross section, and $J^\varepsilon = r^\varepsilon \omega^a \times \{0\}$ represents the interface at the junction between the beam and the plate.

Keywords and phrases. Junctions, thin structures, plates, beams, linear elasticity, asymptotic analysis.

Partial support of the first author by MURST 40% and by MURST 60% (Italy).

1 Dipartimento di Automazione, Elettromagnetismo, Ingegneria dell’Informazione e Matematica Industriale, Università di Cassino, via G. Di Biasio 43, 03043 Cassino (FR), Italia; gaudiello@unina.it
2 CERMICS, École Nationale des Ponts et Chaussées, 6 et 8 Avenue Blaise Pascal, Cité Descartes, 77455 Champs-sur-Marne Cedex 2, France; monneau@cermics.enpc.fr
3 CMLA, École Normale Supérieure de Cachan, 61 Avenue du Président Wilson, 94235 Cachan Cedex, France; mossino@cmla.ens-cachan.fr
4 Laboratoire Jacques-Louis Lions, Université Pierre et Marie Curie, Boîte courrier 187, 75252 Paris Cedex 05, France; murat@ann.jussieu.fr
5 Département de Mathématiques, Université de Toulon et du Var, BP 132, 83957 La Garde Cedex, France; sili@univ-tln.fr

© EDP Sciences, SMAI 2007

Article published by EDP Sciences and available at http://www.esaim-cocv.org or http://dx.doi.org/10.1051/cocv:2007036
In this thin multidomain, we consider the displacement \( \mathbf{U}^\varepsilon \), solution of the three-dimensional linearized elasticity system:

\[
\begin{align*}
\mathbf{U}^\varepsilon & \in Y^\varepsilon \quad \text{and} \quad \forall U \in Y^\varepsilon, \\
\int_{\Omega^\varepsilon} \left[ A^\varepsilon \mathbf{e} \left( \nabla \mathbf{U} \right), \mathbf{e}(U) \right] \, dx = \int_{\Omega^\varepsilon} F^\varepsilon \cdot U \, dx + \int_{\Omega^\varepsilon} \left[ G^\varepsilon, \mathbf{e}(U) \right] \, dx + \int_{\Sigma^{ae} \cup T^{bc} \cup B^{bc}} H^\varepsilon \cdot U \, d\sigma,
\end{align*}
\]

(1.2)

where:

- \( Y^\varepsilon = \{ U \in (H^1(\Omega^\varepsilon))^3, U = 0 \text{ on } T^{ae} = \varepsilon \omega^a \times \{ 1 \} \text{ and on } \Sigma^{bc} = \partial \omega^b \times (-\varepsilon, 0) \} \),

- \( A^\varepsilon = A^\varepsilon(x) = \begin{cases} A^a, & \text{if } x \in \Omega^{ae}, \\ k^\varepsilon A^b, & \text{if } x \in \Omega^{bc}, \end{cases} \)

with \( k^\varepsilon \) a positive parameter depending on \( \varepsilon \) and \( A^a, A^b \) tensors with constant coefficients \( A^a_{ijkl} \) and \( A^b_{ijkl} \), \( i, j, k, l \in \{ 1, 2, 3 \} \), satisfying the usual symmetry and coercivity conditions:

\[
A^a_{ijkl} = A^a_{jikl} = A^b_{ijkl}, \quad A^b_{ijkl} = A^b_{jikl} = A^b_{ijkl},
\]

\[
\exists C > 0, \forall \xi \in \mathbb{R}^{3 \times 3}_3, \left[ A^a \xi, \xi \right] \geq C|\xi|^2, \left[ A^b \xi, \xi \right] \geq C|\xi|^2,
\]

where \( \mathbb{R}^{3 \times 3}_3 \) denotes the set of symmetric \( 3 \times 3 \)-matrices, \( (A^a \xi)_{ij} = \sum_{kl} A^a_{ijkl} \xi_{kl} \), the scalar product \([,] \) in \( \mathbb{R}^{3 \times 3}_3 \) is defined by \([\eta, \xi] = \sum_{ij} \eta_i \xi_{ij} \) and \(|.|\) is the associated norm; the euclidian scalar product in \( \mathbb{R}^3 \) is denoted by a dot;

- \( e_{ij}(U) = \frac{1}{2} \left( \frac{\partial U_i}{\partial x_j} + \frac{\partial U_j}{\partial x_i} \right) \),

- \( F^\varepsilon \in (L^2(\Omega^\varepsilon))^3 \),

- \( G^\varepsilon \in (L^2(\Omega^\varepsilon))^{3 \times 3} \),

- \( H^\varepsilon \in (L^2(\Sigma^{ae} \cup T^{bc} \cup B^{bc}))^3 \), where \( \Sigma^{ae} \) denotes the lateral boundary of the beam, \( T^{bc} \) and \( B^{bc} \) are respectively the top and the bottom of the plate:

\[
\Sigma^{ae} = \varepsilon \partial \omega^a \times (0,1), \quad T^{bc} = (\omega^b \setminus \varepsilon \omega^a) \times \{ 0 \}, \quad B^{bc} = \omega^b \times \{ -\varepsilon \}.
\]

The constraint "\( U = 0 \)" in the definition of \( Y^\varepsilon \) means that the multistructure is clamped on the top \( T^{ae} \) of the beam and on the lateral boundary \( \Sigma^{bc} \) of the plate. The case \( k^\varepsilon \) tending to zero or infinity corresponds to very different materials in \( \Omega^{ae} \) and \( \Omega^{bc} \) (note that breaking the symmetry between \( \Omega^{ae} \) and \( \Omega^{bc} \) by introducing the coefficient \( k^\varepsilon \) in front of \( A^b \) is not restrictive). In the right-hand side of (1.2), the second term is written in divergence form like in [15,27,28]. It is well known that, by means of the Green formula, this second term can contribute to the other ones, giving possibly less regular (not necessarily \( L^2 \)) volume and surface source terms. For convenience of the reader, we have chosen to write the three integrals: one recovers the classical formulation by setting \( G^\varepsilon = 0 \), but the simplest case corresponds to \( F^\varepsilon = 0, H^\varepsilon = 0 \) and \( G^\varepsilon \neq 0 \). This case was considered in the short preliminary version [15].

Problem (1.2) admits a unique solution \( \mathbf{U}^\varepsilon \) (see e.g. [29]). The aim of this paper is to describe the limit behaviour of the displacement \( \mathbf{U}^\varepsilon \), as \( \varepsilon \) tends to zero. We prove that this behaviour depends on the limit of the sequence \( q^\varepsilon \) defined by:

\[
q^\varepsilon = k^\varepsilon \frac{\varepsilon^3}{(\varepsilon^3)^2}.
\]
When $k^2 \varepsilon^3$ and $(r^2)^2$ have same order (i.e. when $q^2$ tends to $q$ with $0 < q < +\infty$), the limit problem (obtained after suitable rescaling) is a coupled problem between a two-dimensional plate and a one-dimensional beam, with six junction conditions. If $k^2 \varepsilon^3 \gg (r^2)^2$, the multistructure has the limit behaviour of a thin rigid plate and a thin elastic plate which are independent of each other, the beam being clamped at both ends; on the contrary, if $k^2 \varepsilon^3 \ll (r^2)^2$, the structure behaves as a thin rigid beam and a thin elastic plate which are independent of each other, the plate being clamped on its contour and fixed vertically at the junction.

The reader is referred to [1,3,4,6–8,10–12,21–23,25–28,30,31] for the derivation of the equations of plates and beams by asymptotic analysis. Junction problems are considered in [5,9,13,14,16–20]. The present work is a natural follow up of [27,28], which deal with reduction of dimension for elastic thin cylinders, and of [13,14], which deal with the diffusion equation in the thin multistructure considered in this paper. Our results were announced in the short note [15].

2. The result

2.1. The rescaled problem

In the sequel, the indexes $\alpha$ and $\beta$ take values in the set $\{1,2\}$. Moreover, $x = (x', x_3)$ denotes the generic point in $\mathbb{R}^3$.

Let $\Omega^a = \omega^a \times (0,1)$, $\Omega^b = \omega^b \times (-1,0)$, $T^a = \omega^a \times \{1\}$, $\Sigma^a = \partial \omega^a \times (0,1)$ and $\Sigma^b = \partial \omega^b \times (-1,0)$. The asymptotic behaviour of $u^\varepsilon$ can be described by using a convenient rescaling (the reader is referred to Sect. 3.1 for details). This rescaling maps the space $\mathcal{Y}^\varepsilon$ onto the space $\mathcal{Y}$ defined by:

$$\mathcal{Y}^\varepsilon = \left\{ u = (u^a, u^b) \in (H^1(\Omega^a))^3 \times (H^1(\Omega^b))^3, \quad u^a = 0 \text{ on } T^a, u^b = 0 \text{ on } \Sigma^b, \quad u^a_0(x',0) = \varepsilon r^a u^a_0(r^a x',0) \text{ and } u^a_0(x',0) = u^b_0(r^a x',0), \text{ for a.e. } x' \in \omega^a \right\}.$$ (2.1)

In particular, we denote by $\overline{u} = (\overline{u}^a, \overline{u}^b)$ the rescaling of the solution $u^\varepsilon$ of problem (1.2). We set

$$e^{\alpha \varepsilon}(u^a) = \begin{pmatrix} \frac{1}{(r^2)^2}e_{\alpha \beta}(u^a) & \frac{1}{\varepsilon^2}e_{\alpha \lambda}(u^a) \\ \frac{1}{\varepsilon}e_{\lambda \alpha}(u^a) & e_{33}(u^a) \end{pmatrix}, \quad e^{\beta \varepsilon}(u^b) = \begin{pmatrix} e_{\alpha \beta}(u^b) & \frac{1}{\varepsilon}e_{\alpha \lambda}(u^b) \\ \frac{1}{\varepsilon^2}e_{33}(u^b) \end{pmatrix}. \quad (2.2)$$

Then $\overline{u}$ is the unique solution of the following problem:

$$\begin{aligned}
\int_{\Omega^a} [A^a e^{\alpha \varepsilon} (\overline{u}^a), e^{\alpha \varepsilon}(u^a)] \, dx + q^\varepsilon \int_{\Omega^b} [A^b e^{\beta \varepsilon} (\overline{u}^b), e^{\beta \varepsilon}(u^b)] \, dx \\
= \int_{\Omega^a} f^{a \varepsilon} u^a \, dx + \int_{\Omega^a} f^{b \varepsilon} u^b \, dx + \int_{\Omega^a} [g^{a \varepsilon}(u^a)] \, dx + \int_{\Omega^b} [g^{b \varepsilon}, e^{\beta \varepsilon}(u^b)] \, dx \\
+ \int_{\Sigma^a} h^{a \varepsilon} u^a \, d\sigma + \int_{\omega^a} \left( h^b_{\varepsilon}, u^b \right)_{x_3 = 0} + h^b_{\varepsilon}, u^b \right)_{x_3 = -1} \, dx',
\end{aligned} \quad (2.3)$$

where $q^\varepsilon$ is defined by:

$$q^\varepsilon = k^2 \frac{\varepsilon^3}{(r^2)^2}, \quad (2.4)$$

and where the source terms are suitable transforms of $(F^\varepsilon, G^\varepsilon, H^\varepsilon)$ (see Sect. 3.1).
2.2. The setting of the limit problem

For the definition of the limit problem, we introduce the following functional spaces:

\[ U^a = \left\{ u^a \in (H^2_0(0, 1))^2 \times H^1(\Omega^a), \exists \zeta^a \in H^1(0, 1), \zeta^a(1) = 0, u^a_3 = \zeta^a - x_1 \frac{d u^a_1}{dx_3} - x_2 \frac{d u^a_2}{dx_3} \right\}, \]

\[ V^a = \left\{ v^a \in (H^1(\Omega^a))^2 \times L^2(0, 1; H^1(\omega^a)), \exists c \in H^1_0(0, 1), v^a = -c x_2, v^a_2 = c x_1, \right\}, \]

\[ \mathcal{W}^a = \left\{ w^a \in (L^2(0, 1; H^1(\omega^a)))^2 \times \{0\}, \int_{\omega^a} w^a_0 dx' = \int_{\omega^a} (x_1 w^a_2 - x_2 w^a_3) dx' = 0, \text{ for a.e. } x_3 \in (0, 1) \right\}, \]

\[ \mathcal{U}^b = \left\{ u^b \in (H^1(\Omega^b))^2 \times H^2_0(\omega^b), \exists \zeta^b \in H^1_0(\omega^b), u^b_3 = \zeta^b - x_1 \frac{\partial u^b_1}{\partial x_3} \right\}, \]

\[ \mathcal{V}^b = \left\{ v^b \in (L^2(\omega^b; H^1(-1, 0)))^2 \times \{0\}, \int_{-1}^{0} v^b_1(x', x_3) dx_3 = 0, \text{ for a.e. } x' \in \omega^b \right\}, \]

\[ \mathcal{W}^b = \left\{ w^b \in (\{0\})^2 \times L^2(\omega^b; H^1(-1, 0)), \int_{-1}^{0} w^b_1(x', x_3) dx_3 = 0, \text{ for a.e. } x' \in \omega^b \right\}, \]

\[ Z^a = U^a \times V^a \times \mathcal{W}^a, \quad Z^b = U^b \times V^b \times \mathcal{W}^b. \]

Without loss of generality, we assume that \( q^* \) defined by (2.4) satisfies:

\[ q^* \rightarrow q, \quad \text{with } 0 \leq q \leq +\infty. \]  \hspace{1cm} (2.5)

According to the value of \( q \), the functional space for the limit problem is the following one:

\[ Z = \{ z = (z^a, z^b) = ((u^a, v^a, w^a), (u^b, v^b, w^b)) \in Z^a \times Z^b, u^a_3(x', 0) = u^b_3(0), \text{ for a.e. } x' \in \omega^a \}, \]

\[ Z_{\infty} = \{ z = (u^a, v^a, w^a) \in Z^a, u^a_3(x', 0) = 0, \text{ for a.e. } x' \in \omega^a \}, \quad \text{if } q = +\infty, \]

\[ Z_0 = \{ z = (u^b, v^b, w^b) \in Z^b, u^b_3(0) = 0 \}, \quad \text{if } q = 0. \]

Let us observe that \( U^a \) (resp. \( U^b \)) is a Bernoulli-Navier (resp. Kirchhoff-Love) space of displacements. Less classical spaces are \( V^a, \mathcal{W}^a, V^b, \mathcal{W}^b \), which are introduced in a way similar to [27, 28] (see also App., Sect. 8.1).

As for the boundary conditions, some of them are due to the clamping. These are more or less standard ones:

\[ u^a_3(1) = \frac{\partial u^a_1}{\partial x_3}(1) = c(1) = 0, \quad u^b_3(0) = 0 \quad \text{and} \quad \frac{\partial u^b_1}{\partial x_3} = 0 \quad \text{on } \partial \omega^b. \]

In contrast with the other requirements, the six conditions:

\[ u^a_3(0) = \frac{\partial u^a_1}{\partial x_3}(0) = c(0) = 0, \quad u^b_3(x', 0) = u^b_3(0) \quad (\text{respectively } u^a_3(x', 0) = 0 \text{ or } u^b_3(0) = 0), \]

which appear in the definition of the above spaces \( U^a, V^a \) and \( Z \) (respectively \( Z_{\infty} \) or \( Z_0 \)), are specific to the junction between the beam and the plate. Note also that, in view of the definition of \( U^a \), the condition \( u^a_3(x', 0) = u^b_3(0) \) (respectively \( u^a_3(x', 0) = 0 \) or \( u^b_3(0) = 0 \)) reduces to \( \zeta^a(0) = u^b_3(0) \) (respectively \( \zeta^a(0) = 0 \)).
We finally introduce, for \( za = (u^a, v^a, w^a) \) in \( Z^a \) and \( zb = (u^b, v^b, w^b) \) in \( Z^b \):

\[
e^a(z^a) = \begin{pmatrix}
e_{a3}(w^a) & e_{a3}(v^a) \\
e_{a3}(u^a) & e_{a3}(w^a)
\end{pmatrix},
\]

\[
e^b(z^b) = \begin{pmatrix}
e_{a3}(w^b) & e_{a3}(v^b) \\
e_{a3}(u^b) & e_{a3}(w^b)
\end{pmatrix}.
\]

(2.6)

2.3. The main result

We describe the limit behaviour of problem (2.3), as \( \varepsilon \) tends to zero. In the sequel, we assume that

\[
f^{ae} \rightharpoonup f^a \text{ weakly in } (L^2(\Omega^a))^3,
\]

(2.7)

\[
f^{be} \rightharpoonup f^b \text{ weakly in } (L^2(\Omega^b))^3,
\]

(2.8)

\[
g^{ae} \rightharpoonup g^a \text{ weakly in } (L^2(\Omega^a))^{3 \times 3},
\]

(2.9)

\[
g^{be} \rightharpoonup g^b \text{ weakly in } (L^2(\Omega^b))^{3 \times 3},
\]

(2.10)

\[
h^{ae} \rightharpoonup h^a \text{ weakly in } (L^2(\Sigma^a))^3,
\]

(2.11)

\[
h^{be} \rightharpoonup h^b \text{ weakly in } (L^2(\omega^b))^3,
\]

(2.12)

which is not restrictive, as proved in Remark 4 below.

Our main result is the following one:

**Theorem 1.** Assume that \( \frac{\varepsilon}{\varepsilon^z} \) tends to \(+\infty\) and that (2.5), (2.7) to (2.12) hold true. Then, with the notation \( e^{ae}, e^{be} \) defined in (2.2) and \( e^a, e^b \) defined in (2.6), one has:

(i) If \( 0 < q < +\infty \), there exists \( \Xi = (\Xi^a, \Xi^b) = ((\Xi^a, \Xi^3, \Xi^3), (\Xi^a, \Xi^a, \Xi^3)) \in Z \) such that:

\[
(\Xi^{ae}, \Xi^{be}) \rightharpoonup (\Xi^a, \Xi^b) \text{ weakly in } (H^1(\Omega^a))^3 \times (H^1(\Omega^b))^3,
\]

(2.13)

\[
(e^{ae}(\Xi^{ae}), e^{be}(\Xi^{be})) \rightharpoonup (e^a(\Xi^a), e^b(\Xi^b)) \text{ weakly in } (L^2(\Omega^a))^{3 \times 3} \times (L^2(\Omega^b))^{3 \times 3},
\]

(2.14)

and \( \Xi \) is the unique solution of the following problem:

\[
\begin{cases}
\Xi \in Z \text{ and } \forall z \in Z, \\
\int_{\Omega^a} [A^a e^{a}(\Xi^a), e^{a}(z^a)] dx + q \int_{\Omega^b} [A^b e^{b}(\Xi^b), e^{b}(z^b)] dx \\
= \int_{\Omega^a} f^a \cdot u^a dx + \int_{\Omega^b} f^b \cdot u^b dx + \int_{\Omega^a} [g^a, e^{a}(z^a)] dx + \int_{\Omega^b} [g^b, e^{b}(z^b)] dx \\
+ \int_{\Sigma^a} h^a \cdot u^a d\sigma + \int_{\Sigma^b} h^b \cdot u^b_{|\Sigma^a=0} + h^b \cdot u^b_{|\Sigma^b=1} dx'.
\end{cases}
\]

(2.15)

Moreover, if the convergences in (2.9), (2.10) are strong, then the convergences in (2.13) and (2.14) are strong.
If $q = +\infty$, there exists $z^a = (u^a, v^a, w^a) \in \mathcal{Z}_\infty$ such that:
\begin{equation}
\bar{\pi}^{ae} \rightharpoonup \bar{\pi}^a \text{ weakly in } (H^1(\Omega^a))^3, \quad \bar{\pi}^{be} \rightarrow 0 \text{ strongly in } (H^1(\Omega^b))^3,
\end{equation}
\begin{equation}
e^{ae}(\bar{\pi}^{ae}) \rightharpoonup e^a(\bar{\pi}^a) \text{ weakly in } (L^2(\Omega^a))^{3 \times 3}, \quad e^{be}(\bar{\pi}^{be}) \rightarrow 0 \text{ strongly in } (L^2(\Omega^b))^{3 \times 3},
\end{equation}
and $z^a$ is the unique solution of the following problem:
\begin{equation}
\begin{cases}
z^a \in \mathcal{Z}_\infty \text{ and } \forall \varepsilon^a \in \mathcal{Z}_\infty, \\
\iiint_{\Omega^a} [A^a e^{\alpha}(\bar{\pi}^a), e^{\alpha}(z^a)] \, dx = \iiint_{\Omega^a} \sigma^a, u^a \, dx + \iiint_{\Omega^a} [g^a, e^{\alpha}(z^a)] \, dx + \iiint_{\Sigma^a} h^a, u^a \, d\sigma.
\end{cases}
\end{equation}
Moreover, if the convergence in (2.9) is strong, then:
\begin{equation}
\bar{\pi}^{ae} \rightarrow \bar{\pi}^a \text{ strongly in } (H^1(\Omega^a))^3,
\end{equation}
\begin{equation}
e^{ae}(\bar{\pi}^{ae}) \rightarrow e^a(\bar{\pi}^a) \text{ strongly in } (L^2(\Omega^a))^{3 \times 3}, \quad \sqrt{\sigma^a} e^{be}(\bar{\pi}^{be}) \rightarrow 0 \text{ strongly in } (L^2(\Omega^b))^{3 \times 3}.
\end{equation}

If $q = 0$, there exists $z^b = (u^b, v^b, w^b) \in \mathcal{Z}_0$ such that:
\begin{equation}
 q^e \bar{\pi}^{ae} \rightarrow 0 \text{ strongly in } (H^1(\Omega^a))^3, \quad q^e \bar{\pi}^{be} \rightharpoonup \bar{\pi}^b \text{ weakly in } (H^1(\Omega^b))^3,
\end{equation}
\begin{equation}
 q^e e^{ae}(\bar{\pi}^{ae}) \rightarrow 0 \text{ strongly in } (L^2(\Omega^a))^{3 \times 3}, \quad q^e e^{be}(\bar{\pi}^{be}) \rightharpoonup e^b(\bar{\pi}^b) \text{ weakly in } (L^2(\Omega^b))^{3 \times 3},
\end{equation}
and $z^b$ is the unique solution of the following problem:
\begin{equation}
\begin{cases}
z^b \in \mathcal{Z}_0 \text{ and } \forall \varepsilon^b \in \mathcal{Z}_0, \\
\iiint_{\Omega^b} [A^b e^{\alpha}(\bar{\pi}^b), e^{\alpha}(z^b)] \, dx = \iiint_{\Omega^b} \sigma^b, u^b \, dx + \iiint_{\Omega^b} [g^b, e^{\alpha}(z^b)] \, dx + \iiint_{\Sigma^b} h^b, u^b \, d\sigma.
\end{cases}
\end{equation}
Moreover, if the convergence in (2.10) is strong, then:
\begin{equation}
 q^e \bar{\pi}^{be} \rightarrow \bar{\pi}^b \text{ strongly in } (H^1(\Omega^b))^3,
\end{equation}
\begin{equation}
\sqrt{\sigma^b} e^{ae}(\bar{\pi}^{ae}) \rightarrow 0 \text{ strongly in } (L^2(\Omega^b))^{3 \times 3}, \quad q^e e^{be}(\bar{\pi}^{be}) \rightarrow e^b(\bar{\pi}^b) \text{ strongly in } (L^2(\Omega^b))^{3 \times 3}.
\end{equation}

Remark 1. The condition that $\frac{r^e}{\varepsilon^e}$ tends to $+\infty$ is only used to prove that $\bar{\pi}^e(x', 0) = \bar{\pi}^e_0(0)$ and $\bar{\pi}(0) = 0$ (via a convenient Sobolev embedding theorem, as regards the second equality). We do not know if it is just a technical condition or not.

Remark 2. In the Appendix (Sect. 8.1) we prove that the functions $\bar{\pi}^a$ and $\bar{\pi}^b$ (resp. $\bar{\pi}^a$ and $\bar{\pi}^b$) which appear in the limit problem are the limits of suitable expressions of $\bar{\pi}^{ae}$ (resp. $\bar{\pi}^{be}$).
2.4. Back to the problem in the thin multidomain

As far as the asymptotic behaviour of the “energy” of the solution of problem (1.2) in the thin multidomain is concerned, we define the following renormalized energy by:

$$\mathcal{E}^\varepsilon = \left(\frac{\lambda^\varepsilon}{r^\varepsilon}\right)^2 \int_{\Omega} [A^\varepsilon e(\overline{U}^\varepsilon), e(\overline{U}^\varepsilon)] \, dx,$$

(2.26)

where $\lambda^\varepsilon$ can be made explicit in terms of $\varepsilon, r^\varepsilon, F^\varepsilon, G^\varepsilon, H^\varepsilon$ (see (3.2) in Sect. 3.1); we also have:

$$\mathcal{E}^\varepsilon = \int_{\Omega^a} [A^a e^{ae}(\overline{u}^a), e^{ae}(\overline{u}^a)] \, dx + q^\varepsilon \int_{\Omega^b} [A^b e^{be}(\overline{u}^b), e^{be}(\overline{u}^b)] \, dx,$$

and from Theorem 1 we deduce the following corollary:

**Corollary 1.** Assume that $r^\varepsilon / \varepsilon^2$ tends to $+\infty$ and that (2.5), (2.7) to (2.12) hold true.

(i) If $0 < q < +\infty$ and if the convergences in (2.9), (2.10) are strong, then:

$$\mathcal{E}^\varepsilon \to \mathcal{E} = \int_{\Omega^a} [A^a e^a(\overline{u}^a), e^a(\overline{u}^a)] \, dx + q \int_{\Omega^b} [A^b e^b(\overline{u}^b), e^b(\overline{u}^b)] \, dx.$$

(ii) If $q = +\infty$ and if the convergence in (2.9) is strong, then:

$$\mathcal{E}^\varepsilon \to \mathcal{E}_{\infty} = \int_{\Omega^a} [A^a e^a(\overline{u}^a), e^a(\overline{u}^a)] \, dx.$$

(iii) If $q = 0$ and if the convergence in (2.10) is strong, then:

$$q^\varepsilon \mathcal{E}^\varepsilon \to \mathcal{E}_0 = \int_{\Omega^b} [A^b e^b(\overline{u}^b), e^b(\overline{u}^b)] \, dx.$$

Actually, the proof of Corollary 1 is part of proof of Theorem 1, since the strong convergences of $\overline{w}^{ae}$ to $\overline{w}$ (resp. $\overline{w}^{be}$ to $\overline{w}$) and $e^{ae}(\overline{w}^{ae})$ to $e^a(\overline{w})$ (resp. $e^{be}(\overline{w}^{be})$ to $e^b(\overline{w})$) follow from the convergence of the energy $\mathcal{E}^\varepsilon$. The following interpretation is a direct consequence of the strong convergences of $e^{ae}(\overline{w}^{ae})$ and $e^{be}(\overline{w}^{be})$.

**Interpretation.** For example, let us consider the particular case of problem (1.2), for which $G^\varepsilon = 0$, $H^\varepsilon = 0$, $k^\varepsilon = 1$ and $A^a = A^b = A$:

$$\begin{align*}
\overline{U}^\varepsilon &\in Y^\varepsilon \quad \text{and} \quad \forall U \in Y^\varepsilon, \\
\int_{\Omega^a} [A e(\overline{U}^\varepsilon), e(U)] \, dx &\to \int_{\Omega^a} F^\varepsilon. U \, dx,
\end{align*}$$

and let us assume that $r^\varepsilon = \varepsilon^{3/2}$ and that:

$$\frac{1}{\varepsilon^2} \sum_{\alpha} \|F^\varepsilon_{\alpha}\|^2_{L^2(\Omega^\varepsilon)} + \frac{1}{\varepsilon^2} \sum_{\alpha} \|F^\varepsilon_{\alpha}\|^2_{L^2(\Omega^\varepsilon)} + \frac{1}{\varepsilon^2} \sum_{\alpha} \|F^\varepsilon_{\alpha}\|^2_{L^2(\Omega^\varepsilon)} + \frac{1}{\varepsilon^2} \sum_{\alpha} \|F^\varepsilon_{\alpha}\|^2_{L^2(\Omega^\varepsilon)} = 1. \quad (2.27)$$
This last condition is not restrictive, since it is just a matter of normalization. One can observe that, in this case, the parameter $\lambda^2$ introduced in (3.2), in Section 3.1, has value $\epsilon^{-3/2}$. Defining the rescaled force and the rescaled solution by:

$$f^{a\epsilon}_\alpha(x) = \frac{1}{\epsilon^3} F^{a\epsilon}_\alpha(\frac{x'}{\epsilon}, x_3), \quad f^{a\epsilon}_\beta(x) = \frac{1}{\epsilon^3} F^{a\epsilon}_\beta(\frac{x'}{\epsilon}, x_3), \quad \text{for } x \in \Omega^a,$$

$$f^{b\epsilon}_\alpha(x) = \frac{1}{\epsilon^3} F^{b\epsilon}_\alpha(x', \epsilon x_3), \quad f^{b\epsilon}_\beta(x) = \frac{1}{\epsilon^3} F^{b\epsilon}_\beta(x', \epsilon x_3), \quad \text{for } x \in \Omega^b,$$

$$\overline{\Pi}^{\epsilon}_\alpha(x) = \overline{\Pi}^{\epsilon}_\alpha(\frac{x'}{\epsilon}, x_3), \quad \overline{\Pi}^{\epsilon}_\beta(x) = \frac{1}{\epsilon^3} \overline{\Pi}^{\epsilon}_\beta(x', \epsilon x_3), \quad \text{for } x \in \Omega^a,$$

$$\overline{\Pi}^{\epsilon}_\alpha(x) = \frac{1}{\epsilon^3} \overline{\Pi}^{\epsilon}_\alpha(x', \epsilon x_3), \quad \overline{\Pi}^{\epsilon}_\beta(x) = \frac{1}{\epsilon^3} \overline{\Pi}^{\epsilon}_\beta(x', \epsilon x_3), \quad \text{for } x \in \Omega^b,$$

one can check that $\overline{\Pi}^{\epsilon}$ solves the rescaled problem:

$$\begin{cases}
\overline{\Pi}^{\epsilon} \in Y^\epsilon \text{ and } \forall u \in Y^\epsilon,
\int_{\Omega^a} [A^{a\epsilon}(\overline{\Pi}^{\epsilon}), e^{a\epsilon}(u^\alpha)] \, dx + \int_{\Omega^b} [A^{b\epsilon}(\overline{\Pi}^{\epsilon}), e^{b\epsilon}(u^\beta)] \, dx = \int_{\Omega^a} f^{a\epsilon} \cdot u^\alpha \, dx + \int_{\Omega^b} f^{b\epsilon} \cdot u^\beta \, dx.
\end{cases}$$

Since, thanks to (2.27),

$$\int_{\Omega^a} |f^{a\epsilon}|^2 \, dx + \int_{\Omega^b} |f^{b\epsilon}|^2 \, dx = 1,$$

it is not restrictive to assume that, for some subsequence of $\epsilon$, still denoted by $\epsilon$, and for some $f^a$ in $L^2(\Omega^a)$ and $f^b$ in $L^2(\Omega^b)$:

$$f^{a\epsilon} \to f^a \text{ in } L^2(\Omega^a) \text{ and } f^{b\epsilon} \to f^b \text{ in } L^2(\Omega^b).$$

Then, Theorem 1 asserts that:

$$\overline{\Pi}^{a\epsilon} \to \overline{\Pi}^a \text{ strongly in } (H^1(\Omega^a))^3 \text{ and } \overline{\Pi}^{b\epsilon} \to \overline{\Pi}^b \text{ strongly in } (H^1(\Omega^b))^3, \quad (2.28)$$

$$e^{a\epsilon}(\overline{\Pi}^{a\epsilon}) \to e^a(\overline{\Pi}^a) \text{ strongly in } (L^2(\Omega^a))^{3 \times 3} \text{ and } e^{b\epsilon}(\overline{\Pi}^{b\epsilon}) \to e^b(\overline{\Pi}^b) \text{ strongly in } (L^2(\Omega^b))^{3 \times 3}, \quad (2.29)$$

where $\overline{\Pi}^a = e^a(\overline{\Pi}^a)$, $\overline{\Pi}^b = e^b(\overline{\Pi}^b)$ and $\overline{\Pi} = (\overline{\Pi}^a, \overline{\Pi}^b)$ is the unique solution of the rescaled limit problem:

$$\begin{cases}
\overline{\Pi} \in Z \text{ and } \forall z \in Z, \\
\int_{\Omega^a} [A^a(\overline{\Pi}^a), e^a(z^a)] \, dx + \int_{\Omega^b} [A^b(\overline{\Pi}^b), e^b(z^b)] \, dx = \int_{\Omega^a} f^a \cdot u^a \, dx + \int_{\Omega^b} f^b \cdot u^b \, dx.
\end{cases} \quad (2.30)$$

Coming back to the initial domain, we define $\overline{E}^{a\epsilon}$ and $\overline{E}^{b\epsilon}$ by:

$$\overline{E}^{a\epsilon} = \epsilon^{\frac{1}{2}} \overline{\Pi}^{a\epsilon}\left(\frac{x'}{\epsilon}, x_3\right), \quad \text{for } x \in \Omega^{a\epsilon}, \quad \overline{E}^{a\epsilon} = \epsilon^{\frac{1}{2}} \overline{\Pi}^{a\epsilon}\left(\frac{x'}{\epsilon}, x_3\right), \quad \text{for } x \in \Omega^{b\epsilon},$$
and we define the relative errors $\Delta_{ae}$, $\Delta_{be}$ and $\Delta^\varepsilon$ by:

$$
\Delta_{ae} = \frac{\int_{\Omega^e} |e(U^e) - E^{ae}|^2 \, dx}{\int_{\Omega^e} |E^{ae}|^2 \, dx}, \quad \Delta_{be} = \frac{\int_{\Omega^b} |e(U^b) - E^{be}|^2 \, dx}{\int_{\Omega^b} |E^{be}|^2 \, dx},
$$

$$
\Delta^\varepsilon = \frac{\int_{\Omega^e} |e(U^e) - E^{ae}|^2 \, dx + \int_{\Omega^b} |e(U^b) - E^{be}|^2 \, dx}{\int_{\Omega^e} |E^{ae}|^2 \, dx + \int_{\Omega^b} |E^{be}|^2 \, dx}.
$$

Assuming that $\bar{v}^a \neq 0$ and $\bar{v}^b \neq 0$, an easy computation gives that:

$$
\Delta_{ae} = \frac{\int_{\Omega^e} |e^{ae}(\bar{v}^{ae}) - \bar{v}^{ae}|^2 \, dx}{\int_{\Omega^e} |\bar{v}^{ae}|^2 \, dx}, \quad \Delta_{be} = \frac{\int_{\Omega^b} |e^{be}(\bar{v}^{be}) - \bar{v}^{be}|^2 \, dx}{\int_{\Omega^b} |\bar{v}^{be}|^2 \, dx}.
$$

Hence the strong convergences in (2.29) imply that $\Delta_{ae}$, $\Delta_{be}$, and then $\Delta^\varepsilon$, tend to zero with $\varepsilon$. These convergences of the relative errors mean that the deformation of the original displacement is well described by $E^{ae}$ and $E^{be}$:

$$
e(U^e) \simeq E^{ae} \text{ in } \Omega^{ae}, \quad e(U^b) \simeq E^{be} \text{ in } \Omega^{be}.
$$

In the same spirit, from the solution $\bar{v} = (\bar{v}^a, \bar{v}^b) = ((\bar{v}^a, \bar{v}^a, \bar{v}^a), (\bar{v}^b, \bar{v}^b, \bar{v}^b))$ of problem (2.30), we are going to define $\bar{U}^{ae}$ and $\bar{U}^{be}$, which are good approximates of the restrictions of $U^e$ to $\Omega^{ae}$ and $\Omega^{be}$, respectively. Actually, let us set:

$$
\bar{u}^{ae} = \bar{v}^a + \varepsilon \bar{v}^a + (\varepsilon^2)\bar{v}^a = \bar{v}^a + \varepsilon \bar{v}^a + \varepsilon^3 \bar{v}^a,
$$

$$
\bar{u}^{be} = \bar{v}^b + \varepsilon \bar{v}^b + \varepsilon^2 \bar{v}^b,
$$

$$
\bar{U}^{ae}_\alpha(x) = \bar{u}^{ae}_\alpha \left( \frac{x'}{\varepsilon}, x_3 \right), \quad \bar{U}^{be}_\alpha(x) = \varepsilon^2 \bar{u}^{be}_\alpha \left( \frac{x'}{\varepsilon}, x_3 \right), \quad \text{for } x \in \Omega^{ae},
$$

$$
\bar{U}^{be}_\alpha(x) = \varepsilon^2 \bar{u}^{be}_\alpha \left( x', \frac{x_3}{\varepsilon} \right), \quad \bar{U}^{be}_\alpha(x) = \varepsilon^2 \bar{u}^{be}_\alpha \left( x', \frac{x_3}{\varepsilon} \right), \quad \text{for } x \in \Omega^{be}.
$$

Assuming that $(\bar{v}^a, \bar{v}^b)$ have $H^1$ regularity, and since:

$$
e^{ae}(\bar{u}^{ae}) = \bar{v}^a + \varepsilon \left( \begin{array}{cc} 0 & e_{03}(\bar{v}^a) \\ e_{33}(\bar{v}^a) & e_{33}(\bar{v}^a) \end{array} \right), \quad e^{be}(\bar{u}^{be}) = \bar{v}^b + \varepsilon \left( \begin{array}{cc} e_{03}(\bar{v}^b) & e_{03}(\bar{v}^b) \\ e_{33}(\bar{v}^b) & 0 \end{array} \right),
$$

it is clear that, as $\varepsilon$ tends to zero, $e^{ae}(\bar{u}^{ae})$ tends to $\bar{v}^a$ strongly in $(L^2(\Omega^a))^3 \times 3$ and that $e^{be}(\bar{u}^{be})$ tends to $\bar{v}^b$ strongly in $(L^2(\Omega^b))^3 \times 3$, and then, from (2.29), that:

$$
\int_{\Omega^a} |e^{ae}(\bar{u}^{ae} - \bar{u}^{ae})|^2 \, dx + \int_{\Omega^b} |e^{be}(\bar{u}^{be} - \bar{u}^{be})|^2 \, dx \to 0.
$$
As above, if $\pi^a \neq 0$ and $\pi^b \neq 0$, we get that:

$$\Delta^\alpha = \frac{\int_{\Omega^\alpha} |e(U - U^\alpha)|^2 \, dx}{\int_{\Omega^\alpha} |e(U^\alpha)|^2 \, dx} = \frac{\int_{\Omega} |e^{\alpha \varepsilon}(\pi^\alpha - u^\alpha)|^2 \, dx}{\int_{\Omega} |e^{\alpha \varepsilon}(u^\alpha)|^2 \, dx} \to 0,$$

$$\Delta^\beta = \frac{\int_{\Omega^\beta} |e(U - U^\beta)|^2 \, dx}{\int_{\Omega^\beta} |e(U^\beta)|^2 \, dx} = \frac{\int_{\Omega} |e^{\beta \varepsilon}(\pi^\beta - u^\beta)|^2 \, dx}{\int_{\Omega} |e^{\beta \varepsilon}(u^\beta)|^2 \, dx} \to 0,$$

$$\Delta^\varepsilon = \frac{\int_{\Omega^\alpha} |e(U - U^\varepsilon)|^2 \, dx + \int_{\Omega^\beta} |e(U - U^\varepsilon)|^2 \, dx}{\int_{\Omega^\alpha} |e(U^\alpha)|^2 \, dx + \int_{\Omega^\beta} |e(U^\beta)|^2 \, dx} \to 0.$$

At least formally, this means that:

$$U^\varepsilon \simeq U^\alpha \text{ in } \Omega^\alpha, \quad U^\varepsilon \simeq U^\beta \text{ in } \Omega^\beta. \quad (2.31)$$

Let us prove that, from the equivalence (2.31), one can recover heuristically the conditions at the junction. As a matter of fact, suppose we just know that:

$$\pi^\alpha_3 = \pi^\alpha_3(x_3), \quad \pi^\beta_3 = \pi^\beta_3(x_3) = x_1 \frac{\partial \pi^\alpha_3}{\partial x_3}(x_3) - x_2 \frac{\partial \pi^\beta_3}{\partial x_3}(x_3),$$

$$\pi^\alpha_3 = \pi(x_3) x^R_\alpha, \quad \text{that is } \pi^\alpha_3 = -\pi(x_3) x_2 \text{ and } \pi^\beta_3 \pi(x_3) x_1,$$

$$\pi_3 = 0,$$

$$\pi_3 = \pi_3(x'), \quad \pi_\alpha = \pi_\beta(x') - x_3 \frac{\partial \pi_3}{\partial x_\alpha}(x'),$$

$$\pi_3 = 0, \quad \pi_3 = 0.$$

From the above expressions of $\pi^\alpha, \pi^\beta$, we deduce that:

$$\begin{cases} 
\hat{U}^\alpha_\alpha(x', x_3) = \pi^\alpha_3(x_3) + \varepsilon \hat{\pi}(x_3) x_3^R + \varepsilon \hat{\pi}_3(x'), \quad \text{for } x \in \Omega^a, \\
\hat{U}^\alpha_\beta(x', x_3) = \varepsilon \hat{x} \left( \frac{\partial \pi^\alpha_3}{\partial x_\alpha}(x') - x_3 \frac{\partial \pi_\beta}{\partial x_\alpha}(x') + \varepsilon \hat{\pi}_3(x') + \varepsilon^2 \cdot 0 \right), \quad \text{for } x \in \Omega^b.
\end{cases} \quad (2.32)$$

$$\begin{cases} 
\hat{U}^\varepsilon_\alpha(x', x_3) = \varepsilon \hat{x} \left( \pi^\varepsilon(x_3) - x_1 \frac{\partial \pi^\varepsilon}{\partial x_3}(x_3) - x_2 \frac{\partial \pi^\varepsilon}{\partial x_3}(x_3) + \varepsilon \hat{\pi}_3(x') + \varepsilon^3 \cdot 0 \right), \quad \text{for } x \in \Omega^a, \\
\hat{U}^\varepsilon_\beta(x', x_3) = \varepsilon \hat{x} \left( \pi^\varepsilon_3(x') + \varepsilon \cdot 0 + \varepsilon^2 \hat{\pi}_3(x) \right), \quad \text{for } x \in \Omega^b.
\end{cases} \quad (2.33)$$

At least formally, from (2.31), (2.32) and (2.33), it follows that:

$$U^\alpha_3 = O(1) \text{ in } \Omega^\alpha, \quad U^\alpha_3 = O(\varepsilon \hat{\pi}) \text{ in } \Omega^\beta,$$

$$U^\varepsilon_3 = O(\varepsilon \hat{x}) \text{ in } \Omega^\alpha, \quad U^\varepsilon_3 = O(\varepsilon \hat{x}) \text{ in } \Omega^\beta.$$
We deduce from these estimates that the main observable displacement is the transversal displacement of the beam. At the junction, the continuity of $\mathbf{U}^\varepsilon$ formally implies that, for $x' \in \omega^a$:

$$
\begin{align*}
\overline{\varphi}_a^3(0) + \varepsilon \overline{\varphi}_a^2(0) x'_3 R^a + \varepsilon^3 \overline{\varphi}_a^1(x', 0) & \simeq \varepsilon^2 \left( \overline{\zeta}_a(\varepsilon^3 x') - 0 \cdot \frac{\partial \overline{\varphi}_a^3}{\partial x_3}(\varepsilon^3 x', 0) + \varepsilon \overline{\varphi}_a^0(\varepsilon^3 x', 0) + \varepsilon^2 \cdot 0 \right), \\
\overline{\zeta}(0) - x_1 \frac{\partial \overline{\varphi}_a^3}{\partial x_3}(0) - x_2 \frac{\partial \overline{\varphi}_a^2}{\partial x_3}(0) + \varepsilon \overline{\varphi}_a^0(x', 0) + \varepsilon^3 \cdot 0 & \simeq \overline{\varphi}_a^3(\varepsilon^3 x') + \varepsilon \cdot 0 + \varepsilon^2 \overline{\varphi}_a^0(\varepsilon^3 x', 0).
\end{align*}
$$

This gives formally:

$$
\overline{\varphi}_a^3(0) = 0, \quad \overline{\varphi}(0) = 0,
$$

$$
\overline{\zeta}(0) = \overline{\varphi}_a^3(0), \quad \frac{\partial \overline{\varphi}_a^3}{\partial x_3}(0) = 0,
$$

which are the six conditions on the junction, a rigorous proof of which is given in Section 5. Moreover we get at the junction the following estimates:

$$
\mathbf{U}^\varepsilon_a = O(\varepsilon^2), \quad \mathbf{U}^\varepsilon_3 = O(\varepsilon^3) \text{ on } J^\varepsilon.
$$

**Remark 3.** We could go further and formally deduce for instance that:

$$
\overline{\zeta}_a^h(0) = 0, \quad \overline{\varphi}_a^3(x', 0) = x_1 \frac{\partial \overline{\varphi}_a^3}{\partial x_1}(0) + x_2 \frac{\partial \overline{\varphi}_a^3}{\partial x_2}(0).
$$

But these relations have no sense since the solutions are not sufficiently smooth. For instance $\overline{\zeta}_a^h$ only belongs to $H^1(\omega^h)$, and its value $\overline{\zeta}_a^h(0)$ is not well defined. In contrast, the functions involved in the conditions at the junction have a value in zero, since they belong to the functional space given by the limit problem. □

The remaining part of the paper is devoted to the proofs of Theorem 1 and Corollary 1.

### 3. The derivation of the rescaled problem

Let us emphasize that we perform different scalings for the respective restrictions of $U \in Y^\varepsilon$ to the respective subdomains $\Omega^{a\varepsilon}$ and $\Omega^{b\varepsilon}$, in order to get convenient transmission conditions for their transforms $u^a$ and $u^b$. We mean that, with the transmission conditions appearing in the definition (2.1) of $Y^\varepsilon$, namely:

$$
u^a_1(x', 0) = \varepsilon r^x u^a_1(r^x x', 0) \quad \text{and} \quad u^b_3(x', 0) = u^b_3(r^x x', 0), \quad \text{for a.e. } x' \in \omega^a, \quad \text{(3.1)}$$

we are able to derive the junction conditions for the limit problem. The derivation of the limit junction conditions seems to be delicate otherwise. Moreover this is the scaling for which the coupling is maximum at the limit, at least for the third component of the displacement.

#### 3.1. The result of the scaling

In this subsection, we give the explicit expressions of the source terms and the solution of the rescaled problem (2.3), as functions of the corresponding terms of the initial problem (1.2). An explanation is given in Section 3.2.
On the first hand, assuming that $(F^\varepsilon, G^\varepsilon, H^\varepsilon) \neq (0, 0, 0)$ (otherwise the problem is trivial), we define $\lambda^\varepsilon$ by:

\[
\begin{align*}
\frac{1}{(r^\varepsilon)^2} \sum_{\alpha = 1}^{2} \| F^\varepsilon_\alpha \|_{L^2(\Omega^\varepsilon)}^2 + \| F^\varepsilon_3 \|_{L^2(\Omega^\varepsilon)}^2 + \| F^\varepsilon_\alpha \|_{L^2(\Omega^\varepsilon)}^2 + \frac{\varepsilon^3}{(r^\varepsilon)^2} \sum_{\alpha = 1}^{2} \| F^\varepsilon_\alpha \|_{L^2(\Omega^\varepsilon)}^2 + \frac{\varepsilon}{(r^\varepsilon)^2} \| F^\varepsilon_3 \|_{L^2(\Omega^\varepsilon)}^2 + \\
+ \| G^\varepsilon \|_{(L^2(\Omega^\varepsilon))^3 \times 3}^2 + \frac{\varepsilon^3}{(r^\varepsilon)^2} \| G^\varepsilon \|_{(L^2(\Omega^\varepsilon))^3 \times 3}^2 + \frac{1}{(r^\varepsilon)^2} \sum_{\alpha = 1}^{2} \| H^\varepsilon_\alpha \|_{L^2(\Sigma^\varepsilon)}^2 + \frac{1}{(r^\varepsilon)^2} \| H^\varepsilon_3 \|_{L^2(\Sigma^\varepsilon)}^2 = 1.
\end{align*}
\]

(3.2)

Then we set:

\[
\begin{align*}
& f^\varepsilon_\alpha(x) = \frac{\lambda^\varepsilon}{r^\varepsilon} F^\varepsilon_\alpha(r^\varepsilon x', x_3), \quad f^\varepsilon_3(x) = \frac{\lambda^\varepsilon}{r^\varepsilon} F^\varepsilon_3(r^\varepsilon x', x_3), \quad \text{for } x \in \Omega^a, \\
& f^\varepsilon_\alpha(x) = \frac{\lambda^\varepsilon}{r^\varepsilon} \frac{\varepsilon^2}{(r^\varepsilon)^2} F^\varepsilon_\alpha(x', \varepsilon x_3), \quad f^\varepsilon_3(x) = \frac{\lambda^\varepsilon}{r^\varepsilon} \frac{\varepsilon^2}{(r^\varepsilon)^2} F^\varepsilon_3(x', \varepsilon x_3), \quad \text{for } x \in \Omega^b, \\
& g^\varepsilon(x) = \frac{\lambda^\varepsilon}{r^\varepsilon} G^\varepsilon(r^\varepsilon x', x_3), \quad \text{for } x \in \Omega^a, \quad g^\varepsilon(x) = \frac{\lambda^\varepsilon}{r^\varepsilon} \frac{\varepsilon^2}{(r^\varepsilon)^2} G^\varepsilon(x', \varepsilon x_3), \quad \text{for } x \in \Omega^b,
\end{align*}
\]

(3.3)

(3.4)

\[
\begin{align*}
& h^\varepsilon_\alpha(x') = \frac{\lambda^\varepsilon}{r^\varepsilon} H^\varepsilon_\alpha(r^\varepsilon x', x_3), \quad h^\varepsilon_3(x') = \frac{\lambda^\varepsilon}{r^\varepsilon} H^\varepsilon_3(r^\varepsilon x', x_3), \quad \text{for } x \in \Sigma^a, \\
& h^\varepsilon_\alpha(x') = \frac{\lambda^\varepsilon}{r^\varepsilon} \frac{\varepsilon}{(r^\varepsilon)^2} H^\varepsilon_\alpha(x', 0), \quad h^\varepsilon_3(x') = \frac{\lambda^\varepsilon}{r^\varepsilon} \frac{1}{(r^\varepsilon)^2} H^\varepsilon_3(x', 0), \quad \text{for } x' \in \omega^b \setminus r^\varepsilon \omega^a, \\
& h^\varepsilon_\alpha(x') = \frac{\lambda^\varepsilon}{r^\varepsilon} \frac{\varepsilon}{(r^\varepsilon)^2} H^\varepsilon_\alpha(x', -\varepsilon), \quad h^\varepsilon_3(x') = \frac{\lambda^\varepsilon}{r^\varepsilon} \frac{1}{(r^\varepsilon)^2} H^\varepsilon_3(x', -\varepsilon), \quad \text{for } x' \in \omega^b.
\end{align*}
\]

(3.5)

Note that $h^\varepsilon_\alpha = 0$ on $r^\varepsilon \omega^a$, since there is no contribution of $H^\varepsilon$ on $J^\varepsilon$.

On the other hand, for any $U \in Y^\varepsilon$, we define the rescaled function $u = (u^a, u^b)$ by:

\[
\begin{align*}
u^a_\alpha(x) &= \frac{\lambda^\varepsilon}{r^\varepsilon} U_\alpha(r^\varepsilon x', x_3), \quad u^a_3(x) = \frac{\lambda^\varepsilon}{r^\varepsilon} U_3(r^\varepsilon x', x_3), \quad \text{for } x \in \Omega^a, \\
\end{align*}
\]

(3.6)

\[
\begin{align*}
u^b_\alpha(x) &= \frac{\lambda^\varepsilon}{r^\varepsilon} U_\alpha(x', \varepsilon x_3), \quad u^b_3(x) = \frac{\lambda^\varepsilon}{r^\varepsilon} U_3(x', \varepsilon x_3), \quad \text{for } x \in \Omega^b.
\end{align*}
\]

(3.7)

Remark 4. Let us observe that the rescaled source terms are bounded, but not strongly converging to zero, since, by definition of $\lambda^\varepsilon$ (see (3.2)) and by (3.3) to (3.5):

\[
\| f^\varepsilon_\alpha \|_{(L^2(\Omega^\varepsilon))^3}^2 + \| f^\varepsilon_\alpha \|_{(L^2(\Omega^\varepsilon))^3}^2 + \| g^\varepsilon \|_{(L^2(\Omega^\varepsilon))^3 \times 3}^2 + \| g^\varepsilon \|_{(L^2(\Omega^\varepsilon))^3 \times 3}^2 + \| h^\varepsilon_\alpha \|_{(L^2(\Omega^\varepsilon))^3}^2 + \| h^\varepsilon_\alpha \|_{(L^2(\omega^\varepsilon))^3}^2 + \| h^\varepsilon_\alpha \|_{(L^2(\omega^\varepsilon))^3}^2 = 1.
\]
3.2. The derivation of the scaling

Let us consider the possible scalings for the solution $U$ and test function $U$. If, instead of a multidomain, one considers a single thin cylinder, the natural scaling is (see [21, 27, 28]):

$$u_a(x) = r^2 U_a(r^2 x', x_3), \quad u_3(x) = U_3(r^2 x', x_3), \quad \text{for} \ x \in \Omega^a,$$

while for a single plate, the natural scaling is (see [5, 7]):

$$u_a(x) = U_a(x', \varepsilon x_3), \quad u_3(x) = \varepsilon U_3(x', \varepsilon x_3), \quad \text{for} \ x \in \Omega^b.$$

For the multidomain made of the union of the beam and the plate, the idea is to consider different coefficients of normalization, $\lambda^{ae}$ and $\lambda^{be}$, for $\Omega^{ae}$ and $\Omega^{be}$ respectively, that is we set:

$$u_a(x) = \lambda^{ae} r U_a(r^2 x', x_3), \quad u_3(x) = \lambda^{ae} U_3(r^2 x', x_3), \quad \text{for} \ x \in \Omega^a,$$

$$u_b(x) = \lambda^{be} U_b(x', \varepsilon x_3), \quad u_3(x) = \lambda^{be} \varepsilon U_3(x', \varepsilon x_3), \quad \text{for} \ x \in \Omega^b.$$

Then one has, with $e_{ae}, e_{be}$ defined in (2.2):

$$e(U)(r^2 x', x_3) = \frac{1}{\lambda^{ae}} e_{ae}(u^{ae}) (x) \quad \text{for} \ x \in \Omega^a \quad \text{and} \quad e(U)(x', \varepsilon x_3) = \frac{1}{\lambda^{be}} e_{be}(u^{be})(x) \quad \text{for} \ x \in \Omega^b,$$

and it is easy to check that the variational equality in (1.2) reads, once each integral is written on the corresponding fixed domain:

$$\left\langle \frac{(r^2)^2}{(\lambda^{ae})^2} \int_{\Omega^a} [A^{ae} e^{ae}(u^{ae}), e^{ae}_{ae}(u^a)] \, dx + \frac{\varepsilon}{(\lambda^{be})^2} \int_{\Omega^b} [A^{be} e^{be}(u^{be}), e^{be}_{be}(u^b)] \, dx \right\rangle$$

$$= \frac{1}{\lambda^{ae}} \left( \sum_{\alpha=1}^{2} \int_{\Omega^a} r^2 F_{a}^{e}(r^2 x', x_3) u_a^\alpha(x) \, dx + \int_{\Omega^a} (r^2)^2 F_{a}^{2e}(r^2 x', x_3) u_a^3(x) \, dx \right)$$

$$+ \frac{1}{\lambda^{be}} \left( \sum_{\alpha=1}^{2} \int_{\Omega^b} \varepsilon F_{b}^{e}(x', \varepsilon x_3) u_b^\alpha(x) \, dx + \int_{\Omega^b} \varepsilon F_{b}^{2e}(x', \varepsilon x_3) u_b^3(x) \, dx \right)$$

$$+ \frac{(r^2)^2}{\lambda^{ae}} \int_{\Omega^a} G^{e}(r^2 x', x_3), e^{ae}(u^a)] \, dx + \frac{\varepsilon}{\lambda^{be}} \int_{\Omega^b} G^{e}(x', \varepsilon x_3), e^{be}(u^b)] \, dx$$

$$= \frac{1}{\lambda^{ae}} \left( \sum_{\alpha=1}^{2} \int_{\Omega^a} H_{a}^{e}(r^2 x', x_3) u_a^\alpha(x) \, d\sigma + \int_{\Sigma^a} r^2 H_{a}^{2e}(r^2 x', x_3) u_a^3(x) \, d\sigma \right)$$

$$+ \frac{1}{\lambda^{be}} \left( \sum_{\alpha=1}^{2} \int_{\Omega^b} H_{b}^{e}(x', 0) u_b^\alpha(x', 0) \, dx' + \int_{\omega^b \setminus r^2 \omega} \frac{1}{\varepsilon} H_{b}^{2e}(x', 0) u_b^3(x', 0) \, dx' \right)$$

$$+ \frac{1}{\lambda^{be}} \left( \sum_{\alpha=1}^{2} \int_{\omega^b} H_{b}^{e}(x', -\varepsilon) u_b^\alpha(x', -1) \, dx' + \int_{\omega^b \setminus r^2 \omega} \frac{1}{\varepsilon} H_{b}^{2e}(x', -\varepsilon) u_b^3(x', -1) \, dx' \right),$$

$$3.2.$$
We decide to choose \( \lambda^{a\varepsilon} = \varepsilon \lambda^{b\varepsilon} \), so that the junction condition written for \((u_a, u_b)\) reads: for almost every \( x' \) in \( \omega^2 \), one has:

\[
u_a^\varepsilon(x', 0) = \frac{\lambda^{a\varepsilon}}{\lambda^{b\varepsilon}} r^\varepsilon u_a^\varepsilon(x', 0) = \varepsilon r^\varepsilon u_a^\varepsilon(x', 0) \quad \text{and} \quad u_b^\varepsilon(x', 0) = \frac{\lambda^{a\varepsilon}}{\lambda^{b\varepsilon}} \varepsilon u_b^\varepsilon(x', 0) = u_b^\varepsilon(x', 0)
\]

(see also the beginning of Sect. 3). Then, after dividing by \((r^\varepsilon)^2/(\lambda^{a\varepsilon})^2\), writing \( \lambda^\varepsilon \) instead of \( \lambda^{a\varepsilon} \), for simplicity, and defining the rescaled source terms by (3.3), (3.4), (3.5), the equality (3.8) is exactly the variational equality in (2.3). Finally, we recall that the particular choice of \( \lambda^\varepsilon \) given in (3.2) makes the source terms bounded, but not strongly converging to zero (see also Rem. 4).

**Remark 5.** Since the left-hand side of (3.8) is another way of writing

\[
\left( \frac{r^\varepsilon}{\lambda} \right)^2 \left( \int_{\Omega^a} [A^a e^{a\varepsilon}(\pi^{a\varepsilon}), e^{a\varepsilon}(\pi^{a\varepsilon})] \, dx + q^\varepsilon \int_{\Omega^b} [A^b e^{b\varepsilon}(\pi^{b\varepsilon}), e^{b\varepsilon}(\pi^{b\varepsilon})] \, dx \right) = \int_{\Omega^b} [A^b(\pi^{a\varepsilon}), e(\pi^{a\varepsilon})] \, dx,
\]

which gives the definition of the renormalized energy in (2.26). In [15], we took \( \lambda^\varepsilon = r^\varepsilon \), since the initial problem (1.2) was supposed to be suitably normalized.

\[\square\]

4. The a priori estimates and the compactness arguments

4.1. A priori estimates

In the following, we denote by \( C \) any positive constant which does not depend on \( \varepsilon \) and we write \( \tau^{a\varepsilon} \) (resp. \( \tau^{b\varepsilon} \)) for \( e^{a\varepsilon}(\pi^{a\varepsilon}) \) (resp. \( e^{b\varepsilon}(\pi^{b\varepsilon}) \)). Taking \( u = \tau^\varepsilon = (\pi^{a\varepsilon}, \pi^{b\varepsilon}) \) as test function in (2.3), we get:

\[
\begin{align*}
&\int_{\Omega^a} [A^a \tau^{a\varepsilon}, \tau^{a\varepsilon}] \, dx + q^\varepsilon \int_{\Omega^b} [A^b \tau^{b\varepsilon}, \tau^{b\varepsilon}] \, dx \\
&= \int_{\Omega^a} f^{a\varepsilon} \tau^{a\varepsilon} \, dx + \int_{\Omega^b} f^{b\varepsilon} \tau^{b\varepsilon} \, dx + \int_{\Omega^a} [g^{a\varepsilon}, \tau^{a\varepsilon}] \, dx + \int_{\Omega^b} [g^{b\varepsilon}, \tau^{b\varepsilon}] \, dx \\
&\quad + \int_{\Sigma^a} h^{a\varepsilon} \tau^{a\varepsilon} \, \sigma \, d\sigma + \int_{\Sigma^b} \left( h^{b\varepsilon} \tau^{a\varepsilon} \right|_{x_3=0} + h^{b\varepsilon} \tau^{a\varepsilon} \right|_{x_3=-1} \, dx'.
\end{align*}
\]

From Korn’s inequality, since \( \pi^{a\varepsilon} \) vanishes on \( T^a \) and \( \pi^{b\varepsilon} \) vanishes on \( \Sigma^b \), we get for \( \varepsilon \leq 1 \) and \( r^\varepsilon \leq 1 \):

\[
\|\pi^{a\varepsilon}\|_{(H^1(\Omega^a))^3} \leq C\|e(\pi^{a\varepsilon})\|_{(L^2(\Omega^a))^3} \leq C\|\pi^{a\varepsilon}\|_{(L^2(\Omega^a))^3},
\]

\[
\|\pi^{b\varepsilon}\|_{(H^1(\Omega^b))^3} \leq C\|e(\pi^{b\varepsilon})\|_{(L^2(\Omega^b))^3} \leq C\|\pi^{b\varepsilon}\|_{(L^2(\Omega^b))^3},
\]

and, by continuity of the trace mapping:

\[
\|\pi^{a\varepsilon}\|_{(L^2(\Sigma^a))^3} \leq C\|\pi^{a\varepsilon}\|_{(H^1(\Omega^a))^3},
\]

\[
\|\pi^{b\varepsilon}\|_{(x_3=0)(L^2(\omega^b))^3} + \|\pi^{b\varepsilon}\|_{(x_3=-1)(L^2(\omega^b))^3} \leq C\|\pi^{b\varepsilon}\|_{(H^1(\Omega^b))^3}.
\]

By using the above inequalities, the coercivity of \( A^a \) and \( A^b \) and the boundedness of the source terms (see (2.7)
Compactness arguments

4.2. If \( q^x \) is bounded from below by some positive constant, that is if \( q \) defined in (2.5) is equal to some positive number or to \(+\infty\), it follows that \( \tilde{\epsilon}^{x} \) is bounded in \((L^2(\Omega^1))^3 \times 3\) and \( \tilde{\tau}^{bc} \) is bounded in \((L^2(\Omega^1))^3 \times 3\). Then, from Korn’s inequality, it results that \( \tilde{\epsilon}^{x} \) is bounded in \((H^1(\Omega^1))^3\) and \( \tilde{\tau}^{bc} \) is bounded in \((H^1(\Omega^1))^3\). Moreover, in the particular case where \( q = +\infty \), \( \tilde{\epsilon}^{x} \) tends to zero (strongly) in \((L^2(\Omega^1))^3 \times 3\) and \( \tilde{\tau}^{bc} \) tends to zero (strongly) in \((H^1(\Omega^1))^3\).

Otherwise, i.e. if \( q^x \) tends to zero, we define \( \tilde{u}^{\epsilon} \) by:

\[
\tilde{u}^{\epsilon} = \left( \tilde{a}^{x\epsilon}, \tilde{b}^{bc} \right) = q^x \tilde{\tau}^{bc} = q^x \left( \tilde{\tau}^{x\epsilon}, \tilde{\tau}^{bc} \right).
\]

It is clear that \( \tilde{u}^{\epsilon} \) solves:

\[
\begin{align*}
\tilde{u}^{\epsilon} & \in \mathcal{Y}^{\epsilon} \text{ and } \forall \ u \in \mathcal{Y}^{\epsilon}, \\
1 \ & \frac{1}{q^x} \int_{\Omega^x} \left[ A^x e^{x\epsilon}(\tilde{a}^{x\epsilon}), e^{x\epsilon}(u^a) \right] \, dx + \int_{\Omega^x} \left[ A^x b^{bc}(\tilde{b}^{bc}), e^{x\epsilon}(u^b) \right] \, dx \\
& = \int_{\Omega^x} f^{x\epsilon} \cdot u^a \, dx + \int_{\Omega^x} f^{bc} \cdot u^b \, dx + \int_{\Omega^x} \left[ g^{x\epsilon}(\tilde{a}^{x\epsilon}), e^{x\epsilon}(u^a) \right] \, dx + \int_{\Omega^x} \left[ g^{bc}(\tilde{b}^{bc}), e^{x\epsilon}(u^b) \right] \, dx \\
& + \int_{\Sigma^x} h^{x\epsilon} \cdot u^a \, d\sigma + \int_{\Sigma^x} \left( h^{bc}_{+} u^a_{x=0} + h^{bc}_{-} u^a_{x=-1} \right) \, dx.
\end{align*}
\]

Taking \( u = \tilde{u}^{\epsilon} \) as test function in (4.3), it is easy to prove (as we have done in the case \( q^x \geq C > 0 \)) that \( \tilde{e}^{x\epsilon} = e^{x\epsilon}(\tilde{a}^{x\epsilon}) = q^x \tilde{\tau}^{x\epsilon} \) tends to zero in \((L^2(\Omega^1))^3 \times 3\), \( \tilde{e}^{bc} = e^{bc}(\tilde{b}^{bc}) = q^x \tilde{\tau}^{bc} \) is bounded in \((L^2(\Omega^1))^3 \times 3\), \( \tilde{u}^{\epsilon} = q^x \tilde{\tau}^{x\epsilon} \) tends to zero in \((H^1(\Omega^1))^3\) and \( \tilde{b}^{bc} = q^x \tilde{\tau}^{bc} \) is bounded in \((H^1(\Omega^1))^3\).

4.2. Compactness arguments

- If \( q^x \) tends to \( q \) with \( 0 < q \leq +\infty \), it results from the \textit{a priori} estimates that there exist \( \bar{\tau} = (\bar{\tau}^{x\epsilon}, \bar{\tau}^{bc}) \) in \((H^1(\Omega^1))^3 \times (H^1(\Omega^1))^3\) and \( \bar{\tau} = (\bar{\tau}^x, \bar{\tau}^{bc}) \) in \((L^2(\Omega^1))^3 \times (L^2(\Omega^1))^3 \) such that:

\[
\begin{align*}
\tilde{\tau}^{x\epsilon} = (\tilde{\tau}^{x\epsilon}, \tilde{\tau}^{bc}) & \rightarrow \bar{\tau} = (\bar{\tau}^{x\epsilon}, \bar{\tau}^{bc}) \text{ weakly in } (H^1(\Omega^1))^3 \times (H^1(\Omega^1))^3, \quad (4.4) \\
\tilde{\tau}^{bc} = (\tilde{\tau}^{bc}, \tilde{\tau}^{bc}) & \rightarrow \bar{\tau} = (\bar{\tau}^{x\epsilon}, \bar{\tau}^{bc}) \text{ weakly in } (L^2(\Omega^1))^3 \times (L^2(\Omega^1))^3. \quad (4.5)
\end{align*}
\]

Clearly \( \bar{\tau}^{x\epsilon} = 0 \) on \( T^x \), \( \bar{\tau}^{bc} = 0 \) on \( \Sigma^x \) and \( \bar{\tau}^x, \bar{\tau}^{bc} \) are symmetric matrices. Moreover, from the boundedness of \( \tilde{\tau}^{x\epsilon} = (\tilde{\tau}^{x\epsilon}, \tilde{\tau}^{bc}) \) and a classical semicontinuity argument, we get that \( \bar{\tau}^{x\epsilon} \) is a Bernoulli-Navier displacement and \( \bar{\tau}^{bc} \) is a Kirchhoff-Love displacement:

\[
e_{ \alpha\beta}(\bar{\tau}^{x\epsilon}) = 0 \text{ and } e_{ \alpha\beta}(\bar{\tau}^{bc}) = 0, \quad e_{ \alpha\beta}(\bar{\tau}^x) = 0 \text{ and } e_{ \alpha\beta}(\bar{\tau}^{bc}) = 0,
\]
which, combined with the constraints $\overline{\pi} \circ 0$ on $T^a$, $\overline{\pi} = 0$ on $\Sigma^b$, is equivalent to (see [20]):

$$\overline{\pi} \in (H^2(0,1))^2 \times H^1(\Omega^a), \quad \overline{\pi}(1) = \frac{d\overline{\pi}_1}{dx_3}(1) = 0,$$

$$\exists \zeta \in H^1(0,1), \quad \zeta(1) = 0, \quad \overline{\pi}_2 = \zeta = \frac{d\overline{\pi}_2}{dx_3}(1) = 0,$$

$$\overline{\pi} \in \mathcal{U}^b.$$

Moreover one can prove as in [28] that there exist $(\overline{\pi}^a, \overline{\pi}^b)$ such that $\overline{\pi}^a = e^a(\overline{\pi}^a, \overline{\pi}^b, \overline{\pi}^c)$ and $\overline{\pi}^b = e^b(\overline{\pi}^a, \overline{\pi}^b, \overline{\pi}^c)$ (see the definitions of $e^a$ and $e^b$ in (2.6)) and such that:

$$\overline{\pi}^a \in (H^1(\Omega^a))^2 \times L^2(0,1; H^1(\omega^a)), \quad \overline{\pi}(1) = 0, \quad \overline{\pi}_1 = -\zeta x_2, \quad \overline{\pi}_2 = \zeta x_1,$$

$$\int_{\omega^a} \overline{\pi}_3(x', x_3) dx' = 0, \quad \text{for a.e. } x_3 \in (0,1),$$

$$\overline{\pi}^a \in W^a, \quad \overline{\pi}^b \in V^b, \quad \overline{\pi}^b \in W^b,$$

and suitable expressions of $\overline{\pi}^c$ (resp. $\overline{\pi}^c$) tend to $(\overline{\pi}^a, \overline{\pi}^b)$ (resp. $(\overline{\pi}^a, \overline{\pi}^b)$). For the convenience of the reader, the proof of this fact is given in the Appendix (see Sect. 8.1). In particular, $\overline{\pi}^a$ defines some $\overline{\pi} \in H^1(0,1)$ with $\overline{\pi}(1) = 0$, which is actually the limit in $L^2(0,1)$ of $\overline{\pi}$ given by

$$\overline{\pi}^c(x_3) = \frac{\int_{\omega^a} (x_1 \overline{\pi}^c_2(x', x_3) - x_2 \overline{\pi}^c_1(x', x_3)) dx'}{r^c \int_{\omega^a} (x_1^2 + x_2^2) dx'}.$$

In conclusion we have proved (2.13), (2.14).

In the particular case $q = +\infty$, we have already noticed (see the a priori estimates) that:

$$\overline{\pi}^c \to \overline{\pi}^a = 0 \text{ strongly in } (H^1(\Omega^a))^3 \text{ and } \overline{\pi}^c \to \overline{\pi}^b = 0 \text{ strongly in } (L^2(\Omega^b))^{3\times 3},$$

that is we have proved (2.16), (2.17).

• If $q^c$ tends to zero, it results from the a priori estimates that:

$$\begin{cases} q^c \overline{\pi}^c \to 0 \text{ strongly in } (H^1(\Omega^a))^3, & q^c \overline{\pi}^c \to \overline{\pi}^b \text{ weakly in } (H^1(\Omega^b))^3, \\ q^c \overline{\pi}^c \to 0 \text{ strongly in } (L^2(\Omega^a))^{3\times 3}, & q^c \overline{\pi}^c \to \overline{\pi}^b \text{ weakly in } (L^2(\Omega^b))^{3\times 3}, \end{cases}$$

for some $\overline{\pi}^b \in \mathcal{U}^b$ and some symmetric matrix $\overline{\pi}^b \in (L^2(\Omega^b))^{3\times 3}$. Again (see the App., Sect. 8.1), there exists $(\overline{\pi}^a, \overline{\pi}^b)$ in $V^a \times W^b$, which are limits of suitable expressions of $\overline{\pi}^c$ and such that $\overline{\pi}^b = e^b(\overline{\pi}^a, \overline{\pi}^b, \overline{\pi}^c)$. In other words, we have proved (2.21), (2.22).
5. The limit constraints that are due to the junction

As for the limit constraints, it remains to prove that

1) \( \overline{\pi}_a(0) = 0 \),
2) \( \overline{\pi}_3(x', 0) = \overline{\nu}_3(0) \), which is equivalent to \( \overline{\zeta}'(0) = \overline{\nu}_3(0) \) and \( \frac{d\overline{\pi}_3}{dx_3}(0) = 0 \),
3) \( \overline{\tau}(0) = 0 \),

since the above three conditions give \( \overline{\pi}_a \in (H^0_0(0, 1))^2 \) and \( \overline{\tau} \in H^0_0(0, 1) \), so that \( \overline{\pi} \in \mathcal{U}^a \) and \( \overline{\tau} \in \mathcal{V}^a \). These limit constraints are derived below.

5.1. Proof of \( \overline{\pi}_a^0(0) = 0 \)

The fact that \( \overline{\pi}_a^0(0) = 0 \) results from the following easy lemma:

**Lemma 1.** Assume that \( \{u^{bc}\}_\varepsilon \) is bounded in \( L^2(\omega^b) \). Then \( \{r^{\varepsilon} u^{bc}(r^{\varepsilon})\}_\varepsilon \) is bounded in \( L^2(\omega^a) \), for every \( \omega^a \) such that \( r^{\varepsilon} \omega^a \subset \omega^b \), for any \( \varepsilon \).

**Proof.** We have:

\[
\int_{\omega^a} |r^{\varepsilon} u^{bc}(r^{\varepsilon})|^2 \, dx' = \int_{r^{\varepsilon} \omega^a} |u^{bc}(x')|^2 \, dx' \leq \int_{\omega^b} |u^{bc}(x')|^2 \, dx' \leq C.
\]

**Application.** If \( \varepsilon \neq 0 \), we write the junction condition for \( \overline{\pi}_a^0 \) as:

\[
\overline{\pi}_a^0(x', 0) = \varepsilon r^{\varepsilon} \overline{\pi}_a^{bc}(r^{\varepsilon}x', 0), \quad \text{for a.e. } x' \in \omega^a.
\]

The left-hand side tends to \( \overline{\pi}_a^0(x', 0) = \overline{\pi}_a^0(0) \) in \( L^2(\omega^a) \). The right-hand side tends to zero in this space, by Lemma 1, since \( \overline{\pi}_a^{bc}(., 0) \) is bounded in \( L^2(\omega^b) \), so that \( \overline{\pi}_a^0(0) = 0 \). If \( \varepsilon = 0 \), the same proof applies to \( \overline{u}^0 = q^0 \overline{\pi} \).

5.2. Proof of \( \overline{\pi}_3^0(x', 0) = \overline{\nu}_3(0) \)

This is a crucial part of this paper. It is derived from the following general lemma:

**Lemma 2.** Assume that \( \varepsilon \) and \( r^{\varepsilon} \) tend to zero, with \( 0 < \varepsilon^2 \ll r^{\varepsilon} \). Let \( u^{bc} \in (H^3(\Omega^b))^3 \) be such that:

\[
u^{bc} = 0 \text{ on } \Sigma^b,
\]

\[
\{e^{bc}(u^{bc})\}_\varepsilon \text{ is bounded in } (L^2(\Omega^b))^3 \times 3,
\]

with \( e^{bc} \) defined in (2.2). Then, up to a subsequence:

\[
u^{bc} \rightharpoonup u^b \text{ weakly in } (H^1(\Omega^b))^3,
\]

for some \( u^b \in \mathcal{U}^b \) (in particular \( u^b_3 \in H^2_0(\omega^b) \)). Moreover \( u^{bc}_3(r^{\varepsilon} \cdot, 0) \) tends to \( u^b_3(0) \) strongly in \( L^2(\omega^a) \), for every \( \omega^a \) such that \( r^{\varepsilon} \omega^a \subset \omega^b \), for any \( \varepsilon \).

**Proof.** The first part of the lemma is classical (see [5]). Let us prove the convergence of \( u^{bc}_3(r^{\varepsilon} \cdot, 0) \). We define \( U^{\varepsilon} : \omega^b \rightarrow \mathcal{R} \) by:

\[
U^{\varepsilon}(x') = k \int_{-1}^{0} \int_{-1}^{0} \int_{t < x_3 < 1} u^{bc}_3(x', x_3) \, dx_3 \, dt \, dt' = k \int_{-1}^{0} \int_{-1}^{0} \rho(t, t') \int_{t}^{t'} u^{bc}_3(x', x_3) \, dx_3 \, dt \, dt',
\]

with \( \rho(t, t') = 1 \) if \( t < t' \), 0 otherwise, and with \( k \) chosen so that:

\[
k \int_{-1}^{0} \int_{-1}^{0} \rho(t, t')(t' - t) \, dt \, dt' = 1.
\]
Moreover we define $e_\varepsilon^\alpha : \Omega^b \to \mathbb{R}$, $E_\varepsilon^\alpha$ and $D_\varepsilon^\alpha : \omega^b \to \mathbb{R}$ by:

$$e_\varepsilon^\alpha = 2 e_{\alpha3}(u^b_\varepsilon) = \frac{\partial u^b_\varepsilon}{\partial x_3} + \frac{\partial u^b_\varepsilon}{\partial x_\alpha}$$  \hspace{1cm} (5.5)$$

$$E_\varepsilon^\alpha(x') = k \int_{-1}^0 \int_{-1}^0 \rho(t, t') \int_t^{t'} e_\varepsilon^\alpha(x', x_3) \, dx_3 \, dt \, dt',$$ \hspace{1cm} (5.6)$$

$$D_\varepsilon^\alpha(x') = k \int_{-1}^0 \int_{-1}^0 \rho(t, t') \int_t^{t'} \frac{\partial u^b_\varepsilon}{\partial x_3}(x', x_3) \, dx_3 \, dt \, dt' = k \int_{-1}^0 \int_{-1}^0 \rho(t, t') \left( u^b_\varepsilon(x', t') - u_\varepsilon^\alpha(x', t) \right) \, dt \, dt'.$$ \hspace{1cm} (5.7)$$

It is clear that:

$$\nabla U^\varepsilon = E^\varepsilon - D^\varepsilon.$$  \hspace{1cm} (5.8)$$

Still denoting by $C$ various constants that do not depend on $\varepsilon$, we have from Cauchy-Schwarz inequality:

$$|E_\varepsilon^\alpha(x')|^2 \leq C \int_{-1}^0 |e_\varepsilon^\alpha(x', x_3)|^2 \, dx_3,$$

which gives, by definition of $e_\varepsilon^\alpha$ and by (5.1):

$$\|E_\varepsilon^\alpha\|_{L^2(\omega^b)} \leq C\|e_\varepsilon^\alpha\|_{L^2(\Omega^b)} = C\|e_{\alpha3}(u^b_\varepsilon)\|_{L^2(\Omega^b)} \leq C\varepsilon.$$ \hspace{1cm} (5.9)$$

From (5.7), Cauchy-Schwarz inequality and the boundedness of $u^b_\varepsilon$ in $H^1_0(\Omega^b)$, we have:

$$\|D_\varepsilon^\alpha\|_{H^1(\omega^b)} \leq C\|u^b_\varepsilon\|_{H^3(\Omega^b)} \leq C.$$ \hspace{1cm} (5.10)$$

From (5.8), we get the following decomposition:

$$U^\varepsilon = \hat{U}^\varepsilon + \tilde{U}^\varepsilon,$$

with $\hat{U}^\varepsilon$, $\tilde{U}^\varepsilon$ the respective solutions in $H^1_0(\omega^b)$ of:

$$-\Delta \hat{U}^\varepsilon = -\text{div} \, E^\varepsilon \text{ and } -\Delta \tilde{U}^\varepsilon = \text{div} \, D^\varepsilon \text{ in } \omega^b,$$

and from (5.9), (5.10):

$$\|\nabla \hat{U}^\varepsilon\|_{(L^2(\omega^b))^2} \leq \|E^\varepsilon\|_{(L^2(\omega^b))^2} \leq C\varepsilon,$$ \hspace{1cm} (5.11)$$

$$\hat{U}^\varepsilon \to 0 \text{ in } H^1_0(\omega^b),$$ \hspace{1cm} (5.12)$$

$$\|\tilde{U}^\varepsilon\|_{H^2(\omega^b)} \leq C\|\text{div} \, D^\varepsilon\|_{L^2(\omega^b)} \leq C.$$ \hspace{1cm} (5.13)$$

But, using (5.2) and (5.4), it is easy to prove that:

$$U^\varepsilon \to u_\varepsilon^b = u_\varepsilon^b(x') \text{ weakly in } L^2(\omega^b),$$

which gives, by virtue of (5.12), (5.13):

$$\tilde{U}^\varepsilon = U^\varepsilon - \hat{U}^\varepsilon \to u_\varepsilon^b \text{ weakly in } H^2(\omega^b).$$
Then, as the embedding $H^2(\omega^b) \subset C^0(\overline{\omega^b})$ is compact, for $\omega^b$ bidimensional, we get that:

$$\hat{U}^\varepsilon \to u_3^b \text{ in } C^0(\overline{\omega^b}).$$  \hfill (5.14)

This is enough to prove that $u_3^b(r^\varepsilon, 0)$ tends to $u_3^b(0)$ strongly in $L^2(\omega^a)$.

Actually we have, for a.e. $x'$ in $\omega^a$,

$$\left\{ \begin{aligned}
&u_3^b(r^\varepsilon, x'), 0) - u_3^b(0) \\
&= [u_3^b(r^\varepsilon, x') - U^\varepsilon(r^\varepsilon x')] + [U^\varepsilon(r^\varepsilon x') - u_3^b(r^\varepsilon x')] + [u_3^b(r^\varepsilon x') - u_3^b(0)].
\end{aligned} \right. \hfill (5.15)$$

We will show that each of the above brackets tends strongly to zero in $L^2(\omega^a)$.

As for the first bracket, we have:

$$\int_{\omega^a} |u_3^b(r^\varepsilon x', 0) - U^\varepsilon(r^\varepsilon x')|^2 \, dx' = \frac{1}{(r^\varepsilon)^2} \int_{r^\varepsilon \omega^a} |u_3^b(x', 0) - U^\varepsilon(x')|^2 \, dx'. \hfill (5.16)$$

But, by using (5.4):

$$U^\varepsilon(x') = k \int_{-1}^{0} \int_{-1}^{0} \rho(t, t') \int_{t}^{t'} \left( u_3^b(x', 0) + \int_{0}^{x_3} \frac{\partial u_3^b}{\partial x_3}(x', y_3) \, dy_3 \right) \, dx_3 \, dt \, dt'$$

$$= u_3^b(x', 0) + k \int_{-1}^{0} \int_{-1}^{0} \rho(t, t') \int_{t}^{t'} \int_{0}^{x_3} \frac{\partial u_3^b}{\partial x_3}(x', y_3) \, dy_3 \, dx_3 \, dt \, dt',$$

so that:

$$|U^\varepsilon(x') - u_3^b(x', 0)| \leq C \int_{-1}^{0} \left| \frac{\partial u_3^b}{\partial x_3}(x', y_3) \right| \, dy_3,$$

which combined with (5.1) gives:

$$\int_{r^\varepsilon \omega^a} |u_3^b(x', 0) - U^\varepsilon(x')|^2 \, dx' \leq C \int_{\Omega^b} \left| \frac{\partial u_3^b}{\partial x_3} \right|^2 \, dx \leq C \varepsilon^4.$$

Coming back to (5.16), it results that:

$$\int_{\omega^a} |u_3^b(r^\varepsilon x', 0) - U^\varepsilon(r^\varepsilon x')|^2 \, dx' \leq C \frac{\varepsilon^4}{(r^\varepsilon)^2},$$

which tends to zero, since we have assumed that $\varepsilon^2 \ll r^\varepsilon$. Now we consider the second bracket in (5.15), that is $U^\varepsilon(r^\varepsilon x')$, and we are going to prove that its $L^2$-norm tends to zero, again if $\varepsilon^2 \ll r^\varepsilon$. In fact, from Cauchy-Schwarz inequality, the continuity of the embedding $H^1_0(\omega^b) \subset L^q(\omega^b)$ (actually $L^q(\omega^b)$, for every finite $q$, in dimension 2) and from (5.11):

$$\int_{\omega^a} |\hat{U}^\varepsilon(r^\varepsilon x')|^2 \, dx' = \frac{1}{(r^\varepsilon)^2} \int_{r^\varepsilon \omega^a} |\hat{U}^\varepsilon(x')|^2 \, dx' \leq \frac{1}{(r^\varepsilon)^2} \left( \int_{r^\varepsilon \omega^a} |\hat{U}^\varepsilon(x')|^4 \, dx' \right)^{\frac{1}{2}} |r^\varepsilon \omega^a|^{\frac{1}{2}}$$

$$\leq C \frac{1}{r^\varepsilon} ||\hat{U}^\varepsilon||_{L^4(\omega^b)} \leq C \frac{1}{r^\varepsilon} ||\hat{U}^\varepsilon||_{H^1_0(\omega^b)} \leq C \frac{\varepsilon^2}{r^\varepsilon}.$$  

By virtue of (5.14), the third and the fourth brackets in (5.15) tend to zero in $L^\infty(\omega^a)$. This concludes the proof of Lemma 2. \hfill \square
Application: If \( q \neq 0 \), we write the junction condition for \( v_{\varepsilon}^3 \) as:

\[
\bar{u}_{\varepsilon}^3(x', 0) = \bar{u}_{\varepsilon}^3(r^\varepsilon x', 0), \quad \text{for } a.e. \; x' \in \omega^\varepsilon.
\]

The left-hand side tends to \( \bar{u}_{\varepsilon}^3(x', 0) \) in \( L^2(\omega^\varepsilon) \) while the right-hand side tends to \( \bar{u}_{\varepsilon}^3(0) \) in the same space by Lemma 2. It follows that \( \bar{u}_{\varepsilon}^3(x', 0) = \bar{u}_{\varepsilon}^3(0) \) for a.e. \( x' \) in \( \omega^\varepsilon \). If \( q = 0 \) the same proof applies to \( \tilde{u}^\varepsilon = q' \bar{u}^\varepsilon \).

5.3. Proof of \( \gamma(0) = 0 \)

This proof also is crucial.

Lemma 3. Assume that \( \varepsilon \) and \( r^\varepsilon \) tend to zero, with \( 0 < \varepsilon^2 \ll r^\varepsilon \). Let \((u^{ae}, u^{be}) \in (H^1(\Omega^a))^3 \times (H^1(\Omega^b))^3\) be such that:

\[
u_{ae}^{\varepsilon} |_{x_3 = 1} = 0, \tag{5.17}
\]

\[
u_{a}^{ae}(x', 0) = \varepsilon r^\varepsilon u_{a}^{be}(r^\varepsilon x', 0), \quad a.e. \; x' \in \omega^\varepsilon, \tag{5.18}
\]

\[
\{e^{ae}(u^{ae})\}^\varepsilon \text{ is bounded in } (L^2(\Omega^\varepsilon))^{3 \times 3}, \tag{5.19}
\]

\[
\{u_{\varepsilon}^{be}\}^\varepsilon \text{ is bounded in } H^1(\Omega^b). \tag{5.20}
\]

Let \( c_\varepsilon \) be defined by:

\[
c^\varepsilon(x_3) = \frac{\int_{\omega^\varepsilon} (x_1 u_2^{ae}(x', x_3) - x_2 u_1^{ae}(x', x_3)) \, dx' \, r^\varepsilon}{\int_{\omega^\varepsilon} (x_1^2 + x_2^2) \, dx'} \tag{5.21}
\]

Then \( c_\varepsilon \) tends to \( c \) in \( L^2(0, 1) \), where \( c \) belongs to \( H^1_0(0, 1) \).

Proof. For \( \alpha = 1, 2 \), we define \( x_3^R \) by

\[
x_3^R = -x_2, \quad x_2^R = x_1,
\]

and we set:

\[
v^{ae} = \frac{u^{ae}}{r^\varepsilon}, \quad e_\alpha^\varepsilon = 2e_{\alpha 3}(u^{ae}) = 2e_{\alpha 3}^{ae}(u^{ae}),
\]

(this notation should not be confused with the notation \( e_\alpha^\varepsilon \) appearing in (5.5)),

\[
m^\varepsilon_\alpha = \frac{1}{|\omega^\varepsilon|} \int_{\omega^\varepsilon} v_{\alpha}^{ae} \, dx', \quad \rho^\varepsilon_\alpha = \frac{1}{r^\varepsilon} \left[ v_{\alpha}^{ae} - e_\alpha^\varepsilon x_3^R - m^\varepsilon_\alpha \right],
\]

with \( e_\alpha^\varepsilon \) given by (5.21).

We begin by proving two a priori estimates. Due to (5.19), we have:

\[
\|e^\varepsilon\|_{(L^2(\Omega^\varepsilon))^3} \leq C. \tag{5.22}
\]

As for \( \rho^\varepsilon \), it follows from (1.1) that \( \rho^\varepsilon_\alpha(x_3) \) has mean-value zero on \( \omega^\varepsilon \), for every \( x_3 \) and, as \( e_{\alpha \beta}(\rho^\varepsilon) = (1/r^\varepsilon)e_{\alpha \beta}(v^{ae}) \), we get from the Poincaré-Wirtinger inequality for elasticity:

\[
\|\rho^\varepsilon\|_{(L^2(\Omega^\varepsilon))^3} \leq C \sum_{\alpha \beta} \|e_{\alpha \beta}(\rho^\varepsilon)\|_{L^2(\Omega^\varepsilon)}^2 \leq C \sum_{\alpha \beta} \|e_{\alpha \beta}(v^{ae})\|_{L^2(\Omega^\varepsilon)}^2 = C \sum_{\alpha \beta} \|e_{\alpha \beta}^{ae}(u^{ae})\|_{L^2(\Omega^\varepsilon)}^2,
\]

which gives, with (5.19):

\[
\|\rho^\varepsilon\|_{(L^2(\Omega^\varepsilon))^3} \leq C. \tag{5.23}
\]
Now we prove that one can derive a single equation, of the form $c^\varepsilon = K^\varepsilon - r^\varepsilon R^\varepsilon$, from the system of two equations $c^\varepsilon x^R_{3\alpha} + m^\varepsilon_{\alpha} = e^\varepsilon_{\alpha} - r^\varepsilon \rho^\varepsilon_{\alpha}$. This is a clever argument appearing in [28], see also Section 8.1. Indeed we get by differentiating the previous system with respect to $x_3$:

$$\frac{dc^\varepsilon}{dx_3} x^R_{3\alpha} + \frac{dm^\varepsilon_{\alpha}}{dx_3} + \frac{\partial e^\varepsilon_{\alpha}}{\partial x_3} = e^\varepsilon_{\alpha} - r^\varepsilon \frac{\partial \rho^\varepsilon_{\alpha}}{\partial x_3}, \quad \forall \alpha = 1, 2. \quad (5.24)$$

After multiplying (5.24) by a test function $\varphi_\alpha \in \mathcal{D}(\omega^a)$, summing over $\alpha$ and integrating over $\omega^a$, we have:

$$\begin{align*}
\int_{\omega^a} \sum_{\alpha} \varphi_\alpha x^R_{3\alpha} dx' + \sum_{\alpha} \frac{dm^\varepsilon_{\alpha}}{dx_3} \int_{\omega^a} \varphi_\alpha dx' - \int_{\omega^a} v^\varepsilon_{3\alpha} \text{div}\varphi dx' &= \int_{\omega^a} \sum_{\alpha} e^\varepsilon_{\alpha} \varphi_\alpha dx' - r^\varepsilon \int_{\omega^a} \sum_{\alpha} \rho^\varepsilon_{\alpha} \varphi_\alpha dx'. \\
&= \int_{\omega^a} \sum_{\alpha} e^\varepsilon_{\alpha} \varphi_\alpha dx' - r^\varepsilon \int_{\omega^a} \sum_{\alpha} \rho^\varepsilon_{\alpha} \varphi_\alpha dx'. \quad (5.25)
\end{align*}$$

We choose the test function $\varphi_\alpha$ so that:

$$\begin{align*}
\int_{\omega^a} \sum_{\alpha} \varphi_\alpha x^R_{3\alpha} dx' &= 1, \\
\int_{\omega^a} \varphi_\alpha dx' &= 0, \quad \forall \alpha = 1, 2, \\
\text{div}\varphi &= 0. \quad (5.26-5.28)
\end{align*}$$

It is easy to check that such test function does exist: take e.g.

$$\varphi_1 = \frac{\partial \phi}{\partial x_2}, \quad \varphi_2 = \frac{\partial \phi}{\partial x_1}, \quad \text{with} \quad \phi \in \mathcal{D}(\omega^a), \quad \int_{\omega^a} \phi dx' = \frac{1}{2}.$$

Now we set (this notation should not be confused with the notation $E^\varepsilon$ appearing in (5.6)):

$$E^\varepsilon = \int_{\omega^a} e^\varepsilon . \varphi dx', \quad K^\varepsilon = -\int_{x_3}^{1} E^\varepsilon(y_3) dy_3, \quad R^\varepsilon = \int_{\omega^a} \rho^\varepsilon . \varphi dx',$$

where $.$ denotes the scalar product in $\mathbb{R}^2$. Then (5.25) reads as:

$$\frac{dc^\varepsilon}{dx_3} = \frac{dK^\varepsilon}{dx_3} - r^\varepsilon \frac{dR^\varepsilon}{dx_3},$$

which gives by integration:

$$c^\varepsilon = K^\varepsilon - r^\varepsilon R^\varepsilon, \quad (5.29)$$

Since $c^\varepsilon(1) = K^\varepsilon(1) = 0$ and since also $R^\varepsilon(1) = 0$, because $\rho^\varepsilon(1) = 0$.

Now we pass to the limit in (5.29). Due to (5.22) and (5.23), $E^\varepsilon$ and $R^\varepsilon$ are bounded in $L^2(0,1)$. Moreover it follows that $K^\varepsilon$ is bounded in $H^1(0,1)$, since by Poincaré inequality one has:

$$\|K^\varepsilon\|_{H^1(0,1)} \leq C \int_0^1 \left| \frac{dK^\varepsilon}{dx_3} \right|^2 dx_3 = C \int_0^1 |E^\varepsilon|^2 dx_3 \leq C.$$

Then we deduce that there exists $c$ in $H^1(0,1)$, with $c(1) = 0$, such that:

$$K^\varepsilon \rightharpoonup c \quad \text{weakly in} \quad H^1(0,1), \quad \text{hence} \quad K^\varepsilon \rightarrow c \quad \text{strongly in} \quad C^0(0,1).$$

As $r^\varepsilon R^\varepsilon$ tends to zero strongly in $L^2(0,1)$, it follows from (5.29) and the above that $c^\varepsilon$ tends to $c$ strongly in $L^2(0,1)$. 

It remains to prove that \( c \) vanishes at the origin. For this, we notice that \( K^\varepsilon(0) \to c(0) \). But one has also another expression for \( K^\varepsilon \). Actually, from (5.29), (5.26), (5.27) and by the definition of \( \rho^\varepsilon_\alpha \):

\[
K^\varepsilon = r^\varepsilon R^\varepsilon + c^\varepsilon = r^\varepsilon \int_{\omega^\varepsilon} \rho^\varepsilon \cdot \varphi \, dx' + c^\varepsilon \int_{\omega^\varepsilon} \sum_{\alpha} \varphi_\alpha w^{\varepsilon R}_\alpha \, dx' + \sum_{\alpha} m^\varepsilon_{\alpha} \int_{\omega^\varepsilon} \sum_{\alpha} \varphi_\alpha \, dx'
\]

\[
= \sum_{\alpha} \int_{\omega^\varepsilon} (r^\varepsilon \rho^\varepsilon_\alpha + c^\varepsilon x^{R}_\alpha + m^\varepsilon_{\alpha}) \varphi \, dx' = \sum_{\alpha} v^{a^\varepsilon}_\alpha \varphi_\alpha \, dx',
\]

that is:

\[
K^\varepsilon = \sum_{\alpha} \int_{\omega^\varepsilon} v^{a^\varepsilon}_\alpha \varphi_\alpha \, dx' = \sum_{\alpha} \int_{\omega^\varepsilon} \frac{1}{r^\varepsilon} v^{a^\varepsilon}_\alpha \varphi_\alpha \, dx',
\]

and in particular, due to the boundary condition (5.18):

\[
K^\varepsilon(0) = \varepsilon \sum_{\alpha} \int_{\omega^\varepsilon} v^{h^\varepsilon}_\alpha (r^\varepsilon x', 0) \varphi_\alpha \, dx'.
\]

Hence, by using Hölder inequality, the continuity of the embedding of \( H^{\frac{1}{2}}(\omega^\varepsilon) \) in \( L^q(\omega^\varepsilon) \) (in dimension 2), the continuity of the trace mapping from \( H^1(\Omega^\varepsilon) \) to \( H^{\frac{1}{2}}(\Omega^\varepsilon) \) and (5.20), we get:

\[
|K^\varepsilon(0)| \leq C\varepsilon \sum_{\alpha} \int_{\omega^\varepsilon} |v^{h^\varepsilon}_\alpha (r^\varepsilon x', 0)| \, dx' = C\varepsilon \sum_{\alpha} \int_{r^\varepsilon\omega^\varepsilon} |v^{h^\varepsilon}_\alpha (x', 0)| \, dx'
\]

\[
\leq C\varepsilon \sum_{\alpha} \left[ \int_{r^\varepsilon\omega^\varepsilon} |v^{h^\varepsilon}_\alpha (x', 0)|^4 \, dx' \right]^{\frac{1}{4}} |r^\varepsilon \omega^\varepsilon|^\frac{1}{4} = C\varepsilon |r^\varepsilon|^{\frac{1}{4}} \sum_{\alpha} \left[ \int_{r^\varepsilon\omega^\varepsilon} |v^{h^\varepsilon}_\alpha (x', 0)|^4 \, dx' \right]^{\frac{1}{4}}
\]

\[
\leq C\varepsilon |r^\varepsilon|^{\frac{1}{4}} \sum_{\alpha} \|v^{h^\varepsilon}_\alpha (., 0)\|_{L^4(\omega^\varepsilon)} \leq C\varepsilon |r^\varepsilon|^{\frac{1}{4}} \sum_{\alpha} \|v^{h^\varepsilon}_\alpha (., 0)\|_{H^{\frac{1}{2}}(\Omega^\varepsilon)} \leq C\varepsilon |r^\varepsilon|^{\frac{1}{4}},
\]

which tends to zero, since \( 0 < \varepsilon^2 \ll r^\varepsilon \). As we have proved that \( K^\varepsilon(0) \to c(0) \), we conclude that \( c(0) = 0 \). \( \square \)

6. The use of convenient test functions

This is the third crucial part of the paper, at least in the case \( 0 < q < +\infty \).

6.1. The case \( q = +\infty \)

Observe that \( Z_\infty = \{ z^a \in Z^a, \zeta^a (= \zeta^a(u^a)) \in H^1_0(0, 1) \} \). Let \( u^a \in \mathcal{U}^a \), with \( \zeta^a \in H^1_0(0, 1) \) and let \((v^a, w^a)\) be such that:

\[
v^a_1 = -cx_2 \text{ and } v^a_2 = cx_1 \text{ with } c \in H^1_0(0, 1), \ v^a_3 \in C^1(\Omega^a), \ v^a_3 |_{x_3=0} = 0, \]

\[
w^a_\alpha \in C^1(\Omega^a), \ w^a_\alpha |_{x_3=0} = 0, \ w^a_3 = 0.
\]

In other words, \( v^a \) and \( w^a \) satisfy all the conditions given in the definitions of \( \mathcal{V}^a \) and \( \mathcal{W}^a \), but the integral ones; moreover \( v^a_3 \) and \( w^a_3 \) belong to the space \( \mathcal{R} \) defined by:

\[
\mathcal{R} = \{ v \in C^1(\Omega^a), \ v|_{x_3=0} = 0 \}.
\]
Let $u^{az} = u^a + r^a v^a + (r^a)^2 w^a$. Then it is easy to check that $u = (u^{az}, 0)$ is in $\mathcal{Y}^\varepsilon$. Taking it as test function in the variational equation of problem (1.2), we get:

$$
\int_{\Omega^\varepsilon} [A^a e^{az}, e^{az}(u^{az})] \, dx = \int_{\Omega^\varepsilon} f^{az}, u^{az} \, dx + \int_{\Omega^\varepsilon} [g^{az}, e^{az}(u^{az})] \, dx + \int_{\Sigma^\varepsilon} h^{az}, u^{az} \, d\sigma. \quad (6.3)
$$

But we have, since $e_{\alpha\beta}(u^a) = e_{\alpha3}(u^a) = e_{\alpha3}(v^a) = e_{33}(u^a) = 0$:

$$
e^{az}(u^{az}) = \begin{pmatrix} e_{\alpha\beta}(u^a) & e_{\alpha3}(v^a) \\ e_{3\alpha}(v^a) & e_{33}(u^a) \end{pmatrix} + r^a \begin{pmatrix} e_{\alpha3}(u^a) \\ e_{33}(u^a) \end{pmatrix},
$$

so that $e^{az}(u^{az})$ tends to $e^a(z^a) = e^a(u^a, v^a, w^a)$ (strongly) in $(L^2(\Omega^\varepsilon))^3$. Moreover $u^{az}$ tends to $u^a$ (strongly) in $(H^1(\Omega^\varepsilon))^3$ and we have seen in (4.5) that $e^{az}$ tends to $e^a(z^a)$ weakly in $(L^2(\Omega^\varepsilon))^3$. By passing to the limit in (6.3), using (2.7), (2.9), (2.11), it follows that:

$$
\int_{\Omega^\varepsilon} [A^a e^{az}, e^a(z^a)] \, dx = \int_{\Omega^\varepsilon} f^a, u^a \, dx + \int_{\Omega^\varepsilon} [g^a, e^a(z^a)] \, dx + \int_{\Sigma^\varepsilon} h^a, u^a \, d\sigma, \quad (6.4)
$$

which is the variational equation of (2.18). It holds also true, by density and continuity, for every $(v^a, w^a)$ such that:

$$
\begin{align*}
v_1^a &= -c x_2 \\
v_2^a &= c x_1
\end{align*}
\quad (6.5)
$$

with $c \in H^1_\delta(0, 1)$, $v_3^a \in L^2(0, 1; H^1(\omega^a))$, $w_3^a = 0$,

$$
i.e. \text{ for every } (v^a, w^a) \text{ satisfying the conditions given in the definitions of } \mathcal{Y}^a \text{ and } \mathcal{W}^a, \text{ but the integral ones (note that } \mathcal{R} \text{ defined in } (6.2) \text{ is dense in } L^2(0, 1; H^1(\omega^a))). \text{ In particular } (6.4) \text{ is also true for any } z^a \in \mathcal{Z}_\infty.
$$

This means that $\mathcal{Z}$ solves the variational problem (2.18).

6.2. The case $q = 0$

We have seen that $\tilde{a}^z = q^a \tilde{u}^z = q^a (u^{az}, v^{az})$ solves (4.3) and that (see (4.8)) $\tilde{a}^{az} = q^a \tilde{u}^{az}$ tends to $\tilde{u}^z = 0$ in $(H^1(\Omega^\varepsilon))^3$, $\tilde{b}^{bc} = q^a \tilde{u}^{bc}$ tends to $\tilde{v}^z = (v^{bc}, \tilde{v}^z)$ weakly in $(L^2(\Omega^\varepsilon))^3$, for some $\tilde{v}^z$ in $\mathcal{Z}_0$ (in particular $\mathcal{Z}_0(0) = 0$).

Let $B$ be some given small ball, with center zero, in $\omega^b$. Let $z^b = (u^b, v^b, w^b)$ be such that:

$$
\begin{align*}
&u^b \in U^b, \quad \zeta^b_{\alpha} (= \zeta^b_{\alpha}(u^b)) = u^b_0 = 0 \text{ in } B, \\
v^b_0 \in C^1(\overline{\Omega^b}), \quad v^b_0 = 0 \text{ in } B \times \{0\}, \quad v^b_3 = 0, \\
w^b_0 = 0, \quad w^b_3 \in C^1(\overline{\Omega^b}), \quad w^b_3 = 0 \text{ in } B \times \{0\}.
\end{align*}
\quad (6.5)
$$

In other words, $z^b$ satisfies all the conditions given in the definition of $\mathcal{Z}_0$, except the integral ones; moreover $\zeta^b$ and $u^b_0$ vanish in $B$, $v^b_0$ and $w^b_3$ belong to $C^1(\overline{\Omega^b})$ and vanish in $B \times \{0\}$. Let $u^{bc} = u^b + \varepsilon v^b + (\varepsilon)^2 w^b$. Then it is easy to check that $u = (0, u^{bc})$ is in $\mathcal{Y}^\varepsilon$, for $\varepsilon$ small enough. Taking it as test function in the variational equation of problem (1.2), we get:

$$
\int_{\Omega^\varepsilon} [A^b e^{bc}, e^{bc}(u^{bc})] \, dx = \int_{\Omega^\varepsilon} f^{bc}, u^{bc} \, dx + \int_{\Omega^\varepsilon} [g^{bc}, e^{bc}(u^{bc})] \, dx + \int_{\omega^b} (h^{bc} \cdot u^{bc})_{|z_3=0} + h^{bc} \cdot u^{bc}_{|z_3=-1} \, dx. \quad (6.6)
$$

But we have, since $e_{\alpha3}(u^b) = e_{\alpha3}(v^b) = e_{\alpha3}(w^b) = e_{\alpha3}(w^b) = 0$:

$$
e^{bc}(u^{bc}) = \begin{pmatrix} e_{\alpha\beta}(u^b) & e_{\alpha3}(v^b) \\ e_{3\alpha}(v^b) & e_{33}(u^b) \end{pmatrix} + \varepsilon \begin{pmatrix} e_{\alpha\beta}(v^b) & e_{\alpha3}(w^b) \\ e_{3\alpha}(w^b) & 0 \end{pmatrix}.
$$
so that $e^{bc}(u^{bc})$ tends to $e^{b}(z^{b})$ (strongly) in $(L^2(\Omega^b))^{3\times 3}$. Moreover $u^{bc}$ tends to $u^{b}$ (strongly) in $(H^1(\Omega^b))^{3\times 3}$ and we have seen that $e^{bc}$ tends to $e^{b}(\mathcal{Z}^{b})$ weakly in $(L^2(\Omega^b))^{3\times 3}$. By passing to the limit in (6.6), using (2.8), (2.10), (2.12), it follows that:

$$\int_{\Omega^b} [A^b e^{b}(\mathcal{Z}^{b}), e^{b}(z^{b})] \, dx = \int_{\Omega^b} f^{b} \, u^{b} \, dx + \int_{\Omega^b} [g^{b}, e^{b}(z^{b})] \, dx + \int_{\Omega^b} \left( h_{\alpha}^{b} u^{b}_{|x_{3}=0} + h_{b}^{b} u^{b}_{|x_{3}=-1} \right) \, dx', \quad (6.7)$$

for every $z^{b} = (u^{b}, v^{b}, w^{b})$ having the regularity (6.5).

But the following density results are proved in the Appendix (Sect. 8.2). First, from Lemma 5, any $\zeta^{b}_{a} \in H_{0}^{1}(\omega^b)$ can be approximated (in the strong topology of $H_{0}^{1}(\omega^b)$) by a sequence $\zeta^{b}_{na}$ with $\zeta^{b}_{na} = 0$ in a ball $B^{n}$ of radius $r^{n}$ tending to zero. Moreover, from Lemma 6, any $u^{b}_{a} \in H_{0}^{1}(\omega^b)$, with $u^{b}_{a}(0) = 0$ can be approximated (in the weak topology of $H_{0}^{1}(\omega^b)$) by a sequence $u^{b}_{na}$ that vanishes in $B^{n}$. Finally, from Lemma 7, any $v^{b}_{a}$ (or $w^{b}_{a}$) in $L^{2}(\omega^b; H^{1}(-1,0))$ can be approximated (in the strong topology of $L^{2}(\omega^b; H^{1}(-1,0))$) by a sequence of functions $v^{b}_{na}$ (or $w^{b}_{na}$) in $C^{1}(\Omega^b)$ that vanish in $B^{n} \times \{0\}$.

By continuity, it results that (6.7) holds true for any $(u^{a}, v^{b}, w^{b})$ such that:

$$\begin{align*}
    u^{b} &\in \mathcal{U}^{b}, \quad u^{b}_{a}(0) = 0, \\
v^{b}_{a} &\in L^{2}(\omega^b; H^{1}(-1,0)), \quad v^{b}_{a} = 0, \\
w^{b}_{a} &\in L^{2}(\omega^b; H^{1}(-1,0)),
\end{align*}$$

i.e. for every $z^{b}$ satisfying the conditions given in the definition of $Z_{0}$, but the integral ones. In particular (6.7) is also true for any $z^{b} \in Z_{0}$. This means that $\mathcal{Z}^{b}$ solves the variational problem (2.23).

### 6.3. The case $0 < q < +\infty$

Let $z = (z^{a}, z^{b}) = ((u^{a}, v^{a}, w^{a}), (u^{b}, v^{b}, w^{b})) \in (C^{1}(\overline{\Omega^b}))^{3} \times (C^{1}(\overline{\Omega^b}))^{3}$. We assume that $z$ satisfies all the conditions required in the definition of $Z$, except the integral ones, and we assume that it is “more regular”. In particular $u^{b}_{a}(x', 0) = u^{b}_{a}(0)$, that is $\zeta^{a}(0) = u^{b}_{a}(0)$. The precise requirements are given by:

$$\begin{align*}
    u^{a} &\in \mathcal{U}^{a}, \quad u^{a}_{a} \in C^{2}[0, 1], \quad \zeta^{a} \in C^{1}[0, 1], \\
v^{a}_{1} &= -cz^{a}_{2} \quad \text{and} \quad v^{a}_{2} = cx^{a}_{1} \quad \text{with} \quad c \in C^{1}[0, 1], \quad c(0) = c(1) = 0, \quad v^{a}_{3} \in C^{1}(\overline{\Omega^b}), \quad v^{a}_{3}|_{x_{3}=0} = 0, \\
w^{a}_{a} &\in C^{1}(\overline{\Omega^b}), \quad w^{a}_{a}|_{x_{3}=0} = 0, \quad w^{a}_{a} = 0, \\
u^{b} &\in \mathcal{U}^{b}, \quad \zeta^{b}_{a} \in C^{1}(\overline{\omega^b}) \cap H_{0}^{1}(\omega^b), \quad u^{b}_{a} \in C^{1}(\overline{\omega^b}) \cap H_{0}^{2}(\omega^b), \\
v^{b}_{a} &\in (\{0\})^{2} \times (C^{1}(\overline{\Omega^b})), \quad v^{b}_{a} = 0 \quad \text{on} \quad \Sigma^{b}, \\
w^{b}_{a} &\in (\{0\})^{2} \times C^{1}(\overline{\Omega^b}), \quad w^{b}_{a} = 0 \quad \text{on} \quad \Sigma^{b}, \\
u^{b}_{a}(0) &= \zeta^{a}(0).
\end{align*}$$

We are going to define a convenient test function $u^{c} = (u^{ae}, u^{be})$ in $\mathcal{Y}^{c}$.

- In $\Omega^b$, we choose:

$$\begin{align*}
u^{bc} &= u^{b} + \varepsilon v^{b} + \varepsilon^{2} w^{b}.
\end{align*}$$

As the couple $u^{c} = (u^{ae}, u^{be})$ needs to satisfy the transmission conditions (3.1), i.e.:

$$\begin{align*}
u^{a}_{a}(x', 0) &= \varepsilon r^{a} u^{b}_{a}(r^{a} x', 0) \quad \text{and} \quad \nu^{a}_{a}(x', 0) = u^{b}_{a}(r^{a} x', 0), \quad \text{for a.e.} \ x' \in \omega^{a},
\end{align*}$$
then, necessarily, \( u^{ac}(x', 0) \) is given by:

\[
\begin{align*}
\frac{\partial u}{\partial x} (x', 0) &= \varepsilon r \eta (\zeta b\alpha(r \varepsilon x') + \ldots ) \\
\frac{\partial u}{\partial x} (x', 0) &= \varepsilon^2 w_b(r \varepsilon x', 0).
\end{align*}
\]

- In \( \Omega^a \cap \{ x_3 > r^\varepsilon \} \), we choose

\[
u^{ac} = \frac{\varepsilon}{\varepsilon} + r^\varepsilon v^a(r \varepsilon x') + (r^\varepsilon)^2 w^a.
\]

- In \( \Omega^a \cap \{ 0 < x_3 < r^\varepsilon \} \), \( u^{ac} \) is obtained by linear interpolation between \( u^{ac}(x', 0) \) and \( u^{ac}(x', r^\varepsilon) \):

\[
u^{ac}(x', x_3) = \frac{r^3}{r^\varepsilon} \left( \nu^a(x', r^\varepsilon) + \frac{\varepsilon}{\varepsilon} (\zeta b\alpha(r \varepsilon x') + \ldots ) \right) + \left( 1 - \frac{r^3}{r^\varepsilon} \right) \varepsilon r \eta (\zeta b\alpha(r \varepsilon x') + \ldots ),
\]

that is (see above):

\[
u^{ac}(x', x_3) = \frac{r^3}{r^\varepsilon} \left( \nu^a(x', r^\varepsilon) + \frac{\varepsilon}{\varepsilon} (\zeta b\alpha(r \varepsilon x') + \ldots ) \right) + \left( 1 - \frac{r^3}{r^\varepsilon} \right) \varepsilon r \eta (\zeta b\alpha(r \varepsilon x') + \ldots ),
\]

for \( 0 < x_3 > r^\varepsilon \). Taking \( u^a = (u^{ac}, u^{bc}) \) as test function in the variational equation of problem (2.3), we get:

\[
\left\{ \begin{array}{l}
\int_{\Omega^a} [A^a e^{ac}, e^{ac}(u^{ac})] \, dx + q^e \int_{\Omega^a} [A^b e^{bc}, e^{bc}(u^{bc})] \, dx \\
= \int_{\Omega^a} f^{ac} u^{ac} \, dx + \int_{\Omega^a} f^{bc} u^{bc} \, dx + \int_{\Omega^a} g^{ac} e^{ac}(u^{ac}) \, dx + \int_{\Omega^a} g^{bc} e^{bc}(u^{bc}) \, dx \\
+ \int_{\Sigma^a} h^{ac} u^{ac} \, d\sigma + \int_{\Sigma^b} \left( h^{bc} u^{bc} |_{x_3=0} + h^{bc} u^{bc} |_{x_3=-1} \right) \, dx',
\end{array} \right.
\]

Passing to the limit in the integral terms in \( \Omega^b \) is easy. As for the terms in \( \Omega^a \cap \{ x_3 > r^\varepsilon \} \) and \( \Sigma^b \cap \{ x_3 > r^\varepsilon \} \), we have from Lebesgue’s theorem, with \( u^{ac} = u^a + r^\varepsilon v^a + (r^\varepsilon)^2 w^a \) and \( \chi^\varepsilon \) the characteristic function of \( \{ x_3 > r^\varepsilon \} \):

\[
\chi^\varepsilon e^{ac}(u^{ac}) \to e^a(z^a) \text{ strongly in } (L^2(\Omega^a))^{3 \times 3},
\]

\[
\chi^\varepsilon u^{ac} \to u^a \text{ strongly in } (L^2(\Omega^a))^3,
\]

\[
\chi^\varepsilon u^{ac} |_{\Sigma^a} \to u^a |_{\Sigma^a} \text{ strongly in } (L^2(\Sigma^a))^3,
\]

so that, by virtue of (2.7), (2.9), (2.11), (4.5):

\[
\int_{\Omega^a \cap \{ x_3 > r^\varepsilon \}} [A^a e^{ac} - g^{ac}, e^{ac}(u^{ac})] \, dx - \int_{\Omega^a \cap \{ x_3 > r^\varepsilon \}} f^{ac} u^{ac} \, dx - \int_{\Sigma^a \cap \{ x_3 > r^\varepsilon \}} h^{ac} u^{ac} \, d\sigma \\
\to \int_{\Omega^a} [A^a e^{ac} - g^{ac}, e^{ac}(u^{ac})] \, dx - \int_{\Omega^a} f^{ac} u^{ac} \, dx - \int_{\Sigma^a} h^{ac} u^{ac} \, d\sigma.
\]

For the terms in \( \Omega^a \cap \{ 0 < x_3 < r^\varepsilon \} \) and \( \Sigma^b \cap \{ 0 < x_3 < r^\varepsilon \} \), it is clear, from (2.7), (2.11) and from the uniform boundedness of \( u^{ac} \), that:

\[
\int_{\Omega^a \cap \{ 0 < x_3 < r^\varepsilon \}} f^{ac} u^{ac} \, dx - \int_{\Sigma^b \cap \{ 0 < x_3 < r^\varepsilon \}} h^{ac} u^{ac} \, d\sigma \to 0.
\]
Hence it remains to show that:
\[ \int_{\Omega^a \cap \{0 < x_3 < r_{\varepsilon}\}} [A^a e^{\varepsilon} - g^a e^{\varepsilon}(u^{a\varepsilon})] \, dx \to 0. \]

But we have, from Cauchy-Schwarz inequality, (2.9) and (4.5):
\[ \int_{\Omega^a \cap \{0 < x_3 < r_{\varepsilon}\}} [A^a e^{\varepsilon} - g^a e^{\varepsilon}(u^{a\varepsilon})] \, dx \leq C \|e^{a\varepsilon}(u^{a\varepsilon})\|_{L^2(\Omega^a \cap \{0 < x_3 < r_{\varepsilon}\}))^{3 \times 3}, \]
and it is enough to prove that:
\[ \|e^{a\varepsilon}(u^{a\varepsilon})\|_{(L^2(\Omega^a \cap \{0 < x_3 < r_{\varepsilon}\}))^{3 \times 3}} \to 0. \] (6.14)

Then, by passing to the limit in (6.13), we get:
\[
\int_{\Omega^a} [A^a e^a(\varepsilon), e^a(z^a)] \, dx + q \int_{\Omega^a} [A^b e^b(\varepsilon), e^b(z^b)] \, dx = \int_{\Omega^a} f^a u^a \, dx + \int_{\Omega^b} f^b u^b \, dx \\
+ \int_{\Omega^a} [g^a, e^a(z^a)] \, dx + \int_{\Omega^b} [g^b, e^b(z^b)] \, dx + \int_{\Omega_a} h^a u^a \, d\sigma + \int_{\omega_b} (h^b u^b)_{x_3=0} + (h^b u^b)_{x_3=-1} \, dx',
\]
for any \( z \) having the regularity given in (6.8), and then, by a density argument given in Lemma 8 of the Appendix (Sect. 8.2), for any \( z \) satisfying all the requirements of \( Z \), except the integral conditions. \textit{A fortiori}, the same variational equality holds true for any \( z \) in \( Z \), that is \((\tilde{\varepsilon}, \tilde{\varepsilon})\) solves (2.15).

\textbf{Proof of (6.14).} We will prove that the norms in \( L^2(\{0 < x_3 < r_{\varepsilon}\}) \) of the terms \( e_{33}(u^{a\varepsilon}) \), \( \frac{1}{(r_{\varepsilon})^2} e_{a3}(u^{a\varepsilon}) \) and \( \frac{1}{r_{\varepsilon}} e_{a3}(u^{a\varepsilon}) \) tend to zero.

- **Term** \( e_{33}(u^{a\varepsilon}) \). We easily get from (6.12) that:
\[
e_{33}(u^{a\varepsilon}) = \frac{\partial u^{a\varepsilon}}{\partial x_3} = \frac{1}{r_{\varepsilon}} \left( u^a_3(x', r_{\varepsilon}) - u^a_3(r_{\varepsilon} x') \right) + v^a_3(x', r_{\varepsilon}) - \frac{\varepsilon^2}{r_{\varepsilon}} u^3_3(r_{\varepsilon} x', 0). \] (6.16)

The norms in \( L^2(\{0 < x_3 < r_{\varepsilon}\}) \) of the two last terms in (6.16) tend to zero, since \( v^a_3(x', r_{\varepsilon}) \) and \( u^a_3(r_{\varepsilon} x', 0) \) are uniformly bounded:
\[
\int_{0 < x_3 < r_{\varepsilon}} |v^a_3(x', r_{\varepsilon})|^2 \, dx \leq C r_{\varepsilon} \to 0,
\]
\[
\int_{0 < x_3 < r_{\varepsilon}} \left( \frac{x^2}{r_{\varepsilon}^2} \right)^2 |u^3_3(r_{\varepsilon} x', 0)|^2 \, dx \leq C \frac{r_{\varepsilon}^4}{r_{\varepsilon}^2} \ll C \frac{r_{\varepsilon}^2}{r_{\varepsilon}^2} \to 0,
\]
since, by assumption, \( r_{\varepsilon}^2 \ll r_{\varepsilon} \). As for the first term in (6.16), it is uniformly bounded, because of the junction condition:
\[
\frac{1}{r_{\varepsilon}} \left( u^a_3(x', r_{\varepsilon}) - u^a_3(r_{\varepsilon} x') \right) = \frac{1}{r_{\varepsilon}} \left( u^a_3(x', 0) + \int_0^{r_{\varepsilon}} \frac{\partial u^a_3}{\partial x_3}(x', t) \, dt - u^a_3(0) - \int_0^{r_{\varepsilon}} \nabla u^3_3(x') \, dx' \, dt \right)
\]
\[
= \frac{1}{r_{\varepsilon}} \int_0^{r_{\varepsilon}} \frac{\partial u^a_3}{\partial x_3}(x', t) \, dt - \frac{1}{r_{\varepsilon}} \int_0^{r_{\varepsilon}} \nabla u^3_3(x') \, dx' \, dt \leq C,
\]
and hence, its norm in \( L^2(\{0 < x_3 < r_{\varepsilon}\}) \) tends to zero.
• Term $\frac{1}{(r^\varepsilon)^2} e_{\alpha\beta}(u_{a\varepsilon})$. From (6.11) we have:

$$\frac{\partial u_{a\varepsilon}}{\partial x_\beta} = \frac{x_3}{r^\varepsilon} \left( r^\varepsilon \frac{\partial v_{a}^b}{\partial x_{\beta}}(x', r^\varepsilon) + (r^\varepsilon)^2 \frac{\partial w_{a}^b}{\partial x_\beta}(x', r^\varepsilon) \right) + \left(1 - \frac{x_3}{r^\varepsilon}\right) \varepsilon (r^\varepsilon)^2 \left( \frac{\partial v_{\alpha}^b}{\partial x_{\beta}}(r^\varepsilon x') + \varepsilon \frac{\partial w_{\alpha}^b}{\partial x_{\beta}}(r^\varepsilon x', 0) \right),$$

and hence, since $e_{\alpha\beta}(v^a) = 0$:

$$\frac{1}{(r^\varepsilon)^2} e_{\alpha\beta}(u_{a\varepsilon}) = \frac{x_3}{r^\varepsilon} e_{\alpha\beta}(u^a)(x', r^\varepsilon) + \left(1 - \frac{x_3}{r^\varepsilon}\right) \varepsilon \left( e_{\alpha\beta}(\zeta^b)(r^\varepsilon x') + \varepsilon e_{\alpha\beta}(v^b)(r^\varepsilon x', 0) \right),$$

which gives, from the regularity of $w^a$, $\zeta^b$ and $v^b$ (see (6.8)):

$$\left| \frac{1}{(r^\varepsilon)^2} e_{\alpha\beta}(u_{a\varepsilon}) \right| \leq C + C \varepsilon (1 + \varepsilon) \leq C,$$

and hence, the norm in $L^2([0 < x_3 < r^\varepsilon])$ of this term tends to zero.

• Term $\frac{1}{r^\varepsilon} e_{\alpha\beta}(u_{a\varepsilon})$. From (6.11) we have:

$$\frac{\partial u_{a\varepsilon}}{\partial x_\beta} = \frac{1}{r^\varepsilon} \left( u_{a}^b(r^\varepsilon) + r^\varepsilon v_{a}^b(x', r^\varepsilon) + (r^\varepsilon)^2 w_{a}^b(x', r^\varepsilon) \right) - \varepsilon \left( C_{\alpha}^b(r^\varepsilon x') + \varepsilon C_{\alpha}^b(r^\varepsilon x', 0) \right),$$

and, from (6.12):

$$\frac{\partial u_{a\varepsilon}}{\partial x_\alpha} = \frac{x^3}{r^\varepsilon} \left( \frac{\partial u_{a}^b}{\partial x_\alpha}(x', r^\varepsilon) + r^\varepsilon \frac{\partial v_{a}^b}{\partial x_\alpha}(x', r^\varepsilon) \right) + \left(1 - \frac{x_3}{r^\varepsilon}\right) r^\varepsilon \left( \frac{\partial w_{a}^b}{\partial x_\alpha}(r^\varepsilon x') + \varepsilon^2 \frac{\partial w_{a}^b}{\partial x_\alpha}(r^\varepsilon x', 0) \right),$$

so that:

$$\frac{2}{r^\varepsilon} e_{\alpha\beta}(u_{a\varepsilon}) = \frac{1}{r^\varepsilon} \left( \frac{\partial u_{a\varepsilon}}{\partial x_\beta} + \frac{\partial u_{a\varepsilon}}{\partial x_\beta} \right) = T_1 + T_2 + T_3 + T_4,$$

with:

$$T_1 = \frac{1}{(r^\varepsilon)^2} \left( u_{a}^b(r^\varepsilon) + x_3 \frac{\partial u_{a}^b}{\partial x_\alpha}(x', r^\varepsilon) \right),$$

$$T_2 = \frac{1}{r^\varepsilon} \left( v_{a}^b(x', r^\varepsilon) - \varepsilon \left( C_{\alpha}^b(r^\varepsilon x') + \varepsilon C_{\alpha}^b(r^\varepsilon x', 0) \right) \right),$$

$$T_3 = u_{a}^b(x', r^\varepsilon),$$

$$T_4 = \frac{x_3}{r^\varepsilon} \frac{\partial u_{a}^b}{\partial x_\alpha}(x', r^\varepsilon) + \left(1 - \frac{x_3}{r^\varepsilon}\right) \left( \frac{\partial u_{a}^b}{\partial x_\alpha}(r^\varepsilon x') + \varepsilon \frac{\partial w_{a}^b}{\partial x_\alpha}(r^\varepsilon x', 0) \right).$$

We will show that the norm in $L^2([0 < x_3 < r^\varepsilon])$ of each term tends to zero.

○ Term $T_1$. As $u_{a}^b(0) = 0$, we have:

$$u_{a}^b(r^\varepsilon) = \int_0^{r^\varepsilon} \frac{d u_{a}^b}{d x_3}(t) dt,$$
and, as \( \epsilon_3(A) = 0 \):
\[
x_3 \frac{\partial u_3^a}{\partial x_3}(x', r^\epsilon) = -x_3 \frac{d u_3^a}{d x_3}(r^\epsilon) = -x_3 \frac{d u_3^a}{d x_3}(r^\epsilon) + x_3 \frac{d u_3^a}{d x_3}(r^\epsilon) \int_0^{r^\epsilon} \left( \frac{d u_3^a}{d x_3}(t) - \frac{d u_3^a}{d x_3}(r^\epsilon) \right) dt,
\]
so that, since \( \frac{d u_3^a}{d x_3}(0) = 0 \):
\[
u_3^a(r^\epsilon) + x_3 \frac{d u_3^a}{d x_3}(x', r^\epsilon) = \left( 1 - \frac{x_3}{r^\epsilon} \right) \int_0^{r^\epsilon} \frac{d u_3^a}{d x_3}(t) dt + x_3 \frac{d u_3^a}{d x_3}(r^\epsilon) \int_0^{r^\epsilon} \left( \frac{d u_3^a}{d x_3}(t) - \frac{d u_3^a}{d x_3}(r^\epsilon) \right) dt = \int_0^{r^\epsilon} \int_0^{r^\epsilon} \frac{d^2 u_3^a}{d x_3^2}(r) d\tau dt,
\]
and, from the regularity of \( u_3^a \):
\[
|T_1| = \frac{1}{(r^\epsilon)^2} \left| \nu_3^a(r^\epsilon) + x_3 \frac{d u_3^a}{d x_3}(x', r^\epsilon) \right| \leq \frac{1}{(r^\epsilon)^2} \int_0^{r^\epsilon} \int_0^{r^\epsilon} \left| \frac{d^2 u_3^a}{d x_3^2}(r) \right| d\tau dt \leq C,
\]
so the norm in \( L^2(\{0 < x_3 < r^\epsilon\}) \) of \( T_1 \) tends to zero.

**Term \( T_2 \).** We have:
\[
T_2 = \frac{1}{r^\epsilon} \nu_3^a(x', r^\epsilon) - \frac{\epsilon}{r^\epsilon} \left( \zeta^b_1(r^\epsilon, x') + \epsilon v_3^b(r^\epsilon, x') \right).
\]
But, as \( c(0) = 0 \):
\[
\left| \frac{1}{r^\epsilon} \nu_3^a(x', r^\epsilon) \right| \leq \frac{C}{r^\epsilon} |c(r^\epsilon)| \leq C,
\]
and the norm of this term in \( L^2(\{0 < x_3 < r^\epsilon\}) \) tends to zero. On the other hand, as \( \epsilon^2 \ll r^\epsilon \) and as \( \zeta^b_1 \) and \( v_3^b \) are uniformly bounded, due to the regularity conditions (6.8), we have:
\[
\left| \frac{\epsilon}{r^\epsilon} \left( \zeta^b_1(r^\epsilon, x') + \epsilon v_3^b(r^\epsilon, x') \right) \right| \leq C \frac{\epsilon}{r^\epsilon},
\]
so the norm of this term in \( L^2(\{0 < x_3 < r^\epsilon\}) \) is bounded by \( C \epsilon / \sqrt{r^\epsilon} \), which tends to zero by assumption. Therefore the norm in \( L^2(\{0 < x_3 < r^\epsilon\}) \) of \( T_2 \) tends to zero.

**Terms \( T_3 \) and \( T_4 \).** These terms are bounded, due to the regularity conditions (6.8), and therefore the norms in \( L^2(\{0 < x_3 < r^\epsilon\}) \) of those two terms tend to zero.

**7. PROOF OF STRONGER CONVERGENCES AND PROOF OF COROLLARY 1**

Actually, the stronger convergences in Theorem 1 are deduced from Corollary 1. The proof is as follows.

Taking \( \mathbf{E}^\epsilon = (E^\alpha, E^\beta, E^\gamma) \) as test function in the variational equation of problem (2.3), we get
\[
\begin{cases}
E^\epsilon = \int_{\Omega_3} [A^\alpha \frac{\partial E^\alpha}{\partial x_3}, \frac{\partial E^\alpha}{\partial x_3}] dx + q^\epsilon \int_{\Omega_3} [A^\alpha \frac{\partial E^\alpha}{\partial x_3}, \frac{\partial E^\alpha}{\partial x_3}] dx \\
= \int_{\Omega_3} f^\alpha \frac{\partial E^\alpha}{\partial x_3} dx + \int_{\Omega_3} g^\alpha \frac{\partial E^\alpha}{\partial x_3} dx + \int_{\Omega_3} [g^\alpha, \frac{\partial E^\alpha}{\partial x_3}] dx + \int_{\Omega_3} [h^\alpha, \frac{\partial E^\alpha}{\partial x_3}] dx \\
+ \int_{\Omega_3} h^\alpha \frac{\partial E^\alpha}{\partial x_3} dx + \int_{\Omega_3} \left( h^\alpha \frac{\partial E^\alpha}{\partial x_3} |_{x_3=0} + h^\alpha \frac{\partial E^\alpha}{\partial x_3} |_{x_3=-1} \right) dx',
\end{cases}
\]
(7.1)

We are going to pass to the limit in the right-hand side of the above equality.
• If $0 < q < +\infty$, we have, from the convergences already proved in Theorem 1 and from classical compactness arguments,

\[
(\pi \varepsilon, \varepsilon) \to (\pi^a, \varepsilon^a) \quad \text{weakly in } (L^2(\Omega^a))^3 \times (L^2(\Omega^b))^3,
\]

\[
(\pi^a, \varepsilon^a) \to (\pi^a, \varepsilon^a) \quad \text{strongly in } (L^2(\Omega^a))^3,
\]

\[
\pi^a |_{\Sigma^a} \to \pi^a |_{\Sigma^a} \quad \text{strongly in } (L^2(\Sigma^a))^3,
\]

\[
\pi^b |_{\Sigma^b} \to \pi^b |_{\Sigma^b} \quad \text{strongly in } (L^2(\Sigma^b))^3,
\]

\[
\int_{\Omega^a} \left[ A^a \pi^a, \varepsilon^a \right] \, dx \to \int_{\Omega^a} \left[ A^a \pi^a, \varepsilon^a \right] \, dx,
\]

\[
\int_{\Omega^b} \left[ A^b \pi^b, \varepsilon^b \right] \, dx \to \int_{\Omega^b} \left[ A^b \pi^b, \varepsilon^b \right] \, dx.
\]

If $(g^{a\varepsilon}, g^{b\varepsilon})$ tends to $(g^a, g^b)$ strongly in $(L^2(\Omega^a))^3 \times (L^2(\Omega^b))^3$, it follows that:

\[
\mathcal{E}^\varepsilon = \int_{\Omega^a} f^a \cdot \pi^a \, dx + \int_{\Omega^b} f^b \cdot \pi^b \, dx + \int_{\Omega^a} \left[ g^a, \varepsilon^a \right] \, dx + \int_{\Omega^b} \left[ g^b, \varepsilon^b \right] \, dx
\]

\[
+ \int_{\Sigma^a} h^{a\varepsilon} \cdot \pi^a \, d\sigma + \int_{\Sigma^b} \left( h^{b\varepsilon} + h^{b\varepsilon}_- \right) \, d\sigma' \to \int_{\Omega^a} f^a \cdot \pi^a \, dx + \int_{\Omega^b} f^b \cdot \pi^b \, dx + \int_{\Omega^a} \left[ g^a, \varepsilon^a \right] \, dx + \int_{\Omega^b} \left[ g^b, \varepsilon^b \right] \, dx
\]

\[
+ \int_{\Sigma^a} h^a \cdot \pi^a \, d\sigma + \int_{\Sigma^b} \left( h^b + h^b_- \right) \, d\sigma' = \int_{\Omega^a} \left[ A^a \pi^a, \varepsilon^a \right] \, dx + q \int_{\Omega^b} \left[ A^b \pi^b, \varepsilon^b \right] \, dx = \mathcal{E},
\]

which proves the first part of Corollary 1. Moreover, we get, from the convergence of $\mathcal{E}^\varepsilon$ to $\mathcal{E}$ and from a classical lower semicontinuity argument:

\[
0 = \liminf \left( \int_{\Omega^a} \left[ A^a \pi_{\varepsilon a}, \varepsilon_{\varepsilon a} \right] \, dx - \int_{\Omega^a} \left[ A^a \pi^a, \varepsilon^a \right] \, dx - q \int_{\Omega^b} \left[ A^b \pi^b, \varepsilon^b \right] \, dx - q \int_{\Omega^b} \left[ A^b \pi^b, \varepsilon^b \right] \, dx \right)
\]

\[
\geq \liminf \left( \int_{\Omega^a} \left[ A^a \pi_{\varepsilon a}, \varepsilon_{\varepsilon a} \right] \, dx - \int_{\Omega^a} \left[ A^a \pi^a, \varepsilon^a \right] \, dx \right) + \liminf \left( q \int_{\Omega^b} \left[ A^b \pi^b, \varepsilon^b \right] \, dx - q \int_{\Omega^b} \left[ A^b \pi^b, \varepsilon^b \right] \, dx \right)
\]

\[
= \liminf \left( \int_{\Omega^a} \left[ A^a \pi_{\varepsilon a}, \varepsilon_{\varepsilon a} \right] \, dx - \int_{\Omega^a} \left[ A^a \pi^a, \varepsilon^a \right] \, dx \right) + \liminf \left( q \left( \int_{\Omega^b} \left[ A^b \pi^b, \varepsilon^b \right] \, dx - \int_{\Omega^b} \left[ A^b \pi^b, \varepsilon^b \right] \, dx \right) \right) \geq 0,
\]

which gives, up to extraction of a new subsequence,

\[
\int_{\Omega^a} \left[ A^a \pi_{\varepsilon a}, \varepsilon_{\varepsilon a} \right] \, dx \to \int_{\Omega^a} \left[ A^a \pi^a, \varepsilon^a \right] \, dx,
\]

\[
\int_{\Omega^b} \left[ A^b \pi_{\varepsilon a}, \varepsilon_{\varepsilon a} \right] \, dx \to \int_{\Omega^b} \left[ A^b \pi^a, \varepsilon^a \right] \, dx.
\]
It follows that:
\[
C \| \pi^{\varepsilon} - \pi^0 \|^2_{L^2(\Omega^q)^{3 \times 3}} \leq \int_{\Omega^q} [A^a(\pi^{\varepsilon} - \pi^a), (\pi^{\varepsilon} - \pi^a)] \, dx
\]
\[
= \int_{\Omega^q} [A^a\pi^{\varepsilon}, \pi^a] \, dx + \int_{\Omega^q} [A^a\pi, \pi^a] \, dx - \int_{\Omega^q} [A^a\pi^{\varepsilon}, \pi^a] \, dx - \int_{\Omega^q} [A^a\pi^a, \pi^{\varepsilon}] \, dx \to 0,
\]
and hence \( \pi^{\varepsilon} \) tends to \( \pi^a \) strongly in \( (L^2(\Omega^q))^3 \times 3 \). Therefore \( e(\pi^{\varepsilon}) \) tends to \( e(\pi^a) \) strongly in \( (L^2(\Omega^q))^3 \times 3 \) and then, from Korn’s inequality, \( \pi^{\varepsilon} \) tends to \( \pi^a \) strongly in \( (H^1(\Omega^q))^3 \). By the same proof, \( \pi^{\varepsilon} \) tends to \( \pi^b \) strongly in \( (L^2(\Omega^q))^3 \times 3 \) and \( u^{\varepsilon} \) tends to \( u^b \) strongly in \( (H^1(\Omega^q))^3 \). In conclusion, we proved the stronger convergences mentioned in Theorem 1 when \( 0 < q < +\infty \).

- If \( q = +\infty \), we have seen that:
  \[
  \tilde{u}^{\varepsilon} \to \tilde{u}^b = 0 \text{ strongly in } (H^1(\Omega^q))^3,
  \]
  \[
  \tilde{v}^{\varepsilon} \to \tilde{v}^b = 0 \text{ strongly in } (L^2(\Omega^q))^3 \times 3,
  \]
and, with appropriate changes in the above proof, we have, if \( g^{\varepsilon} \) tend to \( g^a \) strongly in \( (L^2(\Omega^q))^3 \times 3 \):

\[
E^\varepsilon \to \int_{\Omega^q} f^a \pi^a \, dx + \int_{\Omega^q} [g^a, \pi^a] \, dx + \int_{\Omega^q} h^a \pi^a \, d\sigma = \int_{\Omega^q} [A^a\pi, \pi^a] \, dx = E_\infty,
\]

\[
0 = \liminf \left( \int_{\Omega^q} [A^a\pi^{\varepsilon}, \pi^a] \, dx - \int_{\Omega^q} [A^a\pi^a, \pi^a] \, dx + q^\varepsilon \int_{\Omega^q} [A^b\pi^{\varepsilon}, \pi^{\varepsilon}] \, dx \right)
\]
\[
\geq \liminf \left( \int_{\Omega^q} [A^a\pi^{\varepsilon}, \pi^a] \, dx - \int_{\Omega^q} [A^a\pi^a, \pi^a] \, dx \right) + \liminf \left( q^\varepsilon \int_{\Omega^q} [A^b\pi^{\varepsilon}, \pi^{\varepsilon}] \, dx \right) \geq 0,
\]

\[
\int_{\Omega^q} [A^a\pi^{\varepsilon}, \pi^a] \, dx \to \int_{\Omega^q} [A^a\pi^a, \pi^a] \, dx,
\]

\[
q^\varepsilon \int_{\Omega^q} [A^b\pi^{\varepsilon}, \pi^{\varepsilon}] \, dx \to 0,
\]

\( \pi^{\varepsilon} \to \pi^a \) strongly in \( (L^2(\Omega^q))^3 \times 3 \),

\( \pi^{\varepsilon} \to \pi^a \) strongly in \( (H^1(\Omega^q))^3 \).

- If \( q = 0 \), we have, with \( \tilde{u}^x = q^0 \tilde{u}^x \), \( \tilde{v}^x = q^0 \tilde{v}^x \):

\[
\begin{aligned}
E^x &= \frac{1}{q^x} \int_{\Omega^q} [A^a\tilde{u}^{ax}, \tilde{v}^{ax}] \, dx + \int_{\Omega^q} [A^b\tilde{u}^{bc}, \tilde{v}^{bc}] \, dx \\
&= \int_{\Omega^q} f^{ax} \tilde{u}^{ax} \, dx + \int_{\Omega^q} f^{bc} \tilde{u}^{bc} \, dx + \int_{\Omega^q} [g^{ax}, \tilde{v}^{ax}] \, dx + \int_{\Omega^q} [g^{bc}, \tilde{v}^{bc}] \, dx \\
&\quad + \int_{\Omega^q} h^{ax} \tilde{u}^{ax} \, d\sigma + \int_{\Omega^q} \left( h^{bc}_{+} \tilde{u}^{bc}_{x=0} + h^{bc}_{-} \tilde{u}^{bc}_{x=-1} \right) \, dx',
\end{aligned}
\] (7.2)
\[ u^{a \varepsilon} \rightarrow u^a = 0 \text{ strongly in } (H^1(\Omega^a))^3, \]
\[ e^{a \varepsilon} \rightarrow e^a = 0 \text{ strongly in } (L^2(\Omega^a))^3, \]

and we have, if \( g^{b \varepsilon} \) tend to \( g^b \) strongly in \( (L^2(\Omega^b))^3 \):

\[ E^\varepsilon \longrightarrow \int_{\Omega^b} f^b \bar{u}^b \, dx + \int_{\Omega^b} \left[ g^b(\bar{u}^\varepsilon, \bar{e}^\varepsilon) \right] \, dx + \int_{\omega^b} \left( h^b_+ \bar{u}^{\varepsilon 2} f^b \big|_{z_2 = 0} + h^b_- \bar{u}^{\varepsilon 2} f^b \big|_{z_2 = -1} \right) \, dx' = \int_{\Omega^b} [A^b \bar{v}^b, \bar{w}^b] \, dx = E_0, \]

\[ 0 = \liminf \left( \frac{1}{q^b} \int_{\Omega^b} [A^a \bar{v}^{a\varepsilon}, \bar{e}^{a\varepsilon}] \, dx + \int_{\Omega^b} [A^b \bar{v}^{b\varepsilon}, \bar{e}^{b\varepsilon}] \, dx - \int_{\Omega^b} [A^b \bar{v}^b, \bar{w}^b] \, dx \right) \geq 0, \]

\[ \int_{\Omega^b} [A^b \bar{v}^{b\varepsilon}, \bar{e}^{b\varepsilon}] \, dx \longrightarrow \int_{\Omega^b} [A^a \bar{v}^a, \bar{w}^a] \, dx, \]

\[ \frac{1}{q^a} \int_{\Omega^a} [A^a \bar{v}^{a\varepsilon}, \bar{e}^{a\varepsilon}] \, dx \longrightarrow 0, \]

\[ q^a \bar{v}^{a\varepsilon} = \bar{e}^{a\varepsilon} \rightarrow \bar{v}^{a} \text{ strongly in } (L^2(\Omega^a))^3, \]

\[ \sqrt{q^a} \bar{v}^{a\varepsilon} = \frac{1}{\sqrt{q^a}} \bar{e}^{a\varepsilon} \rightarrow 0 \text{ strongly in } (L^2(\Omega^a))^3, \]

\[ q^a \bar{w}^{a\varepsilon} \rightarrow \bar{w}^a \text{ strongly in } (H^1(\Omega^a))^3. \]

8. APPENDIX

8.1. The definitions of \((v^a, w^a)\) and \((v^b, w^b)\) as suitable limits

For the convenience of the reader, we give in this appendix a sketch of the proof of the following result, mentioned in Section 4.2 (for thin cylinders, a complete proof is given in [28]). The case of plates is analogous and simpler.

**Lemma 4.** (i) Let \( \{v^c\}_c \) be a sequence in \( (H^1(\Omega^a))^3 \) such that \( v^c = 0 \) on \( T^a = \omega^a \times \{1\} \) and:

\[ \{e^{a\varepsilon}(v^c)\}_c \text{ is bounded in } (L^2(\Omega^a))^3. \]

Let \( \mathcal{W}^a \) be the space defined in Section 2.2 and let:

\[ \mathcal{V}^a = \left\{ v^a \in (H^1(\Omega^a))^2 \times L^2(0,1; H^1(\omega^a)), \quad e(1) = 0, \quad v^1_2 = -c x_2, \quad v^2_2 = c x_1, \quad \int_{\omega^a} v^a_3(x', x_3) \, dx' = 0, \quad \text{for a.e. } x_3 \in (0,1) \right\}, \]

(note that \( \mathcal{V}^a \) satisfies the same requirements as \( \mathcal{V}^a \), in Section 2.2, except \( c(0) = 0 \)). Then there exists a pair...
\((v^\alpha, w^\alpha) \in V^\alpha \times W^\alpha\) such that for all \(\alpha, \beta = 1, 2\):

\[
\frac{1}{r^2} e_{\alpha 3}(u^\varepsilon) \rightharpoonup e_{\alpha 3}(v^\alpha) \text{ weakly in } L^2(\Omega^\alpha),
\]

\[
\frac{1}{(r^2)^2} e_{\alpha \beta}(u^\varepsilon) \rightharpoonup e_{\alpha \beta}(v^\alpha) \text{ weakly in } L^2(\Omega^\alpha).
\]

Moreover, denoting by \((c, v_3^\varepsilon)\) the couple defining \(v^\varepsilon\) and setting:

\[
e^\varepsilon(x_3) = \frac{\int_{\omega^\alpha} (x_1 u_2^\varepsilon(x', x_3) - x_2 u_1^\varepsilon(x', x_3)) \, dx'}{r^\varepsilon \int_{\omega^\alpha} (x_1^2 + x_2^2) \, dx'},
\]

\[
v_3^\varepsilon = \frac{u_3^\varepsilon}{r^\varepsilon} - \frac{1}{|\omega^\alpha|} \int_{\omega^\alpha} \frac{u_3^\varepsilon}{r^\varepsilon} \, dx' + \frac{1}{|\omega^\alpha|} \sum_{\alpha} x_\alpha \frac{d}{dx_3} \int_{\omega^\alpha} u_\alpha \, dx',
\]

we have:

\[
e^\varepsilon \to c \text{ strongly in } L^2(0, 1),
\]

\[
v_3^\varepsilon \to v_3^\alpha \text{ weakly in } H^{-1}(0, 1; H^1(\omega^\alpha)).
\]

Finally, setting:

\[
d_\alpha^\varepsilon(x_3) = \frac{1}{|\omega^\alpha|} \int_{\omega^\alpha} \frac{u_\alpha^\varepsilon(x', x_3)}{r^\varepsilon} \, dx'
\]

and \(x_1^R = -x_2, x_2^R = x_1\), we have:

\[
\frac{u_\alpha^\varepsilon}{(r^\varepsilon)^2} - \frac{1}{r^\varepsilon} (e^\varepsilon x_\alpha^R + d^\alpha_\alpha) \to u_\alpha^\alpha \text{ weakly in } L^2(0, 1; H^1(\omega^\alpha)).
\]

(ii) If \(\{u^\varepsilon\}_\varepsilon\) is a sequence in \((H^1(\Omega^\varepsilon))^3\) such that \(u^\varepsilon = 0\) on \(\Sigma^b = \partial \omega^b \times (-1, 0)\) and:

\[
\{e^{bx_\varepsilon}(u^\varepsilon)\}_\varepsilon \text{ is bounded in } (L^2(\Omega^\varepsilon))^3 \times 3,
\]

then there exists a pair \((v^b, w^b) \in V^b \times W^b\) such that for all \(\alpha = 1, 2\):

\[
\frac{1}{\varepsilon} e_{\alpha 3}(u^\varepsilon) \rightharpoonup e_{\alpha 3}(v^b) \text{ weakly in } L^2(\Omega^b),
\]

\[
\frac{1}{\varepsilon^2} e_{33}(u^\varepsilon) \rightharpoonup e_{33}(w^b) \text{ weakly in } L^2(\Omega^b).
\]

In addition, we have:

\[
\frac{u_\alpha^\varepsilon}{\varepsilon} - \bar{u}_\alpha^\varepsilon - \int_{-1}^0 \left( \frac{u_\alpha^\varepsilon}{\varepsilon} - \bar{u}_\alpha^\varepsilon \right) \, dx_3 \to v_\alpha^b \text{ weakly in } L^2(\omega^b; H^1(-1, 0)), \text{ for } \alpha = 1, 2,
\]

with \(\bar{u}_\alpha^\varepsilon\) defined by:

\[
\bar{u}_\alpha^\varepsilon = -\int_0^1 \frac{1}{\varepsilon} \frac{\partial u_\alpha^\varepsilon}{\partial x_3}(x', s) \, ds.
\]

Moreover:

\[
\frac{u_3^\varepsilon}{\varepsilon^2} - \int_{-1}^0 \frac{u_3^\varepsilon}{\varepsilon^2} \, dx_3 \to w_3^b \text{ weakly in } L^2(\omega^b; H^1(-1, 0)).
\]
Proof of (i). We use the following decomposition and estimate, whose proof may be found for instance in [20,21]: there exists a positive constant $C$ such that, for every $u$ in $L^2(0,1;H^1(\omega^a))^2$, there exist $\bar{u}$ and $\hat{u}$ satisfying:

\[
\begin{cases}
    u = \bar{u} + \hat{u}, \\
    \int_\omega \bar{u}_\alpha(x',x_3) \, dx' = 0, \\
    \int_\omega (x_1 \bar{u}_2(x',x_3) - x_2 \bar{u}_1(x',x_3)) \, dx' = 0, \\
    e_{\alpha\beta}(\hat{u}) = 0, \quad \forall \alpha, \beta = 1, 2,
\end{cases}
\tag{8.15}
\]

The function $\hat{u}$ is a rigid displacement:

\[
\hat{u}_\alpha(x',x_3) = c(x_3) x'_\alpha + d_\alpha(x_3),
\tag{8.17}
\]

with $x'_1 = -x_2$, $x'_2 = x_1$ ($R$ for “rotation”). Applying (8.15) and (8.17) to $u = \frac{1}{r^c}(u_1^\varepsilon, u_2^\varepsilon)$, we get:

\[
\frac{1}{r^c} u_\alpha^\varepsilon = \bar{u}_\alpha + \hat{u}_\alpha^\varepsilon, \quad \text{with} \quad \hat{u}_\alpha^\varepsilon = c(x_3) x'_\alpha + d_\alpha^\varepsilon(x_3).
\tag{8.18}
\]

One can check easily that the functions $c^\varepsilon$ and $d^\varepsilon_\alpha$ are given in terms of $u^\varepsilon$ by the formulae (8.4) and (8.8). From (8.16), we obtain:

\[
\|\bar{u}_\alpha\|_{L^2(0,1;H^1(\omega^a))} \leq C \sum_{\alpha, \beta} \left\| e_{\alpha\beta}(u) \right\|_{L^2(\Omega^c)}.
\]

Setting $w_\alpha^\varepsilon = \bar{u}_\alpha / r^c$ and using (8.1), it follows that:

\[
\|w_\alpha^\varepsilon\|_{L^2(0,1;H^1(\omega^a))} \leq C.
\]

So, taking a subsequence of $\varepsilon$, still denoted by the same letter, we may assume the existence of $w_\alpha^0$ such that:

\[
w_\alpha^\varepsilon \rightharpoonup w_\alpha^0 \quad \text{weakly in} \quad L^2(0,1;H^1(\omega^a)), \quad \forall \alpha = 1, 2,
\]

that is (8.9). Moreover it is clear that $(u_1^\varepsilon, u_2^\varepsilon, 0)$ and $u^0 = (u_1^0, u_2^0, 0)$ belong to $\mathcal{W}^a$. Since (8.18) implies that:

\[
\frac{1}{(r^c)^2} e_{\alpha\beta}(u^\varepsilon) = e_{\alpha\beta}(w^\varepsilon),
\]

we see that (8.3) is proved.

It remains to prove the convergences involving $v^a$. In Section 5.3, it is proved that there exists $c$ in $H^1(0,1)$, $c(1) = 0$ such that, for a subsequence of $\varepsilon$, (8.6) holds true. As for the other convergences involving $v^a$, we use again the decomposition (8.18), from which we deduce the following equality:

\[
\frac{2}{r^c} e_{\alpha3}(u^\varepsilon) = \frac{\partial \bar{u}_3^\varepsilon}{\partial x_3} + \frac{d c^\varepsilon}{d x_3} x'_\alpha + \frac{d d_3^\varepsilon}{d x_3} + \frac{1}{r^c} \frac{\partial u_3^\varepsilon}{\partial x_\alpha} \quad \forall \alpha = 1, 2.
\tag{8.19}
\]

Now, setting

\[
v_3^\varepsilon = \frac{u_3^\varepsilon}{r^c} - \frac{1}{|\omega^a|} \int_{\omega^a} \frac{u_3^\varepsilon}{r^c} \, dx' + \sum_{\beta} x_\beta \frac{d}{d x_3} d_3^\varepsilon(x_3),
\]
equality (8.19) can be written as:

\[ \frac{2}{\varepsilon} e^{\alpha \beta}(u^\varepsilon) = \frac{d e^\alpha}{d x_3} + \frac{\partial v^\varepsilon}{\partial x_\alpha} + \frac{\partial v^\varepsilon_\alpha}{\partial x_3}. \]  

(8.20)

The following estimate is proved in [24]:

\[ \|v^\varepsilon_\alpha\|_{H^{-1}(0,1; H^1(\omega^\varepsilon))} \leq C \left( \sum_{\alpha} \|e^{\alpha \beta}(y^\varepsilon)\|_{L^2(\Omega^\varepsilon)} + \sum_{\alpha} \|e^{\alpha \varepsilon}(y^\varepsilon)\|_{L^2(\Omega^\varepsilon)} \right), \]

so that, from (8.1), the sequence \{v^\varepsilon_\alpha\}_\varepsilon is bounded in \( H^{-1}(0,1; H^1(\omega^\varepsilon)) \). Therefore there exists some \( v^\alpha_3 \) in \( H^{-1}(0,1; H^1(\omega^\varepsilon)) \), with zero mean-value on \( \omega^\varepsilon \), such that (8.7) holds true (for a subsequence). It follows also from (8.1) that:

\[ \frac{1}{\varepsilon} e^{\alpha \beta}(u^\varepsilon) \rightarrow \tau_\alpha \text{ weakly in } L^2(\Omega^\varepsilon), \]  

(8.21)

(again for some subsequence and some \( \tau_\alpha \) in \( L^2(\Omega^\varepsilon) \)). Moreover, since \( w^\varepsilon_\alpha \) is bounded in \( L^2(0,1; H^1(\omega^\varepsilon)) \):

\[ \frac{\partial v^\alpha_3}{\partial x_3} = \tau_\varepsilon \frac{\partial w^\varepsilon_\alpha}{\partial x_3} \rightarrow 0 \text{ in the sense of distributions}. \]  

(8.22)

By passing to the limit in (8.20), using (8.6), (8.7), (8.21) and (8.22), we get:

\[ 2\tau_\alpha = \frac{d e}{d x_3} x^R_\alpha + \frac{\partial}{\partial x_\alpha} v^\alpha_3, \]  

(8.23)

which, using \( e \in H^1(0,1) \), implies that:

\[ \frac{\partial}{\partial x_\alpha} v^\alpha_3 \in L^2(\Omega^\varepsilon). \]  

(8.24)

From (8.24) and from the fact that \( v^\alpha_3 \) belongs to \( H^{-1}(0,1; H^1(\omega^\varepsilon)) \) and has zero mean-value on \( \omega^\varepsilon \), one deduces that \( v^\alpha_3 \) belongs to \( L^2(0,1; H^1(\omega^\varepsilon)) \), so that \( v^\alpha = (e(x_3) x^R_\alpha, v^\alpha_3) \in V^\alpha \), and satisfies (8.2).

**Proof of (ii).** Now we prove the analogous of the previous properties in the framework of 3d-2d reduction of dimension. This is much easier. Indeed, in order to prove (8.11) and (8.13), we consider the sequence \{v^\varepsilon_\alpha\}_\varepsilon defined by:

\[ v^\varepsilon_\alpha = \frac{u^\varepsilon_\alpha}{\varepsilon} - \bar{u}^\varepsilon_\alpha - \int_{-1}^{0} \left( \frac{u^\varepsilon_\alpha}{\varepsilon} - \bar{u}^\varepsilon_\alpha \right) dx_3, \]

and

\[ \bar{u}^\varepsilon = \left( -\int_{0}^{x_3} \frac{1}{\varepsilon} \frac{\partial u^\varepsilon_3}{\partial x_1}(x',s) ds, -\int_{0}^{x_3} \frac{1}{\varepsilon} \frac{\partial u^\varepsilon_3}{\partial x_2}(x',s) ds \frac{u^\varepsilon_3}{\varepsilon} \right). \]

Then we have as above:

\[ \frac{\partial v^\varepsilon_\alpha}{\partial x_3} = \frac{2}{\varepsilon} e^{\alpha \beta}(u^\varepsilon), \]  

(8.25)

which is bounded in \( L^2(\Omega^h) \), as a consequence of (8.10). As \( v^\alpha_3 \) has mean-value zero with respect to \( x_3 \), it is bounded in \( L^2(\omega^h; H^1(-1,0)) \), so that (8.13) holds true, i.e.:

\[ v^\varepsilon_\alpha \rightarrow v^\alpha_3 \text{ weakly in } L^2(\omega^h; H^1(-1,0)), \]  

(8.26)

for some subsequence of \( \varepsilon \) and for some \( v^\alpha_3 \) in \( L^2(\omega^h; H^1(-1,0)) \).
Setting \( v^b = (v_1^b, v_2^b, 0) \), we get:

\[
\varepsilon_{\alpha 3}(v^b) = \frac{1}{2} \frac{\partial v_{\alpha}^b}{\partial x_3},
\]

so that we derive (8.11) from (8.25) and (8.26).

Finally we prove (8.12) and (8.14), by introducing the sequence of functions \( w^\varepsilon \) defined by:

\[
w^\varepsilon = \frac{1}{\varepsilon^2} u_3^\varepsilon - \int_{-1}^0 \frac{1}{\varepsilon^2} u_3^\delta \, dx_3,
\]

which is bounded in \( L^2(\omega^b; H^1(-1,0)) \), since \( \frac{\partial w^\varepsilon}{\partial x_3} = \frac{1}{\varepsilon^2} \varepsilon_{33}(u^\varepsilon) \) is bounded in \( L^2(\Omega^b) \), due to (8.10). So, extracting a subsequence, we can find \( v_3^b \) in \( L^2(\omega^b; H^1(-1,0)) \), with mean-value zero in \( x_3 \), such that (8.12) and (8.14) hold true, which completes the proof of Lemma 4.

### 8.2. The density arguments

In Section 6, we have mentioned four density arguments. These are stated in the following lemmata and proved below. This is done for the sake of completeness, since Lemmata 7 and 8 are very classical, Lemma 5 is classical and very similar to the density result proved in [13], while Lemma 6, though less classical, results from Theorem 9.1.3 of [2].

**Lemma 5.** Let \( v \in H^1_0(\omega^b), 0 \in \omega^b \subset \mathbb{R}^2 \). There exist a sequence of positive numbers \( r_n \), tending to zero, and a sequence of functions \( v^n \in H^1_0(\omega^b) \) such that:

\[
v^n = 0 \text{ in the ball } B^n \text{ of center } 0 \text{ and radius } r^n, \quad v^n \rightarrow v \text{ in } H^1_0(\omega^b).
\]

**Proof.** Let \( \tilde{V} = \{ v \in C^1(\overline{\omega^b}), v = 0 \text{ on } \partial \omega^b \} \). As \( \tilde{V} \) is dense in \( H^1_0(\omega^b) \), we may restrict to \( v \in \tilde{V} \). Then the proof goes as follows. For any integer \( n \), we consider two balls \( B^n \) and \( B'^n \in \omega^b \subset \mathbb{R}^2 \), with center 0 and respective radii \( r^n \) and \( R^n \), to be determined later on, and such that \( 0 < r^n < R^n \). Then we define \( v^n \in H^1_0(\omega^b) \) by:

\[
v^n = 0 \text{ in } B^n, \quad v^n = v \text{ in } \omega^b \setminus B'^n, \quad v^n = (1 - \phi^n) v \text{ in } B'^n \setminus B^n,
\]

where \( \phi^n \) is the solution of the capacity problem in \( B'^n \setminus B^n \):

\[
\Delta \phi^n = 0 \text{ in } B'^n \setminus B^n, \quad \phi^n = 1 \text{ on } \partial B^n, \quad \phi^n = 0 \text{ on } \partial B'^n.
\]

It is clear that \( v^n \in W^{1,\infty}(\omega^b) \cap H^1_0(\omega^b) \) and \( v^n = 0 \) in \( B^n \). We are going to prove that, for convenient \( r^n \) and \( R^n \), \( v^n \rightarrow v \) in \( H^1_0(\omega^b) \). Actually, as \( 0 \leq \phi^n \leq 1 \), we have:
Lemma 6. Let $v \in H^2_0(\omega^b)$, $0 \in \omega^b \subset \mathbb{R}^2$, $v(0) = 0$. There exist a sequence of positive numbers $r^n$, tending to zero, and a sequence of functions $v^n \in H^2_0(\omega^b)$ such that:

$$v^n = 0 \text{ in the ball } B^n \text{ of center } 0 \text{ and radius } r^n,$$

$$v^n \to v \text{ weakly in } H^2_0(\omega^b).$$

Proof. • For any $v \in H^2_0(\omega^b)$, with $v(0) = 0$, there exists $\varphi \in C^2(\omega^b) \cap H^2_0(\omega^b)$ such that $\varphi$ tends to $v$ in $H^2(\omega^b)$ and hence in $C^0(\omega^b)$. In particular, $\varphi^n(0)$ tends to $v(0) = 0$. Setting $v^n = \varphi - \varphi^n(0)\phi$, with $\phi \in C(\omega^b)$ and $\phi(0) = 1$, it is clear that $v^n \in C^2(\omega^b) \cap H^2_0(\omega^b)$, $v^n(0) = 0$ and that $v^n$ tends to $v$ in $H^2(\omega^b)$.

• In view of the result of the previous step, we may restrict to $v$ in $C^2(\omega^b) \cap H^2_0(\omega^b)$, $v(0) = 0$. Let $v^n = v\phi^n$, with $\phi^n(x') = \phi(n|x'|)$ and $\phi \in C^\infty(\mathbb{R})$, $0 \leq \phi \leq 1$, $\phi = 0$ on $(-\infty, 1]$, $\phi = 1$ on $[2, +\infty)$. Clearly $v^n \in H^2_0(\omega^b)$, $v^n = 0$ in the ball of center $0$ and radius $1/n$ and we have:

$$\int_{\omega^b} |v^n - v|^2 \, dx' \leq \int_{|x'|<\frac{1}{n}} |v|^2 \, dx' \to 0,$$

that is $v^n \to v$ in $L^2(\omega^b)$. Hence the lemma is proved, as soon as we have proved that $v^n$ is bounded uniformly in $H^2_0(\omega^b)$, i.e.:

$$\frac{\partial^2 v^n}{\partial x_\alpha \partial x_\beta} \text{ is bounded in } L^2(\omega^b). \quad (8.27)$$

But we have:

$$\frac{\partial^2 v^n}{\partial x_\alpha \partial x_\beta} = v \frac{\partial^2 \phi^n}{\partial x_\alpha \partial x_\beta} + \phi^n \frac{\partial^2 v}{\partial x_\alpha \partial x_\beta} + \frac{\partial v}{\partial x_\alpha} \frac{\partial \phi^n}{\partial x_\beta} + \frac{\partial v}{\partial x_\beta} \frac{\partial \phi^n}{\partial x_\alpha}.$$

The second term is obviously bounded in $L^\infty(\omega^b)$. Moreover, since:

$$\frac{\partial \phi^n}{\partial x_\alpha} = n\phi'(n|x'|)\frac{x_\alpha}{|x'|} \text{ and } \frac{\partial^2 \phi^n}{\partial x_\alpha \partial x_\beta} = n^2 \phi''(n|x'|)\frac{x_\alpha x_\beta}{|x'|^2} + n \phi'(n|x'|) \left( \frac{\delta_{\alpha\beta}}{|x'|} - \frac{x_\alpha x_\beta}{|x'|^3} \right),$$
it follows that:
\[
\left| \frac{\partial \phi_n}{\partial x_\alpha} \right| \leq C_n, \quad \left| \frac{\partial^2 \phi_n}{\partial x_\alpha \partial x_\beta} \right| \leq C_n^2,
\]
\[
\int_{\omega^b} \left| \frac{\partial v}{\partial x_\alpha} \right|^2 \, dx' \leq C \left\| \frac{\partial v}{\partial x_\alpha} \right\|_\infty^2 \int_{1/2 < |x'| < 1} n^2 \, dx' = C, \quad \int_{\omega^b} \left| \frac{\partial^2 \phi_n}{\partial x_\alpha \partial x_\beta} \right|^2 \, dx' \leq C n^4 \, dx' = C n^2 \left\| v \right\|_{L^\infty(1/2 < |x'| < 1)}^2.
\]

But, for \(1/n < |x'| < 2/n\), \(|v(x')| \leq C|x'| \leq C/n\), since \(v\) is regular and \(v(0) = 0\). It follows that:
\[
\int_{\omega^b} \left| \frac{\partial^2 \phi_n}{\partial x_\alpha \partial x_\beta} \right|^2 \, dx' \leq C,
\]
and finally, (8.27) holds true, which completes the proof of Lemma 6.

**Lemma 7.** Let \(v \in L^2(\omega^b; H^1(-1, 0))\), \(0 \in \omega^b \subset \mathbb{R}^2\). There exist a sequence of positive numbers \(r^n\), tending to zero, and a sequence of functions \(v^n\) such that:
\[
v^n \in C^1(\overline{\Omega^b}),
\]
\[
v^n = 0 \text{ in } B^n \times \{0\}, B^n \text{ denoting the ball of center } 0 \text{ and radius } r^n,
\]
\[
v^n \to v \text{ in } L^2(\omega^b; H^1(-1, 0)).
\]

**Proof.** By density of \(C^1(\overline{\Omega^b})\) in \(L^2(\omega^b; H^1(-1, 0))\), we may restrict to \(v \in C^1(\overline{\Omega^b})\). We consider a sequence \(r^n\) of positive numbers, converging to zero, and a sequence of functions \(\phi^n : \omega^b \to \mathbb{R}\), of class \(C^\infty\), with \(\phi^n = 0\) in the ball \(B^n\) of center 0 and radius \(r^n\), \(\phi^n = 1\) outside the ball \(B^n\) of center 0 and radius \(2r^n\), \(0 \leq \phi^n \leq 1\) in \(B^n \setminus B^n\). We set \(v^n = \phi^n v\). Then clearly \(v^n \in C^1(\overline{\Omega^b})\) and:
\[
\|v^n - v\|_{L^2(\omega^b; H^1(-1, 0))}^2 = \int_{\Omega^b} |v^n - v|^2 \, dx + \int_{\Omega^b} \left| \frac{\partial}{\partial x_3} (v^n - v) \right|^2 \, dx
\]
\[
= \int_{B^n \times (-1, 0)} |v|^2 \, dx + \int_{(B^n \setminus B^n) \times (-1, 0)} |(1 - \phi^n) v|^2 \, dx + \int_{B^n \times (-1, 0)} \left| \frac{\partial v}{\partial x_3} \right|^2 \, dx + \int_{(B^n \setminus B^n) \times (-1, 0)} \left| (1 - \phi^n) \frac{\partial v}{\partial x_3} \right|^2 \, dx
\]
\[
\leq \int_{B^n \times (-1, 0)} \left( |v|^2 + \left| \frac{\partial v}{\partial x_3} \right|^2 \right) \, dx,
\]
which tends to zero, as soon as \(r^n\) tends to zero.

**Lemma 8.** Assume that \(0 \in \omega^b \subset \mathbb{R}^2\). Let \(U = \{u \in H^1(0, 1), u(1) = 0\}\), \(\tilde{U} = \{u \in C^1[0, 1], u(1) = 0\}\), \(V = H_0^2(\omega^b)\), \(\tilde{V} = C^1(\overline{\omega^b}) \cap H_0^2(\omega^b)\), \(W = \{(u, v) \in U \times V, u(0) = v(0)\}\) and \(\tilde{W} = \{(u, v) \in \tilde{U} \times \tilde{V}, u(0) = v(0)\}\). Then \(\tilde{W}\) is dense in \(W\).
Proof. It is clear that \( \tilde{U} \) is dense in \( U \) and that \( \tilde{V} \) is dense in \( V \). Therefore, for any \( (u,v) \in W \), there exists \( (\pi^u,\pi^v) \in \tilde{U} \times \tilde{V} \) such that:

\[
\pi^u \to u \quad \text{in} \quad H^1(0,1) \quad \text{and hence in} \quad C^0[0,1],
\]

\[
\pi^v \to v \quad \text{in} \quad H^2(\omega^b) \quad \text{and hence in} \quad C^0(\omega^b).
\]

Let \( \phi^1 \in C^\infty[0,1] \) with \( \phi^1(0) = 1, \phi^1(1) = 0, \phi^2 \in D(\omega^b) \) with \( \phi^2(0) = 1 \) and let:

\[
u^n = \pi^n - (\pi^n(0) - u(0))\phi^1, \]

\[
u^n = \pi^n - (\pi^n(0) - v(0))\phi^2.
\]

It is clear that \( u^n \in \tilde{U}, \nu^n \in \tilde{V} \) and \( u^n(0) = u(0) = v(0) = v^n(0) \), so that \( (u^n, \nu^n) \in \tilde{W} \). Moreover:

\[
\|u^n - \pi^n\|^2_{H^1(0,1)} = (\|\pi^n(0) - u(0)\|^2_{H^1(0,1)}) \to 0
\]

and hence \( u^n \) tends to \( u \) in \( H^1(0,1) \). Similarly \( \nu^n \) tends to \( v \) in \( H^2(\omega^b) \).

Acknowledgements. The work of Antonio Gaudiello and Jacqueline Mossino was partially supported by the project “Struttura sottili” of the 2004–2006 program “Collaborazioni interuniversitarie internazionali” of the Italian Ministry of Education, University and Research.

References