

FINITE VOLUME SCHEME FOR TWO-PHASE FLOWS IN HETEROGENEOUS POROUS MEDIA INVOLVING CAPILLARY PRESSURE DISCONTINUITIES *

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Abstract. We study a one-dimensional model for two-phase flows in heterogeneous media, in which the capillary pressure functions can be discontinuous with respect to space. We first give a model, leading to a system of degenerated nonlinear parabolic equations spatially coupled by nonlinear transmission conditions. We approximate the solution of our problem thanks to a monotonous finite volume scheme. The convergence of the underlying discrete solution to a weak solution when the discretization step tends to 0 is then proven. We also show, under assumptions on the initial data, a uniform estimate on the flux, which is then used during the uniqueness proof. A density argument allows us to relax the assumptions on the initial data and to extend the existence-uniqueness frame to a family of solution obtained as limit of approximations. A numerical example is then given to illustrate the behavior of the model.

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INTRODUCTION

The models of immiscible two-phase flows in porous media are widely used in petroleum engineering in order to predict the positions where oil could be collected. The discontinuities of the physical characteristics due to brutal change of lithology play a crucial role in the phenomenon of oil trapping, preventing the light hydrocarbons from reaching the surface. It seems that the discontinuities with respect to the space variable of a particular function, called the capillary pressure, are responsible of the phenomenon of oil-trapping [10,37].

In this paper, we consider one-dimensional two-phase flows in heterogeneous porous media, which are made of several homogeneous submedia. A simplified model of two-phase flow within this rock is described in the first section, leading to the definition of the weak solution. The transmission conditions at the interface between the different submedia are written using the graph formalism introduced in [18] for the connection of the capillary pressures, which is simple to manipulate and allows to deal with any type of discontinuity of the domain, without any compatibility constraint, contrary to what occurs in [14] and to a lesser extent in [10,22].

The graph way to connect the capillary pressures at the interfaces is well suited to be discretized by a monotonous Finite Volume scheme. A discretization is proposed in the second section of the paper. Adapting the material from the book of Eymard *et al.* [24] to our case, it is shown that the discrete solution

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provided by the scheme converges, up to a subsequence, to a weak solution as the step of the discretization tends to 0. The monotonicity of the transmission conditions is fundamental for proving the convergence of the scheme.

Unfortunately, we are not able to show the uniqueness of the weak solution to the problem, because of the lack of regularity. As it will be shown in the fourth section, supposing that the fluxes are uniformly bounded with regard to space and time is sufficient to claim the uniqueness of the solution. The uniqueness proof is an adaptation of the one given in [18] to the case where the convection is not neglected. Here again, the monotonicity of the transmission conditions at the interfaces is strongly used.

The existence of a bounded flux solution is the topic of Section 3. It is shown that if the initial data is regular enough to ensure that the initial flux is bounded with respect to space, then the flux will remain bounded with respect to space and to time. Such a result has already been obtained in [18], where a parabolic regularization of the problem had been introduced. A maximum principle on the flux follows. We also quote [10], in which a *BV*-estimate is shown on the flux. Since the monotonous schemes introduce some numerical diffusion, a strong analogy can be done between a uniformly parabolic regularization of the problem and the numerical approximation *via* a monotonous scheme. The convergence of the discrete solution to a bounded flux solution for regular enough initial data is thus naturally expected and stated in Theorem 3.1. The monotonicity of the transmission relations is essential during the proof.

We are able to prove the uniqueness of the bounded-flux solution to the problem using the doubling variable technique. This work performed in Section 4 is summarized in Theorem 4.1

In Section 5, a density argument allows to extend the existence and uniqueness frame to any initial data, using the notion of SOLA (Solution Obtained as Limit of Approximation). It is a more restrictive notion than the notion of weak solution, even if we are not able to prove the existence of a weak solution which is not a SOLA. The main result of the paper is given in Theorem 5.1, which claims that the *whole sequence* of discrete solutions built using the finite volume scheme introduced in Section 2 converges towards the unique SOLA to the problem.

Finally, a numerical example is given in Section 6. This example gives an evidence of the entrapment of a certain quantity of oil under the interface.

1. PRESENTATION OF THE PROBLEM

We consider a one-dimensional heterogeneous porous medium, which is an apposition of homogeneous porous media, representing the different geological layers. The physical properties of the medium only depend on the rock type and are piece-wise constant.

For the sake of simplicity, we only deal with two geological layers of same size. A generalization to an arbitrary finite number of geological layers would only lead to notation difficulties. In the sequel, we denote by $\Omega = (-1, 1)$ the heterogeneous porous medium, and by $\Omega_1 = (-1, 0)$, $\Omega_2 = (0, 1)$ the two homogeneous layers. The interface between the layers is thus $\{x = 0\}$. T is a positive real value.

We consider an incompressible and immiscible oil-water flow through Ω . Writing the conservation of each phase, and using Darcy’s law leads to: for all $(x, t) \in \Omega_i \times (0, T)$,

$$\phi_i \partial_t u - \partial_x [\mu_{o,i}(u) (\partial_x P_{o,i} - \rho_o g)] = 0, \tag{1.1}$$

$$- \phi_i \partial_t u - \partial_x [\mu_{w,i}(u) (\partial_x P_{w,i} - \rho_w g)] = 0, \tag{1.2}$$

where $\phi_i \in (0, 1)$ is the porosity of the porous media Ω_i , u is the oil-saturation (then $(1 - u)$ is the water-saturation), $\mu_{\beta,i}$ is the mobility of the phase $\beta = w, o$, where w stands for water, and o for oil. We denote by $P_{\beta,i}$ the pressure of the phase β , by ρ_β its density, and by g the gravity.

Adding (1.1) and (1.2) shows that:

$$\partial_x q = 0,$$

where

$$q = -\mu_{w,i}(u) (\partial_x P_{w,i} - \rho_w g) - \mu_{o,i}(u) (\partial_x P_{o,i} - \rho_o g) \tag{1.3}$$

is the total flow-rate. For the sake of simplicity, we suppose that q does not depend on time, even if all the results presented below still hold for $q \in BV(0, T)$, as it is shown in [13], Chapter 4.

Using (1.3) in (1.1) and (1.2) yields:

$$\phi_i \partial_t u + \partial_x \left(\frac{\mu_{o,i}(u)}{\mu_{o,i}(u) + \mu_{w,i}(u)} q + \lambda_i(u)(\rho_o - \rho_w)g - \lambda_i(u) \partial_x (P_{o,i} - P_{w,i}) \right) = 0, \tag{1.4}$$

where

$$\lambda_i(u) = \frac{\mu_{o,i}(u)\mu_{w,i}(u)}{\mu_{o,i}(u) + \mu_{w,i}(u)}.$$

One assumes that the capillary pressure $(P_{o,i} - P_{w,i})$ depends only on the saturation and of the rock type. More precisely, $(P_{o,i} - P_{w,i}) = \pi_i(u)$, where $\pi_i(u)$ is supposed to be an increasing Lipschitz continuous function. The equation (1.4) becomes

$$\phi_i \partial_t u + \partial_x (f_i(u) - \lambda_i(u) \partial_x \pi_i(u)) = 0, \tag{1.5}$$

where

$$f_i(u) = \frac{\mu_{o,i}(u)}{\mu_{o,i}(u) + \mu_{w,i}(u)} q + \lambda_i(u)(\rho_o - \rho_w)g.$$

We do the following assumptions on the functions appearing in the equation.

Assumptions 1.1. For $i = 1, 2$, one has:

- (1) π_i is an increasing Lipschitz continuous function;
- (2) $\mu_{o,i}$ is an increasing Lipschitz continuous function on $[0, 1]$, with $\mu_{o,i}(0) = 0$;
- (3) $\mu_{w,i}$ is a decreasing Lipschitz continuous function on $[0, 1]$, with $\mu_{w,i}(1) = 0$.

Remark 1.1. It is often supposed for such problems that the functions $\mu_{\beta,i}$ are monotonous in a large sense, and that there exist irreducible saturations $s_i, S_i \in (0, 1)$, with $s_i < S_i$, such that

$$\mu_{o,i}(u) = 0 \text{ if } u \in [0, s_i], \quad \mu_{w,i}(u) = 0 \text{ if } u \in [S_i, 1].$$

If we assume that the functions $\mu_{\beta,i}$ are strictly monotonous on their support, a convenient scaling would allow us to suppose that Assumptions 1.1 are fulfilled.

We denote by $\varphi_i(s) = \int_0^s \lambda_i(a)\pi'_i(a)da$, then (1.5) can be rewritten

$$\phi_i \partial_t u + \partial_x (f_i(u) - \partial_x \varphi_i(u)) = 0. \tag{1.6}$$

Properties 1.1. It follows directly from Assumptions 1.1 that for $i = 1, 2$:

- (1) f_i is Lipschitz continuous and $f_i(0) = 0, f_i(1) = q$;
- (2) λ_i is Lipschitz continuous, and $\lambda_i(0) = \lambda_i(1) = 0, \lambda_i(u) > 0$ if $u > 0$;
- (3) φ_i is an increasing Lipschitz continuous fulfilling $\varphi_i(0) = 0, \varphi'_i(0) = \varphi'_i(1) = 0$.

We deduce from the Properties 1.1 that (1.6) is a degenerated nonlinear parabolic equation.

Let us now focus on the transmission conditions through the interface $\{x = 0\}$. We denote by $\alpha_i = \lim_{s \rightarrow 0} \pi_i(s)$ and $\beta_i = \lim_{s \rightarrow 1} \pi_i(s)$. We define the monotonous graphs $\tilde{\pi}_i$ by:

$$\tilde{\pi}_i(s) = \begin{cases} \pi_i(s) & \text{if } s \in (0, 1), \\ (-\infty, \alpha_i] & \text{if } s = 0, \\ [\beta_i, +\infty) & \text{if } s = 1. \end{cases} \tag{1.7}$$

Let u_i denote the trace of $u|_{\Omega_i}$ on $\{x = 0\}$ (which is supposed to exist for the moment). The trace on $\{x = 0\}$ from Ω_i of the pressure $P_{\beta,i}$ of the phase β is still denoted by $P_{\beta,i}$. As it is exposed in [22] (see also [18]),

the pressure of the phase β can be discontinuous through the interface $\{x = 0\}$ in the case where it is missing in the upstream side. This can be written

$$\mu_{\beta,1}(u_1)(P_{\beta,1} - P_{\beta,2})^+ - \mu_{\beta,2}(u_2)(P_{\beta,2} - P_{\beta,1})^+ = 0, \quad \beta \in \{o, w\}. \tag{1.8}$$

The conditions (1.8) have direct consequences on the connection of the capillary pressures through $\{x = 0\}$. Indeed, if $0 < u_1, u_2 < 1$, then the partial pressures P_o and P_w have both to be continuous, thus the connection of the capillary pressures $\pi_1(u_1) = \pi_2(u_2)$ is satisfied. If $u_1 = 0$ and $0 < u_2 \leq 1$, then $P_{o,1} \geq P_{o,2}$ and $P_{w,1} \leq P_{w,2}$, thus $\pi_2(u_2) \leq \pi_1(0)$. The same way, $u_1 = 1$ and $0 \leq u_2 < 1$ implies $\pi_2(u_2) \geq \pi_1(1)$. Checking that the definition of the graphs $\tilde{\pi}_1$ and $\tilde{\pi}_2$ implies $\tilde{\pi}_1(0) \cap \tilde{\pi}_2(0) \neq \emptyset$, $\tilde{\pi}_1(1) \cap \tilde{\pi}_2(1) \neq \emptyset$, we can claim that (1.8) implies:

$$\tilde{\pi}_1(u_1) \cap \tilde{\pi}_2(u_2) \neq \emptyset. \tag{1.9}$$

The conservation of each phase leads to the connection of the fluxes on $\{x = 0\}$. Denoting by F_i the flux in Ω_i , *i.e.* for all $x \in \Omega_i$,

$$F_i(x, t) = f_i(u)(x, t) - \partial_x \varphi_i(u)(x, t),$$

the connection of the fluxes through the interface can be written

$$F_1(0, \cdot) = F_2(0, \cdot), \tag{1.10}$$

where (1.10) has to be understood in a weak sense.

We now turn to the problem of the boundary conditions. Because of technical difficulties occurring during Section 4, we want that the solution to the flow admits bounded fluxes, at least for regular initial data. This will force us to consider specific boundary conditions, which will involve bounded fluxes.

Let $G_i : (a, b) \mapsto G_i(a, b)$ ($i = 1, 2$) be a function fulfilling the following properties:

- G_i is Lipschitz continuous, non-decreasing w.r.t. its first argument, and non-increasing w.r.t. the second;
- for all $a \in [0, 1]$, $G_i(a, a) = f_i(a)$.

Let $\underline{u}, \bar{u} \in L^\infty(0, T)$, $0 \leq \underline{u}, \bar{u} \leq 1$ a.e., we choose the boundary condition

$$F_1(-1, t) = G_1(\underline{u}(t), u(-1, t)), \quad F_2(1, t) = G_2(u(1, t), \bar{u}(t)). \tag{1.11}$$

The way in which we approximate the boundary condition shall be judiciously compared with the discretization of the boundary conditions for scalar hyperbolic conservation laws using monotonous Finite Volume schemes (see [38]).

We consider an initial data $u_0 \in L^\infty(\Omega)$, with $0 \leq u_0 \leq 1$, then we can write the initial-boundary-value problem:

$$\begin{cases} \phi_i \partial_t u + \partial_x [f_i(u) - \partial_x \varphi_i(u)] = 0 & \text{in } \Omega_i \times (0, T), \\ F_1(0, \cdot) = F_2(0, \cdot) & \text{on } (0, T), \\ \tilde{\pi}_1(u_1) \cap \tilde{\pi}_2(u_2) \neq \emptyset & \text{on } (0, T), \\ u(t = 0) = u_0 & \text{in } \Omega, \\ F_1(-1, t) = G_1(\underline{u}(t), u(-1, t)) & \text{on } (0, T), \\ F_2(1, t) = G_2(u(1, t), \bar{u}(t)) & \text{on } (0, T). \end{cases} \tag{P}$$

We now define the notion of weak-solution

Definition 1.1. A function u is said to be a **weak solution** to the problem (P) if it fulfills:

- (1) $u \in L^\infty(\Omega \times (0, T))$, with $0 \leq u \leq 1$;
- (2) for $i = 1, 2$, $\varphi_i(u) \in L^2(0, T; H^1(\Omega_i))$;
- (3) for a.e. $t \in (0, T)$, $\tilde{\pi}_1(u_1(t)) \cap \tilde{\pi}_2(u_2(t)) \neq \emptyset$, where u_i denotes the trace of $u|_{\Omega_i}$ on $\{x = 0\}$;

(4) for all $\psi \in \mathcal{D}(\overline{\Omega} \times [0, T])$, denoting by $u(1, \cdot)$ and $u(-1, \cdot)$ the traces of u on the boundary,

$$\begin{aligned} & \int_0^T \sum_{i=1,2} \int_{\Omega_i} \phi_i u(x, t) \partial_t \psi(x, t) dx dt + \sum_{i=1,2} \int_{\Omega_i} \phi_i u_0(x) \psi(x, 0) dx \\ & + \int_0^T \sum_{i=1,2} \int_{\Omega_i} [f_i(u)(x, t) - \partial_x \varphi_i(u)(x, t)] \partial_x \psi(x, t) dx dt \\ & + \int_0^T G_1(\underline{u}(t), u(-1, t)) \psi(-1, t) dt - \int_0^T G_2(u(1, t), \overline{u}(t)) \psi(1, t) dt = 0. \end{aligned} \tag{1.12}$$

2. THE FINITE VOLUME SCHEME

In this section, we build an implicit finite volume scheme in order to approximate a solution of (\mathcal{P}) . We will adapt the convergence proofs stated in [20,22,24], which are based on monotonicity properties of the scheme. This will allow us to claim the convergence in $L^p(\Omega \times (0, T))$, up to a subsequence, of the discrete solutions built using the finite volume scheme towards a weak solution to the problem as step of the discretization tends to 0.

2.1. The finite volume approximation

We first need to discretize all the data, so that we can define an approximate problem through the finite volume scheme.

Discretization of Ω . For the sake of simplicity, we will only deal with uniform spatial discretizations. Let $N \in \mathbb{N}^*$, one defines:

$$\begin{cases} x_j = j/N, & \forall j \in \llbracket -N, N \rrbracket, \\ x_{j+1/2} = \frac{j+1/2}{N}, & \forall j \in \llbracket -N, N-1 \rrbracket. \end{cases}$$

One denotes by $\delta x = 1/N$.

Discretization of $(0, T)$. Once again, we will only deal with uniform discretizations. Let $M \in \mathbb{N}^*$, one defines: for all $n \in \llbracket 0, M \rrbracket$, $t^n = nT/M$. One denotes by $\delta t = T/M$. We denote by \mathcal{D} the discretization of $\Omega \times (0, T)$ deduced of those of Ω and $(0, T)$.

Discretization of u_0 . $\forall j \in \llbracket -N, N-1 \rrbracket$,

$$u_{0,\mathcal{D}}(x_{j+1/2}) = u_{j+1/2}^0 = \frac{1}{\delta x} \int_{x_j}^{x_{j+1}} u_0(x) dx. \tag{2.1}$$

Discretization of the boundary conditions. $\forall n \in \llbracket 0, M \rrbracket$,

$$\underline{u}^{n+1} = \frac{1}{\delta t} \int_{t^n}^{t^{n+1}} \underline{u}(t) dt, \quad \overline{u}^{n+1} = \frac{1}{\delta t} \int_{t^n}^{t^{n+1}} \overline{u}(t) dt.$$

The Finite Volume scheme. The first equation of (\mathcal{P}) can be rewritten:

$$\phi_i \partial_t u + \partial_x F_i(x, t) = 0, \quad \text{in } \Omega \times (0, T)$$

with $F_i(x, t) = f_i(u) - \partial_x \varphi_i(u)$. We consider the following implicit scheme: $\forall j \in \llbracket -N, N-1 \rrbracket, \forall n \in \llbracket 0, M-1 \rrbracket$,

$$\phi_i \frac{u_{j+1/2}^{n+1} - u_{j+1/2}^n}{\delta t} \delta x + F_{j+1}^{n+1} - F_j^{n+1} = 0 \tag{2.2}$$

where F_j^{n+1} is an approximation of the mean flux through x_j on (t^n, t^{n+1}) , and i is chosen such that $(x_j, x_{j+1}) \subset \Omega_i$. This notation will hold all along the paper. We choose a monotonous discretization of the flux: $\forall j \in \llbracket -N + 1, -1 \rrbracket \cup \llbracket 1, N - 1 \rrbracket, \forall n \in \llbracket 0, M - 1 \rrbracket$,

$$F_j^{n+1} = G_i(u_{j-1/2}^{n+1}, u_{j+1/2}^{n+1}) - \frac{\varphi_i(u_{j+1/2}^{n+1}) - \varphi_i(u_{j-1/2}^{n+1})}{\delta x}, \tag{2.3}$$

where G_i is the same function as the one defined in (1.11). We also define

$$F_{-N}^{n+1} = G_1(\underline{u}^{n+1}, u_{-N+1/2}), \quad F_N^{n+1} = G_2(u_{N-1/2}, \overline{u}^{n+1}), \tag{2.4}$$

$$F_0^{n+1} = G_1(u_{-1/2}^{n+1}, u_{0,1}^{n+1}) - \frac{2(\varphi_1(u_{0,1}^{n+1}) - \varphi_1(u_{-1/2}^{n+1}))}{\delta x} \tag{2.5}$$

$$= G_2(u_{0,2}^{n+1}, u_{1/2}^{n+1}) - \frac{2(\varphi_2(u_{1/2}^{n+1}) - \varphi_2(u_{0,2}^{n+1}))}{\delta x}, \tag{2.6}$$

where $u_{0,1}^{n+1}, u_{0,2}^{n+1}$ moreover satisfy

$$\tilde{\pi}_1(u_{0,1}^{n+1}) \cap \tilde{\pi}_2(u_{0,2}^{n+1}) \neq \emptyset. \tag{2.7}$$

Remark 2.1. The choice of the boundary conditions $F_{\pm N}^{n+1}$ has been done in order to ensure

$$|F_{-N}^{n+1}| \leq \|G_1\|_\infty < \infty, \quad |F_N^{n+1}| \leq \|G_2\|_\infty < \infty.$$

Thanks to the following lemma, such a couple $(u_{0,1}^{n+1}, u_{0,2}^{n+1})$ is unique in $[0, 1]^2$, thus the discrete transmission conditions system (2.5)–(2.7) is well posed.

Lemma 2.1. *For all $(a, b) \in [0, 1]^2$, there exists a unique couple $(c, d) \in [0, 1]^2$ such that:*

$$\begin{cases} G_1(a, c) - \frac{2(\varphi_1(c) - \varphi_1(a))}{\delta x} = G_2(d, b) - \frac{2(\varphi_2(b) - \varphi_2(d))}{\delta x}, \\ \tilde{\pi}_1(c) \cap \tilde{\pi}_2(d) \neq \emptyset. \end{cases} \tag{2.8}$$

Furthermore, $(a, b) \mapsto c$ and $(a, b) \mapsto d$ are continuous and nondecreasing w.r.t. each one of their arguments.

Proof. For $i = 1, 2$, $\tilde{\pi}_i^{-1}$ are continuous non-decreasing functions, increasing on $[\pi_i(0), \pi_i(1)]$ and constant otherwise. Then we can build the continuous non-decreasing function Λ , defined by

$$\Lambda : \begin{cases} \mathbb{R} & \rightarrow \mathbb{R} \\ p & \mapsto G_2(\tilde{\pi}_2^{-1}(p), b) - G_1(a, \tilde{\pi}_1^{-1}(p)) + \frac{2}{\delta x} (\varphi_1 \circ \tilde{\pi}_1^{-1}(p) - \varphi_1(a) + \varphi_2 \circ \tilde{\pi}_2^{-1}(p) - \varphi_2(b)). \end{cases}$$

For all p such that $\Lambda(p) = 0$, the couple $(\tilde{\pi}_1^{-1}(p), \tilde{\pi}_2^{-1}(p))$ is a solution to the discrete transmission conditions system (2.5)–(2.7). It is easy to check, using the monotonicity of the functions G_i that for all $p \leq \min \pi_i(0)$, $\Lambda(p) \leq 0$. Symmetrically, for all $p \geq \max \pi_i(1)$, $\Lambda(p) \geq 0$. Thus there exists p_\star such that $\Lambda(p_\star) = 0$.

Suppose that there exists i such that $p_\star \in (\pi_i(0), \pi_i(1))$, then since φ_i is increasing, Λ is increasing on a neighborhood of p_\star , and then the solution to the system (2.8) is unique.

Suppose now that $p_\star \notin \bigcup_i (\pi_i(0), \pi_i(1))$. Either $p_\star \leq \min_i \pi_i(0)$, then $c = d = 0$, or $p_\star \geq \max_i \pi_i(1)$, then $c = d = 1$, or $p_\star \in [\pi_k(1), \pi_l(0)]$ for $k \neq l$. We can suppose without any loss of generality that $p_\star \in [\pi_1(1), \pi_2(0)]$, then the unique solution to the system (2.8) is given by $c = 1, d = 0$.

To conclude the proof of the lemma, it only remains to check that $(a, b) \mapsto \Lambda$ is decreasing w.r.t. each one of its arguments, then the monotonicity of Λ and $\tilde{\pi}_i^{-1}$ ensures that $(a, b) \mapsto c$ and $(a, b) \mapsto d$ are non-decreasing. \square

2.2. Existence and uniqueness of the discrete solution

We will now work on the implicit finite volume scheme given by (2.1)–(2.7) to show that this approximate problem is well-posed.

Definition 2.1. Let N, M be two positive integers and \mathcal{D} be the associated discretization of $\Omega \times (0, T)$. One defines:

$$\mathcal{X}_{\mathcal{D},i} = \left\{ \begin{array}{l} z \in L^\infty(\Omega_i \times (0, T)) / \forall (x_j, x_{j+1}) \subset \Omega_i, \forall n \in \llbracket 0, M - 1 \rrbracket, \\ z|_{(x_j, x_{j+1}) \times (t^n, t^{n+1}]} \text{ is a constant} \end{array} \right\},$$

and

$$\mathcal{X}_{\mathcal{D}} = \{ z \in L^\infty(\Omega \times (0, T)) / \forall i = 1, 2, z|_{\Omega_i \times (0, T)} \in \mathcal{X}_{\mathcal{D},i} \}.$$

One defines $u_{\mathcal{D}}(x, t) \in \mathcal{X}_{\mathcal{D}}$, called **discrete solution**, given almost everywhere in $(-1, 1) \times (0, T)$ by: for all $j \in \llbracket -N, N - 1 \rrbracket$, for all $n \in \llbracket 0, M - 1 \rrbracket$,

$$\begin{cases} u_{\mathcal{D}}(x, 0) = u_{0,\mathcal{D}}(x) = u_{j+1/2}^0 \text{ if } (x, t) \in (x_j, x_{j+1}), \\ u_{\mathcal{D}}(x, t) = u_{j+1/2}^{n+1} \text{ if } (x, t) \in (x_j, x_{j+1}) \times (t_n, t_{n+1}], \end{cases}$$

where $(u_{j+1/2}^{n+1})_{j,n}$ are given by the scheme (2.2).

The monotonicity of the flux F_j^{n+1} w.r.t. $(u_{k+1/2}^{n+1})_k$ allows us to rewrite the scheme (2.2) under the form

$$H_{j+1/2} \left(u_{j+1/2}^{n+1}, u_{j+1/2}^n \left(u_{k+1/2}^{n+1} \right)_{k \neq j} \right) = 0, \tag{2.9}$$

where $H_{j+1/2}$ is continuous, increasing w.r.t. its first argument, and non-increasing w.r.t. all the others.

Definition 2.2. A function $v_{\mathcal{D}}$ is said to be a **discrete supersolution** (resp. $w_{\mathcal{D}}$ is a discrete subsolution) if it belongs to $\mathcal{X}(\mathcal{D})$, and if it satisfies: $\forall j \in \llbracket -N, N - 1 \rrbracket$,

$$\begin{aligned} & H_{j+1/2} \left(v_{j+1/2}^{n+1}, v_{j+1/2}^n \left(v_{k+1/2}^{n+1} \right)_{k \neq j} \right) \geq 0, \\ & \left(\text{resp. } H_{j+1/2} \left(w_{j+1/2}^{n+1}, w_{j+1/2}^n \left(w_{k+1/2}^{n+1} \right)_{k \neq j} \right) \leq 0 \right). \end{aligned}$$

Remark 2.2. A function $u_{\mathcal{D}}$ is a discrete solution to the scheme if and only if it is both a supersolution and a subsolution.

Remark 2.3. It follows from the definition of the scheme, particularly from the definitions of the discrete boundary conditions (2.4) and of the discrete fluxes at the interface (2.5)–(2.6), that the constant function equal to 1 is a discrete supersolution, and that the constant function equal to 0 is a discrete subsolution.

We now focus on the existence and the uniqueness of the discrete solution to the scheme. In order to prove the existence of a discrete solution, we first need an *a priori* estimate on it.

Lemma 2.2. Let $u_{\mathcal{D}}$ be a discrete solution to the scheme associated to the initial data $u_{0,\mathcal{D}}$, let $v_{\mathcal{D}}$ be a discrete supersolution associated to the initial data $v_{0,\mathcal{D}}$, then for all $t \in [0, T]$,

$$\sum_{i=1,2} \int_{\Omega_i} \phi_i (u_{\mathcal{D}}(x, t) - v_{\mathcal{D}}(x, t))^+ dx \leq \sum_{i=1,2} \int_{\Omega_i} \phi_i (u_{0,\mathcal{D}}(x) - v_{0,\mathcal{D}}(x))^+ dx.$$

Symmetrically, if $w_{\mathcal{D}}$ is a subsolution associated to the initial $w_{0,\mathcal{D}}$,

$$\sum_{i=1,2} \int_{\Omega_i} \phi_i (u_{\mathcal{D}}(x, t) - w_{\mathcal{D}}(x, t))^- dx \leq \sum_{i=1,2} \int_{\Omega_i} \phi_i (u_{0,\mathcal{D}}(x) - w_{0,\mathcal{D}}(x))^- dx.$$

Proof. Denoting by $a \top b = \max(a, b)$, and $a \perp b = \min(a, b)$, it follows from the monotonicity of the functions $H_{j+1/2}$ implies that

$$\begin{aligned} H_{j+1/2} \left(u_{j+1/2}^{n+1}, u_{j+1/2}^n \top w_{j+1/2}^n \left(u_{k+1/2}^{n+1} \top w_{k+1/2}^{n+1} \right)_{k \neq j} \right) &\leq 0, \\ H_{j+1/2} \left(w_{j+1/2}^{n+1}, u_{j+1/2}^n \top w_{j+1/2}^n \left(u_{k+1/2}^{n+1} \top w_{k+1/2}^{n+1} \right)_{k \neq j} \right) &\leq 0, \end{aligned}$$

where $w_{\mathcal{D}}$ is a subsolution. Since $u_{j+1/2}^{n+1} \top w_{j+1/2}^{n+1}$ is either equal to $u_{j+1/2}^{n+1}$ or to $w_{j+1/2}^{n+1}$,

$$H_{j+1/2} \left(u_{j+1/2}^{n+1} \top w_{j+1/2}^{n+1}, u_{j+1/2}^n \top w_{j+1/2}^n \left(u_{k+1/2}^{n+1} \top w_{k+1/2}^{n+1} \right)_{k \neq j} \right) \leq 0. \tag{2.10}$$

Thanks to the conservativity of the scheme, subtracting (2.9) to (2.10), and summing on $j \in \llbracket -N, N - 1 \rrbracket$ yields

$$\sum_{i=1,2} \int_{\Omega_i} \phi_i (u_{\mathcal{D}}(x, t^{n+1}) - w_{\mathcal{D}}(x, t^{n+1}))^- dx \leq \sum_{i=1,2} \int_{\Omega_i} \phi_i (u_{\mathcal{D}}(x, t^n) - w_{\mathcal{D}}(x, t^n))^- dx.$$

Since this inequality holds for any $n \in \llbracket 0, M - 1 \rrbracket$, it directly gives: $\forall t \in [0, T]$,

$$\sum_{i=1,2} \int_{\Omega_i} \phi_i (u_{\mathcal{D}}(x, t) - w_{\mathcal{D}}(x, t))^- dx \leq \sum_{i=1,2} \int_{\Omega_i} \phi_i (u_{\mathcal{D}}(x, 0) - w_{\mathcal{D}}(x, 0))^- dx. \tag{2.11}$$

The proof of the discrete comparison principle between a discrete solution and a discrete supersolution can be performed similarly. □

Let us now state the existence and the uniqueness of the discrete solution.

Proposition 2.3. *Let $u_0 \in L^\infty(\Omega)$, $0 \leq u_0 \leq 1$ a.e., then there exists a unique discrete solution $u_{\mathcal{D}}$ to the scheme, which furthermore fulfills $0 \leq u_{\mathcal{D}} \leq 1$ a.e. Moreover, if v_0 stands for another initial data, $0 \leq v_0 \leq 1$, approximated by $v_{0,\mathcal{D}}$ following (2.1), and if we denote by $v_{\mathcal{D}}$ the corresponding discrete solution, then the following L^1 -contraction principle holds;*

$$\sum_{i=1,2} \int_{\Omega_i} \phi_i (u_{\mathcal{D}}(x, t) - v_{\mathcal{D}}(x, t))^\pm dx \leq \sum_{i=1,2} \int_{\Omega_i} \phi_i (u_{0,\mathcal{D}}(x) - v_{0,\mathcal{D}}(x))^\pm dx, \quad \forall t \in [0, T].$$

Proof. It follows from Remark 2.3 and from Lemma 2.2 that the following L^∞ a priori estimate holds:

$$0 \leq u_{\mathcal{D}}(x, t) \leq 1, \quad \text{for all } t \in [0, T], \text{ for almost all } x \in \Omega.$$

Thanks to this estimate, mimicking the proof given in [23], we can claim the existence of a discrete solution $u_{\mathcal{D}}$. Suppose that $u_{\mathcal{D}}$ and $v_{\mathcal{D}}$ are two solutions associated to the initial data $u_{0,\mathcal{D}}$ and $v_{0,\mathcal{D}}$. As it was stressed in Remark 2.2, both $u_{\mathcal{D}}$ and $v_{\mathcal{D}}$ are both discrete sub- and supersolutions. Then, Lemma 2.2 ensures that the following L^1 -contraction principle holds:

$$\sum_{i=1,2} \int_{\Omega_i} \phi_i (u_{\mathcal{D}}(x, t) - v_{\mathcal{D}}(x, t))^\pm dx \leq \sum_{i=1,2} \int_{\Omega_i} \phi_i (u_{0,\mathcal{D}}(x) - v_{0,\mathcal{D}}(x))^\pm dx, \quad \forall t \in [0, T].$$

The uniqueness of the discrete solution $u_{\mathcal{D}}$ corresponding to the initial data u_0 follows. □

2.3. The $L^2((0, T); H^1(\Omega_i))$ estimates

The current subsection is devoted to the proof of the discrete energy estimate stated in Proposition 2.4. Since the discrete solutions are only piecewise constant, we need to introduce discrete semi-norms, which are discrete analogues to the $L^2((0, T); H^1(\Omega_i))$ semi-norms.

Definition 2.3. Let $i = 1, 2$, one defines the discrete $L^2(0, T; H^1(\Omega_i))$ semi-norms $|\cdot|_{1, \mathcal{D}, i}$ on $\mathcal{X}_{\mathcal{D}, i}$ by: $\forall z \in \mathcal{X}_{\mathcal{D}, i}$,

$$|z|_{1, \mathcal{D}, i}^2 = \sum_{n=0}^{M-1} \delta t \sum_{j \in J_{\text{int}, i}} \delta x \left(\frac{z(x_{j+1/2}, t^{n+1}) - z(x_{j-1/2}, t^{n+1})}{\delta x} \right)^2,$$

where $J_{\text{int}, 1} = \llbracket -N + 1, -1 \rrbracket$ and $J_{\text{int}, 2} = \llbracket 1, N - 1 \rrbracket$.

Proposition 2.4. For $i = 1, 2$, one defines the Lipschitz continuous increasing functions

$$\xi_i : s \mapsto \int_0^s \sqrt{\lambda_i(a)} \pi_i'(a) da.$$

There exists $C > 0$ only depending on π_i, ϕ_i, T, G_i such that:

$$\sum_{i=1,2} |\xi_i(u_{\mathcal{D}})|_{1, \mathcal{D}, i}^2 \leq C.$$

This estimate is the discrete analogue to:

$$\sum_{i=1,2} \int_0^T \int_{\Omega_i} |\partial_x \xi_i(u)(x, t)|^2 dx dt \leq C.$$

In order to prove Proposition 2.4, we will need the following technical lemma. To understand this lemma, first suppose that the total flow rate q is 0. Then, roughly speaking, it claims that, in the case where the capillary pressure is discontinuous at the interface, the discrete flux is oriented from the high capillary pressure to the low capillary pressure. Suppose now that $q \neq 0$. In order to respect the conservation of mass, some fluid will have to go through the interface, but we keep a control on the energy.

Lemma 2.5. Let $(a, b) \in [0, 1]^2$, and let $(c, d) \in [0, 1]^2$ be the unique solution to the system (2.8), as stated in Lemma 2.1, then the following inequality holds:

$$(\pi_1(c) - \pi_2(d)) \left(G_1(a, c) + \frac{\varphi_1(a) - \varphi_1(c)}{\delta x/2} \right) = (\pi_1(c) - \pi_2(d)) \left(G_2(d, b) + \frac{\varphi_2(d) - \varphi_1(b)}{\delta x/2} \right) \geq -|q| |\pi_1(c) - \pi_2(d)|.$$

Proof. In this proof, we suppose that $\pi_1(0) \geq \pi_2(0)$ and $\pi_1(1) \geq \pi_2(1)$, the other cases do not bring any other difficulties. One has $\tilde{\pi}_1(c) \cap \tilde{\pi}_2(d) \neq \emptyset$, so there are three different cases:

- $\pi_1(c) = \pi_2(d)$. In this case, one has directly:

$$(\pi_1(c) - \pi_2(d)) \left(G_1(a, c) + \frac{\varphi_1(a) - \varphi_1(c)}{\delta x/2} \right) = 0.$$

- $\pi_2(d) < \pi_1(0)$. The relation $\tilde{\pi}_1(c) \cap \tilde{\pi}_2(d) \neq \emptyset$ ensures that $c = 0$, thus it follows from the monotonicity of φ_1 and G_1 that $\varphi_1(a) \geq \varphi_1(0) = 0$, and $G_1(a, 0) \geq G_1(0, 0) = f_1(0) = 0$. This gives:

$$(\pi_1(c) - \pi_2(d)) \left(G_1(a, c) + \frac{\varphi_1(a) - \varphi_1(c)}{\delta x/2} \right) \geq 0.$$

- $\pi_1(c) > \pi_2(1)$. This implies $d = 1$. From the monotonicity of φ_2 and G_2 , we deduce that $\varphi_2(b) \leq \varphi_2(1)$ and $G_2(1, b) \geq G_2(1, 1) = q$. This yields

$$(\pi_1(c) - \pi_2(d)) \left(G_2(d, b) + \frac{\varphi_2(d) - \varphi_1(b)}{\delta x/2} \right) \geq q|\pi_1(c) - \pi_2(d)|. \quad \square$$

Proof of Proposition 2.4. First check that the scheme (2.2) can be rewritten

$$\frac{u_{j+1/2}^{n+1} - u_{j+1/2}^n}{\delta t} \delta x + \left(F_{j+1}^{n+1} - f_i(u_{j+1/2}^{n+1}) \right) - \left(F_j^{n+1} - f_i(u_{j+1/2}^{n+1}) \right) = 0.$$

We multiply the previous equation by $\delta t \pi_i(u_{j+1/2}^{n+1})$ and sum on $j = -N, N - 1$. This leads to

$$A^{n+1} + B^{n+1} + C^{n+1} + D^{n+1} + E^{n+1} = 0, \tag{2.12}$$

where

$$\begin{aligned} A^{n+1} &= \sum_{j=-N}^{N-1} \phi_i \pi_i(u_{j+1/2}^{n+1}) \left(u_{j+1/2}^{n+1} - u_{j+1/2}^n \right) \delta x; \\ B^{n+1} &= \sum_{j \notin \{-N, 0, N\}} \delta t \left[\begin{array}{l} \pi_i(u_{j-1/2}^{n+1}) \left(G_i \left(u_{j-1/2}^{n+1}, u_{j+1/2}^{n+1} \right) - G_i \left(u_{j-1/2}^{n+1}, u_{j-1/2}^{n+1} \right) \right) \\ - \pi_i(u_{j+1/2}^{n+1}) \left(G_i \left(u_{j-1/2}^{n+1}, u_{j+1/2}^{n+1} \right) - G_i \left(u_{j+1/2}^{n+1}, u_{j+1/2}^{n+1} \right) \right) \end{array} \right]; \\ C^{n+1} &= \delta t \sum_{j \notin \{-N, 0, N\}} \left(\pi_i(u_{j+1/2}^{n+1}) - \pi_i(u_{j-1/2}^{n+1}) \right) \frac{\varphi_i(u_{j+1/2}^{n+1}) - \varphi_i(u_{j-1/2}^{n+1})}{\delta x}; \\ D^{n+1} &= \delta t F_0^{n+1} \left(\pi_1(u_{-1/2}^{n+1}) - \pi_2(u_{1/2}^{n+1}) \right) \delta x - \delta t \pi_1(u_{-1/2}^{n+1}) f_1(u_{-1/2}^{n+1}) + \delta t \pi_2(u_{1/2}^{n+1}) f_2(u_{1/2}^{n+1}); \\ E^{n+1} &= \delta t \pi_1(u_{-N+1/2}^{n+1}) \left(G_1 \left(u_{-N+1/2}^{n+1}, u_{-N+1/2}^{n+1} \right) - G_1 \left(u_{-N+1/2}^{n+1}, u_{-N+1/2}^{n+1} \right) \right) \\ &\quad + \delta t \pi_2(u_{N-1/2}^{n+1}) \left(G_2 \left(u_{N-1/2}^{n+1}, \bar{u}^{n+1} \right) - G_2 \left(u_{N-1/2}^{n+1}, u_{N-1/2}^{n+1} \right) \right). \end{aligned}$$

Denoting by L_G a Lipschitz constant of both G_i ,

$$E^{n+1} \geq -\delta t L_G (\|\pi_1\|_\infty + \|\pi_2\|_\infty). \tag{2.13}$$

One has

$$\begin{aligned} F_0^{n+1} \left(\pi_1(u_{-1/2}^{n+1}) - \pi_2(u_{1/2}^{n+1}) \right) &= F_0^{n+1} \left(\pi_1(u_{-1/2}^{n+1}) - \pi_1(u_{0,1}^{n+1}) \right) + F_0^{n+1} \left(\pi_1(u_{0,1}^{n+1}) - \pi_2(u_{0,2}^{n+1}) \right) \\ &\quad + F_0^{n+1} \left(\pi_2(u_{0,2}^{n+1}) - \pi_2(u_{1/2}^{n+1}) \right). \end{aligned}$$

It has been proven in Lemma 2.5 that there exists C_1 depending only on q and π_i such that

$$F_0^{n+1} \left(\pi_1(u_{0,1}^{n+1}) - \pi_2(u_{0,2}^{n+1}) \right) \geq C_1. \tag{2.14}$$

Using the definition of F_0^{n+1} , it is then easy to check that there exists C_2 only depending on G_i, q, π_i ,

$$D^{n+1} \geq \delta t C_2 + \delta t \left(\pi_1(u_{-1/2}^{n+1}) - \pi_1(u_{0,1}^{n+1}) \right) \frac{\varphi_1(u_{-1/2}^{n+1}) - \varphi_1(u_{0,1}^{n+1})}{\delta x/2} + \delta t \left(\pi_2(u_{1/2}^{n+1}) - \pi_2(u_{0,2}^{n+1}) \right) \frac{\varphi_2(u_{1/2}^{n+1}) - \varphi_2(u_{0,2}^{n+1})}{\delta x/2}.$$

Since π_i is a non-decreasing function, $\mathcal{G}_i : s \mapsto \int_0^s \phi_i \pi_i(a) da$ is convex, then: $\forall n \in \llbracket 0, M - 1 \rrbracket$,

$$A^{n+1} \geq \sum_{j=-N}^{N-1} \left(\mathcal{G}_i(u_{j+1/2}^{n+1}) - \mathcal{G}_i(u_{j+1/2}^n) \right) \delta x. \tag{2.15}$$

We denote by $\Psi_i(s) = \int_0^s \pi_i(\tau) f'_i(\tau) d\tau$, then an integration by parts leads to

$$\Psi_i(b) - \Psi_i(a) = \pi_i(a)(G_i(a, b) - f_i(a)) - \pi_i(b)(G_i(a, b) - f_i(b)) - \int_a^b \pi'_i(s)(f_i(s) - G_i(a, b)) ds.$$

Since $f_i(s) = G_i(s, s)$, it follows from the monotonicity of G_i and π_i that

$$\int_a^b \pi'_i(s)(f_i(s) - G_i(a, b)) ds \geq 0.$$

Thus

$$B^{n+1} \geq \delta t \sum_{j \notin \{-N, 0, N\}} \left(\Psi_i(u_{j+1/2}^{n+1}) - \Psi_i(u_{j-1/2}^{n+1}) \right) \geq \delta t \left(\Psi_1(u_{-1/2}^{n+1}) - \Psi_1(u_{-N+1/2}^{n+1}) + \Psi_2(u_{N-1/2}^{n+1}) - \Psi_2(u_{1/2}^{n+1}) \right).$$

So there exists C_3 , only depending on π_i, f_i such that

$$B^{n+1} \geq \delta t C_3. \tag{2.16}$$

Let $\xi_i : s \mapsto \int_0^s \sqrt{\lambda_i(a)} \pi'_i(a) da$, Cauchy-Schwarz inequality yields: $\forall (a, b) \in [0, 1]^2$,

$$(\pi_i(a) - \pi_i(b))(\varphi_i(a) - \varphi_i(b)) \geq (\xi_i(a) - \xi_i(b))^2.$$

This ensures that

$$C^{n+1} \geq \delta t \sum_{j \notin \{-N, 0, N\}} \frac{\left(\xi_i(u_{j+1/2}^{n+1}) - \xi_i(u_{j-1/2}^{n+1}) \right)^2}{\delta x}; \tag{2.17}$$

$$D^{n+1} \geq \delta t C_2 + \delta t \frac{\left(\xi_1(u_{0,1}^{n+1}) - \xi_1(u_{-1/2}^{n+1}) \right)^2}{\delta x/2} + \delta t \frac{\left(\xi_2(u_{1/2}^{n+1}) - \xi_2(u_{0,2}^{n+1}) \right)^2}{\delta x/2}. \tag{2.18}$$

Summing (2.12) on $n \in \llbracket 0, M - 1 \rrbracket$, and taking into account (2.13), (2.15)–(2.18), provides the existence of a quantity C , depending only on T, π_i, G_i, ϕ_i such that

$$\sum_{i=1,2} |\xi_i(u_{\mathcal{D}})|_{1,\mathcal{D},i}^2 + \sum_{n=0}^{M-1} \delta t \left(\frac{(\xi_1(u_{0,1}^{n+1}) - \xi_1(u_{-1/2}^{n+1}))^2}{\delta x/2} + \frac{(\xi_2(u_{1/2}^{n+1}) - \xi_2(u_{0,2}^{n+1}))^2}{\delta x/2} \right) \leq C. \tag{2.19} \quad \square$$

Remark 2.4. The estimate (2.19) is stronger than the one stated in Proposition 2.4, since it lets also appear some contributions coming from the interface. They will be useful in the sequel. Indeed, if we denote by $u_{\mathcal{D},i}$ the trace of $(u_{\mathcal{D}})|_{\Omega_i}$ on the interface $\{x = 0\}$, and if we denote by $\gamma_{\mathcal{D},i}(t) = u_{0,i}^{n+1}$ if $t \in (n\delta t, (n + 1)\delta t]$, then it follows from (2.19) that

$$\lim_{\delta t, \delta x \rightarrow 0} \|u_{\mathcal{D},i} - \gamma_{\mathcal{D},i}\|_{L^p(0,T)} = 0, \quad \forall p \in [1, \infty).$$

Suppose that $u_{\mathcal{D},i}$ converges in $L^p(0, T)$ towards a function u_i , as it will be proven later. Then, we directly obtain that $\gamma_{\mathcal{D},i}$ also converges towards u_i . Moreover, for all $t > 0$, $\tilde{\pi}_1(\gamma_{\mathcal{D},1}(t)) \cap \tilde{\pi}_2(\gamma_{\mathcal{D},2}(t)) \neq \emptyset$. Since

$$F = \{(a, b) \in [0, 1]^2 \mid \tilde{\pi}_1(a) \cap \tilde{\pi}_2(b) \neq \emptyset\}$$

is a closed set of $[0, 1]^2$,

we can claim that $\tilde{\pi}_1(u_1) \cap \tilde{\pi}_2(u_2) \neq \emptyset$ a.e. in $(0, T)$.

2.4. Compactness of a family of approximate solutions

Let $(M_p)_{p \in \mathbb{N}}, (N_p)_{p \in \mathbb{N}}$ be two sequences of positive integers tending to $+\infty$. We denote \mathcal{D}_p the discretization of $\Omega \times (0, T)$ associated to M_p , and N_p . The L^∞ -estimate stated in Proposition 2.3 shows that there exists $u \in L^\infty(\Omega \times (0, T))$, $0 \leq u \leq 1$, such that, up to a subsequence, $u_{\mathcal{D}_p} \rightarrow u$ in the $L^\infty(\Omega \times (0, T))$ weak- \star sense as $p \rightarrow +\infty$.

We just need to prove that $u_{\mathcal{D}_p} \rightarrow u$ almost everywhere in $\Omega \times (0, T)$ to get the convergence of $(u_{\mathcal{D}_p})$ towards u in $L^r(\Omega \times (0, T))$ for any $1 \leq r < +\infty$. To apply Kolmogorov criterion (see e.g. [12]) we need some estimates on the space and time translates of $\xi_i(u_{\mathcal{D}})$.

Lemma 2.6 (space and time translates estimates). *For all $\eta \in \mathbb{R}$, for $i = 1, 2$, one denotes $\Omega_{i,\eta} = \{x \in \Omega_i \mid (x + \eta) \in \Omega_i\}$, then the following estimate holds:*

$$\|\xi_i(u_{\mathcal{D}})(\cdot + \eta, \cdot) - \xi_i(u_{\mathcal{D}})(\cdot, \cdot)\|_{L^2(\Omega_{i,\eta} \times (0,T))} \leq |\xi_i(u_{\mathcal{D}})|_{1,\mathcal{D},i} |\eta| (|\eta| + 2\delta x). \tag{2.20}$$

One denotes $w_{i,\mathcal{D}}$ the function defined almost everywhere by:

$$w_{i,\mathcal{D}}(x, t) = \begin{cases} \xi_i(u_{\mathcal{D}})(x, t) & \text{in } \Omega_i \times (0, T), \\ 0 & \text{in } \mathbb{R}^2 \setminus (\Omega_i \times (0, T)). \end{cases}$$

There exists C_1 depending only on π_i, ϕ_i, T, G_i and C_2 only depending on $\pi_i, \phi_i, T, \lambda_i, G_i$ such that:

$$\forall \eta \in \mathbb{R}, \quad \|w_{i,\mathcal{D}}(\cdot + \eta, \cdot) - w_{i,\mathcal{D}}(\cdot, \cdot)\|_{L^2(\mathbb{R}^2)} \leq C_1 \eta, \tag{2.21}$$

$$\forall \tau \in (0, T), \quad \|w_{i,\mathcal{D}}(\cdot, \cdot + \tau) - w_{i,\mathcal{D}}(\cdot, \cdot)\|_{L^2(\Omega_i \times (0, T - \tau))} \leq C_2 \tau. \tag{2.22}$$

The previous lemma is in fact a compilation of Lemmata 4.2, 4.3 and 4.6 of [24] adapted to our framework. The estimates (2.21) and (2.22) allows us to use the Kolmogorov compactness criterion on the sequence $(w_{i,\mathcal{D}_p})_{p \in \mathbb{N}}$, and thus, there exists $w_i \in L^2(\Omega_i \times (0, T))$ such that for almost every $(x, t) \in (\Omega_i \times (0, T))$, $\xi_i(u_{\mathcal{D}_p})(x, t) \rightarrow w_i(x, t)$, and then thanks to the L^∞ -estimate $0 \leq u_{\mathcal{D}_p}(x, t) \leq 1$, one can claim that $\xi_i(u_{\mathcal{D}_p}) \rightarrow w_i$

in $L^r(\Omega_i \times (0, T))$, for all $r \in [1, +\infty[$. Letting p tend to $+\infty$ in (2.20) ensures that w_i belongs to $L^2(0, T; H^1(\Omega_i))$. Since ξ_i^{-1} is a continuous function, we can identify the limit:

$$w_i = \xi_i(u).$$

Thus $\xi_i(u) \in L^2(0, T; H^1(\Omega_i))$, and since $\varphi_i \circ \xi_i^{-1}$ is a Lipschitz function, there exists C depending only on $T, \pi_i, \phi_i, G_i, \lambda_i$ such that:

$$\|\varphi_i(u)\|_{L^2(0, T; H^1(\Omega_i))} \leq C, \tag{2.23}$$

and that $\xi_i(u_{\mathcal{D}_p}) \rightarrow \xi_i(u)$, up to a subsequence, in $L^r(\Omega_i \times (0, T))$ as $p \rightarrow +\infty$ for any $r \in [1, +\infty)$. Since $\xi_i, i = 1, 2$, is an increasing function, one can claim that $u_{\mathcal{D}_p}$ converges a.e. in $\Omega \times (0, T)$ towards u , and then:

$$u_{\mathcal{D}_p} \rightarrow u \quad \text{in the } L^\infty(\Omega \times (0, T))\text{-weak-}\star \text{ sense,} \tag{2.24}$$

$$u_{\mathcal{D}_p} \rightarrow u \quad \text{in } L^r(\Omega_i \times (0, T)), \forall r \in [1, +\infty[. \tag{2.25}$$

Roughly speaking, the approximation $u_{\mathcal{D}}$ obtained *via* a monotonous finite volume scheme, which introduces numerical diffusion, is “close” to the approximation u^ϵ obtained by adding additional diffusion $-\epsilon \Delta u^\epsilon$ to the problem. For such a continuous problem, we would have an estimate of type

$$\int_0^T \int_{\Omega_i} (\partial_x \xi_i(u^\epsilon)) \, dx \, dt \leq C',$$

which would lead to the relative compactness of the family $(\xi_i(u^\epsilon))_{\epsilon > 0}$ in $L^2(\Omega_i \times (0, T))$. Then the family $(\xi_i(u^\epsilon))_{\epsilon > 0}$ is also relatively compact in $L^2((0, T); H^s(\Omega_i))$ for all $s \in (1/2, 1)$. This ensures that, up to a subsequence, the traces on the boundary and on the interface of $(\xi_i(u^\epsilon))$ converge in $L^2(0, T)$. The continuity of ξ_i^{-1} , and the L^∞ -estimate ensure that the traces of u^ϵ on the boundary and on the interface converge in $L^r(0, T)$, for all $r \in [1, \infty)$.

This sketch has to be modified in order to deal with discrete solutions, which do not belong to $L^2((0, T); H^s(\Omega_i))$ for $s > 1/2$. Nevertheless, a convenient estimate on the translates at the boundary, based on the discrete $L^2((0, T); H^1(\Omega_i))$ estimate stated in Proposition 2.4, leads to the following convergence result whose proof is left to the reader.

Lemma 2.7. *Let $i = 1, 2$, and let $\alpha \in \partial\Omega_i$. We denote by $u_{\alpha, \mathcal{D}_p, i}$ the trace of $(u_{\mathcal{D}_p})|_{\Omega_i}$ on $\{x = \alpha\}$. Then, one has: for all $r \in [1, \infty)$,*

$$u_{\alpha, \mathcal{D}_p, i} \rightarrow u|_{\Omega_i}(\alpha, \cdot) \text{ in } L^r(0, T) \text{ as } p \rightarrow +\infty.$$

If we denote by $u_i(t) = u|_{\Omega_i}(0, t)$, it follows from Remark 2.4 that $\tilde{\pi}_1(u_1) \cap \tilde{\pi}_2(u_2) \neq \emptyset$ a.e. in $(0, T)$. We can summarize all the results of this subsection in the following proposition:

Proposition 2.8. *Let $(M_p)_p, (N_p)_p$ tend to ∞ as $p \rightarrow \infty$, and let $(\mathcal{D}_p)_p$ be the corresponding sequence of discretizations of $\Omega \times (0, T)$. Let $(u_{\mathcal{D}_p})_p$ be the sequence of corresponding discrete solutions to the scheme, then, up to a subsequence (still denoted by $(u_{\mathcal{D}_p})_p$), there exists $u \in L^\infty(\Omega \times (0, T))$, $0 \leq u \leq 1$ a.e., with $\xi_i(u) \in L^2((0, T); H^1(\Omega_i))$ ($i = 1, 2$) such that:*

$$u_{\mathcal{D}_p} \rightarrow u \quad \text{a.e. in } \Omega \times (0, T) \quad \text{as } p \rightarrow \infty.$$

Moreover, keeping the notations of Lemma 2.7,

$$\begin{aligned} u_{-1, \mathcal{D}_p, 1}(t) &\rightarrow u(-1, t) && \text{for a.e. } t \in (0, T) \quad \text{as } p \rightarrow \infty, \\ u_{1, \mathcal{D}_p, 2}(t) &\rightarrow u(1, t) && \text{for a.e. } t \in (0, T) \quad \text{as } p \rightarrow \infty, \\ u_{0, \mathcal{D}_p, i}(t) &\rightarrow u|_{\Omega_i}(0, t) = u_i(t) && \text{for a.e. } t \in (0, T) \quad \text{as } p \rightarrow \infty, \quad i = 1, 2, \end{aligned}$$

and $\tilde{\pi}_1(u_1) \cap \tilde{\pi}_2(u_2) \neq \emptyset$ almost everywhere in $(0, T)$.

2.5. Convergence of the scheme

We will now achieve the proof of the following result.

Theorem 2.9. *Let $(M_p)_{p \in \mathbb{N}}, (N_p)_{p \in \mathbb{N}}$ be two sequences of positive integers tending to $+\infty$, and $(\mathcal{D}_p)_{p \in \mathbb{N}}$ the associated sequence of discretizations of $\Omega \times (0, T)$. Then, up to a subsequence, the sequence $(u_{\mathcal{D}_p})_p$ of the discrete solutions converges in $L^r(\Omega \times (0, T))$ for all $r \in [1, \infty)$ to a weak solution to the problem (\mathcal{P}) in the sense of Definition 1.1.*

Proof. As it has been seen in Proposition 2.8, the discrete solution $u_{\mathcal{D}_p}$ converges, up to a subsequence, towards a function u fulfilling all the regularity criteria to be a weak solution. In order to prove the convergence of the subsequence to a weak solution, it only remains to show that the weak formulation (1.12) is satisfied by the limit u .

In order to simplify the proof of convergence of the scheme towards a weak solution, we will use a density result, which is a simple particular case of those stated in [21].

Lemma 2.10. *Let $a, b \in \mathbb{R}, a < b$, then: $\{\psi \in C_c^\infty([a, b]) / \psi' \in C_c^\infty((a, b))\}$ is dense in $W^{1,q}(a, b)$, $q \in [1, +\infty[$.*

This lemma particularly allows us, thanks to a straightforward generalization, to restrict the set of test functions ψ for the weak formulation (1.12) to

$$\mathcal{T} = \{\psi \in \mathcal{D}(\bar{\Omega} \times [0, T]) / \partial_x \psi \in \mathcal{D}((\cup_{i=1,2} \Omega_i) \times [0, T])\}.$$

Let $\psi \in \mathcal{T}$. For $j \in \llbracket -N_p, N_p - 1 \rrbracket, n \in \llbracket 0, M_p - 1 \rrbracket$, we denote by $\psi_{j+1/2}^n = \psi(x_{j+1/2}, t^n)$. Assume that p is large enough to ensure:

$$\psi_{-1/2}^n = \psi_{1/2}^n, \quad \forall n \in \llbracket 0, M_p - 1 \rrbracket, \tag{2.26}$$

$$\forall n \in \llbracket 0, M_p - 1 \rrbracket, \quad \begin{cases} \psi_{-N+1/2}^n = \psi(-1, t^n), \\ \psi_{N-1/2}^n = \psi(1, t^n). \end{cases} \tag{2.27}$$

One has also

$$\psi_{j+1/2}^{M_p} = 0, \quad \forall j \in \llbracket -N_p, N_p - 1 \rrbracket. \tag{2.28}$$

For $j \in \llbracket -N_p, N_p - 1 \rrbracket, n \in \llbracket 0, M_p - 1 \rrbracket$, let us multiply equation (2.2) by $\psi_{j+1/2}^n \delta t$, and sum on $j \in \llbracket -N_p, N_p - 1 \rrbracket, n \in \llbracket 0, M_p - 1 \rrbracket$, we get:

$$\sum_{n=0}^{M_p-1} \sum_{j=-N_p}^{N_p-1} \phi_i(u_{j+1/2}^{n+1} - u_{j+1/2}^n) \psi_{j+1/2}^n \delta x + \sum_{n=0}^{M_p-1} \delta t \sum_{j=-N_p}^{N_p-1} (F_{j+1}^{n+1} - F_j^{n+1}) \psi_{j+1/2}^n = 0,$$

which can be rewritten thanks to (2.26)–(2.28):

$$\begin{aligned} & \sum_{n=0}^{M_p-1} \sum_{j=-N_p}^{N_p-1} \phi_i u_{j+1/2}^{n+1} (\psi_{j+1/2}^n - \psi_{j+1/2}^{n+1}) \delta x - \sum_{j=-N_p}^{N_p-1} \phi_i u_{j+1/2}^0 \psi_{j+1/2}^0 \delta x \\ & + \sum_{n=0}^{M_p-1} \delta t \sum_{j \notin \{-N_p, 0, N_p\}} F_j^{n+1} (\psi_{j-1/2}^n - \psi_{j+1/2}^n) \\ & - \sum_{n=0}^{M_p-1} \delta t F_{-N}^{n+1} \psi(-1, t^n) + \sum_{n=0}^{M_p-1} \delta t F_N^{n+1} \psi(1, t^n) = 0. \end{aligned} \tag{2.29}$$

Using the definition of F_j^{n+1} , we obtain

$$A_p + B_p + C_p + D_p + E_p = 0, \tag{2.30}$$

with, using the notation $\psi_{-N-1/2}^n = \psi_{-N+1/2}^n$, and $\psi_{N+1/2}^n = \psi_{N-1/2}^n$,

$$\begin{aligned}
 A_p &= \sum_{n=0}^{M_p-1} \sum_{j=-N_p}^{N_p-1} \phi_i u_{j+1/2}^{n+1} (\psi_{j+1/2}^n - \psi_{j+1/2}^{n+1}) \delta x; \\
 B_p &= - \sum_{j=-N_p}^{N_p-1} \phi_i u_{j+1/2}^0 \psi_{j+1/2}^0 \delta x; \\
 C_p &= \sum_{n=0}^{M_p-1} \delta t \sum_{j \notin \{-N_p, 0, N_p\}} G_i(u_{j-1/2}^{n+1}, u_{j+1/2}^{n+1}) (\psi_{j-1/2}^n - \psi_{j+1/2}^n); \\
 D_p &= - \sum_{n=0}^{M_p-1} \delta t \sum_{j=-N_p}^{N_p-1} \varphi_i(u_{j+1/2}^{n+1}) \frac{\psi_{j+3/2}^n - 2\psi_{j+1/2}^n + \psi_{j-1/2}^n}{\delta x}; \\
 E_p &= - \sum_{n=0}^{M_p-1} \delta t G_1(\underline{u}^{n+1}, u_{-N+1/2}^{n+1}) \psi(-1, t^n) + \sum_{n=0}^{M_p-1} \delta t G_2(u_{N-1/2}^{n+1}, \bar{u}^{n+1}) \psi(1, t^n).
 \end{aligned}$$

Since $h_{A_p} : (x, t) \mapsto \frac{\psi_{j+1/2}^n - \psi_{j+1/2}^{n+1}}{\delta t}$ if $(x, t) \in (x_j, x_{j+1}) \times (t^n, t^{n+1})$, converges uniformly towards $-\partial_t \psi$ as $p \rightarrow \infty$, and since $u_{\mathcal{D}}$ converges in $L^1(\Omega \times (0, T))$ towards u ,

$$\lim_{p \rightarrow \infty} A_p = - \int_0^T \sum_{i=1,2} \int_{\Omega_i} \phi_i u(x, t) \partial_t \psi(x, t) dx dt. \tag{2.31}$$

Thanks to the convergence in $L^1(\Omega)$ of $u_{\mathcal{D}}(x, 0)$ towards u_0 , we have

$$\lim_{p \rightarrow \infty} B_p = - \sum_{i=1,2} \int_{\Omega_i} \phi_i u_0(x) \psi(x, 0) dx. \tag{2.32}$$

We have to rewrite $C_p = C_p^1 + C_p^2$, with

$$\begin{aligned}
 C_p^1 &= \sum_{n=0}^{M_p-1} \delta t \sum_{j \notin \{-N_p, 0, N_p\}} f_i(u_{j-1/2}^{n+1}) (\psi_{j-1/2}^n - \psi_{j+1/2}^n), \\
 C_p^2 &= \sum_{n=0}^{M_p-1} \delta t \sum_{j \notin \{-N_p, 0, N_p\}} \left(G_i(u_{j-1/2}^{n+1}, u_{j+1/2}^{n+1}) - f_i(u_{j-1/2}^{n+1}) \right) (\psi_{j-1/2}^n - \psi_{j+1/2}^n).
 \end{aligned}$$

Thanks to Proposition 2.8, the quantity C_p^1 converges towards $-\int_0^T \sum_{i=1,2} \int_{\Omega_i} f_i(u)(x, t) \partial_x \psi(x, t) dx dt$ as $p \rightarrow \infty$.

Concerning C_p^2 , since

$$\left| G_i(u_{j-1/2}^{n+1}, u_{j+1/2}^{n+1}) - f_i(u_{j-1/2}^{n+1}) \right| = \left| G_i(u_{j-1/2}^{n+1}, u_{j+1/2}^{n+1}) - G_i(u_{j-1/2}^{n+1}, u_{j-1/2}^{n+1}) \right| \leq L_G |u_{j+1/2}^{n+1} - u_{j-1/2}^{n+1}|,$$

and since $(x, t) \mapsto \frac{\psi_{j-1/2}^n - \psi_{j+1/2}^n}{\delta x}$ on $(x_{j-1/2}, x_{j+1/2}) \times (t^n, t^{n+1})$ is uniformly bounded by $\|\partial_x \psi\|_\infty$,

$$|C_p^2| \leq L_G \|\partial_x \psi\|_\infty \int_0^T \int_{\Omega} |\delta u_{\mathcal{D}_p}(x, t)| dx dt,$$

where $\delta u_{\mathcal{D}_p}(x, t) = u_{j+1/2}^{n+1} - u_{j-1/2}^{n+1}$ on $(x_{j-1/2}, x_{j+1/2}) \times (t^n, t^{n+1})$ ($j \in \llbracket -N_p + 1, N_p - 1 \rrbracket$), and 0 otherwise. It is easy to check, thanks to the discrete $L^2((0, T); H^1(\Omega_i))$ estimates stated in Proposition 2.4, that $\delta u_{\mathcal{D}_p}$ tends to 0 in $L^1(\Omega \times (0, T))$ as $p \rightarrow \infty$. Then

$$\lim_{p \rightarrow \infty} C_p = - \int_0^T \sum_{i=1,2} \int_{\Omega_i} f_i(u)(x, t) \partial_x \psi(x, t) dx dt. \tag{2.33}$$

Since, using Proposition 2.8, $\varphi_i(u_{\mathcal{D}_p})$ tends to $\varphi_i(u) \in L^2((0, T); H^1(\Omega_i))$ in the $L^2(\Omega_i \times (0, T))$ -topology, one has:

$$\lim_{p \rightarrow \infty} D_p = - \int_0^T \sum_{i=1,2} \int_{\Omega_i} \varphi_i(u)(x, t) \partial_{xx}^2 \psi(x, t) dx dt = \int_0^T \sum_{i=1,2} \int_{\Omega_i} \partial_x \varphi_i(u)(x, t) \partial_x \psi(x, t) dx dt. \tag{2.34}$$

The strong convergence of the traces, stated in Proposition 2.8 allows us to claim that

$$\lim_{p \rightarrow \infty} E_p = - \int_0^T G_1(\underline{u}(t), u(-1, t)) \psi(-1, t) dt + \int_0^T G_2(u(1, t), \bar{u}(t)) \psi(1, t) dt. \tag{2.35}$$

We can thus take the limit for $p \rightarrow \infty$ in (2.30), and it follows from (2.31)–(2.35) that u fulfills the weak formulation (1.12). □

3. UNIFORM BOUND ON THE FLUXES

In this section, we show that, under some regularity assumptions on the initial data, there exists a solution with bounded fluxes. This existence result is the consequence of some additional estimates on the discrete solution, and will be necessary to get the uniqueness result of Theorem 4.1.

Definition 3.1. A function u is said to be a **bounded-flux solution** to the problem (\mathcal{P}) if:

- (1) u is a weak solution to the problem (\mathcal{P}) in the sense of Definition 1.1;
- (2) $\partial_x \varphi_i(u)$ belongs to $L^\infty(\Omega_i \times (0, T))$.

In order to get an existence result, we need more regularity on the initial data, as stated below.

Assumptions 3.1. *We assume that:*

- (1) $\partial_x \varphi_i(u_0) \in L^\infty(\Omega_i)$, $0 \leq u_0 \leq 1$;
- (2) $\tilde{\pi}_1(u_{0,1}) \cap \tilde{\pi}_2(u_{0,2}) \neq \emptyset$, where $u_{0,i}$ is the trace of $u_0|_{\Omega_i}$ on $\{x = 0\}$.

Theorem 3.1. *Suppose that Assumptions 3.1 are fulfilled. Let $(M_p)_{p \in \mathbb{N}}$, $(N_p)_{p \in \mathbb{N}}$ be two sequences of positive integers tending to $+\infty$. Let $(u_{\mathcal{D}_p})_{p \in \mathbb{N}}$ be the sequence of the associated discrete solutions obtained via the finite volume scheme (2.2), and let u be an adherence value of the sequence $(u_{\mathcal{D}_p})_{p \in \mathbb{N}}$. Then u is a bounded flux solution to the problem (\mathcal{P}) in the sense of Definition 3.1. This particularly ensures the existence of such a bounded-flux solution.*

All Section 3 will be devoted to the proof of Theorem 3.1. We only need to verify the second point in Definition 3.1, because we have already proven in Theorem 2.9 that u is a weak solution. So the aim of this section is to get the uniform bound on the fluxes. Such an estimate can be found in [18] in the case where the convection is neglected. It is obtained using a thin regular transition layer between Ω_1 and Ω_2 , and a regularization of the initial data u_0 . This technique was also used in [10] to get a BV -estimate on the fluxes in the case of a non-bounded domain Ω , and for particular values of the data (which are supposed to be more regular). In this paper, we only deal with the discrete solution, which can be seen as a regularization of the solution to the continuous problem (\mathcal{P}) .

We extend the definitions of the discrete internal fluxes (2.3)–(2.6) to the case $n = -1$, i.e. in the time $t = 0$. For all $j \in \llbracket -N + 1, N - 1 \rrbracket$, $j \neq 0$,

$$F_j^0 = G_i(u_{j-1/2}^0, u_{j+1/2}^0) - \frac{\varphi_i(u_{j+1/2}^0) - \varphi_i(u_{j-1/2}^0)}{\delta x}. \tag{3.1}$$

Thanks to Lemma 2.1, there exists a unique couple $(u_{0,1}^0, u_{0,2}^0)$ solution to the system

$$F_0^0 = G_1(u_{-1/2}^0, u_{0,1}^0) - \frac{\varphi_1(u_{0,1}^0) - \varphi_1(u_{-1/2}^0)}{\delta x/2} = G_2(u_{0,2}^0, u_{1/2}^0) - \frac{\varphi_2(u_{1/2}^0) - \varphi_2(u_{0,2}^0)}{\delta x/2}, \tag{3.2}$$

$$\tilde{\pi}_1(u_{0,1}^0) \cap \tilde{\pi}_2(u_{0,2}^0) \neq \emptyset. \tag{3.3}$$

Remark 3.1. $u_{0,1}^0$ and $u_{0,2}^0$ are given by Lemma 2.1, and so they are different of $u_{0,1}$ and $u_{0,2}$.

Lemma 3.2. *There exists $C > 0$ depending only on u_0, φ_i, q such that*

$$\max_{j \in \llbracket -N+1, N-1 \rrbracket} |F_j^0| \leq C.$$

Proof. Since $\varphi_i(u_0)$ is a Lipschitz continuous function, and φ_i^{-1} is continuous, $u_0|_{\Omega_i}$ is a continuous function, and there exists $y_{j+1/2} \in (x_j, x_{j+1})$ such that $u_{j+1/2}^0 = u_0(y_{j+1/2})$. Then (3.1) can be rewritten

$$F_j^0 = G_i(u_0(y_{j-1/2}), u_0(y_{j+1/2})) - \frac{\varphi_i(u_0(y_{j+1/2})) - \varphi_i(u_0(y_{j-1/2}))}{\delta x}.$$

Using the fact that $\partial_x \varphi_i(u_0) \in L^\infty(\Omega_i)$ gives directly: $\forall j \in \llbracket -N + 1, N - 1 \rrbracket \setminus \{0\}$,

$$|F_j^0| \leq \max_{i=1,2} \|G_i\|_\infty + 2 \max_{i=1,2} (\|\partial_x \varphi_i(u_0)\|_{L^\infty(\Omega_i)}). \tag{3.4}$$

The monotony of the transmission conditions $\tilde{\pi}_1(u_{0,1}^0) \cap \tilde{\pi}_2(u_{0,2}^0) \neq \emptyset$ and $\tilde{\pi}_1(u_{0,1}) \cap \tilde{\pi}_2(u_{0,2}) \neq \emptyset$ implies that either $u_{0,1}^0 \geq u_{0,1}$ and $u_{0,2}^0 \geq u_{0,2}$, or $u_{0,1}^0 \leq u_{0,1}$ and $u_{0,2}^0 \leq u_{0,2}$. Assume for example that $u_{0,1}^0 \geq u_{0,1}$ and $u_{0,2}^0 \geq u_{0,2}$ – the other case could be treated similarly – then one deduce from (3.2) that:

$$G_2(u_{0,2}, u_0(y_{1/2})) - \frac{\varphi_2(u_0(y_{1/2})) - \varphi_2(u_{0,2})}{\delta x/2} \leq F_0^0 \leq G_1(u_0(y_{-1/2}), u_{0,1}) - \frac{\varphi_1(u_{0,1}) - \varphi_1(u_0(y_{-1/2}))}{\delta x/2},$$

and so since $\varphi_i(u_0)$ is a Lipschitz continuous function,

$$|F_0^0| \leq \max_{i=1,2} \|G_i\|_\infty + 2 \max_{i=1,2} (\|\partial_x \varphi_i(u_0)\|_{L^\infty(\Omega_i)}). \quad \square$$

Proposition 3.3. *There exists $C > 0$ depending only on u_0, φ_i, G_i , such that*

$$\max_{j \in \llbracket -N+1, N-1 \rrbracket} \left(\max_{n \in \llbracket 0, M \rrbracket} |F_j^n| \right) \leq C.$$

Proof. For all $j \in \llbracket -N + 1, N - 1 \rrbracket \setminus \{0\}$, for all $n \in \llbracket 0, M - 1 \rrbracket$,

$$\begin{aligned} F_j^{n+1} - F_j^n &= \left(G_i(u_{j-1/2}^{n+1}, u_{j+1/2}^{n+1}) - G_i(u_{j-1/2}^n, u_{j+1/2}^n) \right) + \left(G_i(u_{j-1/2}^n, u_{j+1/2}^{n+1}) - G_i(u_{j-1/2}^n, u_{j+1/2}^n) \right) \\ &\quad + \left(\frac{\varphi_i(u_{j-1/2}^{n+1}) - \varphi_i(u_{j-1/2}^n)}{\delta x} \right) - \left(\frac{\varphi_i(u_{j+1/2}^{n+1}) - \varphi_i(u_{j+1/2}^n)}{\delta x} \right). \end{aligned}$$

Thus, using (2.2) yields

$$\begin{aligned}
 F_j^{n+1} - F_j^n &= \frac{\delta t}{\phi_i \delta x} \frac{G_i(u_{j-1/2}^{n+1}, u_{j+1/2}^{n+1}) - G_i(u_{j-1/2}^n, u_{j+1/2}^n)}{u_{j-1/2}^{n+1} - u_{j-1/2}^n} (F_j^{n+1} - F_{j-1}^{n+1}) \\
 &+ \frac{\delta t}{\phi_i \delta x} \frac{G_i(u_{j-1/2}^n, u_{j+1/2}^{n+1}) - G_i(u_{j-1/2}^n, u_{j+1/2}^n)}{u_{j+1/2}^{n+1} - u_{j+1/2}^n} (F_{j+1}^{n+1} - F_j^n) \\
 &+ \frac{\delta t}{\phi_i \delta x^2} \frac{\varphi_i(u_{j-1/2}^{n+1}) - \varphi_i(u_{j-1/2}^n)}{u_{j-1/2}^{n+1} - u_{j-1/2}^n} (F_j^{n+1} - F_{j-1}^{n+1}) \\
 &- \frac{\delta t}{\phi_i \delta x^2} \frac{\varphi_i(u_{j+1/2}^{n+1}) - \varphi_i(u_{j+1/2}^n)}{u_{j+1/2}^{n+1} - u_{j+1/2}^n} (F_{j+1}^{n+1} - F_j^{n+1}).
 \end{aligned}$$

The monotonicity of the scheme is once again crucial, since it implies that there exist two non-negative values $a_{j,j+1}^{n+1}, a_{j,j-1}^{n+1}$ such that

$$(1 + a_{j,j-1}^{n+1} + a_{j,j+1}^{n+1}) F_j^{n+1} - a_{j,j-1}^{n+1} F_{j-1}^{n+1} - a_{j,j+1}^{n+1} F_{j+1}^{n+1} = F_j^n. \tag{3.5}$$

The monotonicity of the graph transmission condition (2.7) ensures that either $u_{0,1}^{n+1} \geq u_{0,1}^n$ and $u_{0,2}^{n+1} \geq u_{0,2}^n$, or $u_{0,1}^{n+1} \leq u_{0,1}^n$ and $u_{0,2}^{n+1} \leq u_{0,2}^n$. Suppose for example that $u_{0,1}^{n+1} \geq u_{0,1}^n$ and $u_{0,2}^{n+1} \geq u_{0,2}^n$, the other case being completely symmetrical

$$\begin{aligned}
 F_0^{n+1} - F_0^n &= \left(G_1(u_{-1/2}^{n+1}, u_{0,1}^{n+1}) - G_1(u_{-1/2}^n, u_{0,1}^n) \right) \\
 &+ \left(\frac{\varphi_1(u_{-1/2}^{n+1}) - \varphi_1(u_{-1/2}^n)}{\delta x/2} \right) - \left(\frac{\varphi_1(u_{0,1}^{n+1}) - \varphi_1(u_{0,1}^n)}{\delta x/2} \right) \tag{3.6}
 \end{aligned}$$

$$\begin{aligned}
 &= \left(G_2(u_{0,2}^{n+1}, u_{1/2}^{n+1}) - G_2(u_{0,2}^n, u_{1/2}^n) \right) \\
 &+ \left(\frac{\varphi_2(u_{0,2}^{n+1}) - \varphi_2(u_{1/2}^n)}{\delta x/2} \right) - \left(\frac{\varphi_2(u_{0,2}^n) - \varphi_2(u_{1/2}^n)}{\delta x/2} \right). \tag{3.7}
 \end{aligned}$$

It follows from (3.6) and from the monotony of G_1, φ_1 that

$$F_0^{n+1} - F_0^n \leq \left(G_1(u_{-1/2}^{n+1}, u_{0,1}^n) - G_1(u_{-1/2}^n, u_{0,1}^n) \right) + \left(\frac{\varphi_1(u_{-1/2}^{n+1}) - \varphi_1(u_{-1/2}^n)}{\delta x/2} \right).$$

Similar computations as those done to obtain (3.5) provide the existence of a non-negative value $a_{0,-1}^{n+1}$ such that

$$(1 + a_{0,-1}^{n+1}) F_0^{n+1} - a_{0,-1}^{n+1} F_{-1}^{n+1} \leq F_0^n. \tag{3.8}$$

Considering (3.7) instead of (3.6) shows the existence of a non-negative value $b_{0,1}^{n+1}$ such that

$$(1 + b_{0,1}^{n+1}) F_0^{n+1} - b_{0,1}^{n+1} F_1^{n+1} \geq F_0^n. \tag{3.9}$$

We denote by j_{\max}^{n+1} (resp. j_{\min}^{n+1}) the integer such that

$$F_{j_{\max}^{n+1}}^{n+1} = \max_{j \in [-N, N]} F_j^{n+1} \quad (\text{resp. } F_{j_{\min}^{n+1}}^{n+1} = \min_{j \in [-N, N]} F_j^{n+1}).$$

Either $j_{\max}^{n+1} \in \{-N, N\}$, then it follows from Remark 2.1 that $\max_{j \in \llbracket -N, N \rrbracket} F_j^{n+1} \leq \max_{i=1,2} \|G_i\|_\infty$, or $j_{\max}^{n+1} \in \llbracket -N+1, N-1 \rrbracket$. In the latter case, (3.5) and (3.8) imply

$$\max_j F_j^{n+1} = F_{j_{\max}^{n+1}}^{n+1} \leq F_{j_{\max}^n}^n \leq \max_j F_j^n.$$

Similarly, (3.5) and (3.8) yield

$$\min_j F_j^{n+1} = F_{j_{\min}^{n+1}}^{n+1} \geq F_{j_{\min}^n}^n \geq \min_j F_j^n.$$

We obtain a kind of discrete maximum principle on the discrete fluxes, which corresponds to the uniform bound on the continuous fluxes proven in [18]. It follows from Lemma 3.2 that

$$\max_{n \in \llbracket 0, M \rrbracket} \left(\max_{j \in \llbracket -N+1, N-1 \rrbracket} |F_j^{n+1}| \right) \leq \max_{i=1,2} \|G_i\|_\infty + 2 \max_{i=1,2} (\|\partial_x \varphi_i(u_0)\|_{L^\infty(\Omega_i)}). \quad \square$$

Conclusion of proof of Theorem 3.1. Let $(N_p)_{p \in \mathbb{N}}, (M_p)_{p \in \mathbb{N}}$ be two sequences of positive integers tending to $+\infty$, and let $(u_{\mathcal{D}_p})_{p \in \mathbb{N}}$ the sequences of associated discrete solutions. It has been seen in Theorem 2.9 that $(u_{\mathcal{D}_p})_p$ tends to a weak solution u in $L^r(\Omega \times (0, T))$, for all $r \in [1, +\infty)$.

Let $i = 1, 2$, let $(x, y) \in \Omega_i$, let $t \in (0, T]$. For p large enough, there exists $j_0, j_1 \in J_{\text{int}}$ such that $x_{j_0} \leq x \leq x_{j_0+1}$ and $x_{j_1} \leq y \leq x_{j_1+1}$, and there exists n such that $t \in (t^n, t^{n+1}]$

$$\begin{aligned} |\varphi_i(u_{\mathcal{D}_p})(x, t) - \varphi_i(u_{\mathcal{D}_p})(y, t)| &= \left| \varphi_i(u_{j_0+1/2}^{n+1}) - \varphi_i(u_{j_1+1/2}^{n+1}) \right| \\ &= \left| \sum_{j=j_1+1}^{j_0} \varphi_i(u_{j+1/2}^{n+1}) - \varphi_i(u_{j-1/2}^{n+1}) \right| \\ &\leq \sum_{j=j_1+1}^{j_0} \left| \varphi_i(u_{j+1/2}^{n+1}) - \varphi_i(u_{j-1/2}^{n+1}) \right|. \end{aligned}$$

Using the definition of the discrete flux (2.3):

$$|\varphi_i(u_{\mathcal{D}_p})(x, t) - \varphi_i(u_{\mathcal{D}_p})(y, t)| \leq \sum_{j=j_1+1}^{j_0} \delta x \left| F_j^{n+1} - G_i(u_{j-1/2}^{n+1}, u_{j+1/2}^{n+1}) \right|.$$

We deduce from Proposition 3.3 that there exists $C > 0$, depending only on u_0, φ_i, G_i such that:

$$|\varphi_i(u_{\mathcal{D}_p})(x, t) - \varphi_i(u_{\mathcal{D}_p})(y, t)| \leq \sum_{j=j_1+1}^{j_0} \delta x C \leq C(|x - y| + 2\delta x).$$

Letting p tend towards $+\infty$, i.e. δx and δt towards 0 gives

$$|\varphi_i(u)(x, t) - \varphi_i(u)(y, t)| \leq C|x - y|. \tag{3.10}$$

So we deduce from (3.10) that $\partial_x \varphi_i(u) \in L^\infty(\Omega_i \times (0, T))$. □

4. UNIQUENESS OF THE BOUNDED-FLUX SOLUTION

This section is devoted to the proof of Theorem 4.1, which is an adaptation of [18], Theorem 5.1, to the case where the convection is taken into account.

Theorem 4.1. *If u, v are bounded-flux solutions in the sense of Definition 3.1 associated to the initial data u_0, v_0 , then for all $p \in [1, +\infty[$, u and v belong to $C([0, T]; L^p(\Omega))$, and the following L^1 -contraction principle holds: $\forall t \in [0, T]$,*

$$\int_{\Omega_i} \phi_i(u(x, t) - v(x, t))^{\pm} dx \leq \int_{\Omega_i} \phi_i(u_0(x) - v_0(x))^{\pm} dx.$$

This particularly implies the uniqueness of the bounded flux solution to the problem (P).

Obtaining a L^1 -contraction principle for a nonlinear parabolic equation is classical. We refer for example to [5,11,19,25,30,31,33] for the case of homogeneous domains, and for boundary conditions of Dirichlet or Neumann type. We have to adapt the proof of the L^1 -contraction principle to our problem, and thus particularly to the boundary conditions and to the transmission conditions at the interface.

We need to introduce the *cut-off* functions $\rho_{\alpha}^{\varepsilon} \in C^{0,1}(\Omega, \mathbb{R}^+)$ defined by

$$\rho_{\alpha}^{\varepsilon}(x) = \left(\frac{\varepsilon - |x - \alpha|}{\varepsilon} \right)^+.$$

Lemma 4.2. *For all $\theta \in \mathcal{D}^+([0, T])$,*

$$\liminf_{\varepsilon \rightarrow 0} \int_0^T \theta(t) \sum_{i=1,2} \int_{\Omega_i} \left(\text{sign}_{\pm}(u - v)(f_i(u) - f_i(v)) - \partial_x(\varphi_i(u) - \varphi_i(v))^{\pm} \right) \partial_x \rho_0^{\varepsilon}(x) dx dt \geq 0.$$

Proof. We define the subsets of $(0, T)$

$$E_{u > v} = \left\{ t \in (0, T) \mid u_1(t) > v_1(t) \text{ or } u_2(t) > v_2(t) \right\},$$

$$E_{u \leq v} = (E_{u > v})^c = \left\{ t \in (0, T) \mid u_1(t) \leq v_1(t) \text{ and } u_2(t) \leq v_2(t) \right\}.$$

Since the trace on $\{x = 0\}$ of the function $\text{sign}_+(u - v)(f_i(u) - f_i(v))$ is equal to 0 for all $t \in E_{u \leq v}$, it is easy to check that

$$\lim_{\varepsilon \rightarrow 0} \int_{E_{u \leq v}} \theta \sum_{i=1,2} \int_{\Omega_i} \text{sign}_+(u - v)(f_i(u) - f_i(v)) \partial_x \rho_0^{\varepsilon} dx dt = 0.$$

Thanks to the fact that the trace of $(\varphi_i(u) - \varphi_i(v))^+$ is equal to 0 on the interface, one has also,

$$\liminf_{\varepsilon \rightarrow 0} \int_{E_{u \leq v}} \theta \sum_{i=1,2} \int_{\Omega_i} \partial_x(\varphi_i(u) - \varphi_i(v))^+ \partial_x \rho_0^{\varepsilon} dx dt \geq 0.$$

This particularly implies that

$$\liminf_{\varepsilon \rightarrow 0} \int_{E_{u \leq v}} \theta \sum_{i=1,2} \int_{\Omega_i} \left[\text{sign}_+(u - v)(f_i(u) - f_i(v)) - \partial_x(\varphi_i(u) - \varphi_i(v))^+ \right] \partial_x \rho_0^{\varepsilon} dx dt \geq 0. \tag{4.1}$$

Since u, v are two weak solutions, subtracting their corresponding weak formulation (1.12) for the test function $\psi(x, t) = \theta(t)\rho_0^{\varepsilon}(x)$ leads to

$$\begin{aligned} & \int_0^T \sum_{i=1,2} \int_{\Omega_i} \phi_i(u - v) \rho_0^{\varepsilon} \partial_t \theta dx dt + \sum_{i=1,2} \int_{\Omega_i} \phi_i(u_0 - v_0) \rho_0^{\varepsilon} \theta(0) dx \\ & + \int_0^T \theta \sum_{i=1,2} \int_{\Omega_i} ((f_i(u) - f_i(v)) - \partial_x(\varphi_i(u) - \varphi_i(v))) \partial_x \rho_0^{\varepsilon} dx dt = 0. \end{aligned}$$

Since ρ_0^ε tends to 0 in $L^1(\Omega)$ as $\varepsilon \rightarrow 0$, one has:

$$\lim_{\varepsilon \rightarrow 0} \int_0^T \sum_{i=1,2} \int_{\Omega_i} \phi_i(u-v) \rho_0^\varepsilon \partial_t \theta \, dx \, dt + \sum_{i=1,2} \int_{\Omega_i} \phi_i(u_0-v_0) \rho_0^\varepsilon \theta(0) \, dx = 0,$$

thus

$$\lim_{\varepsilon \rightarrow 0} \int_0^T \theta \sum_{i=1,2} \int_{\Omega_i} ((f_i(u) - f_i(v)) - \partial_x(\varphi_i(u) - \varphi_i(v))) \partial_x \rho_0^\varepsilon \, dx \, dt = 0. \tag{4.2}$$

Thanks to the $L^\infty(\Omega \times (0, T))$ bound on the fluxes, one has

$$\left| \int_0^T \theta \sum_{i=1,2} \int_{\Omega_i} ((f_i(u) - f_i(v)) - \partial_x(\varphi_i(u) - \varphi_i(v))) \partial_x \rho_0^\varepsilon \, dx \, dt \right| \leq C \|\theta\|_{L^1(0,T)},$$

then, using a density argument, (4.2) holds for all $\theta \in L^1(0, T)$.

Replacing θ by $\theta \chi_{E_{u>v}}$ in (4.2), and splitting the positive and the negative parts $a = a^+ - a^-$, we obtain

$$\begin{aligned} & \int_{E_{u>v}} \theta \sum_{i=1,2} \int_{\Omega_i} (\text{sign}_+(u-v)(f_i(u) - f_i(v)) - \partial_x(\varphi_i(u) - \varphi_i(v))^+) \partial_x \rho_0^\varepsilon \, dx \, dt \\ &= \int_{E_{u>v}} \theta \sum_{i=1,2} \int_{\Omega_i} (\text{sign}_-(u-v)(f_i(u) - f_i(v)) - \partial_x(\varphi_i(u) - \varphi_i(v))^-) \partial_x \rho_0^\varepsilon \, dx \, dt + r(\varepsilon), \end{aligned} \tag{4.3}$$

with

$$\lim_{\varepsilon \rightarrow 0} r(\varepsilon) = 0.$$

For almost every $t \in E_{u>v}$, it follows from the monotonicity of the graph relations for the capillary pressure

$$\tilde{\pi}_1(u_1) \cap \tilde{\pi}_2(u_2) \neq \emptyset, \quad \tilde{\pi}_1(v_1) \cap \tilde{\pi}_2(v_2) \neq \emptyset,$$

that t belongs to $E_{u \geq v} = \{t \in (0, T) \mid u_1(t) \geq v_1(t) \text{ and } u_2(t) \geq v_2(t)\}$. So we obtain exactly in the same way that for (4.1), that

$$\liminf_{\varepsilon \rightarrow 0} \int_{E_{u>v}} \theta \sum_{i=1,2} \int_{\Omega_i} \left[\text{sign}_-(u-v)(f_i(u) - f_i(v)) - \partial_x(\varphi_i(u) - \varphi_i(v))^- \right] \partial_x \rho_0^\varepsilon \, dx \, dt \geq 0.$$

It follows directly from (4.3) that

$$\liminf_{\varepsilon \rightarrow 0} \int_{E_{u>v}} \theta \sum_{i=1,2} \int_{\Omega_i} \left[\text{sign}_+(u-v)(f_i(u) - f_i(v)) - \partial_x(\varphi_i(u) - \varphi_i(v))^+ \right] \partial_x \rho_0^\varepsilon \, dx \, dt \geq 0. \tag{4.4}$$

Adding (4.1) and (4.4) achieves the proof of Lemma 4.2. □

Lemma 4.3. For all $\theta \in \mathcal{D}^+([0, T])$,

$$\liminf_{\varepsilon \rightarrow 0} \int_0^T \theta \int_{\Omega_1} (\text{sign}_\pm(u-v)(f_1(u) - f_1(v)) - \partial_x(\varphi_1(u) - \varphi_1(v))^\pm) \partial_x \rho_{-1}^\varepsilon \, dx \, dt \geq 0, \tag{4.5}$$

$$\liminf_{\varepsilon \rightarrow 0} \int_0^T \theta \int_{\Omega_2} (\text{sign}_\pm(u-v)(f_2(u) - f_2(v)) - \partial_x(\varphi_2(u) - \varphi_2(v))^\pm) \partial_x \rho_1^\varepsilon \, dx \, dt \geq 0. \tag{4.6}$$

Proof. For the sake of simplicity, we will only prove

$$\liminf_{\varepsilon \rightarrow 0} \int_0^T \theta \int_{\Omega_2} (\text{sign}_+(u - v)(f_2(u) - f_2(v)) - \partial_x(\varphi_2(u) - \varphi_2(v))^+) \partial_x \rho_1^\varepsilon dx dt \geq 0,$$

but all the steps of the proof can be extended to the other cases. We denote by $F_{u>v}$ and $F_{u\geq v}$ the subsets of $(0, T)$ given by

$$F_{u>v} = \{t \in (0, T) \mid u(1, t) > v(1, t)\}, \quad F_{u\leq v} = (F_{u>v})^c = \{t \in (0, T) \mid u(1, t) \leq v(1, t)\}.$$

Let $\varepsilon > 0$. For almost every $t \in F_{u\leq v}$, one has

$$\int_{\Omega_2} \partial_x(\varphi_2(u)(x, t) - \varphi_2(v)(x, t))^+ \partial_x \rho_1^\varepsilon(x) dx \leq 0.$$

Then, using the fact that for almost every $t \in F_{u\leq v}$, the trace of $\text{sign}_+(u(\cdot, t) - v(\cdot, t))(f_2(u)(\cdot, t) - f_2(v)(\cdot, t))$ on $\{x = 1\}$ is equal to 0,

$$\liminf_{\varepsilon \rightarrow 0} \int_{F_{u\leq v}} \theta \int_{\Omega_2} (\text{sign}_+(u - v)(f_2(u) - f_2(v)) - \partial_x(\varphi_2(u) - \varphi_2(v))^+) \partial_x \rho_1^\varepsilon dx \geq 0. \tag{4.7}$$

We deduce from the weak formulation that for all $\theta \in \mathcal{D}([0, T])$,

$$\lim_{\varepsilon \rightarrow 0} \int_0^T \theta \left(\int_{\Omega_2} (f_2(u) - \partial_x \varphi_2(u)) \partial_x \rho_1^\varepsilon dx - G_2(u(1, t), \bar{u}(t)) \right) dt = 0. \tag{4.8}$$

Since the fluxes $f_2(u) - \partial_x \varphi_2(u)$ and $f_2(v) - \partial_x \varphi_2(v)$ belong to $L^\infty(\Omega_2 \times (0, T))$, a density argument, which has already been used during the proof of Lemma 4.2, allows us to claim that (4.8) still holds for any $\theta \in L^1(0, T)$. So, it particularly holds if we replace θ by $\theta \chi_{F_{u>v}}$. This leads to

$$\lim_{\varepsilon \rightarrow 0} \int_{F_{u<v}} \theta \int_{\Omega_2} (f_2(u) - f_2(v) - \partial_x(\varphi_2(u) - \varphi_2(v))) \partial_x \rho_1^\varepsilon dx dt = \int_{F_{u>v}} \theta(t) (G_2(u(1, t), \bar{u}(t)) - G_2(v(1, t), \bar{u}(t))) dt.$$

It follows from the monotonicity of G_2 that

$$\forall t \in F_{u>v}, \quad G_2(u(1, t), \bar{u}(t)) \geq G_2(v(1, t), \bar{u}(t)),$$

thus

$$\liminf_{\varepsilon \rightarrow 0} \int_{F_{u<v}} \theta \int_{\Omega_2} (f_2(u) - f_2(v) - \partial_x(\varphi_2(u) - \varphi_2(v))) \partial_x \rho_1^\varepsilon dx dt \geq 0. \tag{4.9}$$

In order to conclude the proof of Lemma 4.3, it only remains to check that

$$\begin{aligned} & \liminf_{\varepsilon \rightarrow 0} \int_{F_{u<v}} \theta \int_{\Omega_2} (f_2(u) - f_2(v) - \partial_x(\varphi_2(u) - \varphi_2(v))) \partial_x \rho_1^\varepsilon dx dt \\ &= \liminf_{\varepsilon \rightarrow 0} \int_{F_{u<v}} \theta \int_{\Omega_2} (\text{sign}_+(u - v)(f_2(u) - f_2(v)) - \partial_x(\varphi_2(u) - \varphi_2(v))^+) \partial_x \rho_1^\varepsilon dx dt. \end{aligned} \tag{4.10}$$

Since φ_2^{-1} is a continuous function, $u(\cdot, t)$ can be supposed to be continuous on Ω_2 for almost every t in $(0, T)$. Particularly, for almost every $t \in F_{u>v}$, there exists a neighborhood \mathcal{V}_t of $\{x = 1\}$ such that $u(\cdot, t) > v(\cdot, t)$ for all $x \in \mathcal{V}_t$. On \mathcal{V}_t , one has

$$R(x, t) = (f_2(u) - f_2(v) - \partial_x(\varphi_2(u) - \varphi_2(v))) - (\text{sign}_+(u - v)(f_2(u) - f_2(v)) - \partial_x(\varphi_2(u) - \varphi_2(v))^+) = 0.$$

Then, for almost every $t \in F_{u>v}$,

$$\lim_{\varepsilon \rightarrow 0} \int_{\Omega_2} R(x, t) \partial_x \rho_1^\varepsilon(x) dx = 0.$$

Moreover, since the fluxes $f_2(u) - \partial_x \varphi_2(u)$ and $f_2(v) - \partial_x \varphi_2(v)$ belong to $L^\infty(\Omega_2 \times (0, T))$, there exists $C > 0$ not depending on ε such that for almost every t ,

$$\left| \int_{\Omega_2} R(x, t) \partial_x \rho_1^\varepsilon(x) dx \right| \leq C.$$

We deduce from the dominated convergence theorem that

$$\lim_{\varepsilon \rightarrow 0} \int_0^T \int_{\Omega_2} R(x, t) \partial_x \rho_1^\varepsilon(x) dx dt = 0.$$

This particularly implies that (4.10) holds. This achieves the proof of Lemma 4.3. □

Proof of Theorem 4.1. First, since u and v are weak solutions to a parabolic equation, they are also entropy solutions (see [19,25]), and it has been proven in [17] that u and v belong to $C([0, T], L^p(\Omega))$, in the sense that there exists $\tilde{u}, \tilde{v} \in C([0, T], L^p(\Omega))$ such that $u = \tilde{u}, v = \tilde{v}$ almost everywhere in $\Omega \times (0, T)$.

Let u and v be two weak solutions, then some classical computations, based on the doubling variable technique applied on both the time and the space variable (see e.g. [19,25]) yields that for any $\psi \in \mathcal{D}^+(\Omega_i \times [0, T])$

$$\begin{aligned} & \int_0^T \int_{\Omega_i} \phi_i(u(x, t) - v(x, t))^\pm \partial_t \psi(x, t) dx dt + \int_{\Omega_i} \phi_i(u_0(x) - v_0(x))^\pm \psi(x, 0) dx \\ & + \int_0^T \int_{\Omega_i} \text{sign}_\pm(u(x, t) - v(x, t)) (f_i(u)(x, t) - f_i(v)(x, t)) \partial_x \psi(x, t) dx dt \\ & - \int_0^T \int_{\Omega_i} \partial_x (\varphi_i(u)(x, t) - \varphi_i(v)(x, t))^\pm \partial_x \psi(x, t) dx dt \geq 0. \end{aligned} \tag{4.11}$$

Let $\theta \in \mathcal{D}^+([0, T])$, then summing (4.11) with respect to $i = 1, 2$, choosing

$$\psi(x, t) = \theta(t) (1 - \rho_{-1}^\varepsilon(x) - \rho_0^\varepsilon(x) - \rho_1^\varepsilon(x))$$

as test function, and letting ε tend to 0 leads to, thanks to Lemmata 4.2 and 4.3:

$$\int_0^T \partial_t \theta(t) \sum_{i=1,2} \int_{\Omega_i} \phi_i(u(x, t) - v(x, t))^\pm dx dt + \sum_{i=1,2} \int_{\Omega_i} \phi_i(u_0(x) - v_0(x))^\pm \theta(0) dx \geq 0. \tag{4.12}$$

Since u, v belong to $C([0, T]; L^1(\Omega))$, the relation (4.12) still holds for any $\theta \in BV(0, T)$ with $\theta(T^+) = 0$. Let $t \in [0, T]$, we choose $\theta = \chi_{[0,t]}$ in (4.12), obtaining this way the L^1 -contraction and comparison principle stated in the Theorem 4.1. □

5. SOLUTIONS OBTAINED AS LIMIT OF APPROXIMATIONS

We aim in this section to extend the existence-uniqueness result obtained in Theorems 3.1 and 4.1 for any initial data $u_0 \in L^\infty(\Omega)$, $0 \leq u_0 \leq 1$ a.e. We are unfortunately not able to prove the uniqueness of the weak solution to the problem (P) in such a general case, but we are able to prove the existence and the uniqueness of the solution obtained as limit of approximation by bounded flux solution. Moreover, this limit is the weak solution obtained *via* the convergence of the implicit scheme (2.2) studied previously.

Definition 5.1. A function u is said to be a **SOLA** (solution obtained as limit of approximation) to the problem (\mathcal{P}) if it fulfils:

- u is a weak solution to the problem (\mathcal{P}) ;
- there exists a sequence $(u_\nu)_{\nu \in \mathbb{N}}$ of bounded flux solutions such that

$$u_n \rightarrow u \text{ in } C([0, T]; L^1(\Omega)), \text{ as } n \rightarrow +\infty.$$

Theorem 5.1. Let $u_0 \in L^\infty(\Omega)$, $0 \leq u_0 \leq 1$ a.e., then there exists a unique SOLA u to the problem (\mathcal{P}) in the sense of Definition 5.1.

Furthermore, if $(M_p)_{p \in \mathbb{N}}$, $(N_p)_{p \in \mathbb{N}}$ are to sequences of positive integers tending to $+\infty$, and if $(u_{\mathcal{D}_p})_{p \in \mathbb{N}}$ is the corresponding sequence of discrete solutions, then $u_{\mathcal{D}_p} \rightarrow u$ in $L^r(\Omega \times (0, T))$, $r \in [1, +\infty)$.

Proof. The set

$$\mathcal{E} = \left\{ u_0 \in L^\infty(\Omega) \mid 0 \leq u_0 \leq 1, \partial_x \varphi_i(u_0) \in L^\infty(\Omega_i), \tilde{\pi}_1(u_{0,1}) \cap \tilde{\pi}_2(u_{0,2}) \neq \emptyset \right\}$$

is dense in $\{u_0 \in L^\infty(\Omega) \mid 0 \leq u_0 \leq 1\}$ for the $L^1(\Omega)$ -topology. Then we can build a sequence $(u_{0,\nu})_{\nu \in \mathbb{N}}$ such that

$$\lim_{\nu \rightarrow \infty} \|u_{0,\nu} - u_0\|_{L^1(\Omega)} = 0.$$

Let $(u_\nu)_\nu$ be the corresponding sequence of bounded flux solutions, then we deduce from Theorem 4.1 that for all $\nu, \mu \in \mathbb{N}$,

$$\forall t \in [0, T], \quad \sum_{i=1,2} \int_{\Omega_i} \phi_i(u_\nu(x, t) - u_\mu(x, t))^\pm dx \leq \sum_{i=1,2} \int_{\Omega_i} \phi_i(u_{0,\nu}(x) - u_{0,\mu}(x))^\pm dx. \quad (5.1)$$

Then $(u_\nu)_\nu$ is a Cauchy sequence in $C([0, T]; L^1(\Omega))$, thus it converges towards $u \in C([0, T]; L^1(\Omega))$, and

$$\forall t \in [0, T], \quad \sum_{i=1,2} \int_{\Omega_i} \phi_i(u_\nu(x, t) - u(x, t))^\pm dx \leq \sum_{i=1,2} \int_{\Omega_i} \phi_i(u_{0,\nu}(x) - u_0(x))^\pm dx. \quad (5.2)$$

Let us now check that u is a weak solution. Since φ_i is continuous, and since $0 \leq u_\nu \leq 1$ a.e., $\varphi_i(u_\nu)$ converges in $L^2(\Omega_i \times (0, T))$ towards $\varphi_i(u)$. The $L^2((0, T); H^1(\Omega_i))$ estimate (2.23) does not depend on u_0 , thus, up to a subsequence, $(\varphi_i(u_\nu))_\nu$ converges weakly to $\varphi_i(u)$ in $L^2((0, T); H^1(\Omega_i))$. It also converges strongly in $L^2((0, T); H^s(\Omega_i))$ for all $s \in (0, 1)$. This particularly ensures the strong convergence of the traces of $(\varphi_i(u_\nu))_\nu$ on the interface. Since φ_i^{-1} is continuous, we obtain the strong convergence of the traces of $(u_\nu)_\nu$. Checking that the set

$$F = \{(a, b) \in [0, 1]^2 \mid \tilde{\pi}_1(a) \cap \tilde{\pi}_2(b) \neq \emptyset\}$$

the limits u_i fulfill $\tilde{\pi}_1(u_1) \cap \tilde{\pi}_2(u_2) \neq \emptyset$, and so u is a weak solution, then it is a SOLA.

If u and v are two SOLAs associated to the initial data u_0 and v_0 , we can easily prove, using Theorem 4.1 that

$$\forall t \in [0, T], \quad \sum_{i=1,2} \int_{\Omega_i} \phi_i(u(x, t) - v(x, t))^\pm dx \leq \sum_{i=1,2} \int_{\Omega_i} \phi_i(u_0(x) - v_0(x))^\pm dx. \quad (5.3)$$

The uniqueness particularly follows.

Let $u_0 \in L^\infty(\Omega)$, $0 \leq u_0 \leq 1$, and let $(u_{0,\nu})_\nu \subset \mathcal{E}$ a sequence of approximate initial data tending to u_0 in $L^1(\Omega)$. We denote by u the unique SOLA associated to u_0 , and by $(u_\nu)_\nu$ the bounded flux solutions associated to $(u_{0,\nu})_\nu$. Let $(M_p)_{p \in \mathbb{N}}$, $(N_p)_{p \in \mathbb{N}}$ be two sequences of positive integers tending to $+\infty$. Let $p \in \mathbb{N}$, $\nu \in \mathbb{N}$, let $u_{\mathcal{D}_p}$ the discrete solution corresponding to u_0 , and let u_{ν, \mathcal{D}_p} the discrete solution corresponding to $u_{0,\nu}$:

$$\|u_{\mathcal{D}_p} - u\|_{L^1(\Omega \times (0, T))} \leq \|u_{\mathcal{D}} - u_{\nu, \mathcal{D}_p}\|_{L^1(\Omega \times (0, T))} + \|u_{\nu, \mathcal{D}_p} - u_\nu\|_{L^1(\Omega \times (0, T))} + \|u_\nu - u\|_{L^1(\Omega \times (0, T))}.$$

From the discrete L^1 -contraction principle (2.11), and from the continuous one (5.2), we have

$$\begin{aligned} \|u_{\mathcal{D}_p} - u\|_{L^1(\Omega \times (0,T))} &\leq T \frac{\max \phi_i}{\min \phi_i} \|u_{0,\mathcal{D}} - u_{0,\nu,\mathcal{D}_p}\|_{L^1(\Omega)} + \|u_{\nu,\mathcal{D}_p} - u_\nu\|_{L^1(\Omega \times (0,T))} \\ &\quad + T \frac{\max \phi_i}{\min \phi_i} \|u_{0,\nu} - u_0\|_{L^1(\Omega)}. \end{aligned}$$

Letting p tend to ∞ , it follows from the definition of $(u_{0,\nu,\mathcal{D}})$ (adapted from (2.1)) that

$$\lim_{p \rightarrow \infty} \|u_{0,\mathcal{D}} - u_{0,\nu,\mathcal{D}_p}\|_{L^1(\Omega)} = \|u_{0,\nu} - u_0\|_{L^1(\Omega)}.$$

We have proven in Theorem 3.1 that the sequence of discrete solutions converges, under assumptions on the initial data, to the unique bounded flux solution, thus

$$\lim_{p \rightarrow \infty} \|u_{\nu,\mathcal{D}_p} - u_\nu\|_{L^1(\Omega \times (0,T))} = 0.$$

This implies

$$\limsup_{p \rightarrow \infty} \|u_{\mathcal{D}_p} - u\|_{L^1(\Omega \times (0,T))} \leq 2T \frac{\max \phi_i}{\min \phi_i} \|u_{0,\nu} - u_0\|_{L^1(\Omega)}.$$

Letting ν tend to ∞ provides

$$\lim_{p \rightarrow \infty} \|u_{\mathcal{D}_p} - u\|_{L^1(\Omega \times (0,T))} = 0.$$

The convergence occurs in $L^1(\Omega \times (0,T))$, but the uniform bound on the sequence $(u_{\mathcal{D}_p})$ in $L^\infty(\Omega \times (0,T))$ ensures that the convergence also take place in all the $L^p(\Omega \times (0,T))$, for $p \in [1, \infty)$. \square

6. NUMERICAL RESULT

In order to illustrate this model, we use a test case developed by Anthony Michel [32]. The porous medium $\Omega = (0, 1)$ is made of sand for $x \in (0, 0.5) \cup (0.7, 1)$, with a layer of shale for $x \in (0.5, 0.7)$.

First case

The total flow rate is equal to 0, since $f_{\text{sand}}(1) = f_{\text{shale}}(1) = 0$, and the convection is the exclusive of the volume mass difference between the oil, which is lighter, and the water. The convection functions are given by:

$$f_{\text{sand}}(u) = 100 * f_{\text{shale}}(u) = 50 * \frac{u^2(1 - u^2)}{1 - 2u + 2u^2}.$$

The capillary pressures are first given by

$$\pi_{\text{sand}}(u) = u^5, \quad \pi_{\text{shale}}(u) = 0.5 + u^5.$$

The functions φ_{sand} and φ_{shale} , given by

$$\varphi_{\text{sand}}(u) = 10 * \int_0^u \frac{s^2(1 - s^2)}{1 - 2s + 2s^2} \pi'_{\text{sand}}(s) ds, \quad \varphi_{\text{shale}}(u) = 0.1 * \int_0^u \frac{s^2(1 - s^2)}{1 - 2s + 2s^2} \pi'_{\text{shale}}(s) ds,$$

are computed using an approximate integration formula. The initial data u_0 is equal to 0, and $\underline{u} = 0.001$, $\bar{u} = 0$.

The convection is approximated by a Godunov scheme, defined by

$$G_i(a, b) = \begin{cases} \min_{s \in [a,b]} f_i(s) & \text{if } a \leq b, \\ \max_{s \in [b,a]} f_i(s) & \text{otherwise.} \end{cases}$$

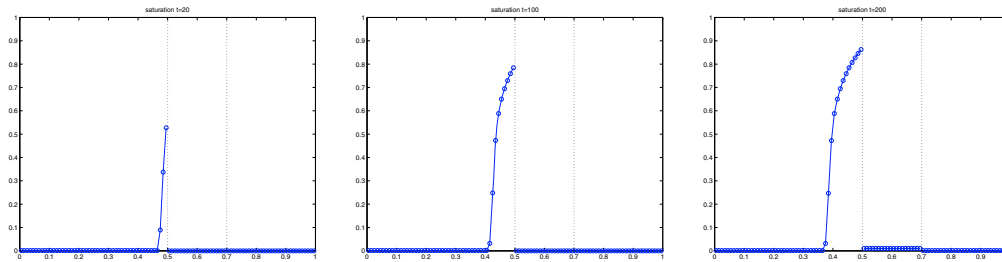


FIGURE 1. Saturation profiles for $t = 20$, $t = 100$, $t = 200$.

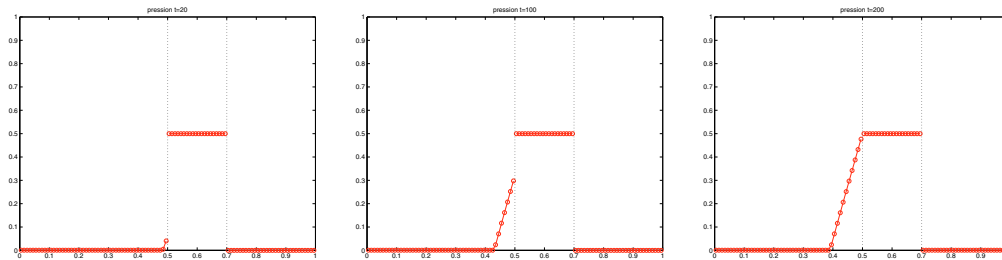


FIGURE 2. Capillary pressure profiles for $t = 20$, $t = 100$, $t = 200$.

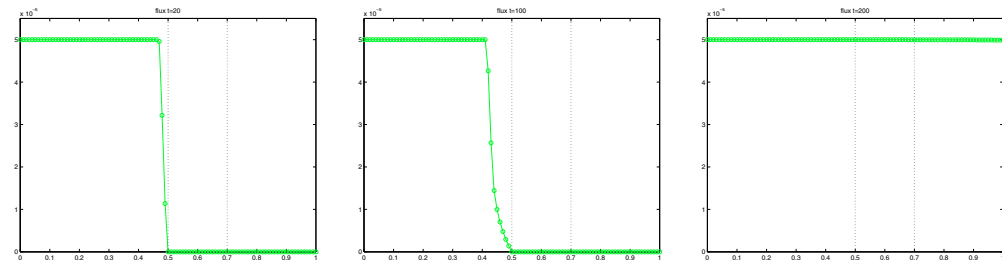


FIGURE 3. Oil-flux profiles for $t = 20$, $t = 100$, $t = 200$.

A little quantity of oil enters the domain from the left boundary condition, and it moves forward in the first part made of sand. The discontinuity of the capillary pressure (Fig. 2) stops the migration of oil, which begins to collect at the left of the interface, as shown in Figure 1. One can check in Figure 3 that for t small enough, the oil-flux through the interface $\{x = 0.5\}$ is equal to 0. The accumulation of oil at the left of $\{x = 0.5\}$ implies an increase of the capillary pressure. As soon as the capillary pressure connects at $\{x = 0.5\}$, the oil can flow through the shale. The next discontinuity at $\{x = 0.7\}$ does not impede the progression of the oil, since the capillary pressure force, oriented from the large pressure to the small pressure (here from the left to the right), works in the same direction that the buoyancy, which drives the migration of oil.

For $t = 200$, the presented solution is a steady solution, with constant flux (Fig. 3). Some oil remains blocked in the first subdomain $(0, 0.5)$. Even if one puts $\underline{u}(t) = 0$ for $t \geq 200$, the main proportion of oil in the porous medium can not overpass the interface $\{x = 0.5\}$ and leave the porous medium $(0, 1)$. Indeed, the function defined by

$$u^s(x) = \begin{cases} 0 & \text{if } x \notin (0.4, 0.5), \\ \pi_{\text{sand}}^{-1}(5(x - 0.4)) & \text{if } x \in (0.4, 0.5) \end{cases}$$

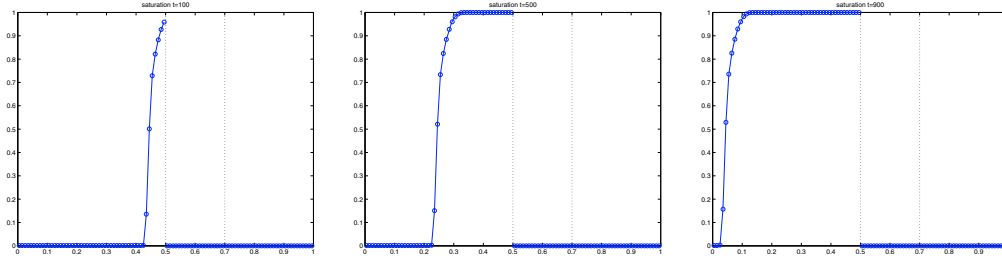


FIGURE 4. Saturation profiles for $t = 100$, $t = 500$, $t = 900$.

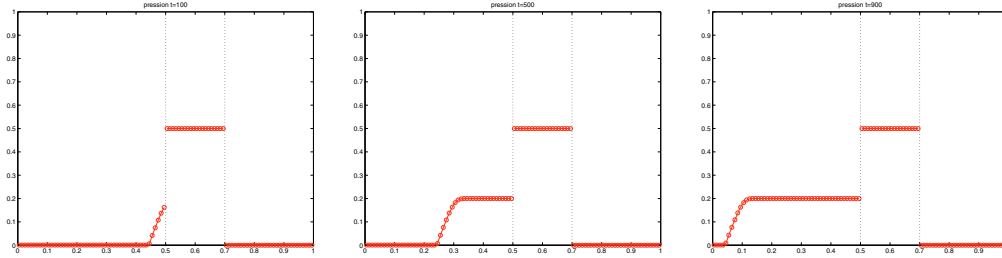


FIGURE 5. Capillary pressure profiles for $t = 100$, $t = 500$, $t = 900$.

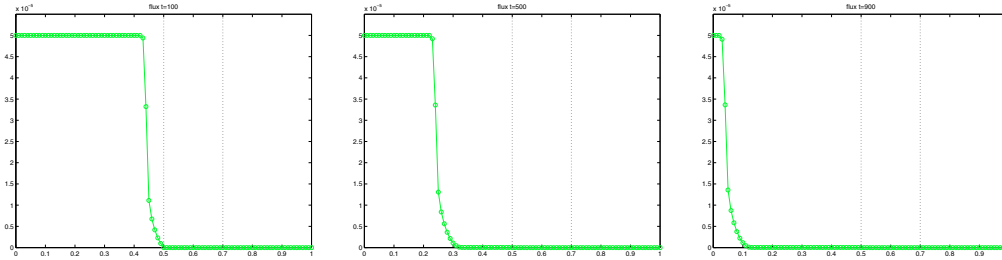


FIGURE 6. Oil-flux profiles for $t = 100$, $t = 500$, $t = 900$.

is a steady solution to the problem for $\underline{u} = 0$. It is easy to check that $u(\cdot, 200) \geq u^s$, thus the comparison principle stated in Theorem 4.1 ensures that for all $t \geq 200$, $u(\cdot, t) \geq u^s$. Thus for all $t \geq 200$

$$\int_0^{0.5} u(x, t) dx \geq \int_0^{0.5} u^s(x) dx > 0.$$

This quantity is said to be trapped by the geology change. Further illustrations, and a scheme comparison will be given in [32].

Second case

We only change the values of the capillary pressure functions (and also the linked functions φ_{sand} and φ_{shale}). The amplitude of the variation of each function is reduced from 1 to 0.2, *i.e.*

$$\pi_{\text{sand}}(u) = 0.2 * u^5, \quad \pi_{\text{shale}}(u) = 0.5 + 0.2 * u^5.$$

The graph transmission condition for the capillary pressure turns to

$$(1 - u_{\text{sand}})u_{\text{shale}} = 0,$$

where u_{sand} (resp u_{shale}) denotes the trace of the oil saturation at the interfaces $\{x = 0.5\}$ and $\{x = 0.7\}$. In this case, no oil can overpass the first interface, which is thus impermeable for oil (see Figs. 4, 5 and 6). The only steady solution is

$$u^s(x) = \begin{cases} 1 & \text{if } x < 0.5, \\ 0 & \text{if } x > 0.5. \end{cases}$$

An asymptotic study for capillary pressures tending to functions depending only of space, and not on the saturation has been performed in [13], Chapters 5 and 6 (see also [15,16]). It has been proven that either the limit solution for the saturation is an entropy solution for the hyperbolic scalar conservation law with discontinuous fluxes in the sense of [1–4,6–9,26,34–36] (see also [27–29]), mainly when the capillary forces at the interface are oriented in the same direction that the gravity forces, or that non-classical shocks can occur at the interfaces when the capillary forces and the gravity are oriented in opposite directions.

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