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Existence Theorems
for Moving Boundary Optimization Problems.

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SUMMARY - We prove the existence of a minimum for an integral functional whose domain of integration varies in the class of closed convex subsets of a bounded closed convex set in $\mathbb{R}^n$.

1. Introduction.

Let $\mathbb{R}^n$ be the usual $n$-dimensional euclidean space; we are given $T$, a bounded closed convex subset of $\mathbb{R}^n$, $L : T \times \mathbb{R} \times \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$, a normal proper integrand and $l$, an extended real valued function defined on the space $K(T)$ of all closed convex subsets of $T$, which is lower semicontinuous with respect to a suitable sort of convergence in $K(T)$.

For any $\Omega \in K(T)$ we denote by $\Omega^0$ the interior of $\Omega$ and we consider $H^{1,1}(\Omega^0)$, the usual Sobolev space of real valued functions.

For any given pair $(\Omega, x)$, $\Omega \in K(T)$, $x \in H^{1,1}(\Omega^0)$, we define

$$F(\Omega, x) = \int_{\Omega} L(t, x(t), \nabla x(t)) \ dt + l(\Omega)$$

and if $u \in H^{1,1}(T^0)$ is a fixed function and $\gamma_\Omega$ is the trace operator in

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we consider the problem

\[ \text{Minimize } \{ F(\Omega, x): \Omega \in \mathcal{K}(T), \ x \in H^{1,1}(\Omega^0), \ \gamma_D(x) = \gamma_D(u) \}. \]

In this paper we shall prove a theorem which assures that it has at least one solution.

Our problem has been already treated by Ioffe in [10] in the one-dimensional case, while the problem to minimize \[ \int L(t, x(t), \nabla x(t)) \, dt \]

is also treated in [8] when \( \Omega \) is a fixed set in \( \mathbb{R}^n \).

We also recall that one-dimensional case in a fixed interval is studied in [1-2-3-4-5] also when the arcs take values in an infinite dimensional space and when the integrand depends upon higher order derivatives.

We wish to express our thanks to Professor J. P. Cecconi for his interest in this work.

2. Notations.

Throughout all of this work \( \mathbb{R}^n \) is the usual \( n \)-dimensional euclidean space with norm \( | \cdot | \) and inner product \( \langle \cdot, \cdot \rangle \); \( T \) is a fixed bounded closed convex subset of \( \mathbb{R}^n \) and \( \mathcal{K}(T) \) is the set of all closed convex subsets of \( T \), equipped with the Kuratowski convergence [12].

For any fixed \( \Omega \in \mathcal{K}(T) \), \( \Omega^0 \) is the interior of \( \Omega \), \( H^{1,1}(\Omega^0) \) is the space of all real functions \( x \in L^1(\Omega) \) such that \( \partial x/\partial t_i \), in the sense of distributions, is in \( L^1(\Omega) \), for every \( i = 1, 2, \ldots, n \), while \( H^{1,1}_0(\Omega^0) \) is the closure in \( H^{1,1}(\Omega^0) \) of \( C_0^\infty(\Omega^0) \), the space of all real functions, which have compact support contained in \( \Omega^0 \) and derivatives of any order in \( \Omega^0 \); the vector

\[ (\partial x/\partial t_1, \ \partial x/\partial t_2, \ \ldots, \ \partial x/\partial t_n) \]

will be indicated briefly by \( \nabla x \).

Since \( \Omega^0 \) is a bounded convex set, we may assert that there is a linear continuous trace operator:

\[ \gamma_D: H^{1,1}(\Omega^0) \to L^1(\partial \Omega), \]

and it can be proved, [13-14], that

\[ H^{1,1}_0(\Omega^0) = \{ x \in H^{1,1}(\Omega^0): \gamma_D(x) = 0 \}. \]
\[ L: T \times \mathbb{R} \times \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\} \] is a normal proper integrand, such that \( L(t, x, \cdot) \) is convex for every \((t, x) \in T \times \mathbb{R}\) and

\[ H: T \times \mathbb{R} \times \mathbb{R}^n \to \mathbb{R} \cup \{\pm \infty\} \]
is defined as

\[ H(t, x, p) = \sup \{ \langle p, v \rangle - L(t, x, v) : v \in \mathbb{R}^n \} \]

and is usually called the Hamiltonian function associated to \( L \).

\[ l: K(T) \to \mathbb{R} \cup \{+\infty\} \] is a lower semicontinuous function.

For every pair \((\Omega, x), \Omega \in K(T), x \in H^{1, 1}(\Omega^0)\)

\[ F(\Omega, x) = \int_{\Omega} L(t, x(t), \nabla x(t)) \, dt + l(\Omega) \]
is a well defined real extended valued functional, as soon as we adopt the usual conventions about infinite values [1-2-3-4-5].

To avoid trivial cases we always suppose that there is at least one pair \((\Omega_1, x_1)\) such that \( F(\Omega_1, x_1) \) is a real number.

### 3. Statement of the problem.

The problem we are dealing with can be posed in the following form:

Let \( u \in H^{1, 1}(T^0) \) and let

\[ \beta = \inf \{ F(\Omega, x) : \Omega \in K(T), x \in H^{1, 1}(\Omega^0), \gamma_\Omega(x) = \gamma_\Omega(u) \} . \]

Are there \( \Omega_0 \in K(T), x_0 \in H^{1, 1}(\Omega^0_0) \) such that \( \gamma_{\Omega_0}(x_0) = \gamma_{\Omega_0}(u) \) and \( F(\Omega_0, x_0) = \beta \)?

Here we prove an existence theorem which gives an affirmative answer to this question as soon as the following conditions are satisfied:

1. \( \inf \{ l(\Omega) : \Omega \in K(T) \} = k > -\infty \);

2. there is a normal integrand \( g: T \times \mathbb{R}_+ \to \mathbb{R} \) such that \( g(\cdot, p) \) is summable for every \( p \) and there is \( x \in \mathbb{R} \) such that

\[ H(t, x, p) \leq g(t, |p|) + \alpha |x| . \]
REMARKS. We may always suppose, with no loss of generality, that $g$ assumes positive values.

Let $\Omega^0 \in K(T)$, if we choose

$$
l(\Omega) = \begin{cases} 
0, & \Omega = \Omega^0 \\
+\infty, & \Omega \neq \Omega^0
\end{cases}
$$

our problem reduces to an usual fixed boundary problem.

We wish to remark that, in this case, we give an existence result which is better than the ones proved in [8]. In particular condition (2) is weaker than the « growth condition » used in [8] (for instance $L(t, x, v) = v^2 - |x|$ satisfies (2) and does not satisfies the growth condition of [8]).

4. Some preliminary results.

We begin recalling the concept of Kuratowski convergence.

**Definition 1.** Let $\Omega_n \in K(T)$, we say that $\Omega_n$ converges to $\Omega$ in the sense of Kuratowski and we simply write $\Omega_n \rightharpoonup \Omega$ when the following facts are verified:

(i) for every $x \in \Omega$ there is $x_n \in \Omega_n$ such that $x_n \to x$;

(ii) let $x_n \in \Omega_n$, for any subsequence $x_{n_k} \to x$, we have $x \in \Omega$.

**Proposition 2.** Let $\Omega_n \rightharpoonup \Omega$, then $\Omega \in K(T)$.

The proof is an easy verification.

For every subset $\Omega \in \mathbb{R}^n$ we write $\partial \Omega$ for the boundary of $\Omega$ and $\Omega^\varepsilon$ for $\mathbb{R}^n \setminus \Omega$.

**Definition 3.** Let $\Omega \in K(T)$, $\varepsilon \in \mathbb{R}_+$, we define

$$
\Omega_{\varepsilon^+} = \{ x \in \mathbb{R}^n : d(x, \Omega) < \varepsilon \}
$$

$$
\Omega_{\varepsilon^-} = \{ x \in \mathbb{R}^n : d(x, \Omega^\varepsilon) \geq \varepsilon \}.
$$

**Proposition 4.** Let $\Omega_n \in K(T)$, $\Omega_n \rightharpoonup \Omega$; then for every $\varepsilon \in \mathbb{R}_+$ there is $n_\varepsilon \in \mathbb{N}$ such that, for $n > n_\varepsilon$

(i) $\Omega_n \subseteq \Omega_{\varepsilon^+}$

(ii) $\Omega \subseteq (\Omega_n)_{\varepsilon^+}$. 

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**Proof.** Suppose that (i) is not true, then there are \( x_n \in \Omega_n \) and \( \varepsilon_0 \in \mathbb{R}_+ \) such that \( d(x_n, \Omega) > \varepsilon_0 \). Since we may suppose \( x_n \to x_0 \), we have \( x_0 \in \Omega \) and \( d(x_0, \Omega) > \varepsilon_0 \) which is absurd.

To prove (ii) let \( B(x_i, \varepsilon/2) = \{ x \in \mathbb{R}^* : |x_i - x| < \varepsilon/2 \} \); then we may find a finite subset \( N \subset \mathbb{N} \) such that

\[
\Omega \subset \bigcup_{i \in N} B(x_i, \varepsilon/2), \quad \text{with } x_i \in \Omega.
\]

Since \( \Omega_n \to \Omega \), there is \( n_\varepsilon \in \mathbb{N} \) such that \( d(x_i, \Omega_n) < \varepsilon/2 \) for every \( i \in N \) and for \( n > n_\varepsilon \). So, if \( x_0 \in \Omega \), there is \( i_0 \in N \) such that

\[
d(x_0, \Omega_n) < |x_0 - x_{i_0}| + d(x_{i_0}, \Omega_n) < \varepsilon \quad \text{for } n > n_\varepsilon. \quad \Box
\]

**Lemma 5.** Let \( \Omega \in \mathbb{K}(T) \), then \( \Omega = (\Omega_{e^+})_{e^-} \).

**Proof.** Let \( x \in \Omega \), if \( \inf \{|x - y| : y \in (\Omega_{e^+})^c\} < \varepsilon \) there is \( x_0 \in (\Omega_{e^+})^c \) such that \( |x - x_0| < \varepsilon \) and so we have \( x_0 \in (\Omega_{e^+})^c \) and \( x \in \Omega_{e^+} \); this is absurd.

So \( d(x, (\Omega_{e^+})^c) > \varepsilon \) and \( x \in (\Omega_{e^+})_{e^-} \).

Conversely let \( x \notin \Omega \), then there is \( x_0 \in \Omega \) such that \( 0 < |x - x_0| \), \( x - x_0 = \nu \), where \( \nu \) is in the cone of the normals to \( \Omega \) at \( x_0 \).

Now two cases are possible:

(i) \( |\nu| > \varepsilon \);
(ii) \( 0 < |\nu| < \varepsilon \).

In the first case \( d(x, \Omega) = |x - x_0| = |\nu| > \varepsilon \); so \( x \notin \Omega_{e^+} \), i.e. \( x \in (\Omega_{e^+})^c \) and, since \( d(x, (\Omega_{e^+})^c) = 0 \), \( x \notin (\Omega_{e^+})_{e^-} \).

In the second case let \( \lambda = \varepsilon + |\nu|/2 \) and \( y_0 = x_0 + \lambda \nu/|\nu| \); we have:

\[
d(y_0, \Omega) = |y_0 - x_0| = \lambda > \varepsilon \quad \text{and } y_0 \in (\Omega_{e^+})^c. \quad \Box
\]

**Theorem 6.** Let \( \Omega_n \in \mathbb{K}(T) \), \( \Omega_n \to \Omega \), then for every \( \varepsilon \in \mathbb{R}_+ \) there is \( n_\varepsilon \in \mathbb{N} \) such that

\[
\Omega_{e^-} \subset \Omega_n \subset \Omega_{e^+} \quad \text{for every } n > n_\varepsilon.
\]

**Proof.** It follows from proposition 4 and lemma 5 as soon as we observe that if \( \Omega_1, \Omega_2 \in \mathbb{K}(T) \), \( \Omega_1 \subset \Omega_2 \) then \( (\Omega_1)_{e^-} \subset (\Omega_2)_{e^-} \). \( \Box \)
When $\Omega_1, \Omega_2 \in K(T)$, we define the symmetric difference between $\Omega_1$ and $\Omega_2$ as

$$\Omega_1 \Delta \Omega_2 = (\Omega_1 \setminus \Omega_2) \cup (\Omega_2 \setminus \Omega_1).$$

**Theorem 7.** Let $\Omega_n \in K(T)$, $\Omega_n \to \Omega$, then

$$\lim_{n} \text{meas} (\Omega_n \Delta \Omega) = 0.$$

**Proof.** We have $\Omega_n \Delta \Omega \subseteq \Omega_{\varepsilon^+} \setminus \Omega_{\varepsilon^-}$ for $n > n_{\varepsilon}$; so it is enough to prove that $\text{meas} (\Omega_{\varepsilon^+} \setminus \Omega_{\varepsilon^-}) \to 0$ as $\varepsilon \to 0$.

Fixed any real positive number $\delta$, there is an open set $G \supset \Omega$ and a closed set $F \subset \Omega^0$ such that $\text{meas} (G \setminus \Omega) < \delta/2$ and $\text{meas} (\Omega \setminus F) = \text{meas} (\Omega^0 \setminus F) < \delta/2$.

Since it is easily seen that there is $\varepsilon_0 \in \mathbb{R}_+$ such that when $\varepsilon < \varepsilon_0$ $G \supset \Omega_{\varepsilon^+}$ and $F \subset \Omega_{\varepsilon^-}$, we may assert that

$$\text{meas} (\Omega_{\varepsilon^+} \setminus \Omega_{\varepsilon^-}) \leq \text{meas} (G \setminus \Omega) + \text{meas} (\Omega \setminus F) < \delta. \quad \square$$

**Corollary 8.** Let $\Omega_n \in K(T)$, $\Omega_n \to \Omega$, then

$$\lim_{\varepsilon} \lim_{n} \text{meas} (\Omega_n \setminus \Omega_{\varepsilon^-}) = 0.$$

**Proof.** When $n$ is sufficiently large we have

$$\Omega_n \setminus \Omega_{\varepsilon^-} = [(\Omega_n \setminus \Omega) \cup (\Omega \setminus \Omega_{\varepsilon^-})] \setminus (\Omega \setminus \Omega_n),$$

$$\Omega_n \setminus \Omega \cap (\Omega \setminus \Omega_{\varepsilon^-}) = \emptyset,$$

$$\Omega \setminus \Omega_n \subset [(\Omega_n \setminus \Omega) \cup (\Omega \setminus \Omega_{\varepsilon^-})],$$

and so

$$\text{meas} (\Omega_n \setminus \Omega_{\varepsilon^-}) = \text{meas} (\Omega_n \setminus \Omega) + \text{meas} (\Omega \setminus \Omega_{\varepsilon^-}) - \text{meas} (\Omega \setminus \Omega_n). \quad \square$$

5. **Main theorem.**

In this part we state and prove the existence result for our problem.

**Theorem 9.** Suppose that conditions (1) and (2) are satisfied and let $u \in H^{1,1}(T^n)$ be a fixed function; then there is $\Omega_0 \in K(T)$ and there is
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\( x_0 \in H^{1,1}(\Omega^0) \) such that \( \gamma_{\Omega_0}(x_0) = \gamma_{\Omega_0}(u) \) and

\[
F(\Omega_0, x_0) = \inf \{ F(\Omega, x) : \Omega \in \mathcal{K}(T), \ x \in H^{1,1}(\Omega^0), \ \gamma_{\Omega}(x) = \gamma_{\Omega}(u) \}.
\]

**Proof.** Unless to substitute \( L(t, x, v) \) with \( L(t, x + u(t), v + \nabla u(t)) \), we may reduce ourselves to prove that there is \( \Omega_0 \in \mathcal{K}(T) \) and there is \( x_0 \in H^{1,1}(\Omega^0) \) such that

\[
F(\Omega_0, x_0) = \inf \{ F(\Omega, x) : \Omega \in \mathcal{K}(T), \ x \in H^{1,1}(\Omega^0) \}.
\]

(Observe that \( L(t, x + u(t), v + \nabla u(t)) \) satisfies condition (2) as soon as it holds for \( L(t, x, v) \).)

For any \( x \in H^{1,1}(\Omega^0) \) we define:

\[
y(t) = \begin{cases} x(t), & t \in \Omega^0 \\ 0, & t \in T^0 \setminus \Omega. \end{cases}
\]

Obviously it results \( y \in H^{1,1}(T^0) \).

Now, let \( \Omega_n \in \mathcal{K}(T) \), \( x_n \in H^{1,1}(\Omega^0) \) be a minimizing sequence. Since \( T \) is a bounded set, we may suppose, [9], that \( \Omega_n \to \Omega_0 \) and \( \Omega_0 \in \mathcal{K}(T) \) (see also proposition 2); moreover, for some constant \( M \), we have, for every \( \lambda \in \mathbb{R}_+ \),

\[
M \geq \int_{\Omega_n} L(t, x_n(t), \nabla x_n(t)) \, dt + l(\Omega_n) \geq \int_{\Omega_n} \sup \{ \langle p, \nabla x_n \rangle - H(t, x_n(t), p) : p \in \mathbb{R}^n \} \, dt + k \\
> \int_{\Omega_n} \{ \lambda |\nabla x_n(t)| - g(t, \lambda) - \alpha |x_n(t)| \} \, dt + k \\
> \lambda \int_T |\nabla y_n(t)| \, dt - \int_T g(t, \lambda) \, dt - \alpha \int_T |y_n(t)| \, dt + k.
\]

Now, by Poincaré's inequality [10-11], we deduce that:

\[
M \geq \lambda C \int_T |y_n(t)| \, dt - \int_T g(t, \lambda) \, dt - \alpha \int_T |y_n(t)| \, dt + k \leq (\lambda C - \alpha) \|y_n\|_{L^1(T)} + H
\]

and \( M - H \geq (\lambda C - \alpha) \|y_n\|_{L^1(T)} \).
So, since \( \lambda \) may be chosen arbitrarily large, we conclude that

\[ \| y_n \|_{L^1(T)} < N. \]

If we put

\[ f(t, s) = \sup \{ rs - g(t, r) : r \in \mathbb{R}_+ \} \]

by (3) we have

\[ M - k \geq \int_T \sup \{ |\nabla y_n(t)| - g(t, \lambda) : \lambda \in \mathbb{R}_+ \} \, dt - \alpha \| y_n \|_{L^1(T)} \geq \int_T f(t, |\nabla y_n(t)|) \, dt - \alpha N. \]

So using (2) and [14], we deduce that \( \nabla y_n \) is weakly compact in \((L^1(T))^n\), and in particular we obtain that

\[ \| \nabla y_n \|_{(L^1(T))^n} < R. \]

Now, since \( y_n \) is bounded in \( L^1(T) \) while \( \nabla y_n \) is weakly compact in \((L^1(T))^n\), we may find a subsequence, which we call \( y_n \) again, such that \( y_n \to x_0 \) weakly in \( H^{1,1}_0(T^\circ) \).

Let \( t \in T^\circ \setminus \Omega_0 \), then, since \( \Omega_n \to \Omega_0 \), for \( n \) sufficiently large \( t \notin \Omega_n \) and \( y_n(t) = 0 \); so by [8], \( x_0(t) = 0 \) for almost every \( t \in T^\circ \setminus \Omega_0 \). Moreover

\[ \int_{T^\circ \setminus \Omega_0} |\nabla y_n(x_0)| < A \int_{T^\circ \setminus \Omega_0} \{|x_0| + |\nabla x_0|\} = 0 \]

and we have \( x_0 \in H^{1,1}_0(\Omega_0^c) \).

Finally let

\[ \beta = \inf \{ F(\Omega, x) : \Omega \in \mathcal{K}(T), x \in H^{1,1}_0(\Omega_0^c) \}; \]

we have:

\[ \beta = \lim \int_{\Omega_n} L(t, x_n(t), \nabla x_n(t)) \, dt + l(\Omega_n) \geq \lim \inf \int_{\Omega_n} L(t, y_n(t), \nabla y_n(t)) \, dt + \]

\[ + \int_{\Omega_n \setminus \Omega_0} L(t, y_n(t), \nabla y_n(t)) \, dt + l(\Omega_0) \geq \int_{\Omega_n \setminus \Omega_0} L(t, x_0(t), \nabla x_0(t)) \, dt + l(\Omega_0) + \]

\[ + \lim \inf \int_{\Omega_n \setminus \Omega_0} \{- g(t, 0) - \alpha |y_n(t)| \} \, dt \]
for every $s \in \mathbb{R}_+$, as soon as we remember the semicontinuity result of [11].

Now, by monotone convergence theorem, as $L(t, x_0(t), \nabla x_0(t))$ is minorated by a summable function (see (2)),

$$\lim_{\varepsilon \to 0} \int_{\Omega_\varepsilon} L(t, x_0(t), \nabla x_0(t)) \, dt = \int_{\Omega} L(t, x_0(t), \nabla x_0(t)) \, dt;$$

on the other hand, using corollary 8 and the Dunford-Pettis theorem, we deduce that

$$\lim_{\varepsilon \to 0} \liminf_{n} \int_{\Omega_n \setminus \Omega_\varepsilon} \{ - g(t, 0) - \alpha|y_n(t)| \} \, dt = 0.$$

So when $\varepsilon \to 0$ we obtain

$$\beta = F(\Omega_0, x_0). \quad \square$$

6. Some particular cases.

Let's now briefly consider some possible forms for $l$, which are of particular interest.

Let $\Omega \in \mathcal{K}(T)$ and let

$$\chi_\Omega(t) = \begin{cases} 1, & t \in \Omega \\ 0, & t \notin \Omega \end{cases}$$

be its characteristic function.

Let moreover $\pi_\Omega$ be the vector valued measure defined on Borel sets in $\mathbb{R}^n$ as the distributional derivative of $\chi_\Omega$.

It is well known that the perimeter of $\Omega$ may be defined as

$$p(\Omega) = |\pi_\Omega|$$

where $|\pi_\Omega|$ denotes the total variation of $\pi_\Omega$ in $\mathbb{R}^n$, [6-7-9].

Using the results of [6-7] and taking into account theorem 7 we may also state the following
PROPOSITION 10. Let $\Omega_n \in K(T)$, $\Omega_n \rightarrow \Omega$, then $\liminf \limits_n p(\Omega_n) > p(\Omega)$; moreover if $p(\Omega_n) < k$, for some $k \in \mathbb{R}_{+}$, then for every function $f \in C_{0}^{\infty}(\mathbb{R}^{n})$ we have

$$\lim \int_{\mathbb{R}^{n}} f \, d\pi_{\Omega_n} = \int_{\mathbb{R}^{n}} f \, d\pi_{\Omega}.$$ 

Therefore we may assert that if we define

$$l_{1}(\Omega) = p(\Omega), \quad l_{2}(\Omega) = \begin{cases} 0, & p(\Omega) < k \\ +\infty, & p(\Omega) > k \end{cases}, \quad l_{3}(\Omega) = \begin{cases} \int_{\mathbb{R}^{n}} f \, d\pi_{\Omega}, & p(\Omega) < k \\ +\infty, & p(\Omega) > k \end{cases},$$

where $k \in \mathbb{R}_{+}$ and $f \in C_{0}^{\infty}(\mathbb{R}^{n})$, then $l_{i}$, $i = 1, 2, 3$, is lower semicontinuous in $K(T)$ and satisfies condition (1). This fact allows us to apply theorem 9 with such functions.

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