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PATHWISE DIFFERENTIABILITY WITH RESPECT TO A PARAMETER  
OF SOLUTIONS OF STOCHASTIC DIFFERENTIAL EQUATIONS

by

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Abstract

We consider a stochastic differential equation

$$X^u(t) = V^u(t) + \int_0^t \sigma(u, s, X_{s^-}^u) dS_s + \int_0^t f(u, s, X_{s^-}^u, x) q(ds, dx)$$

where  $S$  is a semimartingale and  $q$  a random measure and where the "coefficients" depend on a parameter  $u$ . We prove under suitable differentiability-conditions that the solution  $X^u(t, \omega)$  can be chosen for each  $u$  in such a way that the mapping  $u \sim X^u(t, \omega)$  is continuously differentiable for every  $(t, \omega)$ .

I - INTRODUCTION

The goal of this paper is to prove that under sufficient differentiability conditions on the coefficients, stochastic differential equations of the type

$$(1.1) \quad X^u(t) = V^u(t) + \int_0^t \sigma(u, s, X_{s^-}^u) dS_s + \int_0^t f(u, s, X_{s^-}^u, x) q(ds, dx)$$

where  $S$  is a semimartingale,  $q$  a random measure with zero dual predictable projection and  $u$  a parameter taking its values in a bounded open subset  $G$  of  $\mathbb{R}^d$ , admit for each  $u$  a solution which can be determined in such a way that P.a.s. the functions  $u \sim X^u(t, \omega)$  are for every  $t$  continuously differentiable.

This is a concept of differentiability different from the one considered by Gikhmann (see [3] and [4]), who studied the differentiability of the mapping  $u \sim X_t^u(\cdot)$  as a mapping from  $G$  into  $L^p(\Omega)$  for some  $p$  and in the

framework of Ito-equations. Recently Bichteler took the same point of view and considered equations of the type (1.1) with  $q = u$  and  $S$  and  $X^u$  possibly infinite dimensional. J. Jacod in [6] considered differentiability "in probability".

Pathwise differentiability was considered by P. Malliavin and M. Bismut for the solutions of Ito-Stratonovitch equation as functions of the initial conditions (see [2] and [8]). In [7] H. Kunita proved pathwise differentiability with respect to the initial conditions for the solutions of an equation driven by a continuous martingale. In [11] P.A. Meyer proved the same result for equations driven by a semimartingale (equations of Doleans-Dade-Protter type).

We consider here equations of type (1.1) and of a more general type with coefficients depending on a parameter  $u$ .

In section II we recall a few facts on the type of equations which are studied here. In section III we give sufficient conditions for the continuity of solutions with respect to  $u$  and in section IV we deal with differentiability.

## II - THE EQUATION UNDER CONSIDERATION

### 2.1. - Inequalities for stochastic integrals

We assume that the random measure  $q$  in (1.1) is of the form  $\mu(\omega; ds; du) - \nu(\omega; ds; du)$  where  $\mu(\omega; ]0, t], du)$  is for each  $\omega$  and  $t$  a borelian measure in an open subset  $\mathbb{E}$  of  $\mathbb{R}^m - \{0\}$  such that for some  $\alpha > 0$

$$\int \frac{|x|^\alpha}{1+|x|^\alpha} |\mu|(\omega; ]0, t], du) < \infty \quad (|\mu| \text{ denotes the variation of } \mu \text{ and } \alpha \text{ does not depend on } \omega \text{ and } t)$$

and where  $\nu$  is the dual predictable projection of  $\mu$ ).

$\mathbb{H}$  denotes a separable Hilbert space. We have shown in [9] (see also J. Jacod [5]) the existence of an increasing positive adapted process  $b$  and of a process  $\{q(\omega, s, \cdot) : (\omega, s) \in \Omega \times \mathbb{R}^+\}$  the values of which are measures on  $\mathbb{E} \times \mathbb{E}$  such that :

- i) For each  $\mathbb{H}$ -valued function  $h$  on  $\mathbb{E}$  such that  $\langle h(x), h(y) \rangle_{\mathbb{H}}$  is  $q(\omega, s, dx \otimes dy)$  integrable, the integral  $\int \langle h(x), h(y) \rangle_{\mathbb{H}} q(\omega, s, dx \otimes dy)$  defines a positive optional process ;

ii) If  $Y$  is an  $\mathbb{H}$ -valued  $\mathcal{P} \otimes \mathcal{B}_{\mathbb{E}}$  measurable<sup>(\*)</sup> function on  $\mathbb{R}^+ \times \Omega \times \mathbb{E}$  and if we denote by  $\lambda_s(Y)$  the  $\mathbb{H}$ -valued positive random variable

$$\lambda_s(Y) := \left\langle Y(s, \cdot, x), Y(s, \cdot, y) \right\rangle_{\mathbb{H}} q(\cdot, s, dx \otimes dy)$$

(set to be equal to  $+\infty$  when the integral does not exist) and  
 iii) the following inequality holds for every stopping time  $\tau$

$$(2.1) \quad E \left( \sup_{t < \tau} \left\| \int_{]0, t] \times \mathbb{E}} Y(s, \cdot, x) q(\cdot, ds, dx) \right\|^2 \right) \leq 4 E \left( \int_{]0, \tau[} \lambda_s(Y) db_s \right)$$

where  $\left( \int_{]0, t] \times \mathbb{E}} Y(s, \cdot, x) q(\cdot, ds, dx) \right)_{t \geq 0}$  is the stochastic integral process of  $Y$  with respect to  $q$  which is defined as soon as the process  $\left( \int_{]0, t] \lambda_s(Y) db(s) \right)_{t \geq 0}$  is finite.

If  $S$  is a  $\mathbb{K}$ -valued ( $\mathbb{K}$  : separable Hilbert space) right continuous semimartingale we know that there exist two positive increasing adapted processes  $a$  and  $\tilde{a}$  such that for every  $\mathcal{L}(\mathbb{K}; \mathbb{H})$ -valued locally bounded predictable process  $\{f(s, \omega); (s, \omega) \in \mathbb{R}^+ \times \Omega\}$  and every stopping time  $\tau$  :

$$(2.2) \quad E \left( \sup_{t < \tau} \left\| \int f(s, \cdot) dS_s \right\|^2 \right) \leq E \left( \tilde{a}_{\tau-} \cdot \int_{]0, \tau[} \|f(s)\|^2 da(s) \right)$$

To simplify the writing we shall call  $Z_t$  the process  $Z_t := (S_t, q(\cdot, ]0, t], dx)$  which takes its values in  $(\mathcal{L}(\mathbb{K}; \mathbb{H}) \times \mathcal{M}^{\alpha})$  where  $\mathcal{M}^{\alpha}$  is the space of borelian measures  $\nu$  on  $\mathbb{E}$  such that

$$\int_{\mathbb{E}} \frac{|x|^{\alpha}}{1+|x|^{\alpha}} |\nu| (du) < \infty .$$

Setting  $A_t := b(t) + a(t) \quad \tilde{A}_t := 8 + 2\tilde{a}_t \quad \phi := (f, Y)$

$$(2.3) \quad \int_{]0, t] \phi(s) dZ_s := \int_{]0, t] f(s, \cdot) dS_s + \int_{]0, t] \times \mathbb{E}} Y(s, \cdot, x) q(\cdot, ds, dx)$$

and

$$(2.4) \quad \lambda_s(\phi) := \|f(s, \cdot)\|^2 + \lambda_s(Y)$$

the following inequality holds for every stopping time

$$(2.5) \quad E \left( \sup_{t < \tau} \left\| \int_{]0, t] \phi(s) dZ_s \right\|^2 \right) \leq E \left( \tilde{A}_{\tau-} \cdot \int_{]0, \tau[} \lambda_s(\phi) dA_s \right)$$

(\*)  $\mathcal{P}$  is the  $\sigma$ -algebra of predictable subsets of  $\mathbb{R}^+ \times \Omega$  and  $\mathcal{B}_{\mathbb{E}}$  of Borel subsets of  $\mathbb{E}$ .

Extending a classical argument on martingales (see [13]) it is also easy to see that for every  $p \geq 2$  exists an increasing positive adapted process  $(\tilde{A}_t^p)_{t \geq 0}$  such that for every stopping  $\tau$

$$(2.6) \quad E \left( \sup_{t < \tau} \left\| \int_{]0, t]} \phi(s) dz_s \right\|^p \right) \leq E \left( \tilde{A}_\tau^p \cdot \int_{]0, \tau]} \left( \lambda_s(\phi) \right)^{p/2} dA_s \right)$$

## 2.2. - Hypothesis on equation (1.1)

The space of parameters  $u$  is an open bounded subset  $G$  of  $\mathbb{R}^d$ .

In equation (1.1)  $\sigma$  is a mapping from  $(G \times \mathbb{R}^+ \times \Omega \times \mathbb{H})$  into  $\mathcal{L}(\mathbb{K}; \mathbb{H})$  which is continuous on  $\mathbb{H}$  and such that for every  $h \in \mathbb{H}$  and  $u \in G$  the process  $\{\sigma(u, s, \omega, h) : (s, \omega) \in \mathbb{R}^+ \times \Omega\}$  is predictable.  $f$  is a mapping of  $(G \times \mathbb{R}^+ \times \Omega \times \mathbb{H}, \mathbb{E})$  into  $\mathbb{H}$  which is continuous on  $\mathbb{H}$  and such that for every  $u \in G$ ,  $h \in \mathbb{H}$  the mapping  $(s, \omega, x) \sim f(u, s, \omega, h, x)$  is  $\mathcal{P} \otimes \mathcal{H}_{\mathbb{E}}$  measurable

In the sequel we shall call  $g$  the couple  $(\sigma, f)$  and according to the notations of (2.1) the equation (1.1) will be written in the *abbreviated form* :

$$(2.7) \quad X^u(t) = V^u(t) + \int_0^t g(u, s, X_s^u) dz_s$$

Here  $V^u$  is for each  $u \in G$  a given  $\mathbb{H}$ -valued adapted cad-lag process.

## III - CONTINUITY OF THE SOLUTIONS WITH RESPECT TO $u$ .

### 3.1. - Hypothesis

$L$  is an increasing positive adapted process and  $p$  is a positive real number with  $p \geq d + \varepsilon$  for some  $\varepsilon > 0$ .

If  $\xi$  is a cad-lag  $\mathbb{H}$ -valued adapted process we write  $g(u, \xi)$  for the process  $(t, \omega) \sim g(u, s, \omega, \xi_{s-}(\omega))$  and  $\lambda_s \circ g(u, \xi)$  for the positive functional of this process defined by formula (2.4).

With these notations we formulate the following hypotheses :

$$(H_1) \quad \sup_{s \leq t} \|V_s^u - V_s^v\| \leq L_t \|u - v\| \quad \text{for all } t, u \text{ and } v \in G$$

and

$$\sup_{u \in G} \sup_{s < t} \|V_t^u\| < \infty$$

(H<sub>2</sub>) (Lipschitz hypotheses) :

$$\forall t \in \mathbb{R}^+ \quad \int_{]0,t]} [\lambda_s \circ (g(u, \xi) - g(u, \xi'))]^{p/2} dA_s \leq \int_{]0,t]} \sup_{r \leq s} \|\xi_r - \xi'_r\|^p dL_s$$

for every couple  $(\xi, \xi')$  of  $\mathbb{H}$ -valued adapted cad-lag processes, P.a.s.

$$(H_3) \quad \int_{]0,t]} [\lambda_s \circ g(u, \xi)]^{p/2} dA_s \leq \int_{]0,t]} (1 + \sup_{r \leq s} \|\xi_s\|^p) dL_s$$

for every  $u \in G$  every  $\mathbb{H}$ -valued adapted cal-lag  $\xi$ , P.a.s.

(Note that  $(H_3)$  is implied by  $(H_2)$  in most classical cases).

(H<sub>4</sub>)  $\Psi$  being a given positive increasing (possibly constant) function on  $\mathbb{R}^+$ , for every stopping time  $\tau$  the following inequality holds for every  $\mathbb{H}$ -valued cad-lag adapted  $\xi$  every  $u$  and  $v$  in  $G$  :

$$E \left( \sup_{t < \tau} [\lambda_t \circ [g(u, \xi) - g(v, \xi)]]^{p/2} \right) \leq \|u - v\|^{d + \epsilon_\Psi} \left( E \left( \sup_{t < \tau} \|\xi_t\|^p \right) \right)$$

### 3.2. - Theorem

1°) Under the above hypotheses  $(H_1)$  to  $(H_4)$ , the equation (2.7) has for each  $u$  a unique strong solution  $X^u$  on  $\mathbb{R}^+$  and the random function  $(t, \omega, u) \rightsquigarrow X_t^u(\omega)$  can be determined in such a way that  $u \rightsquigarrow X_t^u(\omega)$  is continuous on  $G$  for every  $t$  and  $\omega$  while the mapping  $t \rightsquigarrow X_t^{(\cdot)}(\omega)$  is for each  $\omega$  cad-lag from  $\mathbb{R}^+$  into the set  $C_b^{\mathbb{H}}(G)$  of bounded continuous  $\mathbb{H}$ -valued functions on  $G$  endowed with the uniform topology.

2°) There exists an increasing sequence  $(\sigma_n)$  of stopping times and constants  $K(\Psi, n, p, Z)$  such that

$$a) \quad \lim_n P\{\sigma_n < T\} = 0 \quad \text{for every } T > 0$$

$$b) \quad E \left( \sup_{t < \sigma_n} \|X^u(t) - X^v(t)\|^p \right) \leq K(\Psi, n, p, Z) \|u - v\|^p$$

Proof.

The stopping times  $\sigma_n$  are defined as follows :

$$\sigma_n := \inf \{ t : \tilde{A}_t^p \vee L_t \vee \sup_{\substack{u \in G \\ s \leq t}} \|V_t^u\|^p \vee A_t > n \}$$

Next we have the following lemmas

3.3. - Lemma 1

$$E \left( \sup_{t < \sigma_n} \|X_t^u\|^p \right) \leq 2^p (n+n^2) \sum_{j=0}^{2^p n^2} (2^p n^2)^j$$

Proof of Lemma 1

We remark that  $A_{\sigma_n}^p \leq n, L_{\sigma_n} \leq n, \sup_{t < \sigma_n} \sup_u \|V_t^u\|^p \leq n$

We then apply inequality (2.6) to the second member of (2.7) and get

$$E \left( \sup_{t < \sigma_n} \|X_t^u\|^p \right) \leq 2^{(P-1)} n + 2^{(P-1)} E \left( \tilde{A}_{\sigma_n}^p \int_{]0, \sigma_n[} [\lambda_s \circ g(u, X_s^u)]^{P/2} dA_s \right)$$

and property  $(H_3)$  gives for every stopping time  $\tau \leq \sigma_n$

$$E \left( \sup_{t < \sigma_n} \|X_t^u\|^p \right) \leq 2^{(P-1)} (n+n^2) + 2^{(P-1)} n E \left( \int_{]0, \tau[} (\sup_{s \leq t} \|X_s^u\|^p) dL_s \right)$$

Applying the "Gronwall stochastic lemma" as in [10] section 7.1 we get the inequality of the lemma.

3.4. - Lemma 2

There exist constants  $K(\Psi, n, p, A, \tilde{A}^p)$  such that

$$\forall u, v \quad E \left( \sup_{t < \sigma_n} \|X_t^u - X_t^v\|^p \right) \leq K(\Psi, n, p, A, \tilde{A}^p) \|u-v\|^p$$

Proof of Lemma 2

Applying again inequality (2.6) to the stochastic integrals

$$\int_{]0,t]} (g_s(u, X_s^u) - g_s(v, X_s^u)) dZ_s \quad \text{and}$$

$$\int_{]0,t]} [g_s(v, X_s^u) - g_s(v, X_s^v)] dZ_s$$

and using properties  $(H_1)$ ,  $(H_2)$  and  $(H_4)$  we can write for every stopping time  $\tau \leq \sigma_n$  :

$$\begin{aligned} E\left(\sup_{s < \tau} \|X^u(s) - X^v(s)\|^p\right) &\leq 3^{p-1} n^p \|u-v\|^p + 3^{(p-1)} n \Psi\left(E\left(\sup_{s < \tau} \|X_s^u\|^p\right)\right) \\ &\quad + 3^{(p-1)} n E\left(\int_{]0,\tau[} (\sup_{t < s} \|X^u(s) - X^v(s)\|^p) dL_s\right) \end{aligned}$$

Applying as above the same "Gronwall-inequality" we obtain the lemma.

Theorem 3.2 is now a direct consequence of the following lemma which is a straightforward extension of a lemma as stated by Neveu in [12] (see also P. Priouret [13] chap. 3. Lemme 13 :

3.5 - Lemma 3

Let  $\{Y(t, \omega, u) : t \in \mathbb{R}^+, \omega \in \Omega, u \in G\}$  an  $\mathbb{H}$ -valued random function such that for every  $u : t \sim Y(t, \omega, u)$  is a.s. cad-lag and such that for every  $t$  :

$$E\left(\sup_{s < t} \|Y_{s,u} - Y_{s,v}\|^p\right) \leq a_{t,p} \|u-v\|^{d+\varepsilon}$$

Then there exists a mapping  $Y^* : (t, \omega, u) \sim Y^*(t, \omega, u) \in \mathbb{H}$  such that

- a)  $u \sim Y^*(t, \omega, u)$  is continuous
- b)  $\forall u \in G, Y(t, u, \cdot) = Y^*(t, u, \cdot)$  for all  $t$  a.s.
- b)  $t \sim Y^*(t, \cdot, \omega)$  is for  $P$ -almost all  $\omega$  a cad-lag mapping from  $\mathbb{R}^+$  into  $C_b^{\mathbb{H}}(G)$  endowed with the uniform topology.

Proof.

We omit the proof which is pretty similar to the one given in [13].

This finishes the proof of theorem 3.2.  $\blacksquare$

IV - PATHWISE DIFFERENTIABILITY4.1. - Hypothesis

We consider the same equation (1.1) or in abbreviated notation : (2.7).

For a couple  $g := (\sigma, f)$  of "coefficients" as in (1.1) we write to simplify :

$$\|g(u, s, \omega, h, \cdot)\|_{\Lambda} := \left[ \|\sigma(u, s, \omega, h)\|_{L^2(\mathbb{K}; \mathbb{H})}^2 + \int_{\mathbb{E} \times \mathbb{E}} \langle f(u, s, \omega, h, x), f(u, s, \omega, h, y) \rangle_{\mathbb{H}} \right. \\ \left. \mathbb{Q}(\omega, s, dx \otimes dy) \right]^{\frac{1}{2}}$$

$$\text{We set } v_t^* := \sup_{u \in G} \sup_{s < t} \|D_u V_s^u\| + \|V_s^u\| + \|D_{u^2}^2 V_s^u\|$$

where  $D_u \phi$  denotes the *first order* derivative with respect to  $u$  of a function  $\phi$  on  $u$ .  
and  $D_{u^2}^2 \phi$  the *second order derivative*

In the hypotheses below  $C$  is a constant and  $(K_t)_{t \geq 0}$  is an increasing positive process.

[D<sub>1</sub>] For all  $t$  and  $\omega$  the derivatives  $D_u V^u(t, \omega)$  and  $D_{u^2}^2 V^u(t, \omega)$  exist and  $v_t^* < \infty$

[D<sub>2</sub>] The derivatives  $D_u g(s, u, x)$ ,  $D_{u^2}^2 g(s, u, x)$ ,  $D_{u, x} g(s, u, x)$  and  $D_x g(s, u, x)$  exist and

$$\sup_{u, s, x} (\|D_u g(s, u, x)\|_{\Lambda} + \|D_{u^2}^2 g(s, u, x)\|_{\Lambda} + \|D_{u, x} g(s, u, x)\|_{\Lambda} + \|D_x g(s, u, x)\|_{\Lambda}) \leq C$$

[D<sub>3</sub>] For all  $x, y, u$  and  $v$  :

$$\|D_x g(s, u, x) - D_x g(s, v, y)\|_{\Lambda} \leq C(\|y-x\| + \|u-v\|)$$

4.2. - Theorem

Under the above hypothesis [D<sub>1</sub>] to [D<sub>3</sub>] equation (2.7) has a unique (up to indistinguishability) solution  $X^u$  on  $\mathbb{R}^+$  and there exists a version  $(\omega, t, u) \leadsto X_t^u(\omega)$  of this random function such that for  $P$ -almost all  $\omega$  :

a)  $u \leadsto X_t^u(\omega)$  is continuously differentiable for every  $t$

b)  $t \leadsto X_t^{(\cdot)}(\omega)$  and  $t \leadsto D_u X_t^{(\cdot)}(\omega)$  are cad-lag for the uniform norm on  $C_b(G; \mathbb{H})$  and  $C_b(G; L(G; \mathbb{H}))$  respectively.

c) For every  $u$  the stochastic process  $(D_u X_t^u)_{t \geq 0}$  is a strong solution of the following stochastic equation (where  $X^u$  is the process solution of 2.7 as in theorem 3.2) :

$$(4.1) \quad Y^u(t) = D_u V_t^u + \int_{]0, t[} \left( D_u g(s, u, X_{s-}^u) + D_x g(s, u, X_{s-}^u) \circ Y_s^u \right) dZ_s$$

Proof.

The proof is in several steps corresponding to lemmas 4 and 5 and section 4.5 below :

#### 4.3. - Lemma 4

Under hypothesis  $[D_1]$ ,  $[D_2]$ ,  $[D_3]$ , equations (2.7) and (4.1) satisfy the conditions  $[H_1]$  to  $[H_4]$  of section 3.1 for every  $p \geq 2$  on any interval  $]0, \sigma_n]$  as defined in theorem 1.

Proof.

Let us first consider equation (2.7).  $(H_1)$  is trivially implied by  $[D_1]$ .  $[D_2]$  implies also the Lipschitz property  $(H_2)$  and conditions  $(H_3)$  and  $(H_4)$  which is here expressed in the much stronger form  $\|g(s, u, x) - g(s, v, x)\|_{\Lambda} \leq C \|u - v\|$ .

We turn now to equation (4.1). The only condition  $(H_1)$  which is not immediately implied by the hypothesis of the lemma is condition  $(H_4)$ . We write

$$\begin{aligned} & \|D_u g(s, v, X_{t-}^V) - D_u g(s, u, X_{t-}^U) + D_x g(s, v, X_{t-}^V) \circ \xi_t - D_x g(s, u, X_{t-}^U) \circ \xi_t\|_{\Lambda}^p \\ & \leq 4^{p-1} \{ \|D_u g(s, v, X_{t-}^V) - D_u g(s, u, X_{t-}^V)\|_{\Lambda}^p \} + \\ & \quad + 4^{p-1} \{ \|D_u g(s, u, X_{t-}^V) - D_u g(s, u, X_{t-}^U)\|_{\Lambda}^p \} \\ & \quad + 4^{p-1} \{ \| [D_x g(s, v, X_{t-}^V) - D_x g(s, u, X_{t-}^V)] \circ \xi_t \|_{\Lambda}^p \} \\ & \quad + 4^{p-1} \{ \| [D_x g(s, u, X_{t-}^V) - D_x g(s, u, X_{t-}^U)] \circ \xi_t \|_{\Lambda}^p \} \\ & \leq 4^{p-1} C^p (\|u - v\|^p + \|X_{t-}^V - X_{t-}^U\|^p) + \\ & \quad + 4^{p-1} C^p \|u - v\|^p \|\xi_t\|^p + 4^{p-1} C^p \|X_{t-}^V - X_{t-}^U\|^p \|\xi_t\|^p \end{aligned}$$

One knows from proposition 2 that there exists an increasing sequence  $(\sigma_n)$  of stopping times and constants  $C_n$  such that

$$E \sup_{t < \sigma_n} \|Y^U(s) - Y^V(s)\|^{2p} \leq C_n \|u - v\|^{2p}$$

If we write for every stopping time  $\tau$

$$E \left( \sup_{t < \tau \wedge \sigma_n} \| (X_t^V - X_t^U) \circ \xi_t \|_{\Lambda}^p \right) <$$

$$\left[ E \left( \sup_{t < \tau_{\Lambda \sigma_n}} \| X_t^v - X_t^u \|^2 \right)^p \right]^{\frac{1}{2}} \left[ E \left( \sup_{t < \tau_{\Lambda \sigma_n}} \| \xi_t \|^{\frac{2p}{2p-1}} \right)^{\frac{2p-1}{2}} \right]$$

$$\leq C_n^{\frac{1}{2}} \|u-v\|^p E \left( \sup_{t < \tau_{\Lambda \sigma_n}} \| \xi_t \|^{\alpha} \right)^{p/\alpha}$$

with  $\alpha = \frac{2p}{2p-1}$

Therefore

$$E \left( \sup_{t < \tau_{\Lambda \sigma_n}} \| g(s, u, \xi_{s-}) - g(s, v, \xi_{s-}) \|_{\Lambda}^p \right) \leq 4^{p-1} C^p \|u-v\|^p [1 + C_n + E \left( \sup_{t < \tau_{\Lambda \sigma_n}} \| \xi_t \|^p \right)]$$

$$+ C_n^{\frac{1}{2}} [E \left( \sup_{t < \tau_{\Lambda \sigma_n}} \| \xi_t \|^{\alpha} \right)]^{p/\alpha}$$

If we remark that  $E \left( \sup_{t < \tau_{\Lambda \sigma_n}} \| \xi_t \|^p \right) \geq [E \left( \sup_{t < \tau_{\Lambda \sigma_n}} \| \xi_t \|^{\alpha} \right)]^{p/\alpha}$

we see that property (H<sub>4</sub>) holds with

$$\Psi(\rho) = 1 + C_n + (1 + C_n^{\frac{1}{2}})\rho$$

4.4. - Lemma 2

If we define

$$\phi_t(e, u, \lambda) = \frac{1}{\lambda} [X_t^{u+\lambda e} - X_t^u - \lambda Y_t^u \circ e]$$

there exists an increasing sequence  $(\tau_n)$  of stopping times such that  $\lim_n P\{\tau_n < T\} = 0$  and a sequence  $C_n$  of constants such that

$$E \left\{ \sup_{t < \tau_n} \| \phi_t(e, \cdot, \lambda) \|_{L^2(G)}^2 \right\} \leq C_n \lambda^2$$

Proof.

For each  $u$  the process  $(\phi_t(e, u, \lambda))_{t \leq T}$  is solution of

$$(4.2) \quad \phi_t(e, u, \lambda) = \frac{1}{\lambda} (V_t^{u+\lambda e} - V_t^u - \lambda D_e V_t^u) +$$

$$+ \int_{]0, t]} \frac{1}{\lambda} \left[ g(s, u+\lambda e, X_{s-}^{u+\lambda e}) - g(s, u, X_{s-}^u) - \right.$$

$$\left. \lambda D_e g(s, u, X_{s-}^u) - \lambda D_x g(s, u, X_{s-}^u) \circ Y_{s-}^u \circ e \right] ds_s$$

We may write for  $x, y \in \mathbb{H}$  and  $\eta \in \mathcal{L}(\mathbb{H}; \mathbb{H})$

$$\begin{aligned}
 (4.3) \quad & g(s, u + \lambda e, y) - g(s, u, x) - \lambda D_e g(s, u, x) - \lambda D_x g(s, u, x) \circ \eta \circ e = \\
 & \lambda D_e g(s, u, y) + D_x g(s, u, x) \circ (y - x) - \lambda D_e g(s, u, x) - \lambda D_x g(s, u, x) \circ \eta \circ e + \\
 & \quad + h(s, u, x, y, \eta, \lambda, e) \\
 & = D_x g(s, u, x) \circ (y - x - \lambda \eta \circ e) + \tilde{h}(s, u, x, y, \eta, \lambda)
 \end{aligned}$$

with

$$(4.4) \quad \|\tilde{h}(s, u, x, y, \eta, \lambda)\|_{\mathbb{H}} \leq |\lambda| K (\|y - x\| + |\lambda|)$$

for some constant  $K$

The equation (4.2) can therefore be written

$$(4.5) \quad \Phi_t(u, \lambda, e) = H_t(u, \lambda, e) + \int_{]0, t]} D_x g(s, u, X_{s-}^u) \circ \Phi_{s-}(e, u, \lambda) dZ_s$$

where the process  $H(u, \lambda, e)$  satisfies

$$(4.6) \quad \|H_t(u, \lambda, e)\|_{\mathbb{H}} \leq |\lambda| v_t^k + \left\| \int_{]0, t]} \frac{1}{\lambda} h(s, u, X_{s-}^{u+\lambda e}, X_{s-}^u, Y_{s-}^u \circ e) dZ_s \right\|$$

Using (4.5) we obtain from (4.6) for every stopping time  $\sigma$  :

$$E\left(\sup_{t < \sigma} \|H_t(u, \lambda, e)\|^2\right) \leq 2 \lambda^2 v_{\sigma-}^* + E\left(\tilde{A}_{\tau-} \cdot \int_{]0, \tau]} [\lambda^2 + c^2 \|X_{s-}^{u+\lambda e} - X_{s-}^u\|^2] dA_s\right)$$

Using then theorem we see that there exists a sequence  $(\sigma_n)$  of stopping times and a sequence of constants  $(K_n)$  such that

$$(4.7) \quad \sup_{s < \sigma_n} (\tilde{A}_s \vee A_s) \leq n \quad \text{and}$$

$$(4.8) \quad E\left(\sup_{t < \sigma_n} \|H_t(u, \lambda, e)\|^2\right) \leq K_n \lambda^2 \quad (\text{use a standard stopping procedure for processes } v^*, \tilde{A} \text{ and } A).$$

This implies

$$(4.9) \quad E \left( \sup_{t < \sigma_n} \int_G \|H_t(u, \lambda, e)\|^2 du \right) \leq \int_G K_n \lambda^2 du \leq \tilde{K}_n \lambda^2$$

We next consider the  $L^2(G)$ -valued process  $(\phi_t(e, \lambda))_{t \leq \tau}$

As  $D_{X^g}$  is bounded by some constant  $C$ , inequality (4.6) shows that the  $L^2(G)$ -valued process  $\phi_t$  satisfies an inequality of the following type for every stopping time  $\tau \leq \sigma_n$

$$\begin{aligned} E \left\{ \sup_{t < \tau} \|\phi_t(e, \lambda)\|_{L^2(G)} \right\} &\leq 2 \tilde{K}_n \lambda^2 + 2 E \left( \tilde{A}_{\tau-} \int_{[0, \tau[} \sup_{s < t} C^2 \|\phi_s(e, \lambda)\|_{L^2(G)}^2 dA_s \right) \\ &\leq 2 \tilde{K}_n \lambda^2 + 2n C^2 \int_{[0, \tau[} \sup_{s < t} \|\phi_s(e, \lambda)\|_{L^2(G)} dA_s \end{aligned}$$

The already used "Gronwall inequality" of [10] shows immediately the existence of a constant  $C_n$  as in the lemma.

#### 4.5. - End of the proof of the theorem

We make use of the following easily proved property : let  $f \in L^2_{\mathbb{H}}(\bar{G})$ , let  $f \in L^2(G; \mathbb{H}) \cap C(G; \mathbb{H})$  and  $\bar{f} \in L^2(G; \mathcal{L}(\mathbb{H}; \mathbb{H}) \cap C(G; \mathcal{L}(\mathbb{H}; \mathbb{H}))$  such that for all  $e \in \mathbb{R}^d$ , all  $u \in \mathbb{R}^d$  and some decreasing sequence  $\lambda_k \downarrow 0$  :

$$\lim_{k \rightarrow \infty} \|f(u + \lambda_k e) - f(u) - \lambda_k \bar{f}(u) \circ e\|_{L^2(G; \mathbb{H})} = 0$$

then  $\bar{f}$  is the derivative of  $f$  in the sense of distributions and therefore in the ordinary sense in every point  $u \in G$ . Let us consider for each  $\omega$  and  $n$  a  $P$ -negligeable set  $\Omega_n$  and a sequence  $\lambda_k$  such that  $\lambda_k \downarrow 0$  and

$$\lim_{k \rightarrow \infty} \sup_{t < \tau_n(\omega)} \|\phi_t(e, \lambda_k)\|_{L^2(G)} = 0 \text{ for every } \omega \notin \Omega_n$$

The above property shows that for every  $\omega \notin \Omega_n$  and  $t < \tau_n(\omega)$   $Y_t^u(\omega)$  is the derivative of  $u \sim X_t^u(\omega)$  at point  $u$ . Therefore  $Y_t^u(\omega)$  is the derivative of  $u \sim X_t^u(\omega)$  for all  $t < \tau_n(\omega)$  and  $\omega \notin (\cup_n \Omega_n)$ .

This proves the theorem. ■

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