

Smooth approximation of bi-Lipschitz orientation-preserving homeomorphisms

Sara Daneri ^a, Aldo Pratelli ^{b,*}

^a Institut für Mathematik, Universität Zürich, Winterthurerstrasse 190, 8057 Zürich, Switzerland

^b Department Mathematik, University of Erlangen, Cauerstraße 11, 91058 Erlangen, Germany

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Abstract

We show that a planar bi-Lipschitz orientation-preserving homeomorphism can be approximated in the $W^{1,p}$ norm, together with its inverse, with an orientation-preserving homeomorphism which is piecewise affine or smooth.

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1. Introduction

In this paper we deal with approximations of bi-Lipschitz orientation-preserving homeomorphisms $u : \Omega \subseteq \mathbb{R}^2 \rightarrow \Delta \subseteq \mathbb{R}^2$, where Ω and $\Delta = u(\Omega)$ are two open bounded subsets of \mathbb{R}^2 . In particular, we show that both u and its inverse can be approximated in the $W^{1,p}$ norm ($p \in [1, +\infty)$) by piecewise affine or smooth orientation-preserving homeomorphisms. Our main theorem is the following.

Theorem 1.1. *Let $\Omega \subseteq \mathbb{R}^2$ be any bounded open set, and let $u : \Omega \rightarrow \Delta$ be a bi-Lipschitz orientation-preserving homeomorphism. Then, for any $\bar{\varepsilon} > 0$ and any $1 \leq p < \infty$, there exists a bi-Lipschitz orientation-preserving homeomorphism $v : \Omega \rightarrow \Delta$ such that $u = v$ on $\partial\Omega$,*

$$\|u - v\|_{L^\infty(\Omega)} + \|u^{-1} - v^{-1}\|_{L^\infty(\Delta)} + \|Du - Dv\|_{L^p(\Omega)} + \|Du^{-1} - Dv^{-1}\|_{L^p(\Delta)} \leq \bar{\varepsilon}, \quad (1.1)$$

and v is either countably piecewise affine or smooth. More precisely, there exist two geometric constants C_1 and C_2 such that, if u is L bi-Lipschitz, then the countably piecewise affine approximation can be chosen to be $C_1 L^4$ bi-Lipschitz, while the smooth approximation can be chosen to be $C_2 L^{28/3}$ bi-Lipschitz.

Thanks to a result by Mora-Corral and the second author [29] (see Theorem 2.1 below), the problem of finding smooth approximations can be actually reduced to find countably piecewise affine ones—i.e. affine on the elements of a locally finite triangulation of Ω , see Definition 3.2.

* Corresponding author.

E-mail addresses: sara.daneri@math.uzh.ch (S. Daneri), pratelli@math.fau.de (A. Pratelli).

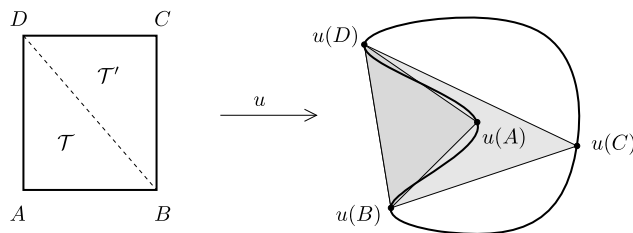


Fig. 1. The square $ABCD$ is divided in the triangles \mathcal{T} and \mathcal{T}' . The affine interpolation v of u on $ABCD$ is not injective, since $v(\mathcal{T}) \subseteq v(\mathcal{T}')$ ($v(\mathcal{T})$ and $v(\mathcal{T}')$ are shaded). Moreover, u is orientation-preserving in the square while v is orientation-reversing on \mathcal{T} .

The fact that v might not be (finitely) piecewise affine but countably piecewise affine is due to the fact that we require $u = v$ on $\partial\Omega$, so it is clearly impossible to find a (finitely) piecewise affine approximation v unless the domain is a polygon and u is piecewise affine on the boundary. In fact, we also prove the following result.

Theorem 1.2. *If under the assumptions of Theorem 1.1 one has also that Ω is polygonal and u is (finitely) piecewise affine on $\partial\Omega$, then there exists a (finitely) piecewise affine approximation $v : \Omega \rightarrow \Delta$ as in Theorem 1.1 which is $C_1C'(\Omega)L^4$ bi-Lipschitz.*

About the dependence of $C'(\Omega)$ in Theorem 1.2 on the domain Ω , see Remark 6.1.

The first naive idea coming to one’s mind in order to construct a piecewise affine approximation of u could be the following: first, to select an arbitrary locally affine triangulation of Ω with triangles of sufficiently small diameter; then, to define v as the function which, on every triangle, is the affine interpolation of the values of u on its vertices. Unfortunately, if on one hand the functions defined in this way provide an approximation of u in L^∞ , on the other hand they may fail to be homeomorphisms. The problem is due to the fact that, taking arbitrary nondegenerate triangles in Ω —no matter how small—then the affine interpolation of u on the vertices of the triangles can be orientation-preserving on some triangles and orientation-reversing on the others (see Fig. 1). This prevents the affine interpolation to be injective since a homeomorphism on a connected domain in \mathbb{R}^2 must be either orientation-preserving on every subdomain, or orientation-reversing on every subdomain. An explicit example of a function with such a bad behavior can be found in [34].

The general problem of finding suitable approximations of homeomorphisms $u : \mathbb{R}^d \supseteq \Omega \rightarrow u(\Omega) \subseteq \mathbb{R}^d$ with piecewise affine homeomorphisms has a long history. As far as we know, in the simplest non-trivial setting (i.e. $d = 2$, approximations in the L^∞ norm) the problem was solved by Radó [32]. Due to its fundamental importance in geometric topology, the problem of finding piecewise affine homeomorphic approximations in the L^∞ norm and dimensions $d > 2$ was deeply investigated in the 50s and 60s. In particular, it was solved by Moise [26] and Bing [7] in the case $d = 3$ (see also the survey book [27]), while for contractible spaces of dimension $d \geq 5$ the result follows from theorems of Connell [9], Bing [8], Kirby [23] and Kirby, Siebenmann and Wall [24] (for a proof see, e.g., Rushing [33] or Luukkainen [25]). Finally, twenty years later, while studying the class of quasi-conformal variates, Donaldson and Sullivan [13] proved that the result is false in dimension 4.

Once completely solved in the uniform sense, the approximation problem suddenly became of interest again in a completely different context, namely for variational models in nonlinear elasticity. In this setting (see the pioneering work by Ball [3]), one is led to study existence and regularity property of minimizers of energy functionals of the form

$$I(u) = \int_{\Omega} W(Du) \, dx, \tag{1.2}$$

where $u : \Omega \subseteq \mathbb{R}^n \rightarrow \Delta \subseteq \mathbb{R}^n$ ($n = 2, 3$) models the deformation of a homogeneous elastic material w.r.t. a reference configuration Ω and prescribed boundary values, while $W : \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$ is the stored-energy functional. In order for the model to be physically relevant, as pointed out by Ball in [4,5], one has to require that u is a homeomorphism—this corresponds to the non-impenetrability of the material—and that

$$W(A) \rightarrow +\infty \text{ as } \det A \rightarrow 0, \quad W(A) = +\infty \text{ if } \det A \leq 0. \tag{1.3}$$

The first condition in (1.3) prevents from too high compressions of the elastic body, while the latter guarantees that the orientation is preserved. In particular, if u is an admissible deformation with finite energy, then one has that

$$\det Du > 0 \quad \text{a.e. in } \Omega. \quad (1.4)$$

Another property of W that appears naturally in many problems of nonlinear elasticity is the *quasiconvexity* (see for instance [2]). Unfortunately, no general existence result is known under condition (1.3), not even if the quasiconvexity assumption is added: one has either to drop condition (1.3) and impose p -growth conditions on W (see [30,1]), or to require that W is *polyconvex* and that some coercivity conditions are satisfied (see [2,31]). Moreover, also in the cases in which the existence of $W^{1,p}$ -minimizers is known, very little is known about their regularity. As pointed out by Ball in [4,5] (who ascribes the question to Evans [14]), an important issue toward the understanding of the regularity of the minimizers in this setting (i.e., W quasiconvex and satisfying (1.3)) would be to show the existence of minimizing sequences given by piecewise affine homeomorphisms. In particular, a first step would be to prove that any homeomorphism $u \in W^{1,p}(\Omega; \mathbb{R}^n)$, $p \in [1, +\infty)$, can be approximated in $W^{1,p}$ by piecewise affine ones. And then, one should also be able to estimate from below the Jacobians of the approximating maps, both to control their energy and to eventually see whether the minimizers satisfy (1.4) uniformly, namely,

$$\det Du \geq \sigma > 0 \quad \text{a.e. in } \Omega.$$

It is now known that the property (1.4) is not necessarily satisfied by a $W^{1,p}$ homeomorphism (see [16] for an example of a $W^{1,p}$ homeomorphism satisfying $\det Du = 0$ on a set of positive measure). Therefore, a class that one could consider is that of *bi-Sobolev maps*, i.e. maps belonging to $W^{1,p}$ together with their inverses; it can be proved that for those maps the property (1.4) is satisfied as soon as $p \geq n$. In fact, it turns out that the bi-Sobolev maps are the natural class in which studying the problem, since Hencĭ and Koskela [17] proved that if $u \in W^{1,1}(\Omega; \mathbb{R}^2)$ is a planar homeomorphism satisfying (1.4), then $u^{-1} \in W^{1,1}(u(\Omega); \mathbb{R}^2)$; in other words, every map which is not bi-Sobolev, at least for $p = 1$, has infinite energy. Actually, the result by Hencĭ and Koskela is even stronger, since it states that for a $W^{1,1}$ map one has that $u^{-1} \in W^{1,1}$ if and only if u has finite distortion; the study of maps of finite distortion in connection with Sobolev homeomorphisms is very active in last years, see for instance [10,16,15,19,17,18,20,12].

Summarizing, the functional setting in which one can formulate the Ball–Evans problem is the following: given any p bi-Sobolev homeomorphism u with $p \geq 1$ (or $p \geq n$), and given $\bar{\varepsilon} > 0$, find a piecewise affine homeomorphism v such that

$$\|u - v\|_{W^{1,p}(\Omega)} + \|u^{-1} - v^{-1}\|_{W^{1,p}(u(\Omega))} \leq \bar{\varepsilon}.$$

The results available in the literature concern the first step of the problem, namely, the approximation of $W^{1,p}$ maps, and they provide, under increasingly weaker hypotheses on the derivatives of u , piecewise affine or smooth approximations of u and its derivatives. The first results were obtained by Mora-Corral [28] (for planar bi-Lipschitz mappings that are smooth outside a finite set) and by Bellido and Mora-Corral [6], in which they prove that if $u, u^{-1} \in C^{0,\alpha}$ for some $\alpha \in (0, 1]$, then one can find piecewise affine approximations v of u in $C^{0,\beta}$, where $\beta \in (0, \alpha)$ depends only on α .

Recently, Iwaniec, Kovalev and Onninen [22] almost completely solved the approximation problem of planar Sobolev homeomorphisms, proving that whenever u belongs to $W^{1,p}$ for some $1 < p < +\infty$, then it can be approximated by smooth diffeomorphisms v in the $W^{1,p}$ norm (improving the previous result for homeomorphisms in $W^{1,2}$ found in [21]).

However, in all the above-mentioned results one has no control on the inverses of u and v , thus it is not known whether v approximates u also in the sense of the elastic energy I defined in (1.2)—and in fact it is also possible that the map v has infinite elastic energy. As explained before, one has then to pass from the Sobolev to the bi-Sobolev approximation problem: in doing so, the additional difficulty is basically to keep under control the derivatives of the approximating functions (to avoid that they become too small). In particular, one has to prevent the angles and the sides of the triangulations defining v from becoming comparatively too big/small.

The present paper is the first one to take care also of the distance of the inverse maps, leading to a partial result towards the solution of the general problem (hence, we also give a partial positive answer to Question 4.2 of the paper by Iwaniec, Kovalev and Onninen [22]): in fact, we are able to deal with homeomorphisms which are bi-Sobolev for $p = +\infty$. The techniques adopted in [6] and [22] are completely different with respect to the ones which will be

used throughout this paper. While the proof in [6] is based on a refinement of the supremum norm approximation of Moise [26] (which, as pointed out by the authors themselves, cannot be extended to deal with the Sobolev case) and the approach of [22] makes use of the identification $\mathbb{R}^2 \simeq \mathbb{C}$ and involves coordinate-wise p -harmonic functions, our proof is constructive and based on an explicit subdivision of the domain of u depending on the Lebesgue points of Du .

We conclude giving a bound on the values of the constants C_1 , C_2 and C_3 appearing in [Theorems 1.1, 1.2 and 2.2](#) (while the constant $C'(\Omega)$ depends on the set Ω , see [Remark 6.1](#)),

$$C_1 = 72^4 C_3, \quad C_2 = 50C_1^{7/3}, \quad C_3 = 460\,000.$$

2. Scheme of the proof and plan of the paper

Our proof is constructive, thus long, but it relies essentially on three known facts: the Lebesgue Differentiation Theorem for L^1 -maps in \mathbb{R}^d , the Jordan curve theorem and a planar bi-Lipschitz extension theorem for homeomorphic images of squares proved in [11]. As already mentioned in the introduction, all our effort will be to get a piecewise affine approximation of u , since then the smooth extension readily follows by the following recent result from [29].

Theorem 2.1. *Let $v : \Omega \rightarrow \mathbb{R}^2$ be a (countably) piecewise affine homeomorphism, bi-Lipschitz with constant L . Then there exists a smooth diffeomorphism $\hat{v} : \Omega \rightarrow v(\Omega)$ such that $\hat{v} \equiv v$ on $\partial\Omega$, \hat{v} is bi-Lipschitz with constant at most $50L^{7/3}$, and*

$$\|\hat{v} - v\|_{L^\infty(\Omega)} + \|D\hat{v} - Dv\|_{L^p(\Omega)} + \|\hat{v}^{-1} - v^{-1}\|_{L^\infty(v(\Omega))} + \|D\hat{v}^{-1} - Dv^{-1}\|_{L^p(v(\Omega))} \leq \varepsilon.$$

A rough idea and scheme of our construction is as follows.

Approximation of u on Lebesgue squares. The first idea is to use the fact that, in a sufficiently small neighborhood of each Lebesgue point z for the differential Du , the map u is arbitrarily close, both in $W^{1,p}$ and in L^∞ , to an affine L bi-Lipschitz map (given by its linearization around the point z). The $W^{1,p}$ estimate is simply a restatement of the definition of Lebesgue point of Du , while the L^∞ estimate is proven in [Lemma 4.2](#). Indeed we prove that, given a square $\mathcal{D} \subseteq \Omega$ (e.g. a neighborhood of z), the more Du is close in $L^p(\mathcal{D})$ to an L bi-Lipschitz matrix M (given e.g. by $Du(z)$), the more u is close in $L^\infty(\mathcal{D})$ to an L bi-Lipschitz affine map u_M with $Du_M = M$. Moreover, since u is bi-Lipschitz, we have that also the inverse of u is close both in $W^{1,p}(u(\mathcal{D}))$ and in $L^\infty(u(\mathcal{D}))$ to the inverse of u_M .

The main implication of these estimates towards the construction of a piecewise affine bi-Lipschitz map approximating u is the following. Let us take a square $\mathcal{D} \subseteq \Omega$ as above and let us consider the piecewise affine function v which coincides with u on the vertices of \mathcal{D} and is affine on each of the two triangles obtained dividing \mathcal{D} with a diagonal. If $\|Du - M\|_{L^p(\mathcal{D})}$ is sufficiently small, then the L^∞ estimate implies that $u(\partial\mathcal{D})$ is uniformly relatively close to the parallelogram of side lengths at least $\text{side}(\mathcal{D})/L$ given by $u_M(\partial\mathcal{D})$. Hence, since $v = u$ on the vertices of the square and is affine on each side of $\partial\mathcal{D}$, the same uniform estimate holds also for v . In particular, the map v is orientation-preserving, injective, and approximates u and its inverse as desired.

Finally, thanks to the fact that the Lebesgue points of Du have full measure in Ω , we fix two orthonormal vectors $e_1, e_2 \in \mathbb{R}^2$ and, $\forall \varepsilon > 0$, we find a set $\Omega_\varepsilon \Subset \Omega$ with $\mathcal{L}(\Omega \setminus \Omega_\varepsilon) \leq \varepsilon$ which is made by a uniform “tiling” of squares with sides parallel to e_1, e_2 with the following property. On each square \mathcal{D} of the tiling, Du is sufficiently close to an L bi-Lipschitz matrix M (in particular, M will be equal to $Du(z)$ for some Lebesgue point $z \in \mathcal{D}$). Then, by the previous remarks, one can show that the piecewise affine function v obtained interpolating between the values of u on the vertices of the squares is injective and satisfies (1.1) on Ω_ε . Moreover, v is $L + \varepsilon$ bi-Lipschitz. The squares of the tiling covering Ω_ε will be called *Lebesgue squares*, and the set Ω_ε *right polygon*, due to its shape—see [Fig. 2](#).

Thus, the first idea of the proof leads to define a piecewise affine approximation of u on a set whose Lebesgue measure is as close as we want to $\mathcal{L}(\Omega)$. In order to complete the construction, we have to define v in the interior of the set $\Omega \setminus \Omega_\varepsilon$.

Countably piecewise affine bi-Lipschitz extension. The second idea of our proof is to reduce to the following model case: $\Omega \setminus \Omega_\varepsilon$ is a square of Lebesgue measure at most ε and $u|_{\partial(\Omega \setminus \Omega_\varepsilon)}$ is a piecewise affine function. In particular, by the previous construction, $v = u$ on $\partial\Omega_\varepsilon$. In this case, an approximating function v is provided by the following bi-Lipschitz extension theorem, proved in [11].

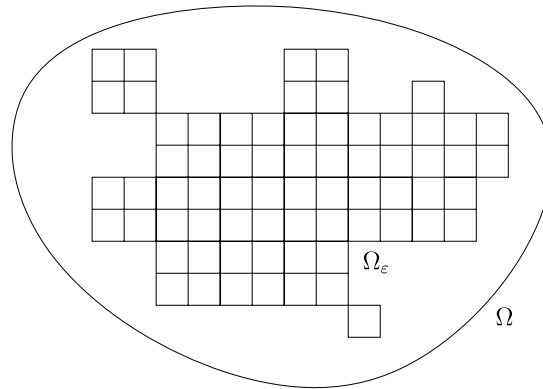


Fig. 2. An open set Ω and a right polygon $\Omega_\varepsilon \in \Omega$.

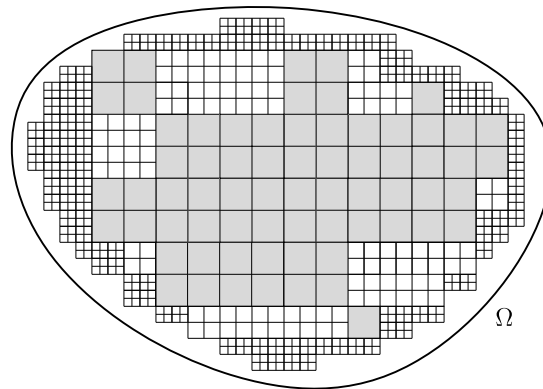


Fig. 3. (A part of) the countable tiling of $\Omega \setminus \Omega_\varepsilon$ —the shaded region is Ω_ε .

Theorem 2.2. (See [11].) *There exists a geometric constant C_3 such that every L bi-Lipschitz piecewise affine map $u : \partial\mathcal{D}(0, 1) \rightarrow \mathbb{R}^2$ defined on the boundary of the unit square admits a C_3L^4 bi-Lipschitz piecewise affine extension $v : \mathcal{D}(0, 1) \rightarrow \Gamma$, where Γ is the bounded closed set such that $\partial\Gamma = u(\partial\mathcal{D}(0, 1))$.*

In particular, it is shown in [11] that one can take $C_3 = 460\,000$. We recall that an analogous result had already been proved by Tukia in [35]. However, explicit estimates of the Lipschitz constant of the extension v were not provided.

It is then easy to verify that, provided ε is chosen sufficiently small at the beginning, such an extension of $u|_{\partial(\Omega \setminus \Omega_\varepsilon)}$ together with the already defined piecewise affine interpolation of u on the Lebesgue squares, satisfies the assumptions of Theorem 1.1. Indeed, by definition, v is injective on the whole Ω . Moreover, we know by the previous construction that it satisfies (1.1) on Ω_ε . And on the other hand, on $\Omega \setminus \Omega_\varepsilon$, $|Du|$ and $|Dv|$ are bounded by the two Lipschitz constants L and CL^4 (together with their inverses) on a set of small area and then the $W^{1,p}$ estimates in (1.1) follow. Finally, since $\Omega \setminus \Omega_\varepsilon$ and $u(\Omega \setminus \Omega_\varepsilon)$ have small Lebesgue measure, v and v^{-1} are also close to u and u^{-1} in L^∞ .

In order to reduce to this model case, we perform the following steps:

1. We cover $\Omega \setminus \Omega_\varepsilon$ with a countable (locally finite in Ω) “tiling” of small squares whose sides are parallel to e_1 and e_2 (see Fig. 3).

2. On the 1-dimensional grid \mathcal{Q} given by the boundaries of the squares of the tiling we define the piecewise affine approximation v in such a way that $v(\mathcal{Q}) \subseteq \Delta$ and v is $72L$ bi-Lipschitz.

3. We “fill” the squares of the tiling extending $v|_{\mathcal{Q}}$ by means of Theorem 2.2, thus getting a globally $C_3(72L)^4$ bi-Lipschitz function on $\Omega \setminus \Omega_\varepsilon$.

The fact that the Lipschitz constant of v on Ω_ε depends only on the Lipschitz constant of u will tell us that, as in the model case, the $W^{1,p}$ and L^∞ norms of $u - v$ and $u^{-1} - v^{-1}$ can be made as small as we want—provided we choose ε sufficiently small at the beginning. Thus we end the proof of Theorem 1.1.

Let us also give a very rough idea of how the proofs of Steps 1, 2 and 3 works. While Step 1 is a simple geometric construction, Step 2 essentially consists in approximating u on the grid \mathcal{Q} with a piecewise affine function. This will be possible thanks to [Lemma 5.5](#), which tells that it is possible to approximate u on the segments, and to [Lemma 5.6](#), which takes care of the “crosses”. Finally, [Proposition 5.1](#) in Section 5 concludes the argument of Steps 2 and 3. The essential idea there is that, since on the “non-Lebesgue squares” the behavior of u is wilder, one cannot simply take v equal to the affine interpolation of u on the vertices. Indeed, as already pointed out in the introduction, this could easily give a non-injective function. However, since the total area of the non-Lebesgue squares is small, any bi-Lipschitz function which preserves the boundary values approximates u as in (1.1). This is why we use the extension of $v|_{\mathcal{Q}}$ given by [Theorem 2.2](#) in Step 3.

Plan of the paper. Section 3 contains the main notation and some preliminary definitions.

Section 4 is devoted to the construction of v on a large right polygon made of “Lebesgue squares”.

In Section 5 we complete the proof of [Theorem 1.1](#) using the reduction argument outlined above and the bi-Lipschitz extension [Theorem 2.2](#).

Finally, in Section 6, we adapt the proof of [Theorem 1.1](#) to provide a (finitely) piecewise affine approximation of u whenever Ω is polygonal and $u|_{\partial\Omega}$ is piecewise affine, thus proving [Theorem 1.2](#).

3. Preliminary notation and definitions

In this section we give some preliminary definitions and fix some useful notation which will be used throughout the paper.

First we recall the definition of orientation-preserving (resp. reversing) homeomorphism.

Definition 3.1 (*Orientation-preserving (reversing) homeomorphism*). We say that a homeomorphism $u : \Omega \rightarrow u(\Omega) \subseteq \mathbb{R}^2$ is orientation-preserving (reversing) if whenever a simple closed curve $[0, 1] \ni t \mapsto \gamma(t) \in \Omega$ is parameterized clockwise, then $[0, 1] \ni t \mapsto u(\gamma(t)) \in u(\Omega)$ is parameterized clockwise (resp. anti-clockwise).

It is well known that if Ω is connected, then any homeomorphism $u : \Omega \rightarrow u(\Omega) \subseteq \mathbb{R}^2$ is either orientation-preserving or orientation-reversing.

Next, we define the class of functions in which we look for approximations of u . To this aim we recall the definitions of (*finite*) *triangulation* of a polygon and of *locally finite triangulation* of an open set $\Omega \subseteq \mathbb{R}^2$.

Definition 3.2 (*Finite triangulation*). A (*finite*) *triangulation* of a polygon $\Omega' \subseteq \mathbb{R}^2$ is a finite collection of closed triangles $\{T_i\}_{i=1}^N$ whose union is equal to $\text{clos } \Omega'$ and, for all $i \neq j$,

$$T_i \cap T_j \text{ is either empty, or a common vertex, or a common side.} \quad (3.1)$$

Definition 3.3 (*Locally finite triangulation*). Let $\Omega \subseteq \mathbb{R}^2$ be a bounded open set. A *locally finite triangulation* of Ω is a locally finite collection of closed triangles $\{T_i\}_{i \in \mathbb{N}}$ such that $\Omega \subseteq \bigcup_{i \in \mathbb{N}} T_i \subseteq \text{clos } \Omega$ and (3.1) holds.

We notice that, unless Ω is a polygon, the number of elements of a triangulation cannot be finite.

Definition 3.4 (*Piecewise affine and countably piecewise affine function*). A function $v : \Omega \rightarrow \mathbb{R}^2$ is *countably piecewise affine* if $v|_T$ is affine on every triangle T of a suitable locally finite triangulation of Ω . If Ω is a polygon and the triangulation is finite, then we say that v is (*finitely*) *piecewise affine*.

In order to build the triangulation on which the function v of [Theorem 1.1](#) is countably piecewise affine, we will use, on a subset of Ω of Lebesgue measure as close as we want to $\mathcal{L}(\Omega)$, uniform triangulations into right triangles. The union of such triangles will be called a right polygon, according to the following definition. From now on, e_1, e_2 will be two fixed orthonormal vectors in \mathbb{R}^2 .

Definition 3.5 (*Right polygon and r -piecewise affine function*). An open bounded set $\Omega' \subset \mathbb{R}^2$ is called a *right polygon of side length r* (or simply an *r -polygon*) if it is a finite union of closed polygons whose sides are all parallel to $e_1,$

e_2 , and have lengths which are integer multiples of $r > 0$. Let now Ω' be an r -polygon, and consider a bi-Lipschitz function $u : \Omega' \rightarrow \mathbb{R}^2$. For every side $\Gamma \subseteq \partial\Omega'$, write $\Gamma = \bigcup_{i=1}^N \Gamma_i$ where the Γ_i 's are essentially disjoint segments of length r . We say that u is r -piecewise affine on $\partial\Omega'$ if for any such segment Γ and for any i , the function u is affine on Γ_i .

Points in Ω will be denoted by $z \in \mathbb{R}^2$ or by $(x, y) \in \mathbb{R} \times \mathbb{R}$, with $z = xe_1 + ye_2$. We denote with $\mathcal{B}(z, r)$ the ball of center z and radius r and with $\mathcal{D}(z, r)$ the square of center z , side length r and sides parallel to e_1, e_2 . Moreover, the generic square of a collection of squares $\{\mathcal{D}(z_\alpha, r_\alpha)\}_{\alpha \in \mathbb{N}}$ will be also sometimes denoted simply by \mathcal{D}_α . Instead of working directly with triangulations, it will be convenient, in order to apply our method, to subdivide Ω into a countable and locally finite family of squares called tiling.

Definition 3.6 (Tiling). Given an open, bounded set Ω , a *tiling of Ω* is a locally finite (in Ω) collection of closed squares $\{\mathcal{D}_\alpha(z_\alpha, r_\alpha)\}_{\alpha \in \mathbb{N}}$ whose union is contained between Ω and $\text{clos } \Omega$ and such that, $\forall \alpha \neq \beta \in \mathbb{N}$, $\mathcal{D}_\alpha \cap \mathcal{D}_\beta$ is either empty, or a common vertex of \mathcal{D}_α and \mathcal{D}_β , or a side of one of the two. Two squares of a tiling are said to be *adjacent* if their intersection is nonempty.

Notice that a tiling of Ω can be either finite or countable and in particular it is surely countable if Ω is not a right polygon.

It will be often useful to regard a given tiling of Ω as the union of the finite tiling corresponding to a right polygon $\Omega' \Subset \Omega$ and a countable tiling of $\Omega \setminus \Omega'$, locally finite in Ω . Since these kinds of “sub-tilings” will be frequently used in the paper, we define them separately.

Definition 3.7 (r -Tiling of a right polygon and tiling of (Ω, Ω')). Given an r -polygon Ω' , the r -tiling of Ω' is the (unique) finite collection of closed squares $\{\mathcal{D}(z_\alpha, r)\}_{\alpha \in \mathcal{I}(r)}$ whose union is equal to $\text{clos } \Omega'$ and, $\forall \alpha \neq \beta \in \mathcal{I}(r)$, $\mathcal{D}_\alpha \cap \mathcal{D}_\beta$ is either empty, or a common vertex, or a common side of \mathcal{D}_α and \mathcal{D}_β . Given a bounded, open set Ω and an r -polygon $\Omega' \Subset \Omega$, a *tiling of (Ω, Ω')* is a tiling of Ω whose restriction to Ω' is the r -tiling of Ω' .

The 1-dimensional skeleton of a tiling will be called grid, according to the following definition.

Definition 3.8 (Grid). Let $\{\mathcal{D}_\alpha\}_{\alpha \in \mathbb{N}}$ be a tiling of Ω . We call *grid of the tiling* the 1-dimensional set given by the union of the boundaries of the squares of the tiling. Each side (resp. vertex) of the squares of a tiling will be called *side* (resp. *vertex*) of the grid.

A possible definition of a piecewise affine approximation of u on a given r -polygon, which will be used in Section 4, is the following.

Definition 3.9 ((Ω', r) -interpolation of u). Let $\Omega' \Subset \Omega$ and $\{\mathcal{D}_\alpha\}_{\alpha \in \mathcal{I}(r)}$ be an r -right polygon and its r -tiling. We call (Ω', r) -interpolation of u the piecewise affine function $v : \Omega' \rightarrow v(\Omega') \subseteq \mathbb{R}^2$ which coincides with u on the vertices of the r -tiling and, for each $\alpha \in \mathcal{I}(r)$, is affine on the two right triangles forming \mathcal{D}_α and having as common hypotenuse the north-east/south-west diagonal of \mathcal{D}_α .

We conclude this section with a table collecting the main notation used in this paper.

$\Omega \subseteq \mathbb{R}^2$	a given open bounded set,	$\mathcal{D}(z, r)$	square with center z , side length r
$u : \Omega \rightarrow \Delta$	a given L bi-Lipschitz function,		and sides parallel to e_1, e_2 ,
$\mathcal{M}(2 \times 2)$	two by two real matrices,	\mathcal{L}	Lebesgue measure on \mathbb{R}^2 ,
$ M $	$\sup\{ Mv : v = 1\}$,	\mathcal{H}^1	1-dimensional Hausdorff measure,
$\mathcal{M}(2 \times 2; L)$	$\{M \in \mathcal{M}(2 \times 2) : \text{Det } M > 0,$ $ M \leq L, M^{-1} \leq L\}$,	$\text{int } A$	interior of a set $A \subseteq \mathbb{R}^2$,
e_1, e_2	two fixed positively oriented orthonormal vectors in \mathbb{R}^2 ,	$\text{clos } A$	closure of A ,
$\mathcal{B}(z, r)$	ball with center z and radius r ,	∂A	boundary of $A \subseteq \mathbb{R}^2$,
		$\Omega' \Subset \Omega$	$\text{clos } \Omega' \subseteq \Omega$,
		$d(A, B)$	$\inf\{ z - w : z \in A, w \in B\}$.

4. Approximation on the “Lebesgue squares”

The aim of this section is to prove the following

Proposition 4.1. *For every $\varepsilon > 0$ there exists a right polygon $\Omega_\varepsilon \Subset \Omega$ of side length r such that the (Ω_ε, r) -interpolation $v : \Omega_\varepsilon \rightarrow v(\Omega_\varepsilon) \subseteq \mathbb{R}^2$ is $L + \varepsilon$ bi-Lipschitz and satisfies*

$$\Delta_\varepsilon := v(\Omega_\varepsilon) \Subset \Delta, \tag{4.1}$$

$$\|v - u\|_{L^\infty(\Omega_\varepsilon)} + \|v^{-1} - u^{-1}\|_{L^\infty(\Delta_\varepsilon)} + \|Du - Dv\|_{L^p(\Omega_\varepsilon)} + \|Du^{-1} - Dv^{-1}\|_{L^p(\Delta_\varepsilon)} \leq \varepsilon, \tag{4.2}$$

$$\mathcal{L}(\Omega \setminus \Omega_\varepsilon) \leq \varepsilon, \quad \mathcal{L}(\Delta \setminus \Delta_\varepsilon) \leq \varepsilon, \quad d(\Omega_\varepsilon, \mathbb{R}^2 \setminus \Omega) \geq 2r, \tag{4.3}$$

$$\|v - u\|_{L^\infty(\Omega_\varepsilon)} \leq \frac{\sqrt{2}r}{6L^3}. \tag{4.4}$$

The reason why the piecewise affine interpolation of u will be injective on Ω_ε is that, for each square \mathcal{D}_α of the r -tiling of Ω_ε , the function u will be uniformly close to an affine L bi-Lipschitz function on the nine squares around \mathcal{D}_α . The linear part of each of these affine functions will be the differential of u at some Lebesgue point for Du inside \mathcal{D}_α . For this reason, the squares of such r -tiling will be called “Lebesgue squares”.

The plan of this section is the following. Section 4.1 contains Lemma 4.2, which is the main ingredient in the proof of Proposition 4.1. Indeed, Lemma 4.2 says that, when on a square Du is close in average to an L bi-Lipschitz matrix M , then u is close in L^∞ to an affine function u_M with $Du_M = M$. Then, in Section 4.2, we will determine Ω_ε as a suitable union of squares of an r -tiling on which Lemma 4.2 holds and provides a sufficiently strong L^∞ estimate. Finally, in Section 4.3 we show that the (Ω_ε, r) -interpolation of u satisfies the required properties.

4.1. An L^∞ lemma

We are now ready to begin the proof of Proposition 4.1, starting from the following fundamental lemma. Here and in the following, by $\mathcal{M}(2 \times 2; L)$ we denote the set of the two by two invertible matrices such that the affine map $z \mapsto Mz$ is L bi-Lipschitz. Moreover, Ω and u will always be a set and a function as in the assumptions of Theorem 1.1.

Lemma 4.2. *For any $\eta > 0$ there exists $\delta = \delta(\eta) > 0$ such that, if $\bar{z} \in \Omega$, $M \in \mathcal{M}(2 \times 2; L)$ and $\rho > 0$ are so that $\mathcal{D}(\bar{z}, \rho) \Subset \Omega$ and*

$$\int_{\mathcal{D}(\bar{z}, \rho)} |Du(z) - M| dz \leq \delta, \tag{4.5}$$

then there exists an affine function $u_M : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ with $Du_M = M$ and such that

$$|u(z) - u_M(z)| \leq \eta\rho \quad \forall z \in \mathcal{D}(\bar{z}, \rho). \tag{4.6}$$

Proof. Up to a translation, we are allowed to assume for simplicity that $\bar{z} = u(\bar{z}) = (0, 0) \in \mathbb{R}^2$. Let us then call, for a big constant R to be specified later,

$$B^1 := \left\{ x \in [-\rho/2, \rho/2]: \int_{-\rho/2}^{\rho/2} |Du(x, t) - M| dt \leq \rho R\delta \right\},$$

$$B^2 := \left\{ y \in [-\rho/2, \rho/2]: \int_{-\rho/2}^{\rho/2} |Du(t, y) - M| dt \leq \rho R\delta \right\}.$$

Notice that, since u is bi-Lipschitz on Ω , then so are its restrictions to the horizontal and vertical segments of the square $\mathcal{D}(0, \rho)$. Hence, the above integrals make sense for every x and y . By (4.5) and Fubini–Tonelli Theorem, we readily obtain

$$\mathcal{H}^1([- \rho/2, \rho/2] \setminus B^1) \leq \frac{\rho}{R}, \quad \mathcal{H}^1([- \rho/2, \rho/2] \setminus B^2) \leq \frac{\rho}{R}. \tag{4.7}$$

Define now $u_M(z) = Mz$, and $\varphi(z) = u(z) - u_M(z)$. For any $x_1, x_2 \in B^1$ and $y_1, y_2 \in B^2$ we immediately get

$$\begin{aligned} |\varphi(x_1, y_1) - \varphi(x_2, y_2)| &\leq |\varphi(x_1, y_1) - \varphi(x_2, y_1)| + |\varphi(x_2, y_1) - \varphi(x_2, y_2)| \\ &\leq \int_{x_1}^{x_2} |Du(t, y_1) - M| dt + \int_{y_1}^{y_2} |Du(x_2, t) - M| dt \leq 2\rho R\delta. \end{aligned} \tag{4.8}$$

Let now $(x, y) \in \mathcal{D}(\bar{z}, \rho)$ be a generic point. By (4.7), there exist $x_1 \in B^1$ and $y_1 \in B^2$ so that

$$|x - x_1| \leq \frac{\rho}{R}, \quad |y - y_1| \leq \frac{\rho}{R},$$

and since u and u_M are L bi-Lipschitz, thus φ is $2L$ -Lipschitz, we get

$$|\varphi(x, y) - \varphi(x_1, y_1)| \leq \frac{2\sqrt{2}\rho L}{R}. \tag{4.9}$$

Let finally (x, y) and (\tilde{x}, \tilde{y}) be two generic points in $\mathcal{D}(\bar{z}, r)$. Putting together (4.8) and (4.9) we immediately get

$$|\varphi(x, y) - \varphi(\tilde{x}, \tilde{y})| \leq \frac{4\sqrt{2}\rho L}{R} + 2\rho R\delta \leq \eta\rho,$$

where the last inequality is true up to take R big enough and then δ small enough. Since $\varphi(0, 0) = 0$, this concludes the proof. \square

4.2. A large right polygon made of Lebesgue squares

In this section we show that, for any $\eta > 0$, it is possible to construct a right polygon $\Omega_\eta \Subset \Omega$ of side length r_η such that $\mathcal{L}(\Omega \setminus \Omega_\eta) \leq \eta$ and such that, for any square $\mathcal{D}(z, r_\eta)$ of the r_η -tiling of Ω_η , the assumption (4.5) of Lemma 4.2 holds on the bigger square $\mathcal{D}(z, 3r_\eta)$. As we will show in Section 4.3, if we choose η and then r_η small enough, the corresponding (Ω_η, r_η) -interpolation of u satisfies the requirements of Proposition 4.1. Then, Ω_η will turn out to be the right polygon of Lebesgue squares we are looking for. The goal of this section is to show the following estimate.

Lemma 4.3. *For every $\eta > 0$ there exists a constant $r = r(\eta) > 0$ and an r -polygon $\Omega_\eta \Subset \Omega$ such that $\mathcal{L}(\Omega \setminus \Omega_\eta) \leq \eta$ and each square of the r -tiling $\{\mathcal{D}(z_\alpha, r)\}_{\alpha \in \mathcal{I}(r)}$ satisfies the following properties,*

$$\mathcal{D}(z_\alpha, 3r) \Subset \Omega \quad \forall \alpha \in \mathcal{I}(r), \tag{4.10}$$

$$\int_{\mathcal{D}(z_\alpha, 3r)} |Du(z) - M| dz \leq \delta(\eta) \quad \text{for some } M = M(\alpha) \in \mathcal{M}(2 \times 2; L). \tag{4.11}$$

Proof. We start selecting some $r_0 = r_0(\eta) > 0$ and an r_0 -polygon $\Omega_0 \Subset \Omega$ such that $\mathcal{L}(\Omega \setminus \Omega_0) \leq \eta/2$ and each square of the r_0 -tiling of Ω_0 satisfies (4.10). Then, for every r such that $r_0 \in r\mathbb{N}$, we can regard Ω_0 also as an r -polygon, and consequently call $\{\mathcal{D}(z_\alpha, r)\}_{\alpha \in \mathcal{I}_0(r)}$ its r -tiling. We define the set

$$\mathcal{I}(r) := \left\{ \alpha \in \mathcal{I}_0(r) : \int_{\mathcal{D}(z_\alpha, 3r)} |Du - M| \leq \delta \text{ for some } M = M(\alpha) \in \mathcal{M}(2 \times 2; L) \right\},$$

where $\delta = \delta(\eta)$ is given by Lemma 4.2, and we let

$$\Omega_\eta := \bigcup_{\alpha \in \mathcal{I}(r)} \mathcal{D}(z_\alpha, r).$$

Since property (4.11) is true by construction, to conclude the proof it is enough to select a suitable $r = r(\eta)$ in such a way that $\mathcal{L}(\Omega_0 \setminus \Omega_\eta) \leq \eta/2$.

To do so, we apply the Lebesgue Differentiation Theorem to the map Du finding that, for \mathcal{L} -a.e. $z \in \Omega_0$, there exists $r(z) > 0$ such that $\mathcal{D}(z, 4r(z)) \subseteq \Omega_0$ and

$$\int_{\mathcal{D}(z, \rho)} |Du(w) - Du(z)| dw \leq \frac{\delta}{2} \quad \forall 0 < \rho \leq 4r(z).$$

We can then choose $r = r(\eta)$ so small that the set $A(r) := \{z \in \Omega_0: r(z) \leq r\}$ satisfies

$$\mathcal{L}(A(r)) \leq \eta/2. \tag{4.12}$$

We now claim that, for each $\alpha \in \mathcal{I}_0(r)$,

$$\mathcal{D}(z_\alpha, r) \not\subseteq A(r) \implies \alpha \in \mathcal{I}(r). \tag{4.13}$$

Indeed, letting $M = Du(z)$ for some $z \in \mathcal{D}(z_\alpha, r) \setminus A(r)$, by definition of $A(r)$ and $r(z)$ we get

$$\int_{\mathcal{D}(z_\alpha, 3r)} |Du - M| = \frac{1}{9r^2} \int_{\mathcal{D}(z_\alpha, 3r)} |Du - M| \leq \frac{1}{9r^2} \int_{\mathcal{D}(z, 4r)} |Du - M| = \frac{16}{9} \int_{\mathcal{D}(z, 4r)} |Du - M| \leq \frac{8}{9}\delta,$$

thus (4.13) is obtained. As a consequence, by (4.12) we have that

$$\mathcal{L}(\Omega_0 \setminus \Omega_\eta) = \mathcal{L}\left(\bigcup_{\alpha \in \mathcal{I}_0(r) \setminus \mathcal{I}(r)} \mathcal{D}(z_\alpha, r)\right) \leq \mathcal{L}(A(r)) \leq \frac{\eta}{2}$$

and, as we noticed above, this concludes the proof. \square

4.3. Affine approximation of u on Lebesgue squares

In this section we complete the proof of Proposition 4.1. At this point the proof reduces to show that, provided we choose η small enough, the (Ω_η, r) -interpolation of u on the right polygon Ω_η as in Lemma 4.3 satisfies the properties of Proposition 4.1.

Proof of Proposition 4.1. Let $\varepsilon > 0$ be a given constant. Then, let $\eta = \eta(\varepsilon)$ be a sufficiently small constant, whose value will be precised later. Define now $\delta = \delta(\eta(\varepsilon))$ as in Lemma 4.2, and define also $r = r(\eta(\varepsilon))$ and $\Omega_\varepsilon = \Omega_{\eta(\varepsilon)}$ according to Lemma 4.3. We will show that the right polygon Ω_ε fulfills all the requirements of the proposition as soon as $\eta(\varepsilon)$ is small enough. To this aim we call, as in the statement, $v : \Omega_\varepsilon \rightarrow \Delta_\varepsilon$ the (Ω_ε, r) -interpolation of u (see Definition 3.9) on the right polygon Ω_ε .

Let us briefly fix some notation which will be used through the proof. For any $\alpha \in \mathcal{I}(r)$, we define $M_\alpha \in \mathcal{M}(2 \times 2; L)$ so that (4.11) holds. Applying Lemma 4.2 with $\rho = 3r$, we get an affine function $u_\alpha : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ such that $Du_\alpha = M_\alpha$ and

$$|u - u_\alpha| \leq 3\eta r \quad \text{on } \mathcal{D}(z_\alpha, 3r). \tag{4.14}$$

Fig. 4 depicts the functions u , v and u_α .

We can then start the proof, which will be divided in some steps for clarity.

Step I. For any $\alpha \in \mathcal{I}(r)$, $v(\mathcal{D}(z_\alpha, r)) \subseteq u(\mathcal{D}(z_\alpha, 3r))$.

Take $\alpha \in \mathcal{I}(r)$. Keeping in mind (4.14) and recalling the definition of v , we get that

$$v(\mathcal{D}(z_\alpha, r)) \subseteq \mathcal{B}(u_\alpha(\mathcal{D}(z_\alpha, r)), 3\eta r), \tag{4.15}$$

where for any set $X \subseteq \mathbb{R}^2$ we denote by $\mathcal{B}(X, r)$ the r -neighborhood of X . Similarly, we get that

$$u(\mathcal{D}(z_\alpha, 3r)) \supseteq \{x: \mathcal{B}(x, 3\eta r) \subseteq u_\alpha(\mathcal{D}(z_\alpha, 3r))\}.$$

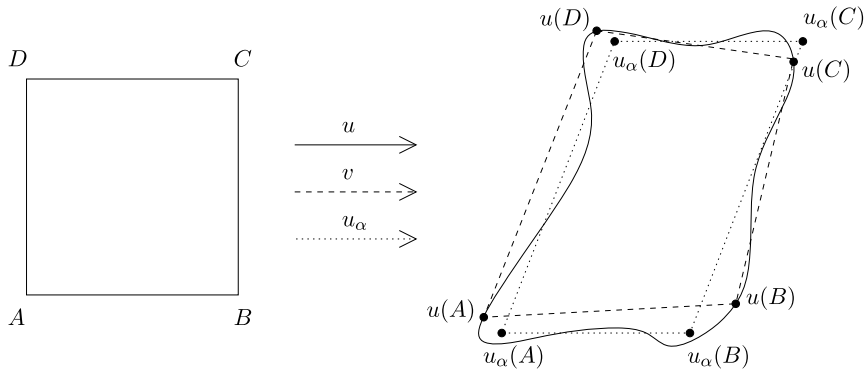


Fig. 4. The functions u , v and u_α on a square.

Hence, the step is concluded if

$$\mathcal{B}(u_\alpha(\mathcal{D}(z_\alpha, r)), 6\eta r) \subseteq u_\alpha(\mathcal{D}(z_\alpha, 3r)),$$

which in turn, recalling that $Du_\alpha \equiv M_\alpha \in \mathcal{M}(2 \times 2; L)$, is true as soon as $\eta < (6L)^{-1}$.

Observe that, as an immediate consequence of this step and (4.10), we have $\Delta_\varepsilon \in \Delta$, that is, (4.1) holds.

Step II. Injectivity of v .

Take $\alpha \in \mathcal{I}(r)$. Applying again (4.14) as in Step I, we deduce that v is injective on $\mathcal{D}(z_\alpha, 3r) \cap \Omega_\varepsilon$ as soon as $\eta < (6L)^{-1}$. To conclude that v is injective, then, we have to show that $v(\mathcal{D}(z_\alpha, r)) \cap v(\mathcal{D}(z_\beta, r)) = \emptyset$ if $\mathcal{D}(z_\alpha, r)$ and $\mathcal{D}(z_\beta, r)$ are two non-adjacent squares of the tiling of Ω_ε . And in fact, if \mathcal{D}_α and \mathcal{D}_β are non-adjacent, then the fact that $v(\mathcal{D}(z_\alpha, r)) \cap v(\mathcal{D}(z_\beta, r)) = \emptyset$ for a small η follows as an immediate consequence of (4.14) and (4.15) arguing as in Step I.

Step III. Estimate on $\|v - u\|_{L^\infty(\Omega_\varepsilon)}$ and on $\|v^{-1} - u^{-1}\|_{L^\infty(\Delta_\varepsilon)}$.

Fix a generic square \mathcal{D}_α of the r -tiling of Ω_ε , and observe that $\|u_\alpha - u\|_{L^\infty(\mathcal{D}_\alpha)} \leq 3\eta r$ by (4.14). Moreover, v and u_α are both affine on each of the two right triangles on which \mathcal{D}_α is divided, and since on the vertices of these triangles v equals u , again by (4.14) we deduce also $\|v - u_\alpha\|_{L^\infty(\mathcal{D}_\alpha)} \leq 3\eta r$. Thanks to these two estimates, we deduce

$$\begin{aligned} \|v - u\|_{L^\infty(\Omega_\varepsilon)} &= \sup_{\alpha \in \mathcal{I}(r)} \|v - u\|_{L^\infty(\mathcal{D}_\alpha)} \leq \sup_{\alpha \in \mathcal{I}(r)} \|v - u_\alpha\|_{L^\infty(\mathcal{D}_\alpha)} + \|u_\alpha - u\|_{L^\infty(\mathcal{D}_\alpha)} \\ &\leq 6\eta r \leq \frac{\varepsilon}{4L}, \end{aligned} \tag{4.16}$$

where the last inequality is true as soon as η , hence also r , is small enough.

Since we have already proven that v is injective, the L^∞ estimate for the inverse maps is now a simple consequence. Indeed, taking a generic point $w = v(z) \in \Delta_\varepsilon$, with $z \in \Omega_\varepsilon$, by (4.16) we have

$$|u^{-1}(w) - v^{-1}(w)| = |u^{-1}(v(z)) - u^{-1}(u(z))| \leq L|v(z) - u(z)| \leq \frac{\varepsilon}{4},$$

so that

$$\|u^{-1} - v^{-1}\|_{L^\infty(\Delta_\varepsilon)} \leq \frac{\varepsilon}{4}. \tag{4.17}$$

Step IV. Estimate on $\|Dv - Du\|_{L^p(\Omega_\varepsilon)}$.

Let us start observing that, since by construction $|Du| \leq L$ and $|Dv| \leq \sqrt{2}L$, one has

$$\begin{aligned} \|Dv - Du\|_{L^p(\Omega_\varepsilon)}^p &= \sum_{\alpha \in \mathcal{I}(r)} \|Dv - Du\|_{L^p(\mathcal{D}_\alpha)}^p \\ &\leq (3L)^{p-1} \sum_{\alpha \in \mathcal{I}(r)} \|Dv - Du\|_{L^1(\mathcal{D}_\alpha)} \\ &\leq (3L)^{p-1} \sum_{\alpha \in \mathcal{I}(r)} (\|Dv - Du_\alpha\|_{L^1(\mathcal{D}_\alpha)} + \|Du_\alpha - Du\|_{L^1(\mathcal{D}_\alpha)}). \end{aligned} \tag{4.18}$$

By (4.11), we already know that for each $\alpha \in \mathcal{J}(r)$

$$\|Du - Du_\alpha\|_{L^1(\mathcal{D}_\alpha)} = \int_{\mathcal{D}(z_\alpha, r)} |Du - Du_\alpha| \leq 9r^2 \int_{\mathcal{D}(z_\alpha, 3r)} |Du - M_\alpha| \leq 9\delta r^2 = 9\delta |\mathcal{D}_\alpha|. \tag{4.19}$$

Let us then concentrate on $\|Dv - Du_\alpha\|_{L^1(\mathcal{D}_\alpha)}$. Consider the triangle $T = z_1 z_2 z_3$, being

$$z_1 \equiv z_\alpha + (-r/2, -r/2), \quad z_2 \equiv z_\alpha + (r/2, -r/2), \quad z_3 \equiv z_\alpha + (r/2, r/2).$$

Since both v and u_α are affine on T , then in particular $Dv - Du_\alpha$ is a constant linear function on T . Recalling again (4.14), let us then calculate

$$\begin{aligned} |(Dv|_T - Du_\alpha)(re_1)| &= |(v(z_2) - v(z_1)) - (u_\alpha(z_2) - u_\alpha(z_1))| \\ &= |(u(z_2) - u(z_1)) - (u_\alpha(z_2) - u_\alpha(z_1))| \leq 6\eta r, \end{aligned}$$

and similarly

$$|(Dv|_T - Du_\alpha)(re_2)| = |(v(z_3) - v(z_2)) - (u_\alpha(z_3) - u_\alpha(z_2))| \leq 6\eta r.$$

We deduce that $\|Dv - Du_\alpha\|_{L^\infty(T)} \leq 6\sqrt{2}\eta$. We can argue in the same way for all the different triangles in which $\mathcal{D}(z_\alpha, 3r) \cap \Omega_\varepsilon$ is divided, thus getting

$$\|Dv - Du_\alpha\|_{L^\infty(\mathcal{D}(z_\alpha, 3r) \cap \Omega_\varepsilon)} \leq 6\sqrt{2}\eta \leq 9\eta. \tag{4.20}$$

Inserting this estimate and (4.19) into (4.18), we get

$$\|Dv - Du\|_{L^p(\Omega_\varepsilon)}^p \leq (3L)^{p-1} 9(\delta + \eta) \sum_{\alpha \in \mathcal{J}(r)} |\mathcal{D}_\alpha| = (3L)^{p-1} 9(\eta + \delta) |\Omega_\varepsilon| \leq \left(\frac{\varepsilon}{4}\right)^p, \tag{4.21}$$

where again the last inequality holds true as soon as η , hence also δ , is small enough.

Step V. Bi-Lipschitz estimate for v.

Take a point $z \in \mathcal{D}(z_\alpha, 3r) \cap \Omega_\varepsilon$. Recalling that u_α is L bi-Lipschitz and (4.20), we get

$$\frac{1}{L} - 9\eta \leq |Dv(z)| \leq L + 9\eta. \tag{4.22}$$

Let then $z, z' \in \Omega_\varepsilon$ be two generic points, and assume that $z \in \mathcal{D}(z_\alpha, r)$. If one has $z' \in \mathcal{D}(z_\alpha, 3r)$, then an immediate geometric argument using the definition of v and (4.22) yields

$$\left(\frac{1}{L} - 9\eta\right) |z - z'| \leq |v(z) - v(z')| \leq (L + 9\eta) |z - z'|. \tag{4.23}$$

On the other hand, assume that $z' \notin \mathcal{D}(z_\alpha, 3r)$, so that $|z - z'| \geq r$. In this case, the L^∞ estimate (4.16) gives

$$|v(z) - v(z')| \leq |u(z) - u(z')| + |v(z) - u(z)| + |v(z') - u(z')| \leq (L + 12\eta) |z - z'|, \tag{4.24}$$

and similarly

$$|v(z) - v(z')| \geq |u(z) - u(z')| - |v(z) - u(z)| - |v(z') - u(z')| \geq \left(\frac{1}{L} - 12\eta\right) |z - z'|. \tag{4.25}$$

Putting together (4.23), (4.24) and (4.25), provided that η is small enough we conclude that v is $L + \varepsilon$ bi-Lipschitz.

Step VI. Estimate on $\|Dv^{-1} - Du^{-1}\|_{L^p(\Delta_\varepsilon)}$.

Fix a generic $\alpha \in \mathcal{J}(r)$, and recall the elementary fact that, given two invertible matrices A and B , one always has $|B^{-1} - A^{-1}| \leq |A^{-1}| |B^{-1}| |B - A|$. Since by construction u and u_α are L bi-Lipschitz, and Du_α is constant on \mathcal{D}_α , then Step I, (4.11) and (4.19) ensure that

$$\begin{aligned} \|Du^{-1} - Du_\alpha^{-1}\|_{L^1(v(\mathcal{D}_\alpha))} &= \int_{v(\mathcal{D}(z_\alpha, r))} |Du^{-1}(z) - Du_\alpha^{-1}(z)| dz \\ &\leq L^2 \int_{u(\mathcal{D}(z_\alpha, 3r))} |Du(u^{-1}(z)) - M_\alpha| dz \leq L^4 \int_{\mathcal{D}(z_\alpha, 3r)} |Du(w) - M_\alpha| dw \\ &= 9r^2 L^4 \int_{\mathcal{D}(z_\alpha, 3r)} |Du - M_\alpha| \leq 9r^2 L^4 \delta = 9L^4 \delta |\mathcal{D}_\alpha|. \end{aligned}$$

On the other hand, again using $|B^{-1} - A^{-1}| \leq |A^{-1}| |B^{-1}| |B - A|$, the fact that Du_α is constant on \mathcal{D}_α , the fact that u_α is L bi-Lipschitz by definition while v is $(L + \varepsilon)$ bi-Lipschitz by Step V, and (4.20), we readily obtain

$$\|Dv^{-1} - Du_\alpha^{-1}\|_{L^\infty(v(\mathcal{D}_\alpha))} \leq L(L + \varepsilon)9\eta \leq 18L^2\eta.$$

We can then repeat the same argument as in (4.18) to get

$$\begin{aligned} \|Dv^{-1} - Du^{-1}\|_{L^p(\Delta_\varepsilon)}^p &\leq (3L)^{p-1} \sum_{\alpha \in \mathcal{I}(r)} \|Dv^{-1} - Du_\alpha^{-1}\|_{L^1(v(\mathcal{D}_\alpha))} + \|Du_\alpha^{-1} - Du^{-1}\|_{L^1(v(\mathcal{D}_\alpha))} \\ &\leq (3L)^{p-1} (18L^2\eta|\Delta_\varepsilon| + 9L^4\delta|\Omega_\varepsilon|) \leq \left(\frac{\varepsilon}{4}\right)^p, \end{aligned} \tag{4.26}$$

where as usual the last estimate holds possibly decreasing η and then also δ .

Step VII. Conclusion.

Let us now conclude the proof of Proposition 4.1 by checking that Ω_ε fulfills all the requirements of the statement. The fact that v is $L + \varepsilon$ bi-Lipschitz is given by Step V. The validity of (4.1) has been observed in Step I. The estimate (4.2) just follows adding (4.16), (4.17), (4.21) and (4.26). Concerning (4.3), the facts that $\Omega \setminus \Omega_\varepsilon$ is small and that $d(\Omega_\varepsilon, \mathbb{R}^2 \setminus \Omega) \geq 2r$ are given by Lemma 4.3, while the fact that also $\Delta \setminus \Delta_\varepsilon$ is small is immediate by the bi-Lipschitz property of u and the L^∞ estimate (4.6) of Lemma 4.2. Finally, (4.4) is immediate provided that we choose $\eta \leq \sqrt{2}/(36L^3)$, since (4.16) ensures that $\|v - u\|_{L^\infty(\Omega_\varepsilon)} \leq 6\eta r$. \square

5. Approximation out of “Lebesgue squares”

In this section we complete the proof of Theorem 1.1, defining the countably piecewise affine approximation of u out of the large right polygon Ω_ε of “Lebesgue squares” constructed in Proposition 4.1. Following the scheme outlined in Section 2, the construction is carried out in three steps: the covering of $\Omega \setminus \Omega_\varepsilon$ with a suitable (locally finite) tiling, the definition of a bi-Lipschitz piecewise affine approximation of u on the grid of the tiling and, finally, the extension of the approximating function to the interior of the grid by means of Theorem 2.2. The main result of this section is the following.

Proposition 5.1. *Let $v_\varepsilon : \Omega_\varepsilon \rightarrow \Delta_\varepsilon$ be a piecewise affine bi-Lipschitz function as in Proposition 4.1. Then, there exists a C_1L^4 bi-Lipschitz countably piecewise affine function $\tilde{v}_\varepsilon : \Omega \setminus \Omega_\varepsilon \rightarrow \Delta \setminus \Delta_\varepsilon$, where C_1 is a geometric constant, such that $\tilde{v}_\varepsilon = u$ on $\partial\Omega$ and $\tilde{v}_\varepsilon = v_\varepsilon$ on $\partial\Omega_\varepsilon$.*

We can immediately notice that Theorem 1.1 follows as an easy consequence of Propositions 4.1 and 5.1.

Proof of Theorem 1.1. Take $\varepsilon > 0$, and apply Proposition 4.1 to get an r -polygon $\Omega_\varepsilon \Subset \Omega$ and a piecewise affine bi-Lipschitz function $v_\varepsilon : \Omega_\varepsilon \rightarrow \Delta_\varepsilon$. By Proposition 5.1, we have a C_1L^4 bi-Lipschitz function $\tilde{v}_\varepsilon : \Omega \setminus \Omega_\varepsilon \rightarrow \Delta \setminus \Delta_\varepsilon$, so we can define the function $v : \Omega \rightarrow \Delta$ as $v \equiv v_\varepsilon$ on Ω_ε and $v \equiv \tilde{v}_\varepsilon$ on $\Omega \setminus \Omega_\varepsilon$. Since v_ε (resp., \tilde{v}_ε) is bi-Lipschitz with constant $L + \varepsilon$ (resp., C_1L^4), and $\tilde{v}_\varepsilon = v_\varepsilon$ on $\partial\Omega_\varepsilon$, we have that v is a bi-Lipschitz homeomorphism with constant C_1L^4 . Moreover, by construction v is countably piecewise affine and it is orientation-preserving, since so is u and $v \equiv u$ on $\partial\Omega$. We are then left with showing that v satisfies (1.1), and by (4.2) this basically reduces to consider what happens in $\Omega \setminus \Omega_\varepsilon$. Since \tilde{v}_ε is bi-Lipschitz with constant C_1L^4 , by (4.3) we clearly have

$$\|Dv - Du\|_{L^p(\Omega \setminus \Omega_\varepsilon)} \leq \|Dv - Du\|_{L^\infty(\Omega \setminus \Omega_\varepsilon)} |\Omega \setminus \Omega_\varepsilon|^{1/p} \leq (L + C_1 L^4) \varepsilon^{1/p}, \quad (5.1)$$

and similarly

$$\|Dv^{-1} - Du^{-1}\|_{L^p(\Delta \setminus \Delta_\varepsilon)} \leq (L + C_1 L^4) \varepsilon^{1/p}. \quad (5.2)$$

Concerning the L^∞ estimates, since $|\Omega \setminus \Omega_\varepsilon| \leq \varepsilon$ then for every $z \in \Omega \setminus \Omega_\varepsilon$ there exist $z' \in \Omega_\varepsilon$ such that $|z - z'| \leq \sqrt{\varepsilon/\pi}$, thus by (4.2) we find

$$\begin{aligned} |v(z) - u(z)| &\leq |v(z) - v(z')| + |v(z') - u(z')| + |u(z') - u(z)| \\ &\leq (L + C_1 L^4) \sqrt{\frac{\varepsilon}{\pi}} + \|v_\varepsilon - u\|_{L^\infty(\Omega_\varepsilon)} \leq (L + C_1 L^4) \sqrt{\frac{\varepsilon}{\pi}} + \varepsilon. \end{aligned}$$

Arguing in the same way to bound $|v^{-1}(w) - u^{-1}(w)|$ for a generic $w \in \Delta \setminus \Delta_\varepsilon$ yields

$$\|v - u\|_{L^\infty(\Omega \setminus \Omega_\varepsilon)} \leq (L + C_1 L^4) \sqrt{\frac{\varepsilon}{\pi}} + \varepsilon, \quad \|v^{-1} - u^{-1}\|_{L^\infty(\Delta \setminus \Delta_\varepsilon)} \leq (L + C_1 L^4) \sqrt{\frac{\varepsilon}{\pi}} + \varepsilon. \quad (5.3)$$

Putting together (5.1), (5.2) and (5.3), we find that v satisfies (1.1) as soon as ε is chosen small enough, depending on $\bar{\varepsilon}$. Hence, we have found the countably piecewise affine approximation as required. Concerning the smooth approximation, its existence directly follows applying Theorem 2.1, thus we have in particular $C_2 = 50C_1^{7/3}$. \square

We have now to prove Proposition 5.1. To do so, let us fix some notation. Recall that Ω_ε is an r -polygon for some $r = r(\varepsilon)$. We will then start by selecting a suitable tiling $\{\mathcal{D}_j = \mathcal{D}(z_j, r_j)\}_{j \in \mathbb{N}}$ of $(\Omega, \Omega_\varepsilon)$, according with Definition 3.7. This means that $\{\mathcal{D}_j\}$ is a tiling of Ω whose restriction to Ω_ε coincides with the r -tiling of Ω_ε . The only requirements that we ask to $\{\mathcal{D}_j\}$ are the following,

$$r_j = r \quad \forall j: \quad \text{clos } \mathcal{D}_j \cap \partial \Omega_\varepsilon \neq \emptyset, \quad (5.4)$$

$$\mathcal{D}_j \Subset \Omega \quad \forall j \in \mathbb{N}. \quad (5.5)$$

Notice that (5.4) is possible thanks to (4.3), while (5.5) basically means that the tiling has to be countable instead of finite, and the squares have to become smaller and smaller when approaching the boundary of Ω . Of course, in the particular case when Ω itself is a right polygon, instead of (5.5) one could have asked the tiling to be finite (we will discuss this possibility more in detail in Remark 5.7).

Since it is of course possible to find a tiling of $(\Omega, \Omega_\varepsilon)$ which satisfies (5.4) and (5.5), from now on we fix such a tiling, and we denote by \mathcal{Q} its associated 1-dimensional grid according to Definition 3.8. Moreover, we set $\mathcal{Q}' = \mathcal{Q} \cap (\Omega \setminus \text{clos } \Omega_\varepsilon)$, which is the part of the grid on which we really need to work. Notice that \mathcal{Q}' is a 1-dimensional set, made by all the sides of the grid \mathcal{Q} which lie in $\Omega \setminus \text{clos } \Omega_\varepsilon$.

Let us call now w_α the generic vertex of \mathcal{Q}' , hence, the generic vertex of the grid \mathcal{Q} which does not belong to Ω_ε (however, notice that w_α may belong to $\partial \Omega_\varepsilon$, since by definition \mathcal{Q}' is relatively open around $\partial \Omega_\varepsilon$). Each vertex w_α is of the form $w_\alpha = z_j + (\pm r_j/2, \pm r_j/2)$ for some j , and it is one extreme of either three, or four sides of \mathcal{Q} . To shorten the notation, we will denote the other extremes of these sides by w_α^i with $1 \leq i \leq \bar{i}(\alpha)$, being then $\bar{i}(\alpha) \in \{3, 4\}$. Finally, we will denote by ℓ_α the minimum of the lengths of the sides $w_\alpha w_\alpha^i$. Observe that if $w_\alpha \notin \partial \Omega_\varepsilon$, then w_α is one extreme of either three or four sides of $\mathcal{Q}' \subseteq \mathcal{Q}$. On the other hand, if $w_\alpha \in \partial \Omega_\varepsilon$, then by (5.4) it is one extreme of four sides of \mathcal{Q} , either one or two of these four sides lies in \mathcal{Q}' , and $\ell_\alpha = r$.

Thanks to Theorem 2.2, to obtain the piecewise affine function \tilde{v}_ε of Proposition 5.1 we essentially have to define it, in a suitable way, on the 1-dimensional grid \mathcal{Q}' . To do so, our main ingredients are the following two lemmas. The first one (Lemma 5.5) states that, on any given segment of Ω , u can be approximated as well as desired in L^∞ with suitable piecewise affine $4L$ bi-Lipschitz functions. This is of course of primary importance to define the piecewise affine approximation \tilde{v}_ε of u on the sides of the grid \mathcal{Q}' , but it is still not enough. In fact, we have to take some additional care to treat the ‘‘crosses’’ of \mathcal{Q}' (that is, the regions around the vertices), in order to be sure that our affine \tilde{v}_ε on \mathcal{Q}' remains injective. This will be obtained thanks to the second Lemma 5.6.

To state the next two lemmas, it will be useful to introduce some piece of notation.

Definition 5.2 (*Interpolation of u*). Given a segment $pq \Subset \Omega$, let $\{z_i z_{i+1}\}_{0 \leq i < N}$ be N essentially disjoint segments whose union is pq , with $z_0 = p$ and $z_N = q$. For any such subdivision of the segment, we call *interpolation of u* the finitely piecewise affine function $u_{pq} : pq \rightarrow \mathbb{R}^2$ such that, for any $0 \leq i \leq N - 1$ and any $0 \leq t \leq 1$,

$$u_{pq}(z_i + t(z_{i+1} - z_i)) = u(z_i) + t(u(z_{i+1}) - u(z_i)).$$

Definition 5.3 (*Adjusted function and crosses*). Let $\{\xi_\alpha\}_{\alpha \in \mathbb{N}}$ be a sequence such that for any α one has $3L\xi_\alpha \leq \ell_\alpha$. For any $\alpha \in \mathbb{N}$ and any $1 \leq i \leq \bar{i}(\alpha)$, we define ξ_α^i as the biggest number such that

$$\begin{cases} |u(w_\alpha) - u(w_\alpha + \xi_\alpha^i(w_\alpha^i - w_\alpha))| \leq \xi_\alpha & \text{if } w_\alpha w_\alpha^i \subset \mathcal{Q}', \\ |u(w_\alpha) - v_\varepsilon(w_\alpha + \xi_\alpha^i(w_\alpha^i - w_\alpha))| \leq \xi_\alpha & \text{if } w_\alpha w_\alpha^i \subset \mathcal{Q} \setminus \mathcal{Q}'. \end{cases}$$

We will call *adjusted function* the function $u_{\text{adj}} : \mathcal{Q} \rightarrow \mathbb{R}^2$ defined as follows. First of all, we set $u_{\text{adj}} = v_\varepsilon$ on $\mathcal{Q} \setminus \mathcal{Q}'$. Then, let $w_\alpha w_\beta$ be a side of \mathcal{Q}' , thus being $w_\beta = w_\alpha^i$ and $w_\alpha = w_\beta^j$ for two suitable i and j . We define

$$u_{\text{adj}}(w_\alpha + t(w_\beta - w_\alpha)) := \begin{cases} u(w_\alpha) + \frac{t}{\xi_\alpha^i}(u(w_\alpha + \xi_\alpha^i(w_\beta - w_\alpha)) - u(w_\alpha)) & \text{in } (0, \xi_\alpha^i), \\ u(w_\alpha + t(w_\beta - w_\alpha)) & \text{in } (\xi_\alpha^i, 1 - \xi_\beta^j), \\ u(w_\beta) + \frac{(1-t)}{\xi_\beta^j}(u(w_\beta + \xi_\beta^j(w_\alpha - w_\beta)) - u(w_\beta)) & \text{in } (1 - \xi_\beta^j, 1). \end{cases}$$

In words, for any side in \mathcal{Q}' , u_{adj} coincides with u in the internal part of the side, while the two parts closest to the vertices w_α and w_β are replaced with segments. Moreover, for any vertex w_α of \mathcal{Q}' we will define its associated *cross* as

$$Z_\alpha = \bigcup_{i=1}^{\bar{i}(\alpha)} \{w_\alpha + t(w_\alpha^i - w_\alpha) : 0 \leq t \leq \xi_\alpha^i\}.$$

Remark 5.4. Some remarks are now in order. First of all, since u is L bi-Lipschitz on Ω , and also v_ε is L bi-Lipschitz on any segment $w_\alpha w_\alpha^i \subseteq \mathcal{Q} \setminus \mathcal{Q}'$, by the choice $3L\xi_\alpha \leq \ell_\alpha$ we directly deduce that $0 < \xi_\alpha^i \leq 1/3$ for any α and any i . Thus, two different crosses have always empty intersection. For the same reason, each of the $\bar{i}(\alpha)$ extremes of the cross Z_α has a distance at least ξ_α/L from w_α . Finally, for all different α and β one has $\mathcal{B}(u(w_\alpha), \xi_\alpha) \cap \mathcal{B}(u(w_\beta), \xi_\beta) = \emptyset$. Indeed, assuming without loss of generality that $\ell_\alpha \geq \ell_\beta$, we have $|u(w_\beta) - u(w_\alpha)| \geq \ell_\alpha/L$. And as a consequence, $\xi_\alpha + \xi_\beta \leq \ell_\alpha/(3L) + \ell_\beta/(3L) \leq 2\ell_\alpha/(3L) < |u(w_\beta) - u(w_\alpha)|$.

Lemma 5.5. For every segment $pq \Subset \Omega$ and every $\delta > 0$, there exists a function $u_{pq}^\delta : pq \rightarrow \Delta$ which is a $4L$ bi-Lipschitz interpolation of u with the property that $\|u_{pq}^\delta - u\|_{L^\infty(pq)} \leq \delta$.

Lemma 5.6. There exists a sequence $\{\xi_\alpha\}_{\alpha \in \mathbb{N}}$ such that the associated adjusted function $u_{\text{adj}} : \mathcal{Q} \rightarrow \mathbb{R}^2$ is $18L$ bi-Lipschitz and $u_{\text{adj}}(\mathcal{Q}) \subseteq \Delta$.

Before giving the proof of [Lemmas 5.5 and 5.6](#), we show how they enter into the proof of [Proposition 5.1](#).

Proof of Proposition 5.1. To define the searched function $\tilde{v}_\varepsilon : \Omega \setminus \Omega_\varepsilon \rightarrow \Delta \setminus \Delta_\varepsilon$, let first $u_{\text{adj}} : \mathcal{Q} \rightarrow \mathbb{R}^2$ be an adjusted function according with [Lemma 5.6](#), corresponding to the sequence $\{\xi_\alpha\}$. Our strategy will be first to define a suitable piecewise affine and injective function $u'_{\text{adj}} : \mathcal{Q} \rightarrow \Delta$, coinciding with u_{adj} near the vertices w_α , and then to obtain \tilde{v}_ε extending u'_{adj} in the interior of each square making use of [Theorem 2.2](#). We divide the proof in some steps.

Step I. Definition of $u'_{\text{adj}} : \mathcal{Q} \rightarrow \Delta$.

First of all, we define $u'_{\text{adj}} = u_{\text{adj}} = v_\varepsilon$ on $\mathcal{Q} \setminus \mathcal{Q}'$. Then, we consider a generic side $w_\alpha w_\beta \subseteq \mathcal{Q}'$ and define pq the *internal segment* of the side $w_\alpha w_\beta$, that is, p and q are the extremes of the segment $w_\alpha w_\beta \setminus (Z_\alpha \cup Z_\beta)$. Taking now a small constant $\delta = \delta(\alpha, \beta)$, to be fixed later, we set $u'_{\text{adj}} = u_{\text{adj}}$ on $w_\alpha w_\beta \cap (Z_\alpha \cup Z_\beta)$, and $u'_{\text{adj}} = u_{pq}^\delta$ on pq , where u_{pq}^δ is given by [Lemma 5.5](#).

By definition, it is clear that u'_{adj} is a continuous, countably piecewise affine function on \mathcal{Q} . Moreover, since the different constants $\delta(\alpha, \beta)$ can be chosen arbitrarily small, each one independently of the others, and any internal segment pq is compactly supported in Ω , one can clearly assume that $u'_{\text{adj}}(\mathcal{Q}) \subseteq \Delta$. In addition, since u'_{adj} is obtained gluing the $4L$ bi-Lipschitz functions u_{pq}^δ and the $18L$ bi-Lipschitz function u_{adj} , we clearly have that u'_{adj} is $18\sqrt{2}L$ -Lipschitz (but, *a priori*, not bi-Lipschitz and not even injective!). To conclude the proof, we will then show that in fact u'_{adj} is bi-Lipschitz (hence, in particular, injective), and eventually we will extend u'_{adj} to the interior of the squares of the tiling (hence, to the whole $\Omega \setminus \Omega_\varepsilon$).

Let us then fix two points $z, z' \in \mathcal{Q}$. In the next Steps II–IV we will show that, provided that the constants $\delta(\alpha, \beta)$ are chosen small enough,

$$|u'_{\text{adj}}(z) - u'_{\text{adj}}(z')| \geq \frac{1}{72L} |z - z'|. \tag{5.6}$$

We consider separately the different possible reciprocal positions of z and z' .

Step II. The case in which $z \in pq \subseteq w_\alpha w_\beta, z' \notin w_\alpha w_\beta$.

In this case, as observed in Remark 5.4, we know that $|z - z'| \geq \xi_\alpha/L$. Thus, there are two subcases. If z' does not belong to any internal segment (hence, either z' belongs to some cross, or $z' \in \Omega_\varepsilon$), then $u'_{\text{adj}}(z') = u_{\text{adj}}(z')$ and then by Lemma 5.6, provided that we choose

$$\delta(\alpha, \beta) \leq \frac{\min\{\xi_\alpha, \xi_\beta\}}{36L^2}, \tag{5.7}$$

we have

$$\begin{aligned} |u'_{\text{adj}}(z) - u'_{\text{adj}}(z')| &= |u_{pq}^\delta(z) - u_{\text{adj}}(z')| \geq |u_{\text{adj}}(z) - u_{\text{adj}}(z')| - |u_{pq}^\delta(z) - u_{\text{adj}}(z)| \\ &= |u_{\text{adj}}(z) - u_{\text{adj}}(z')| - |u_{pq}^\delta(z) - u(z)| \geq \frac{1}{18L} |z - z'| - \delta(\alpha, \beta) \\ &\geq \frac{1}{18L} |z - z'| - \frac{\xi_\alpha}{36L^2} \geq \frac{1}{36L} |z - z'|, \end{aligned}$$

so that (5.6) is proved.

Consider now the other subcase, namely, when z' belongs to some other internal segment $p'q' \subseteq w_{\alpha'} w_{\beta'}$. In that case, since by construction and (5.7) it is $|z - z'| \geq 36L\delta(\alpha, \beta)$ and $|z - z'| \geq 36L\delta(\alpha', \beta')$, one directly has

$$\begin{aligned} |u'_{\text{adj}}(z) - u'_{\text{adj}}(z')| &= |u_{pq}^\delta(z) - u_{p'q'}^{\delta'}(z')| \geq |u(z) - u(z')| - |u(z) - u_{pq}^\delta(z)| - |u(z') - u_{p'q'}^{\delta'}(z')| \\ &\geq \frac{1}{L} |z - z'| - \delta(\alpha, \beta) - \delta(\alpha', \beta') \geq \frac{17}{18L} |z - z'|, \end{aligned}$$

hence again (5.6) is established.

Step III. The case in which $z \in pq \subseteq w_\alpha w_\beta, z' \in w_\alpha w_\beta$.

The second case is when z still belongs to an internal segment pq contained in the side $w_\alpha w_\beta \subseteq \mathcal{Q}'$, and also z' belongs to the side $w_\alpha w_\beta$. In particular, if also z' is in the internal segment pq then we already know the validity of (5.6) because $u'_{\text{adj}}(z) = u_{pq}^\delta(z)$ and $u'_{\text{adj}}(z') = u_{pq}^\delta(z')$, while u_{pq}^δ is $4L$ bi-Lipschitz. Therefore, we can directly assume that $z' \in w_\alpha p$, being the case $z' \in qw_\beta$ clearly the same.

By Definition 5.3 we know that $u'_{\text{adj}}(z') = u_{\text{adj}}(z')$ lies in the segment $u(w_\alpha)u(p)$, which is a radius of the ball $\mathcal{B}(u(w_\alpha), \xi_\alpha)$. Hence, for any point s outside the same ball, a trivial geometric argument tells us that

$$|s - u_{\text{adj}}(z')| \geq \frac{|s - u(p)| + |u(p) - u_{\text{adj}}(z')|}{3}. \tag{5.8}$$

Notice now that it is not true, in general, that $u'_{\text{adj}}(z) = u_{pq}^\delta(z)$ lies outside the ball $\mathcal{B}(u(w_\alpha), \xi_\alpha)$. However, recalling that u_{pq}^δ is an interpolation of u , by Definition 5.2 we know that $u_{pq}^\delta(z)$ is in a segment whose both extremes are out of the ball. Thus, if $|u_{pq}^\delta(z) - u(w_\alpha)| < \xi_\alpha$, up to possibly decreasing $\delta(\alpha, \beta)$ it is surely true that

$$\xi_\alpha - |u_{pq}^\delta(z) - u(w_\alpha)| \ll |u_{pq}^\delta(z) - u(p)|.$$

Putting this observation together with (5.8) we readily obtain that

$$|u_{pq}^\delta(z) - u_{\text{adj}}(z')| \geq \frac{|u_{pq}^\delta(z) - u(p)| + |u(p) - u_{\text{adj}}(z')|}{4} = \frac{|u_{pq}^\delta(z) - u_{pq}^\delta(p)| + |u_{\text{adj}}(p) - u_{\text{adj}}(z')|}{4},$$

recalling that $u_{\text{adj}}(p) = u_{pq}^\delta(p) = u(p)$ (of course, by selecting $\delta(\alpha, \beta)$ small enough, we could have used any number greater than 3, instead of 4, in the above estimate). Therefore, since u_{pq}^δ is $4L$ bi-Lipschitz while u_{adj} is $18L$ bi-Lipschitz, we readily obtain

$$\begin{aligned} |u'_{\text{adj}}(z) - u'_{\text{adj}}(z')| &= |u_{pq}^\delta(z) - u_{\text{adj}}(z')| \geq \frac{|u_{pq}^\delta(z) - u_{pq}^\delta(p)|}{4} + \frac{|u_{\text{adj}}(p) - u_{\text{adj}}(z')|}{4} \\ &\geq \frac{|z - p|}{16L} + \frac{|p - z'|}{72L} \geq \frac{|z - z'|}{72L}, \end{aligned}$$

recalling that z, p and z' are aligned. Hence, (5.6) is checked once again also in this case.

Step IV. The case in which neither z nor z' are in some internal segment.

Thanks to Step II and Step III and by the symmetry of the inequality (5.6), we are left to consider only the situation where no one between z and z' is inside some internal segment. In other words, both z and z' must be either in $\mathcal{Q} \setminus \mathcal{Q}'$ or in some cross. By the definition of u'_{adj} , this means that $u'_{\text{adj}}(z) = u_{\text{adj}}(z)$ and $u'_{\text{adj}}(z') = u_{\text{adj}}(z')$. And thus, since u_{adj} is $18L$ bi-Lipschitz thanks to Lemma 5.6, the validity of (5.6) is already known. Summarizing, we have shown the validity of (5.6) in any possible case, and this means that the function $u'_{\text{adj}} : \mathcal{Q} \rightarrow \Delta$ is injective and $72L$ bi-Lipschitz.

Step V. Conclusion.

We have now to define the piecewise affine and bi-Lipschitz function $\tilde{v}_\varepsilon : \Omega \setminus \Omega_\varepsilon \rightarrow \Delta \setminus \Delta_\varepsilon$, matching u on $\partial\Omega$ and matching v_ε on $\partial\Omega_\varepsilon$. To do so, consider each square \mathcal{D}_j of the tiling contained in $\Omega \setminus \Omega_\varepsilon$. The function u'_{adj} is $72L$ bi-Lipschitz from $\partial\mathcal{D}_j$ to a subset of Δ , then by Theorem 2.2 it can be continuously extended to a piecewise affine bi-Lipschitz function of the whole square \mathcal{D}_j , with bi-Lipschitz constant $C_3 72^4 L^4$. Define \tilde{v}_ε as the countably piecewise affine function on $\Omega \setminus \Omega_\varepsilon$ which gathers all these extensions on all the squares $\mathcal{D}_j \subseteq \Omega \setminus \Omega_\varepsilon$ of the tiling.

For each square $\mathcal{D}_j \subseteq \Omega \setminus \Omega_\varepsilon$, we clearly have that $\partial(\tilde{v}_\varepsilon(\mathcal{D}_j)) = u'_{\text{adj}}(\partial\mathcal{D}_j)$. This yields that \tilde{v}_ε is injective. Moreover, by continuity it is clear that $\tilde{v}_\varepsilon = u$ on $\partial\Omega$, and by construction $\tilde{v}_\varepsilon = v_\varepsilon$ on $\partial\Omega_\varepsilon$. As a consequence, $\tilde{v}_\varepsilon : \Omega \setminus \Omega_\varepsilon \rightarrow \Delta \setminus \Delta_\varepsilon$ fulfills all our requirements. In particular, one has $C_1 = 72^4 C_3$. \square

Let us now make a simple observation, which will be useful in the sequel.

Remark 5.7. Assume that Ω is a right polygon of side length \bar{r} and that u is \bar{r} -piecewise affine on $\partial\Omega$, according to Definition 3.5. Then, consider the r -polygon Ω_ε given by Proposition 4.1. By the construction of Section 4, it is not restrictive to assume that $\bar{r} \in r\mathbb{N}$, and that Ω_ε is a subset of the r -tiling of Ω . Therefore, we can repeat *verbatim* the construction of Proposition 5.1 using, as tiling, the r -tiling of Ω . Notice that in this case assumption (5.5) is not valid—see the remark right after (5.5)—but in fact if Ω is an \bar{r} -polygon, and u is \bar{r} -piecewise affine on $\partial\Omega$, there is no need for the tiling to use smaller and smaller squares at the boundary. As a consequence, the bi-Lipschitz approximation \tilde{v}_ε provided by Proposition 5.1 is (finitely) piecewise affine instead of countably piecewise affine. Observe that the assumption that u is \bar{r} -piecewise affine on $\partial\Omega$ is essential, because otherwise the map \tilde{v}_ε would not coincide with u on $\partial\Omega$.

To conclude the proof of Theorem 1.1, we then only need to give the proofs of Lemma 5.5 and of Lemma 5.6.

Proof of Lemma 5.5. Let $\rho > 0$ be a small number, to be fixed later. Define then $t_0 = 0, z_0 = p$ and then recursively

$$t_{i+1} := \max\{1 \geq t > t_i : |u(z_i) - u(p + t(q - p))| \leq \rho\}, \quad z_{i+1} := p + t_{i+1}(q - p).$$

In this way, we have selected a finite sequence of points $z_0 = p, z_1, \dots, z_N = q$ in the segment pq , where $N = N(p, q, \rho)$. We can then already define the function u_{pq}^δ by setting, for any $0 \leq i \leq N - 1$ and any $0 \leq t \leq 1$,

$$u_{pq}^\delta(z_i + t(z_{i+1} - z_i)) = u(z_i) + t(u(z_{i+1}) - u(z_i)).$$

Hence, u_{pq}^δ is the interpolation of u associated with the points $\{z_i\}$, according with Definition 5.2. The function u_{pq}^δ is by construction finitely piecewise affine and L -Lipschitz. By the uniform continuity of u in pq it is also clear that the bound $\|u - u_{pq}^\delta\|_{L^\infty(pq)} \leq \delta$ holds true as soon as ρ is small enough. To conclude, we have thus only to check that

$$|u_{pq}^\delta(z) - u_{pq}^\delta(z')| \geq \frac{1}{4L}|z - z'| \tag{5.9}$$

for all z, z' in pq . If both z and z' belong to the same segment $z_i z_{i+1}$, then the estimate is true because u_{pq}^δ is affine on that segment and u is L bi-Lipschitz.

Assume then that $z \in z_i z_{i+1}$ and $z' \in z_j z_{j+1}$ with $j > i$. If $j = i + 1$, that is, z and z' belong to two consecutive segments, then by the definition of the points z_i the angle $u_{pq}^\delta(z)u_{pq}^\delta(\widehat{z_{i+1}})u_{pq}^\delta(z')$ is at least $\pi/3$. Hence,

$$\begin{aligned} |u_{pq}^\delta(z) - u_{pq}^\delta(z')| &\geq \frac{|u_{pq}^\delta(z) - u_{pq}^\delta(z_{i+1})|}{2} + \frac{|u_{pq}^\delta(z_{i+1}) - u_{pq}^\delta(z')|}{2} \\ &= |z - z_{i+1}| \frac{|u(z_i) - u(z_{i+1})|}{2|z_i - z_{i+1}|} + |z_{i+1} - z'| \frac{|u(z_{i+1}) - u(z_{i+2})|}{2|z_{i+1} - z_{i+2}|} \geq \frac{|z - z'|}{2L}, \end{aligned}$$

so that (5.9) is checked.

Instead, let us see what happens if $j > i + 1$. In this case, since $u_{pq}^\delta(z) \in u(z_i)u(z_{i+1})$ and for all $l > i + 1$ one has $u(z_l) \notin \mathcal{B}(u(z_i), \rho) \cup \mathcal{B}(u(z_{i+1}), \rho)$, an immediate geometric argument ensures that $|u_{pq}^\delta(z) - u_{pq}^\delta(z')| \geq \sqrt{3}\rho/2$. As a consequence, we have

$$|u(z_i) - u(z_{j+1})| \leq |u_{pq}^\delta(z) - u_{pq}^\delta(z')| + 2\rho \leq \left(1 + \frac{4}{3}\sqrt{3}\right) |u_{pq}^\delta(z) - u_{pq}^\delta(z')| \leq 4|u_{pq}^\delta(z) - u_{pq}^\delta(z')|,$$

which yields

$$|u_{pq}^\delta(z) - u_{pq}^\delta(z')| \geq \frac{|u(z_i) - u(z_{j+1})|}{4} \geq \frac{|z_i - z_{j+1}|}{4L} \geq \frac{|z - z'|}{4L},$$

hence (5.9) holds true also in this case and we conclude the proof. \square

Proof of Lemma 5.6. Let us take a vertex w_α of the grid \mathcal{Q}' . Take then a constant $\xi_\alpha \leq \ell_\alpha/(3L)$, with $\xi_\alpha = \ell_\alpha/(3L) = r/(3L)$ if $w_\alpha \in \partial\Omega_\varepsilon$, while if $w_\alpha \notin \partial\Omega_\varepsilon$ the inequality can be strict. In particular, it is admissible to ask that for any α one has

$$\xi_\alpha < \frac{r}{2L}. \tag{5.10}$$

Define now ξ_α^i as in Definition 5.3 and, for any $1 \leq i \leq \bar{i}(\alpha)$, let $p_i = w_\alpha + \xi_\alpha^i(w_\alpha^i - w_\alpha)$. If $w_\alpha \in \Omega \setminus \partial\Omega_\varepsilon$, then we have

$$u(w_\alpha)u(p_i) \in \Delta \quad \forall 1 \leq i \leq \bar{i}(\alpha), \tag{5.11}$$

up to possibly decrease the value of ξ_α . Instead, if $w_\alpha \in \partial\Omega_\varepsilon$, then (5.11) is already ensured by (4.4) and (4.3) in Proposition 4.1, without any need of changing ξ_α .

We introduce then the adjusted function u_{adj} of Definition 5.3: to obtain the thesis, we need to check that it fulfills the requirements of Lemma 5.6. Thanks to (5.11), we already know that $u_{\text{adj}} : \mathcal{Q} \rightarrow \Delta$. Hence, all we have to do is to check that

$$\frac{|z - z'|}{18L} \leq |u_{\text{adj}}(z) - u_{\text{adj}}(z')| \leq 18L|z - z'|, \tag{5.12}$$

for all $z, z' \in \mathcal{Q}$. We will do it in some steps.

Step I. For all α , $u_{\text{adj}}^{-1}(\text{clos } \mathcal{B}(u(w_\alpha), \xi_\alpha)) = Z_\alpha$.

We start observing an important property, that is, for any α and for any $z \in \mathcal{Q}$ we have that $|u_{\text{adj}}(z) - u(w_\alpha)| \leq \xi_\alpha$ if and only if $z \in Z_\alpha$. In fact, if $z \in Z_\alpha$ then $z \in w_\alpha p_i$ for some $1 \leq i \leq \bar{i}(\alpha)$, and since u_{adj} is affine in the segment $w_\alpha p_i$, while $|u_{\text{adj}}(p_i) - u(w_\alpha)| = \xi_\alpha$, then of course $|u_{\text{adj}}(z) - u(w_\alpha)| \leq \xi_\alpha$.

On the other hand, assume that $z \notin Z_\alpha$: we have to show that $|u_{\text{adj}}(z) - u(w_\alpha)| > \xi_\alpha$. If $z \in w_\alpha w_\alpha^i$ for some $1 \leq i \leq \bar{i}(\alpha)$, then there are three possibilities. First, if $w_\alpha w_\alpha^i \subset \mathcal{Q} \setminus \mathcal{Q}'$, then $u_{\text{adj}} = v_\varepsilon$ is affine on the side $w_\alpha w_\alpha^i$, so the claim is trivial. Second, if $w_\alpha w_\alpha^i \subset \mathcal{Q}'$ and z belongs to the cross Z_β associated to the vertex $w_\beta = w_\alpha^i$, then again the claim is immediate since $u_{\text{adj}}(z)$ belongs to the ball $\mathcal{B}(u(w_\beta), \xi_\beta)$, which does not intersect $\mathcal{B}(u(w_\alpha), \xi_\alpha)$ by Remark 5.4. Lastly, if $w_\alpha w_\alpha^i \subset \mathcal{Q}'$ and $z \notin Z_\beta$, then $u_{\text{adj}}(z) = u(z)$, thus the claim is again obvious by the definition of ξ_α^i .

To conclude the step, we have to consider a point $z \notin Z_\alpha$ which does not belong to any side of \mathcal{Q} starting at w_α . We have again to distinguish some possible cases. If z belongs to the cross Z_β for some β , then again the claim follows by the fact that $\mathcal{B}(u(w_\alpha), \xi_\alpha) \cap \mathcal{B}(u(w_\beta), \xi_\beta) = \emptyset$. If z does not belong to any cross and $z \in \mathcal{Q}'$, then $u_{\text{adj}}(z) = u(z)$ so the claim follows because, using the bi-Lipschitz property of u and the fact that $\xi_\alpha \leq \ell_\alpha / (3L)$, we have

$$u(z) \in \mathcal{B}(u(w_\alpha), \xi_\alpha) \implies |z - w_\alpha| \leq \frac{\ell_\alpha}{3},$$

which is impossible because $|z - w_\alpha| > \ell_\alpha$. Finally, consider the case when $z \in \mathcal{Q} \setminus \mathcal{Q}'$. In this case, we surely have $|z - w_\alpha| \geq r$ by construction, thus by (4.4) and (5.10) we get

$$\begin{aligned} |u_{\text{adj}}(z) - u(w_\alpha)| &= |v_\varepsilon(z) - u(w_\alpha)| \geq |u(z) - u(w_\alpha)| - |u(z) - v_\varepsilon(z)| \\ &\geq \frac{|z - w_\alpha|}{L} - \frac{\sqrt{2}r}{6L^3} \geq \frac{r}{2L} > \xi_\alpha, \end{aligned}$$

thus the first step is concluded.

Now, taken two points $z, z' \in \mathcal{Q}$, we have to show the validity of (5.12).

Step II. Validity of (5.12) if $z, z' \in Z_\alpha$.

Let us first suppose that both z and z' belong to the same cross Z_α . By construction, u_{adj} is L bi-Lipschitz on each segment $w_\alpha p_i$, hence to show (5.12) we can assume without loss of generality that $z \in w_\alpha p_1$ and $z' \in w_\alpha p_2$. Therefore, on one side we have

$$\begin{aligned} |u_{\text{adj}}(z) - u_{\text{adj}}(z')| &\leq |u_{\text{adj}}(z) - u_{\text{adj}}(w_\alpha)| + |u_{\text{adj}}(w_\alpha) - u_{\text{adj}}(z')| \leq L(|z - w_\alpha| + |w_\alpha - z'|) \\ &\leq \sqrt{2}L|z - z'|. \end{aligned}$$

On the other side, to estimate $|u_{\text{adj}}(z) - u_{\text{adj}}(z')|$ from below, assume without loss of generality that $|u_{\text{adj}}(w_\alpha) - u_{\text{adj}}(z)| \leq |u_{\text{adj}}(w_\alpha) - u_{\text{adj}}(z')|$, and define $z'' \in w_\alpha z'$ so that

$$|u_{\text{adj}}(w_\alpha) - u_{\text{adj}}(z)| = |u_{\text{adj}}(w_\alpha) - u_{\text{adj}}(z'')|.$$

Since the triangle $u_{\text{adj}}(w_\alpha)u_{\text{adj}}(z)u_{\text{adj}}(z'')$ is isosceles, then

$$u_{\text{adj}}(z)u_{\text{adj}}(\widehat{z''})u_{\text{adj}}(z') \geq \frac{\pi}{2}. \tag{5.13}$$

Moreover, we claim that

$$\frac{|u_{\text{adj}}(z) - u_{\text{adj}}(z'')|}{|z - z''|} \geq \frac{1}{2L}. \tag{5.14}$$

Indeed, if both $w_\alpha w_\alpha^1$ and $w_\alpha w_\alpha^2$ belong to \mathcal{Q}' , then by definition

$$\frac{|u_{\text{adj}}(z) - u_{\text{adj}}(z'')|}{|z - z''|} = \frac{|u_{\text{adj}}(p_1) - u_{\text{adj}}(p_2)|}{|p_1 - p_2|} = \frac{|u(p_1) - u(p_2)|}{|p_1 - p_2|} \geq \frac{1}{L},$$

so (5.14) holds true. Conversely, if both $w_\alpha w_\alpha^1$ and $w_\alpha w_\alpha^2$ belong to $\mathcal{Q} \setminus \mathcal{Q}'$, then since v_ε is $L + \varepsilon$ bi-Lipschitz we have

$$\frac{|u_{\text{adj}}(z) - u_{\text{adj}}(z'')|}{|z - z''|} = \frac{|u_{\text{adj}}(p_1) - u_{\text{adj}}(p_2)|}{|p_1 - p_2|} = \frac{|v_\varepsilon(p_1) - v_\varepsilon(p_2)|}{|p_1 - p_2|} \geq \frac{1}{L + \varepsilon},$$

so again (5.14) holds true. Finally, assume that $w_\alpha w_\alpha^1 \subset \mathcal{Q}'$ while $w_\alpha w_\alpha^2 \subset \mathcal{Q} \setminus \mathcal{Q}'$ (the case of $w_\alpha w_\alpha^1 \subset \mathcal{Q} \setminus \mathcal{Q}'$ and $w_\alpha w_\alpha^2 \subset \mathcal{Q}'$ being completely equivalent). In this case, it must clearly be $w_\alpha \in \partial\Omega_\varepsilon$, hence by Remark 5.4 we know

that $|p_1 - w_\alpha|$ and $|p_2 - w_\alpha|$ are both at least $\xi_\alpha/L = r/(3L^2)$, thus $|p_1 - p_2| \geq \sqrt{2}r/(3L^2)$. Therefore, recalling again (4.4), we have

$$\begin{aligned} \frac{|u_{\text{adj}}(z) - u_{\text{adj}}(z'')|}{|z - z''|} &= \frac{|u_{\text{adj}}(p_1) - u_{\text{adj}}(p_2)|}{|p_1 - p_2|} = \frac{|u(p_1) - v_\varepsilon(p_2)|}{|p_1 - p_2|} \\ &\geq \frac{|u(p_1) - u(p_2)|}{|p_1 - p_2|} - \frac{|u(p_2) - v_\varepsilon(p_2)|}{|p_1 - p_2|} \geq \frac{1}{L} - \frac{\sqrt{2}r/(6L^3)}{\sqrt{2}r/(3L^2)} = \frac{1}{2L}, \end{aligned}$$

thus (5.14) has been finally checked in all the possible cases. This inequality, together with (5.13) and again with the fact that u_{adj} is L bi-Lipschitz on the segment $z'z'' \subseteq w_\alpha p_2$, yields

$$\begin{aligned} |u_{\text{adj}}(z) - u_{\text{adj}}(z')| &\geq \frac{\sqrt{2}}{2} (|u_{\text{adj}}(z) - u_{\text{adj}}(z'')| + |u_{\text{adj}}(z'') - u_{\text{adj}}(z')|) \\ &\geq \frac{\sqrt{2}}{2} \left(\frac{|z - z''|}{2L} + \frac{|z'' - z'|}{L} \right) \geq \frac{\sqrt{2}}{4L} |z - z'|. \end{aligned}$$

Summarizing, under the assumptions of this step

$$\frac{\sqrt{2}}{4L} |z - z'| \leq |u_{\text{adj}}(z) - u_{\text{adj}}(z')| \leq \sqrt{2}L |z - z'|. \tag{5.15}$$

Therefore, (5.12) is shown and this step is concluded.

Step III. Validity of (5.12) if for all α one has $z, z' \notin \text{int } Z_\alpha$.

Consider now the situation when neither z nor z' belong to the interior of any cross. In this case, we have that $u_{\text{adj}}(z) = u(z)$ if $z \in Q'$, while $u_{\text{adj}}(z) = v_\varepsilon(z)$ if $z \in Q \setminus Q'$, and the same holds for z' . Since u is L bi-Lipschitz while v_ε is $L + \varepsilon$ bi-Lipschitz, the validity of (5.12) is obvious if both $z, z' \in Q'$, as well as if both $z, z' \in Q \setminus Q'$. Therefore, we can just concentrate on the case in which $z \in Q', z' \in Q \setminus Q'$.

In this case, the main observation is that $|z - z'| \geq \sqrt{2}r/(3L^2)$, since both z and z' must be at distance at least $r/(3L^2)$ from any vertex $w_\alpha \in \partial\Omega_\varepsilon$, because they do not belong to any cross Z_α . As a consequence, again by (4.4) we get

$$\begin{aligned} |u_{\text{adj}}(z) - u_{\text{adj}}(z')| &= |u(z) - v_\varepsilon(z')| \geq |u(z) - u(z')| - |u(z') - v_\varepsilon(z')| \\ &\geq \frac{|z - z'|}{L} - \frac{\sqrt{2}r}{6L^3} \geq \frac{|z - z'|}{2L}, \end{aligned}$$

while

$$\begin{aligned} |u_{\text{adj}}(z) - u_{\text{adj}}(z')| &= |u(z) - v_\varepsilon(z')| \leq |u(z) - u(z')| + |u(z') - v_\varepsilon(z')| \\ &\leq L|z - z'| + \frac{\sqrt{2}r}{6L^3} \leq \left(L + \frac{1}{2L} \right) |z - z'|, \end{aligned}$$

thus also in this case (5.12) is proven (keep in mind that, since u is a L bi-Lipschitz map, then of course $L \geq 1$!). In particular, under the assumptions of this step one has

$$\frac{|z - z'|}{2L} \leq |u_{\text{adj}}(z) - u_{\text{adj}}(z')| \leq \frac{3}{2}L |z - z'|. \tag{5.16}$$

Step IV. Validity of (5.12) if $z \in Z_\alpha$ and for all β one has $z' \notin \text{int } Z_\beta$.

We pass now to consider the case when z belongs to some cross Z_α , while z' does not belong to the interior of any cross. In particular, we can assume that $z \in w_\alpha p_1$. To get the above estimate in (5.12), it is enough to make a trivial geometric observation, namely, that there exists $1 \leq i \leq \bar{i}(\alpha)$ such that

$$|z - z'| \geq \frac{\sqrt{2}}{2} (|z - p_i| + |p_i - z'|),$$

not necessarily with $i = 1$. As a consequence, we can use the estimate (5.15) of Step II for the points z and p_i —which both belong to Z_α —and the estimate (5.16) of Step III for the points p_i and z' —none of which belongs to the interior of some Z_β —to get

$$\begin{aligned} |u_{\text{adj}}(z) - u_{\text{adj}}(z')| &\leq |u_{\text{adj}}(z) - u_{\text{adj}}(p_i)| + |u_{\text{adj}}(p_i) - u_{\text{adj}}(z')| \leq \sqrt{2}L|z - p_i| + \frac{3}{2}L|p_i - z'| \\ &\leq \frac{3}{2}\sqrt{2}L|z - z'|. \end{aligned}$$

On the other hand, to get the below estimate in (5.12), let us recall that by Step I we have

$$u_{\text{adj}}(z) \in \text{clos } \mathcal{B}(u(w_\alpha), \xi_\alpha), \quad u_{\text{adj}}(z') \notin \mathcal{B}(u(w_\alpha), \xi_\alpha). \tag{5.17}$$

Since $u_{\text{adj}}(z)$ belongs to the radius $u(w_\alpha)u_{\text{adj}}(p_1)$, then an immediate geometric argument from (5.17) implies, as already observed in (5.8), that

$$|u_{\text{adj}}(z) - u_{\text{adj}}(z')| \geq \frac{|u_{\text{adj}}(z) - u_{\text{adj}}(p_1)| + |u_{\text{adj}}(p_1) - u_{\text{adj}}(z')|}{3}. \tag{5.18}$$

Thus, using the L bi-Lipschitz property of u_{adj} in the segment $w_\alpha p_1$, and the estimate (5.16) of Step III for p_1 and z' , we get

$$|u_{\text{adj}}(z) - u_{\text{adj}}(z')| \geq \frac{|z - p_1|}{3L} + \frac{|p_1 - z'|}{6L} \geq \frac{|z - z'|}{6L}.$$

Summarizing, under the assumptions of this step we have

$$\frac{|z - z'|}{6L} \leq |u_{\text{adj}}(z) - u_{\text{adj}}(z')| \leq \frac{3}{2}\sqrt{2}L|z - z'|, \tag{5.19}$$

hence in particular (5.12) is again checked.

Step V. Validity of (5.12) if $z \in Z_\alpha$ and $z' \in Z_\beta$.

The last situation which is left to consider is when z and z' belong to two different crosses. This situation will be very similar to that of Step IV. Indeed, for the above estimate in (5.12) we can again start observing that for some $1 \leq i \leq \bar{i}(\alpha)$ it must be

$$|z - z'| \geq \frac{\sqrt{2}}{2}(|z - p_i| + |p_i - z'|).$$

Then, we use the estimate (5.15) of Step II for the points $z, p_i \in Z_\alpha$, and the estimate (5.19) of Step IV for the points $z' \in Z_\beta$ and p_i —which does not belong to the interior of any cross—getting

$$\begin{aligned} |u_{\text{adj}}(z) - u_{\text{adj}}(z')| &\leq |u_{\text{adj}}(z) - u_{\text{adj}}(p_i)| + |u_{\text{adj}}(p_i) - u_{\text{adj}}(z')| \\ &\leq \sqrt{2}L|z - p_i| + \frac{3}{2}\sqrt{2}L|p_i - z'| \leq 3L|z - z'|. \end{aligned}$$

Finally, to find the below estimate in (5.12) we notice again that (5.18) holds true, and we use the L bi-Lipschitz property of u_{adj} in $w_\alpha p_1$ and the estimate (5.19) of Step IV for p_1 and z' , obtaining

$$|u_{\text{adj}}(z) - u_{\text{adj}}(z')| \geq \frac{|z - p_1|}{3L} + \frac{|p_1 - z'|}{18L} \geq \frac{|z - z'|}{18L}.$$

Thus, we have finally checked (5.12) in all the possible cases and the proof is concluded. \square

6. Finitely piecewise affine approximation on polygonal domains

In this last section we give a proof of Theorem 1.2. In fact, the proof is quite short, since it is just a simple adaptation of the arguments of Section 5.

Proof of Theorem 1.2. First of all, assume that Ω is an \bar{r} -right polygon and that u is \bar{r} -piecewise affine on $\partial\Omega$ according to Definition 3.5. Then, as already underlined in Remark 5.7, we can slightly modify the proofs of Proposition 4.1 and Proposition 5.1 to get what follows. First of all, there exist some r such that $\bar{r} \in r\mathbb{N}$, an r -right polygon $\Omega_\varepsilon \subseteq \Omega$ which is part of the r -tiling of Ω , and an $L + \varepsilon$ bi-Lipschitz and piecewise affine function $v_\varepsilon : \Omega_\varepsilon \rightarrow \mathbb{R}^2$ for which (4.1), (4.2), (4.3) and (4.4) hold. Moreover, there exists also a finitely piecewise affine map $\tilde{v}_\varepsilon : \Omega \setminus \Omega_\varepsilon \rightarrow \Delta \setminus \Delta_\varepsilon$ which is $C_1 L^4$ bi-Lipschitz and which coincides with u on $\partial\Omega$ and with v_ε on $\partial\Omega_\varepsilon$. Therefore, gluing v_ε and \tilde{v}_ε exactly as in the proof of Theorem 1.1, we immediately get the required $C_1 L^4$ bi-Lipschitz and (finitely) piecewise affine approximation of u .

Consider now the general situation of a polygon Ω with a map u which is piecewise affine on $\partial\Omega$. Of course, there exist a right polygon $\widehat{\Omega}$ and a (finitely) piecewise affine and bi-Lipschitz map $\Phi : \Omega \rightarrow \widehat{\Omega}$, having bi-Lipschitz constant $C = C(\Omega)$. The map $u \circ \Phi^{-1}$ is a CL bi-Lipschitz map from the right polygon $\widehat{\Omega}$ to Δ , which is piecewise affine on the boundary. Then, we can apply the first part of the proof to get an approximation $v : \widehat{\Omega} \rightarrow \Delta$ which is finitely piecewise affine and $C_1 C^4 L^4$ bi-Lipschitz. Finally, $v \circ \Phi : \Omega \rightarrow \Delta$ is a $C_1 C^5 L^4$ bi-Lipschitz approximation of u as desired. Thus, the proof is concluded by setting $C'(\Omega) = C^5$. \square

Remark 6.1. Observe that the (best) constant $C'(\Omega)$ depends on the geometric features of Ω , such as the minimum and the maximum angles of its boundary. However, by the construction above one has that $C'(\Omega) = 1$ whenever Ω is a right polygon.

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