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# Permeability through a perforated domain for the incompressible 2D Euler equations 

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#### Abstract

We investigate the influence of a perforated domain on the 2D Euler equations. Small inclusions of size $\varepsilon$ are uniformly distributed on the unit segment or a rectangle, and the fluid fills the exterior. These inclusions are at least separated by a distance $\varepsilon^{\alpha}$ and we prove that for $\alpha$ small enough (namely, less than 2 in the case of the segment, and less than 1 in the case of the square), the limit behavior of the ideal fluid does not feel the effect of the perforated domain at leading order when $\varepsilon \rightarrow 0$.


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## 1. Presentation

The homogenization of the Stokes operator and of the incompressible Navier-Stokes equations in a porous medium is by now a very classical problem [29,31,2,26]. Recently, more attention was given to the homogenization of other fluid models such as the compressible Navier-Stokes system [10,24], the acoustic system [11,4] and the incompressible Euler system [27,21,16].

The goal of this paper is to study the effect of small inclusions of size $\varepsilon$ on the behavior of an ideal fluid governed by the 2D Euler system. One can expect that for very small holes which are well separated, the effect of the inclusions disappears at the limit. This is in the spirit of [8,3] where critical sizes of the holes were studied.

### 1.1. The perforated domain

Let $\mathcal{K}$ be a smooth simply-connected compact set of $\mathbb{R}^{2}$, which is the shape of the inclusions. More precisely, we assume that $\partial \mathcal{K}$ is a $\mathcal{C}^{1,1}$ Jordan curve. Without loss of generality, we assume that $0 \in \mathcal{K} \subset(-1,1)^{2}$. Let $\alpha>0$ and

[^0]

Fig. 1. Geometrical settings.
$\mu \in[0,1]$ be two parameters which represent how the inclusions fill the square $[0,1]^{2}$. For $i \geqslant 1, j \geqslant 1$ and $\varepsilon>0$, we define

$$
\begin{equation*}
z_{i, j}^{\varepsilon, \alpha}:=\left(\varepsilon+2(i-1)\left(\varepsilon+\varepsilon^{\alpha}\right), \varepsilon+2(j-1)\left(\varepsilon+\varepsilon^{\alpha}\right)\right)=(\varepsilon, \varepsilon)+2\left(\varepsilon+\varepsilon^{\alpha}\right)(i-1, j-1) \tag{1.1}
\end{equation*}
$$

the centers of the inclusions of size $\varepsilon$ :

$$
\begin{equation*}
\mathcal{K}_{i, j}^{\varepsilon, \alpha}:=z_{i, j}^{\varepsilon, \alpha}+\varepsilon \mathcal{K} . \tag{1.2}
\end{equation*}
$$

The geometrical setting is represented in Fig. 1 (in the case where $\mathcal{K}=\bar{B}(0,1)$ ).
Let $N_{\varepsilon, \alpha}=\left[\frac{1+2 \varepsilon^{\alpha}}{2\left(\varepsilon+\varepsilon^{\alpha}\right)}\right]$ (where $[x]$ denotes the integer part of $x$ ) be the number of inclusions, of size $\varepsilon$ and separated by $2 \varepsilon^{\alpha}$, that we can distribute on the unit segment [0, 1] (see Fig. 1(a)). In vertical axis, we assume that there are $\left[\left(N_{\varepsilon, \alpha}\right)^{\mu}\right]$ inclusions of size $\varepsilon$ at distance $2 \varepsilon^{\alpha}$ (with $\mu \in[0,1]$ ). For shorter, we denote by $n_{1}$ the number of inclusions along the horizontal axis and $n_{2}$ those on the vertical axis:

$$
n_{1}:=N_{\varepsilon, \alpha} \quad \text { and } \quad n_{2}:=\left[\left(N_{\varepsilon, \alpha}\right)^{\mu}\right] .
$$

We denote by $\mathcal{R}_{\varepsilon, \alpha, \mu}$ the rectangle containing all the inclusions:

$$
\begin{equation*}
\mathcal{R}_{\varepsilon, \alpha, \mu}=\left[0,2\left(\varepsilon+\varepsilon^{\alpha}\right) n_{1}-2 \varepsilon^{\alpha}\right] \times\left[0,2\left(\varepsilon+\varepsilon^{\alpha}\right) n_{2}-2 \varepsilon^{\alpha}\right] . \tag{1.3}
\end{equation*}
$$

Then the total number of inclusions in $\mathcal{R}_{\varepsilon, \alpha, \mu}$ equals

$$
\begin{equation*}
n_{1} n_{2} \leqslant\left(N_{\varepsilon, \alpha}\right)^{1+\mu} \leqslant\left(\frac{1+2 \varepsilon^{\alpha}}{2\left(\varepsilon+\varepsilon^{\alpha}\right)}\right)^{1+\mu} \leqslant \frac{1}{\left(\varepsilon+\varepsilon^{\alpha}\right)^{1+\mu}}, \tag{1.4}
\end{equation*}
$$

as soon as $\varepsilon$ is small enough.
We notice that if $\mu=0$, then $n_{2}=1$ and there are just inclusions along a line. If $\mu=1$, then there are as many inclusions in both directions and in this case the rectangle $\mathcal{R}_{\varepsilon, \alpha, \mu}$ is almost the square $[0,1]^{2}$.

We define $\Omega^{\varepsilon, \alpha, \mu}$ the domain

$$
\begin{equation*}
\Omega^{\varepsilon}=\Omega^{\varepsilon, \alpha, \mu}:=\mathbb{R}^{2} \backslash\left(\bigcup_{i=1}^{n_{1}} \bigcup_{j=1}^{n_{2}} \mathcal{K}_{i, j}^{\varepsilon, \alpha}\right) . \tag{1.5}
\end{equation*}
$$

Since the parameters $\alpha$ and $\mu$ are fixed and we are interested in the limit $\varepsilon \rightarrow 0$, the indices $\alpha, \mu$ will often be omitted in the notation for shorter.

### 1.2. The Euler equations

Let $u^{\varepsilon}=u^{\varepsilon}(t, x)=\left(u_{1}^{\varepsilon}(t, x), u_{2}^{\varepsilon}(t, x)\right)$ be the velocity of an incompressible, ideal flow in $\Omega^{\varepsilon}$. The evolution is governed by the Euler equations

$$
\begin{cases}\partial_{t} u^{\varepsilon}+u^{\varepsilon} \cdot \nabla u^{\varepsilon}=-\nabla p^{\varepsilon} & \text { in }(0, \infty) \times \Omega^{\varepsilon},  \tag{1.6}\\ \operatorname{div} u^{\varepsilon}=0 & \text { in }[0, \infty) \times \Omega^{\varepsilon}, \\ u^{\varepsilon} \cdot \mathbf{n}=0 & \text { in }[0, \infty) \times \partial \Omega^{\varepsilon}, \\ \lim _{n \mid \rightarrow \infty}\left|u^{\varepsilon}(t, x)\right|=0 & \text { for } t \in[0, \infty), \\ u^{\varepsilon}(0, x)=u_{0}^{\varepsilon}(x) & \text { in } \Omega^{\varepsilon} .\end{cases}
$$

Let $\omega^{\varepsilon}$ be the vorticity defined by

$$
\omega^{\varepsilon}:=\operatorname{curl} u^{\varepsilon}=\partial_{1} u_{2}^{\varepsilon}-\partial_{2} u_{1}^{\varepsilon} .
$$

The velocity and the vorticity satisfy

$$
\begin{cases}\operatorname{div} u^{\varepsilon}=0 & \text { in }[0, \infty) \times \Omega^{\varepsilon}  \tag{1.7}\\ \operatorname{curl} u^{\varepsilon}=\omega^{\varepsilon} & \text { in }[0, \infty) \times \Omega^{\varepsilon} \\ u^{\varepsilon} \cdot \mathbf{n}=0 & \text { in }[0, \infty) \times \partial \Omega^{\varepsilon} \\ \lim _{|x| \rightarrow \infty}\left|u^{\varepsilon}(t, x)\right|=0 & \text { for } t \in[0, \infty)\end{cases}
$$

The initial velocity in (1.6) has to verify:

$$
\begin{equation*}
\operatorname{div} u_{0}^{\varepsilon}=0 \quad \text { in } \Omega^{\varepsilon}, \quad \lim _{|x| \rightarrow \infty}\left|u_{0}^{\varepsilon}(x)\right|=0, \quad u_{0}^{\varepsilon} \cdot \mathbf{n}=0 \quad \text { on } \partial \Omega^{\varepsilon} . \tag{1.8}
\end{equation*}
$$

As our domain depends on $\varepsilon$, it is standard to give the initial data in terms of an initial vorticity independent of $\varepsilon$. Physically, it is relevant to consider the following setting: we assume that the fluid is steady $u_{0}^{\varepsilon} \equiv 0$ at time $t<0$ (then $\omega^{\varepsilon}(0, \cdot) \equiv 0$ and $u_{0}^{\varepsilon}$ has zero circulation around each inclusion) and at time $t=0$ we add, by an exterior force, a vorticity $\omega_{0}$. More precisely, let $\omega_{0} \in \mathcal{C}_{c}^{\infty}\left(\mathbb{R}^{2}\right)$, then we infer that there exists a unique vector field $u_{0}^{\varepsilon}$ verifying (1.8) which has zero circulation around each inclusion and whose curl is: $\operatorname{curl} u_{0}^{\varepsilon}=\omega_{0}^{\varepsilon}:=\left.\omega_{0}\right|_{\Omega^{\varepsilon}}$ (see e.g. [18,20]).

Then, the vorticity allows us to give an initial condition independent of $\varepsilon$, but the main advantage of the vorticity for the 2D Euler equations comes from the nature of the equations governing the vorticity:

$$
\begin{cases}\partial_{t} \omega^{\varepsilon}+u^{\varepsilon} \cdot \nabla \omega^{\varepsilon}=0 & \text { in }(0, \infty) \times \Omega^{\varepsilon},  \tag{1.9}\\ \operatorname{div} u^{\varepsilon}=0 & \text { in }[0, \infty) \times \Omega^{\varepsilon}, \\ u^{\varepsilon} \cdot \mathbf{n}=0 & \text { in }[0, \infty) \times \partial \Omega^{\varepsilon}, \\ \operatorname{curl} u^{\varepsilon}=\omega^{\varepsilon} & \text { in }[0, \infty) \times \Omega^{\varepsilon}, \\ \lim _{|x| \rightarrow \infty}\left|u^{\varepsilon}(t, x)\right|=0 & \text { for } t \in[0, \infty), \\ \oint_{\partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}} u^{\varepsilon}(0, s) \cdot \tau \text { d } s=0 & \text { for all } i, j, \\ \omega^{\varepsilon}(0, \cdot)=\omega_{0} & \text { in } \Omega^{\varepsilon} .\end{cases}
$$

We can show that the two systems (1.6) and (1.9) are equivalent, but we obtain more properties from the second system because it is a transport equation. Thanks to this structure, for $\omega_{0} \in \mathcal{C}_{c}^{\infty}\left(\mathbb{R}^{2}\right)$, Kikuchi establishes in [18] that there exists a unique global strong solution $u^{\varepsilon}$ of (1.6), such that $\omega^{\varepsilon}$ belongs to $\mathrm{L}^{\infty}\left(\mathbb{R}^{+} ; \mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\Omega^{\varepsilon}\right)\right)$. Actually, for a strong solution $u^{\varepsilon}$, the transport nature of (1.9) implies that:

- the $\mathrm{L}^{p}$ norm of the vorticity is conserved for any $p \in[1, \infty]$ :

$$
\begin{equation*}
\left\|\omega^{\varepsilon}(t, \cdot)\right\|_{L^{p}\left(\Omega^{\varepsilon}\right)}=\left\|\omega_{0}^{\varepsilon}\right\|_{L^{p}\left(\Omega^{\varepsilon}\right)} \leqslant\left\|\omega_{0}\right\|_{\mathrm{L}^{p}\left(\mathbb{R}^{2}\right)}, \quad \forall t \geqslant 0, \quad \forall p \in[1,+\infty] ; \tag{1.10}
\end{equation*}
$$

- the total mass of the vorticity is conserved:

$$
\begin{equation*}
\int_{\Omega^{\varepsilon}} \omega^{\varepsilon}(t, x) \mathrm{d} x=\int_{\Omega^{\varepsilon}} \omega_{0}(x) \mathrm{d} x ; \tag{1.11}
\end{equation*}
$$

- at any time $t \geqslant 0$, the vorticity is compactly supported (but the size of the support can grow);
- the circulation of $u^{\varepsilon}$ around each inclusion is conserved (Kelvin's theorem):

$$
\begin{equation*}
\oint_{\partial \mathcal{K}_{i, j}^{s, \alpha}} u^{\varepsilon}(t, s) \cdot \tau \mathrm{d} s=0, \quad \forall t \geqslant 0, \forall i, j . \tag{1.12}
\end{equation*}
$$

### 1.3. Issue and former results

For $(\alpha, \mu) \in(0, \infty) \times[0,1)$, the complementary of $\Omega^{\varepsilon}$ converges, in the Hausdorff sense, to the unit segment $[0,1] \times\{0\}$ and for $(\alpha, \mu) \in(0, \infty) \times\{1\}$, it converges to the unit square $[0,1]^{2}$. Indeed, we check easily that

$$
d_{H}\left(\bigcup_{j=1}^{n_{2}} \bigcup_{i=1}^{n_{1}} \mathcal{K}_{i, j}^{\varepsilon, \alpha}, \mathcal{R}_{\varepsilon, \alpha, \mu}\right)=\max \left(\sup _{x \in \bigcup_{i, j} \mathcal{K}_{i, j}^{\varepsilon, \alpha}} d\left(x, \mathcal{R}_{\varepsilon, \alpha, \mu}\right), \sup _{x \in \mathcal{R}_{\varepsilon, \alpha, \mu}} d\left(x, \bigcup_{i, j} \mathcal{K}_{i, j}^{\varepsilon, \alpha}\right)\right) \leqslant \max \left(0, \sqrt{2}\left(\varepsilon+\varepsilon^{\alpha}\right)\right)
$$

and

$$
\begin{cases}d_{H}\left(\mathcal{R}_{\varepsilon, \alpha, 1},[0,1]^{2}\right) \leqslant \max \left(0,2\left(\varepsilon+\varepsilon^{\alpha}\right)\right) & \text { for } \mu=1, \\ d_{H}\left(\mathcal{R}_{\varepsilon, \alpha, \mu},[0,1] \times\{0\}\right) \leqslant \max \left(2\left(\varepsilon+\varepsilon^{\alpha}\right)^{1-\mu}, 2\left(\varepsilon+\varepsilon^{\alpha}\right)\right) & \text { for } \mu \in[0,1)\end{cases}
$$

The issue of this article is to determine the limit of $\left(u^{\varepsilon}, \omega^{\varepsilon}\right)$ when $\varepsilon$ tends to zero, for different values of $\alpha$ and $\mu$, and to compare the limit with the solution in the full plane, or in the exterior of a segment, or in the exterior of a square.

The well-posedness of the Euler equations in the full plane is well known since McGrath [25]. In the exterior of a sharp domain, let us mention that the existence of a global weak-solution to the Euler equations in the exterior of the segment, such that $\omega_{0} \in \mathrm{~L}^{\infty}\left(\mathbb{R}^{+} ; \mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\mathbb{R}^{2} \backslash([0,1] \times\{0\})\right)\right)$, is established in [19]. Such a result is recently extended to the exterior of any connected compact set in [12], for example outside the unit square.

Physically, we can preview that we do not feel the presence of the inclusions for small $\alpha$ (i.e. $\varepsilon^{\alpha} \gg \varepsilon$ ) and for small $\mu$, whereas it should appear a wall for $\mu \in[0,1)$ and $\alpha$ large, and the unit square for $\mu=1$ and $\alpha$ large. Moreover, we can think that the critical $\alpha$ should be a decreasing function in terms of $\mu$.

The study of the Euler equations in the exterior of one small obstacle was initiated by Iftimie, Lopes Filho and Nussenzveig Lopes in [16]. In that paper, the authors consider only one obstacle which shrinks homotetically to a point, and indeed, if the initial circulation is zero, then their result reads as the solution $\left(u^{\varepsilon}, \omega^{\varepsilon}\right)$ converges to the solution in the full plane. Later Lopes Filho has treated in [22] the case of several obstacles in a bounded domain when one of them shrinks to a point. The final result is the same: if initially the circulation is zero, we do not feel the presence of the point at the limit. Finally the last generalization can be found in [20] where an infinite number of obstacles is considered. We quote here the theorem in the case where all the initial circulations are equal to zero:

Theorem 1.1. Let $\omega_{0} \in \mathcal{C}_{c}^{\infty}\left(\mathbb{R}^{2}\right)$. Let us also fix $R_{0}>0$ such that $\operatorname{supp} \omega_{0} \subset B\left(0, R_{0}\right)$. For any sequences $\left\{z_{i}^{k}\right\}_{i=1 \cdots n_{k}} \in$ $B\left(0, R_{0}\right)^{n_{k}}$, there exist a subsequence, again denoted $k$, and a sequence $\varepsilon_{k} \in \mathbb{R}_{*}^{+}$tending to zero such that the solutions $\left(u^{k}, \omega^{k}\right)$ of (1.9) in

$$
\Omega^{k}:=\mathbb{R}^{2} \backslash\left(\bigcup_{i=1}^{n_{k}} \bar{B}\left(z_{i}^{k}, \varepsilon_{k}\right)\right),
$$

with initial vorticity $\left.\omega_{0}\right|_{\Omega^{k}}$ and initial circulations 0 around the balls, verify
(a) $u^{k} \rightarrow u$ strongly in $\mathrm{L}_{\mathrm{loc}}^{p}\left(\mathbb{R}_{+} \times \mathbb{R}^{2}\right)$ for any $p \in[1,2)$;
(b) $\omega^{k} \rightharpoonup \omega$ weak $*$ in $\mathrm{L}^{\infty}\left(\mathbb{R}_{+} ; \mathrm{L}^{q}\left(\mathbb{R}^{2}\right)\right.$ ) for any $q \in[1, \infty]$;
(c) the limit pair $(u, \omega)$ is the unique solution of the Euler equations in the full plane, with initial vorticity $\omega_{0}$.

In that theorem, we have extended $u^{k}$ and $\omega^{k}$ by zero in $\left(\Omega^{k}\right)^{c}$. Therefore, we could consider $z_{i, j}^{\varepsilon}$ as in our configuration (see the first subsection), however there is no control on $\varepsilon_{k}$ in terms of the distance between the points. The size of the ball can be very small compare to this distance (i.e. $\alpha \ll 1$ ), and the goal of this article is to get this control. Let us mention that all the works cited before [12,16,19,20,22] consider also non-zero initial circulations, and
in particular around small obstacles [16,20,22] the authors find a reminiscent term which appears from the vanishing obstacles. Removing the assumption of zero initial circulations in the present work could be the subject of a future research.

Before stating our result, we also mention a work with the opposite result. The third author and Lions have treated in [21] a case which is close to our configuration with $(\alpha, \mu)=(1,1)$. We write "close" because that article considers bounded domains [ 0,1$]^{2} \backslash\left(\bigcup_{j=1}^{n_{2}} \bigcup_{i=1}^{n_{1}} \mathcal{K}_{i, j}^{\varepsilon, \alpha}\right)$ and the initial condition is not exactly as ours. Nevertheless, in the spirit of homogenization and two scale convergence, the authors prove that the limit solution is not the Euler solution in the unit square but rather a two-scale system that describes the limit behavior. In particular the limit solution depends on the shape of the obstacles.

### 1.4. Result

As we can expect, our main result reads as for any $\mu$ there exists a critical $\alpha_{c}(\mu)$, such that for any $\alpha$ less than $\alpha_{c}(\mu)$, the perforated domain is perfectly permeable, i.e. the presence of the inclusions does not perturb the behavior of a perfect fluid. More precisely:

Theorem 1.2. Let $\Omega^{\varepsilon}$ defined in (1.1)-(1.5), then for all $\mu \in[0,1]$, we define

$$
\alpha_{c}(\mu)=2-\mu
$$

Let $\omega_{0}$ be a smooth function compactly supported in $\mathbb{R}^{2}, \alpha \in\left(0, \alpha_{c}(\mu)\right)$ and any sequence $\varepsilon \rightarrow 0$, then the solutions $\left(u^{\varepsilon}, \omega^{\varepsilon}\right)$ of (1.9) in $\Omega^{\varepsilon}$ with initial vorticity $\left.\omega_{0}\right|_{\Omega^{\varepsilon}}$ and initial circulations 0 around the inclusions, verify:
(a) $u^{\varepsilon} \rightarrow u$ strongly in $\mathrm{L}_{\mathrm{loc}}^{2}\left(\mathbb{R}^{+} \times \mathbb{R}^{2}\right)$;
(b) $\omega^{\varepsilon} \rightharpoonup \omega$ weak $*$ in $\mathrm{L}^{\infty}\left(\mathbb{R}^{+} \times \mathbb{R}^{2}\right)$;
(c) the limit pair $(u, \omega)$ is the unique global solution to the Euler equations in the full plane $\mathbb{R}^{2}$, with initial vorticity $\omega_{0}$.

Again, in the previous theorem and in all the sequel, we extend $\left(u^{\varepsilon}, \omega^{\varepsilon}\right)$ by zero inside the inclusions.
We note that the function $\mu \mapsto \alpha_{c}(\mu)$ is continuous, decreasing, positive, such that $\alpha_{c}(0)=2$ and $\alpha_{c}(1)=1$. Finally, this result does not depend on the shape $\mathcal{K}$ of the inclusions. This result can be extended to the case where the inclusions have not the same shape (see Remark 2.3).

Even if zero circulation are treated in the previous theorem, the goal here is to investigate the effect of the ratio distance/size of the inclusions, an important parameter not controlled in [20]. Such a question is investigated by the first author on some elliptic problems such that the Laplace and Navier equations in [7,5,6], and we emphasize that the Euler equations are linked to such a problem. Indeed we already have a good control of the $L^{p}$ norm of the vorticity, and the velocity can be deduced from the vorticity by a kernel of the type $\nabla^{\perp} \Delta^{-1}$.

We note that a possible extension can be made considering a less regular $\omega_{0}$, belonging to the space $L^{1} \cap L^{p}\left(\mathbb{R}^{2}\right)$ for some $p>2$.

An important future work will be to prove that this $\alpha_{c}(\mu)$ is indeed critical, in the sense that we note a nonnegligible effect from the inclusions if $\alpha \geqslant \alpha_{c}(\mu)$. In fact, the result in [21] is already a first hint that it is indeed the case at least in the case $\mu=1$ and for any type of obstacles.

Our result should be compared with critical values obtained with other equations. The study of the behavior of a flow through a porous medium has a long story in the homogenization framework. The most common setting is to consider a bounded domain $\Omega$ containing many tiny solid obstacles, distributed in each direction. For the Stokes equations with Dirichlet boundary condition, Cioranescu and Murat considered the case where the ratio $R^{\varepsilon}:=$ (size of the inclusions) $/$ (distance) is $e^{-1 / \varepsilon^{2}} / \varepsilon$, and they obtained in [8] that the limit equation contains an additional term due to the holes. Concerning Stokes and Navier-Stokes, Allaire extensively treated the previous problem, for e.g. in [3] he showed that if $R^{\varepsilon} \ll e^{-1 / \varepsilon^{2}} / \varepsilon$ (the rate of Cioranescu-Murat), the limit is the Stokes system (hence we do not feel the presence of the inclusions). If $R^{\varepsilon} \gg e^{-1 / \varepsilon^{2}} / \varepsilon$, we get the Darcy law (which was well known in the case where the ratio is $\varepsilon / \varepsilon$, see references in [2] and also [13] for different ratios). And if $R^{\varepsilon}=e^{-1 / \varepsilon^{2}} / \varepsilon$, we get the Brinkman type law. Therefore, the above study has treated every case for the viscous problem, and we note that
the critical rate $e^{-1 / \varepsilon^{2}} / \varepsilon$ is very small compared to $\varepsilon / \varepsilon$, which is the rate obtained in the case of the square ( $\mu=1$, $\left.\alpha=\alpha_{c}(1)=1\right)$. Even if the Euler equations are related to the Laplace equation via the stream functions, the inclusions can generate different effects: there is no effect in some regimes for the ideal flow whereas there is for the Stokes equation.

However, an important question is to understand what is the role of the viscosity in the determination of the critical rate (see [27] for more motivation). For a modified Euler equations, Mikelić and Paoli [27] and Lions and Masmoudi [21] consider a bounded domain perforated in both direction where the rate is $\varepsilon / \varepsilon$, and the limit homogenized system takes into account of the inclusions. Our result is complementary of these articles.

There are also many works concerning inclusions distributed on the unit segment (through grids, sieves or porous walls, we refer e.g. to Conca and Sepúlveda [9] and Sánchez-Palenlencia [30]). In this setting, the study of the Stokes and Navier-Stokes system is performed by Allaire [3], where he obtained the similar result than before, except that the critical rate is $e^{-1 / \varepsilon} / \varepsilon$, which is naturally bigger than $e^{-1 / \varepsilon^{2}} / \varepsilon$, but which stays to be very small compared to our rate: $\varepsilon / \varepsilon^{2}\left(\mu=0, \alpha=\alpha_{c}(0)=2\right)$.

### 1.5. Plan of the paper

Thanks to the transport nature of the equation governing the vorticity, we will deduce easily from (1.10) the point (b) of Theorem 1.2 from the Banach-Alaoglu theorem. In the sequel, we keep the notation $\varepsilon$ even if we extract a subsequence. Indeed, as the limit pair is unique, we will be able to conclude that the limit is the same for any subsequence, so for the full sequence.

The difficulty is to prove (a), i.e. that $u^{\varepsilon}=u^{\varepsilon}\left[\omega^{\varepsilon}\right]$ converges to $u$ with

$$
\begin{equation*}
u(x):=K_{\mathbb{R}^{2}}[\omega](x)=\frac{1}{2 \pi} \int_{\mathbb{R}^{2}} \frac{(x-y)^{\perp}}{|x-y|^{2}} \omega(y) \mathrm{d} y, \quad \forall x \in \mathbb{R}^{2} \tag{1.13}
\end{equation*}
$$

This formula is the well-known Biot-Savart law in the full plane, i.e. which gives the unique vector field in $\mathbb{R}^{2}$ which is divergence free, tending to zero at infinity, and whose curl is $\omega$. We need a strong convergence for the velocity in order to pass to the limit in the vorticity equation, and to conclude that the limit pair is well a weak solution of the Euler equations in the full plane. By uniqueness of weak solution (see [17]), it will end the proof of (c) and Theorem 1.2.

The main idea is to introduce an explicit modification of $K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}\right]$, denoted by $v^{\varepsilon}\left[\omega^{\varepsilon}\right]$, in order to have a tangent vector field in $\Omega^{\varepsilon}$ whose curl is $\omega^{\varepsilon}$ plus a small error term. In Section 2, we recall the explicit formula of the BiotSavart law in the exterior of one obstacle $\mathcal{K}$, thanks to the Riemann mapping which sends $\mathcal{K}^{c}$ to $\bar{B}(0,1)^{c}$, and we present a construction of this modification, based on some cut-off functions around each inclusion.

Then we will write the decomposition:

$$
\begin{array}{rlccc}
u^{\varepsilon}-u & = & \left(u^{\varepsilon}\left[\omega^{\varepsilon}\right]-v^{\varepsilon}\left[\omega^{\varepsilon}\right]\right) & +\left(v^{\varepsilon}\left[\omega^{\varepsilon}\right]-K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}\right]\right) & +K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}-\omega\right] \\
& =: & r^{\varepsilon}\left[\omega^{\varepsilon}\right] & - & w^{\varepsilon}\left[\omega^{\varepsilon}\right] \tag{1.14}
\end{array}+K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}-\omega\right] .
$$

The central part of this article will be Section 3: at time $t$ fixed, we will look for the critical value of $\alpha$ (in terms of $\mu$ ), below which the convergence of $w^{\varepsilon}$ to zero in $L^{2}\left(\mathbb{R}^{2}\right)$ holds. This will follow from a careful study of the explicit formula. Next, we will simply note that $r^{\varepsilon}$ is the Leray projection of $w^{\varepsilon}$. As this projector is orthogonal in $\mathrm{L}^{2}$, this will give the convergence of $r^{\varepsilon}$ to zero in $\mathrm{L}^{2}\left(\mathbb{R}^{2}\right)$. Thanks to these two convergences, we will prove in Section 4 the main theorem.

In the sequel, $C$ will denote a constant independent of the underlying parameter (which will often be $\varepsilon$ ), the value of which can possibly change from a line to another.

## 2. Explicit formula of the correction

In $\Omega^{\varepsilon}$, we note that $u^{\varepsilon}$ (solving (1.7) and having zero circulation around each inclusion) and $K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}\right]$ (see (1.13)) are divergence free, with the same curl and the same limit at infinity. Moreover, they have the same circulations because we compute by the Stokes formula that

$$
\oint_{\partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}} K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}\right](s) \cdot \tau \mathrm{d} s=\int_{\mathcal{K}_{i, j}^{\varepsilon, \alpha}} \omega^{\varepsilon}(x) \mathrm{d} x=0
$$

The only differences are that $K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}\right]$ is not tangent to $\partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}$, and that we do not have an explicit formula of $u^{\varepsilon}$ in terms of $\omega^{\varepsilon}$. The goal of this section is to correct this lack of tangency.

In this section, we fix the time $t$, i.e. we consider $f$ as a function depending only on $x \in \mathbb{R}^{2}$, belonging in $\mathrm{L}^{1} \cap$ $L^{\infty}\left(\mathbb{R}^{2}\right)$ whose support is bounded.

### 2.1. The Biot-Savart law in an exterior domain

In the full plane, we know that there is a unique vector field $u$ satisfying in $\mathbb{R}^{2}$ :

$$
\operatorname{div} u=0, \quad \operatorname{curl} u=f, \quad \lim _{|x| \rightarrow \infty}|u(x)|=0
$$

which is given by the standard Biot-Savart formula:

$$
\begin{equation*}
u(x)=K_{\mathbb{R}^{2}}[f](x):=\frac{1}{2 \pi} \int_{\mathbb{R}^{2}} \frac{(x-y)^{\perp}}{|x-y|^{2}} f(y) \mathrm{d} y=\frac{1}{2 \pi} \nabla^{\perp} \int_{\mathbb{R}^{2}} \ln |x-y| f(y) \mathrm{d} y, \quad \forall x \in \mathbb{R}^{2} . \tag{2.1}
\end{equation*}
$$

It is also well known (see e.g. [23]) that there is a universal constant $C$ such that

$$
\begin{equation*}
\left\|K_{\mathbb{R}^{2}}[f]\right\|_{L^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant\left\|\frac{1}{2 \pi} \int_{\mathbb{R}^{2}} \frac{|f(y)|}{|x-y|} \mathrm{d} y\right\|_{L^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant C\|f\|_{\mathrm{L}^{1}\left(\mathbb{R}^{2}\right)}^{1 / 2}\|f\|_{\mathrm{L}^{\infty}\left(\mathbb{R}^{2}\right)}^{1 / 2}, \tag{2.2}
\end{equation*}
$$

and if $f$ is compactly supported, we have the following behavior at infinity:

$$
K_{\mathbb{R}^{2}}[f](x)=\frac{\int_{\mathbb{R}^{2}} f(y) \mathrm{d} y}{2 \pi} \frac{x^{\perp}}{|x|^{2}}+\mathcal{O}\left(\frac{1}{|x|^{2}}\right) .
$$

We note here that considering $u_{0}=K_{\mathbb{R}^{2}}\left[\omega_{0}\right] \in \mathrm{L}^{2}\left(\mathbb{R}^{2}\right)$ is too restrictive because it would imply that $\int \omega_{0}=0$.
In the exterior of a unit disk in dimension 2, we have again an explicit formula for the Biot-Savart law: there exists a unique vector field $\mathrm{u}[f]$ solving in $\mathbb{R}^{2} \backslash B(0,1)$ :

$$
\begin{aligned}
& \operatorname{div} \mathrm{u}[f]=0, \quad \operatorname{curlu}[f]=f, \quad \lim _{|x| \rightarrow \infty}|\mathrm{u}[f](x)|=0, \\
& \left.\mathrm{u}[f] \cdot \mathbf{n}\right|_{\partial B(0,1)}=0, \quad \oint_{\partial B(0,1)} \mathrm{u}[f](s) \cdot \tau \mathrm{d} s=0 .
\end{aligned}
$$

This vector field $u[f]$ is given explicitly by:

$$
\begin{aligned}
\mathrm{u}[f](x) & =\frac{1}{2 \pi} \int_{B(0,1)^{c}}\left(\frac{x-y}{|x-y|^{2}}-\frac{x-y^{*}}{\left|x-y^{*}\right|^{2}}\right)^{\perp} f(y) \mathrm{d} y+\frac{\int_{B(0,1)^{c}} f(y) \mathrm{d} y}{2 \pi} \frac{x^{\perp}}{|x|^{2}} \\
& =\frac{1}{2 \pi} \nabla^{\perp} \int_{B(0,1)^{c}} \ln \frac{|x-y||x|}{\left|x-y^{*}\right|} f(y) \mathrm{d} y,
\end{aligned}
$$

with the notation $z^{*}=z /|z|^{2}$ (coming from the image method in order to have a tangent vector field). As we have mentioned in the introduction, solving the elliptic equation (1.7) is equivalent to solving $\Delta \psi=f$, where $\psi$ is constant on the boundary (here, the boundary has only one connected component) and setting $u:=\nabla^{\perp} \psi$. Hence, the previous Biot-Savart law comes from the explicit formula of the Green's function in $B(0,1)^{c}$. Another advantage of the dimension two is that we can extend this formula to the exterior of any simply-connected compact set $\mathcal{K}$ : thanks to the complex analysis (identifying $\mathbb{R}^{2}$ and $\mathbb{C}$ ) and the fact that holomorphic function is a good change of variable for the Laplace problem. By the Riemann mapping theorem, there exists a unique biholomorphism $\mathcal{T}$ mapping $\mathcal{K}^{c}$ to
$\bar{B}(0,1)^{c}$ and verifying $\mathcal{T}(\infty)=\infty$ and $\mathcal{T}^{\prime}(\infty) \in \mathbb{R}^{+}$. The last condition reads in the Laurent decomposition of $\mathcal{T}$ at infinity:

$$
\mathcal{T}(z)=\beta z+\gamma+\mathcal{O}_{z \rightarrow \infty}\left(\frac{1}{z}\right), \quad \text { with } \beta \in \mathbb{R}^{+} .
$$

Then, we will use several times that

$$
\begin{equation*}
\mathcal{T}(z)=\beta z+h(z) \tag{2.3}
\end{equation*}
$$

where $h$ is a holomorphic function satisfying at infinity $h(z)=\mathcal{O}(1)$ and $h^{\prime}(z)=\mathcal{O}\left(1 /|z|^{2}\right)$. Of course we have a similar behavior for $\mathcal{T}^{-1}$.

In the sequel, we will need a kind of mean value theorem in a non-convex domain given by the following lemma:
Lemma 2.1. We assume that $\mathcal{K}$ is a compact set such that $\partial \mathcal{K}$ is a $\mathcal{C}^{1,1}$ Jordan curve. There exists $C$ such that

$$
|\mathcal{T}(x)-\mathcal{T}(y)| \leqslant C|x-y|, \quad \forall(x, y) \in\left(\mathcal{K}^{c}\right)^{2}, \quad\left|\mathcal{T}^{-1}(x)-\mathcal{T}^{-1}(y)\right| \leqslant C|x-y|, \quad \forall(x, y) \in\left(\bar{B}(0,1)^{c}\right)^{2}
$$

Proof. As long as the boundary is $\mathcal{C}^{1, \alpha}$, we can extend the definition of $\mathcal{T}$ and $D \mathcal{T}$ continuously up the boundary due to Kellogg-Warschawski theorem (see [28, Theorem 3.6]). Hence, by the behavior at infinity (see (2.3)), we infer that $D \mathcal{T}$ is uniformly bounded on $\mathcal{K}^{c}$. The same argument gives also that $\mathcal{T}^{-1}$ is bounded on $\bar{B}(0,1)^{c}$.

By the connectivity of $\mathcal{K}^{c}$, we know that for any $x, y \in \mathcal{K}^{c}$, there exists a smooth path $\gamma$ in $\mathcal{K}^{c}$ joining $x$ and $y$, and we have

$$
|\mathcal{T}(x)-\mathcal{T}(y)|=\left|\int_{0}^{1} D \mathcal{T}(\gamma(t)) \gamma^{\prime}(t) \mathrm{d} t\right| \leqslant\|D \mathcal{T}\|_{\mathrm{L}^{\infty}} \ell(\gamma)
$$

Therefore, it is sufficient to prove that there exists $a \geqslant 1$ such that $\mathcal{K}^{c}$ is $a$-quasiconvex, that is, for all points $x, y$ there exists a rectifiable path $\gamma$ joining $x, y$ and satisfying

$$
\ell(\gamma) \leqslant a|x-y| .
$$

We note easily that $\bar{B}(0,1)^{c}$ is $\frac{\pi}{2}$-quasiconvex which ends the proof for $\mathcal{T}^{-1}$.
Concerning $\mathcal{T}$, we remark that $\mathcal{K}^{c}$ cannot be quasiconvex if $\partial \mathcal{K}$ has a double point or a cusp. Conversely, if $\partial \mathcal{K}$ is a $\mathcal{C}^{1}$ Jordan curve, it is rather classical to show that there exists $a \geqslant 1$ such that $\mathcal{K}^{c}$ is $a$-quasiconvex. We refer to Hakobyan and Herron [15] for recent development about quasiconvexity. This kind of problem is although extensively studied in complex analysis, and Ahlfors shows in [1] the following equivalence in dimension two:

$$
\partial \mathcal{K} \text { is a quasidisk } \Leftrightarrow \mathcal{K}^{c} \text { is quasiconvex }
$$

where it is known that a Jordan curve, piecewise $\mathcal{C}^{1}$, is a quasidisk iff $\partial \mathcal{K}$ has no cusp (see e.g. [14]).
Next, with the definitions (1.1)-(1.2), we set $\mathcal{T}_{i, j}^{\varepsilon, \alpha}$ as

$$
\begin{equation*}
\mathcal{T}_{i, j}^{\varepsilon, \alpha}(z)=\mathcal{T}\left(\frac{z-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right) \tag{2.4}
\end{equation*}
$$

the unique biholomorphism which maps $\left(\mathcal{K}_{i, j}^{\varepsilon, \alpha}\right)^{c}$ to $\bar{B}(0,1)^{c}$ and satisfies $\mathcal{T}_{i, j}^{\varepsilon, \alpha}(\infty)=\infty$ and $\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{\prime}(\infty) \in \mathbb{R}^{+}$. Let us note that

$$
\begin{equation*}
\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{-1}(z)=\varepsilon \mathcal{T}^{-1}(z)+z_{i, j}^{\varepsilon, \alpha} . \tag{2.5}
\end{equation*}
$$

From these formulas and Lemma 2.1, we will often use the following Lipschitz estimates:

$$
\begin{equation*}
\left\|\mathcal{T}_{i, j}^{\varepsilon, \alpha}\right\|_{\mathrm{Lip}} \leqslant \frac{C}{\varepsilon} \quad \text { and } \quad\left\|\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{-1}\right\|_{\mathrm{Lip}} \leqslant C \varepsilon \tag{2.6}
\end{equation*}
$$

Then we infer that there exists a unique vector field $\mathbf{u}_{i, j}^{\varepsilon}[f]$ solving in $\mathbb{R}^{2} \backslash \mathcal{K}_{i, j}^{\varepsilon, \alpha}$ :

$$
\begin{aligned}
& \operatorname{div} \mathrm{u}_{i, j}^{\varepsilon}[f]=0, \quad \operatorname{curl}_{u i, j}^{\varepsilon}[f]=f, \quad \lim _{|x| \rightarrow \infty}\left|\mathrm{u}_{i, j}^{\varepsilon}[f](x)\right|=0, \\
& \left.\mathbf{u}_{i, j}^{\varepsilon}[f] \cdot \mathbf{n}\right|_{\partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}}=0, \quad \oint_{\partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}} \mathrm{u}_{i, j}^{\varepsilon}[f](s) \cdot \tau \mathrm{d} s=0,
\end{aligned}
$$

which is given explicitly by:

$$
\begin{align*}
\mathbf{u}_{i, j}^{\varepsilon}[f](x) & =\frac{1}{2 \pi} \nabla^{\perp} \int_{\left(\mathcal{K}_{i, j}^{\varepsilon, \alpha} c^{c}\right.} \ln \frac{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y) \| \mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|} f(y) \mathrm{d} y \\
& =\frac{1}{2 \pi} \nabla^{\perp} \int_{\left(\mathcal{K}_{i, j}^{\varepsilon, \alpha}\right)^{c}} \ln \frac{\varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|}{\beta\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|} f(y) \mathrm{d} y . \tag{2.7}
\end{align*}
$$

For more details and literature on this problem, we refer to [16, Section 2].
A useful estimate for the next section is:
Lemma 2.2. There exist $C_{1}, C_{2}, C_{3}, C_{4}$ four positive numbers such that for all $\varepsilon>0, \alpha>0, \mu \in[0,1], i \in\left\{1, \ldots, n_{1}\right\}$, $j \in\left\{1, \ldots, n_{2}\right\}, r>0$, we have

$$
\mathcal{T}_{i, j}^{\varepsilon, \alpha}\left(\partial B\left(z_{i, j}^{\varepsilon, \alpha}, r\right) \cap\left(\mathcal{K}_{i, j}^{\varepsilon, \alpha}\right)^{c}\right) \subset B\left(0, C_{1} \frac{r}{\varepsilon}\right) \backslash B\left(0, C_{2} \frac{r}{\varepsilon}\right)
$$

and

$$
\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{-1}(\partial B(0, r+1)) \subset B\left(z_{i, j}^{\varepsilon, \alpha}, \varepsilon C_{3}(r+1)\right) \backslash B\left(z_{i, j}^{\varepsilon, \alpha}, \varepsilon C_{4}(r+1)\right) .
$$

Proof. With the definitions of $\mathcal{K}_{i, j}^{\varepsilon, \alpha}$ and $\mathcal{T}_{i, j}^{\varepsilon, \alpha}$ (see (1.2) and (2.4)) we have to prove that there exist $C_{1}, C_{2}, C_{3}, C_{4}$ such that for all $\varepsilon$ and $r$ we have:

$$
\mathcal{T}\left(\partial B\left(0, \frac{r}{\varepsilon}\right) \cap \mathcal{K}^{c}\right) \subset B\left(0, C_{1} \frac{r}{\varepsilon}\right) \backslash B\left(0, C_{2} \frac{r}{\varepsilon}\right)
$$

and

$$
\mathcal{T}^{-1}(\partial B(0, r+1)) \subset B\left(0, C_{3}(r+1)\right) \backslash B\left(0, C_{4}(r+1)\right) .
$$

The second point is obvious, because $\mathcal{T}^{-1}$ is continuous from $B(0,1)^{c}$ to $\overline{\mathcal{K}^{c}}$ and as $\mathcal{T}^{-1}(z) / z \rightarrow 1 / \beta$ as $|z| \rightarrow \infty$, we can infer that $z \mapsto\left|\mathcal{T}^{-1}(z)\right| /|z|$ has an upper and lower positive bounds. Indeed, we have assumed that there is a small neighborhood of zero inside $\mathcal{K}$.

Actually, the first point is the same. Indeed, we are looking for $C_{1}, C_{2}$ such that for all $s>0$ we have

$$
\mathcal{T}\left(\partial B(0, s) \cap \mathcal{K}^{c}\right) \subset B\left(0, C_{1} s\right) \backslash B\left(0, C_{2} s\right) .
$$

So, the conclusion comes with the same argument applied to $z \mapsto|\mathcal{T}(z)| /|z|$ where $\mathcal{T}$ is continuous from $\overline{\mathcal{K}^{c}}$ to $B(0,1)^{c}$.

Remark 2.3. Even if the shape of $\mathcal{K}$ (via the bounds on the conformal map) is taking into account in the convergence proof, the limit vector field is independent on. Our analysis can be extended to the case where the inclusions have different shapes $\mathcal{K}^{k}$ if we have uniform bounds $\left(\sup \left|\beta^{k}\right|<\infty, \inf \beta^{k}>0, \sup \left\|h^{k}\right\|_{L^{\infty}}\right.$, and uniform constants $C_{1}$, $C_{2}, C_{3}, C_{4}$ in Lemma 2.2). For example, this is the case when we consider a finite number of shapes $\mathcal{K}^{1}, \mathcal{K}^{2}, \ldots, \mathcal{K}^{p}$ (smooth simply-connected compact subsets of $[-1,1]^{2}$ ).

### 2.2. Definition and properties of $v^{\varepsilon}[f]$

A similar modification was introduced in [20] in the case of a finite number of balls, whose centers are fixed and whose radii tend to zero. Our case is more difficult because the centers change, the shape of the inclusion is more general than a ball and the number of inclusions tends to infinity. The idea is to define $v^{\varepsilon}$ such that it is equal to (2.7) in a neighborhood of $\mathcal{K}_{i, j}^{\ell, \alpha}$ and to (2.1) far away.

For this, let us define some cut-off functions $\varphi_{i, j}^{\varepsilon}$. Let $\varphi \in \mathcal{C}^{\infty}(\mathbb{R})$ be a positive non-increasing function such that

$$
\varphi(s)= \begin{cases}1 & \text { if } s \leqslant 1 / 2 \\ 0 & \text { if } s \geqslant 1\end{cases}
$$

We define the cut-off function $\varphi_{i, j}^{\varepsilon}$ on $\Omega^{\varepsilon}$ by

$$
\varphi_{i, j}^{\varepsilon}(x)=\varphi\left(\frac{1}{\varepsilon^{\alpha}}\left(\left\|x-z_{i, j}^{\varepsilon, \alpha}\right\|_{\infty}-\varepsilon\right)\right) .
$$

This function is $\mathcal{C}^{\infty}$ almost everywhere and satisfies

$$
0 \leqslant \varphi_{i, j}^{\varepsilon} \leqslant 1, \quad \varphi_{i, j}^{\varepsilon}(x)= \begin{cases}1 & \text { if }\left\|x-z_{i, j}^{\varepsilon, \alpha}\right\|_{\infty} \leqslant \varepsilon+\frac{\varepsilon^{\alpha}}{2}, \\ 0 & \text { if }\left\|x-z_{i, j}^{\varepsilon, \alpha}\right\|_{\infty} \geqslant \varepsilon+\varepsilon^{\alpha},\end{cases}
$$

and we recall that $\mathcal{K}_{i, j}^{\varepsilon, \alpha} \subset\left\{x \in \mathbb{R}^{2},\left\|x-z_{i, j}^{\varepsilon, \alpha}\right\|_{\infty} \leqslant \varepsilon\right\}$. From the definition, we note that

$$
\begin{align*}
& \left\|\nabla \varphi_{i, j}^{\varepsilon}\right\|_{L^{\infty}\left(\Omega^{\varepsilon}\right)} \leqslant \frac{C}{\varepsilon^{\alpha}}  \tag{2.8}\\
& \operatorname{meas}\left(\operatorname{supp} \nabla \varphi_{i, j}^{\varepsilon}\right)=4\left(\varepsilon+\varepsilon^{\alpha}\right)^{2}-4\left(\varepsilon+\frac{\varepsilon^{\alpha}}{2}\right)^{2}=4 \varepsilon^{\alpha+1}+3 \varepsilon^{2 \alpha} \leqslant 4\left(\varepsilon^{\alpha}\left(\varepsilon+\varepsilon^{\alpha}\right)\right) \tag{2.9}
\end{align*}
$$

Concerning the support of $\varphi_{i, j}^{\varepsilon}$ we have

$$
\operatorname{meas}\left(\operatorname{supp} \varphi_{i, j}^{\varepsilon}\right)=4\left(\varepsilon+\varepsilon^{\alpha}\right)^{2}-\varepsilon^{2} \operatorname{meas}(\mathcal{K}),
$$

so meas $\left(\operatorname{supp} \varphi_{i, j}^{\varepsilon}\right)=\mathcal{O}\left(\varepsilon^{\alpha}\left(\varepsilon+\varepsilon^{\alpha}\right)\right)$ if $\mathcal{K}=[-1,1]^{2}$, and meas $\left(\operatorname{supp} \varphi_{i, j}^{\varepsilon}\right)=\mathcal{O}\left(\varepsilon^{2 \alpha}+\varepsilon^{2}\right)$ if not. In any case, we have

$$
\begin{equation*}
\operatorname{meas}\left(\operatorname{supp} \varphi_{i, j}^{\varepsilon}\right) \leqslant 4\left(\varepsilon+\varepsilon^{\alpha}\right)^{2} \leqslant 8\left(\varepsilon^{2}+\varepsilon^{2 \alpha}\right) \tag{2.10}
\end{equation*}
$$

Moreover, we note easily that all the supports are disjoints, i.e. for all $\alpha>0, \mu \in(0,1],(i, k) \in\left\{1, \ldots, n_{1}\right\}^{2}$ and $(j, l) \in\left\{1, \ldots, n_{2}\right\}^{2}$, we have

$$
\begin{equation*}
\varphi_{i, j}^{\varepsilon} \varphi_{k, l}^{\varepsilon} \equiv 0 \quad \text { iff } \quad(i, j) \neq(k, l) \tag{2.11}
\end{equation*}
$$

Now, we can simply define our correction as:

$$
\begin{equation*}
v^{\varepsilon}[f]:=\nabla^{\perp} \psi^{\varepsilon}[f], \tag{2.12}
\end{equation*}
$$

with

$$
\begin{aligned}
\psi^{\varepsilon}[f](x):= & \frac{1}{2 \pi}\left(1-\sum_{j=1}^{n_{2}} \sum_{i=1}^{n_{1}} \varphi_{i, j}^{\varepsilon}(x)\right) \int_{\Omega^{\varepsilon}} \ln |x-y| f(y) \mathrm{d} y \\
& +\frac{1}{2 \pi} \sum_{j=1}^{n_{2}} \sum_{i=1}^{n_{1}} \varphi_{i, j}^{\varepsilon}(x) \int_{\Omega^{\varepsilon}} \ln \frac{\varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y) \| \mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|}{\beta\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|} f(y) \mathrm{d} y
\end{aligned}
$$

$$
\begin{aligned}
= & \frac{1}{2 \pi} \int_{\Omega^{\varepsilon}} \ln |x-y| f(y) \mathrm{d} y \\
& -\frac{1}{2 \pi} \sum_{j=1}^{n_{2}} \sum_{i=1}^{n_{1}} \varphi_{i, j}^{\varepsilon}(x) \int_{\Omega^{\varepsilon}} \ln \frac{\beta|x-y|}{\varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|} f(y) \mathrm{d} y \\
& +\frac{1}{2 \pi} \sum_{j=1}^{n_{2}} \sum_{i=1}^{n_{1}} \varphi_{i, j}^{\varepsilon}(x) \int_{\Omega^{\varepsilon}} \ln \frac{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|} f(y) \mathrm{d} y .
\end{aligned}
$$

From this definition and the previous subsection, it appears obvious that:

$$
\begin{align*}
& \operatorname{div} v^{\varepsilon}[f]=0 \quad \text { in } \Omega^{\varepsilon}, \quad \lim _{|x| \rightarrow \infty}\left|v^{\varepsilon}[f](x)\right|=0, \\
& \left.v^{\varepsilon}[f] \cdot \mathbf{n}\right|_{\partial \Omega^{\varepsilon}}=0, \quad \oint_{\partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}} v^{\varepsilon}[f](s) \cdot \tau \mathrm{d} s=0, \quad \forall i, j . \tag{2.13}
\end{align*}
$$

We can also note that the curl of $v^{\varepsilon}[f]$ is equal to $f$ in $\Omega^{\varepsilon}$ plus some terms localized on the support of $\nabla \varphi_{i, j}^{\varepsilon}$. In this article, we do not need to estimate precisely this quantity, so we do not write its expression.

## 3. Convergence at fixed time

As we have said in the introduction, we want to decompose $u^{\varepsilon}-u$ as in (1.14) and to pass to limit in each terms. In this section, we fixed the time, i.e. we consider $f$ as a function in $L_{c}^{\infty}\left(\mathbb{R}^{2}\right)$. Then, we introduce $u^{\varepsilon}[f]$ such that:

$$
\begin{align*}
& \operatorname{div} u^{\varepsilon}[f]=0 \quad \text { in } \Omega^{\varepsilon}, \quad \operatorname{curl} u^{\varepsilon}[f]=f \quad \text { in } \Omega^{\varepsilon}, \quad \lim _{|x| \rightarrow \infty}\left|u^{\varepsilon}[f](x)\right|=0, \\
& \left.u^{\varepsilon}[f] \cdot \mathbf{n}\right|_{\partial \Omega^{\varepsilon}}=0, \quad \oint_{\partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}} u^{\varepsilon}[f](s) \cdot \tau \mathrm{d} s=0, \quad \forall i, j, \tag{3.1}
\end{align*}
$$

and $v^{\varepsilon}[f]$ the correction of $K_{\mathbb{R}^{2}}\left[f 1_{\Omega^{\varepsilon}}\right]$, i.e. $v^{\varepsilon}[f]$ given by (2.12).
Let $M_{0}>0$ be fixed, the goal here is to prove the convergence of

$$
w^{\varepsilon}[f]:=K_{\mathbb{R}^{2}}\left[f 1_{\Omega^{\varepsilon}}\right]-v^{\varepsilon}[f] \quad \text { and } \quad r^{\varepsilon}[f]:=u^{\varepsilon}[f]-v^{\varepsilon}[f]
$$

to zero uniformly in $f$ verifying

$$
\|f\|_{\mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant M_{0},
$$

where we have extended by zero $v^{\varepsilon}[f]$ and $u^{\varepsilon}[f]$ inside the inclusions.

### 3.1. Convergence of $w^{\varepsilon}[f]=K_{\mathbb{R}^{2}}\left[f 1_{\Omega^{\varepsilon}}\right]-v^{\varepsilon}[f]$

First, in the inclusions, we prove that
Proposition 3.1. For all $p \in[1, \infty)$,

$$
\begin{equation*}
\left\|w^{\varepsilon}[f]\right\|_{L^{p}\left(\mathbb{R}^{2} \backslash \Omega^{\varepsilon}\right)} \rightarrow 0 \quad \text { as } \varepsilon \rightarrow 0, \forall(\alpha, \mu) \in(0, \infty) \times[0,1) \cup(0,1) \times\{1\} \tag{3.2}
\end{equation*}
$$

uniformly in $f$ verifying

$$
\|f\|_{\mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant M_{0}
$$

Proof. Indeed, we have $K_{\mathbb{R}^{2}}\left[f 1_{\Omega^{\varepsilon}}\right]-v^{\varepsilon}[f]=K_{\mathbb{R}^{2}}\left[f 1_{\Omega^{\varepsilon}}\right]$ on $\mathbb{R}^{2} \backslash \Omega^{\varepsilon}$ and by (2.2) we write that

$$
\| K_{\mathbb{R}^{2}}\left[f 1_{\left.\Omega^{\varepsilon}\right]}\left\|_{L^{p}\left(\mathbb{R}^{2} \backslash \Omega^{\varepsilon}\right)} \leqslant\right\| K_{\mathbb{R}^{2}}\left[f 1_{\Omega^{\varepsilon}}\right] \|_{L^{\infty}\left(\mathbb{R}^{2}\right)}\left(\operatorname{meas}\left(\mathbb{R}^{2} \backslash \Omega^{\varepsilon}\right)\right)^{1 / p} \leqslant C M_{0}\left(\operatorname{meas}\left(\mathbb{R}^{2} \backslash \Omega^{\varepsilon}\right)\right)^{1 / p} .\right.
$$

Using (1.4), we have

$$
\operatorname{meas}\left(\mathbb{R}^{2} \backslash \Omega^{\varepsilon}\right) \leqslant\left(N_{\varepsilon, \alpha}\right)^{1+\mu} \varepsilon^{2} \operatorname{meas}(\mathcal{K}) \leqslant \operatorname{meas}(\mathcal{K}) \frac{\varepsilon^{2}}{\left(\varepsilon+\varepsilon^{\alpha}\right)^{1+\mu}}
$$

which tends to zero when $\varepsilon \rightarrow 0$ for any $\alpha$ if $\mu<1$, and only for $\alpha<1$ if $\mu=1$. Its ends the proof of (3.2).
Now, we are working in $\Omega^{\varepsilon}$ : using the explicit formula (2.12), we decompose as follows

$$
\begin{equation*}
w^{\varepsilon}[f]=\sum_{k=1}^{4} w^{\varepsilon, k}[f], \tag{3.3}
\end{equation*}
$$

with

$$
\begin{aligned}
& w^{\varepsilon, 1}[f](x)=\frac{1}{2 \pi} \sum_{j=1}^{n_{2}} \sum_{i=1}^{n_{1}} \nabla^{\perp} \varphi_{i, j}^{\varepsilon}(x) \int_{\Omega^{\varepsilon}} \ln \frac{\beta|x-y|}{\varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|} f(y) \mathrm{d} y, \\
& w^{\varepsilon, 2}[f](x)=\frac{1}{2 \pi} \sum_{j=1}^{n_{2}} \sum_{i=1}^{n_{1}} \nabla^{\perp} \varphi_{i, j}^{\varepsilon}(x) \int_{\Omega^{\varepsilon}} \ln \frac{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|} f(y) \mathrm{d} y, \\
& w^{\varepsilon, 3}[f](x)=\frac{1}{2 \pi} \sum_{j=1}^{n_{2}} \sum_{i=1}^{n_{1}} \varphi_{i, j}^{\varepsilon}(x) \int_{\Omega^{\varepsilon}}\left(\frac{(x-y)^{\perp}}{|x-y|^{2}}-\left(D \mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{T}(x) \frac{\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right)^{\perp}}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|^{2}}\right) f(y) \mathrm{d} y, \\
& w^{\varepsilon, 4}[f](x)=\frac{1}{2 \pi} \sum_{j=1}^{n_{2}} \sum_{i=1}^{n_{1}} \varphi_{i, j}^{\varepsilon}(x)\left(D \mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{T}(x) \int_{\Omega^{\varepsilon}}\left(\frac{\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|^{2}}-\frac{\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|^{2}}\right)^{\perp} f(y) \mathrm{d} y .
\end{aligned}
$$

We prove separately the convergence to 0 of each term in $L^{2}$.
Let us start by partially dealing with $w^{\varepsilon, 3}$ and $w^{\varepsilon, 4}$. Actually, it is very easy if $\mu<1$, without any condition on $\alpha$ :
Proposition 3.2. Let $\mu \in[0,1)$ and $\alpha>0$ be fixed. Then, for $k=3,4$ and any $p \in[1, \infty)$, we have

$$
\left\|w^{\varepsilon, k}[f]\right\|_{L^{p}\left(\Omega^{\varepsilon}\right)} \rightarrow 0 \quad \text { as } \varepsilon \rightarrow 0
$$

uniformly in $f$ verifying

$$
\|f\|_{L^{1} \cap L^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant M_{0} .
$$

Proof. Changing variables and using the expression (2.4) of $\mathcal{T}_{i, j}^{\varepsilon, \alpha}$ in terms of $\mathcal{T}$, we can get that the quantities

$$
\begin{aligned}
& w_{i, j}^{\varepsilon, 3}(x):=\int_{\Omega^{\varepsilon}} \frac{(x-y)^{\perp}}{|x-y|^{2}} f(y) \mathrm{d} y-\left(D \mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{T}(x) \int_{\Omega^{\varepsilon}} \frac{\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right)^{\perp}}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|^{2}} f(y) \mathrm{d} y, \\
& w_{i, j}^{\varepsilon, 4}(x)
\end{aligned}=\left(D \mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{T}(x) \int_{\Omega^{\varepsilon}}\left(\frac{\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|^{2}}-\frac{\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|^{2}}\right)^{\perp} f(y) \mathrm{d} y,
$$

are uniformly bounded by $C M_{0}$ where $C$ depends only on $\mathcal{K}$. Indeed, the uniform estimate of $\int_{\Omega^{\varepsilon}} \frac{(x-y)^{\perp}}{|x-y|^{2}} f(y) \mathrm{d} y=$ $2 \pi K_{\mathbb{R}^{2}}\left[f 1_{\Omega^{\varepsilon}}\right]$ comes directly from (2.2). Concerning the other term of $w_{3}^{i, j}$ and $w_{4}^{i, j}$, all the details are given in [16, Theorem 4.1].

Hence, as the $\varphi_{i, j}^{\varepsilon}$ have disjoint supports (see (2.11)), we state that the uniform bound and (2.10) imply that for any $p \in[1, \infty)$ and $k=3,4$ :

$$
\left\|w^{\varepsilon, k}[f]\right\|_{L^{p}\left(\Omega^{\varepsilon}\right)} \leqslant \frac{3 C M_{0}}{2 \pi}\left(\left(N_{\varepsilon, \alpha}\right)^{1+\mu} 4\left(\varepsilon+\varepsilon^{\alpha}\right)^{2}\right)^{1 / p} \leqslant C M_{0}\left(\varepsilon+\varepsilon^{\alpha}\right)^{\frac{1-\mu}{p}}
$$

which tends to zero for $\mu<1$.

Notice that Proposition 3.2 holds true for any $p \in[1, \infty)$. When $\mu=1$, the proof is more tricky, and we only establish the convergence in $\mathrm{L}^{2}$ for $w^{\varepsilon, 3}$ and $w^{\varepsilon, 4}$ when $\alpha<1$, as we make for $w^{\varepsilon, 1}, w^{\varepsilon, 2}$.

The terms $w^{\varepsilon, 1}$ and $w^{\varepsilon, 3}$ will be treated in the same spirit. Indeed, we note that if $\mathcal{K}=\bar{B}(0,1)$ then $\mathcal{T}=\operatorname{Id}$ (so $\beta=1$ and $h=0$ in (2.3) in this case) and we would have $\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)=\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}$ hence $w^{\varepsilon, 1} \equiv 0$ and $w^{\varepsilon, 3} \equiv 0$. In the general case, the idea is then to use that $\mathcal{T}$ behaves as $\beta$ Id at infinity (see (2.3)) that justifies the decomposition of the integrals in two parts (close and far away).

Convergence of $w^{\varepsilon, 1}$.
Proposition 3.3. We recall that $\alpha_{c}(\mu)=2-\mu$. Let $\mu \in[0,1]$ and $\alpha \in\left(0, \alpha_{c}(\mu)\right)$ be fixed. Then

$$
\left\|w^{\varepsilon, 1}[f]\right\|_{L^{2}\left(\Omega^{\varepsilon}\right)} \rightarrow 0 \quad \text { as } \varepsilon \rightarrow 0,
$$

uniformly in $f$ verifying

$$
\|f\|_{\mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant M_{0} .
$$

Proof. We fix $i, j$ and work on the support of $\nabla^{\perp} \varphi_{i, j}^{\varepsilon}$. For $x \in \operatorname{supp} \nabla^{\perp} \varphi_{i, j}^{\varepsilon}$ fixed, we decompose the integral in two parts:

$$
\begin{align*}
& \Omega_{1}^{\varepsilon}:=\left\{y \in \Omega^{\varepsilon},\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right| \leqslant \varepsilon^{-1 / 2}\right\}, \\
& \text { and } \quad \Omega_{2}^{\varepsilon}:=\left\{y \in \Omega^{\varepsilon},\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|>\varepsilon^{-1 / 2}\right\} . \tag{3.4}
\end{align*}
$$

In the first subdomain $\Omega_{1}^{\varepsilon}$, we set $z=\varepsilon \mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)$ and we change variables $\eta=\varepsilon \mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)$ and use (2.5):

$$
\begin{aligned}
\int_{\Omega_{1}^{\varepsilon}}\left|\ln \left(\varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|\right) f(y)\right| \mathrm{d} y & \leqslant \int_{B\left(z, \varepsilon^{1 / 2}\right)}|\ln | z-\eta\left|f\left(\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{-1}\left(\frac{\eta}{\varepsilon}\right)\right)\right| \frac{\left|\operatorname{det} D\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{-1}\right|\left(\frac{\eta}{\varepsilon}\right)}{\varepsilon^{2}} \mathrm{~d} \eta \\
& \leqslant \int_{B\left(z, \varepsilon^{1 / 2}\right)}|\ln | z-\eta\left|f\left(\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{-1}\left(\frac{\eta}{\varepsilon}\right)\right)\right|\left|\operatorname{det} D \mathcal{T}^{-1}\right|\left(\frac{\eta}{\varepsilon}\right) \mathrm{d} \eta .
\end{aligned}
$$

Using that $D \mathcal{T}^{-1}$ and $f$ are bounded functions, we compute that:

$$
\begin{equation*}
\int_{\Omega_{1}^{\varepsilon}}\left|\ln \left(\varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|\right) f(y)\right| \mathrm{d} y \leqslant M_{0} C \int_{B\left(0, \varepsilon^{1 / 2}\right)}|\ln | \xi| | \mathrm{d} \xi \leqslant C M_{0} \varepsilon|\ln \varepsilon| . \tag{3.5}
\end{equation*}
$$

To deal with $\ln (\beta|x-y|)$, we remark first that if $y \in \Omega_{1}^{\varepsilon}$, then by (2.6), we have

$$
|x-y|=\left|\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{-1}\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right)-\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{-1}\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right)\right| \leqslant \varepsilon C\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right| \leqslant C \varepsilon^{1 / 2} .
$$

Then we compute that

$$
\begin{align*}
\int_{\Omega_{1}^{\varepsilon}}|\ln (\beta|x-y|) f(y)| \mathrm{d} y & \leqslant \int_{B\left(x, C \varepsilon^{1 / 2}\right)}|\ln (\beta|x-y|) f(y)| \mathrm{d} y \\
& \leqslant\|f\|_{\mathrm{L}^{\infty}} \int_{B\left(0, C \varepsilon^{1 / 2}\right)}|\ln | \beta \xi| | \mathrm{d} \xi \leqslant C M_{0} \varepsilon|\ln \varepsilon| . \tag{3.6}
\end{align*}
$$

In the second subdomain $\Omega_{2}^{\varepsilon}$, we have by (2.6)

$$
\varepsilon^{-1 / 2} \leqslant\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right| \leqslant \varepsilon^{-1} C|x-y|,
$$

hence $|x-y| \geqslant \frac{\varepsilon^{1 / 2}}{C}$. Therefore, with $h$ defined in (2.3), writing

$$
\begin{equation*}
\ln \frac{\varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|}{\beta|x-y|}=\ln \frac{\left|\beta(x-y)+\varepsilon\left(h\left(\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)-h\left(\frac{y-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)\right)\right|}{\beta|x-y|}, \tag{3.7}
\end{equation*}
$$

we have

$$
\frac{\varepsilon\left|h\left(\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)-h\left(\frac{y-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)\right|}{\beta|x-y|} \leqslant \frac{2 C\|h\|_{L^{\infty}}}{\beta} \varepsilon^{1 / 2}
$$

which is smaller that $1 / 2$ for $\varepsilon$ small enough. We note easily that

$$
\begin{equation*}
\left|\ln \frac{|b+c|}{|b|}\right| \leqslant 2 \frac{|c|}{|b|}, \quad \text { if } \frac{|c|}{|b|} \leqslant \frac{1}{2} . \tag{3.8}
\end{equation*}
$$

Applying this inequality (3.8) with $c=h\left(\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)-h\left(\frac{y-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)$ and $b=\frac{\beta(x-y)}{\varepsilon}$, we compute from (3.7):

$$
\left|\ln \frac{\varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|}{\beta|x-y|}\right| \leqslant 2 \frac{\varepsilon\left|h\left(\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)-h\left(\frac{y-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)\right|}{\beta|x-y|} \leqslant \frac{4 \varepsilon\|h\|_{\mathrm{L}^{\infty}}}{\beta|x-y|} .
$$

Therefore, using (2.2), we obtain

$$
\int_{\Omega_{2}^{\varepsilon}}\left|\ln \frac{\beta|x-y|}{\varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|} f(y)\right| \mathrm{d} y \leqslant \int_{\Omega^{\varepsilon}} \frac{4 \varepsilon\|h\|_{\mathrm{L}^{\infty}}}{\beta|x-y|}|f(y)| \mathrm{d} y \leqslant C \varepsilon\|f\|_{\mathrm{L}^{\infty}}^{1 / 2}\|f\|_{\mathrm{L}^{1}}^{1 / 2} \leqslant C M_{0} \varepsilon .
$$

Putting together this last estimate with previous ones (3.5)-(3.6), we get

$$
\left\|\int_{\Omega^{\varepsilon}} \ln \frac{\beta|x-y|}{\varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|} f(y) \mathrm{d} y\right\|_{\mathrm{L}^{\infty}\left(\Omega^{\varepsilon}\right)} \leqslant C M_{0} \varepsilon|\ln \varepsilon|
$$

where $C$ is a constant independent of $i, j, \alpha, \mu, f, \beta, \varepsilon$. Hence, by (2.8), (2.9), (2.11) and since $\varepsilon+\varepsilon^{\alpha}>\varepsilon$, we finally conclude that

$$
\begin{aligned}
\left\|w^{\varepsilon, 1}[f]\right\|_{L^{2}\left(\Omega^{\varepsilon}\right)} & \leqslant C M_{0} \frac{\varepsilon|\ln \varepsilon|}{\varepsilon^{\alpha}}\left(N_{\varepsilon, \alpha}^{1+\mu} \varepsilon^{\alpha}\left(\varepsilon+\varepsilon^{\alpha}\right)\right)^{1 / 2} \leqslant C M_{0} \frac{\varepsilon|\ln \varepsilon|}{\varepsilon^{\alpha}}\left(\frac{\varepsilon^{\alpha}}{\left(\varepsilon+\varepsilon^{\alpha}\right)^{\mu}}\right)^{1 / 2} \\
& \leqslant C M_{0} \frac{\varepsilon|\ln \varepsilon|}{\varepsilon^{\alpha}}\left(\frac{\varepsilon^{\alpha}}{\varepsilon^{\mu}}\right)^{1 / 2}=C M_{0}|\ln \varepsilon| \varepsilon^{\frac{2-\alpha-\mu}{2}}
\end{aligned}
$$

which converges to zero if $\alpha<2-\mu$, uniformly in $f$ verifying

$$
\|f\|_{\mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant M_{0}
$$

Convergence of $w^{\varepsilon, 3}$.
Proposition 3.4. Let $\mu=1$ and $\alpha \in(0,1)$ be fixed. Then

$$
\left\|w^{\varepsilon, 3}[f]\right\|_{L^{2}\left(\Omega^{\varepsilon}\right)} \rightarrow 0 \quad \text { as } \varepsilon \rightarrow 0
$$

uniformly in $f$ verifying

$$
\|f\|_{\mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant M_{0} .
$$

Proof. We fix $i, j$ and work in the support of $\varphi_{i, j}^{\varepsilon}$. For $x \in \operatorname{supp} \varphi_{i, j}^{\varepsilon}$ fixed, we decompose the integral in the two parts defined in (3.4). Using (2.6), we have for $y \in \Omega_{1}^{\varepsilon}$

$$
|x-y|=\left|\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{-1}\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right)-\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{-1}\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right)\right| \leqslant \varepsilon C\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right| \leqslant C \varepsilon^{1 / 2}
$$

which implies that $\Omega_{1}^{\varepsilon} \subset B\left(x, C \varepsilon^{1 / 2}\right)$. Then we deduce

$$
\left|\int_{\Omega_{1}^{\varepsilon}} \frac{(x-y)^{\perp}}{|x-y|^{2}} f(y) \mathrm{d} y\right| \leqslant \int_{B\left(x, C \varepsilon^{1 / 2}\right)} \frac{|f(y)|}{|x-y|} \mathrm{d} y \leqslant C \varepsilon^{1 / 2}\|f\|_{\mathrm{L}^{\infty}}=C M_{0} \varepsilon^{1 / 2}
$$

In the same way, we deduce from [16, Theorem 4.1] that

$$
\begin{aligned}
\left|\left(D \mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{T}(x) \int_{\Omega_{1}^{\varepsilon}} \frac{\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right)^{\perp}}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|^{2}} f(y) \mathrm{d} y\right| & \leqslant C \| f 1_{B\left(x, C \varepsilon^{1 / 2}\right)\left\|_{\mathrm{L}^{\infty}}^{1 / 2}\right\| f 1_{B\left(x, C \varepsilon^{1 / 2}\right)} \|_{\mathrm{L}^{1}}^{1 / 2}} \\
& \leqslant C \varepsilon^{1 / 2}\|f\|_{\mathrm{L}^{\infty}} \leqslant C M_{0} \varepsilon^{1 / 2}
\end{aligned}
$$

For the second subdomain $\Omega_{2}^{\varepsilon}$, we use the expansion (2.3) of $\mathcal{T}$ to write:

$$
\begin{aligned}
& \frac{(x-y)^{\perp}}{|x-y|^{2}}-\left(D \mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{T}(x) \frac{\left(\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right)^{\perp}}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|^{2}} \\
& = \\
& =\frac{(x-y)^{\perp}}{|x-y|^{2}}-\frac{1}{\varepsilon}\left(\beta \operatorname{Id}+D h\left(\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)\right)^{T} \frac{\left(\beta \frac{x-y}{\varepsilon}+h\left(\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)-h\left(\frac{y-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)\right)^{\perp}}{\left|\beta \frac{x-y}{\varepsilon}+h\left(\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)-h\left(\frac{y-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)\right|^{2}} \\
& = \\
& \quad(x-y)^{\perp} \\
& \quad+\frac{\left(x-y+\frac{\varepsilon}{\beta}\left(h\left(\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)-h\left(\frac{y-\left.\right|_{i, j} ^{\varepsilon, \alpha}}{\varepsilon}\right)\right)\right)^{\perp}}{\left|x-y+\frac{\varepsilon}{\beta}\left(h\left(\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)-h\left(\frac{y-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)\right)\right|^{2}} \\
& = \\
& \quad: J_{1}(x, y)+J_{i, j}^{\varepsilon}(x, y) .
\end{aligned}
$$

Due to (2.6), we have for $y \in \Omega_{2}^{\varepsilon}$

$$
\varepsilon^{-1 / 2} \leqslant\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right| \leqslant \frac{C}{\varepsilon}|x-y|
$$

and we can deduce that $\Omega_{2}^{\varepsilon} \subset B\left(x, \frac{\varepsilon^{1 / 2}}{C}\right)^{c}$. Furthermore $\frac{\varepsilon}{\beta}\left|h\left(\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)-h\left(\frac{y-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)\right| \leqslant C \varepsilon$, then, for $\varepsilon$ small enough, we have

$$
\left|J_{1}(x, y)\right|=\frac{\left|\frac{\varepsilon}{\beta}\left(h\left(\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)-h\left(\frac{y-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)\right)\right|}{|x-y|\left|x-y+\frac{\varepsilon}{\beta}\left(h\left(\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)-h\left(\frac{y-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}\right)\right)\right|} \leqslant \frac{C \varepsilon}{|x-y|\left(\frac{\varepsilon^{1 / 2}}{C}-C \varepsilon\right)} \leqslant \frac{C \varepsilon^{1 / 2}}{|x-y|},
$$

where we have used the relation

$$
\begin{equation*}
\left|\frac{a}{|a|^{2}}-\frac{b}{|b|^{2}}\right|=\frac{|a-b|}{|a||b|} \tag{3.9}
\end{equation*}
$$

Hence we get by (2.2)

$$
\left|\int_{\Omega_{2}^{\varepsilon}} J_{1}(x, y) f(y) \mathrm{d} y\right| \leqslant C \varepsilon^{1 / 2} \int_{\mathbb{R}^{2}} \frac{|f(y)|}{|x-y|} \mathrm{d} y \leqslant C \varepsilon^{1 / 2} M_{0}
$$

For $J_{2}$, we know that there exists $C$ such that $\left|z h^{\prime}(z)\right| \leqslant C$ for any $z$ (see (2.3)), so

$$
\left|J_{2}(x, y)\right| \leqslant \frac{1}{\beta} \frac{C}{\frac{\left|x-z_{i, j}^{\varepsilon, \alpha}\right|}{\varepsilon}} \frac{1}{|x-y|-C \varepsilon} \leqslant \frac{C \varepsilon}{\left|x-z_{i, j}^{\varepsilon, \alpha}\right|} \frac{1}{|x-y|},
$$

hence

$$
\left|\int_{\Omega_{2}^{\varepsilon}} J_{2}(x, y) f(y) \mathrm{d} y\right| \leqslant \frac{C \varepsilon}{\mid x-z_{i, j}^{\varepsilon, \alpha}} \int_{\mathbb{R}^{2}} \frac{|f(y)|}{|x-y|} \mathrm{d} y \leqslant \frac{C \varepsilon M_{0}}{\left|x-z_{i, j}^{\varepsilon, \alpha}\right|}
$$

Putting together the previous estimates, we finally obtain that

$$
\left|w_{i, j}^{\varepsilon, 3}(x)\right| \leqslant 3 C M_{0} \varepsilon^{1 / 2}+\frac{C \varepsilon M_{0}}{\left|x-z_{i, j}^{\varepsilon, \alpha}\right|} .
$$

The $\mathrm{L}^{2}$ norm is easy to estimate for the first right-hand side term:

$$
\left\|\sum_{i, j} \varphi_{i, j}^{\varepsilon} 3 C M_{0} \varepsilon^{1 / 2}\right\|_{L^{2}\left(\Omega^{\varepsilon}\right)} \leqslant 3 C M_{0} \varepsilon^{1 / 2}\left(\left(N_{\varepsilon, \alpha}\right)^{2} 4\left(\varepsilon+\varepsilon^{\alpha}\right)^{2}\right)^{1 / 2} \leqslant C M_{0} \varepsilon^{1 / 2}
$$

which tends to zero as $\varepsilon \rightarrow 0$. Concerning the second right-hand side term, we use that $x$ belongs to the support of $\varphi_{i, j}^{\varepsilon}$ and that there exists $\delta$ such that $B(0, \delta) \subset \mathcal{K}$, hence $x \in B\left(z_{i, j}^{\varepsilon, \alpha}, \sqrt{2}\left(\varepsilon+\varepsilon^{\alpha}\right)\right) \backslash B\left(z_{i, j}^{\varepsilon, \alpha}, \delta \varepsilon\right)$. So we compute

$$
\begin{aligned}
\left\|\sum_{i, j} \varphi_{i, j}^{\varepsilon}(x) \frac{C \varepsilon M_{0}}{\left|x-z_{i, j}^{\varepsilon, \alpha}\right|}\right\|_{\mathrm{L}^{2}\left(\Omega^{\varepsilon}\right)} & \leqslant C \varepsilon M_{0}\left(\sum_{i, j} \int_{B\left(z_{i, j}^{\varepsilon, \alpha}, \sqrt{2}\left(\varepsilon+\varepsilon^{\alpha}\right)\right) \backslash B\left(z_{i, j}^{\varepsilon, \alpha}, \delta \varepsilon\right)} \frac{1}{\left|x-z_{i, j}^{\varepsilon, \alpha}\right|^{2}} \mathrm{~d} x\right)^{1 / 2} \\
& \leqslant C \varepsilon M_{0}\left(\left(N_{\varepsilon, \alpha}\right)^{2} \ln \frac{\sqrt{2}\left(\varepsilon+\varepsilon^{\alpha}\right)}{\delta \varepsilon}\right)^{1 / 2} \leqslant C M_{0}|\ln \varepsilon|^{1 / 2} \varepsilon^{1-\alpha},
\end{aligned}
$$

recalling that $\varepsilon<\varepsilon^{\alpha}$ because we have assumed that $\alpha<1$. This ends the estimate of $w_{i, j}^{\varepsilon, 3}$ :

$$
\left\|w^{\varepsilon, 3}[f]\right\|_{L^{2}\left(\Omega^{\varepsilon}\right)} \leqslant C M_{0}\left(\varepsilon^{1 / 2}+|\ln \varepsilon|^{1 / 2} \varepsilon^{1-\alpha}\right) .
$$

The general idea to treat $w^{\varepsilon, 2}$ and $w^{\varepsilon, 4}$ is the following: if $\mathcal{K}=\bar{B}(0,1)$, then $\mathcal{T}=\operatorname{Id}$ and $\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)=\frac{x-z_{i, j}^{\varepsilon, \alpha}}{\varepsilon}$, so we note that

$$
\varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|=\left|x-z_{i, j}^{\varepsilon, \alpha}+\varepsilon^{2} \frac{y-z_{i, j}^{\varepsilon, \alpha}}{\left|y-z_{i, j}^{\varepsilon, \alpha}\right|^{2}}\right| \sim\left|x-z_{i, j}^{\varepsilon, \alpha}\right|=\varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|
$$

at least when $\left|y-z_{i, j}^{\varepsilon, \alpha}\right|>2 \varepsilon$. Hence we will also decompose the domains in two subdomains in order to use this hint.
Convergence of $w^{\varepsilon, 2}$.
Proposition 3.5. We recall that $\alpha_{c}(\mu)=2-\mu$. Let $\mu \in[0,1]$ and $\alpha \in\left(0, \alpha_{c}(\mu)\right)$ be fixed. Then

$$
\left\|w^{\varepsilon, 2}[f]\right\|_{L^{2}\left(\Omega^{\varepsilon}\right)} \rightarrow 0 \quad \text { as } \varepsilon \rightarrow 0
$$

uniformly in $f$ verifying

$$
\|f\|_{\mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant M_{0}
$$

Proof. For $x \in \operatorname{supp} \nabla^{\perp} \varphi_{i, j}^{\varepsilon}$, we set $z=\varepsilon \mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)$, and changing variables $\eta=\varepsilon \mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)$, we deduce from (2.5) that we need to estimate the following quantity:

$$
\begin{equation*}
w_{i, j}^{\varepsilon, 2}(z):=\frac{1}{2 \pi} \int_{B(0, \varepsilon)^{c}} \ln \frac{\left|z-\varepsilon^{2} \eta^{*}\right|}{|z|} f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right)\left|\operatorname{det} D \mathcal{T}^{-1}\right|\left(\frac{\eta}{\varepsilon}\right) \mathrm{d} \eta . \tag{3.10}
\end{equation*}
$$

From the definition of the cut-off function, we know that $x \in \operatorname{supp} \nabla^{\perp} \varphi_{i, j}^{\varepsilon}$ implies that

$$
\varepsilon+\frac{\varepsilon^{\alpha}}{2} \leqslant\left|x-z_{i, j}^{\varepsilon, \alpha}\right| \leqslant \sqrt{2}\left(\varepsilon+\varepsilon^{\alpha}\right)
$$

then by Lemma 2.2, we deduce that

$$
C_{2}\left(\varepsilon+\frac{\varepsilon^{\alpha}}{2}\right) \leqslant|z| \leqslant C_{1} \sqrt{2}\left(\varepsilon+\varepsilon^{\alpha}\right)
$$

Therefore, for any $\eta \in B(0, \varepsilon)^{c}$ we have

$$
\frac{\left|\varepsilon^{2} \eta^{*}\right|}{|z|} \leqslant \frac{\varepsilon^{2}}{C_{2}\left(\varepsilon+\frac{\varepsilon^{\alpha}}{2}\right)|\eta|}
$$

Hence, using (3.8) with $b=z$ and $c=-\varepsilon^{2} \eta^{*}$, we infer that we have

$$
\begin{equation*}
\left|\ln \frac{\left|z-\varepsilon^{2} \eta^{*}\right|}{|z|}\right| \leqslant 2 \frac{\varepsilon^{2}\left|\eta^{*}\right|}{|z|} \leqslant \frac{2 \varepsilon^{2}}{C_{2}\left(\varepsilon+\frac{\varepsilon^{\alpha}}{2}\right)|\eta|} \quad \text { if } \frac{\varepsilon^{2}}{C_{2}\left(\varepsilon+\frac{\varepsilon^{\alpha}}{2}\right)|\eta|} \leqslant \frac{1}{2} \tag{3.11}
\end{equation*}
$$

Keeping in mind this inequality, we define $R=2 / C_{2}$ and we split the integral (3.10) in two parts: $B(0, R \varepsilon)^{c}$ and $B(0, R \varepsilon) \backslash B(0, \varepsilon)$.

In the first subdomain $B(0, R \varepsilon)^{c}$, we use that $\varepsilon+\varepsilon^{\alpha}>\varepsilon$ and

$$
\frac{\varepsilon^{2}}{C_{2}\left(\varepsilon+\frac{\varepsilon^{\alpha}}{2}\right)|\eta|} \leqslant \frac{\varepsilon^{2}}{C_{2} \varepsilon R \varepsilon}=\frac{1}{2}
$$

hence by (3.11), we compute

$$
\begin{aligned}
& \left.\quad \int_{B(0, R \varepsilon)^{c}} \ln \frac{\left|z-\varepsilon^{2} \eta^{*}\right|}{|z|} f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right)\left|\operatorname{det} D \mathcal{T}^{-1}\right|\left(\frac{\eta}{\varepsilon}\right) \mathrm{d} \eta \right\rvert\, \\
& \leqslant \int_{B(0, R \varepsilon)^{c}} \frac{2 \varepsilon^{2}}{C_{2}\left(\varepsilon+\frac{\varepsilon^{\alpha}}{2}\right)|\eta|}\left|f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right)\right|\left|\operatorname{det} D \mathcal{T}^{-1}\right|\left(\frac{\eta}{\varepsilon}\right) \mathrm{d} \eta \\
& \leqslant \frac{2 \varepsilon^{2}}{C_{2} \varepsilon} \int_{\mathbb{R}^{2}} \frac{\left|f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right)\right|\left|\operatorname{det} D \mathcal{T}^{-1}\right|\left(\frac{\eta}{\varepsilon}\right)}{|\eta|} \mathrm{d} \eta \\
& \leqslant C \varepsilon\left\|f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right) \operatorname{det} D \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)\right\|_{\mathrm{L}^{\infty}}^{1 / 2}\left\|f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right) \operatorname{det} D \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)\right\|_{L^{1}}^{1 / 2} \\
& \leqslant C \varepsilon\|f\|_{\mathrm{L}^{\infty}}^{1 / 2}\|f\|_{\mathrm{L}^{1}}^{1 / 2} \leqslant C M_{0} \varepsilon
\end{aligned}
$$

where we have applied (2.2) for the function $\eta \mapsto\left|f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right)\right|\left|\operatorname{det} D \mathcal{T}^{-1}\right|\left(\frac{\eta}{\varepsilon}\right)$ at $x=0$, used that $D \mathcal{T}^{-1}$ is bounded and that $\left\|f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right) \operatorname{det} D \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)\right\|_{\mathrm{L}^{1}}=\|f\|_{\mathrm{L}^{1}}$ by changing variables back.

In the second subdomain $B(0, R \varepsilon) \backslash B(0, \varepsilon)$, we come back to the original variables: by Lemma 2.2, we compute

$$
\begin{align*}
& \left|\int_{B(0, R \varepsilon) \backslash B(0, \varepsilon)} \ln \frac{\left|z-\varepsilon^{2} \eta^{*}\right|}{|z|} f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right)\right| \operatorname{det} D \mathcal{T}^{-1}\left|\left(\frac{\eta}{\varepsilon}\right) \mathrm{d} \eta\right| \\
& \leqslant \int_{B\left(0, C_{3} R \varepsilon\right) \backslash \mathcal{K}_{i, j}^{\varepsilon, \alpha}}\left|\ln \frac{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|}\right||f(y)| \mathrm{d} y \tag{3.12}
\end{align*}
$$

Now we note that $\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}$ belongs to the unit disk whereas $\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)$ is outside, hence

$$
\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|-1 \leqslant\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right| \leqslant\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|+1
$$

Let $X$ be the point of $\partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}$ such that $\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|-1=\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(X)\right|$. Then, since $x \in \operatorname{supp} \nabla^{\perp} \varphi_{i, j}^{\varepsilon}$, we have $|x-X| \geqslant\left|x-z_{i, j}^{\varepsilon, \alpha}\right|-\left|z_{i, j}^{\varepsilon, \alpha}-X\right| \geqslant \varepsilon^{\alpha} / 2$ and then, with (2.6)

$$
\frac{\varepsilon^{\alpha}}{2} \leqslant|x-X| \leqslant \varepsilon C\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(X)\right|
$$

hence,

$$
\frac{\varepsilon^{\alpha-1}}{2 C\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|} \leqslant \frac{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|} \leqslant 1+\frac{1}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|}
$$

Moreover, Lemma 2.2 yields that $\frac{C_{2}\left(\varepsilon+\varepsilon^{\alpha}\right)}{\varepsilon} \leqslant\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right| \leqslant \frac{C_{1} \sqrt{2}\left(\varepsilon+\varepsilon^{\alpha}\right)}{\varepsilon}$ so

$$
\frac{\varepsilon^{\alpha}}{2 C C_{1} \sqrt{2}\left(\varepsilon+\varepsilon^{\alpha}\right)} \leqslant \frac{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|} \leqslant 1+\frac{\varepsilon}{C_{2}\left(\varepsilon+\varepsilon^{\alpha}\right)} \leqslant 1+\frac{1}{C_{2}}
$$

which implies that

$$
\left|\ln \frac{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|}\right| \leqslant C\left(1+\left|\ln \frac{\varepsilon^{\alpha}}{\varepsilon+\varepsilon^{\alpha}}\right|\right) \leqslant C(1+|\ln \varepsilon|)
$$

Therefore, using (3.12),

$$
\left|\int_{B(0, R \varepsilon) \backslash B(0, \varepsilon)} \ln \frac{\left|z-\varepsilon^{2} \eta^{*}\right|}{|z|} f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)\right)\right| \operatorname{det} D \mathcal{T}^{-1}\left|\left(\frac{\eta}{\varepsilon}\right) \mathrm{d} \eta\right| \leqslant C(1+|\ln \varepsilon|)\|f\|_{\mathrm{L}} \infty \pi\left(C_{3} R \varepsilon\right)^{2}
$$

Putting together the estimates in the two subdomains we get that $w_{i, j}^{\varepsilon, 2}(z)$ is bounded by $C \varepsilon M_{0}$ uniformly for $x \in \nabla^{\perp} \varphi_{i, j}^{\varepsilon}$. Then we conclude as for $w^{\varepsilon, 1}$ :

$$
\left\|w^{\varepsilon, 2}[f]\right\|_{L^{2}\left(\Omega^{\varepsilon}\right)} \leqslant C M_{0} \frac{\varepsilon}{\varepsilon^{\alpha}}\left(N_{\varepsilon, \alpha}^{1+\mu} \varepsilon^{\alpha}\left(\varepsilon+\varepsilon^{\alpha}\right)\right)^{1 / 2} \leqslant C M_{0} \varepsilon^{\frac{2-\alpha-\mu}{2}}
$$

which converges to zero if $\alpha<2-\mu$, uniformly in $f$ verifying

$$
\|f\|_{L^{1} \cap L^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant M_{0} .
$$

Convergence of $w^{\varepsilon, 4}$.
Proposition 3.6. Let $\mu=1$ and $\alpha \in(0,1)$ be fixed. Then

$$
\left\|w^{\varepsilon, 4}[f]\right\|_{L^{2}\left(\Omega^{\varepsilon}\right)} \rightarrow 0 \quad \text { as } \varepsilon \rightarrow 0
$$

uniformly in $f$ verifying

$$
\|f\|_{L^{1} \cap L^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant M_{0}
$$

Proof. The idea is the same as for $w^{\varepsilon, 3}$ : we compare $\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}$ with $\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)$. Let us fix $i, j$ and we work on the support of $\varphi_{i, j}^{\varepsilon}$. We decompose the integral in two parts $\left\{y \in \Omega^{\varepsilon},\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right| \leqslant 2\right\}$ and $\left\{y \in \Omega^{\varepsilon},\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|>2\right\}$. If $y$ verifies $\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right| \leqslant 2$, it implies that there exists $\bar{y} \in \partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}$ such that $\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(\bar{y})\right| \leqslant 1$ (we recall that $\mathcal{T}_{i, j}^{\varepsilon, \alpha}$ maps $\left(\mathcal{K}_{i, j}^{\varepsilon, \alpha}\right)^{c}$ to $\left.\bar{B}(0,1)^{c}\right)$. Hence, by (2.6)

$$
\left|y-z_{i, j}^{\varepsilon, \alpha}\right| \leqslant|y-\bar{y}|+\left|\bar{y}-z_{i, j}^{\varepsilon, \alpha}\right| \leqslant C \varepsilon\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(\bar{y})\right|+\sqrt{2} \varepsilon \leqslant C \varepsilon,
$$

which allows us to estimate in the first subdomain, using [16, Theorem 4.1]:

$$
\begin{aligned}
& \left|\left(D \mathcal{T}_{i, j}^{\varepsilon, \alpha, \alpha}\right)^{T}(x) \int_{\left\{y \in \Omega^{\varepsilon},\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right| \leqslant 2\right\}}\left(\frac{\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|^{2}}-\frac{\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|^{2}}\right)^{\perp} f(y) \mathrm{d} y\right| \\
& \quad \leqslant C\left\|f 1_{B\left(z_{i, j}^{\varepsilon, \alpha}, C \varepsilon\right)}\right\|_{\mathrm{L}^{\alpha} \alpha}^{1 / 2}\left\|f 1_{B\left(z_{i, j}^{\varepsilon, \alpha}, C \varepsilon\right)}\right\|_{\mathrm{L}^{1}}^{1 / 2} \leqslant C \varepsilon\|f\|_{\mathrm{L}^{\infty}} \leqslant C M_{0} \varepsilon .
\end{aligned}
$$

In the second subdomain, we note that $\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|>2$ implies that

$$
\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right| \geqslant\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|-\frac{1}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|} \geqslant \frac{1}{2}
$$

As for $w^{\varepsilon, 2}$, we set $z=\varepsilon \mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)$, and change variables $\eta=\varepsilon \mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)$ to obtain with (3.9):

$$
\begin{aligned}
& \left|\left(D \mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{T}(x) \quad \int_{\left\{y \in \Omega^{\varepsilon},\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|>2\right\}}\left(\frac{\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|^{2}}-\frac{\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|^{2}}\right)^{\perp} f(y) \mathrm{d} y\right| \\
& \quad=\left|(D \mathcal{T})^{T}\left(\frac{x-z_{i, j}^{\varepsilon_{i}}}{\varepsilon}\right) \int_{B(0,2 \varepsilon)^{c}}\left(\frac{z-\varepsilon^{2} \eta^{*}}{\left|z-\varepsilon^{2} \eta^{*}\right|^{2}}-\frac{z}{|z|^{2}}\right)^{\perp} f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right)\right| \operatorname{det} D \mathcal{T}^{-1}\left|\left(\frac{\eta}{\varepsilon}\right) \mathrm{d} \eta\right| \\
& \quad \leqslant C \int_{B(0,2 \varepsilon)^{c}} \frac{\varepsilon^{2}\left|\eta^{*}\right|}{\left|z-\varepsilon^{2} \eta^{*}\right||z|}\left|f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right)\right|\left|\operatorname{det} D \mathcal{T}^{-1}\right|\left(\frac{\eta}{\varepsilon}\right) \mathrm{d} \eta \\
& \quad \leqslant \frac{2 C \varepsilon}{|z|} \int_{B(0,2 \varepsilon)^{c}} \frac{\left|f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right)\right|\left|\operatorname{det} D \mathcal{T}^{-1}\right|\left(\frac{\eta}{\varepsilon}\right)}{|\eta|} \mathrm{d} \eta,
\end{aligned}
$$

so by (2.2)

$$
\begin{aligned}
& \left|\left(D \mathcal{T}_{i, j}^{\varepsilon, \alpha}\right)^{T}(x) \int_{\left\{y \in \Omega^{\varepsilon},\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)\right|>2\right\}}\left(\frac{\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)-\mathcal{T}_{i, j}^{\varepsilon, \alpha}(y)^{*}\right|^{2}}-\frac{\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)}{\left|\mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|^{2}}\right)^{\perp} f(y) \mathrm{d} y\right| \\
& \quad \leqslant \frac{C \varepsilon}{|z|}\left\|f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right) \operatorname{det} D \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)\right\|_{L^{\infty}}^{1 / 2}\left\|f\left(\varepsilon \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)+z_{i, j}^{\varepsilon, \alpha}\right) \operatorname{det} D \mathcal{T}^{-1}\left(\frac{\eta}{\varepsilon}\right)\right\|_{L^{1}}^{1 / 2} \\
& \quad \leqslant \frac{C \varepsilon}{|z|}\|f\|_{\mathrm{L}^{\infty}}^{1 / 2}\|f\|_{\mathrm{L}^{1}}^{1 / 2} \leqslant \frac{C \varepsilon M_{0}}{|z|}
\end{aligned}
$$

where we have changed variables back. Bringing together the estimates in the two subdomains, we conclude that

$$
\left|w_{i, j}^{\varepsilon, 4}(x)\right| \leqslant C M_{0} \varepsilon+\frac{C \varepsilon M_{0}}{\left|\varepsilon \mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|}
$$

As for $\left|w_{i, j}^{\varepsilon, 3}(x)\right|$, the first part is easy to estimate in $\mathrm{L}^{2}$ :

$$
\left\|\sum_{i, j} \varphi_{i, j}^{\varepsilon} C M_{0} \varepsilon\right\|_{\mathrm{L}^{2}\left(\Omega^{\varepsilon}\right)} \leqslant C M_{0} \varepsilon\left(\left(N_{\varepsilon, \alpha}\right)^{2} 4\left(\varepsilon+\varepsilon^{\alpha}\right)^{2}\right)^{1 / 2}=C M_{0} \varepsilon
$$

Concerning the last part, as there exists $\delta$ such that $\operatorname{supp} \varphi_{i, j}^{\varepsilon} \subset B\left(z_{i, j}^{\varepsilon, \alpha}, \sqrt{2}\left(\varepsilon+\varepsilon^{\alpha}\right)\right) \backslash B\left(z_{i, j}^{\varepsilon, \alpha}, \delta \varepsilon\right)$, by Lemma 2.2 we know that $\varepsilon \mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)$ belongs to $B\left(0, C_{1} \sqrt{2}\left(\varepsilon+\varepsilon^{\alpha}\right)\right) \backslash B\left(0, C_{2} \delta \varepsilon\right)$. Hence we use that $\varphi_{i, j}^{\varepsilon}$ have disjoint supports and we change variable $z=\varepsilon \mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)$ :

$$
\begin{aligned}
\left\|\sum_{i, j} \varphi_{i, j}^{\varepsilon}(x) \frac{C \varepsilon M_{0}}{\left|\varepsilon \mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|}\right\|_{\mathrm{L}^{2}\left(\Omega^{\varepsilon}\right)} & \leqslant C \varepsilon M_{0}\left(\sum_{i, j} \int_{\text {supp } \varphi_{i, j}^{\varepsilon}} \frac{1}{\left|\varepsilon \mathcal{T}_{i, j}^{\varepsilon, \alpha}(x)\right|^{2}} \mathrm{~d} x\right)^{1 / 2} \\
& \leqslant C \varepsilon M_{0}\left(\sum_{i, j} \int_{B\left(0, C_{1} \sqrt{2}\left(\varepsilon+\varepsilon^{\alpha}\right)\right) \backslash B\left(0, C_{2} \delta \varepsilon\right)} \frac{1}{|z|^{2}} \mathrm{~d} z\right)^{1 / 2} \\
& \leqslant C \varepsilon M_{0}\left(\left(N_{\varepsilon, \alpha}\right)^{2} \ln \frac{C\left(\varepsilon+\varepsilon^{\alpha}\right)}{\varepsilon}\right)^{1 / 2} \leqslant C M_{0}|\ln \varepsilon|^{1 / 2} \varepsilon^{1-\alpha}
\end{aligned}
$$

Therefore, we have established that

$$
\left\|w^{\varepsilon, 4}[f]\right\|_{L^{2}\left(\Omega^{\varepsilon}\right)} \leqslant C M_{0}\left(\varepsilon+|\ln \varepsilon|^{1 / 2} \varepsilon^{1-\alpha}\right),
$$

which tends to zero as $\varepsilon \rightarrow 0$, because we are considering the case $\alpha<1$. Its ends this proof.
Bringing together all the propositions of this subsection, we have proved the following theorem:
Theorem 3.7. We recall that $\alpha_{c}(\mu)=2-\mu$. Let $\mu \in[0,1]$ and $\alpha \in\left(0, \alpha_{c}(\mu)\right)$ be fixed. Then

$$
\left\|w^{\varepsilon}[f]\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{2}\right)} \rightarrow 0 \quad \text { as } \varepsilon \rightarrow 0,
$$

uniformly in $f$ verifying

$$
\|f\|_{\mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant M_{0} .
$$

### 3.2. Convergence of $r^{\varepsilon}$

In the decomposition

$$
u^{\varepsilon}[f]-K_{\mathbb{R}^{2}}\left[f 1_{\Omega^{\varepsilon}}\right]=r^{\varepsilon}[f]-w^{\varepsilon}[f],
$$

with

$$
w^{\varepsilon}[f]=K_{\mathbb{R}^{2}}\left[f 1_{\Omega^{\varepsilon}}\right]-v^{\varepsilon}[f] \quad \text { and } \quad r^{\varepsilon}[f]:=u^{\varepsilon}[f]-v^{\varepsilon}[f],
$$

we have already dealt with $w^{\varepsilon}$. Now we identify $r^{\varepsilon}$ as the Leray projector of $w^{\varepsilon}$ on $\Omega^{\varepsilon}$ :
Lemma 3.8. With the above definition, for any $\alpha>0, \mu \in[0,1]$ and $\varepsilon>0, r^{\varepsilon}[f]$ is the Leray projector of $w^{\varepsilon}[f]$ :

$$
r^{\varepsilon}[f]=\mathbb{P}^{\varepsilon}\left(w^{\varepsilon}[f]\right) .
$$

Proof. Any $u$ can be decomposed as $u=v+\nabla p$, where $v=\mathbb{P}^{\varepsilon}(u)$ is the Leray projector on $\Omega^{\varepsilon}$, i.e. the unique vector satisfying

$$
\begin{cases}\operatorname{div} v=0, & \text { in } \Omega^{\varepsilon}, \\ \operatorname{curl} v=\operatorname{curl} u, & \text { in } \Omega^{\varepsilon}, \\ v \cdot \mathbf{n}=0, & \text { on } \partial \Omega^{\varepsilon}, \\ \oint_{\partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}} v \cdot \tau \mathrm{~d} s=\oint_{\partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}} u \cdot \tau \mathrm{~d} s, & \text { for any } j \in\left\{1, \ldots, n_{2}\right\}, i \in\left\{1, \ldots, n_{1}\right\} .\end{cases}
$$

In our case, we have according to (2.13) and (3.1):

$$
\begin{cases}\operatorname{div} r^{\varepsilon}[f]=0 & \text { in } \Omega^{\varepsilon}, \\ \operatorname{curl} r^{\varepsilon}[f]=f-\operatorname{curl} v^{\varepsilon}[f]=\operatorname{curl} w^{\varepsilon}[f] & \text { in } \Omega^{\varepsilon}, \\ r^{\varepsilon}[f] \cdot \mathbf{n}=0 & \text { on } \partial \Omega^{\varepsilon}, \\ \oint_{\partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}} r^{\varepsilon}[f] \cdot \tau \mathrm{d} s=\oint_{\partial \mathcal{K}_{i, j}^{\varepsilon, \alpha}} w^{\varepsilon}[f] \cdot \tau \mathrm{d} s & \text { for any } j, i .\end{cases}
$$

The last equality comes from the equality $r^{\varepsilon}[f]=u^{\varepsilon}[f]-K_{\mathbb{R}^{2}}\left[f 1_{\Omega^{\varepsilon}}\right]+w^{\varepsilon}[f]$ and the Green formula

$$
\oint_{\partial \mathcal{K}_{i, j}^{s, \alpha}} K_{\mathbb{R}^{2}}\left[f 1_{\Omega^{\varepsilon}}\right] \cdot \tau \mathrm{d} s=\int_{\mathcal{K}_{i, j}^{s, \alpha}} f 1_{\Omega^{\varepsilon}}=0,
$$

because $1_{\Omega^{\varepsilon}}$ is the characteristic function on $\Omega^{\varepsilon}$. The uniqueness of the decomposition yields the lemma.

The convergence of $r^{\varepsilon}[f]$ is now obvious. Indeed, we recall that the Leray projector is orthogonal for the $\mathrm{L}^{2}$ norm, then for any $\alpha, \mu, \varepsilon$ and $f$ we have:

$$
\left\|r^{\varepsilon}[f]\right\|_{\mathrm{L}^{2}\left(\Omega^{\varepsilon}\right)} \leqslant\left\|w^{\varepsilon}[f]\right\|_{\mathrm{L}^{2}\left(\Omega^{\varepsilon}\right)} \leqslant\left\|w^{\varepsilon}[f]\right\|_{\mathrm{L}^{2}\left(\mathbb{R}^{2}\right)}
$$

So, extending $u^{\varepsilon}[f]$ by zero inside the inclusions, we deduce directly from Theorem 3.7:
Theorem 3.9. We recall that $\alpha_{c}(\mu)=2-\mu$. Let $\mu \in[0,1]$ and $\alpha \in\left(0, \alpha_{c}(\mu)\right)$ be fixed. Then

$$
\left\|u^{\varepsilon}[f]-K_{\mathbb{R}^{2}}\left[f 1_{\Omega^{\varepsilon}}\right]\right\|_{L^{2}\left(\mathbb{R}^{2}\right)} \rightarrow 0 \quad \text { as } \varepsilon \rightarrow 0,
$$

uniformly in $f$ verifying

$$
\|f\|_{\mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant M_{0} .
$$

## 4. Proof of the main theorem

The way to conclude comes from [19] and we write the main steps for a sake of completeness. In general the Sobolev and Lebesgue spaces are considered in the full plane, and $\left(u^{\varepsilon}, \omega^{\varepsilon}\right)$ are extended by zero in the obstacles. In all this section, we fix $\mu \in[0,1]$ and $\alpha \in\left(0, \alpha_{c}(\mu)\right)$.

### 4.1. Weak convergence of the vorticity

Thanks to the transport equation (1.10), extracting a subsequence, we have that

$$
\omega^{\varepsilon} \rightharpoonup \omega \quad \text { weak-* in } \mathrm{L}^{\infty}\left(\mathbb{R}^{+} ; \mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\mathbb{R}^{2}\right)\right),
$$

which establishes the point (b) of Theorem 1.2, up to a subsequence.
We introduce

$$
M_{0}:=\max \left\{\left\|\omega_{0}\right\|_{L^{1}\left(\mathbb{R}^{2}\right)},\left\|\omega_{0}\right\|_{L^{\infty}\left(\mathbb{R}^{2}\right)}\right\},
$$

hence for any $t$ and $\varepsilon$

$$
\begin{equation*}
\left\|\omega^{\varepsilon}(t, \cdot)\right\|_{\mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\mathbb{R}^{2}\right)} \leqslant M_{0} \tag{4.1}
\end{equation*}
$$

### 4.2. Strong convergence of the velocity

First we begin by a temporal estimate.
Lemma 4.1. There exists a constant $C$ independent of $\varepsilon$ and $t$ such that

$$
\left\|\partial_{t} \omega^{\varepsilon}\right\|_{\mathrm{H}^{-1}\left(\mathbb{R}^{2}\right)} \leqslant C
$$

Proof. For any $\varepsilon>0$, as $u^{\varepsilon}$ is regular enough and tangent to the boundary, we can write the equation verified by $\omega^{\varepsilon}$ for any test function $\varphi \in \mathrm{H}^{1}\left(\mathbb{R}^{2}\right)$ :

$$
\left(\partial_{t} \omega^{\varepsilon}, \varphi\right)_{\mathrm{H}^{-1} \times \mathrm{H}^{1}}=\int_{\Omega^{\varepsilon}} u^{\varepsilon} \omega^{\varepsilon} \cdot \nabla \varphi=\int_{\mathbb{R}^{2}}\left(u^{\varepsilon}-K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}\right]\right) \omega^{\varepsilon} \cdot \nabla \varphi+\int_{\mathbb{R}^{2}} K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}\right] \omega^{\varepsilon} \cdot \nabla \varphi,
$$

which is bounded by $C\|\nabla \varphi\|_{L^{2}}$ for the following reason. According to (4.1), Theorem 3.9 states that $u^{\varepsilon}-K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}\right]$ is uniformly bounded in $L^{2}\left(\mathbb{R}^{2}\right)$ which gives the estimate for the first right-hand side term. For the second term, we know from (2.2) and (4.1) that $K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}\right]$ is uniformly bounded whereas $\omega^{\varepsilon}$ is uniformly bounded in $\mathrm{L}^{2}$. It gives the desired estimates in $\mathrm{H}^{-1}$.

Lemma 4.2. There exists a subsequence of $\omega^{\varepsilon}\left(\right.$ again denoted by $\left.\omega^{\varepsilon}\right)$ such that $\omega^{\varepsilon}(t, \cdot) \rightharpoonup \omega(t, \cdot)$ in weak- $\mathrm{L}^{4}\left(\mathbb{R}^{2}\right)$ and in weak-L $\mathrm{L}^{\frac{4}{3}}\left(\mathbb{R}^{2}\right)$ for all $t$.

Proof. The proof of this lemma is done in [19, Proposition 5.2]. The idea is the following: by Banach-Alaoglu's theorem, we can extract, for each $t$, a subsequence such that $\omega^{\varepsilon}(t, \cdot) \rightharpoonup \omega(t, \cdot)$ in weak-L $\mathcal{L}^{4}\left(\mathbb{R}^{2}\right)$ and in weak-L ${ }^{\frac{4}{3}}\left(\mathbb{R}^{2}\right)$, but the subsequence depends on the time $t$, whereas we want a common sequence for each $t$. For that, we choose by diagonal extraction a common sequence for each $t \in \mathbb{Q}$. Next, for any test function in $\mathcal{C}_{0}^{\infty}\left(\mathbb{R}^{2}\right)$ and thanks to the time estimate of the previous lemma, we prove that the sequence works for all $t$. The desired result is obtained by the density of $\mathcal{C}_{0}^{\infty}\left(\mathbb{R}^{2}\right)$ in $H^{1}\left(\mathbb{R}^{2}\right)$.

Now, defining $u:=K_{\mathbb{R}^{2}}[\omega]$, we use this subsequence to pass to the limit in the decomposition

$$
\begin{equation*}
u^{\varepsilon}-u=\left(u^{\varepsilon}-K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}\right]\right)+K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}-\omega\right] . \tag{4.2}
\end{equation*}
$$

Theorem 4.3. We have $u^{\varepsilon} \rightarrow u$ strongly in $\mathrm{L}_{\mathrm{loc}}^{2}\left(\mathbb{R}^{+} \times \mathbb{R}^{2}\right)$, with $u=K_{\mathbb{R}^{2}}[\omega]$.
Proof. The first term on the right-hand side of (4.2) converges uniformly in time to zero in $L^{2}\left(\mathbb{R}^{2}\right)$ (see Theorem 3.9 and (4.1)). Then the dominated convergence theorem gives the limit in $\mathrm{L}_{\text {loc }}^{2}\left(\mathbb{R}^{+} \times \mathbb{R}^{2}\right)$.

Concerning the last term: for $x$ fixed, the map $y \mapsto \frac{(x-y)^{\perp}}{|x-y|^{2}}$ belongs to $\mathrm{L}^{4 / 3}(B(x, 1)) \cap \mathrm{L}^{4}\left(B(x, 1)^{c}\right)$, then Lemma 4.2 implies that for all $t, x$, we have

$$
\int_{\mathbb{R}^{2}} \frac{(x-y)^{\perp}}{|x-y|^{2}}\left(\omega^{\varepsilon}-\omega\right)(t, y) \mathrm{d} y \rightarrow 0 \quad \text { as } \varepsilon \rightarrow 0
$$

So, this integral converges pointwise to zero, and it is uniformly bounded by (2.2) with respect of $x$ and $t$. Applying the dominated convergence theorem, we obtain the convergence of $K_{\mathbb{R}^{2}}\left[\omega^{\varepsilon}-\omega\right]$ in $\mathrm{L}_{\mathrm{loc}}^{2}\left(\mathbb{R}^{+} \times \mathbb{R}^{2}\right)$. This ends the proof.

This theorem gives the point (a) of Theorem 1.2, up to a subsequence.

### 4.3. Passing to the limit in the Euler equations

The purpose of the rest of this section is to prove that $(u, \omega)$ is the unique solution of the Euler equations in $\mathbb{R}^{2}$.
Theorem 4.4. The pair $(u, \omega)$ obtained is a weak solution of the Euler equations in $\mathbb{R}^{2}$.
Proof. The divergence and curl conditions are verified by the expression: $u=K_{\mathbb{R}^{2}}[\omega]$.
Next, we use that $u^{\varepsilon}$ and $\omega^{\varepsilon}$ verify (1.9) in the sense of distribution in $\Omega^{\varepsilon}$ and the fact that $u^{\varepsilon}$ is regular and tangent to the boundary, to infer that for any test function $\varphi \in \mathcal{C}_{0}^{\infty}\left([0, \infty) \times \mathbb{R}^{2}\right)$, we have

$$
\int_{0}^{\infty} \int_{\mathbb{R}^{2}} \varphi_{t} \omega^{\varepsilon} \mathrm{d} x \mathrm{~d} t+\int_{0}^{\infty} \int_{\mathbb{R}^{2}} \nabla \varphi \cdot u^{\varepsilon} \omega^{\varepsilon} \mathrm{d} x \mathrm{~d} t=-\int_{\mathbb{R}^{2}} \varphi(0, x) \omega_{0}(x) 1_{\Omega^{\varepsilon}} \mathrm{d} x,
$$

because we have extended $\omega^{\varepsilon}$ by zero and set $\omega^{\varepsilon}(0, \cdot)=\omega_{0} 1_{\Omega^{\varepsilon}}$. By passing to the limit as $\varepsilon \rightarrow 0$, thanks to the strong-weak convergence of the pair $\left(u^{\varepsilon}, \omega^{\varepsilon}\right)$, we conclude that $(u, \omega)$ verifies the vorticity equation. In the full plane, this is equivalent to state that $u$ verifies the velocity equation.

All the results of this section state that for any sequence $\varepsilon_{k} \rightarrow 0$, we can extract a subsequence such that $\left(u^{\varepsilon}, \omega^{\varepsilon}\right)$ converges to $(u, \omega)$, which is a global weak solution to the 2D Euler equations in the full plane, and where $\omega$ belongs to $\mathrm{L}^{\infty}\left(\mathbb{R}^{+} ; \mathrm{L}^{1} \cap \mathrm{~L}^{\infty}\left(\mathbb{R}^{2}\right)\right.$ ). Such a solution is unique by the celebrated Yudovich's work [17]. Therefore, this solution is the strong solution with initial datum $\omega_{0}$, and we deduce from the uniqueness that the convergences hold without extracting a subsequence. This ends the proof of Theorem 1.2.

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