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Optimal control

Carleman inequalities for the heat equation in singular domains

Inégalités de Carleman pour l'équation de la chaleur dans des domaines singuliers

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ABSTRACT

We consider the Cauchy problem associated to the heat equation firstly in a plane domain with a reentrant corner, then in a cracked domain. By constructing a weight function, we show a result of null controllability using Carleman estimates.

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R É S U M É

On considère le problème de Cauchy associé à l'équation de la chaleur dans un domaine plan avec un coin rentrant puis dans un domaine fissuré. En construisant une fonction poids, on montre un résultat de nulle contrôlabilité grâce à des estimations de type Carleman.

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Notations et hypothèses

Soit Ω un domaine borné de frontière Γ , on note ν la normale unitaire sortante. Soit $\omega \Subset \Omega$ un ouvert non vide de Ω . Pour tout $T > 0$, on pose $Q_T = \Omega \times (0, T)$ et $\Sigma_T = \Gamma \times (0, T)$.

On s'intéresse aux cas suivants :

Cas 1. Ω est un domaine avec un coin rentrant en un point S de Γ d'angle φ , $\pi < \varphi < 2\pi$. $\Gamma \setminus \{S\}$ est supposée régulière.

Cas 2. Ω est un domaine avec une seule fissure rectiligne σ débouchante. On désignera par S sa pointe et par Γ_1 la partie $\Gamma \setminus \sigma$, Γ_1 est supposée régulière.

Étant donnée f dans $L^2(\Omega)$, l'unique solution $u \in H_0^1(\Omega)$ du problème de Dirichlet

$$\begin{cases} -\Delta u = f & \text{dans } \Omega, \\ u = 0 & \text{sur } \Gamma \end{cases}$$

est donnée (P. Grisvard [4]) par :

$$u(r, \theta) = u_R + cr^{\frac{\pi}{\varphi}} \sin\left(\frac{\pi}{\varphi}\theta\right), \quad \pi < \varphi \leq 2\pi$$

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où $u_R \in H_0^1(\Omega) \cap H^2(\Omega)$ désigne la partie régulière de u , c une constante dépendante de f et (r, θ) les coordonnées polaires locales au point S .

Notons que $D(-\Delta) \subset H^s(\Omega)$ où $\frac{3}{2} < s < 2$ dans le 1er cas, et $1 < s < \frac{3}{2}$ dans le 2ème cas.

Position du problème

Le problème de nulle contrôlabilité pour l'équation de la chaleur consiste à trouver, pour toute donnée $u_0 \in L^2(\Omega)$, un contrôle v défini dans $L^2(Q_T)$ tel que la solution du problème de Cauchy

$$(P) \begin{cases} u_t - \Delta u = \chi_\omega v & \text{dans } Q_T, \\ u = 0 & \text{dans } \Sigma_T, \\ u(0) = u_0 & \text{dans } \Omega \end{cases}$$

satisfait $u(T) = 0$. Cela peut être établi à partir d'une inégalité d'observabilité pour le problème adjoint associé

$$(P^*) \begin{cases} -q_t - \Delta q = 0 & \text{dans } Q_T, \\ q = 0 & \text{dans } \Sigma_T, \\ q(T) = q_T & \text{dans } \Omega \end{cases}$$

de type

$$\|q(0)\|_{L^2(\Omega)}^2 \leq C \int_{\omega \times (0, T)} |q(t, x)|^2 dx dt, \quad \forall q_T \in L^2(\Omega).$$

Les estimations de Carleman sont un outil efficace pour montrer de telles inégalités. La preuve est basée sur la construction, pour tout ouvert $\omega \Subset \Omega$ non vide, d'une fonction poids vérifiant

$$\beta \in C^2(\overline{\Omega}), \quad \beta > 0 \text{ dans } \Omega, \quad \beta|_\Gamma = 0, \quad |\nabla \beta| \geq C > 0 \text{ dans } \overline{\Omega \setminus \omega}.$$

L'existence d'une telle fonction dans un domaine singulier n'a pas été démontrée. Néanmoins, on a pu justifier dans ce travail l'inégalité de Carleman, en construisant une fonction poids vérifiant :

$$\beta \in C^1(\overline{\Omega}) \cap W^{2,\infty}(\Omega), \quad \beta > 0 \text{ dans } \Omega, \quad |\nabla \beta| \geq C > 0 \text{ dans } \overline{\Omega \setminus \omega} \text{ et } \frac{\partial \beta}{\partial \nu} \leq 0 \text{ sur } \Gamma.$$

Pour $q_T \in L^2(\Omega)$, (P^*) admet une unique solution dans $C^0([0, T], L^2(\Omega)) \cap C^0([0, T], D(-\Delta)) \cap C^1([0, T], L^2(\Omega))$. On rappelle que si le domaine Ω est régulier on a $D(-\Delta) = H^2(\Omega) \cap H_0^1(\Omega)$, la solution est donc assez régulière pour justifier les calculs. Ce n'est pas notre cas. Pour contourner la difficulté, on approche la solution q par une suite de fonctions régulières.

Résultat principal

Théorème. Pour tout u_0 dans $L^2(\Omega)$, il existe $v \in L^2(Q_T)$ tel que la solution du problème (P) vérifie $u(T) = 0$.

Dans la preuve, on obtient une inégalité grâce à la proposition suivante :

Proposition. Il existe trois constantes $\lambda_1 = \lambda_1(\Omega, \omega) \geq 1$, $s_1 = s_1(\Omega, \omega)(T + T^2)$ et $C_1 = C_1(\Omega, \omega)$ telles que, pour tout $\lambda \geq \lambda_1$ et $s \geq s_1$ l'inégalité suivante soit vérifiée :

$$s^{-1} \int_{Q_T} e^{-2s\alpha} \xi^{-1} (|q_t|^2 + |\Delta q|^2) dx dt + s\lambda^2 \int_{Q_T} e^{-2s\alpha} \xi |\nabla q|^2 dx dt + s^3 \lambda^4 \int_{Q_T} e^{-2s\alpha} \xi^3 |q|^2 dx dt \leq C_1 \left(s^3 \lambda^4 \int_{\omega \times (0, T)} e^{-2s\alpha} \xi^3 |q|^2 dx dt \right), \tag{1}$$

où q est la solution de (P^*) , α et ξ sont données par (2).

Pour cela, on construit une fonction poids qui vérifie les propriétés données par le lemme suivant :

Lemme. Soit $\omega \Subset \Omega$ un ouvert non vide, il existe une fonction β définie dans $\overline{\Omega}$ vérifiant :

$$\beta \in C^1(\overline{\Omega}) \cap W^{2,\infty}(\Omega), \quad \beta > 0 \text{ dans } \Omega, \quad |\nabla \beta| > 0 \text{ dans } \overline{\Omega \setminus \omega}, \quad \frac{\partial \beta}{\partial \nu} \leq 0 \text{ sur } \Gamma.$$

1. Notations and assumptions

Let Ω be a bounded domain in \mathbb{R}^2 with boundary Γ . We denote by ν the outward unit normal vector field on Γ . Let $\omega \Subset \Omega$ be a nonempty open subset of Ω . For $T > 0$, we set $Q_T = \Omega \times (0, T)$ and $\Sigma_T = \Gamma \times (0, T)$. There are two different situations that will be considered in this Note:

Case 1. Ω is supposed to have a reentrant corner at a point S ($S \in \Gamma$) of measure φ , $\pi < \varphi < 2\pi$. $\Gamma \setminus \{S\}$ is supposed regular.

Case 2. Ω contains one straight emerging crack σ , we will designate by S its tip and by Γ_1 the part $\Gamma \setminus \sigma$, Γ_1 is supposed regular.

Given f in $L^2(\Omega)$, the unique solution $u \in H_0^1(\Omega)$ of the Dirichlet problem

$$\begin{cases} -\Delta u = f & \text{in } \Omega, \\ u = 0 & \text{on } \Gamma. \end{cases}$$

is, according to P. Grisvard [4], given by

$$u(r, \theta) = u_R + cr^{\frac{\pi}{\varphi}} \sin\left(\frac{\pi}{\varphi}\theta\right), \quad \pi < \varphi \leq 2\pi,$$

where $u_R \in H_0^1(\Omega) \cap H^2(\Omega)$ is the regular part of u , c is a real constant depending of the data f and (r, θ) are the local polar coordinates at S .

Note that, $D(-\Delta) \subset H^s(\Omega)$ with $\frac{3}{2} < s < 2$ in Case 1 and $1 < s < \frac{3}{2}$ in Case 2.

2. Statement of the problem

The null controllability for the heat equation is as follows: For any Cauchy data u_0 , find a control v defined in $L^2(Q_T)$ such that the solution of the Cauchy problem,

$$(P) \quad \begin{cases} u_t - \Delta u = \chi_\omega v & \text{in } Q_T, \\ u = 0 & \text{on } \Sigma_T, \\ u(0) = u_0 & \text{in } \Omega \end{cases}$$

satisfies $u(T) = 0$. The null controllability can be deduced from an inequality of observability to the associated adjoint problem,

$$(P^*) \quad \begin{cases} -q_t - \Delta q = 0 & \text{in } Q_T, \\ q = 0 & \text{on } \Sigma_T, \\ q(T) = q_T & \text{in } \Omega \end{cases}$$

of the type

$$\|q(0)\|_{L^2(\Omega)}^2 \leq C \int_{\omega \times (0, T)} |q(t, x)|^2 dt dx, \quad \forall q_T \in L^2(\Omega).$$

A powerful tool to prove such inequalities is Carleman estimates. The proof is based on the construction, for each nonempty open subset $\omega \Subset \Omega$, of a weight function β satisfying

$$\beta \in C^2(\overline{\Omega}), \quad \beta > 0 \quad \text{in } \Omega, \quad \beta|_\Gamma = 0, \quad |\nabla \beta| \geq C > 0 \quad \text{in } \overline{\Omega \setminus \omega}.$$

The existence of such a function in a singular domain has not been proved. Nevertheless, we were able in this work to justify Carleman's inequality by constructing a weight function β satisfying

$$\beta \in C^1(\overline{\Omega}) \cap W^{2,\infty}(\Omega), \quad \beta > 0 \quad \text{in } \Omega, \quad |\nabla \beta| \geq C > 0 \quad \text{in } \overline{\Omega \setminus \omega} \quad \text{and} \quad \frac{\partial \beta}{\partial \nu} \leq 0 \quad \text{on } \Gamma.$$

For $q_T \in L^2(\Omega)$, (P^*) admits a unique solution in

$$C^0([0, T], L^2(\Omega)) \cap C^0([0, T[, D(-\Delta)) \cap C^1([0, T[, L^2(\Omega)).$$

When the domain Ω is regular $D(-\Delta) = H^2(\Omega) \cap H_0^1(\Omega)$, the solution is then sufficiently smooth to justify the calculus. That is not our case. To encounter this difficulty, we approximate the solution q by a sequence of regular functions.

3. Main results

Theorem. For every $u_0 \in L^2(\Omega)$, there exists $v \in L^2(Q_T)$ such that the solution u of **(P)** satisfies $u(T) = 0$.

Proof of the theorem. It's a consequence of the proposition below.

First, let λ be a sufficiently large positive constant that depends only on Ω and ω . Following [2] and [3] we introduce the functions

$$\alpha(x, t) = \frac{e^{2\lambda m \|\beta\|_\infty} - e^{\lambda(m\|\beta\|_\infty + \beta(x))}}{t(T-t)}, \quad \xi(x, t) = \frac{e^{\lambda(m\|\beta\|_\infty + \beta(x))}}{t(T-t)} \quad t \in (0, T) \tag{2}$$

where $m > 1$ and β is a suitable weight function which will be constructed in the sequel.

Proposition. There exist three constants $\lambda_1 = \lambda_1(\Omega, \omega) \geq 1$, $s_1 = s_1(\Omega, \omega)(T + T^2)$ and $C_1 = C_1(\Omega, \omega)$ such that, for any $\lambda \geq \lambda_1$ et $s \geq s_1$ the next inequality holds:

$$\begin{aligned} & s^{-1} \int_{Q_T} e^{-2s\alpha} \xi^{-1} (|q_t|^2 + |\Delta q|^2) \, dx \, dt + s\lambda^2 \int_{Q_T} e^{-2s\alpha} \xi |\nabla q|^2 \, dx \, dt + s^3 \lambda^4 \int_{Q_T} e^{-2s\alpha} \xi^3 |q|^2 \, dx \, dt \\ & \leq C_1 \left(s^3 \lambda^4 \int_{\omega \times (0, T)} e^{-2s\alpha} \xi^3 |q|^2 \, dx \, dt \right), \end{aligned} \tag{3}$$

where q is the solution of **(P*)**.

We set $\psi = e^{-s\alpha} q$, we write the equation verified by ψ in the form

$$M_1 \psi + M_2 \psi = g_{s,\lambda}$$

where

$$\begin{cases} M_1 \psi = -2s\lambda^2 |\nabla \beta|^2 \xi \psi - 2s\lambda \nabla \xi \cdot \nabla \psi + \psi_t, \\ M_2 \psi = s^2 \lambda^2 |\nabla \beta|^2 \xi^2 \psi + \Delta \psi + s\alpha_t \psi, \\ g_{s,\lambda} = s\lambda \Delta \beta \xi \psi - s\lambda^2 |\nabla \beta|^2 \xi \psi. \end{cases}$$

We note by $(M_i \psi)_j$ the j -th term in the expression of $M_i \psi$. We have:

$$\|M_1 \psi\|_{L^2(Q_T)}^2 + \|M_2 \psi\|_{L^2(Q_T)}^2 + 2 \sum_{i,j=1}^3 \langle (M_1 \psi)_i, (M_2 \psi)_j \rangle_{L^2(Q_T)} = \|g_{s,\lambda}\|_{L^2(Q_T)}^2.$$

The regularity of the solution q is not sufficient to do some integrations by parts in $\langle (M_1 \psi)_i, (M_2 \psi)_j \rangle_{L^2(Q_T)}$. We show that there exists a sequence $(q_n^T)_n \subset D((-\Delta)^2)$ which converges to q_T in $L^2(\Omega)$.

Let q_n be the solution of the approximate problem:

$$\begin{cases} \partial_t q_n + \Delta q_n = 0 & \text{in } Q_T, \\ q_n = 0 & \text{on } \Sigma_T, \\ q_n(T) = q_n^0 & \text{in } \Omega. \end{cases}$$

We set $\psi_n = e^{-s\alpha} q_n$.

Lemma 1. We have

$$\begin{aligned} & s^{-1} \int_{Q_T} \xi^{-1} (|\psi_{nt}|^2 + |\Delta \psi_n|^2) \, dx \, dt + s\lambda^2 \int_q \xi |\nabla \psi_n|^2 \, dx \, dt + s^3 \lambda^4 \int_q \xi^3 |\psi_n|^2 \, dx \, dt \\ & \leq C_1 s^3 \lambda^4 \int_{\mathbb{O} \times (0, T)} \xi^3 |\psi_n|^2 \, dx \, dt, \end{aligned} \tag{4}$$

for $\lambda > C(\Omega, \omega)$ and $s > C(\Omega, \mathcal{O})(T + T^2)$.

Proof of Lemma 1.

Case 1. When Ω is a domain with a reentrant corner, we have just to follow [2].

Case 2. Ω is a domain with a straight emerging crack of a tip S . Suppose that S is the origin of the Euclidean coordinates system (x_1, x_2) and that the positive x_1 -axis contains the crack.

Set $\Omega_\varepsilon = \Omega \setminus B(0, \varepsilon)$, $\varepsilon > 0$. By integration by parts in Ω_ε , for $\varepsilon > 0$ small enough and taking the limit as $\varepsilon \rightarrow 0$, we get the inequality (4). \square

Lemma 2. We have

1. (q_n) converges to q in $L^2(0, T, H_0^1(\Omega))$.
2. $(\Delta\psi_n)$ converges to $\Delta\psi$ in $L^2(Q_T)$.

Letting $n \rightarrow +\infty$, we obtain the same inequality for ψ . Arguing as [2], we deduce the Carleman's estimate (3).

Lemma 3 (Case 1). Let $\omega \Subset \Omega$, there exists a function β defined in $\overline{\Omega}$ satisfying:

$$\beta \in C^1(\overline{\Omega}) \cap W^{2,\infty}(\Omega), \quad \beta > 0 \text{ in } \Omega, \quad |\nabla\beta| \neq 0 \text{ in } \overline{\Omega} \setminus \omega \text{ and } \frac{\partial\beta}{\partial\nu} < 0 \text{ on } \Gamma.$$

Lemma 4 (Case 2). Let $\omega \Subset \Omega$, there exists a function β defined in $\overline{\Omega}$ satisfying:

$$\beta \in C^1(\overline{\Omega}) \cap W^{2,\infty}(\Omega), \quad \beta > 0 \text{ in } \Omega, \quad |\nabla\beta| \neq 0 \text{ in } \overline{\Omega} \setminus \omega, \quad \frac{\partial\beta}{\partial\nu} < 0 \text{ on } \Gamma_1 \text{ and } \frac{\partial\beta}{\partial\nu^\pm} = 0 \text{ on } \sigma.$$

Proof of Lemma 3. The boundary Γ will be parameterized by the arc length l with origin at S .

Let us fix two points M_1 and M_2 on Γ close enough to S satisfying $l(M_1)l(M_2) < 0$. We note Γ_S the part $\widehat{M_1M_2}$ of Γ containing S and $\Gamma' = \Gamma \setminus \Gamma_S$. We can prove the existence of a function β_s satisfying

$$\beta_s \in C^2(\overline{\Omega}), \quad \beta_s > 0 \text{ in } \overline{\Omega}, \quad \frac{\partial\beta_s}{\partial\nu} < 0 \text{ on } \Gamma_S \text{ and } |\nabla\beta_s| > 0 \text{ in } \Omega.$$

One can take, for instance

$$\beta_s(x, y) = by + c$$

where $b > 0$ and $c > 0$ is large enough.

We denote by $\Omega' \subset \Omega$ a smooth subdomain of class C^2 such that $\partial\Omega' = \Gamma_0 \cup \Gamma'$ and $\frac{\partial\beta_s}{\partial\nu} < 0$ on Γ_0 .

Let us now set $g_0 = \beta_s|_{\Gamma_0}$ and $h_0 = \frac{\partial\beta_s}{\partial\nu}|_{\Gamma_0}$, we extend g_0 (resp. h_0) to $\partial\Omega'$ by a function g (resp. h) of class C^2 (resp. C^1) such that $g > 0$, $h < 0$ on $\partial\Omega'$.

Let \tilde{g} a C^2 lift of g_0 to Ω' such that $\frac{\partial\tilde{g}}{\partial\nu} = h$ on $\partial\Omega'$ and $\tilde{g} > 0$ in Ω' .

For $\varepsilon > 0$, we set $U_\varepsilon = \{X \in \Omega', \text{dist}(X, \partial\Omega') < \varepsilon\}$. As $\frac{\partial\tilde{g}}{\partial\nu} = h < 0$ on $\partial\Omega'$ then, for $\varepsilon > 0$ small enough we have $|\nabla\tilde{g}| \neq 0$ in $\overline{U_\varepsilon}$, so that \tilde{g} satisfies: $\tilde{g} > 0$ in $\overline{U_\varepsilon}$, $|\nabla\tilde{g}| \neq 0$ in $\overline{U_\varepsilon}$ and $\tilde{g} \in C^2(\overline{U_\varepsilon})$.

Using the same ideas as in [1] and [3], we establish the existence of a function β' satisfying

$$\beta' \in C^2(\overline{\Omega'}), \quad \beta' > 0 \text{ in } \Omega', \quad |\nabla\beta'| \neq 0 \text{ in } \overline{\Omega'} \setminus \omega \text{ and } \beta' = g \text{ on } \partial\Omega'.$$

To conclude, we take

$$\beta = \begin{cases} \beta_s & \text{in } \overline{\Omega} \setminus \Omega', \\ \beta' & \text{in } \overline{\Omega'}. \end{cases} \quad \square$$

Proof of Lemma 4. Recall that $\Gamma = \sigma \cup \Gamma_1$.

Set $\sigma = [S; S']$, $S' \in \Gamma_1$ and consider two points M_1, M_2 of Γ_1 close enough to S' such that $S' \in \widehat{M_1M_2}$. We denote this arc by Γ'' and set $\Gamma_1 = \Gamma' \cup \Gamma''$.

We construct a function β_s satisfying

$$\beta_s \in C^2(\overline{\Omega}), \quad \beta_s > 0 \text{ in } \overline{\Omega}, \quad \frac{\partial\beta_s}{\partial\nu} < 0 \text{ on } \Gamma'', \quad \frac{\partial\beta_s}{\partial\nu} = 0 \text{ on } \sigma \text{ and } |\nabla\beta_s| > 0 \text{ in } \Omega.$$

We choose a C^2 open subset $\Omega' \subset \Omega$ such that

$$\partial\Omega' = \Gamma_0 \cup \Gamma' \text{ and } \frac{\partial\beta_s}{\partial\nu} < 0 \text{ on } \Gamma_0$$

and we follow the proof as in Case 1. \square

Remark. We generalize the results established in Case 1 to any polygon.

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