



Partial differential equations

# Applications of Bourgain–Brézis inequalities to fluid mechanics and magnetism <sup>☆</sup>



*Applications des inégalités de Bourgain–Brézis à la mécanique des fluides et au magnétisme*

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## ABSTRACT

As a consequence of inequalities due to Bourgain–Brézis, we obtain local-in-time well-posedness for the two-dimensional Navier–Stokes equation with velocity bounded in spacetime and initial vorticity in bounded variation. We also obtain spacetime estimates for the magnetic field vector through improved Strichartz inequalities.

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## RÉSUMÉ

À partir d'inégalités de Bourgain–Brézis, nous démontrons le caractère bien posé localement dans le temps des équations de Navier–Stokes avec vitesse bornée en espace-temps et un tourbillon initial à variation bornée. Nous obtenons également des estimations en espace-temps pour le champ magnétique grâce à des inégalités de Strichartz améliorées.

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## 1. Incompressible Navier–Stokes flow

Let  $\mathbf{v}(x, t) \in \mathbb{R}^2$  be the velocity and  $p(x, t)$  be the pressure of a fluid of viscosity  $\nu > 0$  at position  $x \in \mathbb{R}^2$  and time  $t \in \mathbb{R}$ , governed by the incompressible two-dimensional Navier–Stokes equation:

$$\begin{cases} \mathbf{v}_t + (\mathbf{v} \cdot \nabla) \mathbf{v} = \nu \Delta \mathbf{v} - \nabla p, \\ \nabla \cdot \mathbf{v} = 0, \end{cases} \quad (1)$$

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When the viscosity coefficient  $\nu$  degenerates to zero, (1) becomes the Euler equation. In two spatial dimensions, the vorticity of the flow is a scalar, defined by

$$\omega = \partial_{x_1} v_2 - \partial_{x_2} v_1$$

where we wrote  $\mathbf{v} = (v_1, v_2)$ . In the sequel, when we consider the Navier–Stokes equation, without loss of generality we set the viscosity coefficient  $\nu = 1$ .

The vorticity associated with the incompressible Navier–Stokes flow in two dimensions propagates according to the equation

$$\omega_t - \Delta \omega = -\nabla \cdot (\mathbf{v}\omega). \quad (2)$$

This follows from (1) by taking the curl of both sides. We express the velocity  $\mathbf{v}$  in the Navier–Stokes equation in terms of the vorticity through the Biot–Savart relation:

$$\mathbf{v} = (-\Delta)^{-1}(\partial_{x_2}\omega, -\partial_{x_1}\omega). \quad (3)$$

This follows formally by differentiating  $\omega = \partial_{x_1} v_2 - \partial_{x_2} v_1$ , and using that  $\nabla \cdot \mathbf{v} = 0$ .

Our theorem states:

**Theorem 1.** Consider the two-dimensional vorticity equation (2) and an initial vorticity  $\omega_0 \in W^{1,1}(\mathbb{R}^2)$  at time  $t = 0$ . If

$$\|\omega_0\|_{W^{1,1}(\mathbb{R}^2)} \leq A_0,$$

then there exists a unique solution to the vorticity equation (2) for all time  $t \leq t_0 = C/A_0^2$ , such that

$$\sup_{t \leq t_0} \|\omega(\cdot, t)\|_{W^{1,1}(\mathbb{R}^2)} \leq cA_0.$$

Moreover, the solution  $\omega$  depends continuously on the initial data  $\omega_0$ , in the sense that if  $\omega_0^{(i)}$  is a sequence of initial data converging in  $W^{1,1}(\mathbb{R}^2)$  to  $\omega_0$ , then the corresponding solutions  $\omega^{(i)}$  to the vorticity equation (2) satisfy

$$\sup_{t \leq t_0} \|\omega^{(i)}(\cdot, t) - \omega(\cdot, t)\|_{W^{1,1}(\mathbb{R}^2)} \rightarrow 0$$

as  $i \rightarrow \infty$ .

Finally, the velocity vector  $\mathbf{v}$  defined by the Biot–Savart relation (3) solves the 2-dimensional incompressible Navier–Stokes equation (1), and satisfies

$$\sup_{t \leq t_0} \|\mathbf{v}(\cdot, t)\|_{L^\infty(\mathbb{R}^2)} + \sup_{t \leq t_0} \|\nabla \mathbf{v}(\cdot, t)\|_{L^2(\mathbb{R}^2)} \leq cA_0.$$

Via the Gagliardo–Nirenberg inequality, we can conclude from our theorem that

$$\sup_{0 \leq t \leq t_0} \|\omega(\cdot, t)\|_{L^p(\mathbb{R}^2)} \leq C, \quad 1 \leq p \leq 2.$$

In particular, this is enough to apply Theorem II of Kato [8] to express the velocity vector in the Navier–Stokes equation (1) in terms of the vorticity via the Biot–Savart relation displayed above.

In [7,8], it was proved that under the hypothesis that the initial vorticity is a measure, there is a global solution that is well-posed to the vorticity and Navier–Stokes equation; see also an alternative approach in Ben-Artzi [1], and a stronger uniqueness result in Brézis [4]. The velocity constructed then satisfies the estimate [8, (0.5)]:

$$\|\mathbf{v}(\cdot, t)\|_{L^\infty(\mathbb{R}^2)} \leq Ct^{-\frac{1}{2}}, \quad t \rightarrow 0. \quad (4)$$

In contrast, in Theorem 1 we have  $\mathbf{v} \in L_t^\infty L_x^\infty$ ,  $x \in \mathbb{R}^2$ , though we are assuming that the initial vorticity has bounded variation, that is, its gradient is a measure.

The estimate (4) is indeed sharp as can be seen by the famous example of the *Lamb–Oseen vortex* [9], which consists of an initial vorticity  $\omega_0 = \alpha_0 \delta_0$ , a Dirac mass at the origin of  $\mathbb{R}^2$  with strength  $\alpha_0$ . The constant  $\alpha_0$  is called the total circulation of the vortex. A unique solution to the vorticity equation (2) can be obtained by setting

$$\omega(x, t) = \frac{\alpha_0}{4\pi t} e^{-\frac{|x|^2}{4t}}, \quad \mathbf{v}(x, t) = \frac{\alpha_0}{2\pi} \frac{(-x_2, x_1)}{|x|^2} \left(1 - e^{-\frac{|x|^2}{4t}}\right).$$

It can be seen from the identities above that

$$\|\omega(\cdot, t)\|_{W^{1,1}(\mathbb{R}^2)} \sim \|\mathbf{v}(\cdot, t)\|_{L^\infty(\mathbb{R}^2)} \sim ct^{-\frac{1}{2}}, \quad t \rightarrow 0.$$

Hence the assumption that the initial vorticity is a measure cannot yield an estimate like in [Theorem 1](#). Thus to get uniform-in-time,  $L^\infty$  space bounds all the way to  $t = 0$ , we need a stronger hypothesis and one such is vorticity in BV (bounded variation).

It is also helpful to further compare our result with that of Kato [\[8\]](#), who establishes in (0.4) of his paper that given that the initial vorticity is a measure, one has for the vorticity at further time

$$\|\nabla\omega(\cdot, t)\|_{L^q(\mathbb{R}^2)} \leq ct^{\frac{1}{q}-\frac{3}{2}}, \quad 1 < q \leq \infty.$$

In contrast, we obtain uniform-in-time bounds for  $q = 1$ , as opposed to singular bounds for  $q > 1$  when  $t \rightarrow 0$ .

It is an open question whether there is a global version of [Theorem 1](#) of our paper.

In order to prove [Theorem 1](#), we rely on a basic proposition that follows from the work of Bourgain and Brézis [\[2,3\]](#). A part of this proposition also holds in three dimensions. Recall that if  $\mathbf{v}(x, t) \in \mathbb{R}^3$  is the velocity of a fluid at a point  $x \in \mathbb{R}^3$  at time  $t$ , then the vorticity of  $\mathbf{v}$  is defined by

$$\boldsymbol{\omega} = \nabla \times \mathbf{v}.$$

Under the assumption that the flow is incompressible, the Biot–Savart relation reads

$$\mathbf{v} = (-\Delta)^{-1}(\nabla \times \boldsymbol{\omega}). \tag{5}$$

**Proposition 2.**

(a) Consider the velocity  $\mathbf{v}$  in three spatial dimensions. Assume that  $\mathbf{v}$  satisfies the Biot–Savart relation (5). Then at any fixed time  $t$ ,

$$\|\mathbf{v}(\cdot, t)\|_{L^3(\mathbb{R}^3)} + \|\nabla\mathbf{v}(\cdot, t)\|_{L^{3/2}(\mathbb{R}^3)} \leq C\|\nabla \times \boldsymbol{\omega}(\cdot, t)\|_{L^1(\mathbb{R}^3)}$$

where  $C$  is a constant independent of  $t$ ,  $\mathbf{v}$ , and  $\boldsymbol{\omega}$ .

(b) Consider the velocity  $\mathbf{v}$  in two spatial dimensions. Assume that  $\mathbf{v}$  satisfies the Biot–Savart relation (3). Then at any fixed time  $t$ ,

$$\|\mathbf{v}(\cdot, t)\|_{L^\infty(\mathbb{R}^2)} + \|\nabla\mathbf{v}(\cdot, t)\|_{L^2(\mathbb{R}^2)} \leq C\|\nabla\omega(\cdot, t)\|_{L^1(\mathbb{R}^2)}.$$

where  $C$  is a constant independent of  $t$ ,  $\mathbf{v}$  and  $\omega$ .

We remark that in two dimensions, by the Poincaré inequality, it follows from  $\|\nabla\mathbf{v}\|_{L^2(\mathbb{R}^2)} < \infty$ , that  $\mathbf{v}$  lies in  $VMO(\mathbb{R}^2)$ , i.e. has vanishing mean oscillation.

**Proof of Proposition 2.** Note that

$$\nabla \cdot (\nabla \times \boldsymbol{\omega}) = 0.$$

Thus we can immediately apply the result of Bourgain–Brézis [\[3\]](#) (see also [\[2,5,10\]](#)) to the Biot–Savart formula (5) and get the desired conclusions in part (a).

To consider the 2-dimensional flow, note that  $(-\partial_{x_2}\omega, \partial_{x_1}\omega)$  is a vector field in  $\mathbb{R}^2$  with vanishing divergence. In view of the two-dimensional Biot–Savart relation (3), we can then use the two-dimensional Bourgain–Brézis result [\[3\]](#), and we obtain (b).  $\square$

We note further that the proposition applies to both the Euler (inviscid) or the Navier–Stokes (viscous) flow.

**Proof of Theorem 1.** Now set  $K_t$  for the heat kernel in two dimensions, i.e.

$$K_t(x) = \frac{1}{4\pi t} e^{-\frac{|x|^2}{4t}}.$$

Rewriting (2) as an integral equation for  $\omega$  using Duhamel’s theorem, where  $\omega_0$  is the initial vorticity, we have

$$\omega(x, t) = K_t \star \omega_0(x) + \int_0^t \partial_x K_{t-s} \star [\mathbf{v}\omega(x, s)] ds \tag{6}$$

where  $\mathbf{v}$  is given by (3).

We apply a Banach fixed point argument to the operator  $T$  given by

$$T\omega(x, t) = K_t \star \omega_0(x) + \int_0^t \partial_x K_{t-s} \star [\mathbf{v}\omega(x, s)] ds, \tag{7}$$

where again  $\mathbf{v}$  is given by (3). Let us set

$$E = \left\{ g \mid \sup_{0 < t < t_0} \|g(\cdot, t)\|_{W^{1,1}(\mathbb{R}^2)} \leq A \right\}.$$

We will first show that  $T$  maps  $E$  into itself, for  $t_0$  chosen as in the theorem.

Differentiating (7) in the space variable once, we get

$$(T\omega(x, t))_x = K_t \star f_0(x) + \int_0^t \partial_x K_{t-s} \star (\mathbf{v}_x \omega) ds + \int_0^t \partial_x K_{t-s} \star (\mathbf{v} \omega_x) ds.$$

Here we denote by  $f_0$  the spatial derivative of the initial vorticity  $\omega_0$ . Using Young's convolution inequality, we have

$$\|(T\omega(\cdot, t))_x\|_{L^1(\mathbb{R}^2)} \leq \|f_0\|_{L^1(\mathbb{R}^2)} + C \int_0^t (t-s)^{-1/2} (\|\mathbf{v}_x \omega\|_{L^1(\mathbb{R}^2)} + \|\mathbf{v} \omega_x\|_{L^1(\mathbb{R}^2)}) ds.$$

Now we apply Proposition 2(b) to each of the terms on the right. For the first term, we have, by Cauchy–Schwartz,

$$\|\mathbf{v}_x \omega\|_{L^1(\mathbb{R}^2)} \leq C \|\nabla \mathbf{v}\|_{L^2(\mathbb{R}^2)} \|\omega\|_{L^2(\mathbb{R}^2)}.$$

The Gagliardo–Nirenberg inequality applies as  $\omega \in E$  and so  $\omega(\cdot, t) \in L^1(\mathbb{R}^2)$  and so,

$$\|\omega\|_{L^2(\mathbb{R}^2)} \leq C \|\nabla \omega\|_{L^1(\mathbb{R}^2)},$$

and to  $\|\nabla \mathbf{v}\|_{L^2(\mathbb{R}^2)}$  we apply Proposition 2(b). Similarly, for the second term,

$$\|\mathbf{v} \omega_x\|_{L^1(\mathbb{R}^2)} \leq \|\mathbf{v}\|_{L^\infty(\mathbb{R}^2)} \|\omega_x\|_{L^1(\mathbb{R}^2)}.$$

Again we apply Proposition 2(b) to  $\|\mathbf{v}\|_{L^\infty(\mathbb{R}^2)}$ . Hence in all we have,

$$\|(T\omega)_x\|_{L^1(\mathbb{R}^2)} \leq \|f_0\|_{L^1(\mathbb{R}^2)} + C \int_0^t (t-s)^{-1/2} \|\nabla \omega\|_{L^1(\mathbb{R}^2)}^2 ds.$$

Thus setting  $\|f_0\|_{L^1(\mathbb{R}^2)} = \|\omega_0\|_{W^{1,1}(\mathbb{R}^2)} \leq A_0$ , we get for  $t \leq t_0$  and since  $\omega \in E$ ,

$$\|\nabla(T\omega)(\cdot, t)\|_{L^1(\mathbb{R}^2)} \leq A_0 + Ct_0^{1/2} A^2.$$

Next from Young's convolution inequality it follows from (7) that

$$\|T\omega(\cdot, t)\|_{L^1(\mathbb{R}^2)} \leq A_0 + \int_0^t (t-s)^{-1/2} \|\mathbf{v} \omega(\cdot, s)\|_1 ds.$$

But by Proposition 2(b) again,

$$\|\mathbf{v} \omega\|_1 \leq \|\mathbf{v}\|_\infty \|\omega\|_1 \leq cA^2.$$

Thus

$$\|T\omega(\cdot, t)\|_1 \leq A_0 + ct^{1/2} A^2.$$

So, adding the estimates for  $T\omega$  and  $\nabla(T\omega)$ , we have:

$$\sup_{t \leq t_0} \|T\omega(\cdot, t)\|_{W^{1,1}(\mathbb{R}^2)} \leq 2A_0 + ct_0^{1/2} A^2.$$

By choosing  $A$  so that  $A_0 = A/8$  and  $t < t_0 = C/A_0^2$ , we can assure that if  $\omega \in E$ , then

$$\sup_{t \leq t_0} \|(T\omega)(\cdot, t)\|_{W^{1,1}(\mathbb{R}^2)} \leq \frac{A}{2}.$$

Thus  $T\omega \in E$ , if  $\omega \in E$ . If we establish that  $T$  is a contraction, then we are done.

Next we observe that the estimates in Proposition 2(b) are linear estimates. That is

$$\|\mathbf{v}_1 - \mathbf{v}_2\|_\infty + \|\nabla \mathbf{v}_1 - \nabla \mathbf{v}_2\|_2 \leq C \|\omega_1 - \omega_2\|_{W^{1,1}(\mathbb{R}^2)}.$$

We easily can see from the computations above, that we have

$$\sup_{t \leq t_0} \|T\omega_1 - T\omega_2\|_{W^{1,1}(\mathbb{R}^2)} \leq CA t_0^{1/2} \sup_{t \leq t_0} \|\omega_1 - \omega_2\|_{W^{1,1}(\mathbb{R}^2)}.$$

By the choice of  $t_0$ , it is seen that  $T$  is a contraction. Thus using the Banach fixed-point theorem on  $E$ , we obtain our operator  $T$  has a fixed point and so the integral equation (6) has a solution in  $E$ . The remaining part of our theorem follows easily from Proposition 2(b).  $\square$

We note in passing an estimate in  $\mathbb{R}^3$  from Proposition 2(a) above for the Navier–Stokes or the Euler flow:

$$\sup_{t > 0} \|\mathbf{v}\|_{L^3(\mathbb{R}^3)} + \sup_{t > 0} \|\nabla \mathbf{v}\|_{L^{3/2}(\mathbb{R}^3)} \leq C \sup_{t > 0} \|\nabla \times \boldsymbol{\omega}\|_{L^1(\mathbb{R}^3)}. \tag{8}$$

## 2. Magnetism

We next turn to our results on magnetism. We denote by  $\mathbf{B}(x, t)$  and  $\mathbf{E}(x, t)$  the magnetic and electric field vectors at  $(x, t) \in \mathbb{R}^3 \times \mathbb{R}$ . Let  $\mathbf{j}(x, t)$  denote the current density vector. The Maxwell equations imply

$$\nabla \cdot \mathbf{B} = 0, \tag{9}$$

$$\partial_t \mathbf{B} + \nabla \times \mathbf{E} = 0, \tag{10}$$

$$\partial_t \mathbf{E} - \nabla \times \mathbf{B} = -\mathbf{j}. \tag{11}$$

Differentiating (10) in  $t$  and using (11), together with the vector identity  $\nabla \times (\nabla \times \mathbf{B}) = \nabla(\nabla \cdot \mathbf{B}) - \Delta \mathbf{B}$  and (9), one obtains an inhomogeneous wave equation for  $\mathbf{B}$ :

$$\mathbf{B}_{tt} - \Delta \mathbf{B} = \nabla \times \mathbf{j}. \tag{12}$$

The right side of (12) satisfies the vanishing divergence condition

$$\nabla \cdot (\nabla \times \mathbf{j}) = 0$$

for any fixed time  $t$ . Thus an improved Strichartz estimate, namely Theorem 1 in [6], applies. We point out that the Bourgain–Brézis inequalities play a key role in the proof of Theorem 1 in [6]. We conclude easily:

**Theorem 3.** *Let  $\mathbf{B}$  satisfy (12) and let  $\mathbf{B}(x, 0) = \mathbf{B}_0, \partial_t \mathbf{B}(x, 0) = \mathbf{B}_1$  denote the initial data at time  $t = 0$ . Let  $s, k \in \mathbb{R}$ . Assume  $2 \leq q \leq \infty, 2 < \tilde{q} \leq \infty$  and  $2 \leq r < \infty$ . Let  $(q, r)$  satisfy the wave compatibility condition*

$$\frac{1}{q} + \frac{1}{r} \leq \frac{1}{2},$$

and assume the following scale invariance condition is verified:

$$\frac{1}{q} + \frac{3}{r} = \frac{3}{2} - s = \frac{1}{\tilde{q}} + 1 - k.$$

Then, for  $\frac{1}{\tilde{q}} + \frac{1}{\tilde{q}'} = 1$ , we have

$$\|\mathbf{B}\|_{L_t^q L_x^r} + \|\mathbf{B}\|_{C_t^0 \dot{H}_x^s} + \|\partial_t \mathbf{B}\|_{C_t^0 \dot{H}_x^{s-1}} \leq C(\|\mathbf{B}_0\|_{\dot{H}^s} + \|\mathbf{B}_1\|_{\dot{H}^{s-1}} + \|(-\Delta)^{k/2}(\nabla_x \mathbf{j})\|_{L_t^{\tilde{q}'} L_x^1}).$$

The main point in the theorem above is that we have  $L^1$  norm in space on the right side.

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