DIMENSION REDUCTION FOR FUNCTIONALS ON SOLENOIDAL VECTOR FIELDS

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Abstract. We study integral functionals constrained to divergence-free vector fields in L^p on a thin domain, under standard *p*-growth and coercivity assumptions, $1 . We prove that as the thickness of the domain goes to zero, the Gamma-limit with respect to weak convergence in <math>L^p$ is always given by the associated functional with convexified energy density wherever it is finite. Remarkably, this happens despite the fact that relaxation of nonconvex functionals subject to the limiting constraint can give rise to a nonlocal functional as illustrated in an example.

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1. INTRODUCTION

This article is devoted to the study of the "effective" value per unit volume of functionals constrained to solenoidal (*i.e.*, divergence-free) vector fields defined on a thin domain $\omega \times (0, \varepsilon)$, in the limit as the thickness ε goes to zero. We assume that on a domain with finite thickness, our functional (which we call the "energy", although its meaning might be different from a physical point of view) is given by a integral of the form

$$G_{\varepsilon}(v) := \begin{cases} \frac{1}{\varepsilon} \int_{\omega \times (0,\varepsilon)} g(y', v(y)) \, \mathrm{d}y & \text{if } v \in \mathcal{V}_{\varepsilon}, \\ +\infty & \text{if } v \in L^p(\omega \times (0,\varepsilon); \mathbb{R}^N) \setminus \mathcal{V}_{\varepsilon} \end{cases}$$

where $N \geq 2$, ω is a bounded domain in \mathbb{R}^{N-1} , $y = (y', y_N) \in \omega \times (0, \varepsilon)$, $g : \omega \times \mathbb{R}^N \to \mathbb{R}$ is a given energy density, and G_{ε} is finite only in the class of solenoidal vector fields on $\omega \times (0, \varepsilon)$ in L^p for some 1 ,*i.e.*,

$$\mathcal{V}_{\varepsilon} := \left\{ v \in L^{p}(\omega \times (0, \varepsilon); \mathbb{R}^{N}) \mid \operatorname{div} v = 0 \right\}.$$

Here and throughout the rest of this article, differential constraints as for v above are understood in the sense of distributions, in particular, div v = 0 for a $v \in L^p(\omega \times (0, \varepsilon); \mathbb{R}^N)$ means that $\int_{\omega \times (0, \varepsilon)} v \cdot \nabla \varphi \, dy = 0$ for all test functions $\varphi \in C_c^{\infty}(\omega \times (0, \varepsilon))$ (smooth functions with compact support, scalar-valued). Using rescaled variables

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given by $x = (x', x_N) = (y', \varepsilon^{-1}y_N)$ and $u(x) = v(x', \varepsilon x_N)$, G_{ε} is transformed into a functional defined on a fixed domain:

$$F_{\varepsilon}(u) := \begin{cases} \int_{\Omega} f(x, u(x)) \, \mathrm{d}x, & \text{if } u \in \mathcal{U}_{\varepsilon}, \text{ with } \Omega := \omega \times (0, 1), \\ +\infty & \text{if } u \in L^{p}(\Omega; \mathbb{R}^{N}) \setminus \mathcal{U}_{\varepsilon}, \end{cases}$$

where $f(x, \cdot) = g(x', \cdot)$ for $x = (x', x_N) \in \mathbb{R}^{N-1} \times \mathbb{R}$,

$$\mathcal{U}_{\varepsilon} := \left\{ u \in L^{p}(\Omega; \mathbb{R}^{N}) \mid \operatorname{div}_{\varepsilon} u = 0 \right\}$$

and

$$\operatorname{div}_{\varepsilon} u := \operatorname{div}' u' + \frac{1}{\varepsilon} \partial_N u^N := \left(\sum_{\alpha=1}^{N-1} \partial_\alpha u^\alpha\right) + \frac{1}{\varepsilon} \partial_N u^N$$

for $u = (u', u^N) = (u^1, \ldots, u^N)$. As this does not further complicate our approach, we allow f to explicitly depend on x_N as well below. We assume that

$$f: \Omega \times \mathbb{R}^N \to \mathbb{R}$$
 is a Carathéodory function² (f:0)

satisfying the following structural conditions:

(growth)
$$|f(x,\mu)| \le C |\mu|^p + C,$$
 (f:1)

(coercivity)
$$f(x,\mu) \ge \frac{1}{C} |\mu|^p - C,$$
 (f:2)

with constants C > 0 and $1 , for every <math>\mu \in \mathbb{R}^N$ and a.e. $x \in \Omega$.

Using the notion of Γ -convergence introduced by De Giorgi [9,10], the effective energy in the limit $\varepsilon \to 0^+$ is expressed by the Γ -limit of F_{ε} with respect to weak convergence in L^p . For an introduction to the theory of Γ -convergence, the reader is referred to [4,7]. We use the notation

$$\begin{split} &\Gamma(L^p_{\text{weak}}) - \liminf F_{\varepsilon}(u) := \inf \big\{ \liminf_{\varepsilon \to 0^+} F_{\varepsilon}(u_{\varepsilon}) \, \big| \, u_{\varepsilon} \rightharpoonup u \text{ weakly in } L^p \big\}, \\ &\Gamma(L^p_{\text{weak}}) - \limsup F_{\varepsilon}(u) := \inf \big\{ \limsup_{\varepsilon \to 0^+} F_{\varepsilon}(u_{\varepsilon}) \, \big| \, u_{\varepsilon} \rightharpoonup u \text{ weakly in } L^p \big\}. \end{split}$$

Below, we omit the topology indicated in brackets as throughout this paper, this is always the weak topology in L^p . We say that $\Gamma - \lim F_{\varepsilon}$ exists if $\Gamma - \liminf F_{\varepsilon}$ and $\Gamma - \limsup F_{\varepsilon}$ coincide, in which case this quantity is denoted by $\Gamma - \lim F_{\varepsilon}$. In particular, the use of the weak topology in L^p causes a process of relaxation in the limit, roughly speaking because energetically favorable microstructures of a characteristic size converging to zero as $\varepsilon \to 0$ are allowed along the sequences generating the effective (macroscopic) limiting energy.

The corresponding problem of dimension reduction for functionals depending on gradients instead of divergence-free fields was investigated by Le Dret and Raoult [18–20] and stimulated a great deal of further research, including the study of different scalings, partially with energy densities that are realistic from the point of view of hyperelasticity (see [15] and the references therein), as well as extensions to non-flat limiting surfaces [22,23].

Recently, dimension reduction problems for Ginzburg-Landau-type functionals, involving a magnetic potential which is divergence-free as a choice of gauge, were studied in [1,6]. In both cases, the relevant parts of the energy density (apart from compact perturbations) are convex and thus no relaxation occurs during the limit process, avoiding the main difficulty of our problem. Relaxation and homogenization of functionals constrained to solenoidal matrix fields were treated in [2,29] (for related results and some physical background also see [16,28]), as well as in [5,12,14] for a more general constraint of the form Au = 0. In this context, A is a linear differential operator assumed to satisfy Murat's condition of constant rank [26], and apart from the examples in [21,24,31],

 $^{^{2}}I.e.$ measurable in its first and continuous in its second variable.

very little is known if this condition is violated. In our framework, $\operatorname{div}_{\varepsilon}$ satisfies the condition of constant rank for each ε , but the associated limiting operator $\operatorname{div}_0(\operatorname{div}_0 u := \partial_N u^N$ for $u : \Omega \to \mathbb{R}^N)$ does not. From the point of view of the theory for \mathcal{A} -free fields developed in [5,14], this means that important bounds for the projection operator onto $\operatorname{div}_{\varepsilon}$ -free fields and its complementary projection are not uniform in ε and projecting tends to create large errors as $\varepsilon \to 0^+$ (cf. Rem. 2.8). Hence, we can (and do) use the projection only along sequences that are asymptotically $\operatorname{div}_{\varepsilon}$ -free in a very strong sense (cf. Lem. 2.9).

As we shall see, the divergence-free dimension reduction problem with nonconvex energy density exhibits some intriguing features that do not occur in the gradient case. In particular, it turns out that dimension reduction and direct relaxation in the limit setting do not yield the same result in general. While the former simply leads to convexification by our main theorem stated below, the latter may give rise to a nonlocal functional as illustrated by the example discussed in Proposition 3.3.

Unless indicated otherwise, we assume throughout that

$$N \ge 2$$
, $\omega \subset \mathbb{R}^{N-1}$ is open and bounded, $\Omega := \omega \times (0,1)$ and $1 .$

Theorem 1.1. Suppose that (f:0)–(f:2) are satisfied. Then $\Gamma - \lim_{\varepsilon \to 0^+} F_{\varepsilon}$ (with respect to weak convergence in L^p) exists, and it has the representation

$$\Gamma - \lim F_{\varepsilon}(u) = \begin{cases} F^{**}(u) := \int_{\Omega} f^{**}(x, u) \, \mathrm{d}x & \text{if } u \in \mathcal{U}_0, \\ +\infty & \text{if } u \in L^p(\Omega; \mathbb{R}^N) \setminus \mathcal{U}_0, \end{cases}$$

where for each x, $f^{**}(x, \cdot)$ denotes the convex envelope of $f(x, \cdot)$ and

$$\mathcal{U}_0 := \left\{ u \in L^p(\Omega; \mathbb{R}^N) \mid \partial_N u^N = 0 \text{ in } \Omega \right\}.$$

It is fairly easy to see that both $\Gamma - \limsup F_{\varepsilon}(u)$ and $\Gamma - \liminf F_{\varepsilon}(u)$ are finite if and only if $u \in \mathcal{U}_0$ (Lems. 2.2 and 2.3), and the lower bound for $\Gamma - \liminf F_{\varepsilon}(u)$ is of course a simple consequence of the weak lower semicontinuity of convex functionals (Prop. 2.6). However, the upper bound, $\Gamma - \limsup F_{\varepsilon}(u) \leq F^{**}(u)$ for $u \in \mathcal{U}_0$, is far more difficult than in the gradient case. The main issue here is that a priori, we do not know whether or not $\Gamma - \limsup F_{\varepsilon}$ is a local integral functional. The usual trick for a proof of this property, based on "localizing" a sequence u_{ε} that weakly converges to zero by multiplying it with suitable smooth cutoff functions with the desired support. In the gradient case, the fields u with finite Γ -limit are independent of x^N , whence it suffices to localize in the first N - 1 variables. By contrast, in our setting, only the last component u^N is independent of x_N , and we have to somehow localize in x_N as well. But using a cut-off in X_N as described above does not work, because the distance of the modified sequence to the set of div_{\varepsilon}-free fields in L^p may be of an order approaching $1/\varepsilon$ which is an error too large to handle. Indeed, our proof of the upper bound in Section 4 (culminating in Prop. 4.9) does not use this kind of truncation in direction x_N , instead relying on a rather explicit construction of suitable sequences with small support in direction of x_N which are asymptotically div_{\varepsilon}-free in the sense that their distance to $\mathcal{U}_{\varepsilon}$ with respect to the norm of L^p goes to zero as $\varepsilon \to 0^+$ (by Lem. 2.9). A prototype of this construction for a simple example is presented in Proposition 3.5.

2. Preliminary observations

We first observe that both $\Gamma - \limsup F_{\varepsilon}(u)$ and $\Gamma - \liminf F_{\varepsilon}(u)$ are finite if and only if $u \in \mathcal{U}_0$. The following simple density result turns out to be useful.

Lemma 2.1. With respect to the strong topology in $L^p(\Omega; \mathbb{R}^N)$, $\mathcal{U}_0 \cap C^{\infty}(\overline{\Omega}; \mathbb{R}^N)$ is dense in \mathcal{U}_0 .

Proof. Let $u \in \mathcal{U}_0$, and extend $u = (u^1, \ldots, u^N)$ to a function in $L^p_{\text{loc}}(\mathbb{R}^N; \mathbb{R}^N)$ such that $u^j = 0$ on $\mathbb{R}^N \setminus \Omega$ for $j = 1, \ldots, N-1$, $u^N = 0$ on $\mathbb{R}^N \setminus (\omega \times \mathbb{R})$ and $u^N(x', x_N)$ is still constant in x_N for a.e. $x' \in \omega$. Mollifying in the usual way yields a sequence $(u_k)_{k \in \mathbb{N}}$ in $C^{\infty}(\mathbb{R}^N; \mathbb{R}^N) \cap \mathcal{U}_0$ with $u_k \to u$ strongly in $L^p(\Omega; \mathbb{R}^N)$. \Box

Lemma 2.2. Let v_n be a bounded sequence in $L^p(\Omega)$ with $v_n \rightharpoonup v_\infty$ weakly in $L^p(\Omega)$, and suppose that $\partial_N v_n \rightarrow 0$ in the sense of distributions. Then v_∞ is constant in x_N . In particular, if $(u_\varepsilon) \subset \mathcal{U}_\varepsilon$ and $u_\varepsilon \rightharpoonup u$ weakly in L^p , then $u \in \mathcal{U}_0$.

Proof. For every $\varphi \in C_0^{\infty}(\omega)$ and every $\eta \in C_0^{\infty}((0,1))$, we have

$$0 = \lim_{n \to \infty} \int_{\omega} \int_{(0,1)} v_n(x', x_N) \varphi(x') \dot{\eta}(x_N) \, \mathrm{d}x_N \, \mathrm{d}x' = \int_{\omega} \int_{(0,1)} v_\infty(x', x_N) \varphi(x') \dot{\eta}(x_N) \, \mathrm{d}x_N \, \mathrm{d}x'$$

In particular, since φ was arbitrary, we get

$$\int_{(0,1)} v_{\infty}(x', x_N) \dot{\eta}(x_N) \, \mathrm{d}x_N = 0 \quad \text{for a.e. } x' \in \omega \text{ and every } \eta \in C_0^{\infty}((0,1)),$$

which in turn implies that $v_{\infty}(x', x_N)$ is constant in x_N .

Lemma 2.3. For every $u \in \mathcal{U}_0$, there exists a sequence $(u_{\varepsilon}) \subset \mathcal{U}_{\varepsilon}$ such that $u_{\varepsilon} - u \to 0$ in $L^p(\Omega; \mathbb{R}^N)$.

Remark 2.4. Using Lebesgue's theorem, (f:0) and (f:1), we get that $\lim F_{\varepsilon}(u_{\varepsilon}) = \int_{\Omega} f(x, u) dx < \infty$, and thus $\Gamma - \limsup F_{\varepsilon}(u) < \infty$ for every $u \in \mathcal{U}_0$.

Proof of Lemma 2.3.

Step 1: Assume in addition that $u \in C^1(\overline{\Omega}; \mathbb{R}^N)$.

For $j = 1, \ldots, N - 1$ define $u_{\varepsilon}^j := u^j$, and let

$$u_{\varepsilon}^{N}(x', x_{N}) := u^{N}(x', x_{N}) - \varepsilon \int_{0}^{x_{N}} \operatorname{div}' u(x', t) \, \mathrm{d}t,$$

where $\operatorname{div}' u = \partial_1 u^1 + \ldots + \partial_{N-1} u^{N-1}$. We thus have that $\operatorname{div}_{\varepsilon} u_{\varepsilon} = 0$ and $u_{\varepsilon} \to u$ strongly in L^p , whence $v_{\varepsilon} := u_{\varepsilon}$ has the asserted properties.

Step 2: The general case.

By Lemma 2.1, there exists a sequence $(u_k) \subset C^1(\overline{\Omega}; \mathbb{R}^N) \cap \mathcal{U}_0$ with $u_k \to u$ strongly in $L^p(\Omega; \mathbb{R}^N)$ as $k \to \infty$. For each k and each ε , we define $u_{k,\varepsilon} \in \mathcal{U}_{\varepsilon}$ as in the first step, using u_k instead of u. Now choose $(k(\varepsilon))_{\varepsilon>0}$ with $k(\varepsilon) \to \infty$ slow enough such that $\varepsilon ||u_{k(\varepsilon)}||_{C^1(\overline{\Omega}; \mathbb{R}^N)} \to 0$ as $\varepsilon \to 0$. As a consequence, $u_{\varepsilon} := u_{k(\varepsilon),\varepsilon}$ converges to u strongly in L^p , and it satisfies $\operatorname{div}_{\varepsilon} u_{\varepsilon} = 0$ by construction.

To prove the lower bound $\Gamma - \liminf F_{\varepsilon}(u) \ge F^{**}(u)$ for $u \in \mathcal{U}_0$, we first recall the well known characterization of weak lower semicontinuity of convex functionals:

Theorem 2.5 (see [17] or [13], e.g.). Suppose that f satisfies (f:0). Then the functional $J : L^p(\Omega, \mathbb{R}^N) \to [0, \infty]$, $J(u) := \int_{\Omega} f(x, u) \, dx$, is lower semicontinuous with respect to weak convergence in L^p if and only if $f(x, \cdot)$ is convex for a.e. $x \in \Omega$.

As an immediate consequence, we have:

Proposition 2.6 (lower bound). Suppose that the assumptions of Theorem 1.1 hold. Then for every $u \in \mathcal{U}_0$,

$$\Gamma - \liminf F_{\varepsilon}(u) \ge F^{**}(u).$$

For the upper bound, we have to construct a suitable sequence $(u_{\varepsilon}) \subset \mathcal{U}_{\varepsilon}$ such that $u_{\varepsilon} \rightharpoonup u$ in L^p and $F_{\varepsilon}(u_{\varepsilon}) \rightarrow F^{**}(u)$, starting from a given $u \in \mathcal{U}_0$. The main problem here is the constraint $\operatorname{div}_{\varepsilon} u_{\varepsilon} = 0$. In particular, we rely on a projection onto $\operatorname{div}_{\varepsilon}$ -free fields, which is based on the following special case of the projection used in [14].

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Lemma 2.7. Let $1 and let <math>Q \subset \mathbb{R}^N$ be an open cube. For every $\varepsilon > 0$, there exists a linear operator $\mathcal{P}_{\varepsilon}: L^p(Q; \mathbb{R}^N) \to L^p(Q; \mathbb{R}^N)$ with the following properties:

- (i) div_{ε} $\mathcal{P}_{\varepsilon}u = 0$ on \mathbb{R}^N for every $u \in L^p(Q; \mathbb{R}^N)$, where $\mathcal{P}_{\varepsilon}u$ is extended Q-periodically.
- (ii) $\mathcal{P}_{\varepsilon}w = w$ for every $w \in L^p(Q; \mathbb{R}^N)$ such that $\operatorname{div}_{\varepsilon} w = 0$ on \mathbb{R}^N , where w is identified with its Q-periodic extension to \mathbb{R}^N .
- (iii) $\|\mathcal{P}_{\varepsilon}u\|_{L^{p}(Q;\mathbb{R}^{N})} \leq C_{\varepsilon} \|u\|_{L^{p}(Q;\mathbb{R}^{N})}$ for every $u \in L^{p}(Q;\mathbb{R}^{N})$, with a constant $C_{\varepsilon} > 0$ independent of u. (iv) $\|(I \mathcal{P}_{\varepsilon})u\|_{L^{p}(Q;\mathbb{R}^{N})} \leq C_{\varepsilon} \|\operatorname{div}_{\varepsilon} u\|_{W^{-1,p}(Q)}$ for every $u \in L^{p}(Q;\mathbb{R}^{N})$, with a constant $C_{\varepsilon} > 0$ independent. dent of u.

Here, on a given domain $W^{-1,p}$ denotes the dual space of $W_0^{1,p'}$ with p' = p/(p-1).

Proof. For $\xi = (\xi', \xi^N) \in \mathbb{R}^N \setminus \{0\}, (\xi', \frac{1}{\varepsilon}\xi) \in \mathbb{R}^{1 \times N}$ has full rank independent of $\xi \neq 0$, which means that for fixed ε , div $_{\varepsilon}$ satisfies Murat's condition of constant rank [26]. Hence, Lemma 2.14 in [14] applies with $\mathcal{A} := \operatorname{div}_{\varepsilon}$ and $\mathbb{T} = \mathcal{P}_{\varepsilon}$.

Remark 2.8. If p = 2 (avoiding the use of general Fourier multiplier theorems), it is easy to see from the proof of Lemma 2.14 in [14] that (iii) and (iv) actually hold with constants independent of ε . However, we do not exploit this fact, and in any case, the factor $\frac{1}{\varepsilon}$ hidden in the div_{ε} on the right hand side of (iv) is still a major obstacle even if the constant in (iv) does not blow up as $\varepsilon \to 0^+$.

For technical reasons, it is important for us to be able to work with sequences which are not div_{ε} -free but can be projected to div_e-free sequences with an error that is negligible in the limit $\varepsilon \to 0^+$. The following application of Lemma 2.7 gives a useful sufficient criterion for sequences with this property.

Lemma 2.9. Let $\Omega \subset \mathbb{R}^N$ be open and bounded, let $1 and let <math>\varepsilon_n \to 0^+$. Then there exists a sequence $\sigma_n \to 0^+$ such that the following holds: For every sequence $(u_n) \subset L^p(\Omega; \mathbb{R}^N)$ with $u_n \to 0$ in L^p and

$$\left\|\operatorname{div}_{\varepsilon_{n}} u_{n}\right\|_{W^{-1,p}(\Omega)} + \left\|\left(u_{n}^{\prime}, \frac{1}{\varepsilon_{n}} u_{n}^{N}\right)\right\|_{W^{-1,p}(\Omega;\mathbb{R}^{N})} \le \sigma_{n},\tag{2.1}$$

where $u'_n := (u_n^1, \ldots, u_n^{N-1})$, there exists a sequence $(v_n) \subset L^p(\Omega; \mathbb{R}^N)$ such that $\operatorname{div}_{\varepsilon_n} v_n = 0$ in Ω and $u_n - v_n \to 0$ 0 in $L^p(\Omega; \mathbb{R}^N)$.

Proof. For every $k \in \mathbb{N}$ choose a function $\varphi_k \in C_c^{\infty}(\Omega; [0, 1])$ such that $\varphi_k(x) = 1$ for every $x \in \Omega$ with dist $(x; \partial \Omega) \geq \frac{1}{k}$. Moreover, choose a cube Q containing Ω and a sequence $\tilde{\sigma}_n \to 0^+$ such that $C_{\varepsilon_n} \tilde{\sigma}_n \to 0$ with the constants of Lemma 2.7 (iv) (which also depend on Q). We define

$$\sigma_n := \left\| \varphi_{j(n)} \right\|_{W^{2,\infty}(\Omega)}^{-1} \tilde{\sigma}_n \text{ and } \tilde{u}_n := \varphi_{j(n)} u_n$$

with a sequence of integers $j(n) \to \infty$ (fast enough) such that $u_n - \tilde{u}_n \to 0$ in $L^p(\Omega; \mathbb{R}^N)$. Since

$$\operatorname{div}_{\varepsilon_n}(\varphi_k u_n) = \varphi_k \operatorname{div}_{\varepsilon_n} u_n + \nabla \varphi_k \cdot \left(u'_n, \frac{1}{\varepsilon_n} u_n^N \right),$$

we have that

$$\left\|\operatorname{div}_{\varepsilon_n}(\varphi_k u_n)\right\|_{W^{-1,p}} \le \left\|\varphi_k\right\|_{W^{2,\infty}(\Omega)} \left(\left\|\operatorname{div}_{\varepsilon_n} u_n\right\|_{W^{-1,p}} + \left\|\left(u'_n, \frac{1}{\varepsilon_n} u_n^N\right)\right\|_{W^{-1,p}}\right).$$

Hence, (2.1) implies that

$$C_{\varepsilon_n} \| \operatorname{div}_{\varepsilon_n} \tilde{u}_n \|_{W^{-1,p}(\Omega)} = C_{\varepsilon_n} \| \operatorname{div}_{\varepsilon_n} \tilde{u}_n \|_{W^{-1,p}(Q)} \le C_{\varepsilon_n} \tilde{\sigma}_n \to 0$$

as $n \to \infty$. The sequence $v_n := \mathcal{P}_n \tilde{u}_n \in L^p(Q; \mathbb{R}^N)$, restricted to Ω , now has the desired properties by Lemma 2.7.

Applying Lemma 2.9 is not easy because σ_n might converge to zero extremely fast. Nevertheless, it turns out to be possible for certain sequences constructed below, first in Proposition 3.5 for a simple example and then in Proposition 4.3 as the first step in proof of the upper bound.

3. An example and a related relaxation problem

When studying the dimension reduction problem for functionals depending on gradients (instead of divergencefree functions), one usually relies on a characterization of the associated relaxed functional in the limit setting, both as a lower semicontinuity result for the lower bound and as a first step in the construction of a sequence for the upper bound. In our framework, the associated relaxed functional in the limit setting corresponds to the functional \tilde{F}_0 introduced below. Although \tilde{F}_0 does not play a role in the proof our main result, we briefly discuss it here to point out the somewhat surprising fact that \tilde{F}_0 does not always give the right limiting model for the divergence-free dimension reduction problem and may even be nonlocal, in sharp contrast to the gradient case. In addition, the crucial idea for the proof of the upper bound in our main result is developed in Proposition 3.5 for a simple model problem.

In the following, we consider the functional

$$\tilde{F}(u) := \begin{cases} \int_{\Omega} f(x, u) \, \mathrm{d}x & \text{if } u \in \mathcal{U}_0, \\ +\infty & \text{if } u \notin \mathcal{U}_0. \end{cases}$$

By definition, the relaxed functional associated to \tilde{F} is given by the lower semicontinuous hull of \tilde{F} with respect to weak convergence in L^p . For $u \in L^p(\Omega; \mathbb{R}^N)$, it can be expressed by

$$\tilde{F}_0(u) := \Gamma - \lim \tilde{F}(u) = \inf \left\{ \liminf \tilde{F}(u_n) \mid u_n \rightharpoonup u \text{ weakly in } L^p \right\}.$$
(3.1)

Here, note that since \tilde{F} does not depend on n, $\Gamma - \liminf \tilde{F} = \Gamma - \limsup \tilde{F}$. Moreover, \mathcal{U}_0 is weakly closed in L^p , whence $\tilde{F}_0(u)$ is finite if and only if $u \in \mathcal{U}_0$.

Proposition 3.1 (partial representation of \tilde{F}_0). Let $f : \omega \times \mathbb{R}^N \to [0, \infty)$ (identified with $f : \Omega \times \mathbb{R}^N \to \mathbb{R}$ constant in x_N) satisfy (f:0)-(f:2). Then for every $u \in L^p(\omega; \mathbb{R}^N)$ (identified with $u = (u^1, \ldots, u^N) \in L^p(\Omega; \mathbb{R}^N)$ with u^j independent of x_N for every $j = 1, \ldots, N$), we have $\tilde{F}_0(u) = F^{**}(u)$, the convexified functional.

Proof. Since $f \ge f^{**}$ and F^{**} is weakly lower semicontinuous in $L^p(\Omega; \mathbb{R}^N)$, it is clear that $\tilde{F}_0(u) \ge F^{**}(u)$. On the other hand, for any $u \in L^p(\Omega; \mathbb{R}^N)$ which is constant in x_N , we have

$$\begin{split} \tilde{F}_0(u) &= \inf \left\{ \liminf \tilde{F}(u_n) \middle| u_n \rightharpoonup u \text{ weakly in } L^p(\Omega; \mathbb{R}^N), \, \partial_N u_n^N = 0 \in \mathbb{R} \right\} \\ &\leq \inf \left\{ \liminf \tilde{F}(u_n) \middle| u_n \rightharpoonup u \text{ weakly in } L^p(\Omega; \mathbb{R}^N), \, \partial_N u_n = 0 \in \mathbb{R}^N \right\} \\ &= \inf \left\{ \liminf \int_{\omega} f(x', \tilde{u}_n) \, \mathrm{d}x' \middle| \tilde{u}_n \rightharpoonup u \text{ weakly in } L^p(\omega; \mathbb{R}^N) \right\} \\ &= \int_{\omega} f^{**}(x', u) \, \mathrm{d}x' = \int_{\Omega} f^{**}(x', u) \, \mathrm{d}x, \end{split}$$

where we used that $\int_{\omega} f^{**}(x', v) dx'$ is the weakly lower semicontinuous hull of $v \mapsto \int_{\omega} f(x', v) dx'$ in L^p . \Box Example 3.2. Let p = 6, let N = 2, let $f : \mathbb{R}^2 \to \mathbb{R}$ be the three-well potential given by

$$f(\mu) := |\mu - \zeta_1|^2 |\mu - \zeta_2|^2 |\mu - \zeta_3|^2,$$

with $\zeta_1 := (0, -1), \ \zeta_2 := (1, 0), \ \zeta_3 := (0, 1)$

and consider the function $u_0 \in \mathcal{U}_0$ given by

$$u_0(x_1, x_2) := \begin{cases} (0, 0) & \text{if } x_2 \in (0, \frac{1}{2}], \\ (1, 0) & \text{if } x_2 \in (\frac{1}{2}, 1). \end{cases}$$

Proposition 3.3 (possible nonlocal character of \tilde{F}_0). In the situation of Example 3.2, we have that

$$\tilde{F}_0(u_0) > 0 = \frac{|\omega \times (0, \frac{1}{2})|}{|\Omega|} \tilde{F}_0((0, 0)) + \frac{|\omega \times (\frac{1}{2}, 1)|}{|\Omega|} \tilde{F}_0((1, 0)).$$

In particular, $\tilde{F}_0(u)$ cannot be written in the form $\int_{\Omega} V(u) dx$ with some function $V : \mathbb{R}^2 \to \mathbb{R}$, and $\tilde{F}_0(u_0) > F^{**}(u_0)$.

Remark 3.4. As recently discovered in [8], the lower semicontinuous hull with respect to strong convergence in L^2 of certain integral functionals of the form $u \mapsto \int_{\Omega} f(u, \nabla u) \, dx$ can also be nonlocal, if there is a lack of coercivity with respect to the gradient variable.

Proof of Proposition 3.3. Since $f^{**} = 0$ on the closed triangle formed by ζ_1 , ζ_2 and ζ_3 , $\tilde{F}_0((0,0)) = \tilde{F}_0((1,0)) = 0$ by Proposition 3.1. To prove that $\tilde{F}_0(u_0) > 0$, we proceed indirectly. Suppose that $\tilde{F}_0(u_0) = 0$. By a standard diagonalization argument, we may choose a sequence $u_n \in \mathcal{U}_0$ with $u_n \rightharpoonup u_0$ weakly in $L^6(\Omega, \mathbb{R}^2)$ such that $\tilde{F}_0(u_0) = \lim \tilde{F}(u_n)$. By passing to a subsequence (not relabeled), we may assume that u_n generates a Young measure ν_x , which for a.e. $x \in \Omega$ is a probability measure on \mathbb{R}^2 , and by the fundamental theorem for Young measures (see [3,13,25], e.g.), also exploiting that $f \ge 0$, we get that

$$0 = \tilde{F}_0(u_0) = \lim \int_{\Omega} f(u_n) \mathrm{d}x \ge \int_{\Omega} \int_{\mathbb{R}^2} f(\xi) \mathrm{d}\nu_x(\xi) \mathrm{d}x.$$

Since f vanishes only on $\{\zeta_1, \zeta_2, \zeta_3\}$, this implies that ν_x is supported in $\{\zeta_1, \zeta_2, \zeta_3\}$ for a.e. x, *i.e.*,

$$\nu_x = \sum_{j=1}^3 \sigma_j(x) \delta_{\zeta_j},\tag{3.2}$$

where δ_z denotes the Dirac mass concentrated at the point z in \mathbb{R}^2 . Moreover, since $\int_{\mathbb{R}^2} \xi \, d\nu_x(\xi) = u_0(x)$ and ν_x is a probability measure for a.e. x, the coefficients $\sigma_i(x) \in [0, 1]$ are determined by the linear system

$$\sum_{j=1}^{3} \sigma_j(x) \zeta_j = u_0(x)$$
 and $\sum_{j=1}^{3} \sigma_j(x) = 1.$

One easily checks that the unique solution of this system is given by

$$\begin{aligned}
\sigma_1(x) &= \frac{1}{2}, \quad \sigma_2(x) = 0, \quad \sigma_3(x) = \frac{1}{2} & \text{if } x_2 \le \frac{1}{2} \text{ (i.e., } u_0(x) = (0,0)), \\
\sigma_1(x) &= 0, \quad \sigma_2(x) = 1, \quad \sigma_3(x) = 0 & \text{if } x_2 > \frac{1}{2} \text{ (i.e., } u_0(x) = (1,0)),
\end{aligned} \tag{3.3}$$

where $x = (x_1, x_2)$. In addition, the marginal of ν_x on the second coordinate axis,

$$\nu_x^2(A) := \nu_x(\mathbb{R} \times A)$$
 for $A \subset \mathbb{R}$ Borel-measurable,

is the Young measure generated by u_n^2 . Since $u_n \in \mathcal{U}_0$, $u_n^2(x)$ is independent of x_2 for each n and consequently, ν_x^2 only depends on x_1 . This contradicts (3.2), because the latter implies that $\nu_x^2 = \sigma_1(x)\delta_{-1} + \sigma_2(x)\delta_0 + \sigma_3(x)\delta_1$, and the coefficients given by (3.3) are not constant in x_2 (only piecewise constant).

The dimension reduction problem is different because the constraint $\operatorname{div}_{\varepsilon} u_{\varepsilon} = 0$ is actually genuinely less restrictive than $\partial_N u_{\varepsilon}^N = 0$:

Proposition 3.5. In the situation of Example 3.2, for every given pair of sequences $\varepsilon_n \to 0^+$ and $\sigma_n \to 0^+$, there exists a bounded sequence $(u_n) \subset L^{\infty}(\Omega; \mathbb{R}^N)$ such that $u_n \rightharpoonup 0$ in L^p ,

$$\int_{\Omega} f(u_n + u_0) \,\mathrm{d}x \to \int_{\Omega} f^{**}(u_0) \,\mathrm{d}x = 0, \tag{3.4}$$

and

$$\left\|\operatorname{div}_{\varepsilon_{n}} u_{n}\right\|_{W^{-1,p}(\Omega)} + \left\|\left(u_{n}^{\prime}, \frac{1}{\varepsilon_{n}} u_{n}^{N}\right)\right\|_{W^{-1,p}(\Omega;\mathbb{R}^{N})} \le \sigma_{n}$$

$$(3.5)$$

for every n. In particular, u_n can be projected onto $\mathcal{U}_{\varepsilon_n}$ with an error that goes to zero strongly in L^p by Lemma 2.9, and since $\operatorname{div}_{\varepsilon_n} u_0 = \operatorname{div}' u'_0 = 0$, this entails that $\Gamma - \liminf F_{\varepsilon_n}(u_0) \leq 0 < \tilde{F}_0(u_0)$.

Proof. For each n fix a function $\varphi_n \in C_c^{\infty}((0,1);[0,1])$ such that $\varphi_n = 1$ on $[\varepsilon_n, 1 - \varepsilon_n]$, and for $k \in \mathbb{N}$ let

$$w_k(t) = \left(w_k^1(t), w_k^2(t)\right) := \begin{cases} \zeta_3 = (0, 1) & \text{if } 0 < t \le \frac{1}{2k}, \\ \zeta_1 = (0, -1) & \text{if } \frac{1}{2k} < t \le \frac{1}{k}, \end{cases}$$

extended periodically to a function $w_k : \mathbb{R} \to \mathbb{R}^2$ with period $\frac{1}{k}$. Note that

$$w_k \rightharpoonup \frac{1}{2}\zeta_3 + \frac{1}{2}\zeta_1 = (0,0)$$
 weakly in $L^p(T;\mathbb{R}^2)$ (3.6)

for any bounded open set $T \subset \mathbb{R}$. We define $v_{k,n} \in L^p(\Omega; \mathbb{R}^2)$ by

$$v_{k,n}(x_1, x_2) := \begin{cases} \varphi_n(2x_2)w_k(\frac{1}{\varepsilon_n}x_1) & \text{if } 0 < x_2 < \frac{1}{2}, \\ \\ 0 & \text{if } \frac{1}{2} \le x_2 < 1. \end{cases}$$

Observe that although $v_{k,n}$ is not continuous, its jumps do not contribute to $\operatorname{div}_{\varepsilon_n} v_{k,n}$ (as a distribution), and thus the latter is actually a function with

$$\operatorname{div}_{\varepsilon_n} v_{k,n}(x_1, x_2) = \frac{2}{\varepsilon_n} \dot{\varphi}_n(2x_2) w_k^2 \left(\frac{1}{\varepsilon_n} x_1 \right).$$

In particular, as $k \to \infty$ for fixed n, $\operatorname{div}_{\varepsilon_n} v_{k,n} \to 0$ weakly in $L^p(\Omega)$ as a consequence of (3.6), and thus $\operatorname{div}_{\varepsilon_n} v_{k,n} \to 0$ strongly in $W^{-1,p}(\Omega)$, by compact embedding. Analogously, we get that $(v_{k,n}^1, \frac{1}{\varepsilon_n} v_{k,n}^2) \to 0$ in $W^{-1,p}(\Omega; \mathbb{R}^N)$ as $k \to \infty$. Hence, we may choose k = k(n) with $k(n) \to \infty$ as $n \to \infty$ fast enough such that (3.5) holds for $u_n := v_{k(n),n}$. Again using (3.6), it is not difficult to check that $u_n \to 0$ weakly in L^p , and since $f(\zeta_1) = f(\zeta_2) = 0$, u_n is bounded in L^∞ and $|\{u_n \neq \zeta_1\} \cap \{u_n \neq \zeta_2\}| \to 0$, (3.4) holds as well. \Box

Remark 3.6. The choice of the dimension N = 2 is not crucial for Example 3.2, it is just the simplest possible case. In fact, a completely analogous argument can be used for suitable potentials f with N + 1 wells in \mathbb{R}^N for any $N \ge 2$.

4. The upper bound

In this section, we provide the remaining part of the proof of Theorem 1.1, namely the upper bound

$$\Gamma - \limsup F_{\varepsilon}(u) \leq F^{**}(u) \text{ for } u \in \mathcal{U}_0,$$

by constructing a suitable recovery sequence. In particular, we need some results from convex analysis:

Lemma 4.1 (Carathéodory's theorem, see [30], e.g.). Let $g : \mathbb{R}^N \to [0, \infty)$ be continuous. Then for every $\xi \in \mathbb{R}^N$ and every $\delta > 0$, there exists an $m \in \{0, \ldots, N\}$ and $\xi_j \in \mathbb{R}^N$, $\theta_j \in (0, 1]$, $j = 0, \ldots, m$, such that $\sum_j \theta_j = 1, \ \xi = \sum_j \theta_j \xi_j$,

$$g^{**}(\xi) \leq \sum_{j=0}^{m} \theta_j g(\xi_j) \leq g^{**}(\xi) + \delta,$$

and the vectors $\xi_j - \xi_0$, j = 1, ..., m, are linearly independent. Here, g^{**} denotes the convex envelope of g.

Lemma 4.2. Suppose that the assumptions of Lemma 4.1 hold. If, in addition, there exist constants p > 1 and C > 0 such that

$$\frac{1}{C}\left|\mu\right|^{p} - C \le g(\mu) \le C\left|\mu\right|^{p} + C \quad \text{for every } \mu \in \mathbb{R}^{N},\tag{4.1}$$

then the assertion of Lemma 4.1 stays true even for $\delta = 0$, and in this case,

$$|\xi_j| \le K(|\xi|+1) \quad for \ j = 0, \dots, m,$$
(4.2)

where K is a constant that only depends on p and C.

Proof. With some background in convex analysis, this is not hard to prove, and we just sketch some details: It is well known that the convex envelope of g can be represented as

$$g^{**}(\xi) = \sup\left\{ A(\xi) \mid A : \mathbb{R}^N \to \mathbb{R} \text{ affine and } A \le g \right\}, \ \xi \in \mathbb{R}^N.$$

If g is (lower semi-)continuous and has superlinear growth, the supremum is attained at a suitable affine function A (see [13], e.g.), and A always touches g from below at suitable points ξ_j as in Lemma 4.1 with $\delta = 0$. In addition, as a consequence of (4.1), we have that

$$\frac{1}{C} |\mu|^p - C \le A_{\xi}(\mu) \le C |\mu|^p + C \text{ for every } \mu \in \operatorname{co}\{\xi_j\}$$

(the convex hull of the points ξ_j , j = 0, ..., m). Clearly, the existence of an affine function satisfying the latter implies that $co\{\xi_j\}$ is bounded for fixed ξ , and it is not difficult to obtain more precise estimates that yield (4.2).

The following result is the crucial step towards the upper bound for $\Gamma - \limsup F_{\varepsilon}$ in the general case.

Proposition 4.3. Let $N \ge 2$, let $1 \le p < \infty$, let $I \subset (0,1)$ be an open interval and let $\varepsilon_n \to 0^+$. Then for every sequence $\tau_n \to 0^+$ and every pair of points $\zeta_1, \zeta_2 \in \mathbb{R}^N$ and numbers $\gamma_1, \gamma_2 \in (0,1)$ such that $\zeta_1^N \ne \zeta_2^N$, $\gamma_1\zeta_1 + \gamma_2\zeta_2 = 0$ and $\gamma_1 + \gamma_2 = 1$, there exists a sequence $(v_n) \subset L^{\infty}(\mathbb{R}^N; \mathbb{R}^N)$ such that

$$\|v_n\|_{L^{\infty}} \le \max\{|\zeta_1|, |\zeta_2|\},\tag{4.3}$$

$$\left\|\operatorname{div}_{\varepsilon_{n}} v_{n}\right\|_{W^{-1,p}(\Omega)} + \left\| \left(v_{n}^{\prime}, \frac{1}{\varepsilon_{n}} v_{n}^{N} \right) \right\|_{W^{-1,p}(\Omega;\mathbb{R}^{N})} \leq \tau_{n}$$

$$(4.4)$$

for every $n \in \mathbb{N}$,

$$v_n \to 0 \quad in \ L^p_{\mathrm{loc}}(\mathbb{R}^N; \mathbb{R}^N) \ as \ n \to \infty, \ \operatorname{supp}(v_n) \subset \mathbb{R}^{N-1} \times \bigcup_{z \in \mathbb{Z}} \left(\varepsilon_n z + \varepsilon_n I^{[\varepsilon_n]} \right),$$
(4.5)

where $I^{[\varepsilon]} := \{ t \in I \mid \text{dist}(t; \partial I) \ge \varepsilon \}$, and

$$|\{v_n = \zeta_j\} \cap U| \underset{n \to \infty}{\longrightarrow} \gamma_j |U| |I| \text{ for every measurable set } U \subset \mathbb{R}^N$$

$$(4.6)$$

and j = 1, 2.

Remark 4.4. The assumption $\zeta_1^N \neq \zeta_2^N$ is actually obsolete. The case of equality is only excluded above because it is much simpler and will be treated separately in Proposition 4.6 below.

Proof of Proposition 4.3. For each $n \in \mathbb{N}$ fix a function $\varphi_n \in C_c^{\infty}(\mathbb{R}; [0, 1])$ such that $\varphi_n = 1$ on $I^{[2\varepsilon_n]}$ and $\varphi_n = 0$ on $\mathbb{R} \setminus I^{[\varepsilon_n]}$, and define

$$\psi_n \in C^{\infty}(\mathbb{R}; [0, 1]), \quad \psi_n := \sum_{z \in \mathbb{Z}} \varphi_n(\cdot + z).$$

Furthermore, for $k \in \mathbb{N}$ let

$$w_k(t) := \begin{cases} \zeta_1 & \text{if } 0 < t \le \gamma_1 \frac{1}{k}, \\ \zeta_2 & \text{if } -\gamma_2 \frac{1}{k} < t \le 0, \end{cases}$$

extended periodically to a function $w_k : \mathbb{R} \to \mathbb{R}^N$ with period $\frac{1}{k}$. Note that

$$w_k \rightharpoonup \gamma_1 \zeta_1 + \gamma_2 \zeta_2 = 0$$
 weakly in $L^p_{\text{loc}}(\mathbb{R}; \mathbb{R}^N)$. (4.7)

With a fixed unit vector $\zeta_{12}^{\perp} \in \mathbb{R}^N$ perpendicular to $\zeta_1 - \zeta_2$, we define $v_{k,n} \in L^{\infty}(\mathbb{R}^N; \mathbb{R}^N)$ by

$$v_{k,n}(x) := \psi_n\left(\frac{1}{\varepsilon_n}x_N\right) w_k\left(\left(\frac{1}{\varepsilon_n^2}x', \frac{1}{\varepsilon_n}x_N\right) \cdot \zeta_{12}^{\perp}\right).$$

Observe that although $x \mapsto w_k \left(\left(\frac{1}{\varepsilon_n^2} x', \frac{1}{\varepsilon_n} x_N \right) \cdot \zeta_{12}^{\perp} \right)$ is not continuous, it is $\operatorname{div}_{\varepsilon_n}$ -free (as a distribution), and thus $\operatorname{div}_{\varepsilon_n} v_{k,n}$ is actually a function with

$$\operatorname{div}_{\varepsilon_n} v_{k,n}(x) = \frac{1}{\varepsilon_n^2} \dot{\psi}_n\left(\frac{1}{\varepsilon_n} x_N\right) w_k^N\left(\left(\frac{1}{\varepsilon_n^2} x', \frac{1}{\varepsilon_n} x_N\right) \cdot \zeta_{12}^{\perp}\right).$$

In particular, as $k \to \infty$ for fixed n, $\operatorname{div}_{\varepsilon_n} v_{k,n} \to 0$ weakly in $L^p(\Omega)$ due to (4.7), and thus $\operatorname{div}_{\varepsilon_n} v_{k,n} \to 0$ strongly in $W^{-1,p}(\Omega)$, by compact embedding. Analogously, we get that $(v'_{k,n}, \frac{1}{\varepsilon_n} v^N_{k,n}) \to 0$ in $W^{-1,p}(\Omega; \mathbb{R}^N)$ as $k \to \infty$. Hence, we may choose k = k(n) with $k(n) \to \infty$ as $n \to \infty$ fast enough such that (4.4) holds for $v_n := v_{k(n),n}$, and (4.3), (4.5) and (4.6) hold by construction.

Carathéodory's theorem requires convex combination of up to N + 1 points, but Proposition 4.3 only admits two points. The following elementary lemma allows us to handle general convex combinations by breaking them into suitable pairs of two. Essentially, it states that if $\xi = \sum_{j} \theta_{j} \xi_{j}$ is a convex combination with $\xi \in H$, where H is an affine hyperplane, then ξ can be rewritten as a convex combination of points $\bar{\xi}_{ij} \in H$, such that each $\bar{\xi}_{ij}$ is a convex combination of two of the original points, *i.e.*, $\bar{\xi}_{ij} = \beta_{ij}\xi_{j} + \beta_{ji}\xi_{i}$:

Lemma 4.5. Let $m \leq N$, let $\xi_j \in \mathbb{R}^N$, $\theta_j \in (0,1]$ for $j = 0, \ldots, m$ such that $\sum_{j=0}^m \theta_j = 1$ and the vectors $\xi_j - \xi_0$, $j = 1, \ldots, m$, are linearly independent, and define

$$\beta_{ij} := \begin{cases} \frac{\xi_i^N - \xi^N}{\xi_i^N - \xi_j^N} & if \ (\xi_i^N - \xi^N)(\xi_j^N - \xi^N) < 0, \\ 1 & if \ i = j \ and \ \xi_j^N = \xi^N, \\ 0 & else. \end{cases}$$

Here, note that $\beta_{ij} \in [0,1]$ and $\beta_{ij} + \beta_{ji} = 1$ if $(\xi_i^N - \xi^N)(\xi_j^N - \xi^N) < 0$. Then there exists numbers $\alpha_{ij} \in [0,1]$, $i, j \in \{0, \ldots, m\}$, such that

$$\alpha_{ij} = \alpha_{ji}, \quad \alpha_{ij} = 0 \text{ whenever } \beta_{ij} = 0, \quad \sum_{j=0}^{m} \sum_{i=0}^{j} \alpha_{ij} = 1, \tag{4.8}$$

$$\theta_j = \sum_{i=0}^m \alpha_{ij} \beta_{ij},\tag{4.9}$$

and

$$\xi = \frac{1}{2} \sum_{i,j=0}^{m} \alpha_{ij} \left(\beta_{ij} \xi_j + \beta_{ji} \xi_i \right) = \sum_{i < j} \alpha_{ij} \left(\beta_{ij} \xi_j + \beta_{ji} \xi_i \right) + \sum_j \alpha_{jj} \beta_{jj} \xi_j.$$

$$(4.10)$$

Proof. Let $H := \{y \in \mathbb{R}^N \mid y^N = \xi^N\}$. Since $\xi \in S := \operatorname{co}\{\xi_j \mid j = 0, \dots, m\} \cap H$ (where co A denotes the convex hull of a set A), which is a convex polyhedral set, ξ can be written as a convex combination of the extreme points of S. Such an extreme point is either given by ξ_j for some j such that $\xi_j^N = \xi^N$, or it is the intersection of H with a line segment of the form $\operatorname{co}\{\xi_i, \xi_j\}$, for indices i, j such that ξ_i and ξ_j lie on opposite sides of H (*i.e.*, $(\xi_i^N - \xi^N)(\xi_j^N - \xi^N) < 0$). Note that $\operatorname{co}\{\xi_j, \xi_i\} \cap H = \{\beta_{ij}\xi_j + \beta_{ji}\xi_i\}$ in this case. Hence, there exist $\alpha_{ij} \in [0, 1]$ such that $\alpha_{ij} = \alpha_{ji}, \alpha_{ij} = 0$ if $\beta_{ij} = 0, \sum_{i \leq j} \alpha_{ij} = 1$ and (4.10) holds. Moreover, since $\alpha_{ij} = \alpha_{ji}$, we have that

$$\xi = \frac{1}{2} \sum_{i,j=0}^{m} \alpha_{ij} \left(\beta_{ij} \xi_j + \beta_{ji} \xi_i \right) = \sum_{j=0}^{m} \left(\sum_{i=0}^{m} \alpha_{ij} \beta_{ij} \right) \xi_j.$$

This is another way of expressing ξ as a convex combination of the points ξ_j . Since $\xi_j - \xi_0$, j = 1, ..., N, are linearly independent, the coefficients of the convex combination are uniquely determined, and comparison yields (4.9).

Combining multiple instances of Proposition 4.3 with Lemma 4.5, we obtain:

Proposition 4.6. Let $N \ge 2$, let $1 \le p < \infty$, let $J \subset (0,1)$ be an open interval and let $\varepsilon_n \to 0^+$. Moreover, let $m \le N$, let $\xi_j \in \mathbb{R}^N$ and $\theta_j \in (0,1]$, $j = 0, \ldots, m$, be such that

$$\sum_{j} \theta_j \xi_j = 0, \quad \sum_{j} \theta_j = 1,$$

and the vectors $\xi_j - \xi_0$, j = 1, ..., m, are linearly independent. Then for every sequence $\sigma_n \to 0^+$, there exist sequences $(y_n), (z_n) \subset L^{\infty}(\mathbb{R}^N; \mathbb{R}^N)$ such that

$$||y_n||_{L^{\infty}} \le \max_j |\xi_j| \quad and \quad ||z_n||_{L^{\infty}} \le \max_j |\xi_j|,$$
(4.11)

$$\partial_N y_n^N = \operatorname{div}' y_n' = 0 \quad on \ \mathbb{R}^N, \tag{4.12}$$

$$\left\|\operatorname{div}_{\varepsilon_{n}} z_{n}\right\|_{W^{-1,p}(\Omega)} + \left\| \left(z_{n}^{\prime}, \frac{1}{\varepsilon_{n}} z_{n}^{N} \right) \right\|_{W^{-1,p}(\Omega;\mathbb{R}^{N})} \leq \sigma_{n}$$

$$(4.13)$$

for every $n \in \mathbb{N}$,

$$y_n \rightharpoonup 0, \quad z_n \rightharpoonup 0 \quad in \ L^p(\omega \times J; \mathbb{R}^N) \ as \ n \rightarrow \infty,$$

$$\sup(y_n) \cup \sup(z_n) \subset \mathbb{R}^{N-1} \times K_n \quad \text{for a compact set } K_n \subset J$$

$$(4.14)$$

and

$$|\{y_n + z_n = \xi_j\} \cap U| \longrightarrow \theta_j |U|, \quad for \ every \ measurable \ U \subset \mathbb{R}^{N-1} \times J \tag{4.15}$$

and every $j \in \{0, ..., m\}$.

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Proof. Let α_{ij} and β_{ij} be as in Lemma 4.5 with $\xi = 0$, and divide the unit interval (0, 1) into pairwise disjoint open subintervals I_{ij} , $0 \le i \le j \le m$ (some possibly empty), such that $|I_{ij}| = \alpha_{ij}$. For $\varepsilon > 0$ let

$$T_{ij}(\varepsilon) := \mathbb{R}^{N-1} \times \bigcup_{k \in \mathbb{Z}} (\varepsilon k + \varepsilon I_{ij}), \qquad \bar{\xi}_{ij} := \begin{cases} \beta_{ji}\xi_i + \beta_{ij}\xi_j & \text{if } i \neq j, \\ \xi_j & \text{if } i = j. \end{cases}$$

For $i \leq j$, we define bounded sequence $(y_{ij,n})_n, (z_{ij,n})_n \subset L^{\infty}(\mathbb{R}^N; \mathbb{R}^N)$ as follows:

$$y_{ij,n} := \chi_{T_{ij}(\varepsilon_n)} \xi_{ij},$$

where $\chi_{T_{ij}(\varepsilon_n)}$ denotes the characteristic function of the set $T_{ij}(\varepsilon_n)$. For every j, we set $z_{jj,n} := 0$. For i < j, let $z_{ij,n}$ be the sequence obtained in Proposition 4.3, applied with $I := I_{ij}$, $\tau_n := \frac{1}{(m+1)(m+2)}\varepsilon_n\sigma_n$, $\zeta_1 := \xi_i - \bar{\xi}_{ij}$, $\zeta_2 := \xi_j - \bar{\xi}_{ij}$, $\gamma_1 := \beta_{ji}$ and $\gamma_2 := \beta_{ij} = 1 - \beta_{ji}$. In particular, Proposition 4.3 gives that

$$\left| \{ z_{ij,n} = \xi_i - \bar{\xi}_{ij} \} \cap U \right| \xrightarrow[n \to \infty]{} \beta_{ji} \left| I_{ij} \right| \left| U \right| = \beta_{ji} \alpha_{ij} \left| U \right|, \\ \left| \{ z_{ij,n} = \xi_j - \bar{\xi}_{ij} \} \cap U \right| \xrightarrow[n \to \infty]{} \beta_{ij} \left| I_{ij} \right| \left| U \right| = \beta_{ij} \alpha_{ij} \left| U \right|,$$

$$(4.16)$$

for every measurable $U \subset \mathbb{R}^N$, and

$$\operatorname{supp}(z_{ij,n}) \subset \mathbb{R}^{N-1} \times \bigcup_{k \in \mathbb{Z}} \left(\varepsilon_n k + \varepsilon_n I_{ij}^{[\varepsilon_n]} \right) \text{ with a compact } I_{ij}^{[\varepsilon_n]} \subset I_{ij}$$

$$(4.17)$$

for every $i \leq j$ (for i = j, (4.16) and (4.17) are trivial). In addition,

$$\left\|\operatorname{div}_{\varepsilon_{n}} z_{ij,n}\right\|_{W^{-1,p}(\Omega)} + \left\| \left(z_{ij,n}^{\prime}, \frac{1}{\varepsilon_{n}} z_{ij,n}^{N} \right) \right\|_{W^{-1,p}(\Omega;\mathbb{R}^{N})} \le \frac{1}{(m+1)(m+2)} \varepsilon_{n} \sigma_{n}$$

$$(4.18)$$

for every n and every $i \leq j$. Now let

$$\tilde{z}_n(x) := \sum_{j=0}^m \sum_{i=0}^j z_{ij,n}(x) \text{ and } \tilde{y}_n(x) := \sum_{j=0}^m \sum_{i=0}^j y_{ij,n}(x) \text{ for } x \in \mathbb{R}^N.$$

Note that at any given x, at most one term contributes in each of the double sums above; more precisely, $\tilde{z}_n = z_{ij,n}$ and $\tilde{y}_n = y_{ij,n}$ on $T_{ij}(\varepsilon_n)$. Moreover,

$$\tilde{y}_n \underset{n \to \infty}{\rightharpoonup} \sum_{j=0}^m \sum_{i=0}^j |I_{ij}| \bar{\xi}_{ij} = \sum_{i < j} \alpha_{ij} (\beta_{ij} \xi_j + \beta_{ji} \xi_i) + \sum_j \alpha_{jj} \beta_{jj} \xi_j = 0$$

weakly in $L^p(\Omega; \mathbb{R}^N)$, and

 $\partial_N \tilde{y}_n^N = \operatorname{div}' \tilde{y}_n' = 0 \text{ on } \mathbb{R}^N$ since $\tilde{y}_n(\cdot, x_N)$ is constant for every $x_N \in \mathbb{R}$ and $\tilde{y}_n^N = \bar{\xi}_{ij}^N = 0$ a.e. in $T_{ij}(\varepsilon_n)$. By (4.18), we obtain that

$$\left\|\operatorname{div}_{\varepsilon_{n}}\tilde{z}_{n}\right\|_{W^{-1,p}(\Omega)} + \left\|\left(\tilde{z}_{n}^{\prime}, \frac{1}{\varepsilon_{n}}\tilde{z}_{n}^{N}\right)\right\|_{W^{-1,p}(\Omega;\mathbb{R}^{N})} \leq \sum_{j=0}^{m}\sum_{i=0}^{j}\frac{1}{(m+1)(m+2)}(\varepsilon_{n}+1)\sigma_{n} = \frac{\varepsilon_{n}+1}{2}\sigma_{n} \leq \sigma_{n}$$
(4.19)

for $n \in \mathbb{N}$. By (4.16), we get that

$$|\{\tilde{y}_n + \tilde{z}_n = \xi_j\} \cap U| \underset{n \to \infty}{\longrightarrow} \left(|I_{jj}| + \sum_{i \neq j} \beta_{ij} \alpha_{ij} \right) |U| = \theta_j |U|$$

$$(4.20)$$

for every j and every measurable $U \subset \mathbb{R}^N$, where the latter equality is due to (4.9) combined with the fact that $|I_{ij}^{[\varepsilon_n]}| = \alpha_{jj} = \beta_{jj}\alpha_{jj}$. Finally, define

$$z_n := \chi_{\mathbb{R}^{N-1} \times K_n} \tilde{z}_n$$
 and $y_n := \chi_{\mathbb{R}^{N-1} \times K_n} \tilde{y}_n$

where

$$K_n := \bigcup_{k \in Z_n(J)} \left(\varepsilon_n k + \varepsilon_n[0,1] \right) \text{ and } Z_n(J) := \left\{ k \in \mathbb{Z} \mid \varepsilon_n k + \varepsilon_n[0,1] \subset J \right\}.$$

Clearly, (4.11), (4.14) and (4.15) are satisfied, the latter as a consequence of (4.20). In addition,

 $z_n = 0$ and $y_n^N = \xi^N = 0$ in a neighborhood of $\mathbb{R}^{N-1} \times \partial K_n$,

the former by (4.17). Consequently, $\partial_N y_n^N = \partial_N \tilde{y}_n^N = 0$ and $\operatorname{div}' y_n' = \operatorname{div}' \tilde{y}_n' = 0$ on \mathbb{R}^N , and (4.19) implies (4.13).

The next result essentially yields the upper bound in the piecewise constant case.

Proposition 4.7. Let $f_{\#}$ be a function satisfying (f:0)–(f:2) and let $u_{\#} \in \mathcal{U}_0$. Moreover, let $J_k \subset (0,1)$ be a finite number of pairwise disjoint open intervals covering (0,1) up to a set of measure zero, let $\omega_h \subset \omega$ be a finite number of open, pairwise disjoint sets covering ω up to a set of measure zero, and suppose that for each (h, k) and each $\mu \in \mathbb{R}^N$,

 $u_{\#}$ and $f_{\#}(\cdot,\mu)$ are constant on $Q_{h,k}$, where $Q_{h,k} := \omega_h \times J_k$.

Then for every pair of sequences $\varepsilon_n \to 0^+$ and $\tau_n \to 0^+$, there exist two sequences $(v_n), (w_n) \in L^{\infty}(\Omega; \mathbb{R}^N)$ such that $v_n \to 0$ and $w_n \to 0$ in $L^p(\Omega; \mathbb{R}^N)$,

$$|v_n(x)| \le K(|u_{\#}(x)|+1) \text{ and } |w_n(x)| \le K(|u_{\#}(x)|+1) \text{ for a.e. } x \in \Omega,$$
 (4.21)

where K is a constant that only depends on the constants in (f:1) and (f:2),

$$\operatorname{div}_{\varepsilon_n} v_n = 0 \quad on \ \mathbb{R}^N, \tag{4.22}$$

$$\left\|\operatorname{div}_{\varepsilon_{n}} w_{n}\right\|_{W^{-1,p}(\Omega)} + \left\| \left(w_{n}^{\prime}, \frac{1}{\varepsilon_{n}} w_{n}^{N} \right) \right\|_{W^{-1,p}(\Omega;\mathbb{R}^{N})} \leq \tau_{n}$$

$$(4.23)$$

for every $n \in \mathbb{N}$, and

$$\lim_{n \to \infty} \int_{\Omega} f_{\#}(x, u + v_n + w_n) \, \mathrm{d}x = \int_{\Omega} f_{\#}^{**}(x, u) \, \mathrm{d}x, \tag{4.24}$$

where for every x, $f_{\#}^{**}(x, \cdot)$ denotes the convex envelope of $f_{\#}(x, \cdot)$.

Proof.

Step 1: We first show the assertion with (4.22) replaced by the condition

$$\partial_N v_n^N = 0 \text{ on } \mathbb{R}^N \text{ and } \left\| \operatorname{div}' v_n' \right\|_{L^{\infty}(\Omega)} \le (\varepsilon_n)^{-\frac{1}{2}}.$$
 (4.25)

Clearly, it is enough to define v_n and w_n on each $Q_{h,k}$ and prove the asserted properties with $Q_{h,k}$ instead of Ω , as long as the restriction of v_n and w_n to any one $Q_{h,k}$ has compact support in this set. Hence, we consider h and k to be fixed below.

Let $(\sigma_n) \subset (0,\infty)$ be a sequence with $\sigma_n \to 0^+$ (fast enough, as specified later), and define

$$u_{h,k} := u_{\#}(x)$$
 and $g_{h,k}(\mu) := f_{\#}(x, \mu + u_{h,k})$ for $x \in Q_{h,k}$ and $\mu \in \mathbb{R}^N$.

By Lemmas 4.1 and 4.2, $0 \in \mathbb{R}^N$ can be written as a convex combination $0 = \sum_{j=0}^m \theta_j \xi_j$ such that $\xi_j - \xi_0$, $j = 1, \ldots, m$, are linearly independent and

$$\sum_{j=0}^{m} \theta_j f_{\#}(x,\xi_j + u_{\#}(x)) = \sum_{j=0}^{m} \theta_j g_{h,k}(\xi_j) = g_{h,k}^{**}(0) = f_{\#}^{**}(x,u_{\#}(x)),$$
(4.26)

for every $x \in Q_{h,k}$. Moreover, as a consequence of (4.2),

$$\max_{j} |\xi_{j}| \le K(|u_{h,k}|+1),$$
(4.27)

with a constant K only depending on the constants in (f:1) and (f:2). Proposition 4.6 applied with $J = J_k$ yields two sequences $(y_n), (z_n) \subset L^{\infty}(\mathbb{R}^N; \mathbb{R}^N)$ such that $y_n \rightharpoonup 0$ and $z_n \rightharpoonup 0$ in L^p_{loc} ,

$$|y_n(x)| \le K(|u_{h,k}|+1) \text{ and } |z_n(x)| \le K(|u_{h,k}|+1) \text{ for } x \in \mathbb{R}^N,$$
 (4.28)

$$\partial_N y_n^N = \operatorname{div}' y_n' = 0 \quad \text{on } \mathbb{R}^N, \tag{4.29}$$

$$\left\|\operatorname{div}_{\varepsilon_{n}} z_{n}\right\|_{W^{-1,p}(\Omega)} + \left\| \left(z_{n}^{\prime}, \frac{1}{\varepsilon_{n}} z_{n}^{N} \right) \right\|_{W^{-1,p}(\Omega;\mathbb{R}^{N})} \leq \sigma_{n},$$

$$(4.30)$$

 y_n and z_n vanish in a neighborhood of $\mathbb{R}^{N-1} \times \partial J_k$ (depending on n), (4.31)

and

$$\lim_{n \to \infty} \int_{Q_{h,k}} g_{h,k}(y_n + z_n) \, \mathrm{d}x = |Q_{h,k}| \sum_{j=0}^m \theta_j g_{h,k}(\xi_j), \tag{4.32}$$

the latter due to (4.15) and Lebesgue's theorem. Together with (4.26), (4.32) yields that

$$\lim_{n \to \infty} \int_{Q_{h,k}} g_{h,k}(y_n + z_n) \, \mathrm{d}x = \int_{Q_{h,k}} g_{h,k}^{**}(0) \, \mathrm{d}x.$$
(4.33)

To obtain functions with compact support in $Q_{h,k}$, we have to cut off y_n and z_n near $(\partial \omega_h) \times J_k$. For this purpose choose a sequence of functions $\eta_n \in C_c^{\infty}(\omega_h; [0, 1])$ in such a way that

$$\eta_n \nearrow 1$$
 pointwise and $\|\nabla \eta_n\|_{L^{\infty}} \le (\varepsilon_n)^{-\frac{1}{2}} \frac{1}{K(|u_{h,k}|+1)}$.

Below, we identify η_n with a function in $C^{\infty}(\mathbb{R}^N)$ that is constant in x_N . In particular, we have that

$$(1 - \eta_n)y_n \to 0 \text{ and } (1 - \eta_n)z_n \to 0 \text{ pointwise a.e. on } Q_{h,k}.$$
 (4.34)

We define

 $v_n := \eta_n y_n$ and $w_n := \eta_n z_n$.

By construction, these functions have compact support in $Q_{h,k}$, $v_n \rightarrow 0$ in L^p and $w_n \rightarrow 0$ in L^p , and (4.28) entails (4.21). In addition, we have (4.25), its second part since by (4.29), div' $v'_n = (\nabla' \eta_n) \cdot y'_n = (\nabla \eta_n) \cdot y_n$ and thus

$$\left\|\operatorname{div}' v_n'\right\|_{L^{\infty}} \le \|\nabla \eta_n\|_{L^{\infty}} \|y_n\|_{L^{\infty}} \le (\varepsilon_n)^{-\frac{1}{2}}$$

By Lebesgue's theorem, (4.33) and (4.34) yield (4.24) for $Q_{h,k}$ instead of Ω . Finally,

$$\operatorname{div}_{\varepsilon_n}(\eta_n z_n) = (\nabla' \eta_n) \cdot z'_n + \eta_n \operatorname{div}_{\varepsilon_n} z_n$$

whence

$$\begin{split} \|\operatorname{div}_{\varepsilon_{n}}(\eta_{n}z_{n})\|_{W^{-1,p}(Q_{h,k})} + \left\| \left((\eta_{n}z_{n})', \frac{1}{\varepsilon_{n}}(\eta_{n}z_{n})^{N} \right) \right\|_{W^{-1,p}(Q_{h,k};\mathbb{R}^{N})} \\ & \leq \|\eta_{n}\|_{W^{2,\infty}(\mathbb{R}^{N})} \left(\|\operatorname{div}_{\varepsilon_{n}}z_{n}\|_{W^{-1,p}(\Omega)} + \left\| \left(z'_{n}, \frac{1}{\varepsilon_{n}}z_{n}^{N} \right) \right\|_{W^{-1,p}(\Omega;\mathbb{R}^{N})} \right) \leq \|\eta_{n}\|_{W^{2,\infty}(\mathbb{R}^{N})} \sigma_{n}$$

by (4.30). With $\sigma_n := \tau_n(\|\eta_n\|_{W^{2,\infty}})^{-1}$, this gives (4.23) for $Q_{h,k}$ instead of Ω .

Step 2: We still have to modify v_n to obtain (4.22) instead of (4.25), while maintaining the other asserted properties. For $x \in \mathbb{R}^N$ let

$$\tilde{v}_n(x) := v_n(x) - \left(0, \varepsilon_n \int_0^{x_N} \operatorname{div}' v'_n(x', t) \, \mathrm{d}t\right)$$

for $x = (x', x_N) \in \Omega$, with v_n as in the first step. Since $\partial_N v_n = 0$, we have $\operatorname{div}_{\varepsilon} \tilde{v}_n = 0$ on Ω by construction, and due to the second part of (4.25),

$$\|v_n - \tilde{v}_n\|_{L^{\infty}} \le (\varepsilon_n)^{\frac{1}{2}} \to 0.$$

As a consequence of the latter, (4.21), (4.23) and (4.24) also hold for \tilde{v}_n instead of v_n (in case of (4.21) with a slightly larger constant).

The proof of the upper bound in the general framework relies on approximation and the following well-known property of Carathéodory functions.

Proposition 4.8 (Scorza-Dragoni, e.g. see [11]). Let $\Omega \subset \mathbb{R}^N$ be open and bounded and let $f : \Omega \times \mathbb{R}^N \to \mathbb{R}$ be a Carathéodory function. Then for every $\delta > 0$, there exists a compact set $\tilde{\Omega} \subset \Omega$ such that $|\Omega \setminus \tilde{\Omega}| < \delta$ and f is continuous on $\tilde{\Omega} \times \mathbb{R}^N$.

Proposition 4.9 (upper bound). Assume (f:0)–(f:2), let $u \in U_0$ and let $\varepsilon_n \to 0^+$. Then for every $\delta > 0$, there exists a sequence $(u_n) \subset U_{\varepsilon_n}$ such that $u_n \rightharpoonup u$ in $L^p(\Omega; \mathbb{R}^N)$, and

$$\lim_{n \to \infty} \int_{\Omega} f(x, u_n) \, \mathrm{d}x \le \int_{\Omega} f^{**}(x, u) \, \mathrm{d}x + \delta.$$
(4.35)

Remark 4.10. Since (f:2) yields a bound on $||u_n||_{L^p}$ independent of δ , a diagonalization argument similar to the one in the third step of the proof below shows that the assertion of Proposition 4.9 stays true even for $\delta = 0$.

Proof of Proposition 4.9. Using a series of approximations, the assertion is reduced to Proposition 4.6. Any expression of the form " $A \approx B$ " below means that A = B + e, with an error e whose modulus is controlled by a suitable fraction of δ .

Step 1: Assume that $u \in \mathcal{U}_0$ is continuous in $\overline{\Omega}$ and f is continuous on $\widetilde{\Omega} \times \mathbb{R}^N$, for some compact $\widetilde{\Omega} \subset \overline{\Omega}$. We claim that in this case, there exists sequences $(u_n) \subset \mathcal{U}_{\varepsilon_n}$ and $(r_n) \subset L^p(\Omega; \mathbb{R}^N)$ such that $u_n \to 0$ and $r_n \to 0$ in L^p ,

$$\lim_{n \to \infty} \int_{\tilde{\Omega}} f(x, u_n - r_n) \, \mathrm{d}x = \lim_{n \to \infty} \int_{\tilde{\Omega}} f(x, u_n) \, \mathrm{d}x \approx \int_{\tilde{\Omega}} f^{**}(x, u) \, \mathrm{d}x \tag{4.36}$$

and

$$|u_n(x) - r_n(x)| \le (2K+1)(|u(x)|+1) \text{ for a.e. } x \in \Omega,$$
(4.37)

where K is the constant in (4.28) (which, unlike u_n and r_n , is independent of $\hat{\Omega}$).

For the proof, we divide Ω into sets of the form $Q_{h,k} = \omega_h \times J_k$ and define associated piecewise constant approximations of u and f as follows: For $x \in Q_{h,k}$, let $u_{\#}(x) = (u_{\#}^1, \ldots, u_{\#}^N)(x)$ be given by

$$u^{j}_{\#}(x) := \inf \left\{ \max\{u^{j}(y), 0\} \mid y \in Q_{h,k} \right\} + \sup \left\{ \min\{u^{j}(y), 0\} \mid y \in Q_{h,k} \right\},\$$

for j = 1, ..., N, whence $u_{\#}$ is a piecewise constant function in \mathcal{U}_0 such that $|u_{\#}^j| \leq |u^j|$. Moreover, for $x \in Q_{h,k}$ let

$$f_{\#}(x,\cdot) := f(x_{h,k},\cdot) \quad \text{with a fixed} \quad x_{h,k} \in \begin{cases} \dot{\Omega} \cap Q_{h,k} & \text{if } |\dot{\Omega} \cap Q_{h,k}| > 0\\ Q_{h,k} & \text{otherwise.} \end{cases}$$

Note that $x_{h,k}$ can always be chosen in such a way that $f_{\#}$ satisfies (f:1) and (f:2) with the original constants. In the following, let

$$S := \overline{B_R(0)} \subset \mathbb{R}^N, \text{ with } R := (2K+1)(\|\tilde{u}\|_{L^{\infty}(\tilde{\Omega};\mathbb{R}^N)} + 1),$$

where K is the constant in (4.28). If the mesh size (the maximal side length of the boxes $Q_{h,k}$) is small enough, we get that

$$\max_{x \in \tilde{\Omega}} |u(x) - u_{\#}(x)| \approx 0 \text{ and } \max_{x \in \tilde{\Omega}, \ \mu \in S} |f(x,\mu) - f_{\#}(x,\mu)| \approx 0$$
(4.38)

by the uniform continuity of u and f on compact sets. With the sequences v_n and w_n of Proposition 4.6, using (4.38), (4.21) and the uniform continuity of f on $\tilde{\Omega} \times S$, we thus have that

$$\int_{\tilde{\Omega}} f(x, u+v_n+w_n) \, \mathrm{d}x \approx \int_{\tilde{\Omega}} f(x, u_\#+v_n+w_n) \, \mathrm{d}x \approx \int_{\tilde{\Omega}} f_\#(x, u_\#+v_n+w_n) \, \mathrm{d}x$$

uniformly in n. Similarly, (4.38) and the uniform continuity of f^{**} on $\tilde{\Omega} \times S$ yield that

$$\int_{\tilde{\Omega}} f^{**}(x, u) \, \mathrm{d}x \approx \int_{\tilde{\Omega}} f^{**}(x, u_{\#}) \, \mathrm{d}x \approx \int_{\tilde{\Omega}} f^{**}_{\#}(x, u_{\#}) \, \mathrm{d}x.$$

Here, note that if f is uniformly continuous on $\tilde{\Omega} \times \{K\mu + \eta \mid \mu \in S, \eta \in \overline{B}_1(0)\}$, then f^{**} is uniformly continuous on $\tilde{\Omega} \times S$ as a consequence of Lemma 4.2. Together with (4.24), we infer that

$$\lim_{n \to \infty} \int_{\tilde{\Omega}} f(x, u + v_n + w_n) \, \mathrm{d}x \approx \int_{\tilde{\Omega}} f^{**}(x, u) \, \mathrm{d}x.$$
(4.39)

Finally, by Lemmas 2.3 and 2.9 applied to u and w_n , respectively, there exists a sequence $(r_n) \subset L^p(\Omega; \mathbb{R}^N)$ such that $r_n \to 0$ in L^p and $\operatorname{div}_{\varepsilon_n}(u + w_n + r_n) = 0$ on Ω . By Lebesgue's theorem, (f:0) and (f:1), we have that

$$\lim_{n \to \infty} \int_{\Omega} f(x, u + v_n + w_n) \,\mathrm{d}x = \lim_{n \to \infty} \int_{\Omega} f(x, u + v_n + w_n + r_n) \,\mathrm{d}x,\tag{4.40}$$

also using that $u \in L^p$ is fixed and (v_n) , (w_n) are bounded in L^{∞} . Combining (4.39) and (4.40), we infer (4.36) for $u_n := u + v_n + w_n + r_n$, and (4.37) is a consequence of (4.28) and the fact that $|u_{\#}| \le |u|$ a.e. in Ω .

Step 2: Assume that $u \in \mathcal{U}_0$ is continuous in $\overline{\Omega}$.

As a consequence of Proposition 4.8, there exists a compact subset $\tilde{\Omega}$ of Ω such that f is continuous on $\tilde{\Omega} \times \mathbb{R}^N$, and $|\Omega \setminus \tilde{\Omega}|$ is small enough such that

$$\int_{\Omega \setminus \tilde{\Omega}} |f^{**}(x, u)| \, \mathrm{d}x \approx 0 \tag{4.41}$$

and

$$\sup_{v \in V} \int_{\Omega \setminus \tilde{\Omega}} |f(x, v(x))| \, \mathrm{d}x \approx 0, \tag{4.42}$$

where $V := \{v \in L^p(\Omega; \mathbb{R}^N) \mid |v| \le (2K+1)(|u|+1) \text{ a.e.}\}$. Here, note that the set $\{f(\cdot, v(\cdot)) \mid v \in V\} \subset L^1(\Omega)$ is equiintegrable by (f:1). With the sequences $(u_n) \subset U_{\varepsilon_n}$ and $(r_n) \subset L^p(\Omega; \mathbb{R}^N)$ of Step 1, we thus have that

$$\lim_{n \to \infty} \int_{\Omega} f(x, u_n - r_n) = \lim_{n \to \infty} \int_{\Omega} f(x, u_n) \approx \int_{\Omega} f^{**}(x, u_n)$$

due to (4.36), (4.41), (4.37) and (4.42).

Step 3: The general case.

By Lemma 2.1, there exists a sequence $(\tilde{u}_k) \subset \mathcal{U}_0 \cap C(\bar{\Omega}; \mathbb{R}^N)$ with $\tilde{u}_k \to u$ in $L^p(\Omega)$. Let $(\tilde{u}_{k,n}) \subset \mathcal{U}_{\varepsilon_n}$ and $(\tilde{r}_{k,n}) \subset L^p(\Omega; \mathbb{R}^N)$ denote the sequences corresponding to \tilde{u}_k obtained in the previous step. By (4.37), $\tilde{u}_{k,n} - \tilde{r}_{k,n}$ is bounded in L^p , uniformly in k and n. Since $\tilde{u}_{k,n} - \tilde{r}_{k,n} \rightharpoonup u_k$ in L^p as $n \to \infty$, $\tilde{u}_k \to u$ in L^p as $k \to \infty$, $\tilde{r}_{k,n} \to 0$ in L^p as $n \to \infty$, and

$$\lim_{n \to \infty} \int_{\Omega} f(x, \tilde{u}_{k,n}) \approx \int_{\Omega} f^{**}(x, \tilde{u}_k) \underset{k \to \infty}{\longrightarrow} \int_{\Omega} f^{**}(x, u),$$

there exist diagonal sequences

 $u_n := \tilde{u}_{k(n),n} \in \mathcal{U}_{\varepsilon_n}$ and $r_n := \tilde{r}_{k(n),n} \in L^p(\Omega; \mathbb{R}^N)$

with $k(n) \to \infty$ slow enough such that $u_n - r_n \rightharpoonup u$ in L^p , $r_n \to 0$ in L^p , and

$$\lim_{n \to \infty} \int_{\Omega} f(x, u_n) \approx \int_{\Omega} f^{**}(x, u).$$

Here, note that since the dual of L^p is separable, the weak topology on bounded subsets of L^p is metrizable, which allows us to extract a weakly convergent diagonal subsequence from a sequence of equibounded weakly convergent sequences using the associated metric.

Remark 4.11. It is natural to ask whether our result also holds for functionals on Div-free matrix fields (*i.e.*, each column is divergence-free). The approach presented here extends in a straightforward way to fields with values in $\mathbb{R}^{N \times M}$ for $M \leq N-1$, but it does not work for $M \geq N$. In fact, our construction for the upper bound, based on Carathéodory's theorem, can only be expected to work if Div-quasiconvexity implies convexity. Here, note that Div-quasiconvexity (or S-quasiconvexity in the terminology of [27]) always implies convexity along directions of rank $\leq N-1$. For similar reasons, more general differential constraints of the form $\mathcal{A}u = 0$ are out of reach at the moment, certainly if \mathcal{A} -quasiconvexity (as defined in [14]) does not imply convexity. We expect that in such cases, the convex envelope in Theorem 1.1 has to be replaced by a suitable variant of a quasiconvex envelope. We hope to address this in a future work, maybe for Div-free matrix fields with $M \geq N$ as a first step.

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