

THE INVERSE OF THE DIVERGENCE OPERATOR ON PERFORATED DOMAINS WITH APPLICATIONS TO HOMOGENIZATION PROBLEMS FOR THE COMPRESSIBLE NAVIER–STOKES SYSTEM

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Abstract. We study the inverse of the divergence operator on a domain $\Omega \subset R^3$ perforated by a system of tiny holes. We show that such inverse can be constructed on the Lebesgue space $L^p(\Omega)$ for any $1 < p < 3$, with a norm independent of perforation, provided the holes are suitably small and their mutual distance suitably large. Applications are given to problems arising in homogenization of steady compressible fluid flows.

Mathematics Subject Classification. 35B27, 35Q30, 35Q35.

Received September 29, 2015. Revised January 12, 2016.

1. INTRODUCTION

Homogenization in fluid mechanics gives rise to system of partial differential equations considered on physical domains perforated by a large number of tiny holes. The typical diameter and mutual distance of these holes play a crucial role in the asymptotic behavior of fluid flows in the regime where the number of holes tends to infinity and their size tends to zero.

Viscous fluid flows passing an array of fixed solid obstacles is a situation frequently occurring in applications. *A priori*, the Navier–Stokes equations with a no-slip boundary condition on the obstacles are believed to be the correct model. With an increasing number of holes, the fluid flow approaches an effective state governed by certain “homogenized” equations which are homogeneous in form (without obstacles). We refer to [22] for a number of real world applications.

The problem is relatively well understood in the framework of *stationary, viscous* fluid flows represented by the the standard Stokes and/or Navier–Stokes system of equations. Allaire [3, 4] (see also earlier results by Tartar [23]) identified three different scenarios for the case of periodically distributed holes:

- the supercritical size of holes for which the asymptotic limit is Darcy’s law;
- the critical size giving rise to Brinkman’s law;

Keywords and phrases. Perforated domains, Bogovskii type operators, homogenization, compressible Navier–Stokes system.

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- the subcritical size of holes has no influence on the motion in the asymptotic limit – the limit problem coincides with the original one.

Related results for the evolutionary (time-dependent) incompressible Navier–Stokes system were obtained by Mikelić [18] and, more recently, in [13].

Considerably less is known in the case of *compressible* fluids. Masmoudi [17] identified rigorously the porous medium equation (Darcy’s law) as a homogenization limit for the evolutionary barotropic (compressible) Navier–Stokes system in the case where the diameter of the holes is comparable to their mutual distance, which is a subcase of the supercritical case, similar results for the full Navier–Stokes–Fourier system were obtained in [12].

In [9], we considered the compressible (isentropic) stationary Navier–Stokes system in the subcritical regime, where the spatial domain is perforated by a periodic lattice of holes of subcritical size. Similarly to the incompressible case, we showed that the motion is not affected by the obstacles and the limit problem coincides with the original one. The result was conditioned by two basic hypotheses:

- the isentropic pressure-density state relation

$$p(\varrho) = a\varrho^\gamma, \quad a > 0, \quad \gamma \geq 3; \quad (1.1)$$

- periodic distribution of the holes.

Note that hypothesis (1.1) was also used by Masmoudi [17] in the evolutionary case. In the stationary regime considered in [9], the assumption (1.1) plays a crucial role as it renders the pressure square-integrable. Accordingly, the well developed Hilbertian L^2 -theory can be used to handle the problem, in particular, the restriction operator introduced by Tartar [23] can be used in a compatible way to construct the inverse of the divergence – the so-called Bogovskii’s operator (see [5, 15], Chap. 3).

Our goal in the present paper is to extend the results of [9] to the case:

- the isentropic pressure-density state relation with lower adiabatic number

$$p(\varrho) = a\varrho^\gamma, \quad a > 0, \quad \gamma > 2; \quad (1.2)$$

- general distribution of the holes, only conditions on the diameter, shape, and mutual distance prescribed.

While considering a general distribution of holes represents only an incremental improvement with respect to [9], the seemingly easier step from (1.1) to (1.2) requires more effort. The reason is that the pressure p is no longer (known to be) square integrable, and, consequently, the L^2 -theory cannot be used in order to obtain the necessary uniform bounds on the solutions. In particular, the inverse of the divergence operator used in ([9], Sect. 2.1), based on the standard Bogovskii’s construction acting between the spaces $L_0^2(\Omega_\varepsilon)$ and $W_0^{1,2}(\Omega_\varepsilon; \mathbb{R}^3)$ combined with Tartar’s restriction operator, is no longer applicable and must be replaced by its L^p -analogue for a general $1 < p < 3$. The construction of such an operator may be seen as the main novelty of the present paper in comparison with [9] and may be of independent interest.

The paper is organized as follows. In Section 2, we collect the necessary preliminary materials, formulate the problem, and state our main result. Section 3 is the heart of the paper. Here we construct the inverse of the divergence – a Bogovskii’s type operator – enjoying the desired properties. The uniform estimates obtained *via* this operator are then used in Section 4 to identify the asymptotic limit for the Navier–Stokes system in perforated domains.

2. PRELIMINARIES, PROBLEM FORMULATION, MAIN RESULT

In what follows, we denote by $W^{-1,q}(\Omega)$ the dual space to the Sobolev spaces $W_0^{1,q'}(\Omega)$, where

$$\frac{1}{q} + \frac{1}{q'} = 1,$$

with the standard norm

$$\|u\|_{W^{-1,q}(\Omega)} := \sup_{\phi \in C_0^\infty(\Omega), \|\phi\|_{W_0^{1,q'}} \leq 1} \left| \int_{\Omega} u\phi \, dx \right|. \tag{2.1}$$

The symbol $L_0^q(\Omega)$ denotes the space of functions in $L^q(\Omega)$ with zero integral mean:

$$L_0^q(\Omega) := \left\{ f \in L^q(\Omega) : \int_{\Omega} f \, dx = 0 \right\}. \tag{2.2}$$

2.1. Perforated domain

Consider a bounded domain $\Omega \subset R^3$ of class C^2 . We introduce a family of *perforated domains* $\{\Omega_\varepsilon\}_{\varepsilon>0}$,

$$\Omega_\varepsilon = \Omega \setminus \bigcup_{n=1}^{N(\varepsilon)} T_{\varepsilon,n}, \tag{2.3}$$

where the sets $T_{\varepsilon,n}$ represent *holes* or *obstacles*. We suppose the following property concerning the distribution of the holes:

$$T_{\varepsilon,n} = x_{\varepsilon,n} + \varepsilon^\alpha T_n \subset B(x_{\varepsilon,n}, \delta_0 \varepsilon^\alpha) \subset B(x_{\varepsilon,n}, \delta_1 \varepsilon) \subset B(x_{\varepsilon,n}, \delta_2 \varepsilon) \subset \Omega, \tag{2.4}$$

where for each n , $T_n \subset R^3$ is a simply connected bounded domain of class C^2 and is independent of ε , $B(x, r)$ denotes the open ball centered at x with radius r in R^3 , $\delta_0, \delta_1, \delta_2$ are positive constants independent of ε and there holds $\delta_1 < \delta_2$. Moreover, we suppose balls (control volumes) in $\{B(x_{\varepsilon,n}, \delta_2 \varepsilon)\}_{n \in \mathbb{N}}$ are pairwise disjoint.

Compared to the assumption on the distribution of holes in [9], here we do not assume the periodicity of the distribution, and we do not assume the uniform shape of the holes.

The diameter of each $T_{\varepsilon,n}$ is of order $O(\varepsilon^\alpha)$ and their mutual distance is $O(\varepsilon)$, while their total number $N(\varepsilon)$ can be estimated as

$$N_\varepsilon \leq \frac{3}{4\pi} \frac{|\Omega|}{\varepsilon^3}.$$

2.2. Stationary Navier–Stokes equations

For the fluid density $\varrho = \varrho(x)$ and the velocity field $\mathbf{u} = \mathbf{u}(x)$, we consider the stationary (compressible) *Navier–Stokes system*

$$\operatorname{div}(\varrho \mathbf{u}) = 0, \tag{2.5}$$

$$\operatorname{div}(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla p(\varrho) = \operatorname{div} \mathbb{S}(\nabla \mathbf{u}) + \varrho \mathbf{f} + \mathbf{g}, \tag{2.6}$$

$$\mathbb{S}(\nabla \mathbf{u}) = \mu \left(\nabla \mathbf{u} + \nabla^t \mathbf{u} - \frac{2}{3}(\operatorname{div} \mathbf{u})\mathbb{I} \right) + \eta(\operatorname{div} \mathbf{u})\mathbb{I}, \quad \mu > 0, \quad \eta \geq 0, \tag{2.7}$$

in the spatial domain Ω_ε , supplemented with the standard no-slip boundary condition

$$\mathbf{u} = 0 \quad \text{on } \partial\Omega_\varepsilon. \tag{2.8}$$

The symbol $\mathbb{S}(\nabla \mathbf{u})$ stands for the Newtonian viscous stress tensor with constant viscosity coefficients μ, η . For the sake of simplicity, we focus on the *isentropic* pressure-density state equation

$$p(\varrho) = a\varrho^\gamma, \quad a > 0, \tag{2.9}$$

with the adiabatic exponent γ , the value of which will be specified below.

The motion is driven by the volume force \mathbf{f} and nonvolume force \mathbf{g} , defined on the whole domain Ω and independent of ε , that are supposed, again for the sake of simplicity, to be uniformly bounded,

$$\|\mathbf{f}\|_{L^\infty(\Omega;R^3)} + \|\mathbf{g}\|_{L^\infty(\Omega;R^3)} \leq C < \infty. \tag{2.10}$$

Here and hereafter, the symbol C is used to denote a generic constant that may vary from line to line but it is independent of the parameters of the problem, in particular of ε .

Finally, in agreement with its physical interpretation, the density ϱ is non-negative and we fix the total mass of the fluid to be

$$M = \int_{\Omega_\varepsilon} \varrho \, dx > 0. \tag{2.11}$$

For physical background to these equations and conditions, we refer to Sections 1.2.3, 1.2.4, and 1.2.6 in [19].

2.3. Weak solutions

We recall the definition of finite energy weak solutions to (2.5)–(2.8), see e.g. ([19], Def. 4.1).

Definition 2.1. A couple of functions $[\varrho, \mathbf{u}]$ is said to be a *finite energy weak solution* of the Navier–Stokes system (2.5)–(2.7) supplemented with the conditions (2.8)–(2.11) in Ω_ε provided:

- $\varrho \geq 0$ a.e. in Ω_ε , and

$$\int_{\Omega_\varepsilon} \varrho \, dx = M, \quad \varrho \in L^{\beta(\gamma)}(\Omega_\varepsilon) \text{ for some } \beta(\gamma) > \gamma, \quad \mathbf{u} \in W_0^{1,2}(\Omega_\varepsilon; R^3); \tag{2.12}$$

- for any test functions $\psi \in C^\infty(\overline{\Omega_\varepsilon})$ and $\varphi \in C_c^\infty(\Omega_\varepsilon; R^3)$:

$$\int_{\Omega_\varepsilon} \varrho \mathbf{u} \cdot \nabla \psi \, dx = 0, \tag{2.13}$$

$$\int_{\Omega_\varepsilon} \varrho \mathbf{u} \otimes \mathbf{u} : \nabla \varphi + p(\varrho) \operatorname{div} \varphi - \mathbb{S}(\nabla \mathbf{u}) : \nabla \varphi + (\varrho \mathbf{f} + \mathbf{g}) \cdot \varphi \, dx = 0; \tag{2.14}$$

- the *energy inequality*

$$\int_{\Omega_\varepsilon} \mathbb{S}(\nabla \mathbf{u}) : \nabla \mathbf{u} \, dx \leq \int_{\Omega_\varepsilon} (\varrho \mathbf{f} + \mathbf{g}) \cdot \mathbf{u} \, dx \tag{2.15}$$

holds.

Moreover, a finite energy weak solution $[\varrho, \mathbf{u}]$ is said to be a *renormalized weak solution* if

$$\int_{R^3} b(\varrho) \mathbf{u} \cdot \nabla_x \psi + (b(\varrho) - b'(\varrho)\varrho) \operatorname{div} \mathbf{u} \psi \, dx = 0 \tag{2.16}$$

for any $\psi \in C_c^\infty(R^3)$, where $[\varrho, \mathbf{u}]$ were extended to be zero outside Ω_ε , and any $b \in C^0([0, \infty)) \cap C^1((0, \infty))$ such that

$$b'(s) \leq c s^{-\lambda_0} \text{ for } s \in (0, 1], \quad b'(s) \leq c s^{\lambda_1} \text{ for } s \in [1, \infty), \tag{2.17}$$

with

$$c > 0, \quad \lambda_0 < 1, \quad -1 < \lambda_1 \leq \frac{\beta(\gamma)}{2} - 1. \tag{2.18}$$

Remark 2.2. By DiPerna-Lions’ transport theory (see [8], Sect. II.3) and the modification in ([19], Lem. 3.3), for any $r \in L^\beta(\Omega)$, $\beta \geq 2$, $\mathbf{v} \in W_0^{1,2}(\Omega)$, where $\Omega \subset R^3$ is a bounded domain of class C^2 , such that

$$\operatorname{div}(r\mathbf{v}) = 0 \quad \text{in } \mathcal{D}'(\Omega), \tag{2.19}$$

the renormalized equation

$$\operatorname{div}(b(r)\mathbf{v}) + (rb'(r) - b(r))\operatorname{div} \mathbf{v} = 0, \quad \text{holds in } \mathcal{D}'(R^3), \tag{2.20}$$

for any $b \in C^0([0, \infty)) \cap C^1((0, \infty))$ satisfying (2.17)–(2.18) provided r and \mathbf{v} have been extended to be zero outside Ω . We also note that the hypothesis of the smoothness of Ω can be dropped provided (2.19) is replaced by a stronger stipulation (2.13) for any $\psi \in C^\infty(\overline{\Omega})$.

From the physical point of view, the available *existence* theory of finite energy weak solutions in the sense of Definition 2.1 is still not completely satisfactory. Recall that the relevant values of the adiabatic exponent are $1 \leq \gamma \leq 5/3$, where the case $\gamma = 1$ corresponds to the isothermal case while $\gamma = 5/3$ is the adiabatic exponent of the monoatomic gas. Lions [16] proves the existence of weak solutions in the range $\gamma > 5/3$. His proof is based on energy type arguments combined with the refined pressure estimates adopted also in the present paper. Lions’ theory has been extended to the physical range $\gamma \leq 5/3$ by several authors, see Březina and Novotný [6], Plotnikov and Sokolowski [20] for the case $\gamma > 3/2$, Frehse *et al.* [14] for $\gamma > 4/3$. The best result available has been obtained by Plotnikov and Weigant in [21] for $\gamma > 1$. All the results attacking the physical range $\gamma \leq 5/3$ use delicate estimates that are not directly applicable to the case of perforated domains as they may fail to be uniform with respect to $\varepsilon \rightarrow 0$.

2.4. Main results

Our principal result concerns the construction of the inverse of the divergence operator on the family of perforated domains $\{\Omega_\varepsilon\}_{\varepsilon>0}$.

2.4.1. Inverse of divergence

Theorem 2.3. *Let $\{\Omega_\varepsilon\}_{\varepsilon>0}$ be a family of domains enjoying the properties specified in Section 2.1. Then there exists a linear operator*

$$\mathcal{B}_\varepsilon : L_0^q(\Omega_\varepsilon) \rightarrow W_0^{1,q}(\Omega_\varepsilon; R^3), \quad 1 < q < \infty,$$

such that for any $f \in L_0^q(\Omega_\varepsilon)$,

$$\begin{aligned} \operatorname{div} \mathcal{B}_\varepsilon(f) &= f \quad \text{in } \Omega_\varepsilon, \\ \|\mathcal{B}_\varepsilon(f)\|_{W_0^{1,q}(\Omega_\varepsilon; R^3)} &\leq C \left(1 + \varepsilon^{\frac{(3-q)\alpha-3}{q}}\right) \|f\|_{L^q(\Omega_\varepsilon)}, \end{aligned} \tag{2.21}$$

for some constant C independent of ε .

The existence of such an operator on a *fixed* Lipschitz domain has been established by several authors, notably by Bogovskii [5]. Our contribution is therefore the explicit dependence of the estimate (2.21) on ε . In particular, we recover a uniform bound as soon as $(3 - q)\alpha - 3 \geq 0$. Note that the domains in the family $\{\Omega_\varepsilon\}_{\varepsilon>0}$ are *not* uniformly Lipschitz domains or uniform John domains, for which such a result would follow from Bogovskii [5] and Galdi [15] or Acosta *et al.* [1] and Diening *et al.* [7]. We also note that Theorem 2.3 is optimal with respect to the value of q since functions in the Sobolev spaces $W^{1,q}$ with $q > 3$ are continuous and a uniform bound in (2.21) is not expected if the holes become asymptotically dense and small in Ω .

The proof of Theorem 2.3 is given in Section 3.

2.4.2. Asymptotic limit of compressible fluid flows in perforated domains

As a corollary of Theorem 2.3, we show that the asymptotic limit of solutions $[\varrho_\varepsilon, \mathbf{u}_\varepsilon]$ of the compressible Navier–Stokes system (2.5)–(2.8), (2.11) in Ω_ε coincides with a solution of the same system on the homogeneous domain Ω .

Theorem 2.4. *Suppose conditions (2.9), (2.10) and (2.11) are satisfied. Suppose $2 < \gamma \leq 3$ and $\alpha > 3$ be given such that*

$$\alpha \frac{\gamma - 2}{2\gamma - 3} > 1. \tag{2.22}$$

Let $[\varrho_\varepsilon, \mathbf{u}_\varepsilon]_{0 < \varepsilon < 1}$ be a family of finite energy weak solutions to (2.5)–(2.8) in Ω_ε . Then we have uniform estimates

$$\sup_{0 < \varepsilon < 1} \left(\|\varrho_\varepsilon\|_{L^{\beta(\gamma)}(\Omega_\varepsilon)} + \|\mathbf{u}_\varepsilon\|_{W_0^{1,2}(\Omega_\varepsilon; \mathbb{R}^3)} \right) \leq C < \infty, \quad \beta(\gamma) := 3(\gamma - 1). \tag{2.23}$$

Moreover, extending $[\varrho_\varepsilon, \mathbf{u}_\varepsilon]$ to be zero outside Ω_ε , we get, up to a substruction of subsequence,

$$\varrho_\varepsilon \rightharpoonup \varrho \text{ weakly in } L^{\beta(\gamma)}(\Omega), \quad \mathbf{u}_\varepsilon \rightharpoonup \mathbf{u} \text{ weakly in } W_0^{1,2}(\Omega; \mathbb{R}^3), \tag{2.24}$$

where $[\varrho, \mathbf{u}]$ is a finite energy weak solution to the same system of equations (2.5)–(2.8) in Ω .

The proof of Theorem 2.4 is given in Section 4.

We give a remark concerning the similar result in two dimensional setting:

Remark 2.5. The argument in this paper cannot be directly extended to 2D setting. In particular, the construction of Bogovskii type operator in Section 3 and the choice of g_ε in (4.15) in the proof of Lemma 4.2 do not apply to domains in \mathbb{R}^2 . However, similar result still may hold in 2D setting. Since in 2D setting, the density enjoys better integrability (in $L^{2\gamma}$ as long as $\gamma > 1$) such that the pressure is in L^2 . This allows us to apply the restriction operator constructed by Allaire [3, 4] to construct some uniformly bounded Bogovskii type operators, just as in the previous paper [9]. We employ again Allaire construction to find a function sequence that vanishes on the holes and converges to 1 in some proper sense (w_k^ε and q_k^ε in Hypotheses H(1)–H(6) in Sect. 3.2). So combining the techniques in this paper and in the previous paper [9] should imply similar results in 2D setting. Of course, the holes must be much “smaller” – they have larger capacity in two dimensional spaces. Our interest here is to handle *better* γ in 3D setting.

We finally remark that, in this paper, the obstacles are assumed to be isolated in 3D domain. More realistic situation with connected boundaries may be treated in a similar manner for which the incompressible Stokes equations is considered in [2]. However, such an extension is far from being trivial and a considerable number of new difficulties would have to be overcome.

3. CONSTRUCTION OF THE INVERSE OF THE DIVERGENCE OPERATOR IN PERFORATED DOMAINS

This section is devoted to the proof of Theorem 2.3. For $f \in L^q(\Omega_\varepsilon)$ with $\int_{\Omega_\varepsilon} f \, dx = 0$, we consider the extension $\tilde{f} =: E(f)$ defined as

$$\tilde{f} = f \text{ in } \Omega_\varepsilon, \quad \tilde{f} = 0 \text{ on } \Omega \setminus \Omega_\varepsilon = \bigcup_{n=1}^{N(\varepsilon)} T_{\varepsilon,n}. \tag{3.1}$$

Clearly $\tilde{f} \in L_0^q(\Omega)$. Employing the standard Bogovskii’s construction (see [15], Chap. 3) on the domain Ω we find $\mathbf{u} = \mathcal{B}_\Omega(\tilde{f}) \in W_0^{1,q}(\Omega; \mathbb{R}^3)$ such that

$$\operatorname{div} \mathbf{u} = \tilde{f} \text{ in } \Omega \quad \text{and} \quad \|\mathbf{u}\|_{W_0^{1,q}(\Omega; \mathbb{R}^3)} \leq C \|\tilde{f}\|_{L^q(\Omega)} = C \|f\|_{L^q(\Omega_\varepsilon)} \tag{3.2}$$

for some constant C depending only on Ω and q .

In accordance with hypotheses (2.4), we introduce two cut-off functions $\chi_{\varepsilon,n}$ and $\phi_{\varepsilon,n}$ such that

$$\chi_{\varepsilon,n} \in C_c^\infty(B(x_{\varepsilon,n}, \delta_2\varepsilon)), \chi_{\varepsilon,n}|_{\overline{B(x_{\varepsilon,n}, \delta_1\varepsilon)}} = 1, \|\nabla\chi_{\varepsilon,n}\|_{L^\infty(\mathbb{R}^3;\mathbb{R}^3)} \leq C\varepsilon^{-1}, \tag{3.3}$$

$$\phi_{\varepsilon,n} \in C_c^\infty(B(x_{\varepsilon,n}, \delta_0\varepsilon^\alpha)), \phi_{\varepsilon,n}|_{T_{\varepsilon,n}} = 1, \|\nabla\phi_{\varepsilon,n}\|_{L^\infty(\mathbb{R}^3;\mathbb{R}^3)} \leq C\varepsilon^{-\alpha}. \tag{3.4}$$

Denote

$$D_{\varepsilon,n} = B(x_{\varepsilon,n}, \delta_2\varepsilon) \setminus \overline{B(x_{\varepsilon,n}, \delta_1\varepsilon)}, E_{\varepsilon,n} = B(x_{\varepsilon,n}, \delta_2\varepsilon) \setminus T_{\varepsilon,n}, F_{\varepsilon,n} = B(x_{\varepsilon,n}, \delta_0\varepsilon^\alpha) \setminus T_{\varepsilon,n}.$$

Denoting

$$\langle v \rangle_B = \frac{1}{|B|} \int_B v \, dx,$$

we introduce

$$\begin{aligned} \mathbf{b}_{\varepsilon,n}(\mathbf{u}) &= \chi_{\varepsilon,n} \left(\mathbf{u} - \langle \mathbf{u} \rangle_{D_{\varepsilon,n}} \right) \in W_0^{1,q}(B(x_{\varepsilon,n}, \delta_2\varepsilon); \mathbb{R}^3), \\ \beta_{\varepsilon,n}(\mathbf{u}) &= \phi_{\varepsilon,n} \langle \mathbf{u} \rangle_{D_{\varepsilon,n}} \in W_0^{1,q}(B(x_{\varepsilon,n}, \delta_0\varepsilon^\alpha); \mathbb{R}^3). \end{aligned} \tag{3.5}$$

Revoking Poincaré’s inequality

$$\left\| \mathbf{u} - \langle \mathbf{u} \rangle_{D_{\varepsilon,n}} \right\|_{L^q(D_{\varepsilon,n}; \mathbb{R}^3)} \leq C\varepsilon \|\nabla \mathbf{u}\|_{L^q(D_{\varepsilon,n}; \mathbb{R}^9)}$$

and (3.3), we estimate

$$\begin{aligned} \|\nabla \mathbf{b}_{\varepsilon,n}(\mathbf{u})\|_{L^q(D_{\varepsilon,n}; \mathbb{R}^9)} &\leq \left\| \chi_{\varepsilon,n} \nabla \left(\mathbf{u} - \langle \mathbf{u} \rangle_{D_{\varepsilon,n}} \right) \right\|_{L^q(D_{\varepsilon,n}; \mathbb{R}^9)} + \left\| \nabla \chi_{\varepsilon,n} \otimes \left(\mathbf{u} - \langle \mathbf{u} \rangle_{D_{\varepsilon,n}} \right) \right\|_{L^q(D_{\varepsilon,n}; \mathbb{R}^9)} \\ &\leq C \left(\|\nabla \mathbf{u}\|_{L^q(D_{\varepsilon,n}; \mathbb{R}^3)} + \varepsilon^{-1} \left\| \mathbf{u} - \langle \mathbf{u} \rangle_{D_{\varepsilon,n}} \right\|_{L^q(D_{\varepsilon,n})} \right) \leq C \|\nabla \mathbf{u}\|_{L^q(D_{\varepsilon,n}; \mathbb{R}^3)}. \end{aligned} \tag{3.6}$$

Similarly, by virtue of (3.4) and Jensen’s inequality,

$$\begin{aligned} \|\nabla \beta_{\varepsilon,n}(\mathbf{u})\|_{L^q(B(x_{\varepsilon,n}, \delta_0\varepsilon^\alpha); \mathbb{R}^9)} &= \left\| \nabla \phi_{\varepsilon,n} \cdot \langle \mathbf{u} \rangle_{D_{\varepsilon,n}} \right\|_{L^q(B(x_{\varepsilon,n}, \delta_0\varepsilon^\alpha))} \\ &\leq C\varepsilon^{\left(\frac{3}{q}-1\right)\alpha} \left| \langle \mathbf{u} \rangle_{D_{\varepsilon,n}} \right| \leq C\varepsilon^{\left(\frac{3}{q}-1\right)\alpha - \frac{3}{q}} \|\mathbf{u}\|_{L^q(D_{\varepsilon,n}; \mathbb{R}^3)}. \end{aligned} \tag{3.7}$$

Next, we claim the following result.

Lemma 3.1. *For any $1 < q < \infty$, there exist a linear operator $\mathcal{B}_{E_{\varepsilon,n}} : L_0^q(E_{\varepsilon,n}) \rightarrow W_0^{1,q}(E_{\varepsilon,n}; \mathbb{R}^3)$ and a linear operator $\mathcal{B}_{F_{\varepsilon,n}} : L_0^q(F_{\varepsilon,n}) \rightarrow W_0^{1,q}(F_{\varepsilon,n}; \mathbb{R}^3)$ such that for any $f_1 \in L_0^q(E_{\varepsilon,n})$ and any $f_2 \in L_0^q(F_{\varepsilon,n})$, there holds*

$$\begin{aligned} \operatorname{div} \mathcal{B}_{E_{\varepsilon,n}}(f_1) &= f_1, \quad \|\mathcal{B}_{E_{\varepsilon,n}}(f_1)\|_{W_0^{1,q}(E_{\varepsilon,n}; \mathbb{R}^3)} \leq C \|f_1\|_{L^q(E_{\varepsilon,n})}, \\ \operatorname{div} \mathcal{B}_{F_{\varepsilon,n}}(f_2) &= f_2, \quad \|\mathcal{B}_{F_{\varepsilon,n}}(f_2)\|_{W_0^{1,q}(F_{\varepsilon,n}; \mathbb{R}^3)} \leq C \|f_2\|_{L^q(F_{\varepsilon,n})}, \end{aligned}$$

for some constant C independent of ε and n .

There are several ways how to construct the operators $\mathcal{B}_{E_{\varepsilon,n}}, \mathcal{B}_{F_{\varepsilon,n}}$. We can use the construction of Galdi ([15], Chap. 3) that mimics the original Bogovskii’s proof. Note that this procedure yields indeed the operators with the corresponding norm independent of ε and n , see Galdi ([15], Chap. 3). Alternatively, we observe that both $E_{\varepsilon,n}$ and $F_{\varepsilon,n}$ are uniform families of John domains, whence the desired construction can be found in [1] and [7]. In the case $1 < q < 3$, Lemma 3.1 can be also shown by modifying the arguments of Allaire ([3], Lem. 2.2.4).

We now define a restriction type operator in the following way:

$$R_\varepsilon(\mathbf{u}) := \mathbf{u} - \sum_{n=1}^{N(\varepsilon)} (\mathbf{b}_{\varepsilon,n}(\mathbf{u}) - \mathcal{B}_{E_{\varepsilon,n}}(\operatorname{div} \mathbf{b}_{\varepsilon,n}(\mathbf{u}))) - \sum_{n=1}^{N(\varepsilon)} (\boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u}) - \mathcal{B}_{F_{\varepsilon,n}}(\operatorname{div} \boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u}))), \quad (3.8)$$

where $\mathcal{B}_{E_{\varepsilon,n}}(\operatorname{div} \mathbf{b}_{\varepsilon,n}(\mathbf{u}))$ and $\mathcal{B}_{F_{\varepsilon,n}}(\operatorname{div} \boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u}))$ were extended to be zero outside $E_{\varepsilon,n}$ and $F_{\varepsilon,n}$, respectively. We say such an operator is of restriction type in the sprit of Tartar [23] and Allaire [3, 4], because, as we will see in the sequel argument, R_ε is a well defined linear operator from $W_0^{1,p}(\Omega; R^3)$ to $W_0^{1,p}(\Omega_\varepsilon; R^3)$.

We first check that $R_\varepsilon(\mathbf{u})$ is well defined, specifically that

$$\int_{E_{\varepsilon,n}} \operatorname{div} \mathbf{b}_{\varepsilon,n}(\mathbf{u}) \, dx = 0, \quad \int_{F_{\varepsilon,n}} \operatorname{div} \boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u}) \, dx = 0. \quad (3.9)$$

Indeed, on one hand, by (3.3) and (3.5), we have

$$\int_{B(x_{\varepsilon,n}, \delta_{2\varepsilon})} \operatorname{div} \mathbf{b}_{\varepsilon,n}(\mathbf{u}) \, dx = 0, \quad \int_{B(x_{\varepsilon,n}, \delta_0 \varepsilon^\alpha)} \operatorname{div} \boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u}) \, dx = 0. \quad (3.10)$$

On the other hand, by (3.2), (3.3) and (3.4), in particular, $\operatorname{div} \mathbf{u} = 0$ on $T_{\varepsilon,n}$, we have

$$\begin{aligned} \operatorname{div} \mathbf{b}_{\varepsilon,n}(\mathbf{u}) &= \chi_{\varepsilon,n} \operatorname{div} \mathbf{u} + \nabla \chi_{\varepsilon,n} \cdot (\mathbf{u} - \langle \mathbf{u} \rangle_{D_{\varepsilon,n}}) = 0, & \text{on } T_{\varepsilon,n}, \\ \operatorname{div} \boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u}) &= \nabla \phi_{\varepsilon,n} \cdot \langle \mathbf{u} \rangle_{D_{\varepsilon,n}} = 0, & \text{on } T_{\varepsilon,n}; \end{aligned} \quad (3.11)$$

whence (3.9) follows from (3.10) and (3.11).

By the definition of $R_\varepsilon(\mathbf{u})$ in (3.8) and the property of $\mathbf{u} = \mathcal{B}_\Omega(\tilde{f})$ claimed in (3.2), we have

$$R_\varepsilon(\mathbf{u}) \in W_0^{1,q}(\Omega; R^3), \quad \operatorname{div} R_\varepsilon(\mathbf{u}) = \operatorname{div} \mathbf{u} = \tilde{f} \quad \text{in } \Omega. \quad (3.12)$$

Finally, we define the Bogovskii type operator \mathcal{B}_ε through the composition of the extension operator, the classical Bogovskii operator, and the restriction operator defined above in (3.8):

$$\mathcal{B}_\varepsilon(f) := R_\varepsilon(\mathbf{u}) = R_\varepsilon(\mathcal{B}_\Omega(\tilde{f})) = R_\varepsilon \circ \mathcal{B}_\Omega \circ E(f). \quad (3.13)$$

Our ultimate goal is to show that \mathcal{B}_ε enjoys all the properties claimed in Theorem 2.3.

For any $x \in T_{\varepsilon,n}$, $1 \leq n \leq N(\varepsilon)$, we have

$$\begin{aligned} R_\varepsilon(\mathbf{u})(x) &= \mathbf{u}(x) - \left(\mathbf{b}_{\varepsilon,n}(\mathbf{u}) - \mathcal{B}_{E_{\varepsilon,n}}(\operatorname{div} \mathbf{b}_{\varepsilon,n}(\mathbf{u})) \right)(x) - \left(\boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u}) - \mathcal{B}_{F_{\varepsilon,n}}(\operatorname{div} \boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u})) \right)(x) \\ &= \mathbf{u}(x) - \mathbf{b}_{\varepsilon,n}(\mathbf{u})(x) - \boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u})(x) \\ &= \mathbf{u}(x) - \chi_{\varepsilon,n}(x) (\mathbf{u}(x) - \langle \mathbf{u} \rangle_{D_{\varepsilon,n}}) - \phi_{\varepsilon,n}(x) \langle \mathbf{u} \rangle_{D_{\varepsilon,n}} \\ &= 0, \end{aligned} \quad (3.14)$$

where we used the fact that

$$\chi_{\varepsilon,n}(x) = \phi_{\varepsilon,n}(x) = 1, \quad \text{for any } x \in T_{\varepsilon,n}.$$

Thus, we have shown the desired relations

$$R_\varepsilon(\mathbf{u}) \in W_0^{1,q}(\Omega_\varepsilon; R^3), \quad \operatorname{div} R_\varepsilon(\mathbf{u}) = f \quad \text{in } \Omega_\varepsilon. \quad (3.15)$$

To finish the proof of Theorem 2.3, it remains to show the bound

$$\|R_\varepsilon(\mathbf{u})\|_{W_0^{1,q}(\Omega_\varepsilon; R^3)} \leq C \left(1 + \varepsilon^{\frac{(3-q)\alpha-3}{q}} \right) \|f\|_{L^q(\Omega_\varepsilon)}. \quad (3.16)$$

By (3.6), (3.7) and Lemma 3.1, we have

$$\begin{aligned} \mathbf{b}_{\varepsilon,n}(\mathbf{u}) - \mathcal{B}_{E_{\varepsilon,n}}(\operatorname{div} \mathbf{b}_{\varepsilon,n}(\mathbf{u})) &\in W_0^{1,q}(B(x_{\varepsilon,n}, \delta_2\varepsilon); R^3), \\ \|\mathbf{b}_{\varepsilon,n}(\mathbf{u}) - \mathcal{B}_{E_{\varepsilon,n}}(\operatorname{div} \mathbf{b}_{\varepsilon,n}(\mathbf{u}))\|_{W_0^{1,q}(B(x_{\varepsilon,n}, \delta_2\varepsilon); R^3)} &\leq C \|\nabla \mathbf{u}\|_{L^q(B(x_{\varepsilon,n}, \delta_2\varepsilon); R^9)}, \end{aligned} \tag{3.17}$$

and

$$\begin{aligned} \boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u}) - \mathcal{B}_{F_{\varepsilon,n}}(\operatorname{div} \boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u})) &\in W_0^{1,q}(B(x_{\varepsilon,n}, \delta_0\varepsilon^\alpha); R^3), \\ \|\boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u}) - \mathcal{B}_{F_{\varepsilon,n}}(\operatorname{div} \boldsymbol{\beta}_{\varepsilon,n}(\mathbf{u}))\|_{W_0^{1,q}(B(x_{\varepsilon,n}, \delta_0\varepsilon^\alpha); R^3)} &\leq C \varepsilon^{\frac{(3-q)\alpha-3}{q}} \|\mathbf{u}\|_{L^q(B(x_{\varepsilon,n}, \delta_0\varepsilon^\alpha); R^3)}. \end{aligned} \tag{3.18}$$

Finally, by (3.2), (3.8) and the fact

$$B(x_{\varepsilon,n_1}, \delta_2\varepsilon) \cap B(x_{\varepsilon,n_2}, \delta_2\varepsilon) = \emptyset, \quad \text{whenever } n_1 \neq n_2,$$

a direct calculation implies the estimate (3.16). We have completed the proof of Theorem 2.3.

4. ASYMPTOTIC ANALYSIS OF THE COMPRESSIBLE FLUID FLOW ON A FAMILY OF PERFORATED DOMAINS

This section is devoted to the proof of Theorem 2.4. For any $0 < \varepsilon < 1$, let $[\varrho_\varepsilon, \mathbf{u}_\varepsilon]$ be a finite energy weak solution satisfying the hypotheses of Theorem 2.4. By the known results concerning integrability of weak solutions to the stationary Navier–Stokes system, we have, see *e.g.* Novotný and Straškraba ([19], Chap. 4):

$$\varrho_\varepsilon \in L^{\beta(\gamma)}(\Omega_\varepsilon), \quad \beta(\gamma) = 3(\gamma - 1); \quad \mathbf{u}_\varepsilon \in W_0^{1,2}(\Omega_\varepsilon; R^3). \tag{4.1}$$

As we assume $2 < \gamma \leq 3$, we have $\beta(\gamma) = 3(\gamma - 1) > 3$; whence, by Remark 2.2, the solution $[\varrho_\varepsilon, \mathbf{u}_\varepsilon]$ is also a renormalized weak solution:

Lemma 4.1. *We have*

$$\operatorname{div} (b(\tilde{\varrho}_\varepsilon)\tilde{\mathbf{u}}_\varepsilon) + (\tilde{\varrho}_\varepsilon b'(\tilde{\varrho}_\varepsilon) - b(\tilde{\varrho}_\varepsilon)) \operatorname{div} \tilde{\mathbf{u}}_\varepsilon = 0, \quad \text{in } \mathcal{D}'(R^3), \tag{4.2}$$

for any $b \in C^0([0, \infty)) \cap C^1((0, \infty))$ satisfying (2.17) and (2.18), where $[\tilde{\varrho}_\varepsilon, \tilde{\mathbf{u}}_\varepsilon]$ denotes the functions $[\varrho, \mathbf{u}]$ extended to be zero outside Ω_ε .

4.1. Uniform estimates

We have the solution $[\varrho_\varepsilon, \mathbf{u}_\varepsilon]$ is in the function spaces shown in (4.1), but the classical estimates of their norms depend on the domain Ω_ε , in particular on the Lipschitz character of Ω_ε which is unbounded as $\varepsilon \rightarrow 0$. To show the uniform estimates (2.23), we need to employ the uniform Bogovskii type operator \mathcal{B}_ε obtained in Theorem 2.3 and constructed in Section 3.

By using the Korn’s inequality and Hölder’s inequality, the energy inequality (2.15) implies

$$\begin{aligned} \|\nabla \mathbf{u}_\varepsilon\|_{L^2(\Omega_\varepsilon; R^9)}^2 &\leq C \left(\|\mathbf{f}\|_{L^\infty(\Omega; R^3)} \|\varrho_\varepsilon\|_{L^{\frac{6}{5}}(\Omega_\varepsilon)} \|\mathbf{u}_\varepsilon\|_{L^6(\Omega_\varepsilon; R^3)} \right. \\ &\quad \left. + \|\mathbf{g}\|_{L^\infty(\Omega; R^3)} \|\mathbf{u}_\varepsilon\|_{L^1(\Omega_\varepsilon; R^3)} \right). \end{aligned} \tag{4.3}$$

Since $\mathbf{u}_\varepsilon \in W_0^{1,2}(\Omega_\varepsilon; R^3)$ has zero trace on the boundary, the Sobolev embedding inequality implies

$$\|\mathbf{u}_\varepsilon\|_{L^6(\Omega_\varepsilon; R^3)} \leq C \|\nabla \mathbf{u}_\varepsilon\|_{L^2(\Omega_\varepsilon; R^9)}, \tag{4.4}$$

for some constant C independent of the domain Ω_ε .

By the above two estimates in (4.3) and (4.4), we deduce

$$\begin{aligned} \|\nabla \mathbf{u}_\varepsilon\|_{L^2(\Omega_\varepsilon; \mathbb{R}^9)} + \|\mathbf{u}_\varepsilon\|_{L^6(\Omega_\varepsilon; \mathbb{R}^3)} &\leq C \left(\|\mathbf{f}\|_{L^\infty(\Omega_\varepsilon; \mathbb{R}^3)} \|\varrho_\varepsilon\|_{L^{\frac{6}{5}}(\Omega_\varepsilon)} + \|\mathbf{g}\|_{L^\infty(\Omega_\varepsilon; \mathbb{R}^3)} \right) \\ &\leq C \left(\|\varrho_\varepsilon\|_{L^{\frac{6}{5}}(\Omega_\varepsilon)} + 1 \right). \end{aligned} \quad (4.5)$$

Let \mathcal{B}_ε is the operator introduced in Theorem 2.3, we define the test function

$$\varphi := \mathcal{B}_\varepsilon \left(\varrho_\varepsilon^{2\gamma-3} - \frac{1}{|\Omega_\varepsilon|} \int_{\Omega_\varepsilon} \varrho_\varepsilon^{2\gamma-3} dx \right). \quad (4.6)$$

By (4.1) and $2 < \gamma \leq 3$, we have

$$\varrho_\varepsilon^{2\gamma-3} \in L^{\frac{3\gamma-3}{2\gamma-3}}(\Omega_\varepsilon), \quad 2 \leq \frac{3\gamma-3}{2\gamma-3} < 3. \quad (4.7)$$

Then by Theorem 2.3, we have

$$\begin{aligned} \operatorname{div} \varphi &= \varrho_\varepsilon^{2\gamma-3} - \frac{1}{|\Omega_\varepsilon|} \int_{\Omega_\varepsilon} \varrho_\varepsilon^{2\gamma-3} dx \quad \text{in } \Omega_\varepsilon, \\ \|\varphi\|_{W_0^{1, \frac{3\gamma-3}{2\gamma-3}}(\Omega_\varepsilon; \mathbb{R}^3)} &\leq C(1 + \varepsilon^{\sigma_1}) \left(\|\varrho_\varepsilon^{2\gamma-3}\|_{L^{\frac{3\gamma-3}{2\gamma-3}}(\Omega_\varepsilon)} + \|\varrho_\varepsilon^{2\gamma-3}\|_{L^1(\Omega_\varepsilon)} \right) \\ &\leq C \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{2\gamma-3}, \end{aligned} \quad (4.8)$$

where

$$\sigma_1 := \frac{\left(3 - \frac{3\gamma-3}{2\gamma-3}\right) \alpha - 3}{\frac{3\gamma-3}{2\gamma-3}} = \frac{2\gamma-3}{\gamma-1} \left(\frac{\gamma-2}{2\gamma-3} \cdot \alpha - 1 \right) > 0,$$

for which the positivity is guaranteed by condition (2.22).

Taking φ as a test function in the weak formulation of the momentum equation (2.14) gives

$$\int_{\Omega_\varepsilon} p(\varrho_\varepsilon) \varrho_\varepsilon^{2\gamma-3} dx = \sum_{j=1}^4 I_j \quad (4.9)$$

with

$$\begin{aligned} I_1 &:= \int_{\Omega_\varepsilon} p(\varrho_\varepsilon) dx - \frac{1}{|\Omega_\varepsilon|} \int_{\Omega_\varepsilon} \varrho_\varepsilon^{2\gamma-3} dx, \\ I_2 &:= \int_{\Omega_\varepsilon} \mu \nabla \mathbf{u}_\varepsilon : \nabla \varphi dx + \int_{\Omega_\varepsilon} \left(\frac{\mu}{3} + \eta \right) \operatorname{div} \mathbf{u}_\varepsilon \operatorname{div} \varphi dx, \\ I_3 &:= - \int_{\Omega_\varepsilon} \varrho_\varepsilon \mathbf{u}_\varepsilon \otimes \mathbf{u}_\varepsilon : \nabla \varphi dx, \\ I_4 &:= - \int_{\Omega_\varepsilon} (\varrho_\varepsilon \mathbf{f} + \mathbf{g}) \cdot \varphi dx. \end{aligned}$$

For I_1 :

$$\begin{aligned} I_1 &:= \int_{\Omega_\varepsilon} p(\varrho_\varepsilon) dx - \frac{1}{|\Omega_\varepsilon|} \int_{\Omega_\varepsilon} \varrho_\varepsilon^{2\gamma-3} dx \leq C \|\varrho_\varepsilon\|_{L^\gamma(\Omega_\varepsilon)}^\gamma \|\varrho_\varepsilon\|_{L^{2\gamma-3}(\Omega_\varepsilon)}^{2\gamma-3} \\ &\leq C \left(\|\varrho_\varepsilon\|_{L^1(\Omega_\varepsilon)}^{(1-\theta_1)\gamma} \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{\theta_1\gamma} \right) \left(\|\varrho_\varepsilon\|_{L^1(\Omega_\varepsilon)}^{(1-\theta_2)(2\gamma-3)} \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{\theta_2(2\gamma-3)} \right) \\ &\leq C M^{(1-\theta_1)\gamma + (1-\theta_2)(2\gamma-3)} \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{\theta_1\gamma + \theta_2(2\gamma-3)} \\ &\leq C \left(1 + \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{\max\{\theta_1, \theta_2\}(3\gamma-3)} \right), \end{aligned}$$

where we used (2.11), Young’s inequality, and interpolations between Lebesgue spaces:

$$0 < \theta_1, \theta_2 < 1 \quad \text{s.t.} \quad \frac{1}{\gamma} = (1 - \theta_1) + \frac{\theta_1}{3\gamma - 3}, \quad \frac{1}{2\gamma - 3} = (1 - \theta_2) + \frac{\theta_2}{3\gamma - 3}.$$

For I_2 :

$$\begin{aligned} I_2 &\leq C \|\nabla \mathbf{u}_\varepsilon\|_{L^2(\Omega_\varepsilon; R^9)} \|\nabla \varphi\|_{L^2(\Omega_\varepsilon; R^9)} \leq C \left(\|\varrho_\varepsilon\|_{L^{\frac{6}{5}}(\Omega_\varepsilon)} + 1 \right) \|\nabla \varphi\|_{L^{\frac{3\gamma-3}{2\gamma-3}}(\Omega_\varepsilon; R^9)} \\ &\leq C \left(\|\varrho_\varepsilon\|_{L^{\frac{6}{5}}(\Omega_\varepsilon)} + 1 \right) \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{2\gamma-3} \\ &\leq C \left(M^{(1-\theta_3)} \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{\theta_3} + 1 \right) \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{2\gamma-3} \\ &\leq C \left(1 + \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{2\gamma-2} \right), \end{aligned}$$

where we used (4.5), (4.7) and (4.8). The number $0 < \theta_3 < 1$ is determined by

$$\frac{5}{6} = (1 - \theta_3) + \frac{\theta_3}{3\gamma - 3}.$$

For I_3 :

$$\begin{aligned} I_3 &\leq C \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)} \|\mathbf{u}_\varepsilon\|_{L^6(\Omega_\varepsilon; R^3)}^2 \|\nabla \varphi\|_{L^{\frac{3\gamma-3}{2\gamma-3}}(\Omega_\varepsilon; R^9)} \\ &\leq C \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)} \left(1 + \|\varrho_\varepsilon\|_{L^{6/5}(\Omega_\varepsilon)}^2 \right) \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{2\gamma-3} \\ &\leq C \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{2\gamma-2} \left(1 + \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{2\theta_4} \right) \\ &\leq C \left(1 + \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{(3\gamma-3)-(\gamma-1-2\theta_4)} \right), \end{aligned}$$

where

$$0 < \theta_4 < 1 \quad \text{s.t.} \quad \frac{5}{6} = (1 - \theta_4) + \frac{\theta_4}{3\gamma - 3}.$$

This implies

$$\theta_4 = \frac{\gamma - 1}{2(3\gamma - 4)}, \quad (\gamma - 1 - 2\theta_4) = (\gamma - 1) \frac{3\gamma - 5}{3\gamma - 4} > 0.$$

For I_4 :

$$I_4 \leq C \left(\|\varrho_\varepsilon\|_{L^2(\Omega_\varepsilon)} + 1 \right) \|\varphi\|_{L^2(\Omega_\varepsilon; R^3)} \leq C \left(1 + \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{2\gamma-2} \right).$$

Summing up the estimates in (4.9)–(4.10) implies

$$\|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{3\gamma-3} \leq C \left(1 + \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)}^{\beta_1(\gamma)} \right),$$

for some $\beta_1(\gamma) < 3\gamma - 3$. Then we deduce

$$\|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)} \leq C; \quad \text{moreover, by (4.5), } \|\mathbf{u}_\varepsilon\|_{W_0^{1,2}(\Omega_\varepsilon; R^3)} \leq C. \tag{4.10}$$

Let $[\tilde{\varrho}_\varepsilon, \tilde{\mathbf{u}}_\varepsilon]$ be the zero extension of $[\varrho_\varepsilon, \mathbf{u}_\varepsilon]$ in Ω . Then by (4.10) we have

$$\|\tilde{\varrho}_\varepsilon\|_{L^{3\gamma-3}(\Omega)} + \|\tilde{\mathbf{u}}_\varepsilon\|_{W_0^{1,2}(\Omega; R^3)} \leq C. \tag{4.11}$$

Thus, up to a substraction of subsequence,

$$\tilde{\varrho}_\varepsilon \rightharpoonup \varrho \text{ weakly in } L^{3\gamma-3}(\Omega), \quad \tilde{\mathbf{u}}_\varepsilon \rightharpoonup \mathbf{u} \text{ weakly in } W_0^{1,2}(\Omega; R^3). \tag{4.12}$$

We obtained the uniform estimate (2.23) and the weak convergence in (2.24).

4.2. Equations in homogeneous domain

In this section, we deduce the equations in $[\tilde{\varrho}_\varepsilon, \tilde{\mathbf{u}}_\varepsilon]$ and $[\varrho, \mathbf{u}]$ in the homogeneous domain Ω .

First, the fact that $[\tilde{\varrho}_\varepsilon, \tilde{\mathbf{u}}_\varepsilon]$ is a renormalized weak solution (see Lem. 4.1) implies that $[\tilde{\varrho}_\varepsilon, \tilde{\mathbf{u}}_\varepsilon]$ solves (4.2).

Next we claim that the couple $[\tilde{\varrho}_\varepsilon, \tilde{\mathbf{u}}_\varepsilon]$ solves the same momentum equations as (2.6) in Ω up to a small remainder.

Lemma 4.2. *Under the assumptions in Theorem 2.4, there holds*

$$\operatorname{div}(\tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon \otimes \tilde{\mathbf{u}}_\varepsilon) + \nabla p(\tilde{\varrho}_\varepsilon) = \operatorname{div} \mathbb{S}(\nabla \tilde{\mathbf{u}}_\varepsilon) + \tilde{\varrho}_\varepsilon \mathbf{f} + \mathbf{g} + \mathbf{r}_\varepsilon, \quad \text{in } \mathcal{D}'(\Omega; R^3), \tag{4.13}$$

where the distribution \mathbf{r}_ε is small in the following sense:

$$|\langle \mathbf{r}_\varepsilon, \varphi \rangle_{\mathcal{D}'(\Omega; R^3), \mathcal{D}(\Omega; R^3)}| \leq C \varepsilon^{\delta_1} \left(\|\nabla \varphi\|_{L^{\frac{3\gamma-3}{2\gamma-3}+\delta_0}(\Omega_\varepsilon; R^9)} + \|\varphi\|_{L^{r_1}(\Omega; R^3)} \right), \tag{4.14}$$

where $\delta_0 > 0$ is chosen such that (4.21) is satisfied, $1 < r_1 < \infty$ is determined by (4.18) and $\delta_1 > 0$ is defined in (4.23) later on.

Proof of Lemma 4.2. By the assumption on the distribution and size of the holes in (2.4), there exists $g_\varepsilon \in C^\infty(\Omega)$ satisfying $0 \leq g_\varepsilon \leq 1$ and

$$g_\varepsilon = 0 \text{ on } \bigcup_{n=1}^{N(\varepsilon)} T_{\varepsilon,n}, \quad g_\varepsilon = 1 \text{ in } \Omega \setminus \bigcup_{n=1}^{N(\varepsilon)} \overline{B(x_{\varepsilon,n}, \delta_0 \varepsilon^\alpha)}, \quad \|\nabla g_\varepsilon\|_{L^\infty(\Omega; R^3)} \leq C \varepsilon^{-\alpha}. \tag{4.15}$$

Direct calculation gives that for any $1 \leq q \leq \infty$:

$$\|1 - g_\varepsilon\|_{L^q(\Omega)} \leq C \varepsilon^{\frac{3(\alpha-1)}{q}}, \quad \|\nabla g_\varepsilon\|_{L^q(\Omega; R^3)} \leq C \varepsilon^{\frac{3(\alpha-1)}{q} - \alpha}. \tag{4.16}$$

Then for any $\varphi \in C_c^\infty(\Omega; R^3)$, we have

$$\begin{aligned} & \int_\Omega \tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon \otimes \tilde{\mathbf{u}}_\varepsilon : \nabla \varphi + p(\tilde{\varrho}_\varepsilon) \operatorname{div} \varphi - \mathbb{S}(\nabla \tilde{\mathbf{u}}_\varepsilon) : \nabla \varphi + \tilde{\varrho}_\varepsilon \mathbf{f} \cdot \varphi + \mathbf{g} \cdot \varphi \, dx \\ &= \int_{\Omega_\varepsilon} \left(\tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon \otimes \tilde{\mathbf{u}}_\varepsilon : \nabla(\varphi g_\varepsilon) + p(\tilde{\varrho}_\varepsilon) \operatorname{div}(\varphi g_\varepsilon) - \mathbb{S}(\nabla \tilde{\mathbf{u}}_\varepsilon) : \nabla(\varphi g_\varepsilon) \right. \\ & \quad \left. + \tilde{\varrho}_\varepsilon \mathbf{f} \cdot (\varphi g_\varepsilon) + \mathbf{g} \cdot (\varphi g_\varepsilon) \right) dx + I_\varepsilon \\ &= I_\varepsilon, \end{aligned}$$

where we used the fact $\varphi g_\varepsilon \in C_c^\infty(\Omega_\varepsilon; R^3)$ is a good test function for the momentum equations (2.6) in Ω_ε , and the quantity I_ε is of the form

$$\begin{aligned} I_\varepsilon &:= \sum_{j=1}^4 I_{j,\varepsilon}, \quad \text{with:} \\ I_{1,\varepsilon} &:= \int_\Omega \tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon \otimes \tilde{\mathbf{u}}_\varepsilon : (1 - g_\varepsilon) \nabla \varphi - \tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon \otimes \tilde{\mathbf{u}}_\varepsilon : (\nabla g_\varepsilon \otimes \varphi) \, dx, \\ I_{2,\varepsilon} &:= \int_\Omega p(\tilde{\varrho}_\varepsilon) (1 - g_\varepsilon) \operatorname{div} \varphi - p(\tilde{\varrho}_\varepsilon) \nabla g_\varepsilon \cdot \varphi \, dx, \\ I_{3,\varepsilon} &:= \int_\Omega -\mathbb{S}(\nabla \tilde{\mathbf{u}}_\varepsilon) : (1 - g_\varepsilon) \nabla \varphi + \mathbb{S}(\nabla \tilde{\mathbf{u}}_\varepsilon) : (\nabla g_\varepsilon \otimes \varphi) \, dx, \\ I_{4,\varepsilon} &:= \int_\Omega \tilde{\varrho}_\varepsilon \mathbf{f} \cdot (1 - g_\varepsilon) \varphi + \mathbf{g} \cdot (1 - g_\varepsilon) \varphi \, dx. \end{aligned} \tag{4.17}$$

We now estimate $I_{j,\varepsilon}$ one by one. For $I_{1,\varepsilon}$, direct calculation gives

$$\begin{aligned} |I_{1,\varepsilon}| &\leq C \|\varrho_\varepsilon\|_{L^{3\gamma-3}(\Omega_\varepsilon)} \|\mathbf{u}_\varepsilon\|_{L^6(\Omega_\varepsilon; \mathbb{R}^3)}^2 \left(\|(1-g_\varepsilon)\nabla\varphi\|_{L^{\frac{3\gamma-3}{2\gamma-3}}(\Omega_\varepsilon; \mathbb{R}^9)} + \|\nabla g_\varepsilon \otimes \varphi\|_{L^{\frac{3\gamma-3}{2\gamma-3}}(\Omega_\varepsilon; \mathbb{R}^9)} \right) \\ &\leq C \left(\|1-g_\varepsilon\|_{L^{r_1}(\Omega)} \|\nabla\varphi\|_{L^{\frac{3\gamma-3}{2\gamma-3}+\delta_0}(\Omega_\varepsilon; \mathbb{R}^9)} + \|\nabla g_\varepsilon\|_{L^{\frac{3\gamma-3}{2\gamma-3}+\delta_0}(\Omega_\varepsilon; \mathbb{R}^3)} \|\varphi\|_{L^{r_1}(\Omega; \mathbb{R}^3)} \right), \end{aligned}$$

where

$$0 < \delta_0 < 1, \quad 1 < r_1 < \infty, \quad \frac{1}{r_1} + \left(\frac{3\gamma-3}{2\gamma-3} + \delta_0 \right)^{-1} = \frac{2\gamma-3}{3\gamma-3}. \tag{4.18}$$

By (4.16), we have

$$\|1-g_\varepsilon\|_{L^{r_1}(\Omega)} \leq C \varepsilon^{\frac{3(\alpha-1)}{r_1}}, \quad \|\nabla g_\varepsilon\|_{L^{\frac{3\gamma-3}{2\gamma-3}+\delta_0}(\Omega; \mathbb{R}^3)} \leq C \varepsilon^{3(\alpha-1)\left(\frac{3\gamma-3}{2\gamma-3}+\delta_0\right)^{-1}-\alpha}. \tag{4.19}$$

We calculate

$$3(\alpha-1) \left(\frac{3\gamma-3}{2\gamma-3} \right)^{-1} - \alpha = \frac{\alpha\gamma - 2\alpha - 2\gamma + 3}{\gamma-1} > 0, \tag{4.20}$$

where we used the condition (2.22) which is equivalent to

$$\alpha\gamma - 2\alpha - 2\gamma + 3 > 0.$$

Then by (4.19) and (4.20), we can choose $\delta_0 > 0$ small enough such that

$$3(\alpha-1) \left(\frac{3\gamma-3}{2\gamma-3} + \delta_0 \right)^{-1} - \alpha =: h(\delta_0) > 0. \tag{4.21}$$

We finally obtain

$$|I_{1,\varepsilon}| \leq C \varepsilon^{\delta_1} \left(\|\nabla\varphi\|_{L^{\frac{3\gamma-3}{2\gamma-3}+\delta_0}(\Omega_\varepsilon; \mathbb{R}^9)} + \|\varphi\|_{L^{r_1}(\Omega; \mathbb{R}^3)} \right), \tag{4.22}$$

where

$$\delta_1 := \min \left\{ \frac{3(\alpha-1)}{r_1}, h(\delta_0) \right\} > 0, \tag{4.23}$$

where $\delta_0 > 0$ is chosen such that (4.21) is satisfied and $1 < r_1 < \infty$ is determined by (4.18).

For $I_{2,\varepsilon}$, similar as the estimate for $I_{1,\varepsilon}$, we have

$$\begin{aligned} |I_{2,\varepsilon}| &\leq C \|p(\tilde{\varrho}_\varepsilon)\|_{L^{\frac{3\gamma-3}{\gamma}}(\Omega_\varepsilon)} \left(\|(1-g_\varepsilon)\operatorname{div}\varphi\|_{L^{\frac{3\gamma-3}{2\gamma-3}}(\Omega_\varepsilon)} + \|\nabla g_\varepsilon \cdot \varphi\|_{L^{\frac{3\gamma-3}{2\gamma-3}}(\Omega_\varepsilon)} \right) \\ &\leq C \varepsilon^{\delta_1} \left(\|\nabla\varphi\|_{L^{\frac{3\gamma-3}{2\gamma-3}+\delta_0}(\Omega_\varepsilon; \mathbb{R}^9)} + \|\varphi\|_{L^{r_1}(\Omega; \mathbb{R}^3)} \right). \end{aligned} \tag{4.24}$$

For $I_{3,\varepsilon}$ and $I_{4,\varepsilon}$, the similar argument gives the following non-optimal estimate:

$$|I_{3,\varepsilon}| + |I_{4,\varepsilon}| \leq C \varepsilon^{\delta_1} \left(\|\nabla\varphi\|_{L^{\frac{3\gamma-3}{2\gamma-3}+\delta_0}(\Omega_\varepsilon; \mathbb{R}^9)} + \|\varphi\|_{L^{r_1}(\Omega; \mathbb{R}^3)} \right). \tag{4.25}$$

Summing up the estimates in (4.22), (4.24) and (4.25) implies (4.14). □

4.3. The limit equations

This section is devoted to deduce the equations in the limit couple $[\varrho, \mathbf{u}]$ obtained in (4.12). First of all, by compact Sobolev embedding, we have

$$\tilde{\mathbf{u}}_\varepsilon \rightarrow \mathbf{u} \text{ strongly in } L^q(\Omega; R^3) \text{ for any } 1 \leq q < 6. \tag{4.26}$$

Thus, there holds the weak convergence of nonlinear terms:

$$\begin{aligned} \tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon &\rightarrow \varrho \mathbf{u} && \text{weakly in } L^q(\Omega; R^3) \text{ for any } 1 < q < \frac{6\gamma-6}{\gamma+1}, \\ \tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon \otimes \tilde{\mathbf{u}} &\rightarrow \varrho \mathbf{u} \otimes \mathbf{u} && \text{weakly in } L^q(\Omega; R^9) \text{ for any } 1 < q < \frac{3\gamma-3}{\gamma}. \end{aligned} \tag{4.27}$$

Then passing $\varepsilon \rightarrow 0$ in (4.2) and in (4.13) gives

$$\begin{aligned} \operatorname{div}(\varrho \mathbf{u}) &= 0, \\ \operatorname{div}(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla \overline{p(\varrho)} &= \operatorname{div} \mathbb{S}(\nabla \mathbf{u}) + \varrho \mathbf{f} + \mathbf{g}, \end{aligned} \tag{4.28}$$

in the sense of distribution in $\mathcal{D}'(\Omega)$, where $\overline{p(\varrho)}$ is the weak limit of $p(\tilde{\varrho}_\varepsilon)$ in $L^{\frac{3\gamma-3}{\gamma}}(\Omega)$. Moreover, by Remark 2.2, $[\varrho, \mathbf{u}]$ satisfies the renormalized equation

$$\operatorname{div}(b(\varrho)\mathbf{u}) + (\varrho b'(\varrho) - b(\varrho))\operatorname{div} \mathbf{u} = 0, \text{ in } \mathcal{D}'(R^3), \tag{4.29}$$

where $b \in C^0([0, \infty)) \cap C^1((0, \infty))$ satisfies (2.17)-(2.18).

To finish the proof of Theorem 2.4, it is left to show $\overline{p(\varrho)} = p(\varrho)$. This is done in the next section.

4.4. Convergence of pressure term – end of the proof

We introduce the so-called effective viscous flux $p(\varrho) - (\frac{4\mu}{3} + \eta)\operatorname{div} \mathbf{u}$ enjoying some compactness property given in the following lemma. This property plays a crucial role in the existence theory of weak solutions for the compressible Navier–Stokes equations.

Lemma 4.3. *Up to a substruction of subsequence, there holds for any $\psi \in C_c^\infty(\Omega)$:*

$$\lim_{\varepsilon \rightarrow 0} \int_\Omega \psi \left(p(\tilde{\varrho}_\varepsilon) - \left(\frac{4\mu}{3} + \eta \right) \operatorname{div} \tilde{\mathbf{u}}_\varepsilon \right) \tilde{\varrho}_\varepsilon \, dx = \int_\Omega \psi \left(\overline{p(\varrho)} - \left(\frac{4\mu}{3} + \eta \right) \operatorname{div} \mathbf{u} \right) \varrho \, dx. \tag{4.30}$$

Proof of Lemma 4.3. The proof of Lemma 4.3 is quite tedious but nowadays well understood. The main idea is to employ proper test functions by employing Fourier multiplier and Riesz type operators. We refer to Section 1.3.7.2 in [19] or Section 10.16 in [11] for the definitions and properties used here of Fourier multiplier and Riesz operators. These proper test functions are defined by

$$\psi \nabla \Delta^{-1}(1_\Omega \tilde{\varrho}_\varepsilon), \quad \psi \nabla \Delta^{-1}(1_\Omega \varrho), \tag{4.31}$$

where $\psi \in C_c^\infty(\Omega)$ and Δ^{-1} is the Fourier multiplier on R^3 with symbol $-\frac{1}{|\xi|^2}$.

We observe that

$$\nabla \nabla \Delta^{-1} = (\mathcal{R}_{i,j})_{1 \leq i, j \leq 3}$$

are the classical Riesz operators. Then for any $f \in L^q(R^3)$, $1 < q < \infty$:

$$\|\nabla \nabla \Delta^{-1}(f)\|_{L^q(R^3; R^9)} \leq C \|f\|_{L^q(R^3)}.$$

By the embedding theorem in homogeneous Sobolev spaces (see Thms. 1.55 and 1.57 in [19] or Theorem 10.25 and Theorem 10.26 in [11]), we have for any $f \in L^q(R^3)$, $\text{supp } f \subset \Omega$:

$$\begin{aligned} \|\nabla \Delta^{-1}(f)\|_{L^{q^*}(R^3;R^3)} &\leq C \|f\|_{L^q(R^3)} \quad \frac{1}{q^*} = \frac{1}{q} - \frac{1}{3}, \text{ if } 1 < q < 3, \\ \|\nabla \Delta^{-1}(f)\|_{L^{q^*}(R^3;R^3)} &\leq C \|f\|_{L^q(R^3)} \quad \text{for any } q^* < \infty, \text{ if } q \geq 3. \end{aligned}$$

Then by the uniform estimate for $\tilde{\varrho}_\varepsilon$ and its weak limit ϱ in (4.12) and the fact $3\gamma - 3 > 3$ under our assumption $\gamma > 2$, we have for any $q < \infty$:

$$\begin{aligned} \|\psi \nabla \Delta^{-1}(1_\Omega \tilde{\varrho}_\varepsilon)\|_{L^q(\Omega;R^3)} + \|\psi \nabla \Delta^{-1}(1_\Omega \varrho)\|_{L^q(\Omega;R^3)} &\leq C, \\ \|\nabla(\psi \nabla \Delta^{-1}(1_\Omega \tilde{\varrho}_\varepsilon))\|_{L^{3\gamma-3}(\Omega;R^9)} + \|\nabla(\psi \nabla \Delta^{-1}(1_\Omega \varrho))\|_{L^{3\gamma-3}(\Omega;R^9)} &\leq C. \end{aligned} \tag{4.32}$$

Since $2 < \gamma \leq 3$, we have $3\gamma - 3 > \frac{3\gamma-3}{2\gamma-3}$. Then choosing $\delta_0 > 0$ in Lemma 4.2 to be small enough, we have

$$3\gamma - 3 \geq \frac{3\gamma - 3}{2\gamma - 3} + \delta_0.$$

Thus, (4.14) and (4.32) implies

$$\begin{aligned} &|\langle r_\varepsilon, \psi \nabla \Delta^{-1}(1_\Omega \tilde{\varrho}_\varepsilon) \rangle_{\mathcal{D}'(\Omega;R^3), \mathcal{D}(\Omega;R^3)}| \\ &\leq C \varepsilon^{\delta_1} (\|\nabla(\psi \nabla \Delta^{-1}(1_\Omega \tilde{\varrho}_\varepsilon))\|_{L^{3\gamma-3}(\Omega_\varepsilon;R^9)} + \|\psi \nabla \Delta^{-1}(1_\Omega \tilde{\varrho}_\varepsilon)\|_{L^{r_1}(\Omega;R^3)}) \\ &\leq C \varepsilon^{\delta_1}, \end{aligned}$$

which goes to zero as $\varepsilon \rightarrow 0$.

Now we chose $\psi \nabla \Delta^{-1}(1_\Omega \tilde{\varrho}_\varepsilon)$ as a test functions in the weak formulation of equation (4.13) and pass $\varepsilon \rightarrow 0$. Then we choose $\psi \nabla \Delta^{-1}(1_\Omega \varrho)$ as a test functions in the weak formulation of (4.28)₂. By comparing the results of these two operations, through long but straightforward calculations, we obtain that

$$\begin{aligned} I &:= \lim_{\varepsilon \rightarrow 0} \int_\Omega \psi \left(p(\tilde{\varrho}_\varepsilon) - \left(\frac{4\mu}{3} + \eta\right) \text{div } \tilde{\mathbf{u}}_\varepsilon \right) \tilde{\varrho}_\varepsilon \, dx - \int_\Omega \psi \left(\overline{p(\varrho)} - \left(\frac{4\mu}{3} + \eta\right) \text{div } \mathbf{u} \right) \varrho \, dx \\ &= \lim_{\varepsilon \rightarrow 0} \int_\Omega \tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon^i \tilde{\mathbf{u}}_\varepsilon^j \psi \mathcal{R}_{i,j}(1_\Omega \tilde{\varrho}_\varepsilon) \, dx - \int_\Omega \varrho \mathbf{u}^i \mathbf{u}^j \psi \mathcal{R}_{i,j}(1_\Omega \varrho) \, dx. \end{aligned} \tag{4.33}$$

On the other hand, choosing $1_\Omega \nabla \Delta^{-1}(\psi \tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon)$ as a test function in the weak formulation of (4.2) with $b(\varrho) = \varrho$ and $1_\Omega \nabla \Delta^{-1}(\psi \varrho \mathbf{u})$ as a test function in the weak formulation of (4.28)₁ implies

$$\int_\Omega 1_\Omega \tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon^i \mathcal{R}_{i,j}(\psi \tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon) \, dx = 0, \quad \int_\Omega 1_\Omega \varrho \mathbf{u}^i \mathcal{R}_{i,j}(\psi \varrho \mathbf{u}) \, dx = 0. \tag{4.34}$$

Plugging (4.34) into (4.33) yields

$$\begin{aligned} I &= \lim_{\varepsilon \rightarrow 0} \int_\Omega \tilde{\mathbf{u}}_\varepsilon^i \left(\tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon^j \psi \mathcal{R}_{i,j}(1_\Omega \tilde{\varrho}_\varepsilon) - 1_\Omega \tilde{\varrho}_\varepsilon \mathcal{R}_{i,j}(\psi \tilde{\varrho}_\varepsilon \tilde{\mathbf{u}}_\varepsilon) \right) \, dx \\ &\quad - \int_\Omega \mathbf{u}^i \left(\varrho \mathbf{u}^j \psi \mathcal{R}_{i,j}(1_\Omega \varrho) - 1_\Omega \varrho \mathcal{R}_{i,j}(\psi \varrho \mathbf{u}) \right) \, dx. \end{aligned}$$

We introduce the following lemma, which is a variance of the divergence-curl lemma, and we refer to ([10], Lem. 3.4) for the proof.

Lemma 4.4. *Let $1 < p, q < \infty$ satisfy*

$$\frac{1}{r} := \frac{1}{p} + \frac{1}{q} < 1.$$

Suppose

$$u_\varepsilon \rightharpoonup u \text{ weakly in } L^p(R^3), \quad v_\varepsilon \rightharpoonup v \text{ weakly in } L^q(R^3), \text{ as } \varepsilon \rightarrow 0.$$

Then for any $1 \leq i, j \leq 3$:

$$u_\varepsilon \mathcal{R}_{i,j}(v_\varepsilon) - v_\varepsilon \mathcal{R}_{i,j}(u_\varepsilon) \rightharpoonup u \mathcal{R}_{i,j}(v) - v \mathcal{R}_{i,j}(u) \text{ weakly in } L^r(R^3).$$

The convergence result (4.30) can be deduced by the strong convergence of the velocity in (4.26) and Lemma 4.4. □

A direct consequence of the compactness of the effective viscous flux is the following:

Lemma 4.5. *We denote $\overline{p(\varrho)}\varrho$ as the weak limit of $p(\tilde{\varrho}_\varepsilon)\tilde{\varrho}_\varepsilon$ in $L^{\frac{3\gamma-3}{\gamma+1}}(\Omega)$. Then $\overline{p(\varrho)}\varrho = \overline{p(\varrho)}\varrho$.*

Proof of Lemma 4.5. First of all, we have

$$(3\gamma - 3) - (\gamma + 1) = 2\gamma - 4 > 0.$$

Then by (4.11), we have

$$p(\tilde{\varrho}_\varepsilon)\tilde{\varrho}_\varepsilon \rightharpoonup \overline{p(\varrho)}\varrho \text{ weakly in } L^{\frac{3\gamma-3}{\gamma+1}}(\Omega).$$

Taking $b(s) = s \log s$ in the renormalized equations (4.2) and (4.29) implies

$$\operatorname{div}((\tilde{\varrho}_\varepsilon \log \tilde{\varrho}_\varepsilon)\tilde{\mathbf{u}}_\varepsilon) + \tilde{\varrho}_\varepsilon \operatorname{div} \tilde{\mathbf{u}}_\varepsilon = 0, \quad \operatorname{div}((\varrho \log \varrho)\mathbf{u}) + \varrho \operatorname{div} \mathbf{u} = 0, \text{ in } \mathcal{D}'(\Omega). \tag{4.35}$$

Passing $\varepsilon \rightarrow 0$ in the first equation of (4.35) gives

$$\operatorname{div}(\overline{(\varrho \log \varrho)}\mathbf{u}) + \overline{\varrho \operatorname{div} \mathbf{u}} = 0, \text{ in } \mathcal{D}'(\Omega), \tag{4.36}$$

where we used the strong convergence of the velocity in (4.26) and

$$\begin{aligned} \tilde{\varrho}_\varepsilon \log \tilde{\varrho}_\varepsilon &\rightharpoonup \overline{\varrho \log \varrho} \text{ weakly in } L^q(\Omega) \text{ for any } q < 3\gamma - 3, \\ \tilde{\varrho}_\varepsilon \operatorname{div} \tilde{\mathbf{u}}_\varepsilon &\rightharpoonup \overline{\varrho \operatorname{div} \mathbf{u}} \text{ weakly in } L^{\frac{6\gamma-6}{3\gamma-1}}(\Omega). \end{aligned} \tag{4.37}$$

Then for any $\psi \in C_c^\infty(\Omega)$, (4.36) and (4.37) implies

$$\lim_{\varepsilon \rightarrow 0} \int_\Omega \psi \left(p(\tilde{\varrho}_\varepsilon) - \left(\frac{4\mu}{3} + \eta \right) \operatorname{div} \tilde{\mathbf{u}}_\varepsilon \right) \tilde{\varrho}_\varepsilon \, dx = \int_\Omega \psi \overline{p(\varrho)}\varrho - \left(\frac{4\mu}{3} + \eta \right) \overline{(\varrho \log \varrho)}\mathbf{u} \cdot \nabla \psi \, dx. \tag{4.38}$$

By the second equation in (4.35), we obtain

$$\int_\Omega \psi \left(\overline{p(\varrho)} - \left(\frac{4\mu}{3} + \eta \right) \operatorname{div} \mathbf{u} \right) \varrho \, dx = \int_\Omega \psi \overline{p(\varrho)}\varrho - \left(\frac{4\mu}{3} + \eta \right) (\varrho \log \varrho)\mathbf{u} \cdot \nabla \psi \, dx. \tag{4.39}$$

Let $\{\psi_n\}_{n \in \mathbb{Z}_+} \subset C_c^\infty(\Omega)$ such that

$$\psi_n(x) = 0 \text{ if } d(x, \partial\Omega) < \frac{1}{n}, \quad \psi_n(x) = 1 \text{ if } d(x, \partial\Omega) > \frac{2}{n}, \quad \|\nabla \psi_n\|_{L^\infty(\Omega; R^3)} \leq 4n.$$

Then for any $q \in [1, \infty]$:

$$\|1 - \psi_n\|_{L^q(\Omega)} \leq C n^{-\frac{1}{q}}, \quad \|\nabla \psi_n\|_{L^q(\Omega; R^3)} \leq C n^{1-\frac{1}{q}},$$

and consequently

$$\|d(x, \partial\Omega)\nabla\psi_n\|_{L^q;R^3} \leq C n^{-\frac{1}{q}}.$$

The fact $\mathbf{u} \in W_0^{1,2}(\Omega; R^3)$ implies

$$[d(x, \partial\Omega)]^{-1}\mathbf{u} \in L^2(\Omega; R^3).$$

Therefore,

$$\begin{aligned} \int_{\Omega} \nabla\psi_n \cdot \overline{(\varrho \log \varrho)} \mathbf{u} \, dx &\leq \|d(x, \partial\Omega)\nabla\psi_n\|_{L^{10}(\Omega;R^3)} \|\overline{(\varrho \log \varrho)}\|_{L^{5/2}(\Omega)} \|[d(x, \partial\Omega)]^{-1}\mathbf{u}\|_{L^2(\Omega;R^3)} \\ &\leq C n^{-1/10}. \end{aligned} \tag{4.40}$$

Similarly,

$$\int_{\Omega} \nabla\psi_n \cdot (\varrho \log \varrho) \mathbf{u} \, dx \leq C n^{-1/10}. \tag{4.41}$$

We choose $\psi = \psi_n$ in (4.30) and pass to the limit $n \rightarrow \infty$. By using (4.38), (4.39), (4.40) and (4.41), we deduce

$$\int_{\Omega} \overline{p(\varrho)\varrho} - \overline{p(\varrho)}\varrho \, dx = 0. \tag{4.42}$$

By the strict monotonicity of the mapping $\varrho \mapsto p(\varrho)$, applying Theorem 10.19 in [11] or Lemma 3.35 in [19] implies

$$\overline{p(\varrho)\varrho} \geq \overline{p(\varrho)}\varrho, \quad \text{a.e. in } \Omega.$$

Together with (4.42), we deduce

$$\overline{p(\varrho)\varrho} = \overline{p(\varrho)}\varrho, \quad \text{a.e. in } \Omega.$$

We have completed the proof of Lemma 4.5. □

Thanks to the monotonicity of $p(\cdot)$, again by Theorem 10.19 in [11], we obtain $\overline{p(\varrho)} = p(\varrho)$. Hence, we complete the proof of Theorem 2.4.

For the convenience of readers, we recall Theorem 10.19 in [11]: Let $I \subset R$ be an interval, $Q \subset R^d$ be a domain, P and G be non-decreasing functions in $C(I)$. Let $\{\varrho_n\}_{n \in \mathbb{N}}$ be a sequence in $L^1(Q; I)$ such that

$$P(\varrho_n) \rightarrow \overline{P(\varrho)}, \quad G(\varrho_n) \rightarrow \overline{G(\varrho)}, \quad P(\varrho_n)G(\varrho_n) \rightarrow \overline{P(\varrho)G(\varrho)}, \quad \text{weakly in } L^1(Q).$$

Then the following properties hold:

- (i) $\overline{P(\varrho)} \overline{G(\varrho)} \leq \overline{P(\varrho)G(\varrho)}$.
- (ii) If, in addition, $P \in C(R)$, $G \in C(R)$, $G(R) = R$, G is strictly increasing, and $\overline{P(\varrho)} \overline{G(\varrho)} = \overline{P(\varrho)G(\varrho)}$, then $\overline{P(\varrho)} = P \circ G^{-1} \overline{G(\varrho)}$. If, in particular, $G(z) = z$ be the identity function, there holds $\overline{P(\varrho)} = P(\varrho)$.

5. CONCLUSIONS AND PERSPECTIVES

In this paper, we constructed an inverse of the divergence operator in a domain perforated with tiny holes and we showed the precise and optimal dependency on the size of the holes for the norm of this inverse operator; in particular, under some smallness constrain, this inverse of the divergence operator is uniformly bounded. We apply such an operator in the study of homogenization problems for stationary compressible Navier–Stokes system. Under some constrain (see (2.22)) between the adiabatic exponent and the size of the holes, we show that the homogenization process does not change the motion of the fluids: in the limit, we obtain again compressible Navier–Stokes equations.

Here we focus on the case where the holes are very small, corresponding to $\alpha > 3$. It is also known that if $\alpha = 1$, one can recover Darcy’s law from the homogenization. However, the case with $1 < \alpha \leq 3$, in particular the critical case $\alpha = 3$ is still open.

Acknowledgements. Eduard Feireisl and Yong Lu acknowledges the support of the project LL1202 in the programme ERC-CZ funded by the Ministry of Education, Youth and Sports of the Czech Republic. The authors would like to thank the anonymous referees for the useful comments and suggestions.

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