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## ELENA STROESCU A dilation theorem for operators on Banach spaces

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A DILATION THEOREM FOR OPERATORS ON BANACH SPACES

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Introduction. -

Let  $\mathbb{R}^+$  be the set of all non-negative real numbers and  $\mathbb{R}(\mathfrak{F})$  the Banach algebra of all linear bounded operators on a Banach space  $\mathfrak{F}$ . In this paper, we present a dilation theorem by which an object  $\{\mathfrak{F}, \Gamma, U\}$  dilates into  $\{\mathfrak{F}, \varphi, P, \tilde{\Gamma}, V\}$ ; where  $\mathfrak{F}$  and  $\tilde{\mathfrak{F}}$  are Banach spaces,  $\varphi$  is a bicontinuous isomorphism of  $\mathfrak{F}$  into  $\tilde{\mathfrak{F}}$ , P a continuous projection of  $\tilde{\mathfrak{F}}$  onto  $\varphi(\mathfrak{F})$ ,  $\Gamma = \{\mathbf{T}_t\}_{t \in \mathbb{R}^+} \subset \mathfrak{K}(\mathfrak{F})$  and  $\tilde{\Gamma} = \{\tilde{\mathbf{T}}_t\}_{t \in \mathbb{R}^+} \subset \mathfrak{K}(\tilde{\mathfrak{F}})$  are operator semi-groups, U is a  $\mathfrak{K}(\mathfrak{I})$ -valued linear map on an arbitrary algebra  $\mathfrak{C}$  estimated by a submultiplicative functional and  $\mathbb{V}$  a  $\mathfrak{K}(\tilde{\mathfrak{F}})$ -valued representation on  $\mathfrak{C}$  such that  $V_a \tilde{T}_t = \tilde{T}_t V_a$ , for every  $a \in \mathfrak{C}$  and  $t \in \mathbb{R}^+$ . This theorem is an extension of some previous results (see [8], [9]); it has arisen from the concern to characterize restrictions of spectral operators on invariant subspaces (or operators which dilate in spectral operators) by a map replacing the spectral representation.

#### Notations. -

Throughout the following C denotes the complex plane; N = {0,1,2,...}; **C** an arbitrary algebra over C with unit element denoted by 1; K a submultiplicative functional of C into R<sup>+</sup> (i.e.  $K_{ab} \leq K_a K_b$  for any  $a, b \in C$ ) such that  $K_1 = 1$ ;  $\mathfrak{X}$  a Banach space over C;  $\mathfrak{K}(\mathfrak{X})$  the Banach algebra of all linear bounded operators on  $\mathfrak{X}$  over C; I the identity operator. Let  $T_1$ ,  $T_2 \in \mathfrak{K}(\mathfrak{X})$  two commuting operators; then one says that  $T_1$  is quasi-nilpotent equivalent with  $T_2$  and denotes  $T_1 \sim T_2$ , if  $\lim_{n \to \infty} ||(T_1 - T_2)^n||^{1/n} = 0$ . A family of operators  $\{T_t\}_{t \in \mathbb{R}^+} \subset \mathfrak{K}(\mathfrak{X})$  is called semi-group if  $T_0 = I$  and  $T_{t+s} = T_t T_s$  for any t and  $s \in \mathbb{R}^+$ .

THEOREM. - Let  $\{\mathbf{T}_t\}_{t \in \mathbb{R}^+} \subset \mathcal{B}(\mathfrak{X})$  be a semi-group of operators and  $U: \mathfrak{a} \to \mathcal{B}(\mathfrak{X})$ a linear map such that  $U_1 = I$ ,  $||U_a|| \leq K_a$ , for any  $a \in \mathfrak{a}$ .

Then, there exists a Banach space  $\tilde{x}$ , an isometric isomorphism  $\varphi$  of  $\tilde{x}$  into  $\tilde{x}$ , a continuous projection P of  $\tilde{x}$  onto  $\varphi(\tilde{x})$ , a semi-group  $\tilde{\Gamma} = \{\tilde{\mathbf{T}}_t\}_{t \in \mathbb{R}^+} \subset \mathfrak{g}(\tilde{x})$  and a representation  $V : \mathfrak{a} \rightarrow \mathfrak{g}(\tilde{x})$  such that :

(o) 
$$\|P\| = 1$$
;  $\|\tilde{T}_t\| = \|T_t\|$ , for any  $t \in R^+$ ;  $V_1 = \tilde{I}$  and  $\|V_{\alpha}\| \leq K_{\alpha}$ , for any  $\alpha \in \mathcal{C}$ .

(i) 
$$V_{\alpha}\tilde{T}_{\tau} = \tilde{T}_{\tau}V_{\alpha}$$
, for any  $\alpha \in \Omega$ ,  $\tau \in \mathbb{R}^+$ .

(ii) 
$$P\tilde{T}_{\tau} V_{\sigma} \varphi(x) = \varphi(T_{\tau} U_{\sigma} x)$$
, for any  $\alpha \in \mathcal{C}$ ,  $\tau \in \mathbb{R}^+$ ,  $x \in \mathfrak{X}$ 

(iii) 
$$\tilde{\mathfrak{F}}$$
 is the closed vector space spanned by  $\{\tilde{T}_{\mathfrak{F}} V_{\mathfrak{p}} \varphi(x); \alpha \in \mathfrak{a}, t \in \mathbb{R}^{\mathsf{T}}, x \in \mathfrak{X}\}$ .

(iv) Let 
$$s \in R^+$$
; then we have the following equivalences :  
1°  $\tilde{T}_s \phi(x) = \phi(T_s x)$ , for any  $x \in \mathfrak{X}$ ;  
2°  $P\tilde{T}_s V_{\alpha} \phi(x) = \tilde{T}_s P V_{\alpha} \phi(x)$ , for any  $\alpha \in \alpha$ ,  $x \in \mathfrak{X}$ ;  
3°  $U_a T_s = T_s U_a$ , for any  $a \in \alpha$ .

(v) Let 
$$b \in \mathcal{C}$$
; then  $V_b \varphi(x) = \varphi(U_b x)$ , for any  $x \in \mathfrak{X}$  is equivalent  
with  $U_{ab} = U_a U_b$ , for any  $a \in \mathcal{C}$ .

(vi) Let 
$$\sigma \in \mathbb{R}^+$$
 and  $\beta \in \mathcal{A}$  commuting with all the elements of  $\mathcal{A}$  such that  $U_{\alpha\beta} = U_{\alpha}U_{\beta}$ ,  $T_{\sigma}U_{\alpha} = U_{\alpha}T_{\sigma}$ , for any  $a \in \mathcal{A}$ ; then  $\| (\tilde{T}_{\sigma} - V_{\beta})^n \| = \| (T_{\sigma} - U_{\beta})^n \|$ , for every  $n \in \mathbb{N}$ .

<u>Proof</u>: A) Let us consider the Cartesian product  $\mathfrak{X}^{R^+ \times \mathbb{C}} = \underset{(t,a) \in R^+ \times \mathbb{C}}{\prod_{\substack{(t,a) \in R^+ \times \mathbb{C}}}} \mathfrak{X}^{(t,a)}$ and the direct sum  $\mathfrak{X}^{(R^+ \times \mathbb{C})} = \bigoplus_{\substack{(t,a) \in R^+ \times \mathbb{C}}} \mathfrak{X}^{(t,a)}$ , where  $\mathfrak{X}^{(t,a)} = \mathfrak{X}$ , for  $(t,a) \in R^+ \times \mathbb{C}$  is a family  $(y_{t,a})_{(t,a)} \in R^+ \times \mathbb{C}$ (many times we write  $y = (y_{t,a})_{t,a}$ ) of components  $(y)_{(t,a)} = y_{t,a} \in \mathfrak{X}$ , for every  $t \in \mathbb{R}^+$ ,  $a \in \mathbb{C}$ . If  $y \in \mathfrak{X}^{(\mathbb{R}^+ \times \mathbb{C})} \subset \mathfrak{X}^{\mathbb{R}^+ \times \mathbb{C}}$ , then  $(y)_{t,a} = y_{t,a} \neq 0$  for only a finite number of elements  $(t,a) \in \mathbb{R}^+ \times \mathbb{C}$ .

Let us consider a map :

defined by

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It is easy to see that  $\Theta$  is a well defined linear map. Then, we denote by  $\hat{x}$  the range of  $\Theta$  and by  $\hat{y}$  an arbitrary element of  $\hat{x}$ .

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For every  $\widehat{\mathbf{y}} \in \widehat{\mathfrak{X}}$  , we have :

 $\mathbb{S}^{-1}(\{\hat{\mathbf{y}}\}) = \{\mathbf{y} \in \mathfrak{X}^{(\mathbb{R}^+ \times \mathbb{C})} ; \mathbb{O} | \mathbf{y} = \hat{\mathbf{y}}\}$ .

We define a function  $\omega$ :  $\hat{\mathbf{x}} \to \mathbf{R}^+$  by  $\omega(\hat{\mathbf{y}}) = \inf_{\mathbf{y} \in \mathfrak{G}^{-1}(\{\hat{\mathbf{y}}\}\})} \sum_{s,b} \|\mathbf{T}_s\| \mathbf{K}_b \| \mathbf{y}_{s,b} \|$ , for every  $\hat{y} \in \hat{x}$ ; let us prove that  $\omega$  is a norm on  $\hat{x}$ . Let  $\mu \in C$  be non-zero,  $\hat{\mathbf{y}} \in \hat{\mathbf{x}}$  and  $\Delta(\mu \hat{\mathbf{y}}) = \{\mu \mathbf{y} ; \mathbf{y} \in \mathbb{R}^{-1}(\{\hat{\mathbf{y}}\}) ; \text{ then we show that } \mathbb{R}^{-1}(\{\mu \hat{\mathbf{y}}\}) = \Delta(\mu \hat{\mathbf{y}}).$  Indeed, let  $\mu y \in \Delta(\mu \hat{y})$ , i.e.  $y \in \Theta^{-1}(\{\hat{y}\})$ , then  $\mu \hat{y} = (\mu T_t \sum_{s,b} T_s U_s)_{s,b}_{s,b}_{s,b}_{t,a} = \Theta \mu y$ , hence  $\mu y \in \Theta^{-1}(\{\mu \hat{y}\})$ . Let now  $z \in \Theta^{-1}(\{\mu \hat{y}\})$ , i.e.  $\Theta z = \mu \hat{y}$  or  $\Theta \frac{z}{\mu} = \hat{y}$ , hence  $\mathbf{y'} = \frac{z}{\mu} \in \Theta\left(\{\hat{\mathbf{y}}\}\right) \text{ and } z = \mu \mathbf{y'} \in \Delta(\mu \hat{\mathbf{y}}) \text{ . Then } \omega(\mu \hat{\mathbf{y}}) = \inf_{z \in \Theta^{-1}(\{u \hat{\mathbf{y}}\})} \Sigma \|\mathbf{T}_{s}\| K_{b} \| z_{s,b} \|$  $= \inf_{z \in \Delta(\mu \hat{y})} \sum_{s,b} \|T_s\| \|K_b\| \|z_{s,b}\| = \inf_{y \in \Theta^{-1}(\{\hat{y}\})} \sum_{s,b} \|T_s\| \|K_b\| \|\mu y_{s,b}\| =$  $= |\mu| \inf_{\substack{\mathbf{y} \in \Theta^{-1}(\{\hat{\mathbf{y}}\}) \\ \text{s.b}}} \Sigma \| \mathbf{T}_{s} \| \mathbf{K}_{b} \| \mathbf{y}_{s,b} \| = |\mu| \omega(\hat{\mathbf{y}}), \text{ i.e. } \omega(\mu \hat{\mathbf{y}}) = |\mu| \omega(\hat{\mathbf{y}});$ whence one deduces also that  $\omega(\hat{0})=0$ . Then, for  $\mu=0$  we have  $\omega(0\hat{y})=0$  and  $O\omega(\hat{y}) = 0$ , for any  $\hat{y} \in \hat{x}$ . Hence  $\omega(\mu \hat{y}) = |\mu|\omega(\hat{y})$ , for any  $\hat{y} \in \hat{x}$ ,  $\mu \in \mathbb{C}$ . Let  $\hat{y}^1$ ,  $\hat{y}^2 \in \hat{x}$  and  $h(\hat{\mathbf{y}}^{1} + \hat{\mathbf{y}}^{2}) = \{ \mathbf{y}^{1} + \mathbf{y}^{2} : \mathbf{y}^{1} \in \Theta^{-1}(\{\hat{\mathbf{y}}^{1}\}), \mathbf{y}^{2} \in \Theta^{-1}(\{\hat{\mathbf{y}}^{2}\}) \}.$ then obviously we have  $\Delta(\hat{y}^1 + \hat{y}^2) \subset \Theta^{-1}(\{\hat{y}^1 + \hat{y}^2\})$  and  $\omega(\hat{\mathbf{y}}^{1}+\hat{\mathbf{y}}^{2}) = \inf_{z \in \Theta^{-1}(\hat{\mathbf{y}}^{1}+\hat{\mathbf{y}}^{2})} \sum_{s,b} \|\mathbf{T}_{s}\| \mathbf{K}_{b} \| \mathbf{z}_{s,b} \| \leq$  $\leq \inf_{\substack{\mathbf{z} \in \Lambda(\hat{\mathbf{y}}^{1} + \hat{\mathbf{y}}^{2}) \\ \mathbf{z} \in \Lambda(\hat{\mathbf{y}}^{1} + \hat{\mathbf{y}}^{2}) }} \sum_{s,b} \| \mathbf{T}_{s} \| \mathbf{K}_{b} \| \mathbf{z}_{s,b} \|$  $\begin{array}{l} = \inf_{y^1 \in \Theta^{-1}(\{\hat{y}^1\}), y^2 \in \Theta^{-1}(\{\hat{y}^2\})} & \sum_{s,b} \|\mathbf{T}_s\| \mathbf{K}_b\| \mathbf{y}_{s,b}^1 + \mathbf{y}_{s,b}^2 \| \leq \\ \end{array}$  $\leq \inf_{\substack{\mathbf{y}^{1} \in \Theta^{-1}(\{\hat{\mathbf{y}}^{1}\}) \\ \mathbf{y}^{1} \in \Theta^{-1}(\{\hat{\mathbf{y}}^{1}\}) }} \sum_{\mathbf{s},\mathbf{b}} \|\mathbf{T}_{\mathbf{s}}\| \mathbf{K}_{\mathbf{b}} \| \mathbf{y}_{\mathbf{s},\mathbf{b}}^{1} \| + \inf_{\substack{\mathbf{y}^{2} \in \Theta^{-1}(\{\hat{\mathbf{y}}^{2}\}) \\ \mathbf{y}^{2} \in \Theta^{-1}(\{\hat{\mathbf{y}}^{2}\}) }} \sum_{\mathbf{s},\mathbf{b}} \|\mathbf{T}_{\mathbf{s}}\| \mathbf{K}_{\mathbf{b}} \| \mathbf{y}_{\mathbf{s},\mathbf{b}}^{2} \|$ i.e.  $(\hat{\mathbf{y}}^1 + \hat{\mathbf{y}}^2) \leq \omega(\hat{\mathbf{y}}^1) + \omega(\hat{\mathbf{y}}^2)$ , for all  $\hat{\mathbf{y}}^1$ ,  $\hat{\mathbf{y}}^2 \in \hat{\mathbf{x}}$ . Then, from the definition of  $\omega$  , for every  $\hat{y}\in\hat{\mathfrak{X}}$  , we have :

1) 
$$\omega(\hat{y}) \leq \sum_{s,b} \|T_s\| K_b \|y_{s,b}$$
, for any  $y \in \Theta^{-1}(\{\hat{y}\})$  and

2) 
$$\|\hat{y}_{t,a}\| \leq \|T_t\| K_a \omega(\hat{y})$$
, for  $t \in \mathbb{R}^+$ ,  $a \in \mathcal{C}$ .

Hence  $\omega$  is a norm on  $\hat{\mathfrak{X}}$  ; we denote by  $\tilde{\mathfrak{X}}$  the  $\omega$ -completion of  $\mathfrak{X}$  and the norm on  $\tilde{\mathfrak{X}}$  also by  $\omega$ .

B) We define an isomorphism  $\varphi$  of  $\mathfrak{t}$  into  $\mathfrak{X}^{R^+ \times \mathfrak{A}}$  by  $\varphi(\mathbf{x}) = (\mathbb{T}_t \mathbb{U}_a \mathbf{x})_{t,a} = (\mathbb{T}_t \overset{\Sigma}{=} \mathbb{T}_s \mathbb{U}_{ab} \delta_{os} \delta_{lb} \mathbf{x})_{t,a} \in \hat{\mathfrak{X}}$ , for every  $\mathbf{x} \in \mathfrak{X}$ .

Applying 1) and 2) we get

3) 
$$||x|| \leq \omega(\varphi(x)) \leq ||x||$$
, for any  $x \in \mathfrak{X}$ .

Therefore  $\varphi$  is an isometric isomorphism of  $\mathfrak X$  into  $\widetilde{\mathfrak X}$  .

We define a projection P of  $\hat{\mathfrak{X}}$  onto  $\varphi(\mathfrak{X})$ , by  $P\hat{\mathfrak{y}} = \varphi(\hat{\mathfrak{y}}_{0,1})$ , for every  $\hat{\mathfrak{y}} \in \hat{\mathfrak{X}}$ . Applying 3) and 2), we get  $\omega(P\hat{\mathfrak{y}}) = \omega(\varphi(\hat{\mathfrak{y}}_{0,1})) \leq ||\hat{\mathfrak{y}}_{0,1}|| \leq \omega(\hat{\mathfrak{y}})$ , i.e.

4)  $\omega(P\hat{y}) \leq \omega(\hat{y})$ , for any  $\hat{y} \in \hat{x}$ . Hence, P can be extended by continuity to a continuous projection of  $\tilde{x}$  onto  $\varphi(\tilde{x})$ , that will be denoted by the same symbol.

Let now  $\tau \in R^+$ ; then for every  $\hat{y} \in \hat{x}$  we put

$$\begin{split} \tilde{\mathbf{T}}_{\tau} \, \hat{\mathbf{y}} &= (\mathbf{T}_{t} \quad \sum_{\mathbf{s},\mathbf{b}} \mathbf{T}_{\mathbf{s}+\tau} \, \mathbf{U}_{\mathbf{a}\mathbf{b}} \, \mathbf{y}_{\mathbf{s},\mathbf{b}})_{t,\mathbf{a}}^{\cdot} = (\mathbf{T}_{t} \quad \sum_{\sigma,\mathbf{b}} \mathbf{T}_{\sigma} \, \mathbf{U}_{\mathbf{a}\mathbf{b}} \, \mathbf{y}_{\sigma-\tau,\mathbf{b}})_{t,\mathbf{a}} = \\ &= (\mathbf{T}_{t} \quad \sum_{\sigma,\mathbf{b}} \mathbf{T}_{\sigma} \, \mathbf{U}_{\mathbf{a}\mathbf{b}} \, \boldsymbol{\xi}_{\sigma,\mathbf{b}})_{t,\mathbf{a}}^{\cdot} = \boldsymbol{\Theta}_{z} = \boldsymbol{\hat{\boldsymbol{\xi}}} \in \boldsymbol{\hat{\boldsymbol{x}}} , \end{split}$$

where we denote  $s + \tau = \sigma$ ;  $z_{\sigma,b} = y_{\sigma-\tau,b}$  for  $\sigma \ge \tau$  and  $z_{\sigma,b} = 0$ , for  $0 \le \sigma < \tau$ , with  $b \in a$ .

For every  $\hat{\mathbf{y}} \in \hat{\mathbf{x}}$ , denoting  $\Delta(\tau, \hat{\mathbf{y}}) = \{ \mathbf{\dot{z}} \in \mathbf{x}^{(\mathbb{R}^+ \times \mathfrak{a})} ; \mathbf{\dot{t}}_{\sigma,b} = \mathbf{y}_{\sigma-\tau,b}$  for  $\sigma \ge \tau$  and  $\mathbf{\dot{z}}_{\sigma,b} = 0$  for  $0 \le \sigma < \tau$ ,  $b \in \mathfrak{a}$ ,  $\mathbf{y} \in \Theta^{-1}(\{\hat{\mathbf{y}}\})\}$ , we see that  $\Delta(\tau, \hat{\mathbf{y}}) \subset \Theta^{-1}(\{\tilde{\mathbf{T}}_{\tau}, \hat{\mathbf{y}}\})$ . Then, we have  $\omega(\tilde{\mathbf{T}}_{\tau}, \hat{\mathbf{y}}) = \inf_{\mathbf{z} \in \Theta^{-1}(\{\tilde{\mathbf{T}}_{\tau}, \hat{\mathbf{y}}\})} \sum_{\sigma,b} \|\mathbf{x}_{b}\| \mathbf{\dot{z}}_{\sigma,b}\| \le \mathbf{z}_{\sigma,b}$ 

$$\begin{split} \inf & \sum_{\boldsymbol{\mathfrak{T}}_{\sigma}} \| \boldsymbol{\mathfrak{T}}_{\sigma} \| \boldsymbol{\mathfrak{K}}_{b} \| \boldsymbol{\mathfrak{Z}}_{\sigma,b} \| &= \inf \sum_{\boldsymbol{\mathfrak{T}}_{\sigma} | \boldsymbol{\mathfrak{T}}_{\sigma} \| \boldsymbol{\mathfrak{T}}_{\sigma} \| \boldsymbol{\mathfrak{K}}_{b} \| \boldsymbol{y}_{\sigma-\tau,b} \| \\ \boldsymbol{\mathfrak{T}}_{\varepsilon} \in \mathbb{C}^{1}(\{\tilde{\boldsymbol{\mathfrak{T}}}_{\tau} \hat{\boldsymbol{\mathfrak{y}}}\}) \quad \sigma, b &= \inf \sum_{\boldsymbol{y} \in \Theta^{-1}(\{\hat{\boldsymbol{\mathfrak{y}}}\}) \quad s, b} \| \boldsymbol{\mathfrak{T}}_{s+\tau} \| \boldsymbol{\mathfrak{K}}_{b} \| \boldsymbol{y}_{s,b} \| \leq \| \boldsymbol{\mathfrak{T}}_{\tau} \| \boldsymbol{\omega}(\hat{\boldsymbol{\mathfrak{y}}}), \text{ i.e.} \end{split}$$

5) 
$$\omega(\tilde{\mathbf{T}}_{\tau} \, \hat{\mathbf{y}}) \leq ||\mathbf{T}_{\tau}|| \, \omega(\hat{\mathbf{y}})$$
, for any  $\hat{\mathbf{y}} \in \hat{\mathbf{x}}$ 

Thus, for every  $\tau \in \mathbb{R}^+$ ,  $\tilde{\mathbb{T}}_{\tau}$  can be extended by continuity to an element of  $\mathfrak{B}(\mathfrak{X})$ , that will be denoted by the same symbol. Then, we see easily that  $P\tilde{\mathbb{T}}_{\tau} \phi(x) = \phi(\mathbb{T}_{\tau} x)$ , for any  $x \in \mathfrak{X}$ .

Hence  $\|\mathbf{T}_{\tau} \mathbf{x}\| = \omega(\phi(\mathbf{T}_{\tau} \mathbf{x})) = \omega(P\tilde{\mathbf{T}}_{\tau} \phi(\mathbf{x})) \leq \omega(\tilde{\mathbf{T}}_{\tau} \phi(\mathbf{x})) \leq \|\tilde{\mathbf{T}}_{\tau}\| \omega(\phi(\mathbf{x})) = \|\tilde{\mathbf{T}}_{\tau}\| \|\mathbf{x}\|$ , i.e.

6)  $\|\mathbb{T}_{\tau} x\| \leq \|\tilde{\mathbb{T}}_{\tau}\| \|x\|$ , for any  $x \in \mathfrak{X}$ . At last, we see easily that  $\{\tilde{\mathbb{T}}_{\tau}\}_{\tau \in \mathbb{R}}^+$  is a semi-group of operators, that we denote by  $\tilde{\Gamma}$ .

C) Let us define a representation V . Let  $\alpha\in \mathcal{C}$  ; then for every  $\widehat{y}\in\widehat{\mathfrak{X}}$  , we put

$$V_{\alpha} \hat{y} = (T_{t} \sum_{s,b} T_{s} U_{a\alpha b} y_{s,b})_{t,a} = (T_{t} \sum_{s,c} T_{s} U_{ac} \sum_{b \in \mathcal{A}_{c}} y_{s,b})_{t,a} =$$

$$= (T_{t} \sum_{s,c} T_{s} U_{ac} u_{s,c})_{t,a} = \Theta u = \hat{u} \in \hat{x} , \text{ where}$$

$$a_{c} = \{b \in a; ab = c\} \text{ and } u_{s,c} = \sum_{t \in \mathcal{A}_{c}} y_{s,b} , \text{ for } s \in \mathbb{R}^{+}, c \in a.$$

The map  $V_{\alpha} : \hat{\mathfrak{X}} \to \hat{\mathfrak{X}}$  is well defined. Indeed, let  $\hat{y}^{1} = \hat{y}^{2} \in \hat{\mathfrak{X}}$ ; then there exists  $y^{1}$ ,  $y^{2} \in \mathfrak{X}^{(\mathbb{R}^{+} \times \mathbb{Q})}$  such that  $\hat{y}^{1} = \Theta y^{1}$  and  $\hat{y}^{2} = \Theta y^{2}$ , hence  $T_{t} \overset{\Sigma}{\underset{s,b}{}} T_{s} U_{ab} y^{1}_{s,b} = T_{t} \overset{\Sigma}{\underset{s,b}{}} T_{s} U_{ab} y^{2}_{s,b}$ , for any  $t \in \mathbb{R}^{+}$ ,  $a \in \mathbb{Q}$ .

Then,  $T_t \underset{s,b}{\Sigma} T_s U_{a'b} y_{s,b}^1 = T_t \underset{s,b}{\Sigma} T_s U_{a'b} y_{s,b}^2$ , for  $t \in \mathbb{R}^+$  and  $a' = a \alpha \in \mathcal{A}$ with  $a \in \mathcal{A}$ . We see easily that for every  $\alpha \in \mathcal{A}$ ,  $V_{\alpha} : \hat{x} \to \hat{x}$  is a linear map and  $V_1 \hat{y} = \hat{y}$ , for any  $\hat{y} \in \hat{x}$ . Moreover,  $V : \mathcal{A} \to \mathcal{L}(\hat{x})$  is a representation (see [4]; for a vector space X,  $\mathcal{L}(X)$  denotes the algebra of all linear maps of X into X). Now, we prove that,  $V_{\alpha} : \hat{x} \to \hat{x}$  is continuous, for every  $\alpha \in \mathcal{A}$ . Let  $\alpha \in \mathcal{A}$ ,  $\hat{y} \in \hat{x}$  and  $\Delta(\alpha, \hat{y}) = \{u \in \hat{x}^{(\mathbb{R}^+ \times \mathcal{A})}; u_{s,c} = \sum_{b \in \mathcal{A}_c} y_{s,b}, y \in \Theta^{-1}(\{\hat{y}\})\}$ , then we see  $\Delta(\alpha, \hat{y}) \subset \Theta^{-1}(\{V_{\alpha}, \hat{y}\})$ . Therefore, we have :

$$\begin{split} & \omega(\mathbb{V}_{\alpha} \ \hat{\mathbf{y}}) = \inf_{\substack{\mathbf{u} \in \Theta^{-1}(\{\mathbb{V}_{\alpha} \hat{\mathbf{y}}\}) \quad \mathbf{s}, \mathbf{c}}} \mathbb{I}_{\mathbf{s}} \| \mathbf{K}_{\mathbf{b}} \| \mathbf{u}_{\mathbf{s}, \mathbf{c}} \| \leq \\ & \leq \inf_{\substack{\mathbf{u} \in \Delta(\alpha, \hat{\mathbf{y}}) \quad \mathbf{s}, \mathbf{c}}} \| \mathbf{T}_{\mathbf{s}} \| \mathbf{K}_{\mathbf{c}} \| \mathbf{u}_{\mathbf{s}, \mathbf{c}} \| = \inf_{\substack{\mathbf{y} \in \Theta^{-1}(\{\hat{\mathbf{y}}\}) \quad \mathbf{s}, \mathbf{c}}} \mathbb{I}_{\mathbf{s}} \| \mathbf{K}_{\mathbf{c}} \| \sum_{\substack{\mathbf{b} \in \mathcal{A}_{\mathbf{c}}}} \mathbf{y}_{\mathbf{s}, \mathbf{b}} \| \leq \\ & \leq \inf_{\substack{\mathbf{v} \in \Theta^{-1}(\{\hat{\mathbf{y}}\}) \quad \mathbf{s}, \mathbf{b}}} \mathbb{E} \| \mathbf{T}_{\mathbf{s}} \| \mathbf{K}_{\alpha \mathbf{b}} \| \mathbf{y}_{\mathbf{s}, \mathbf{b}} \| \leq K_{\alpha} \quad \inf_{\substack{\mathbf{y} \in \Theta^{-1}(\{\hat{\mathbf{y}}\}) \quad \mathbf{s}, \mathbf{b}}} \mathbb{E} \| \mathbf{T}_{\mathbf{s}} \| \mathbf{K}_{\mathbf{b}} \| \mathbf{y}_{\mathbf{s}, \mathbf{b}} \| = K_{\alpha} \omega(\hat{\mathbf{y}}); \end{split}$$
  
i.e. for every  $\alpha \in \mathcal{A}$  we get

7)  $\omega(\mathbb{V}_{\alpha}|\hat{\mathbf{y}}) \leq \mathbb{K}_{\alpha} \omega(\hat{\mathbf{y}})$ , for any  $\hat{\mathbf{y}} \in \hat{\mathbf{x}}$ . Hence,  $\mathbb{V}_{\alpha}$  can be extended by continuity to an element of  $\mathfrak{g}(\tilde{\mathbf{x}})$  that will be denoted by  $\mathbb{V}_{\alpha}$ , for every  $\alpha \in \mathfrak{a}$ .

Thus, (0) is completely proved. The property (i) is immediate, since for every  $\alpha \in \alpha$  and  $\tau \in \mathbb{R}^+$ , we have  $\tilde{T}_{\tau} V_{\alpha} \hat{y} = (T_t \sum_{s,b} T_{s+\tau} U_{a\alpha b} y_{s,b})_{t,a} = V_{\alpha} \tilde{T}_{\tau} \hat{y}$ , for any  $\hat{y} \in \hat{x}$ . Using the definitions of  $\varphi$ , P, V<sub>a</sub> and  $\tilde{T}_{\tau}$ , for  $\alpha \in \alpha, \tau \in \mathbb{R}^+$ , we obtain immediately (ii), (iii) and (v).

D) Let us prove (iv). From  $\tilde{T}_{s} \phi(x) = (T_{t} T_{s} U_{a} x)_{t,a}$  and  $\phi(T_{s} x) = (T_{t} U_{a} T_{s} x)_{t,a}$ , we see that 1° and 3° are equivalent.

Now chosing  $\alpha = 1$  in 2°, and using  $P\tilde{T}_{\tau} \phi(x) = \phi(T_{\tau} x)$  for  $\tau \in R^+$ ,  $x \in \mathfrak{X}$  (see (ii)), we get 1°.

Conversely, taking into account of (ii) and writting 1° with  $U_{\alpha} \times ins-$ tead of x, for  $\alpha \in a$ , we get 2°.

At last, we show (vi). Let  $\sigma \in \mathbb{R}^+$ , and  $\beta \in \mathcal{Q}$ , as in the assumption, also let  $n \in \mathbb{N}$  and  $\widehat{y} \in \widehat{x}$ ; then, we write :

$$(\tilde{\mathbf{T}}_{\sigma} - \mathbf{v}_{\beta})^{n} \hat{\mathbf{y}} = \sum_{k=0}^{n} (-1)^{n-k} {n \choose k} \tilde{\mathbf{T}}_{\sigma}^{k} \mathbf{v}_{\beta}^{n-k} \hat{\mathbf{y}} =$$

$$= \sum_{k=0}^{n} (-1)^{n-k} {n \choose k} (\mathbf{T}_{t} \sum_{s,b} \mathbf{T}_{s} \mathbf{U}_{ab} \mathbf{T}_{\sigma}^{k} \mathbf{U}_{\beta}^{n-k} \mathbf{y}_{s,b})_{t,a} = \Theta \mathbf{v} = \hat{\mathbf{v}} \in \hat{\mathbf{x}}$$

where v is defined by

$$\mathbf{v}_{s,b} = \sum_{k=0}^{n} (-1)^{n-k} {n \choose k} \mathbf{T}_{\sigma}^{k} \mathbf{U}_{\beta}^{n-k} \mathbf{y}_{s,b} , \text{ for } \mathbf{y} \in \mathbb{Q}^{-1}(\{\hat{\mathbf{y}}\}) , s \in \mathbb{R}^{+} , \text{ and}$$

b€û .

Denoting by  $\Delta(\sigma,\,\beta,\,n,\,\hat{y})$  = the set of all element  $\,v\,$  so defined, we see that :

$$\Delta (\sigma, \beta, n, \hat{y}) \subset \Theta^{-1} (\{ \tilde{T}_{\sigma} - V_{\beta} \}^{n} \hat{y} \}).$$

Then, we have :

$$\begin{split} & \omega(\left(\tilde{\mathbf{T}}_{\sigma} - \mathbf{V}_{\beta}\right)^{n} \ \hat{\mathbf{y}}) = \inf_{\substack{\mathbf{v} \in \Theta^{-1}\left(\left\{\tilde{\mathbf{T}}_{\sigma} - \mathbf{V}_{\beta}\right)^{n} \cdot \hat{\mathbf{y}}\right\}\right) \\ \mathbf{v} \in \Theta^{-1}\left(\left\{\tilde{\mathbf{T}}_{\sigma} - \mathbf{V}_{\beta}\right)^{n} \cdot \hat{\mathbf{y}}\right\}\right) \\ & \leq \inf_{\substack{\mathbf{v} \in \Delta(\sigma, \beta, n, \hat{\mathbf{y}}) \\ \mathbf{v} \in \Delta(\sigma, \beta, n, \hat{\mathbf{y}}) \\ \mathbf{y} \in \Theta^{-1}\left(\left\{\tilde{\mathbf{y}}\right\}\right) \\ \mathbf{s}, \mathbf{b} \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{K}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{K}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{K}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{s}} \| \mathbf{x}_{\mathbf{b}} \| \\ \mathbf{x} = 0 \\ \end{bmatrix} \\ \begin{bmatrix} \mathbf{T}_{\mathbf{$$

 $= \left\| \begin{smallmatrix} n \\ \Sigma \\ k=0 \end{smallmatrix} \right|^{n-k} \begin{pmatrix} n \\ k \end{smallmatrix} ) \left\| \begin{smallmatrix} n \\ \sigma \end{bmatrix}_{\sigma}^{k} \bigcup_{\beta}^{n-k} \left\| \begin{smallmatrix} \omega(\hat{y}) \end{smallmatrix} \right\| \text{ Therefore, for every } n \in \mathbb{N} \text{ ,}$ 

we have  $\omega((\tilde{T}_{\sigma} - V_{\beta})^{n} \hat{y}) \leq || (\tilde{T}_{\sigma} - U_{\beta})^{n} || \omega(\hat{y})$ , for any  $\hat{y} \in \hat{x}$ ; hence  $|| (\tilde{T}_{\sigma} - V_{\beta})^{n} || \leq || (T_{\sigma} - U_{\beta})^{n} ||$ . Conversely, since  $(\tilde{T}_{\sigma} - V_{\beta})^{n} \phi(x) = \phi((T_{\sigma} - U_{\beta})^{n} x)$ , for any  $x \in \mathfrak{X}$ , we get easily  $|| (\tilde{T}_{\sigma} - V_{\beta})^{n} || \leq || (T_{\sigma} - U_{\beta})^{n} ||$ .

DEFINITION. - Let {  $\mathfrak{X}$ ,  $\Gamma$ , U} be an object, where  $\mathfrak{X}$  is a Banach space,  $\Gamma = \{T_t\}_{t \in \mathbb{R}^+} \subset \mathfrak{G}(\mathfrak{X})$  a semi-group of operators and  $U: \mathcal{A} \rightarrow \mathfrak{G}(\mathfrak{X})$  a linear map as in the above theorem. Then, an object {  $\tilde{\mathfrak{X}}$ ,  $\varphi$ , P,  $\tilde{\Gamma}$ , V} where  $\tilde{\mathfrak{X}}$  is a Banach space,  $\varphi$  a bicontinuous isomorphism of  $\mathfrak{X}$  into  $\tilde{\mathfrak{X}}$ , P a continuous projection of  $\tilde{\mathfrak{X}}$  onto  $\varphi(\mathfrak{X})$ ,  $\tilde{\Gamma} = \{\tilde{T}_t\}_{t \in \mathbb{R}^+} \subset \mathfrak{G}(\tilde{\mathfrak{X}})$  a semi-group of operators and  $V: \mathcal{A} \rightarrow \mathfrak{G}(\tilde{\mathfrak{X}})$  a representation such that  $V_1 = \tilde{I}$ ,  $V_{\alpha} \tilde{T}_{\tau} = \tilde{T}_{\tau} V_{\alpha}$ , for any  $\alpha \in \mathcal{A}$ ,  $\tau \in \mathbb{R}^+$ , is called an  $\mathcal{A}$ -spectral dilation of {  $\mathfrak{X}$ ,  $\Gamma$ , U} if the property (ii) is satisfyed. An  $\mathcal{A}$ -spectral dilation is called minimal if also we have (iii).

<u>Remark 1</u>. - When  $\mathcal{C}$  is a Michael algebra and  $U : \mathcal{C} \to \mathcal{B}(\mathfrak{X})$  a linear continuous map, then K is the seminorm which estimates U.

<u>Remark 2.</u> - Let  $T \in B(\mathfrak{X})$ ; then the above theorem is obviously true with  $\{T^n\}_{n \in \mathbb{N}}$  instead of  $\{T_t\}_{t \in \mathbb{R}^+}$ .

Application. - Let  $\mathcal{U}$  be an admissible algebra in the sense of [1]. Then, an operator  $\mathbf{T} \in \mathcal{B}(\mathfrak{X})$  is called  $\mathcal{U}$ -subspectral (see [9]) if there is a Banach space containing  $\mathfrak{X}$  as a closed subspace, a continuous projection P of  $\mathfrak{X}$  onto  $\mathfrak{X}$ , a  $\mathcal{U}$ -spectral operator  $\mathbf{T} \in \mathcal{B}(\mathfrak{X})$  having a  $\mathcal{U}$ -spectral representation  $\mathbf{V} : \mathcal{Q} \to \mathcal{B}(\mathfrak{X})$  with the properties  $\mathbf{V}_{\mathbf{Z}} \mathfrak{I} \subset \mathfrak{X}$  and  $\tilde{\mathrm{PTV}}_{\mathbf{f}} \mathbf{x} = \tilde{\mathrm{TPV}}_{\mathbf{f}} \mathbf{x}$ , for any  $\mathbf{f} \in \mathcal{U}$ ,  $\mathbf{x} \in \mathfrak{X}$ , such that  $\mathbf{T}|_{\mathfrak{X}} = \mathbf{T}$ .

We have the following characterization for  $\mathcal{U}$ -subspectral operators : an operator  $T \in \mathfrak{g}(\mathfrak{X})$  is  $\mathcal{U}$ -subspectral if and only if there is a linear map  $U : \mathcal{U} \rightarrow \mathfrak{g}(\mathfrak{X})$  with the properties :

- (1)  $U_{1} = I$ ,
- (2)  $U_{f_z} = U_f U_z$ ,
- (3)  $\|U_{\mathbf{r}}\| \leq M L_{\mathbf{r}}$  for any  $f \in \mathcal{U}$ ,

(where M is a positive constant and  $L: \mathcal{U} \rightarrow \mathcal{B}(\mathcal{Y})$ , a linear map satisfying

(j)  $\|L_{f\sigma}\| \leq \|L_{f}\| \|L_{\sigma}\|$ , for any f,  $g \in \mathcal{U}$  and the function

(jj)  $\xi \neq L_{f\xi}$  is analytic in  $\int supp f$ , for every  $f \in \mathcal{U}$ ;

 $\mathcal{Y}$  is a Banach space), such that  $TU_f = U_f T$ , for any  $f \in \mathcal{U}$  and  $U_z \sim T$ , (see [8] and [9]).

If  $\mathcal{U}$  is an admissible topologic algebra with the topology of Michael algebra, then the property (3) of U is replaced by its continuity.

For instance, let  $\forall = \{z \in C \ |z| = 1\}$ ; one denotes by  $L^p(\gamma)(p < \infty)$ the Banach space of the all complex-valued functions f on  $\gamma$  such that  $|f|^p$  is integrable with respect to the Lebesgue measure. (Thus a function  $f \in L^p(\gamma)$  if and only if the function  $\tilde{f}$  defined by  $\tilde{f}(\theta) = f(e^{i\theta})$  for  $\theta \in [-\pi, +\pi]$  belongs to  $L^p(\frac{1}{2\pi} - d\theta))$ .

In the same way one considers the Banach algebra  $L^{\infty}(\gamma)$  of all complexvalued essential bounded functions with respect to the Lebesgue measure on  $\gamma$ , (i.e. a function  $f \in L^{\infty}(\gamma)$  if and only if the function  $\tilde{f}$  defined by  $\tilde{f}(\theta) = f(e^{i\theta})$  belongs to  $L^{\infty}(\frac{1}{2\pi} d\theta))$ .

Let  $p \ge 1$ , as usual, the space  $H^p$  is the set of analytic functions in  $D = \{z \ ; \ |z| < 1\}$  such that  $f_r$  defined by  $f_r(\theta) = f(re^{i\theta})$ , for  $\theta \in [-\pi, +\pi]$ , belongs to  $L^p(\frac{1}{2\pi} d\theta)$  for every  $0 \le r \le 1$ , or with the other words,  $H^p$  is a closed subspace of functions f of  $L^p(\gamma)$  such that  $\int_{-\pi}^{+\pi} e^{in\theta} f(e^{i\theta}) = d\theta = 0$ ,  $n = 1, 2, 3, \dots$ 

Taking  $\mathfrak{X} = L^p(Y)$  and  $\mathcal{U} = L^{\infty}(Y)$ , we define a representation  $V : \mathcal{U} \to \mathfrak{G}(\mathfrak{X})$  by :

 $V_{\!\phi}$  f =  $\phi$  f , for every  $\phi \, \in \, L^{\infty}(Y)$  ,  $f \in \, L^{p}(Y)$  .

From the theorem of M. Riesz ([3], cap. IX) we have  $L^p(\gamma) = H^p \oplus \overline{H}^p_{O}$ , l \infty, where  $\overline{H}^p_{O}$  is the space of complex-conjugate functions of  $H^p$  becoming zero at z = 0. Let P be the continuous projection of  $L^p(\gamma)$  onto  $H^p$ . We define the continuous linear map U :  $L^{\infty}(\gamma) \rightarrow \mathfrak{g}(H^p)$  by :

 $U_{_{\!C\!N}} \ f$  = P  $V_{_{\!C\!N}} \ f$  , for every  $\phi \in L^{^{\infty}}(\gamma)$  ,  $f \in H^{^{\rm D}}$  .

Obviously, U is a continuous linear map with the above properties (1) and (2). Then an operator  $T \in \mathfrak{g}(H^p)$  such that  $U_{\varphi} T = T U_{\varphi}$ , for  $\varphi \in L^{\infty}(\gamma)$  and  $T \sim U_{e^{i\theta}}$  is a  $L^{\infty}(\gamma)$ -subspectral operator. For p = 2,  $V_{e^{i\theta}}$  is the bilateral shift and  $U_{e^{i\theta}}$  is the unilateral shift (see [2]).

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