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# $K(\pi, 1)$ conjecture for Artin groups 

Luis Paris ${ }^{(1)}$


#### Abstract

The purpose of this paper is to put together a large amount of results on the $K(\pi, 1)$ conjecture for Artin groups, and to make them accessible to non-experts. Firstly, this is a survey, containing basic definitions, the main results, examples and an historical overview of the subject. But, it is also a reference text on the topic that contains proofs of a large part of the results on this question. Some proofs as well as few results are new. Furthermore, the text, being addressed to non-experts, is as self-contained as possible.

Résumé. - Le but de cet article est de mettre ensemble une grande partie des résultats connus sur la conjecture du $K(\pi, 1)$ pour les groupes d'Artin et de les rendre accessibles aux non-spécialistes. Tout d'abord, ce texte est un exposé, contenant les définitions de base, les principaux résultats, des exemples et un aperçu historique. C'est aussi un texte qui devrait servir de référence dans le sujet et qui contient des démonstrations de la plupart des résultats énoncés. Certaines démonstrations et quelques résultats sont nouveaux. En outre, le texte, s'adressant à des non-spécialistes, est aussi complet que possible.


## Introduction

Let $X$ be a CW-complex (or a manifold having the same homotopy type as a CW-complex), and let $G$ be a discrete group. We say that $X$ is an Eilenberg MacLane space for $G$ if the universal cover of $X$ is contractible and its fundamental group is $G$. From an Eilenberg MacLane space for $G$ one can easily construct a free resolution of the group algebra $\mathbb{Z} G$ of $G$, thus one gets a way for calculating different (co)homologies of $G$ (see [6]).

[^0]It has been proved in the 60's that the space of configurations of $n$ points in the plane is an Eilenberg MacLane space for the braid group on $n$ strands (see [29]), and this fact has been the starting point for the calculation of the cohomology of this group $[2,30,17,47,53]$. Starting from the observation that the space of configurations of $n$ points in the plane coincides with the complement in $\mathbb{C}^{n}$ of a well-known algebraic set, the discriminant, in the 70 's and 80 's the construction of this space has been extended to all Artin groups as follows.

By [3], it is known that any Coxeter group acts faithfully on an open nonempty convex cone $I$ so that the union of the regular orbits is the complement in $I$ of a (possibly infinite) family of linear hyperplanes. More generally, by [54], if $W$ is a reflection group in Vinberg's sense (see Section 1), then $W$ is a Coxeter group, and it acts faithfully on an open nonempty convex cone $I$ so that the union of the regular orbits is the complement in $I$ of a (possibly infinite) family $\mathcal{A}$ of linear hyperplanes. By [35], the fundamental group of the space

$$
N(W)=\left((I \times I) \backslash\left(\bigcup_{H \in \mathcal{A}}(H \times H)\right)\right) / W
$$

is the Artin group $A$ associated to $W$. The $K(\pi, 1)$ conjecture, due to Arnold, Brieskorn, Pham, and Thom, says that $N(W)$ is an Eilenberg MacLane space for $A$.

The purpose of this paper is to put together a large amount of results on this conjecture and to make them accessible to non-experts. Firstly, this is a survey, containing basic definitions, the main results, examples and an historical overview of the subject. But, it is also a reference text on the topic that contains proofs of a large part of the results on this question. Some proofs as well as few results are new. Furthermore, the text, being addressed to non-experts, is as self-contained as possible.

The paper is organized as follows. In Section 1 we give a precise and detailed presentation of the $K(\pi, 1)$ conjecture, with basic definitions, preliminaries, and examples. Afterwards, we give an overview of the history of this question and of the cases for which the conjecture has been proved. Section 2 contains preliminaries on algebraic topology, Coxeter groups, Vinberg's reflection groups, and Artin monoids.

Section 3 is dedicated to a key tool of the theory: the Salvetti complexes. In Subsection 3.1 we define the Salvetti complex of a (possibly infinite) arrangement $\mathcal{A}$ of hyperplanes in an nonempty open convex cone $I$, and we prove that this complex has the same homotopy type as the complement
of $\cup_{H \in \mathcal{A}}(H \times H)$ in $I \times I$. This construction as well as the proof of this result are new, although they have been more or less known to experts. In Subsection 3.2 we prove that, when $\mathcal{A}$ is determined by a reflection group $W$ in Vinberg's sense, then our complex coincides with the Salvetti complex defined by Charney and Davis in [14]. In Subsection 3.3 we determine some cellular decompositions of the Salvetti complexes that we use, in particular, to show that the fundamental group of the above defined space $N(W)$ is equal to the Artin group associated to $W$.

In Section 4 we reprove Deligne's theorem [26] which says that the $K(\pi, 1)$ conjecture holds if $W$ is finite. The proof is made in a general framework in the sense that we use that $W$ is finite only in the last paragraph of the proof. However, we do not know how to adapt the proof in other cases.

In Section 5 we study a series of results related to the $K(\pi, 1)$ conjecture and to the so-called parabolic subgroups of Artin groups. In particular, we reprove a result by Charney and Davis [13] which says that the $K(\pi, 1)$ conjecture holds for Artin groups of FC type.

## 1. Basic definitions, statements, and examples

Let $S$ be a finite set. A Coxeter matrix over $S$ is a square matrix $M=$ $\left(m_{s, t}\right)_{s, t \in S}$ indexed by the elements of $S$ and satisfying (a) $m_{s, s}=1$ for all $s \in S$; (b) $m_{s, t}=m_{t, s} \in\{2,3, \ldots\} \cup\{\infty\}$ for all $s, t \in S, s \neq t$. A Coxeter matrix is usually represented by its Coxeter graph, $\Gamma=\Gamma(M)$. This is a labelled graph defined as follows. The set of vertices of $\Gamma$ is $S$. Two vertices $s, t \in S$ are joined by an edge if $m_{s, t} \geqslant 3$, and this edge is labelled by $m_{s, t}$ if $m_{s, t} \geqslant 4$.

Let $\Gamma$ be a Coxeter graph. The Coxeter system of $\Gamma$ is defined to be the pair $(W, S)=\left(W_{\Gamma}, S\right)$, where $S$ is the set of vertices of $\Gamma$, and $W$ is the group presented as follows.

$$
W=\left\langle S \left\lvert\, \begin{array}{cl}
s^{2}=1 & \text { for all } s \in S \\
(s t)^{m_{s, t}}=1 & \text { for all } s, t \in S, s \neq t, m_{s, t} \neq \infty
\end{array}\right.\right\rangle
$$

The group $W$ is called Coxeter group of $\Gamma$.
Remark. - It is shown in [3] that, for $s, t \in S, s \neq t$, the element $s t$ is of infinite order if $m_{s, t}=\infty$, and it is of order precisely $m_{s, t}$ if $m_{s, t} \neq \infty$. Hence, the pair $(W, S)$ entirely determines the Coxeter graph $\Gamma$.

If $a, b$ are two letters and $m$ is an integer greater or equal to 2 , we set $\Pi(a, b: m)=(a b)^{\frac{m}{2}}$ if $m$ is even, and $\Pi(a, b: m)=(a b)^{\frac{m-1}{2}} a$ if $m$ is odd.

Let $\Sigma=\left\{\sigma_{s} ; s \in S\right\}$ be an abstract set in one-to-one correspondence with $S$. The Artin system of $\Gamma$ is defined to be the pair $(A, \Sigma)$, where $A=A_{\Gamma}$ is the group presented as follows.
$A=\langle\Sigma| \Pi\left(\sigma_{s}, \sigma_{t}: m_{s, t}\right)=\Pi\left(\sigma_{t}, \sigma_{s}: m_{s, t}\right)$ for all $s, t \in S, s \neq t$ and $\left.m_{s, t} \neq \infty\right\rangle$.
The group $A_{\Gamma}$ is called Artin group of $\Gamma$.
It is easily shown that the Coxeter group of $\Gamma$ admits the following presentation.
$W_{\Gamma}=\left\langle S \left\lvert\, \begin{array}{cl}s^{2}=1 & \text { for all } s \in S \\ \Pi\left(s, t: m_{s, t}\right)=\Pi\left(t, s: m_{s, t}\right) & \text { for all } s, t \in S, s \neq t, m_{s, t} \neq \infty\end{array}\right.\right\rangle$.
Hence, the map $\Sigma \rightarrow S, \sigma_{s} \mapsto s$, induces an epimorphism $\theta: A_{\Gamma} \rightarrow W_{\Gamma}$. The kernel of $\theta$ is called colored Artin group of $\Gamma$ and it is denoted by $C A_{\Gamma}$.

Example. - Consider the Coxeter graph $\mathbb{A}_{n}$ drawn in Figure 1.1. The Coxeter group of $\mathbb{A}_{n}$ has the following presentation.

$$
\left\langle\begin{array}{c|cl}
s_{1}, \ldots, s_{n} & \text { for } 1 \leqslant i \leqslant n \\
s_{i}^{2}=1 & \text { for } 1 \leqslant i \leqslant n-1 \\
\left(s_{i} s_{i+1}\right)^{3}=1 & \text { for } \\
\left(s_{i} s_{j}\right)^{2}=1 & \text { for }|i-j| \geqslant 2
\end{array}\right\rangle .
$$

This is the symmetric group $\mathfrak{S}_{n+1}$ (of permutations of $\{1, \ldots, n+1\}$ ). The Artin group of $\mathbb{A}_{n}$ has the following presentation.

$$
\left\langle\begin{array}{c|cl}
\sigma_{1}, \ldots, \sigma_{n} & \sigma_{i} \sigma_{i+1} \sigma_{i}=\sigma_{i+1} \sigma_{i} \sigma_{i+1} & \text { for } 1 \leqslant i \leqslant n-1 \\
\sigma_{i} \sigma_{j}=\sigma_{j} \sigma_{i} & \text { for }|i-j| \geqslant 2
\end{array}\right\rangle .
$$

This is the braid group $\mathcal{B}_{n+1}$ on $n+1$ strands. The colored Artin group of $\mathbb{A}_{n}$ is the pure braid group $\mathcal{P} \mathcal{B}_{n+1}$.


Figure 1.1. - The Coxeter graph $\mathbb{A}_{n}$

Take a nonempty open convex cone $I$ in a finite dimensional real vector space $V$. We define a hyperplane arrangement in $I$ to be a (possibly infinite) family $\mathcal{A}$ of linear hyperplanes of $V$ satisfying (a) $H \cap I \neq \emptyset$ for all $H \in \mathcal{A}$; (b) $\mathcal{A}$ is locally finite in $I$, that is, for all $x \in I$, there is an open neighborhood $U_{x}$ of $x$ in $I$ such that the set $\left\{H \in \mathcal{A} \mid H \cap U_{x} \neq \emptyset\right\}$ is finite. Note that the "classical" definition of hyperplane arrangement imposes $I=V$ and $\mathcal{A}$ finite (see [39]).

$$
K(\pi, 1) \text { conjecture for Artin groups }
$$

Example. - Set $V=\mathbb{R}^{3}$ and $I=\{(x, y, z) \in V \mid z>0\}$. For $k \in \mathbb{Z}$, we denote by $H_{k}$ the plane of $V$ of equation $x=k z$, and we denote by $H_{k}^{\prime}$ the plane of equation $y=k z$. We set $\mathcal{A}=\left\{H_{k}, H_{k}^{\prime} \mid k \in \mathbb{Z}\right\}$. This is a hyperplane arrangement in $I$. The trace of $\mathcal{A}$ on the affine plane of equation $z=1$ is represented in Figure 1.2.


Figure 1.2. - A hyperplane arrangement

Let $V$ be a finite dimensional real vector space. A reflection on $V$ is defined to be a linear transformation on $V$ of order 2 which fixes a hyperplane. Attention: there is no hypothesis on the orthogonality of the reflection, hence the fixed hyperplane does not necessarily determine the reflection. Let $\bar{C}_{0}$ be a closed convex polyhedral cone in $V$ with nonempty interior, and let $C_{0}$ be the interior of $\bar{C}_{0}$. A wall of $\bar{C}_{0}$ is the support of a (codimensional 1) face of $\bar{C}_{0}$, that is, a hyperplane of $V$ generated by that face. Let $H_{1}, \ldots, H_{n}$ be the walls of $\bar{C}_{0}$. For each $i \in\{1, \ldots, n\}$ we take a reflection $s_{i}$ which fixes $H_{i}$, and we denote by $W$ the subgroup of GL $(V)$ generated by $S=\left\{s_{1}, \ldots, s_{n}\right\}$. The pair $(W, S)$ is called a Vinberg system if $w C_{0} \cap C_{0}=\emptyset$ for all $w \in W \backslash\{1\}$. In that case, the group $W$ is called linear reflection group in Vinberg's sense, $S$ is called canonical generating system for $W$, and $C_{0}$ is called fundamental chamber of $(W, S)$.

Linear reflection groups, Coxeter groups and hyperplane arrangements are linked by the following theorem.

Theorem 1.1 (Vinberg [54]). - Let $(W, S)$ be a Vinberg system. We keep the above notations, and we set

$$
\bar{I}=\bigcup_{w \in W} w \bar{C}_{0}
$$

Then the following statements hold.
(1) $(W, S)$ is a Coxeter system.
(2) $\bar{I}$ is a convex cone with nonempty interior.
(3) The interior $I$ of $\bar{I}$ is stable under the action of $W$, and $W$ acts properly discontinuously on $I$.
(4) Let $x \in I$ be such that $W_{x}=\{w \in W \mid w(x)=x\}$ is different from $\{1\}$. Then there exists a reflection $r$ in $W$ such that $r(x)=x$.

The above cone $I$ is called Tits cone of the Vinberg system $(W, S)$.
Remark. - The reader must pay attention to the fact that there is a difference in Theorem 1.1.(1) between the pair $(W, S)$, viewed as a Vinberg system, and the pair ( $W, S$ ), viewed a Coxeter system. Indeed, in the first case, $W$ is some specific subgroup of a linear group, while, in the second case, $W$ is just an abstract group. Note also that any Coxeter system appears as a Vinberg system (see Theorem 2.5), but this representation is not unique in general.

Let $(W, S)$ be a Vinberg system. Denote by $\mathcal{R}$ the set of reflections belonging to $W$. For $r \in \mathcal{R}$ we denote by $H_{r}$ the fixed hyperplane of $r$, and we set $\mathcal{A}=\left\{H_{r} \mid r \in \mathcal{R}\right\}$. Then, by Theorem 1.1, $\mathcal{A}$ is a hyperplane arrangement in the Tits cone $I$. It is called Coxeter arrangement of $(W, S)$.

Example. - Consider the symmetric group $\mathfrak{S}_{n+1}$ acting on the space $V=\mathbb{R}^{n+1}$ by permutations of the coordinates. Let

$$
\bar{C}_{0}=\left\{x \in V \mid x_{1} \leqslant x_{2} \leqslant \cdots \leqslant x_{n+1}\right\}
$$

For $i, j \in\{1, \ldots, n+1\}, i \neq j$, we denote by $H_{i, j}$ the hyperplane of equation $x_{i}=x_{j}$. Then $\bar{C}_{0}$ is a convex polyhedral cone whose walls are $H_{1,2}, H_{2,3}, \ldots, H_{n, n+1}$. For $i \in\{1, \ldots, n\}, s_{i}=(i, i+1)$ is a reflection whose fixed hyperplane is $H_{i, i+1}$. Then $\left(\mathfrak{S}_{n+1},\left\{s_{1}, \ldots, s_{n}\right\}\right)$ is a Vinberg system. In this case we have

$$
\bar{I}=\bigcup_{w \in \mathfrak{S}_{n+1}} w \bar{C}_{0}=V
$$

So, $I=V$, too. The set $\mathcal{R}$ of reflections coincides with the set of transpositions, thus $\mathcal{A}=\left\{H_{i, j} \mid 1 \leqslant i<j \leqslant n+1\right\}$ is the so-called braid arrangement.

Example. - Consider the affine Euclidean plane $\mathbb{E}^{2}$. For $k \in \mathbb{Z}$, we denote by $D_{k}$ the affine line of equation $x=k$, and we denote by $D_{k}^{\prime}$ the

$$
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$$

affine line of equation $y=k$ (see Figure 1.3). We denote by $s_{k}$ the orthogonal affine reflection of $\mathbb{E}^{2}$ with respect to the line $D_{k}$, and we denote by $s_{k}^{\prime}$ the orthogonal affine reflection with respect to $D_{k}^{\prime}$. We denote by $W$ the subgroup of the orthogonal affine group of $\mathbb{E}^{2}$ generated by $\left\{s_{k}, s_{k}^{\prime} \mid k \in \mathbb{Z}\right\}$. We leave to the reader to determine all the elements of $W$. Say, however, that, among these elements, in addition to the reflections, there are U-turns, translations, and glide reflections. It is easily shown that $W$ is generated by $s_{0}, s_{1}, s_{0}^{\prime}, s_{1}^{\prime}$ and admits the following presentation.

$$
\begin{aligned}
& W=\left\langle s_{0}, s_{1}, s_{0}^{\prime}, s_{1}^{\prime}\right| s_{0}^{2}=s_{1}^{2}=s_{0}^{\prime 2}=s_{1}^{\prime 2}=1 \\
& \left.\quad\left(s_{0} s_{0}^{\prime}\right)^{2}=\left(s_{0} s_{1}^{\prime}\right)^{2}=\left(s_{1} s_{0}^{\prime}\right)^{2}=\left(s_{1} s_{1}^{\prime}\right)^{2}=1\right\rangle
\end{aligned}
$$

This is the Coxeter group of the Coxeter graph drawn in Figure 1.4.


Figure 1.3. - Grid lines in the affine plane


Figure 1.4. - A Coxeter graph
We embed $\mathbb{E}^{2}$ in $\mathbb{R}^{3}$ via the map $(x, y) \mapsto(x, y, 1)$, and we denote by $\operatorname{Aff}\left(\mathbb{E}^{2}\right)$ the affine group of $\mathbb{E}^{2}$. Recall that, for all $f \in \operatorname{Aff}\left(\mathbb{E}^{2}\right)$, there are a unique linear transformation $f_{0} \in \mathrm{GL}\left(\mathbb{R}^{2}\right)$ and a unique vector $u \in \mathbb{R}^{2}$ such that $f=T_{u} \circ f_{0}$, where $T_{u}$ denotes the translation relative to $u$. Recall also that there is an embedding $\operatorname{Aff}\left(\mathbb{E}^{2}\right) \hookrightarrow \mathrm{GL}\left(\mathbb{R}^{3}\right)$ defined by

$$
f \mapsto\left(\begin{array}{cc}
f_{0} & u \\
0 & 1
\end{array}\right)
$$

Note that the elements of $\operatorname{Aff}\left(\mathbb{E}^{2}\right)$, embedded in $\operatorname{GL}\left(\mathbb{R}^{3}\right)$ via the above map, leave invariant $\mathbb{E}^{2}$ embedded into $\mathbb{R}^{3}$ as above. So, in this way, the group $W$
can be regarded as a subgroup of $\mathrm{GL}\left(\mathbb{R}^{3}\right)$. For $k \in \mathbb{Z}$, we denote by $H_{k}$ the linear plane of $\mathbb{R}^{3}$ spanned by $D_{k}$, and we denote by $H_{k}^{\prime}$ the linear plane spanned by $D_{k}^{\prime}$. Then $s_{k}$ is a linear reflection whose fixed hyperplane is $H_{k}$, and $s_{k}^{\prime}$ is a linear reflection whose fixed hyperplane is $H_{k}^{\prime}$.

Consider the square

$$
\bar{C}_{0}^{\prime}=\left\{(x, y) \in \mathbb{E}^{2} \mid 0 \leqslant x, y \leqslant 1\right\} .
$$

Let $\bar{C}_{0}$ denote the cone over $\bar{C}_{0}^{\prime}$. This is a closed convex polyhedral cone whose walls are $H_{0}, H_{1}, H_{0}^{\prime}, H_{1}^{\prime}$. Observe that $w C_{0} \cap C_{0}=\emptyset$ for all $w \in$ $W \backslash\{1\}$, thus $(W, S)$ is a Vinberg system, where $S=\left\{s_{0}, s_{1}, s_{0}^{\prime}, s_{1}^{\prime}\right\}$. It is easily checked that

$$
\bar{I}=\bigcup_{w \in W} w \bar{C}_{0}=\left\{(x, y, z) \in \mathbb{R}^{3} \mid z>0\right\} \cup\{(0,0,0)\},
$$

thus

$$
I=\left\{(x, y, z) \in \mathbb{R}^{3} \mid z>0\right\}
$$

On the other hand,

$$
\mathcal{A}=\left\{H_{k}, H_{k}^{\prime} \mid k \in \mathbb{Z}\right\}
$$

We turn now to show the link between Artin groups and Coxeter arrangements. Besides, the $K(\pi, 1)$ conjecture for Artin groups is the master peace of this link.

For a nonempty open convex cone $I$ in a real vector space $V$ of finite dimension $\ell$, and a hyperplane arrangement $\mathcal{A}$ in $I$, we set

$$
M(\mathcal{A})=(I \times I) \backslash\left(\bigcup_{H \in \mathcal{A}} H \times H\right)
$$

This is a connected manifold of dimension $2 \ell$. Note that, if $I=V$, then $\mathcal{A}$ is finite and

$$
M(\mathcal{A})=(\mathbb{C} \otimes V) \backslash\left(\bigcup_{H \in \mathcal{A}} \mathbb{C} \otimes H\right)
$$

If $(W, S)$ is a Vinberg system and $\mathcal{A}$ is the Coxeter arrangement of $(W, S)$, then we set $M(W, S)=M(\mathcal{A})$. By Theorem 1.1, $W$ acts freely and properly discontinuously on $M(W, S)$. Then, we set

$$
N(W, S)=M(W, S) / W
$$

The following result will be proved in Subsection 3.3.

Theorem 1.2 (Van der Lek [35]). - Let $(W, S)$ be a Vinberg system, and let $\Gamma$ be the Coxeter graph of the pair $(W, S)$, viewed as a Coxeter system. Then the fundamental group of $N(W, S)$ is isomorphic to $A_{\Gamma}$, the fundamental group of $M(W, S)$ is isomorphic to $C A_{\Gamma}$, and the short exact sequence associated with the regular covering $M(W, S) \rightarrow N(W, S)$ is

$$
1 \longrightarrow C A_{\Gamma} \longrightarrow A_{\Gamma} \xrightarrow{\theta} W \longrightarrow 1 .
$$

Recall that a space $X$ is an Eilenberg MacLane space for a discrete group $G$ if the fundamental group of $X$ is $G$ and the universal cover of $X$ is contractible. We also say that $X$ is aspherical or that it is a $K(G, 1)$ space. Eilenberg MacLane spaces play a prominent role in cohomology of groups. We refer to [6] for more details on the subject.

Conjecture $1.3(K(\pi, 1)$ conjecture). - Let $(W, S)$ be a Vinberg system, and let $\Gamma$ be the Coxeter graph of the pair $(W, S)$, viewed as a Coxeter system. Then $N(W, S)$ is an Eilenberg MacLane space for $A_{\Gamma}$.

Let $\mathcal{A}$ be a finite hyperplane arrangement in a finite dimensional real vector space $V$. In [43] Salvetti associates to $\mathcal{A}$ a regular CW-complex, called Salvetti complex and denoted by $\operatorname{Sal}(\mathcal{A})$, and shows that $\operatorname{Sal}(\mathcal{A})$ has the same homotopy type as $M(\mathcal{A})$. (The definitions of regular CW-complex and homotopy equivalence are given in Subsection 2.1.) In Subsection 3.1 we extend the definition of $\operatorname{Sal}(\mathcal{A})$ to any (infinite) hyperplane arrangement $\mathcal{A}$ in a nonempty open convex cone $I$, and we prove that $\operatorname{Sal}(\mathcal{A})$ has the same homotopy type as $M(\mathcal{A})$ (see Theorem 3.1). This result is more or less known to experts, but, as far as I know, its proof does not exist anywhere in the literature. Our proof is inspired by [41]. Note that, in this paper, the complex $\operatorname{Sal}(\mathcal{A})$ will be defined as a simplicial complex, and, when $\mathcal{A}$ is finite and $I=V$, it coincides with the barycentric subdivision of the complex originally defined by Salvetti.

In Subsection 3.2, with a Coxeter graph $\Gamma$ we associate a simplicial complex $\operatorname{Sal}(\Gamma)$. This complex will be naturally endowed with a free and properly discontinuous action of the Coxeter group $W$ of $\Gamma$. Let $(W, S)$ be a Vinberg system, and let $\Gamma$ be the Coxeter graph of the pair $(W, S)$, viewed as a Coxeter system. We show that $\operatorname{Sal}(\Gamma)$ coincides with $\operatorname{Sal}(\mathcal{A})$, where $\mathcal{A}$ is the Coxeter arrangement of $(W, S)$ (see Theorem 3.3). Moreover, we prove that the homotopy equivalence $\operatorname{Sal}(\Gamma) \rightarrow M(W, S)$ is equivariant under the action of $W$ and induces a homotopy equivalence $\operatorname{Sal}(\Gamma) / W \rightarrow M(W, S) / W=$ $N(W, S)$. In particular, this shows the following intermediate result concerning the $K(\pi, 1)$ conjecture.

Theorem 1.4 (Charney, Davis [13]). - Let $(W, S)$ be a Vinberg system. Then the homotopy type of $M(W, S)$ (resp. $N(W, S)$ ) depends only on the Coxeter graph $\Gamma$ of the pair $(W, S)$, viewed as a Coxeter system.

In their proof of Theorem 1.4, Charney and Davis [13] use another space which is homotopy equivalent to $M(W, S)$ and which depends only on the Coxeter graph $\Gamma$. The complex $\operatorname{Sal}(\Gamma)$ itself is also introduced by Chaney and Davis, but in another paper [14], and the homotopy equivalence $\operatorname{Sal}(\Gamma) \rightarrow$ $M(W, S)$ is also proved in [14]. Our proof is slightly different from the one by Charney and Davis.

From now on, we say that a Coxeter graph $\Gamma$ is of type $K(\pi, 1)$ if $\operatorname{Sal}(\Gamma)$ is an Eilenberg MacLane space. By the above, this means that $M(W, S)$ is an Eilenberg MacLane space for any representation of $(W, S)$ as a Vinberg system, where $(W, S)$ is the Coxeter system of $\Gamma$.

Let $\Gamma$ be a Coxeter graph, and let $(W, S)$ be the Coxeter system of $\Gamma$. In Subsection 3.3 we determine cellular decompositions for $\operatorname{Sal}(\Gamma)$ and for $\operatorname{Sal}(\Gamma) / W$. The definition of $\operatorname{Sal}(\Gamma)$ given in Subsection 3.2 coincides with the barycentric subdivision of this cellular decomposition. This cellular decomposition of $\operatorname{Sal}(\Gamma) / W$ is already defined in [14] for all Coxeter graphs, and, independently, in [45] when the Coxeter group $W$ is finite. A first straightforward consequence of this description of $\operatorname{Sal}(\Gamma) / W$ will be that the fundamental group of $\operatorname{Sal}(\Gamma) / W$ (resp. $\operatorname{Sal}(\Gamma))$ is the Artin group $A_{\Gamma}$ (resp. the colored Artin group $C A_{\Gamma}$ ) (see Theorem 3.10). This new proof of Theorem 1.2 is well-known to experts, but, as far as I know, nobody went to the bother of writing down it before. Note also that this cellular decomposition is a useful tool for calculating different cohomologies of $A_{\Gamma}$ (of course, under the condition that $\Gamma$ is of type $K(\pi, 1)$ ) (see $[7,8,9,10$, $11,12,20,21,22,23,24,45,46,48,49])$.

The fact that the Coxeter graph $\mathbb{A}_{n}$ (that is, the Coxeter graph of the braid group $\mathcal{B}_{n+1}$ ) is of type $K(\pi, 1)$ was proved in 1962 by Fox and Neuwirth [29]. This was the first example of a Coxeter graph of type $K(\pi, 1)$. The $K(\pi, 1)$ conjecture itself was firstly stated by Brieskorn in 1971 in [4], but only for Artin groups of spherical type. (We say that a Coxeter graph $\Gamma$ is of spherical type if the Coxeter group $W_{\Gamma}$ is finite.) In the same paper, [4], Brieskorn proved the conjecture for the Artin groups associated to the Coxeter graphs $\mathbb{A}_{n}, \mathbb{B}_{n}, \mathbb{D}_{n}, \mathbb{F}_{4}$ and $\mathbb{I}_{2}(p)(p \geqslant 5)$ (see Subsection 2.2 for the pictures of these graphs). Immediately after, in 1972, Deligne [26] proved the conjecture for all spherical type Artin groups.

The $K(\pi, 1)$ conjecture, as is stated in the present paper, was stated for the first time in [35]. According to Van der Lek, it is due to Arnold, Pham et

$$
K(\pi, 1) \text { conjecture for Artin groups }
$$

Thom. Besides the Artin groups of spherical type, it was previously proved in [38] for two families of so-called "affine type" Artin groups: the groups of type $\tilde{\mathbb{A}}_{n}$, and those of type $\widetilde{\mathbb{C}}_{n}$ (see also [16]).

Let $\Gamma$ be a Coxeter graph. For $X \subset S$, we set $M_{X}=\left(m_{s, t}\right)_{s, t \in X}$, we denote by $\Gamma_{X}$ the Coxeter graph of $M_{X}$, and we denote by $W_{X}$ the subgroup of $W=W_{\Gamma}$ generated by $X$. By [3], the pair $\left(W_{X}, X\right)$ is the Coxeter system of $\Gamma_{X}$. The subgroup $W_{X}$ is called standard parabolic subgroup of $W$.

Two families of subsets of $S$ play an important role in the theory. The first family, denoted by $\mathcal{S}^{f}$, consists of subsets $X \subset S$ such that $W_{X}$ is finite. For $X \subset S$, we say that $\Gamma_{X}$ is free of infinity if $m_{s, t} \neq \infty$ for all $s, t \in X$. The second family, denoted by $\mathcal{S}^{<\infty}$, consists of subsets $X \subset S$ such that $\Gamma_{X}$ is free of infinity. Note that $\mathcal{S}^{f} \subset \mathcal{S}^{<\infty}$.

After [35], the $K(\pi, 1)$ conjecture has been proved in the following cases.
(1) When $m_{s, t} \geqslant 3$ for all $s, t \in S, s \neq t$ (see [33]). (Such a Coxeter graph is called of large type.)
(2) When $|X| \leqslant 2$ for all $X \in \mathcal{S}^{f}$ (see [13]). (Such a Coxeter graph is called of dimension 2.)
(3) When $\mathcal{S}^{f}=\mathcal{S}^{<\infty}$ (see [13]). (Such a Coxeter graph is called of $F C$ type.)
(4) For the "affine type" Artin groups of type $\tilde{B}_{n}$ (see [11]).

Note that large type Artin groups are both, of dimension 2, and of FC type. On the other hand, it is proved in [28] that, if $\Gamma_{X}$ is of type $K(\pi, 1)$ for all $X \in \mathcal{S}^{<\infty}$, then $\Gamma$ is also of type $K(\pi, 1)$ (see also [31]).

Maybe the next advances in the subject will be due to Jon McCammond and Robert Sulway (see [36]). Indeed, they announce that they can embed any affine type Artin group into a Garside group. Eilenberg MacLane spaces for Garside groups are known [25, 15], thus such an embedding determines an Eilenberg MacLane space for the considered Artin group $A_{\Gamma}$. It remains to show that this Eilenberg MacLane space has the same homotopy type as $\operatorname{Sal}(\Gamma) / W$. By the way, I thank Jon McCammond for pointing out to me this remark.

In Section 4 we give a new proof of Deligne's theorem [26]: "spherical type Artin groups are of type $K(\pi, 1)$ ". Almost the whole proof is made for any Artin group and the hypothesis " $\Gamma$ is of spherical type" is used only in the last paragraph. Nevertheless, I am not sure that this is a substantial
progress toward a global proof of the $K(\pi, 1)$ conjecture, as I do not know how to complete the proof for other kind of Artin groups, and Van der Lek had a similar problem (but with another complex) in [35] (see also [27, 40]). Our proof of Theorem 4.10 (Deligne's theorem) is inspired by the proof given in [41] (see also [44]).

For $X \subset S$, we set $\Sigma_{X}=\left\{\sigma_{s} \mid s \in X\right\}$, and we denote by $A_{X}$ the subgroup of $A=A_{\Gamma}$ generated by $\Sigma_{X}$. Such a subgroup is called standard parabolic subgroup of $A$. In Section 5 we use ideas from [31] to prove some results that involve standard parabolic subgroups. In particular, we prove the following statements.
(1) "The pair $\left(A_{X}, \Sigma_{X}\right)$ is the Artin system of $\Gamma_{X}$ ". This result is originally due to Van der Lek [35].
(2) "If $\Gamma$ is of type $K(\pi, 1)$, then $\Gamma_{X}$ is also of type $K(\pi, 1)$ ". This result, although well-known to experts, was curiously proved very recently for the first time (see [31]).
(3) "If $\Gamma_{X}$ is of type $K(\pi, 1)$ for all $X \in \mathcal{S}^{<\infty}$, then $\Gamma$ is also of type $K(\pi, 1)$ ". This is the previously cited result due to Ellis and Skldberg [28], and our proof is essentially the same as the one in [28]. Note that, thanks to Deligne's theorem [26], this proves that FC type Artin groups are of type $K(\pi, 1)$.

So, as pointed out before, many of the known results on the $K(\pi, 1)$ conjecture will be proved in the present paper. In fact, only the Artin groups of dimension 2 will not be treated, as well as some examples of Artin groups of affine type.

## 2. Preliminaries

### 2.1. Preliminaries on algebraic topology

In this subsection we present some definitions and results on algebraic topology that we will need in the sequel. No proof (except one) will be given, and we refer to [32] for details and proofs.

Let $X, Y$ be two topological spaces, and let $f, g: X \rightarrow Y$ be two continuous maps. We say that $f, g$ are homotopic if there exists a continuous map $H: X \times[0,1] \rightarrow Y$ such that $f(x)=H(x, 0)$ and $g(x)=H(x, 1)$ for all $x \in X$. "To be homotopic" is an equivalence relation on the set of continuous maps from $X$ to $Y$, that we denote by $\sim$. A map $f: X \rightarrow Y$ is a homotopy equivalence if there exists a map $g: Y \rightarrow X$ such that $g \circ f \sim \operatorname{Id}_{X}$

$$
K(\pi, 1) \text { conjecture for Artin groups }
$$

and $f \circ g \sim \operatorname{Id}_{Y}$. In that case we say that $X$ has the same homotopy type as $Y$. A space $X$ is contractible if it has the same homotopy type as a point.

We say that a subspace $Y$ of a topological space $X$ is a deformation retract of $X$ if there exists a continuous map $H: X \times[0,1] \rightarrow X$ such that $H(x, 0)=x$ and $H(x, 1) \in Y$ for all $x \in X$, and $H(y, t)=y$ for all $(y, t) \in Y \times[0,1]$. Clearly, if $Y$ is a deformation retract of $X$, then the inclusion $Y \rightarrow X$ is a homotopy equivalence. The reverse is true when $X$ is a CW-complex and $Y$ is a subcomplex of $X$ (see [32, Thm. 4.5]).

A $C W$-complex is defined to be a topological space $X$ endowed with a filtration by closed subspaces,

$$
X_{0} \subset X_{1} \subset \cdots \subset X_{n} \subset X_{n+1} \subset \cdots
$$

satisfying the following properties.
(a) $X_{0}$ is a discrete set.
(b) For all $n \in \mathbb{N}$, there exists a collection $\mathcal{B}_{n}$ of $n$-dimensional closed disks, called $n$-cells, and, for each $\mathbb{B} \in \mathcal{B}_{n}$, there exists a map $\varphi_{\mathbb{B}}$ : $\partial \mathbb{B} \rightarrow X_{n-1}$, such that the image of each $\varphi_{\mathbb{B}}$ is a finite union of cells of $X_{n-1}$, and $X_{n}$ is obtained from $X_{n-1}$ gluing each $\mathbb{B} \in \mathcal{B}_{n}$ to $X_{n-1}$ via the map $\varphi_{\mathbb{B}}$.
(c) $X=\cup_{n=0}^{\infty} X_{n}$, and $X$ is endowed with the weak topology (that is, $A \subset X$ is closed if and only if $A \cap X_{n}$ is closed for all $\left.n \in \mathbb{N}\right)$.

We say, moreover, that $X$ is regular if, for all $n \in \mathbb{N}$ and all $\mathbb{B} \in \mathcal{B}_{n}$, the gluing map $\varphi_{\mathbb{B}}: \partial \mathbb{B} \rightarrow X_{n-1}$ is a homeomorphism onto its image. For $n \in \mathbb{N}$, the subspace $X_{n}$ is called $n$-skeleton of $X$.

Let $X^{\prime}$ be another CW-complex. We denote by $\mathcal{B}_{n}^{\prime}$ the set of $n$-cells of $X^{\prime}$ and, for $\mathbb{B} \in \mathcal{B}_{n}^{\prime}$, we denote by $\varphi_{\mathbb{B}}^{\prime}: \partial \mathbb{B} \rightarrow X_{n-1}^{\prime}$ the gluing map. We say that $X^{\prime}$ is a subcomplex of $X$ if, for all $n \in \mathbb{N}, \mathcal{B}_{n}^{\prime}$ is included in $\mathcal{B}_{n}$, and, for all $\mathbb{B} \in \mathcal{B}_{n}^{\prime}$, the map $\varphi_{\mathbb{B}}^{\prime}: \partial \mathbb{B} \rightarrow X_{n-1}^{\prime}$ coincides with $\varphi_{\mathbb{B}}: \partial \mathbb{B} \rightarrow X_{n-1}$.

An (abstract) simplicial complex is defined to be a pair $\Upsilon=(S, A)$, where $S$ is a set, called set of vertices, and $A$ is a set of subsets of $S$, called set of simplices, satisfying the following properties. (a) $\emptyset$ is not a simplex, and all the simplices are finite. (b) All the singletons are simplices. (c) Any nonempty subset of a simplex is a simplex.

Let $\Upsilon=(S, A)$ be a simplicial complex. Take an abstract set $B=\left\{e_{s} \mid\right.$ $s \in S\}$ in one-to-one correspondence with $S$, and denote by $V$ the real
vector space having $B$ as a basis. For $\Delta=\left\{s_{0}, s_{1}, \ldots, s_{p}\right\}$ in $A$, we set

$$
|\Delta|=\left\{t_{0} e_{s_{0}}+t_{1} e_{s_{1}}+\cdots+t_{p} e_{s_{p}} \mid 0 \leqslant t_{0}, t_{1}, \ldots, t_{p} \leqslant 1 \text { and } \sum_{i=0}^{p} t_{i}=1\right\}
$$

Note that $|\Delta|$ is a (geometric) simplex of dimension $p$. In particular, $|\Delta|$ is topologically a $p$-dimensional disk. The geometric realization of $\Upsilon$ is defined to be the following subset of $V$.

$$
|\Upsilon|=\bigcup_{\Delta \in A}|\Delta|
$$

We endow $|\Upsilon|$ with the weak topology (see [50, Chap. III, Sec. 1]), so that $|\Upsilon|$ is naturally endowed with a structure of regular CW-complex. For $p \in \mathbb{N}$, if $\Delta$ is a simplex of cardinality $p+1$, then $|\Delta|$ is a cell of dimension $p$. The geometric realization of an abstract simplicial complex is called geometric simplicial complex.

If $(E, \leqslant)$ is a partially ordered set, then the nonempty finite chains of $E$ form a simplicial complex, called derived complex of $(E, \leqslant)$ and denoted by $E^{\prime}=(E, \leqslant)^{\prime}$. This observation is of importance in the paper as our different versions of the Salvetti complex will be defined as geometric realizations of derived complexes of ordered sets.

Let $X$ be a regular a CW-complex. Denote by $\mathcal{B}$ the set of all cells of $X$. If $\mathbb{B}$ and $\mathbb{B}^{\prime}$ are two cells of $X$ of dimension $n$ and $m$, respectively, such that $n<m$ and $\mathbb{B} \subset \varphi_{\mathbb{B}^{\prime}}\left(\partial \mathbb{B}^{\prime}\right)$, then we set $\mathbb{B}<\mathbb{B}^{\prime}$. It is easily checked that the relation $\leqslant$ on $\mathcal{B}$, defined by $\mathbb{B} \leqslant \mathbb{B}^{\prime}$ if either $\mathbb{B}<\mathbb{B}^{\prime}$ or $\mathbb{B}=\mathbb{B}^{\prime}$, is a partial order relation. The derived complex of $(\mathcal{B}, \leqslant)$ is called barycentric subdivision of $X$. It is easily shown that $\left|(\mathcal{B}, \leqslant)^{\prime}\right|$ is homeomorphic to $X$.

Let $X$ be a topological space, and let $\mathcal{U}$ be a cover of $X$ by open subsets. The nerve of $\mathcal{U}$, denoted by $N(\mathcal{U})$, is the simplicial complex defined as follows. (a) The vertices of $N(\mathcal{U})$ are the elements of $\mathcal{U}$. (b) A nonempty finite set of vertices $\left\{U_{0}, U_{1}, \ldots, U_{p}\right\}$ is a simplex in $N(\mathcal{U})$ if $U_{0} \cap U_{1} \cap \cdots \cap$ $U_{p} \neq \emptyset$.

We leave to the reader to look in the literature for the definition of a paracompact space. However, we point out that all the spaces that we will consider are paracompact. The following result is one of the main tools in the paper. Its proof can be found for instance in [32, Sec. 4G].

Theorem 2.1.-
(1) Let $X$ be a paracompact space, and let $\mathcal{U}$ be a cover by open subspaces such that any finite nonempty intersection of elements of $\mathcal{U}$ is con-
tractible. Then the geometric realization $|N(\mathcal{U})|$ of the nerve of $\mathcal{U}$ is homotopy equivalent to $X$.
(2) Let $X$ be a $C W$-complex. Suppose there exists an infinite chain

$$
Y_{0} \subset Y_{1} \subset Y_{2} \subset \cdots Y_{n} \subset Y_{n+1} \subset \cdots
$$

of subcomplexes of $X$ such that $Y_{n}$ is contractible for all $n \in \mathbb{N}$, and $\cup_{n \in \mathbb{N}} Y_{n}=X$. Then $X$ is contractible, too.

At some point, we will need an equivariant version of Theorem 2.1.(1), and, for this, we will need an explicit description of the homotopy equivalence $|N(\mathcal{U})| \rightarrow X$.

We take a connected paracompact space $X$ and a cover $\mathcal{U}$ of $X$ by open subsets such that every nonempty finite intersection of elements of $\mathcal{U}$ is contractible. We denote by $\mathcal{N U}$ the set of all finite nonempty intersections of elements of $\mathcal{U}$ ordered by the inclusion. One can show (with some effort) that $\left|\mathcal{N} \mathcal{U}^{\prime}\right|=|N(\mathcal{U})|$, where $N(\mathcal{U})$ denotes the nerve of $\mathcal{U}$. We describe the homotopy equivalence $f:\left|\mathcal{N} \mathcal{U}^{\prime}\right| \rightarrow X$ on the $n$-skeleton of $\left|\mathcal{N} \mathcal{U}^{\prime}\right|$ by induction on $n$.

Let $U \in \mathcal{N} \mathcal{U}$. Denote by $\delta(U)$ the vertex of $\left|\mathcal{N} \mathcal{U}^{\prime}\right|$ corresponding to $U$. Choose a point $x \in U$, and set $f(\delta(U))=x$. This defines $f:\left|\mathcal{N} \mathcal{U}^{\prime}\right|_{0} \rightarrow X$. Let $U_{0} \subset U_{1}$ be a chain of length 2 in $\mathcal{N U}$, and let $\Delta=\Delta\left(U_{0}, U_{1}\right)$ be the 1 -simplex of $\left|\mathcal{N} \mathcal{U}^{\prime}\right|$ corresponding to this chain. By construction, $U_{0} \subset U_{1}$, and, by hypothesis, $U_{1}$ is connected, thus there exists a path $\gamma:[0,1] \rightarrow U_{1}$ such that $\gamma(0)=f\left(\delta\left(U_{0}\right)\right)$ and $\gamma(1)=f\left(\delta\left(U_{1}\right)\right)$. We define $f: \Delta \rightarrow U_{1} \subset X$ by

$$
f\left((1-t) \delta\left(U_{0}\right)+t \delta\left(U_{1}\right)\right)=\gamma(t), \quad t \in[0,1]
$$

This defines the map $f:\left|\mathcal{N} \mathcal{U}^{\prime}\right|_{1} \rightarrow X$.
We assume that $n \geqslant 1$ and that the map $f:\left|\mathcal{N} \mathcal{U}^{\prime}\right|_{n} \rightarrow X$ is constructed. Furthermore, we assume that, if $U_{0} \subset U_{1} \subset \ldots \subset U_{n}$ is a chain of length $n+1$ and $\Delta=\Delta\left(U_{0}, U_{1}, \ldots, U_{n}\right)$ is the corresponding $n$-simplex of $\left|\mathcal{N} \mathcal{U}^{\prime}\right|$, then $f(\Delta) \subset U_{n}$. Let $U_{0} \subset U_{1} \subset \ldots \subset U_{n+1}$ be a chain of length $n+2$ in $\mathcal{N U}$, and let $\Delta=\Delta\left(U_{0}, U_{1}, \ldots, U_{n+1}\right)$ be the corresponding $(n+1)$-simplex in $\left|\mathcal{N U} \mathcal{U}^{\prime}\right|$. By the above, we have $f(\partial \Delta) \subset U_{n+1}$ and, by hypothesis, $U_{n+1}$ is contractible, thus $\left.f\right|_{\partial \Delta}$ extends to a continuous map $f: \Delta \rightarrow U_{n+1} \subset X$. This defines $f:\left|\mathcal{N} \mathcal{U}^{\prime}\right|_{n+1} \rightarrow X$.

The following result is probably known, but I have not found it in the literature, thus I include a proof. It is of importance to prove that the homotopy equivalence $\operatorname{Sal}(\Gamma) \rightarrow M(W, S)$ induces a homotopy equivalence $\operatorname{Sal}(\Gamma) / W \rightarrow M(W, S) / W=N(W, S)$ (see Corollary 3.4).

Proposition 2.2. - Let $X$ be a paracompact space, and let $\mathcal{U}$ be a cover by open subsets such that every finite nonempty intersection of elements of $\mathcal{U}$ is contractible. Let $G$ be a group acting freely and properly discontinuously on $X$, and such that, for all $g \in G \backslash\{1\}$ and all $U \in \mathcal{U}$, we have $g(U) \in \mathcal{U}$ and $U \cap g(U)=\emptyset$. Then $G$ acts freely and properly discontinuously on $|N(\mathcal{U})|$, there exists a G-equivariant homotopy equivalence $f:|N(\mathcal{U})| \rightarrow X$, and this homotopy equivalence induces a homotopy equivalence $\bar{f}:|N(\mathcal{U})| / G \rightarrow$ $X / G$.

Proof. - By construction, the group $G$ acts on $\mathcal{U}$, and sends every simplex of $\left|\mathcal{N} \mathcal{U}^{\prime}\right|$ to a simplex, thus this action induces an action of $G$ on $|N(\mathcal{U})|=\left|\mathcal{N} \mathcal{U}^{\prime}\right|$. It is easily checked that the latter action is free and properly discontinuous. On the other hand, it is easily seen that the homotopy equivalence $f:\left|\mathcal{N} \mathcal{U}^{\prime}\right| \rightarrow X$ described above can be made to be equivariant under the actions of $G$. In particular, such a $f$ induces a continuous map $\bar{f}:\left|\mathcal{N} \mathcal{U}^{\prime}\right| / G \rightarrow X / G$. It remains to show that $\bar{f}$ is a homotopy equivalence.

In order to prove that $\bar{f}$ is a homotopy equivalence, we will use the following results. These are classical and well-known. We refer to [32, Chap. 4] for their proofs. Let $\varphi: X \rightarrow Y$ be a continuous map between two connected spaces having the homotopy type of CW-complexes. Let $x_{0} \in X$ be a base point for $X$, and set $y_{0}=\varphi\left(x_{0}\right)$.
(1) If $\varphi$ is a covering map, then $\varphi$ induces an isomorphism $\varphi_{*}: \pi_{n}\left(X, x_{0}\right) \rightarrow$ $\pi_{n}\left(Y, y_{0}\right)$ for all $n \geqslant 2$.
(2) If $\varphi$ is a regular covering map, and $G$ is its Galois group, then we have a short exact sequence

$$
1 \longrightarrow \pi_{1}\left(X, x_{0}\right) \xrightarrow{\varphi_{*}} \pi_{1}\left(Y, y_{0}\right) \longrightarrow G \longrightarrow 1
$$

(3) The $\operatorname{map} \varphi: X \rightarrow Y$ is a homotopy equivalence if and only if the homomorphism $\varphi_{*}: \pi_{n}\left(X, x_{0}\right) \rightarrow \pi_{n}\left(Y, y_{0}\right)$ is an isomorphism for all $n \geqslant 1$.

The group $\pi_{n}\left(X, x_{0}\right)$ is the $n$-th homotopy group of $X$. The reader do not need its definition to understand the proof of Proposition 2.2. The above properties suffice.

We denote by $p:\left|\mathcal{N} \mathcal{U}^{\prime}\right| \rightarrow\left|\mathcal{N} \mathcal{U}^{\prime}\right| / G$ and by $p^{\prime}: X \rightarrow X / G$ the natural projections. For $n \geqslant 2$ we have the following commutative diagram.

$$
K(\pi, 1) \text { conjecture for Artin groups }
$$



By (1), $p_{*}$ and $p_{*}^{\prime}$ are isomorphisms, and, by (3), $f_{*}$ is an isomorphism, thus $\bar{f}_{*}$ is an isomorphism, too. For $n=1$ we have the following commutative diagram, where the rows are exact sequences.


Since $f_{*}$ is an isomorphism, by the five lemma, $\bar{f}_{*}$ is an isomorphism, too. By (3) we conclude that $\bar{f}$ is a homotopy equivalence.

In order to show that the fundamental group of $\operatorname{Sal}(\Gamma) / W$ is the Artin group $A_{\Gamma}$ (see Theorem 3.10), we will need the following method for computing fundamental groups of CW-complexes.

Take a connected CW-complex $X$. As in the definition, for $n \in \mathbb{N}$, we denote by $\mathcal{B}_{n}$ the set of $n$-dimensional cells of $X$, and, for $\mathbb{B} \in \mathcal{B}_{n}$, we denote by $\varphi_{\mathbb{B}}: \partial \mathbb{B} \rightarrow X_{n-1}$ the gluing map of $\mathbb{B}$. Let $a \in \mathcal{B}_{1}$ be a 1 -cell. We set an orientation on $a$. This means that we choose some identification of $a$ with the interval $[0,1]$. In that way, $a$ determines a path $\tilde{a}:[0,1] \rightarrow X_{1}$ by setting $\tilde{a}(0)=\varphi_{a}(0), \tilde{a}(1)=\varphi_{a}(1)$, and $\tilde{a}(t)=t$ for all $t \in(0,1)$. Let $\mathbb{B} \in \mathcal{B}_{2}$ be a 2 -cell. Then $\mathbb{B}$ is homeomorphic to the disk $\mathbb{D}=\{z \in \mathbb{C}| | z \mid \leqslant 1\}$. Without loss of generality, we can assume that $\varphi_{\mathbb{B}}(1)$ is a vertex $x_{0} \in X_{0}$. Then the $\operatorname{map} \tilde{\varphi}_{\mathbb{B}}:[0,1] \rightarrow X_{1}$ defined by

$$
\tilde{\varphi}_{\mathbb{B}}(t)=\varphi_{\mathbb{B}}\left(e^{2 i \pi t}\right)
$$

is a loop based at $x_{0}$ homotopic in $X_{1}$ to a loop at $x_{0}$ of the form $\tilde{a}_{1}^{\varepsilon_{1}} \cdots \tilde{a}_{\ell}^{\varepsilon_{\ell}}$, with $a_{1}, \ldots, a_{\ell} \in \mathcal{B}_{1}$, and $\varepsilon_{1}, \ldots, \varepsilon_{\ell} \in\{ \pm 1\}$. Recall finally that a maximal tree of the 1-skeleton $X_{1}$ is a subcomplex $T$ of $X_{1}$ such that $T_{0}=X_{0}$, and $T$ is simply connected.

Fix a maximal tree $T$ of $X_{1}$ and a base-point $x_{0} \in X_{0}$. For all $x \in X_{0}$, choose a path $\gamma_{x}$ in $T$ from $x_{0}$ to $x$. Note that $\gamma_{x}$ is unique up to homotopy, since $T$ is simply connected. For a loop $\alpha:[0,1] \rightarrow X$ based at $x_{0}$ we denote
by $[\alpha]$ the element of $\pi_{1}\left(X, x_{0}\right)$ represented by $\alpha$. For $a \in \mathcal{B}_{1}$ we set

$$
s_{a}=\left[\gamma_{\tilde{a}(1)}^{-1} \tilde{a} \gamma_{\tilde{a}(0)}\right] .
$$

Note that, if $a$ is a 1-cell of $T$, then $s_{a}=1$ in $\pi_{1}\left(X, x_{0}\right)$. On the other hand, for $\mathbb{B} \in \mathcal{B}_{2}$, we take a loop of the form $\tilde{a}_{1}^{\varepsilon_{1}} \cdots \tilde{a}_{\ell}^{\varepsilon_{\ell}}$ based at $\varphi_{\mathbb{B}}(1)$ and homotopic in $X_{1}$ to $\tilde{\varphi}_{\mathbb{B}}$, and we set

$$
w(\mathbb{B})=s_{a_{1}}^{\varepsilon_{1}} \cdots s_{a_{\ell}}^{\varepsilon_{\ell}} .
$$

Note that we have $w(\mathbb{B})=1$ in $\pi_{1}\left(X, x_{0}\right)$ for all $\mathbb{B} \in \mathcal{B}_{2}$. The following result is classical in the study of CW-complexes.

Theorem 2.3.- Take a connected $C W$-complex $X$, and keep the above notations. Then $\pi_{1}\left(X, x_{0}\right)$ has a presentation with generators $s_{a}, a \in \mathcal{B}_{1}$, and relations

$$
\begin{array}{r}
s_{a}=1 \quad \text { for all edges } a \text { of } T, \\
\quad w(\mathbb{B})=1 \quad \text { for all } \mathbb{B} \in \mathcal{B}_{2} .
\end{array}
$$

The proof of the following is contained in the proof of [6, II, Thm. 7.3]. It will be the key tool in the proof of Theorem 5.6.

Theorem 2.4. - Let $X$ be a $C W$-complex which is the union of two subcomplexes, $X_{1}$ and $X_{2}$, whose intersection, $Y$, is nonempty and connected. We take a basepoint $x_{0} \in Y$, and we denote by $\iota_{i}: \pi_{1}\left(Y, x_{0}\right) \rightarrow \pi_{1}\left(X_{i}, x_{0}\right)$ the homomorphism induced by the inclusion $Y \hookrightarrow X_{i}$, for $i=1,2$. We assume that
(a) $\iota_{1}$ and $\iota_{2}$ are injective,
(b) $X_{1}, X_{2}$, and $Y$ are Eilenberg MacLane spaces.

Then $X$ is also an Eilenberg MacLane space.

### 2.2. Preliminaries on Coxeter groups

Let $\Gamma$ be a Coxeter graph, and let $(W, S)$ be its Coxeter system. Take an abstract set $\left\{e_{s} \mid s \in S\right\}$ in one-to-one correspondence with $S$, and denote by $V$ the real vector space having $\left\{e_{s} \mid s \in S\right\}$ as a basis. Define the symmetric bilinear form $B: V \times V \rightarrow \mathbb{R}$ by

$$
\begin{gathered}
B\left(e_{s}, e_{t}\right)= \begin{cases}-\cos \left(\frac{\pi}{m_{s, t}}\right) & \text { if } m_{s, t} \neq \infty \\
-1 & \text { if } m_{s, t}=\infty\end{cases} \\
-378-
\end{gathered}
$$

$$
K(\pi, 1) \text { conjecture for Artin groups }
$$

For $s \in S$ define $\rho_{s} \in \mathrm{GL}(V)$ by

$$
\rho_{s}(x)=x-2 B\left(x, e_{s}\right) e_{s}, \quad x \in V .
$$

Then $\rho_{s}$ is a linear reflection for all $s \in S$, and the map $S \rightarrow \operatorname{GL}(V)$, $s \mapsto \rho_{s}$, induces a linear representation $\rho: W \rightarrow \mathrm{GL}(V)$ (see [3]). This linear representation is called canonical representation of $(W, S)$.

Denote by $V^{*}$ the dual space of $V$. Recall that any linear map $f \in \mathrm{GL}(V)$ determines a linear map $f^{t} \in \mathrm{GL}\left(V^{*}\right)$ defined by

$$
\left\langle f^{t}(\alpha), x\right\rangle=\langle\alpha, f(x)\rangle
$$

for all $\alpha \in V^{*}$ and all $x \in V$. The dual representation $\rho^{*}: W \rightarrow \operatorname{GL}\left(V^{*}\right)$ of $\rho$ is defined by

$$
\rho^{*}(w)=\left(\rho(w)^{t}\right)^{-1}
$$

for all $w \in W$. For $s \in S$, we set $H_{s}=\left\{\alpha \in V^{*} \mid\left\langle\alpha, e_{s}\right\rangle=0\right\}$. Let

$$
\bar{C}_{0}=\left\{\alpha \in V^{*} \mid\left\langle\alpha, e_{s}\right\rangle \geqslant 0 \text { for all } s \in S\right\} .
$$

Theorem 2.5 (Tits [52], Bourbaki [3]). - Let $\Gamma$ be a Coxeter graph, and let $(W, S)$ be its Coxeter system.
(1) The canonical representation $\rho: W \rightarrow \mathrm{GL}(V)$ and the dual representation $\rho^{*}: W^{*} \rightarrow \mathrm{GL}\left(V^{*}\right)$ are faithful.
(2) The set $\bar{C}_{0}$ is a simplicial cone whose walls are $H_{s}, s \in S$. The transformation $\rho^{*}(s)$ is a linear reflection whose fixed hyperplane is $H_{s}$, for all $s \in S$. Moreover, we have $\rho^{*}(w) C_{0} \cap C_{0}=\emptyset$ for all $w \in W \backslash\{1\}$.

In particular, $\left(\rho^{*}(W), \rho^{*}(S)\right)$ is a Vinberg system whose associated Coxeter graph is $\Gamma$.

Recall that $\Gamma$ (resp. $A_{\Gamma}$ ) is said to be of spherical type if $W_{\Gamma}$ is finite. Note that, if $\Gamma_{1}, \ldots, \Gamma_{\ell}$ are the connected components of $\Gamma$, then $W_{\Gamma}=$ $W_{\Gamma_{1}} \times \cdots \times W_{\Gamma_{\ell}}$. In particular, $\Gamma$ is of spherical type if and only if all its connected components are of spherical type.

Theorem 2.6 (Coxeter [18, 19]). -
(1) The Coxeter graph $\Gamma$ is of spherical type if and only if the bilinear form $B: V \times V \rightarrow \mathbb{R}$ is positive definite.
(2) The spherical type connected Coxeter graphs are precisely those listed in Figure 2.1.


$$
\mathbb{I}_{2}(p) \stackrel{p}{\longleftrightarrow} \quad p \geq 5
$$

Figure 2.1. - Connected spherical type Coxeter graphs

Let $\Gamma$ be a Coxeter graph, and let $(W, S)$ be its Coxeter system. Denote by $S^{*}$ the free monoid on $S$. Let $w \in W$. A word $\mu=s_{1} \cdots s_{\ell} \in S^{*}$ is an expression of $w$ if the equality $w=s_{1} \cdots s_{\ell}$ holds in $W$. The length of $w$, denoted by $\lg (w)$, is defined to be the minimal length of an expression of $w$. An expression $\mu=s_{1} \cdots s_{\ell}$ of $w$ is said to be reduced if $\ell=\lg (w)$.

Let $\mu, \mu^{\prime} \in S^{*}$. We say that there is an elementary $M$-transformation joining $\mu$ to $\mu^{\prime}$ if there exist $\nu_{1}, \nu_{2} \in S^{*}$ and $s, t \in S$ such that $m_{s, t} \neq \infty$,

$$
\mu=\nu_{1} \Pi\left(s, t: m_{s, t}\right) \nu_{2}, \quad \text { and } \quad \mu^{\prime}=\nu_{1} \Pi\left(t, s: m_{s, t}\right) \nu_{2} .
$$

$$
K(\pi, 1) \text { conjecture for Artin groups }
$$

Theorem 2.7 (Tits [51]). - Let $w \in W$, and let $\mu, \mu^{\prime}$ be two reduced expressions of $w$. Then there is a finite sequence of elementary $M$-transformations joining $\mu$ to $\mu^{\prime}$.

Let $(A, \Sigma)$ be the Artin system of $\Gamma$. Recall the epimorphism $\theta: A \rightarrow W$ which sends $\sigma_{s}$ to $s$ for all $s \in S$. We define a set-section $\tau: W \rightarrow A$ of $\theta$ as follows. Let $w \in W$. We choose a reduced expression $\mu=s_{1} \cdots s_{\ell}$ of $w$ and we set

$$
\tau(w)=\sigma_{s_{1}} \cdots \sigma_{s_{\ell}}
$$

By Theorem 2.7 the definition of $\tau(w)$ does not depend on the choice of the reduced expression. Attention: $\tau$ is a set-section. It is not a homomorphism. However, it is an important tool in the study of Artin groups.

The following theorem is fundamental in the combinatorial study of Coxeter groups.

Theorem 2.8 (Bourbaki [3]). - Let $(W, S)$ be a Coxeter system.
(1) Let $w \in W$, let $s \in S$, and let $\mu=s_{1} \cdots s_{\ell}$ be a reduced expression of $w$. Then, either $\lg (w s)=\lg (w)+1$, or there exists an index $i \in$ $\{1, \ldots, \ell\}$ such that $w=s_{1} \cdots \widehat{s_{i}} \cdots s_{\ell} s$.
(2) Let $w \in W$ and $s, t \in S$. If $\lg (w s)=\lg (t w)=\lg (w)+1$ and $\lg (t w s)<$ $\lg (w s)$, then $w s=t w$.

Recall that, for $X \subset S$, we set $M_{X}=\left(m_{s, t}\right)_{s, t \in X}$, where $M=\left(m_{s, t}\right)_{s, t \in S}$ is the Coxeter matrix of $\Gamma$, we denote by $\Gamma_{X}$ the Coxeter graph of $M_{X}$, and we denote by $W_{X}$ the subgroup of $W=W_{\Gamma}$ generated by $X$. Recall also that, by [3], the pair $\left(W_{X}, X\right)$ is the Coxeter system of $\Gamma_{X}$, and $W_{X}$ is called standard parabolic subgroup of $W$. Let $X, Y$ be two subsets of $S$. We say that an element $w \in W$ is ( $X, Y$ )-minimal if it is of minimal length in the double-coset $W_{X} w W_{Y}$.

Proposition 2.9 (Bourbaki [3]). - Let $(W, S)$ be a Coxeter system.
(1) Let $X, Y$ be two subsets of $S$, and let $w \in W$. Then there exists a unique ( $X, Y$ )-minimal element lying in $W_{X} w W_{Y}$.
(2) Let $X \subset S$, and let $w \in W$. Then $w$ is $(\emptyset, X)$-minimal if and only if $\lg (w s)>\lg (w)$ for all $s \in X$, and $\lg (w s)>\lg (w)$ for all $s \in X$ if and only if $\lg (w u)=\lg (w)+\lg (u)$ for all $u \in W_{X}$.
(3) Let $X \subset S$, and let $w \in W$. Then $w$ is $(X, \emptyset)$-minimal if and only if $\lg (s w)>\lg (w)$ for all $s \in X$, and $\lg (s w)>\lg (w)$ for all $s \in X$ if and only if $\lg (u w)=\lg (u)+\lg (w)$ for all $u \in W_{X}$.

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(4) Let $X \subset S$, and let $w \in W_{X}$. If $\mu=s_{1} \cdots s_{\ell}$ is a reduced expression of $w$, then $s_{1}, \ldots, s_{\ell} \in X$.

### 2.3. Preliminaries on Vinberg systems

In this subsection we present the main tool that we will use to pass from the Salvetti complex of a Coxeter arrangement, denoted by $\operatorname{Sal}(\mathcal{A})$, to the Salvetti complex of the associated Coxeter graph, denoted by $\operatorname{Sal}(\Gamma)$ (see Subsection 3.2). This tool basically says that two posets are isomorphic (see Theorem 2.10 below). The first poset is the poset of facets of the Coxeter arrangement, while the second poset, denoted by $\mathcal{P}^{f}$, is made of the cosets of finite parabolic subgroups in $W$. Theorem 2.10 is essentially due to Vinberg [54], but the proofs of [3, Chap. V] can be easily adapted to prove the theorem.

Let $\mathcal{A}$ be a hyperplane arrangement in an nonempty open convex cone $I$ in $V=\mathbb{R}^{\ell}$. A chamber of $\mathcal{A}$ is defined to be a connected component of $I \backslash\left(\cup_{H \in \mathcal{A}} H\right)$. We denote by $\mathcal{C}(\mathcal{A})$ the set of chambers of $\mathcal{A}$. For $H \in \mathcal{A}$, we set $I^{H}=I \cap H$ and $\mathcal{A}^{H}=\left\{H^{\prime} \cap H \mid H^{\prime} \in \mathcal{A} \backslash\{H\}\right.$ and $\left.H^{\prime} \cap H \cap I \neq \emptyset\right\}$. Observe that $I^{H}$ is a nonempty open convex cone in $H$, and $\mathcal{A}^{H}$ is a hyperplane arrangement in $I^{H}$. For $H \in \mathcal{A}$, a chamber of $\mathcal{A}^{H}$ is called a face of $\mathcal{A}$ (or 1-codimensional facet of $\mathcal{A}$ ). For $d \in \mathbb{N}$, we define a $d$-codimensional facet of $\mathcal{A}$ by induction on $d$ as follows. The chambers of $\mathcal{A}$ are the 0 codimensional facets. The faces of $\mathcal{A}$ are the 1 -codimensional facets. For $d \geqslant 2$, a $d$-codimensional facet of $\mathcal{A}$ is a $(d-1)$-codimensional facet of some $\mathcal{A}^{H}$, where $H \in \mathcal{A}$. We denote by $\mathcal{F}(\mathcal{A})$ the set of all facets of $\mathcal{A}$. Observe that $\mathcal{F}(\mathcal{A})$ is a partition of $I$. For $F \in \mathcal{F}(\mathcal{A})$, we denote by $\bar{F}$ the closure of $F$ in $I$. Then $\mathcal{F}(\mathcal{A})$ is endowed with the partial order relation $\preceq$ defined by $F_{1} \preceq F_{2}$ if $F_{1} \subseteq \bar{F}_{2}$.

Let $F$ be a $d$-codimensional facet. Define the support of $F$, denoted by $|F|$, to be the linear subspace of $V$ spanned by $F$. Set $I^{F}=|F| \cap I$, $\mathcal{A}_{F}=\{H \in \mathcal{A} \mid H \supset F\}$, and $\mathcal{A}^{F}=\left\{H \cap|F| \mid H \in \mathcal{A} \backslash \mathcal{A}_{F}\right.$ and $\left.H \cap I^{F} \neq \emptyset\right\}$. Observe that $|F|$ is a $d$-codimensional linear subspace of $V, I^{F}$ is a nonempty open convex cone in $|F|, \mathcal{A}^{F}$ is a hyperplane arrangement in $I^{F}$, and $F$ is a chamber of $\mathcal{A}^{F}$. On the other hand, $\mathcal{A}_{F}$ is a finite hyperplane arrangement in $I$. Moreover, if $d \geqslant 1$, we have $\cap_{H \in \mathcal{A}_{F}} H=|F|$. For $d=0$, we set $|F|=\cap_{H \in \mathcal{A}_{F}} H=\cap_{H \in \emptyset} H=V$.

Example. - Set $V=\mathbb{R}^{3}$ and $I=\{(x, y, z) \in V \mid z>0\}$. For $k \in \mathbb{Z}$, denote by $H_{k}$ the plane of $V$ of equation $x=k z$, and denote by $H_{k}^{\prime}$ the plane of equation $y=k z$. Set $\mathcal{A}=\left\{H_{k}, H_{k}^{\prime} \mid k \in \mathbb{Z}\right\}$. This is a hyperplane arrangement in $I$. The trace of $\mathcal{A}$ in the affine plane of equation $z=1$
is pictured in Figure 2.2. Let $F=\{(0,0, z) \mid z>0\}$. Then $F$ is a 2codimensional facet of $\mathcal{A}$ whose support is the line $|F|$ of equations $x=y=$ 0 . Here we have $I^{F}=F, \mathcal{A}^{F}=\emptyset$, and $\mathcal{A}_{F}=\left\{H_{0}, H_{0}^{\prime}\right\}$. Observe that the set of facets $F^{\prime} \in \mathcal{F}(\mathcal{A})$ satisfying $F \preceq F^{\prime}$ is made of 4 chambers, 4 faces, and $F$ itself.


Figure 2.2. - A facet
For a given Coxeter graph $\Gamma$ and its Coxeter system $(W, S)$, we set $\mathcal{S}^{f}=$ $\mathcal{S}_{\Gamma}^{f}=\left\{X \subset S \mid W_{X}\right.$ is finite $\}$ and $\mathcal{P}^{f}=\mathcal{P}_{\Gamma}^{f}=\left\{w W_{X} \mid w \in W\right.$ and $X \in$ $\left.\mathcal{S}^{f}\right\}$. The set $\mathcal{P}^{f}$ is assumed to be ordered by the inclusion.

Theorem 2.10 (Vinberg [54]). - Let $(W, S)$ be a Vinberg system, let $C_{0}$ be its fundamental chamber, let $I$ be its Tits cone, and let $\mathcal{A}$ be its Coxeter arrangement. Denote by $\Gamma$ the Coxeter graph of $(W, S)$, viewed as a Coxeter system.
I. Let $\mathcal{F}\left(C_{0}\right)=\left\{F \in \mathcal{F}(\mathcal{A}) \mid F \preceq C_{0}\right\}$. Then there is a bijection $\iota$ : $\mathcal{S}_{\Gamma}^{f} \rightarrow \mathcal{F}\left(C_{0}\right)$ such that

$$
\bigcap_{s \in X} H_{s}=|\iota(X)|
$$

for all $X \in \mathcal{S}_{\Gamma}^{f}$. Moreover, the following properties hold.
(1) Let $X, Y \in \mathcal{S}_{\Gamma}^{f}$. We have $X \subset Y$ if and only if $\iota(Y) \preceq \iota(X)$.
(2) For $X \in \mathcal{S}_{\Gamma}^{f}$, the stabilizer $\{w \in W \mid w(\iota(X))=\iota(X)\}$ of $\iota(X)$ is equal to $W_{X}$, and every element of $W_{X}$ pointwise fixes $\iota(X)$.
II. There is a bijection $\tilde{\iota}: \mathcal{P}_{\Gamma}^{f} \rightarrow \mathcal{F}(\mathcal{A})$ defined by

$$
\tilde{\iota}\left(w W_{X}\right)=w(\iota(X)) .
$$

Moreover, the following properties hold.

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(1) Let $u, v \in W$ and $X, Y \in \mathcal{S}_{\Gamma}^{f}$. We have $u W_{X} \subset v W_{Y}$ if and only if $\tilde{\iota}\left(v W_{Y}\right) \preceq \tilde{\iota}\left(u W_{X}\right)$.
(2) Let $u, v \in W$ and $X, Y \in \mathcal{S}_{\Gamma}^{f}$. We have $u W_{X} \subset v W_{Y}$ if and only if $X \subset Y$ and $u \in v W_{Y}$.
(3) The restriction of $\tilde{\iota}$ to $W$ is the bijection

$$
\begin{array}{rlc}
W & \rightarrow & \mathcal{C}(\mathcal{A}) \\
w & \mapsto & w\left(C_{0}\right)
\end{array}
$$

III. Let $X$ be a subset of $S$, and let $w$ be an element of $W$. Then $w$ is $(\emptyset, X)$-minimal if and only if $H_{r}$ does not separate $C_{0}$ and $w^{-1}\left(C_{0}\right)$ for every reflection $r$ lying in $W_{X}$.

### 2.4. Preliminaries on Artin monoids

In this subsection we present some results on Artin monoids, that we will need to prove Theorem $4.10(K(\pi, 1)$ conjecture for spherical type Artin groups). Most of the results of the subsection come from [5] (see also [37]), and their proofs are independent from the techniques presented here.

The Artin monoid of a Coxeter graph $\Gamma$ is the monoid $A_{\Gamma}^{+}$defined by the following monoid presentation.
$A_{\Gamma}^{+}=\langle\Sigma| \Pi\left(\sigma_{s}, \sigma_{t}: m_{s, t}\right)=\Pi\left(\sigma_{t}, \sigma_{s}: m_{s, t}\right)$ for all $\left.s, t \in S, s \neq t, m_{s, t} \neq \infty\right\rangle^{+}$.
By [42], the natural homomorphism $A_{\Gamma}^{+} \rightarrow A_{\Gamma}$ is injective.
Since the relations that define $A_{\Gamma}^{+}$are homogeneous, $A_{\Gamma}^{+}$is endowed with a length function $\lg : A_{\Gamma}^{+} \rightarrow \mathbb{N}$ that associates to each element $\alpha \in A_{\Gamma}^{+}$the length of any expression of $\alpha$ on the elements of $\Sigma$. Note that $\lg (\alpha \beta)=$ $\lg (\alpha)+\lg (\beta)$ for all $\alpha, \beta \in A_{\Gamma}^{+}$. For $\alpha, \beta \in A_{\Gamma}^{+}$, we set $\alpha \preceq_{L} \beta$ if there exists $\gamma \in A_{\Gamma}^{+}$such that $\alpha \gamma=\beta$. Similarly, we set $\alpha \preceq_{R} \beta$ if there exists $\gamma \in A_{\Gamma}^{+}$ such that $\gamma \alpha=\beta$. Note that the existence of the length function implies that $\preceq_{L}$ and $\preceq_{R}$ are partial order relations on $A_{\Gamma}^{+}$.

Theorem 2.11 (Brieskorn, Saito [5]). - Let $\Gamma$ be a Coxeter graph, and let $E$ be a nonempty finite subset of $A_{\Gamma}^{+}$.
(1) E has a greater lower bound for the relation $\preceq_{L}$ (resp. $\preceq_{R}$ ), denoted by $\wedge_{L} E\left(\right.$ resp. $\left.\wedge_{R} E\right)$.
(2) If $E$ has an upper bound for the relation $\preceq_{L}\left(\right.$ resp. $\left.\preceq_{R}\right)$, then $E$ has a least upper bound for the relation $\preceq_{L}\left(\right.$ resp.$\left.\preceq_{R}\right)$, denoted by $\vee_{L} E$ (resp. $\vee_{R} E$ ).

Recall the natural homomorphism $\theta: A_{\Gamma} \rightarrow W_{\Gamma}$ and its set-section $\tau: W_{\Gamma} \rightarrow A_{\Gamma}$. Notice that the image of $\tau$ is contained in $A_{\Gamma}^{+}$. We complete the above theorem with the following.

Proposition 2.12 (Brieskorn, Saito [5]). - Let $\Gamma$ be a Coxeter graph.
(1) Let $E$ be a nonempty finite subset of $\tau\left(W_{\Gamma}\right)$. If $\vee_{L} E$ (resp. $\vee_{R} E$ ) exists, then $\vee_{L} E \in \tau\left(W_{\Gamma}\right)$ (resp. $\vee_{R} E \in \tau\left(W_{\Gamma}\right)$ ).
(2) Let $X$ be a subset of $S$. Recall that $\Sigma_{X}$ denotes the set $\Sigma_{X}=\left\{\sigma_{s} \mid\right.$ $s \in X\}$. Then $\vee_{L} \Sigma_{X}$ (resp. $\vee_{R} \Sigma_{X}$ ) exists if and only if $W_{X}$ is finite (that is, $X \in \mathcal{S}^{f}$ ).

The last preliminary result on Artin monoids that we will need concerns only the spherical type ones.

Theorem 2.13 (Brieskorn, Saito [5], Deligne [26]). - Let $\Gamma$ be a spherical type Coxeter graph. Set $\Delta=\vee_{L} \Sigma$ (this element exists by Proposition 2.12). Then $\Delta=\vee_{R} \Sigma$, and every element $\beta \in A_{\Gamma}$ can be written in the form $\beta=\Delta^{-k} \alpha$ with $\alpha \in A_{\Gamma}^{+}$and $k \in \mathbb{N}$.

## 3. Salvetti complexes

### 3.1. Salvetti complex of a hyperplane arrangement

In this subsection $I$ denotes an nonempty open convex cone in a real vector space $V$ of dimension $\ell$, and $\mathcal{A}$ denotes a hyperplane arrangement in $I$. Our aim is to define a (geometric) simplicial complex $\operatorname{Sal}(\mathcal{A})$ and to prove that $\operatorname{Sal}(\mathcal{A})$ has the same homotopy type as $M(\mathcal{A})$. We start recalling some definitions from the previous section.

The arrangement $\mathcal{A}$ determines a partition of $I$ into facets. We denote by $\mathcal{F}(\mathcal{A})$ the set of facets, and by $\mathcal{C}(\mathcal{A})$ the set of chambers (0-codimensional facets) of $\mathcal{A}$. We order $\mathcal{F}(\mathcal{A})$ by $F_{1} \preceq F_{2}$ if $F_{1} \subseteq \bar{F}_{2}$, where, for $F \in \mathcal{F}(\mathcal{A})$, $\bar{F}$ denotes the closure of $F$ in $I$. The support of a facet $F$, denoted by $|F|$, is the linear subspace of $V$ spanned by $F$. We set $I^{F}=I \cap|F|, \mathcal{A}_{F}=\{H \in$ $\mathcal{A} \mid F \subset H\}$, and $\mathcal{A}^{F}=\left\{H \cap|F| \mid H \in \mathcal{A} \backslash \mathcal{A}_{F}\right.$ and $\left.H \cap I^{F} \neq \emptyset\right\}$. Finally, for $F \in \mathcal{F}(\mathcal{A})$ and $C \in \mathcal{C}(\mathcal{A})$, we denote by $C_{F}$ the chamber of $\mathcal{A}_{F}$ containing $C$.

Example. - We go back to the example of the previous section. We set $V=\mathbb{R}^{3}$ and $I=\{(x, y, z) \in V \mid z>0\}$. For $k \in \mathbb{Z}$, we denote by $H_{k}$ the plane of $V$ of equation $x=k z$, and by $H_{k}^{\prime}$ the plane of equation $y=k z$, and we set $\mathcal{A}=\left\{H_{k}, H_{k}^{\prime} \mid k \in \mathbb{Z}\right\}$. Consider the facet $F=\{(0,0, z) \mid z>0\}$.

Let $C$ be the cone over a square bounded by $H_{0}, H_{1}, H_{0}^{\prime}, H_{1}^{\prime}$. Then $C$ is a chamber of $\mathcal{A}$, we have $F \preceq C$, and $C_{F}$ is the cone $\{(x, y, z) \in V \mid x>$ $0, y>0, z>0\}$ (see Figure 3.1).


Figure 3.1. $-C_{F}$ : an example

We set

$$
\operatorname{Sal}_{0}(\mathcal{A})=\{(F, C) \in \mathcal{F}(\mathcal{A}) \times \mathcal{C}(\mathcal{A}) \mid F \preceq C\}
$$

We define a relation $\preceq$ on $\operatorname{Sal}_{0}(\mathcal{A})$ as follows.

$$
(F, C) \preceq\left(F^{\prime}, C^{\prime}\right) \text { if } F \preceq F^{\prime} \text { and } C_{F} \subset C_{F^{\prime}}^{\prime}
$$

It is easily checked that $\preceq$ is an order relation on $\operatorname{Sal}_{0}(\mathcal{A})$. We define the Salvetti complex of $\mathcal{A}$, denoted by $\operatorname{Sal}(\mathcal{A})$, as the geometric realization of the derived complex of $\left(\operatorname{Sal}_{0}(\mathcal{A}), \preceq\right)$.

Remark. - If $\mathcal{A}$ is the Coxeter arrangement of a Vinberg system $(W, S)$, then $W$ acts on $\operatorname{Sal}_{0}(\mathcal{A})$ as follows.

$$
w(F, C)=(w F, w C)
$$

for $w \in W$ and $(F, C) \in \operatorname{Sal}_{0}(\mathcal{A})$. The ordering $\preceq$ is invariant under the action of $W$, thus this action induces an action of $W$ on $\operatorname{Sal}(\mathcal{A})$.

Theorem 3.1.- There exists a homotopy equivalence $f: \operatorname{Sal}(\mathcal{A}) \rightarrow$ $M(\mathcal{A})$. Moreover, if $\mathcal{A}$ is the Coxeter arrangement of a Vinberg system $(W, S)$, then $\underline{f}$ is equivariant under the actions of $W$ and induces a homotopy equivalence $\bar{f}: \operatorname{Sal}(\mathcal{A}) / W \rightarrow M(\mathcal{A}) / W$.

Proof. - We shall define a family $\left\{U(F, C) \mid(F, C) \in \operatorname{Sal}_{0}(\mathcal{A})\right\}$ of open subsets of $M(\mathcal{A})$, and we shall prove the following.

$$
K(\pi, 1) \text { conjecture for Artin groups }
$$

(1) Let $(F, C),(G, D) \in \operatorname{Sal}_{0}(\mathcal{A})$. If $U(F, C)=U(G, D)$, then $(F, C)=$ ( $G, D$ ).
(2) We have

$$
M(\mathcal{A})=\bigcup_{(F, C) \in \operatorname{Sal}_{0}(\mathcal{A})} U(F, C)
$$

(3) Let $\left(F_{0}, C_{0}\right),\left(F_{1}, C_{1}\right), \ldots,\left(F_{p}, C_{p}\right) \in \operatorname{Sal}_{0}(\mathcal{A})$. We have

$$
U\left(F_{0}, C_{0}\right) \cap U\left(F_{1}, C_{1}\right) \cap \cdots \cap U\left(F_{p}, C_{p}\right) \neq \emptyset
$$

if and only if, up to permutation, we have a chain

$$
\left(F_{0}, C_{0}\right) \prec\left(F_{1}, C_{1}\right) \prec \cdots \prec\left(F_{p}, C_{p}\right) .
$$

(4) Let $\left(F_{0}, C_{0}\right) \prec \cdots \prec\left(F_{p}, C_{p}\right)$ be a chain in $\operatorname{Sal}_{0}(\mathcal{A})$. Then $U\left(F_{0}, C_{0}\right) \cap$ $U\left(F_{1}, C_{1}\right) \cap \cdots \cap U\left(F_{p}, C_{p}\right)$ is contractible.

Moreover, if $\mathcal{A}$ is the Coxeter arrangement of a Vinberg system ( $W, S$ ), we shall prove the following.
(5) Let $(F, C) \in \operatorname{Sal}_{0}(\mathcal{A})$ and $w \in W \backslash\{1\}$. Then $w U(F, C)=U(w F, w C)$ and $U(F, C) \cap U(w F, w C)=\emptyset$.

By Theorem 2.1 and Proposition 2.2, Theorem 3.1 will be a straightforward consequence of (1)-(5).

For $(F, C) \in \operatorname{Sal}_{0}(\mathcal{A})$, the open subset $U(F, C)$ will be of the form $U(F, C)=\omega(F) \times C_{F}$, where $\omega(F)$ is an open subset of $I$. We turn now to construct $\omega(F)$ and study its properties.

Throughout the proof we adopt the following definitions and notations. A chain of length $p+1$ in $\mathcal{F}(\mathcal{A})$ is a sequence $\left(F_{0}, F_{1}, \ldots, F_{p}\right)$ in $\mathcal{F}(\mathcal{A})$ such that $F_{0} \prec F_{1} \prec \cdots \prec F_{p}$. We set $\gamma \leqslant \gamma^{\prime}$ if $\gamma=\left(F_{0}, F_{1}, \ldots, F_{p}\right)$ and $\gamma^{\prime}=\left(F_{0}^{\prime}, F_{1}^{\prime}, \ldots, F_{q}^{\prime}\right)$ are two chains in $\mathcal{F}(\mathcal{A})$ such that $F_{0}=F_{0}^{\prime}$ and $\left\{F_{1}, \ldots, F_{p}\right\} \subseteq\left\{F_{1}^{\prime}, \ldots, F_{q}^{\prime}\right\}$. For $F \in \mathcal{F}(\mathcal{A})$, we denote by Chain $(F)$ the set of chains $\gamma=\left(F_{0}, F_{1}, \ldots, F_{p}\right)$ such that $F_{0}=F$. More generally, if $\gamma$ is a chain, we denote by Chain $(\gamma)$ the set of chains $\gamma^{\prime}$ such that $\gamma \leqslant \gamma^{\prime}$.

For all $F \in \mathcal{F}(\mathcal{A})$, we fix a point $x(F) \in F$. If $\mathcal{A}$ is the Coxeter arrangement of a Vinberg system ( $W, S$ ), we choose the points $x(F)$ so that $w x(F)=x(w F)$ for all $F \in \mathcal{F}(\mathcal{A})$ and all $w \in W$. For a given chain $\gamma=\left(F_{0}, F_{1}, \ldots, F_{p}\right)$ in $\mathcal{F}(\mathcal{A})$ we set

$$
\Delta(\gamma)=\left\{y+t_{1} x\left(F_{1}\right)+\cdots+t_{p} x\left(F_{p}\right) \mid y \in F_{0} \text { and } t_{1}, \ldots, t_{p}>0\right\} .
$$

Note that $\Delta\left(F_{0}, F_{1}, \ldots, F_{p}\right) \subset F_{p}$. Note also that, if $\mathcal{A}$ is the Coxeter arrangement of a Vinberg system $(W, S)$, then

$$
w \Delta\left(F_{0}, F_{1}, \ldots, F_{p}\right)=\Delta\left(w F_{0}, w F_{1}, \ldots, w F_{p}\right)
$$

for every chain $\left(F_{0}, F_{1}, \ldots, F_{p}\right)$ and every $w \in W$.
For a given $F \in \mathcal{F}(\mathcal{A})$ we set

$$
\omega(F)=\bigcup_{\gamma \in \operatorname{Chain}(F)} \Delta(\gamma)
$$

(see Figure 3.2). More generally, for a given chain $\gamma$ in $\mathcal{F}(\mathcal{A})$, we set

$$
\omega(\gamma)=\bigcup_{\gamma^{\prime} \in \operatorname{Chain}(\gamma)} \Delta\left(\gamma^{\prime}\right)
$$



Figure 3.2. - The set $\omega(F)$
Claim 1.- Let $F \in \mathcal{F}(\mathcal{A})$. Then $\omega(F)$ is an open subset of $I$.
Proof of Claim 1. - Let $d$ be the codimension of $F$. For $k \geqslant 0$, we denote by $I_{d-k}$ the union of facets of $\mathcal{F}(\mathcal{A})$ of codimension $\geqslant d-k$, and we prove by induction on $k$ that $I_{d-k} \cap \omega(F)$ is an open subset of $I_{d-k}$. The set $I_{d} \cap \omega(F)=F$ is obviously open in $I_{d}$, thus we may assume that $k \geqslant 1$ plus the induction hypothesis. If $X$ is a subset of the cone $I$ and $x$ is a point in $I$, the following set

$$
\{y+t x \mid y \in X \text { and } t>0\}
$$

is called the open cone over $X$ with direction $x$. Let $G$ be a facet of codimension $d-k$. We denote by $\partial G$ the union of the facets $K$ such that $K \prec G$.

If $F \nprec G$, then $G \cap \omega(F)=\emptyset$. If $F \prec G$, then $\partial G \cap \omega(F)$ is an open subset of $\partial G$ (by induction) and $G \cap \omega(F)$ is the open cone over $\partial G \cap \omega(F)$ with direction $x(G)$. This implies that $I_{d-k} \cap \omega(F)$ is an open subset of $I_{d-k}$.

CLAIM 2.-Let $\gamma=\left(F_{0}, F_{1}, \ldots, F_{p}\right)$ and $\gamma^{\prime}=\left(F_{0}^{\prime}, F_{1}^{\prime}, \ldots, F_{q}^{\prime}\right)$ be two chains in $\mathcal{F}(\mathcal{A})$. If $q \leqslant p$ and $\Delta(\gamma) \cap \Delta\left(\gamma^{\prime}\right) \neq \emptyset$, then $\left(F_{0}^{\prime}, \ldots, F_{q}^{\prime}\right)=$ $\left(F_{p-q}, \ldots, F_{p}\right)$.

Proof of Claim 2. - We argue by induction on $q$. Suppose $q=0$. Let $z \in \Delta\left(F_{0}, F_{1}, \ldots, F_{p}\right) \cap \Delta\left(F_{0}^{\prime}\right)$. Then $z \in F_{p} \cap F_{0}^{\prime}$, thus $F_{p} \cap F_{0}^{\prime} \neq \emptyset$, therefore $F_{p}=F_{0}^{\prime}$.

Suppose $q>0$ plus the induction hypothesis. Let $z \in \Delta\left(F_{0}, \ldots, F_{p}\right) \cap$ $\Delta\left(F_{0}^{\prime}, \ldots, F_{q}^{\prime}\right)$. Notice that $z \in F_{p} \cap F_{q}^{\prime}$, thus $F_{p} \cap F_{q}^{\prime} \neq \emptyset$, hence $F_{p}=F_{q}^{\prime}$. We write $z$ in the form $z=y+t_{1} x\left(F_{1}\right)+\cdots+t_{p} x\left(F_{p}\right)$, where $y \in F_{0}$ and $t_{1}, \ldots, t_{p}>0$. Similarly, we write $z=y^{\prime}+t_{1}^{\prime} x\left(F_{1}^{\prime}\right)+\cdots+t_{q}^{\prime} x\left(F_{q}^{\prime}\right)$, where $y^{\prime} \in F_{0}^{\prime}$ and $t_{1}^{\prime}, \ldots, t_{q}^{\prime}>0$. Let $z_{1}=y+t_{1} x\left(F_{1}\right)+\cdots+t_{p-1} x\left(F_{p-1}\right)$, and let $z_{1}^{\prime}=y^{\prime}+t_{1}^{\prime} x\left(F_{1}^{\prime}\right)+\cdots+t_{q-1}^{\prime} x\left(F_{q-1}^{\prime}\right)$. Notice that $z_{1} \in F_{p-1}$ and $z_{1}^{\prime} \in F_{q-1}^{\prime}$. If $t_{p}>t_{q}^{\prime}$, then

$$
z_{1}^{\prime}=y+t_{1} x\left(F_{1}\right)+\cdots+t_{p-1} x\left(F_{p-1}\right)+\left(t_{p}-t_{q}^{\prime}\right) x\left(F_{p}\right) \in F_{p}=F_{q}^{\prime}
$$

This is a contradiction since $z_{1}^{\prime} \in F_{q-1}^{\prime}$. We prove in the same way that the inequality $t_{p}<t_{q}^{\prime}$ cannot hold. It follows that $t_{p}=t_{q}^{\prime}$, thus $z_{1}=z_{1}^{\prime}$. By induction, we conclude that $\left(F_{0}^{\prime}, \ldots, F_{q-1}^{\prime}\right)=\left(F_{p-q}, \ldots, F_{p-1}\right)$.

Claim 3.-Let $F \in \mathcal{F}(\mathcal{A})$, and let $z \in \omega(F)$. There exists a unique chain $\gamma \in$ Chain $(F)$ such that $z \in \Delta(\gamma)$.

Proof of Claim 3.- Let $\gamma=\left(F_{0}, \ldots, F_{p}\right)$ and $\gamma^{\prime}=\left(F_{0}^{\prime}, \ldots, F_{q}^{\prime}\right)$ be elements of Chain $(F)$ such that $z \in \Delta(\gamma) \cap \Delta\left(\gamma^{\prime}\right)$. We can assume without loss of generality that $q \leqslant p$. By Claim 2, we have $\left(F_{0}^{\prime}, \ldots, F_{q}^{\prime}\right)=\left(F_{p-q}, \ldots, F_{p}\right)$. Since, moreover, $F_{0}=F_{0}^{\prime}=F$, it follows that $p=q$ and $\gamma=\gamma^{\prime}$.

Claim 4.-Let $F, G \in \mathcal{F}(\mathcal{A})$. If $\omega(F) \cap \omega(G) \neq \emptyset$, then either $F \preceq G$, or $G \preceq F$.

Proof of $\operatorname{Claim} 4$. - Let $F, G \in \mathcal{F}(\mathcal{A})$ such that $\omega(F) \cap \omega(G) \neq \emptyset$. There exist a chain $\gamma=\left(F_{0}, F_{1}, \ldots, F_{p}\right)$ lying in Chain $(F)$ and a chain $\gamma^{\prime}=$ $\left(F_{0}^{\prime}, \ldots, F_{q}^{\prime}\right)$ lying in Chain $(G)$ such that $\Delta(\gamma) \cap \Delta\left(\gamma^{\prime}\right) \neq \emptyset$. We can assume without loss of generality that $q \leqslant p$. By Claim 2, we have $\left(F_{0}^{\prime}, \ldots, F_{q}^{\prime}\right)=$ $\left(F_{p-q}, \ldots, F_{p}\right)$. Hence, $F=F_{0} \preceq F_{p-q}=F_{0}^{\prime}=G$.

A straightforward consequence of Claim 4 is the following.

CLAIM 5. - Let $F_{0}, F_{1}, \ldots, F_{p} \in \mathcal{F}(\mathcal{A})$. If $\omega\left(F_{0}\right) \cap \cdots \cap \omega\left(F_{p}\right) \neq \emptyset$, then, up to a permutation of the indices, we have a chain $F_{0} \prec F_{1} \prec \cdots \prec F_{p}$.

Claim 6. - Let $\gamma=\left(F_{0}, \ldots, F_{p}\right)$ be a chain in $\mathcal{F}(\mathcal{A})$. Then

$$
\omega\left(F_{0}\right) \cap \cdots \cap \omega\left(F_{p}\right)=\omega(\gamma)
$$

Proof of Claim 6. - Since the inclusion $\omega(\gamma) \subset \omega\left(F_{0}\right) \cap \cdots \cap \omega\left(F_{p}\right)$ is obvious, we only need to prove $\omega\left(F_{0}\right) \cap \cdots \cap \omega\left(F_{p}\right) \subset \omega(\gamma)$. Let $z \in$ $\omega\left(F_{0}\right) \cap \cdots \cap \omega\left(F_{p}\right)$. Since $z \in \omega\left(F_{0}\right)$, there exists a chain $\delta=\left(G_{0}, \ldots, G_{q}\right)$ lying in Chain $\left(F_{0}\right)$ such that $z \in \Delta\left(G_{0}, \ldots, G_{q}\right)$. Let $i \in\{1, \ldots, p\}$. There is also a chain $\delta^{\prime}=\left(G_{0}^{\prime}, \ldots, G_{r}^{\prime}\right)$ lying in Chain $\left(F_{i}\right)$ such that $z \in \Delta\left(\delta^{\prime}\right)$. If $q<r$, then, by Claim 2, $F_{0}=G_{0}=G_{r-q}^{\prime}$. But, this is not possible because, otherwise, we would have $F_{i}=G_{0}^{\prime} \preceq G_{r-q}^{\prime}=F_{0}$ and $F_{0} \prec F_{i}$. So, $r \leqslant q$ and, again by Claim $2, F_{i}=G_{0}^{\prime}=G_{q-r}$. This shows that $\gamma \leqslant \delta$, thus $z \in \Delta(\delta) \subset \omega(\gamma)$.

Claim 7.-Let $\gamma=\left(F_{0}, \ldots, F_{p}\right)$ be a chain in $\mathcal{F}(\mathcal{A})$. Then $\omega(\gamma)$ is contractible.

Proof of Claim 7. - We choose $y_{0} \in F_{0}$ and we set

$$
z_{0}=y_{0}+x\left(F_{1}\right)+\cdots+x\left(F_{p}\right)
$$

For $t \in[0,1]$, we define the map $h_{t}: \omega(\gamma) \rightarrow \omega(\gamma)$ as follows. Let $z \in \omega(\gamma)$. Let $\delta=\left(G_{0}, \ldots, G_{q}\right) \in$ Chain $(\gamma)$ such that $z \in \Delta(\delta)$. There exist $y \in F_{0}=$ $G_{0}$ and $t_{1}, \ldots, t_{q}>0$ such that $z=y+t_{1} x\left(G_{1}\right)+\cdots+t_{q} x\left(G_{q}\right)$. We set

$$
h_{t}(z)=t y+(1-t) y_{0}+u_{1}(t) x\left(G_{1}\right)+\cdots+u_{q}(t) x\left(G_{q}\right)
$$

where

$$
u_{j}(t)= \begin{cases}t t_{j} & \text { if } G_{j} \notin\left\{F_{1}, \ldots, F_{p}\right\} \\ t t_{j}+(1-t) & \text { if } G_{j} \in\left\{F_{1}, \ldots, F_{p}\right\}\end{cases}
$$

It is easily seen that the map

$$
\begin{array}{ccc}
\omega(\gamma) \times[0,1] & \rightarrow \omega(\gamma) \\
(z, t) & \mapsto & h_{t}(z)
\end{array}
$$

is well-defined and continuous. Moreover, we have $h_{t}\left(z_{0}\right)=z_{0}$ for all $t \in$ $[0,1], h_{1}=\mathrm{Id}$, and $h_{0}(z)=z_{0}$ for all $z \in \omega(\gamma)$. This shows that $\left\{z_{0}\right\}$ is a deformation retract of $\omega(\gamma)$.

Claim 8. - Suppose that $\mathcal{A}$ is the Coxeter arrangement of a Vinberg $\operatorname{system}(W, S)$. For $F \in \mathcal{F}(\mathcal{A})$, we denote by $W_{F}=\{w \in W \mid w F=F\}$ the

$$
K(\pi, 1) \text { conjecture for Artin groups }
$$

stabilizer of $F$. Let $F \in \mathcal{F}(\mathcal{A})$, and let $w \in W$. If $\omega(F) \cap w \omega(F) \neq \emptyset$, then $w \in W_{F}$.

Proof of Claim 8. - Suppose that $\omega(F) \cap w \omega(F) \neq \emptyset$. Let $z \in \omega(F) \cap$ $w \omega(F)$. There are chains $\gamma=\left(F_{0}, \ldots, F_{p}\right)$ and $\gamma^{\prime}=\left(F_{0}^{\prime}, \ldots, F_{q}^{\prime}\right)$ lying in Chain $(F)$ such that

$$
z \in \Delta(\gamma) \cap w \Delta\left(\gamma^{\prime}\right)=\Delta\left(F_{0}, \ldots, F_{p}\right) \cap \Delta\left(w F_{0}^{\prime}, \ldots w F_{q}^{\prime}\right)
$$

Assume $q \leqslant p$. The case $p \leqslant q$ is proved in the same way. By Claim 2, $\left(w F_{0}^{\prime}, \ldots, w F_{q}^{\prime}\right)=\left(F_{p-q}, \ldots, F_{p}\right)$. Since $\operatorname{codim} F_{0}=\operatorname{codim} w F_{0}^{\prime}=\operatorname{codim} F$, it follows that $p=q$ and $w \gamma^{\prime}=\gamma$. In particular, $F=F_{0}=w F_{0}^{\prime}=w F$, thus $w \in W_{F}$.

For $(F, C) \in \operatorname{Sal}_{0}(\mathcal{A})$, we set

$$
U(F, C)=\omega(F) \times C_{F} .
$$

We turn now to prove in the following claims that the set $\{U(F, C) \mid(F, C) \in$ $\left.\operatorname{Sal}_{0}(\mathcal{A})\right\}$ satisfies (1)-(5).

Claim 9.- Let $(F, C) \in \operatorname{Sal}_{0}(\mathcal{A})$. Then $U(F, C) \subset M(\mathcal{A})$.
Proof of $\operatorname{Claim}$ 9. - Let $(x, y) \in U(F, C)$. Let $G \in \mathcal{F}(\mathcal{A})$ such that $x \in G$. Since $x \in \omega(F)$, we have $F \preceq G$. Let $H \in \mathcal{A}$. If $H \in \mathcal{A}_{F}$, then $y \notin H$, since $y \in C_{F}$, thus $(x, y) \notin H \times H$. If $H \notin \mathcal{A}_{F}$, then $H \notin \mathcal{A}_{G}$, since $\mathcal{A}_{G} \subset \mathcal{A}_{F}$. But, $\mathcal{A}_{G}=\left\{H^{\prime} \in \mathcal{A} \mid x \in H^{\prime}\right\}$, thus $x \notin H$, therefore $(x, y) \notin H \times H$. This shows that $(x, y) \in M(\mathcal{A})$.

Claim 10.— Let $(F, C),(G, D) \in \operatorname{Sal}_{0}(\mathcal{A})$. If $U(F, C)=U(G, D)$, then $(F, C)=(G, D)$.

Proof of Claim 10. - We have $F \subset \omega(F)$ and, if $F^{\prime} \in \mathcal{F}(\mathcal{A})$ intersects $\omega(F)$, then $F \preceq F^{\prime}$, thus $\omega(F)$ determines $F$. This implies that $F=G$. We have $\omega(F) \cap C_{F} \subset C$, thus $U(F, C)=\omega(F) \times C_{F}$ determines $C$. This implies that $C=D$.

Claim 11.- We have

$$
M(\mathcal{A}) \subset \bigcup_{(F, C) \in \operatorname{Sal}_{0}(\mathcal{A})} U(F, C)
$$

Proof of Claim 11.- Let $(x, y) \in M(\mathcal{A})$. Let $F \in \mathcal{F}(\mathcal{A})$ such that $x \in F$. Let $H \in \mathcal{A}_{F}$. Since $x \in H$, we have $y \notin H$. Hence, there exists a chamber $\tilde{C}$

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of $\mathcal{A}_{F}$ such that $y \in \tilde{C}$. Let $C \in \mathcal{C}(\mathcal{A})$ such that $F \preceq C$ and $C_{F}=\tilde{C}$. Then

$$
(x, y) \in F \times C_{F} \subset \omega(F) \times C_{F}=U(F, C)
$$

Claim 12.- Let $(F, C),(G, D) \in \operatorname{Sal}_{0}(\mathcal{A})$. If $U(F, C) \cap U(G, D) \neq \emptyset$, then either $(F, C) \preceq(G, D)$, or $(G, D) \preceq(F, C)$.

Proof of Claim 12. - Suppose that $U(F, C) \cap U(G, D) \neq \emptyset$. We have $\omega(F) \cap \omega(G) \neq \emptyset$, thus, by Claim 4 , either $F \preceq G$, or $G \preceq F$. We can assume without loss of generality that $F \preceq G$. Then $\emptyset \neq C_{F} \cap D_{G} \subset C_{G} \cap D_{G}$, thus $C_{G}=D_{G}$, therefore $C_{F} \subset D_{G}$.

A straightforward consequence of Claim 12 is the following.
Claim 13. - Let $\left(F_{0}, C_{0}\right),\left(F_{1}, C_{1}\right), \ldots,\left(F_{p}, C_{p}\right) \in \operatorname{Sal}_{0}(\mathcal{A}) . \operatorname{If} U\left(F_{0}, C_{0}\right)$ $\cap \cdots \cap U\left(F_{p}, C_{p}\right) \neq \emptyset$, then, up to a permutation of the indices, we have a chain

$$
\left(F_{0}, C_{0}\right) \preceq\left(F_{1}, C_{1}\right) \preceq \cdots \preceq\left(F_{p}, C_{p}\right) .
$$

Claim 14. - Let $\left(\left(F_{0}, C_{0}\right), \ldots,\left(F_{p}, C_{p}\right)\right)$ be a chain in $\operatorname{Sal}_{0}(\mathcal{A})$. Then

$$
U\left(F_{0}, C_{0}\right) \cap U\left(F_{1}, C_{1}\right) \cap \cdots \cap U\left(F_{p}, C_{p}\right)=\omega\left(F_{0}, \ldots, F_{p}\right) \times\left(C_{0}\right)_{F_{0}}
$$

Proof of Claim 14.— Since $\left(C_{0}\right)_{F_{0}} \subset\left(C_{i}\right)_{F_{i}}$ for all $i \in\{1, \ldots, p\}$, by Claim 6 we have

$$
\begin{aligned}
U\left(F_{0}, C_{0}\right) \cap \cdots \cap U\left(F_{p}, C_{p}\right) & =\left(\omega\left(F_{0}\right) \cap \cdots \cap \omega\left(F_{p}\right)\right) \times\left(C_{0}\right)_{F_{0}} \\
& =\omega\left(F_{0}, \ldots, F_{p}\right) \times\left(C_{0}\right)_{F_{0}} .
\end{aligned}
$$

Claim 15.-Let $\left(\left(F_{0}, C_{0}\right), \ldots,\left(F_{p}, C_{p}\right)\right)$ be a chain in $\operatorname{Sal}_{0}(\mathcal{A})$. Then $U\left(F_{0}, C_{0}\right) \cap \cdots \cap U\left(F_{p}, C_{p}\right)$ is nonempty and contractible.

Proof of Claim 15. - $\omega\left(F_{0}, \ldots, F_{p}\right)$ is contractible by Claim 7, and $C_{F}$ is contractible since it is convex. Both spaces are obviously nonempty.

Claim 16. - Suppose $\mathcal{A}$ is the Coxeter arrangement of a Vinberg system $(W, S)$. Let $(F, C) \in \operatorname{Sal}_{0}(\mathcal{A})$, and let $w \in W \backslash\{1\}$. Then $w U(F, C) \in$ $\operatorname{Sal}_{0}(\mathcal{A})$ and $U(F, C) \cap w U(F, C)=\emptyset$.

Proof of Claim 16. - We have $w U(F, C)=U(w F, w C) \in \operatorname{Sal}_{0}(\mathcal{A})$. Recall that $W_{F}=\{w \in W \mid w F=F\}$. Since $W$ acts freely on $\mathcal{C}(\mathcal{A})$,

$$
K(\pi, 1) \text { conjecture for Artin groups }
$$

the group $W_{F}$ acts freely on $\{C \in \mathcal{C}(\mathcal{A}) \mid F \preceq C\}$. If $w \notin W_{F}$, then, by Claim $8, \omega(F) \cap w \omega(F)=\emptyset$. If $w \in W_{F}$, then $F \preceq w C$ and $C \neq$ $w C$, thus $C_{F} \neq w C_{F}$, therefore $C_{F} \cap w C_{F}=\emptyset$. In both cases we have $U(F, C) \cap U(w F, w C)=\emptyset$.

### 3.2. Salvetti complex of a Coxeter system

Recall that, for a given Coxeter system $(W, S)$, we denote by $\mathcal{S}^{f}$ the set of subsets $X$ of $S$ such that $W_{X}$ is finite. The following lemma is a preliminary to the definition of the Salvetti complex of a Coxeter graph.

Lemma 3.2.- Let $\Gamma$ be a Coxeter graph, and let $(W, S)$ be its Coxeter system. Let $\preceq$ be the relation on $W \times \mathcal{S}^{f}$ defined as follows.

$$
(u, X) \preceq(v, Y)
$$

if

$$
X \subset Y, v^{-1} u \in W_{Y}, \text { and } v^{-1} u \text { is }(\emptyset, X) \text {-minimal. }
$$

Then $\preceq$ is a partial order relation.
Proof. - Let $(u, X) \in W \times \mathcal{S}^{f}$. We have $X \subset X, u^{-1} u=1 \in W_{X}$, and $u^{-1} u=1$ is $(\emptyset, X)$-minimal, thus $(u, X) \preceq(u, X)$.

Let $(u, X),(v, Y) \in W \times \mathcal{S}^{f}$ such that $(u, X) \preceq(v, Y)$ and $(v, Y) \preceq$ $(u, X)$. We have $X \subset Y \subset X$, thus $X=Y$. We have $v^{-1} u \in W_{X}$ and $v^{-1} u$ is $(\emptyset, X)$-minimal. But, the only $(\emptyset, X)$-minimal element lying in $W_{X}$ is 1 , thus $v^{-1} u=1$, therefore $v=u$.

Let $(u, X),(v, Y),(w, Z) \in W \times \mathcal{S}^{f}$ such that $(u, X) \preceq(v, Y) \preceq(w, Z)$. We have $X \subset Y$ and $Y \subset Z$, thus $X \subset Z$. We also have $w^{-1} v \in W_{Z}$ and $v^{-1} u \in W_{Y} \subset W_{Z}$, thus $w^{-1} u=w^{-1} v v^{-1} u \in W_{Z}$. Now, because $w^{-1} v$ is $(\emptyset, Y)$-minimal and $v^{-1} u$ is $(\emptyset, X)$-minimal, by Proposition 2.9, for all $u_{0} \in W_{X}$ we have the following equalities.

$$
\begin{aligned}
\lg \left(w^{-1} u u_{0}\right) & =\lg \left(w^{-1} v v^{-1} u u_{0}\right)=\lg \left(w^{-1} v\right)+\lg \left(v^{-1} u u_{0}\right) \\
& =\lg \left(w^{-1} v\right)+\lg \left(v^{-1} u\right)+\lg \left(u_{0}\right) \\
& =\lg \left(w^{-1} v v^{-1} u\right)+\lg \left(u_{0}\right)=\lg \left(w^{-1} u\right)+\lg \left(u_{0}\right)
\end{aligned}
$$

By Proposition 2.9 it follows that $w^{-1} u$ is $(\emptyset, X)$-minimal. So, $(u, X) \preceq$ $(w, Z)$.

Let $\Gamma$ be a Coxeter graph, and let $(W, S)$ be its Coxeter system. The Salvetti complex of $\Gamma$, denoted by $\operatorname{Sal}(\Gamma)$, is defined to be the geometric realization of the derived complex of $\left(W \times \mathcal{S}^{f}, \preceq\right)$. Note that the action of

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$W$ on $W \times \mathcal{S}^{f}$ defined by $w \cdot(u, X)=(w u, X), w \in W$ and $(u, X) \in W \times \mathcal{S}^{f}$, preserves the ordering. Hence, it induces an action of $W$ on $\operatorname{Sal}(\Gamma)$.

Now, we take a Vinberg system $(W, S)$ and we denote by $\Gamma$ the Coxeter graph of $(W, S)$, viewed as a Coxeter system. We go back to the notations and definitions of Subsection 2.3. So, $\mathcal{A}$ denotes the Coxeter arrangement of $(W, S), C_{0}$ denotes the fundamental chamber of $(W, S), \mathcal{F}\left(C_{0}\right)$ denotes the set of facets $F$ of $\mathcal{A}$ such that $F \preceq C_{0}$, and $\mathcal{P}^{f}=\left\{w W_{X} \mid w \in\right.$ $W$ and $\left.X \in \mathcal{S}^{f}\right\}$. Recall also that we have bijective maps $\iota: \mathcal{S}^{f} \rightarrow \mathcal{P}\left(C_{0}\right)$ and $\tilde{\iota}: \mathcal{P}^{f} \rightarrow \mathcal{F}(\mathcal{A})$ whose properties are stated in Theorem 2.10. We define the map $\varphi: W \times \mathcal{S}^{f} \rightarrow \operatorname{Sal}_{0}(\mathcal{A})$ as follows

$$
\varphi(w, X)=\left(\tilde{\iota}\left(w W_{X}\right), \tilde{\iota}(w)\right)=\left(w(\iota(X)), w\left(C_{0}\right)\right) .
$$

The main result of this subsection is the following.

Theorem 3.3. - The map $\varphi$ is a bijective map which satisfies the following property.
(*) Let $(u, X),(v, Y) \in W \times \mathcal{S}^{f}$. We have $(u, X) \preceq(v, Y)$ if and only if $\varphi(v, Y) \preceq \varphi(u, X)$.

Before proving Theorem 3.3, we first give two important consequences. By construction, the map $\varphi$ induces a homeomorphism $h: \operatorname{Sal}(\Gamma) \rightarrow \operatorname{Sal}(\mathcal{A})$. Moreover, $\varphi$ being equivariant, the homeomorphism $h$ is also equivariant. Combining this with Theorem 3.1 we obtain the following.

Corollary 3.4.- There exists a homotopy equivalence $f: \operatorname{Sal}(\Gamma) \rightarrow$ $M(W, S)$ equivariant under the actions of $W$ and that induces a homotopy equivalence $\bar{f}: \operatorname{Sal}(\Gamma) / W \rightarrow M(W, S) / W=N(W, S)$.

The following result is a direct consequence of Corollary 3.4. It was previously proved by Charney and Davis [13].

Corollary 3.5. - The homotopy type of $N(W, S)($ resp. $M(W, S))$ depends only on the Coxeter graph $\Gamma$.

Proof of Theorem 3.3. - Let $(F, C) \in \operatorname{Sal}_{0}(\mathcal{A})$. There exists $w \in W$ such that $C=w\left(C_{0}\right)$. We have $w^{-1}(F) \preceq w^{-1}(C)=C_{0}$, thus $w^{-1}(F) \in \mathcal{F}\left(C_{0}\right)$, therefore there exists $X \in \mathcal{S}^{f}$ such that $w^{-1}(F)=\iota(X)$. Hence, $(F, C)=$ $\varphi(w, X)$. This shows that $\varphi$ is a surjective map.

Let $(u, X),(v, Y) \in W \times \mathcal{S}^{f}$ such that $\varphi(u, X)=\varphi(v, Y)=(F, C)$. We have $u\left(C_{0}\right)=v\left(C_{0}\right)=C$, thus $u=v$. Moreover, $\iota(X)=\iota(Y)=u^{-1}(F)$, thus $X=Y$. This shows that $\varphi$ is injective.

Let $(u, X),(v, Y) \in W \times \mathcal{S}^{f}$ such that $(u, X) \preceq(v, Y)$. Set $(F, C)=$ $\varphi(u, X)$ and $(G, D)=\varphi(v, Y)$. We have $X \subset Y$ and $u$ can be written in the form $u=v w$, where $w \in W_{Y}$ and $w$ is $(\emptyset, X)$-minimal. We have $\iota(Y) \preceq \iota(X)$ by Theorem 2.10.I, thus $\iota(Y)=w^{-1}(\iota(Y)) \preceq w^{-1}(\iota(X))$, therefore $v(\iota(Y))=G \preceq u(\iota(X))=F$. Let $H \in \mathcal{A}_{F}$. We have $u^{-1}(H) \in$ $\mathcal{A}_{\iota(X)}$. By Theorem 2.10.I, there exists a reflection $r$ lying in $W_{X}$ such that $u^{-1}(H)=H_{r}$. By Theorem 2.10.III, $u^{-1}(H)$ does not separate $C_{0}$ and $w^{-1}\left(C_{0}\right)$, thus $H$ does not separate $u\left(C_{0}\right)=C$ and $u w^{-1}\left(C_{0}\right)=v\left(C_{0}\right)=D$. It follows that $C_{F}=D_{F}$, thus $D_{G} \subset C_{F}$. Hence, $(G, D) \preceq(F, C)$.

Let $(u, X),(v, Y) \in W \times \mathcal{S}^{f}$. We set $(F, C)=\varphi(u, X)$ and $(G, D)=$ $\varphi(v, Y)$, and we assume that $(G, D) \preceq(F, C)$. Let $w=v^{-1} u$ (thus $\left.u=v w\right)$. Since $G=\tilde{\iota}\left(v W_{Y}\right) \preceq F=\tilde{\iota}\left(u W_{X}\right)$, by Theorem 2.10.II, $u W_{X} \subset v W_{Y}$, thus, again by Theorem 2.10.II, $X \subset Y$ and $u \in v W_{Y}$. The later inclusion implies that $w \in W_{Y}$. Let $r$ be a reflection lying in $W_{X}$. We have $H_{r} \in \mathcal{A}_{\iota(X)}$ by Theorem 2.10.I, thus $u\left(H_{r}\right) \in \mathcal{A}_{F}$. Since $C_{F}=D_{F}, u\left(H_{r}\right)$ does not separate $C$ and $D$, thus $H_{r}$ does not separate $u^{-1}(C)=C_{0}$ and $u^{-1}(D)=w^{-1}\left(C_{0}\right)$. By Theorem 2.10.III, it follows that $w$ is $(\emptyset, X)$-minimal. We conclude that $(u, X) \preceq(v, Y)$.

### 3.3. Cellular decompositions and fundamental groups

Let $\Gamma$ be a Coxeter graph, and let $(W, S)$ be its Coxeter system. For all $s \in S$ we set $W^{s}=W_{S \backslash\{s\}}$. The Coxeter complex of $\Gamma$, denoted by $\operatorname{Cox}=\operatorname{Cox}(\Gamma)$, is the simplicial complex defined as follows.
(a) The set of vertices of Cox is the set of cosets $\left\{w W^{s} \mid w \in W\right.$ and $s \in$ $S\}$.
(b) A family $\left\{w_{0} W^{s_{0}}, w_{1} W^{s_{1}}, \ldots, w_{p} W^{s_{p}}\right\}$ is a simplex of Cox if the intersection $w_{0} W^{s_{0}} \cap \cdots \cap w_{p} W^{s^{p}}$ is nonempty.

For $X \subset S, X \neq \emptyset$, we set $W^{X}=W_{S \backslash X}$. Let $X \subset S, X \neq \emptyset$, and let $w \in$ $W$. With the coset $w W^{X}$ we associate the simplex $\Delta\left(w W^{X}\right)=\left\{w W^{s} \mid s \in\right.$ $X\}$ of Cox. Every simplex has this form, and we have $\Delta\left(u W^{X}\right)=\Delta\left(v W^{Y}\right)$ if and only if $u W^{X}=v W^{Y}$. The Coxeter complexes play a prominent role in the definition and the study of Tits buildings. We refer to [1] for a detailed study of these complexes and their applications to Tits buildings. In this paper we will use the following result. This is well-known and can be found for instance in [1].

Proposition 3.6. - Let $\Gamma$ be a Coxeter graph of spherical type. Then $|\operatorname{Cox}(\Gamma)|$ is (homeomorphic to) a sphere of dimension $|S|-1$.

Set $\mathcal{P}_{0}=\mathcal{P}_{0}(\Gamma)=\left\{w W_{X} \mid w \in W, X \subset S\right.$ and $\left.X \neq S\right\}=\left\{w W^{Y} \mid w \in\right.$ $W, Y \subset S$ and $Y \neq \emptyset\}$, and $\mathcal{P}=\mathcal{P}(\Gamma)=\left\{w W_{X} \mid w \in W\right.$ and $\left.X \subset S\right\}$ that we order by the inclusion. Note that, if $\Gamma$ is of spherical type, then $\mathcal{P}$ coincides with the set $\mathcal{P}^{f}$ defined in Subsection 2.3. Observe also that $\left|\mathcal{P}^{\prime}\right|$ is the cone over $\left|\mathcal{P}_{0}^{\prime}\right|$. On the other hand, by the above, $\mathcal{P}_{0}$ is (isomorphic to) the barycentric subdivision of $|\operatorname{Cox}(\Gamma)|$. Then the following result follows from Proposition 3.6.

Corollary 3.7. - Let $\Gamma$ be a Coxeter graph of spherical type. Then the geometric realization $\left|\mathcal{P}^{\prime}\right|$ of the derived complex of $\mathcal{P}$ is homeomorphic to a disk of dimension $|S|$, whose boundary is the geometric realization $\left|\mathcal{P}_{0}^{\prime}\right|$ of the derived complex of $\mathcal{P}_{0}$.

There is a "geometric" way to describe the Coxeter complex and see Proposition 3.6. Recall the construction of the canonical representation (see Subsection 2.2). We take an abstract set $\left\{e_{s} \mid s \in S\right\}$ in one-to-one correspondence with $S$, and we denote by $V$ the real vector space with basis $\left\{e_{s} \mid s \in S\right\}$. There is a symmetric bilinear form $B: V \times V \rightarrow \mathbb{R}$, and a faithful linear representation $\rho: W \rightarrow \mathrm{GL}(V)$ that leaves invariant the form $B$ and which is called canonical representation.

Assume that $\Gamma$ is of spherical type. Then $B$ is positive definite (see Theorem 2.6), thus we can identify $V^{*}$ with $V$ via the form $B$. For all $s \in S$, we set $H_{s}=\left\{x \in V \mid B\left(x, e_{s}\right)=0\right\}$. This is the hyperplane orthogonal to $e_{s}$. Then $\rho(s)=\rho^{*}(s)$ is the orthogonal reflection with respect to $H_{s}$ for all $s \in S$, and $W$, identified with $\rho(W)$, is a (finite) linear group generated by reflections. In this case the Tits cone is $I=V$. Recall that $\mathcal{A}$ denotes the set of reflection hyperplanes of $W$. This is a finite hyperplane arrangement in $V$. We observe that the arrangement $\mathcal{A}$ defines a cellular decomposition of the sphere $\mathbb{S}^{|S|-1}=\{x \in V \mid B(x, x)=1\}$. The proof of the following can be found in [1].

Proposition 3.8. - The cellular decomposition of $\mathbb{S}^{|S|-1}$ determined by $\mathcal{A}$ is a simplicial decomposition which is isomorphic to $\operatorname{Cox}(\Gamma)$.

Example. - Let $m \in \mathbb{N}, m \geqslant 2$. We identify $\mathbb{R}^{2}$ with $\mathbb{C}$, we denote by $H_{0}$ the (real) line spanned by 1 , by $H_{1}$ the line spanned by $e^{i \pi / m}$, by $s$ the orthogonal reflection with respect to $H_{0}$, and by $t$ the orthogonal reflection with respect to $H_{1}$. Let $W$ be the group generated by $s$ and $t$. Then $W$ is the dihedral group of order $2 m$ and has the presentation

$$
W=\left\langle s, t \mid s^{2}=t^{2}=(s t)^{m}=1\right\rangle
$$

For $k \in\{0,1, \ldots, m-1\}$, we denote by $H_{k}$ the line spanned by $e^{i k \pi / m}$. Then $\mathcal{A}=\left\{H_{k} \mid 0 \leqslant k \leqslant m-1\right\}$. The cellular decomposition of $\mathbb{S}^{1}$ defined by $\mathcal{A}$ is composed by $2 m$ vertices and $2 m$ edges (see Figure 3.3). Let $\bar{C}_{0}$ be the closed cone spanned by 1 and $e^{i \pi / m}$. Then $a_{0}=\bar{C}_{0} \cap \mathbb{S}^{1}$ is an edge of the decomposition, and $W$ acts freely and transitively on the set of edges. For $w \in W$, the 1 -simplex of Cox corresponding to $w a_{0}$ is $\Delta\left(w W^{\{s, t\}}\right)=$ $\Delta(w \cdot\{1\})$. The vertices adjacent to the edge $w a_{0}$ correspond to the vertices $w W^{s}=w \cdot\{1, t\}$ and $w W^{t}=w \cdot\{1, s\}$ of Cox.


Figure 3.3. - Coxeter complex

We turn back to the assumption that $\Gamma$ is any Coxeter graph. Let $(u, X) \in W \times \mathcal{S}^{f}$. Set

$$
C(u, X)=\left\{(v, Y) \in W \times \mathcal{S}^{f} \mid(v, Y) \preceq(u, X)\right\} .
$$

Furthermore, let $w W_{Y} \in \mathcal{P}\left(\Gamma_{X}\right)$, and let $w_{0}$ be the $(\emptyset, Y)$-minimal element lying in $w W_{Y}$. With the coset $w W_{Y}$ we associate the element $\left(u w_{0}, Y\right)$ of $W \times \mathcal{S}^{f}$, that we denote by $f\left(w W_{Y}\right)$. The key point in the construction of the cellular decomposition of $\operatorname{Sal}(\Gamma)$ is the following.

Lemma 3.9.-Let $(u, X) \in W \times \mathcal{S}^{f}$. Then $f\left(w W_{Y}\right) \in C(u, X)$ for all $w W_{Y} \in \mathcal{P}\left(\Gamma_{X}\right)$, and the map $f: \mathcal{P}\left(\Gamma_{X}\right) \rightarrow C(u, X)$ is a poset isomorphism.

Proof. - Let $w W_{Y} \in \mathcal{P}\left(\Gamma_{X}\right)$. We can assume without loss of generality that $w$ is $(\emptyset, Y)$-minimal. Since $Y \subset X, w \in W_{X}$, and $w$ is $(\emptyset, Y)$-minimal, we have $f\left(w W_{Y}\right)=(u w, Y) \preceq(u, X)$. So, $f\left(w W_{Y}\right) \in C(u, X)$.

If $(v, Y) \in C(u, X)$, then $(v, Y)=f\left(u^{-1} v W_{Y}\right)$. So, $f$ is surjective. On the other hand, if $f\left(w W_{Y}\right)=\left(v^{\prime}, Y^{\prime}\right)$, then $Y=Y^{\prime}$ and $w W_{Y}=u^{-1} v^{\prime} W_{Y}$, thus $w W_{Y}$ is entirely determined by its image. So, $f$ is injective.

Let $w_{1} W_{Y_{1}}, w_{2} W_{Y_{2}} \in \mathcal{P}\left(\Gamma_{X}\right)$. We can assume without loss of generality that $w_{1}$ is $\left(\emptyset, Y_{1}\right)$-minimal and $w_{2}$ is $\left(\emptyset, Y_{2}\right)$-minimal. Suppose $w_{1} W_{Y_{1}} \subset$ $w_{2} W_{Y_{2}}$. Then $Y_{1} \subset Y_{2}$ and $w_{1} \in w_{2} W_{Y_{2}}$ (see Theorem 2.10.II). By Proposition 2.9, $w_{1}$ is of the form $w_{1}=w_{2} w_{1}^{\prime}$, where $\lg \left(w_{1}\right)=\lg \left(w_{2}\right)+\lg \left(w_{1}^{\prime}\right)$, and $w_{1}^{\prime} \in W_{Y_{2}}$. Moreover, $w_{1}^{\prime}$ is $\left(\emptyset, Y_{1}\right)$-minimal because $w_{1}$ is. Since $f\left(w_{1} W_{Y_{1}}\right)=$ $\left(u w_{1}, Y_{1}\right)=\left(u w_{2} w_{1}^{\prime}, Y_{1}\right)$ and $f\left(w_{2} W_{Y_{2}}\right)=\left(u w_{2}, Y_{2}\right)$, it follows that $f\left(w_{1} W_{Y_{1}}\right)$ $\preceq f\left(w_{2} W_{Y_{2}}\right)$. Suppose that $f\left(w_{1} W_{Y_{1}}\right) \preceq f\left(w_{2} W_{Y_{2}}\right)$. Then $Y_{1} \subset Y_{2}$ and $w_{2}^{-1} w_{1} \in W_{Y_{2}}$, thus $w_{1} W_{Y_{1}} \subset w_{2} W_{Y_{2}}$.

We describe the cellular decomposition of $\operatorname{Sal}(\Gamma)$ as follows. For all $w \in$ $W$ we have a vertex $x(w)$ corresponding to the poset $w\{1\}$. The 0 -skeleton of $\operatorname{Sal}(\Gamma)$ is $\{x(w) \mid w \in W\}$. For $p \in \mathbb{N}$, the set of $p$-cells of $\operatorname{Sal}(\Gamma)$ is $\left\{\left|C(u, X)^{\prime}\right| \mid(u, X) \in W \times \mathcal{S}^{f}\right.$ and $\left.|X|=p\right\}$, and the $p$-skeleton $\operatorname{Sal}(\Gamma)_{p}$ is the union of these cells. Lemma 3.9 and Corollary 3.7 imply that this defines a regular cellular decomposition of $\operatorname{Sal}(\Gamma)$.

For $(u, X) \in W \times \mathcal{S}^{f}$ with $|X|=p$, we denote by $\mathbb{B}(u, X)=\left|C(u, X)^{\prime}\right|$ the cell of $\operatorname{Sal}(\Gamma)_{p}$ associated to $(u, X)$, and we denote by $\varphi_{u, X}: \partial \mathbb{B}(u, X) \rightarrow$ $\operatorname{Sal}(\Gamma)_{p-1}$ the gluing map.

We denote by $\overline{\operatorname{Sal}}(\Gamma)$ the quotient of $\operatorname{Sal}(\Gamma)$ under the action of $W$. Then the cellular decomposition of $\operatorname{Sal}(\Gamma)$ determines a cellular decomposition of $\overline{\operatorname{Sal}}(\Gamma)$ that is described as follows. Let $X \in \mathcal{S}^{f}$. The orbit of the cell $\mathbb{B}(1, X)$ under the action of $W$ is $\{\mathbb{B}(u, X) \mid u \in W\}$. With this orbit we associate a cell $\overline{\mathbb{B}}(X)$ of $\overline{\operatorname{Sal}}(\Gamma)$ of dimension $|X|$ and homeomorphic to $\mathbb{B}(1, X)$ via a homeomorphism $h_{X}: \overline{\mathbb{B}}(X) \rightarrow \mathbb{B}(1, X)$. The set of cells of $\overline{\operatorname{Sal}}(\Gamma)$ of dimension $p$ is $\left\{\overline{\mathbb{B}}(X) \mid X \in \mathcal{S}^{f}\right.$ and $\left.|X|=p\right\}$. For $X \in \mathcal{S}^{f}$ such that $|X|=p$, the gluing map $\bar{\varphi}_{X}: \partial \overline{\mathbb{B}}(X) \rightarrow \overline{\operatorname{Sal}}(\Gamma)_{p-1}$ is defined as follows.

$$
\bar{\varphi}_{X}=\pi \circ \varphi_{1, X} \circ h_{X}: \partial \overline{\mathbb{B}}(X) \rightarrow \overline{\operatorname{Sal}}(\Gamma)_{p-1}
$$

where $\pi: \operatorname{Sal}(\Gamma) \rightarrow \overline{\operatorname{Sal}}(\Gamma)$ denotes the natural projection. Note that $\bar{\varphi}_{X}$ is not in general a homeomorphism onto its image, thus $\overline{\operatorname{Sal}}(\Gamma)$ is not a regular CW-complex. Note also that $\mathbb{B}(1, X)$ can be viewed as embedded into $\operatorname{Sal}(\Gamma)$, but $\overline{\mathbb{B}}(X)$ cannot be viewed as embedded into $\overline{\operatorname{Sal}}(\Gamma)$.

For practical reasons (in particular, for calculating fundamental groups), and in order to better understand these complexes, we turn now to describe the $p$-skeletons of $\operatorname{Sal}(\Gamma)$ and $\overline{\operatorname{Sal}}(\Gamma)$ for $p=0,1,2$.

0 -skeleton. As mentioned before, the 0 -skeleton of $\operatorname{Sal}(\Gamma)$ is a set $\{x(w) \mid$ $w \in W\}$ in one-to-one correspondence with $W$. The 0 -skeleton of $\overline{\operatorname{Sal}}(\Gamma)$ is reduced to a point that we denote by $x_{0}$.

1-skeleton. With every $(u, s) \in W \times S$ is associated an edge $\mathbb{B}(u,\{s\})$ of $\operatorname{Sal}(\Gamma)$ whose extremities are $x(u)$ and $x(u s)$. We denote this edge by $a(u, s)$, and we assume it to be oriented from $x(u)$ to $x(u s)$. So, for $u, v \in W$, if $v$ is of the form $v=u s$ with $s \in S$, there is an edge $a(u, s)$ going from $x(u)$ to $x(v)$, and there is another edge $a(v, s)$ going from $x(v)$ to $x(u)$ (see Figure 3.4). On the other hand, there is no edge joining $x(u)$ and $x(v)$ if $v$ is not of the form $v=u s$ with $s \in S$. With every $s \in S$ is associated an edge $\bar{a}_{s}=\overline{\mathbb{B}}(\{s\})$ of $\overline{\operatorname{Sal}}(\Gamma)$ whose extremities are both equal to $x_{0}$. Let $s \in S$. It is easily seen that the action of $W$ on $\{a(u, s) \mid u \in W\}$ preserves the orientations of the $a(u, s)$, thus it induces an orientation on $\bar{a}_{s}$. So, we assume $\bar{a}_{s}$ to be endowed with this orientation.


Figure 3.4. - Edges in $\operatorname{Sal}(\Gamma)$ and in $\overline{\operatorname{Sal}}(\Gamma)$
2 -skeleton. Let $s, t \in S, s \neq t$. Note that we have $\{s, t\} \in \mathcal{S}^{f}$ if and only if $m_{s, t} \neq \infty$. Assume $m=m_{s, t} \neq \infty$. With every $u \in W$ is associated a 2 -cell of $\operatorname{Sal}(\Gamma), \mathbb{B}(u,\{s, t\})$, whose boundary is

$$
\begin{gathered}
a(u, s) a(u s, t) \cdots a(u \Pi(s, t: m-1), t) \\
a(u \Pi(t, s: m-1), s)^{-1} \cdots a(u t, s)^{-1} a(u, t)^{-1}
\end{gathered}
$$

if $m$ is even, and

$$
\begin{gathered}
a(u, s) a(u s, t) \cdots a(u \Pi(s, t: m-1), s) \\
a(u \Pi(t, s: m-1), t)^{-1} \cdots a(u t, s)^{-1} a(u, t)^{-1}
\end{gathered}
$$

if $m$ is odd (see Figure 3.5). The $W$-orbit of 2-cells $\{\mathbb{B}(u,\{s, t\}) \mid u \in W\}$ determines the 2 -cell $\overline{\mathbb{B}}(\{s, t\})$ of $\overline{\operatorname{Sal}}(\Gamma)$. By the above, the boundary curve of $\overline{\mathbb{B}}(\{s, t\})$ is

$$
\bar{a}_{s} \bar{a}_{t} \cdots \bar{a}_{t} \bar{a}_{s}^{-1} \cdots \bar{a}_{s}^{-1} \bar{a}_{t}^{-1}=\Pi\left(\bar{a}_{s}, \bar{a}_{t}: m\right) \Pi\left(\bar{a}_{t}, \bar{a}_{s}: m\right)^{-1}
$$

if $m$ is even, and

$$
\bar{a}_{s} \bar{a}_{t} \cdots \bar{a}_{s} \bar{a}_{t}^{-1} \cdots \bar{a}_{s}^{-1} \bar{a}_{t}^{-1}=\Pi\left(\bar{a}_{s}, \bar{a}_{t}: m\right) \Pi\left(\bar{a}_{t}, \bar{a}_{s}: m\right)^{-1}
$$

if $m$ is odd (see Figure 3.5).

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Figure 3.5. -2 -cells in $\operatorname{Sal}(\Gamma)$ and in $\overline{\operatorname{Sal}}(\Gamma)$

A straightforward consequence of these descriptions and of Theorem 2.3 is the following.

ThEOREM 3.10.- We have $\pi_{1}\left(\overline{\operatorname{Sal}}(\Gamma), x_{0}\right)=A_{\Gamma}, \pi_{1}(\operatorname{Sal}(\Gamma), x(1))=$ $C A_{\Gamma}$, and the exact sequence associated with the regular covering $\operatorname{Sal}(\Gamma) \rightarrow$ $\overline{\operatorname{Sal}}(\Gamma)$ is the following.

$$
1 \longrightarrow C A_{\Gamma} \longrightarrow A_{\Gamma} \xrightarrow{\theta} W \longrightarrow 1
$$

Corollary 3.11 (Van der Lek [35]). - Let ( $W, S$ ) be a Vinberg system. Let $\Gamma$ be the Coxeter graph of $(W, S)$, viewed as a Coxeter system. Then $\pi_{1}(N(W, S))=A_{\Gamma}, \pi_{1}(M(W, S))=C A_{\Gamma}$, and the exact sequence associated with the regular covering $M(W, S) \rightarrow N(W, S)$ is the following.

$$
1 \longrightarrow C A_{\Gamma} \longrightarrow A_{\Gamma} \stackrel{\theta}{\longrightarrow} W \longrightarrow 1
$$

## 4. $K(\pi, 1)$ problem for spherical type Artin groups

In this section we first describe the universal cover $\widetilde{\operatorname{Sal}}(\Gamma)$ of the Savetti complex of any Coxeter graph $\Gamma$ (see Subsection 4.1). Afterwards we prove that a certain subcomplex $\widetilde{\mathrm{Sal}^{+}}(\Gamma)$ of $\widetilde{\operatorname{Sal}}(\Gamma)$ is contractible (see Subsection 4.2). At the end, we prove that $\widetilde{\operatorname{Sal}}(\Gamma)$ is contractible if $\Gamma$ is of spherical type (see Subsection 4.3).

### 4.1. Universal cover of the Salvetti complex

We take a Coxeter graph $\Gamma$, and we denote by $(A, \Sigma)$ the Artin system of $\Gamma$. Recall the homomorphism $\theta: A \rightarrow W$ which sends $\sigma_{s}$ to $s$ for all $s \in S$. Recall also that $\theta$ has a natural set-section $\tau: W \rightarrow A$ defined as follows (see Subsection 2.2). Let $w \in W$. We choose a reduced expression $\mu=s_{1} \cdots s_{\ell}$ of $w$ and we set $\tau(w)=\sigma_{s_{1}} \cdots \sigma_{s_{\ell}}$.

Lemma 4.1. - Let $\preceq$ be the relation on $A \times \mathcal{S}^{f}$ defined by

$$
(\alpha, X) \preceq(\beta, Y)
$$

if $X \subset Y$ and $\alpha$ can be written in the form $\alpha=\beta \tau(w)$, where $w \in W_{Y}$ and $w$ is $(\emptyset, X)$-minimal. Then $\preceq$ is a partial order relation.

Proof. - We cleary have $(\alpha, X) \preceq(\alpha, X)$ for all $(\alpha, X) \in A \times \mathcal{S}^{f}$. Let $(\alpha, X),(\beta, Y) \in A \times \mathcal{S}^{f}$ such that $(\alpha, X) \preceq(\beta, Y)$ and $(\beta, Y) \preceq(\alpha, X)$. We have $X \subset Y$ and $Y \subset X$, thus $X=Y$. By definition, $\alpha$ can be written in the form $\alpha=\beta \tau(u)$, where $u \in W_{X}$ and $u$ is $(\emptyset, X)$-minimal. But, the only $(\emptyset, X)$-minimal element lying in $W_{X}$ is 1 , thus $u=1$ and $\alpha=\beta$.

Let $(\alpha, X),(\beta, Y),(\gamma, Z) \in A \times \mathcal{S}^{f}$ such that $(\alpha, X) \preceq(\beta, Y)$ and $(\beta, Y) \preceq(\gamma, Z)$. We have $X \subset Y \subset Z$. Moreover, $\alpha$ can be written in the form $\alpha=\beta \tau(u)$, where $u \in W_{Y}$ and $u$ is $(\emptyset, X)$-minimal, and $\beta$ can be written in the form $\beta=\gamma \tau(v)$, where $v \in W_{Z}$, and $v$ is $(\emptyset, Y)$-minimal. Set $w=v u$. Since $u \in W_{Y}$ and $v$ is ( $\left.\emptyset, Y\right)$-minimal, by Proposition 2.9, we have $\lg (w)=\lg (v)+\lg (u)$, thus $\tau(w)=\tau(v) \tau(u)$. Hence, $\alpha=\gamma \tau(w)$. We have $w \in W_{Z}$, since $v, u \in W_{Z}$. On the other hand, one can easily prove following the same arguments as in the proof of Lemma 3.2 that $w$ is $(\emptyset, X)$-minimal. So, $(\alpha, X) \preceq(\gamma, Z)$.

We denote by $\widetilde{\operatorname{Sal}}(\Gamma)$ the geometric realization of the derived complex of $\left(A \times \mathcal{S}^{f}, \preceq\right)$. The action of $A$ on $A \times \mathcal{S}^{f}$ defined by

$$
\beta(\alpha, X)=(\beta \alpha, X)
$$

induces a free and properly discontinuous action of $A$ on $\widetilde{\operatorname{Sal}}(\Gamma)$. It is easily shown that $\widetilde{\operatorname{Sal}}(\Gamma) / C A=\operatorname{Sal}(\Gamma)$ and $\widetilde{\operatorname{Sal}}(\Gamma) / A=\overline{\operatorname{Sal}}(\Gamma)$. Hence, since the fundamental group of $\overline{\operatorname{Sal}}(\Gamma)$ is $A$, we have the following.

Proposition 4.2. $-\widetilde{\operatorname{Sal}}(\Gamma)$ is the universal cover of $\operatorname{Sal}(\Gamma)$ and of $\overline{\operatorname{Sal}}(\Gamma)$.

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### 4.2. The subcomplex $\widetilde{\mathrm{Sal}}^{+}(\Gamma)$

Recall that the Artin monoid of a Coxeter graph $\Gamma$ is the monoid $A_{\Gamma}^{+}$ that admits the following monoid presentation:
$A_{\Gamma}^{+}=\langle\Sigma| \Pi\left(\sigma_{s}, \sigma_{t}: m_{s, t}\right)=\Pi\left(\sigma_{t}, \sigma_{s}: m_{s, t}\right)$ for all $\left.s, t \in S, s \neq t, m_{s, t} \neq \infty\right\rangle^{+}$. By [42], the natural homomorphism $A_{\Gamma}^{+} \rightarrow A_{\Gamma}$ is injective.

We define $\widetilde{\mathrm{Sal}}^{+}(\Gamma)$ to be the geometric realization of the derived complex of $\left(A_{\Gamma}^{+} \times \mathcal{S}^{f}, \preceq\right)$, where $\preceq$ is the restriction to $A_{\Gamma}^{+} \times \mathcal{S}^{f}$ of the ordering defined in Lemma 4.1. The main result of this subsection is the following.

Theorem 4.3. - The subcomplex $\widetilde{\mathrm{Sal}}^{+}(\Gamma)$ is contractible.
The remainder of the subsection is dedicated to the proof of Theorem 4.3.

Let $V=\mathbb{R}^{\ell}$, and let $H_{1}, \ldots, H_{k}$ be hyperplanes of $V$. For each $i \in$ $\{1, \ldots, k\}$ we take a linear form $\alpha_{i}: V \rightarrow \mathbb{R}$ such that $\operatorname{Ker} \alpha_{i}=H_{i}$. We say that $H_{1}, \ldots, H_{k}$ are independent if $\alpha_{1}, \ldots, \alpha_{k}$ are linearly independent in $V^{*}$.

Lemma 4.4. - Let $I$ be a nonempty open convex cone in $V=\mathbb{R}^{\ell}$, and let $H_{1}, \ldots, H_{k}$ be independent hyperplanes. Set $L=H_{1} \cap \cdots \cap H_{k}$, and assume that $L \cap I \neq \emptyset$. So, we have $H_{i} \cap I \neq \emptyset$ for all $i \in\{1, \ldots, k\}$. For each $i \in\{1, \ldots, k\}$ we take an open half-space bounded by $H_{i}$ that we denote by $H_{i}^{+}$. Then $\left(\cup_{i=1}^{k} H_{i}^{+}\right) \cap I$ is contractible.

Proof. - We choose a basis $\left\{e_{1}, \ldots, e_{\ell}\right\}$ for $V$ so that $H_{i}$ is defined by the equality $x_{i}=0$ with respect to this basis, and $H_{i}^{+}$is defined by the inequality $x_{i}>0$, for all $i \in\{1, \ldots, k\}$. Choose a point $p_{0} \in L \cap I$. Since $p_{0} \in L$, it can be written in the form $p_{0}=\lambda_{k+1} e_{k+1}+\cdots+\lambda_{\ell} e_{\ell}$, where $\lambda_{k+1}, \ldots, \lambda_{\ell} \in \mathbb{R}$. Since $I$ is open, there is $\varepsilon>0$ such that

$$
q_{0}=\varepsilon e_{1}+\cdots+\varepsilon e_{k}+p_{0}=\varepsilon e_{1}+\cdots+\varepsilon e_{k}+\lambda_{k+1} e_{k+1}+\cdots+\lambda_{\ell} e_{\ell} \in I
$$

For all $t \in[0,1]$ we define $h_{t}: V \rightarrow V$ by

$$
h_{t}(p)=(1-t) p+t q_{0}, \quad p \in V
$$

It is easily checked that $h_{t}(p) \in\left(\cup_{i=1}^{k} H_{i}^{+}\right) \cap I$ if $p \in\left(\cup_{i=1}^{k} H_{i}^{+}\right) \cap I$, that $h_{0}(p)=p$ for all $p \in V$, that $h_{1}(p)=q_{0}$ for all $p \in V$, and that $h_{t}\left(q_{0}\right)=q_{0}$ for all $t \in[0,1]$.

Recall that $\mathcal{P}^{f}$ denotes the set $\left\{w W_{X} \mid w \in W\right.$ and $\left.X \in \mathcal{S}^{f}\right\}$ (see Subsection 2.3). Note that every coset $w W_{X} \in \mathcal{P}^{f}$ is uniquely represented by
the pair $(u, X)$, where $u$ is the unique $(\emptyset, X)$-minimal element lying in $w W_{X}$. For $s \in S$, we say that the coset $w W_{X}$ is s-minimal if $l g(s u)=\lg (u)+1$ and $s u$ is $(\emptyset, X)$-minimal. We denote by $\mathcal{P}_{s}^{f}$ the set of cosets $w W_{X}$ lying in $\mathcal{P}^{f}$ that are $s$-minimal, and we assume $\mathcal{P}_{s}^{f}$ ordered by the inclusion. For $X_{0} \in \mathcal{S}^{f}, X_{0} \neq \emptyset$, we set

$$
\mathcal{P}_{X_{0}}^{f}=\bigcup_{s \in X_{0}} \mathcal{P}_{s}^{f}
$$

Lemma 4.5.- Let $s \in S$, and let $u W_{X}, v W_{Y} \in \mathcal{P}^{f}$. If $u W_{X} \in \mathcal{P}_{s}^{f}$ and $v W_{Y} \subset u W_{X}$, then $v W_{Y} \in \mathcal{P}_{s}^{f}$.

Proof. - We can assume without loss of generality that $u$ is $(\emptyset, X)$ minimal and that $v$ is $(\emptyset, Y)$-minimal. We observe that, by Proposition 2.9, we have $u W_{X} \in \mathcal{P}_{s}^{f}$ if and only if $\lg (s u w)=\lg (u)+l g(w)+1$ for all $w \in W_{X}$. Since $v W_{Y} \subset u W_{X}$, we have $Y \subset X$ and $v \in u W_{X}$. We write $v=u v^{\prime}$, where $v^{\prime} \in W_{X}$. Since $u$ is $(\emptyset, X)$-minimal, we have $\lg (v)=\lg (u)+\lg \left(v^{\prime}\right)$. Moreover, since $v$ is $(\emptyset, Y)$-minimal, $v^{\prime}$ is also $(\emptyset, Y)$-minimal. Let $w \in W_{Y}$. Then

$$
\begin{gathered}
\lg (s v w)=\lg \left(s u v^{\prime} w\right)=\lg (u)+\lg \left(v^{\prime} w\right)+1 \\
=\lg (u)+\lg \left(v^{\prime}\right)+\lg (w)+1=\lg (v)+\lg (w)+1 .
\end{gathered}
$$

This shows that $v W_{Y} \in \mathcal{P}_{s}^{f}$.
LEMMA 4.6.-
(1) The geometric realization $\left|\left(\mathcal{P}^{f}\right)^{\prime}\right|$ of the derived complex of $\mathcal{P}^{f}$ is contractible.
(2) Let $X_{0} \in \mathcal{S}^{f}, X_{0} \neq \emptyset$. Then the geometric realization $\left|\left(\mathcal{P}_{X_{0}}^{f}\right)^{\prime}\right|$ of the derived complex of $\mathcal{P}_{X_{0}}^{f}$ is contractible.

Proof.- Let $\rho^{*}: W \rightarrow \mathrm{GL}\left(V^{*}\right)$ be the dual representation of the canonical representation. Recall that, by Theorem 2.5 , this representation is faithful and, $(W, S)$, identified with $\left(\rho^{*}(W), \rho^{*}(S)\right)$, is a Vinberg system. We denote by $I$ the Tits cone, and by $\mathcal{A}$ the Coxeter arrangement in $I$ associated to $(W, S)$. For a reflection $r$ lying in $W$ we denote by $H_{r}$ the fix hyperplane of $r$. Note that, by construction, the set $\left\{H_{s} \mid s \in S\right\}$ is independent.

We denote by $C_{0}$ the fundamental chamber, and by $\mathcal{F}\left(C_{0}\right)$ the set of facets $F$ of $\mathcal{A}$ such that $F \preceq C_{0}$. Recall that we have a bijection $\iota: \mathcal{S}^{f} \rightarrow$ $\mathcal{F}\left(C_{0}\right)$, and this bijection extends to a bijection $\tilde{\iota}: \mathcal{P}^{f} \rightarrow \mathcal{F}(\mathcal{A}), u W_{X} \mapsto$ $u \iota(X)$. Moreover, we have $u W_{X} \subset v W_{Y}$ if and only if $v \iota(Y) \preceq u \iota(X)$ (see Theorem 2.10).

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For all $s \in S$, we denote by $H_{s}^{+}$the open half-space bounded by $H_{s}$ and containing $C_{0}$. For $X_{0} \in \mathcal{S}^{f}, X_{0} \neq \emptyset$, we set

$$
\Omega\left(X_{0}\right)=\left(\bigcup_{s \in X_{0}} H_{s}^{+}\right) \cap I
$$

Note that $\iota\left(X_{0}\right)$ is contained in $\cap_{s \in X_{0}} H_{s}$, thus $\left(\cap_{s \in X_{0}} H_{s}\right) \cap I \neq \emptyset$, therefore, by Lemma $4.4, \Omega\left(X_{0}\right)$ is contractible.

Claim 1.- Let $s \in S$, and let $u W_{X} \in \mathcal{P}^{f}$. We have $u W_{X} \in \mathcal{P}_{s}^{f}$ if and only if $u \iota(X)$ is contained in $H_{s}^{+}$.

Proof of Claim 1. - We can assume without loss of generality that $u$ is $(\emptyset, X)$-minimal. Set $F=u \iota(X)$. Observe that $F$ is contained in $H_{s}^{+}$if and only if $C$ is contained in $H_{s}^{+}$for every chamber $C \in \mathcal{C}(\mathcal{A})$ satisfying $F \preceq C$.

Suppose that $u W_{X} \in \mathcal{P}_{s}^{f}$. Let $C \in \mathcal{C}(\mathcal{A})$ such that $F \preceq C$. By Theorem 2.10.I, there exists $w \in W_{X}$ such that $C=u w\left(C_{0}\right)$. Then

$$
\begin{array}{lcl} 
& \lg (s u w)=\lg (u w)+1 & \\
\Rightarrow & \lg \left(w^{-1} u^{-1} s\right)=\lg \left(w^{-1} u^{-1}\right)+1 & \\
\Rightarrow & C=u w\left(C_{0}\right) \subset H_{s}^{+} & \\
\hline & \text { (by Theorem 2.10.III) } \left.u W_{X} \in \mathcal{P}_{s}^{f}\right) \\
\end{array}
$$

This shows that $F$ is included in $H_{s}^{+}$.
Suppose now that $F$ is included in $H_{s}^{+}$. Let $w \in W_{X}$. Set $C=u w\left(C_{0}\right)$. Since $F \preceq C$, we have $C \subset H_{s}^{+}$. By Theorem 2.10.III, it follows that
$\lg \left(w^{-1} u^{-1} s\right)=\lg \left(w^{-1} u^{-1}\right)+1 \Rightarrow \lg ($ suw $)=\lg (u w)+1=\lg (u)+\lg (w)+1$.
This shows that $u W_{X} \in \mathcal{P}_{s}^{f}$.
For every facet $F$ of $\mathcal{A}$, we denote by $\omega(F)$ the set defined in the proof of Theorem 3.1 (see Figure 3.2). For $u W_{X} \in \mathcal{P}^{f}$, we set $\omega\left(u W_{X}\right)=\omega(u \iota(X))$. Let $s \in S$, and let $u W_{X} \in \mathcal{P}_{s}^{f}$. Set $F=u \iota(X)$. By Claim 1, we have $F \subset$ $H_{s}^{+}$. Moreover, if $G$ is a facet of $\mathcal{A}$ such that $F \preceq G$, then $G \subset H_{s}^{+}$. Since $\omega\left(u W_{X}\right)=\omega(F)$ is contained in the union of the facets $G$ of $\mathcal{A}$ satisfying $F \preceq G$, it follows that $\omega\left(u W_{X}\right) \subset H_{s}^{+}$. This proves the following.

Claim 2. -
(1) The set $\left\{\omega\left(u W_{X}\right) \mid u W_{X} \in \mathcal{P}^{f}\right\}$ is a cover of I by open subsets.
(2) Let $X_{0} \in \mathcal{S}^{f}, X_{0} \neq \emptyset$. Then the set $\left\{\omega\left(u W_{X}\right) \mid u W_{X} \in \mathcal{P}_{X_{0}}^{f}\right\}$ is a cover of $\Omega\left(X_{0}\right)$ by open subsets.

By Claims 5, 6, and 7 in the proof of Theorem 3.1, we have

$$
\omega\left(u_{0} W_{X_{0}}\right) \cap \omega\left(u_{1} W_{X_{1}}\right) \cap \cdots \cap \omega\left(u_{p} W_{X_{p}}\right) \neq \emptyset
$$

if and only if, up to permutation, we have

$$
u_{p} W_{X_{p}} \subset \cdots \subset u_{1} W_{X_{1}} \subset u_{0} W_{X_{0}}
$$

Moreover, in that case, this intersection is contractible. By Theorem 2.1, it follows that $\left|\left(\mathcal{P}^{f}\right)^{\prime}\right|$ has the same homotopy type as $I$, thus $\left|\left(\mathcal{P}^{f}\right)^{\prime}\right|$ is contractible. Similarly, if $X_{0} \in \mathcal{S}^{f}, X_{0} \neq \emptyset$, then $\left|\left(\mathcal{P}_{X_{0}}^{f}\right)^{\prime}\right|$ has the same homotopy type as $\Omega\left(X_{0}\right)$, thus $\left|\left(\mathcal{P}_{X_{0}}^{f}\right)^{\prime}\right|$ is contractible by Lemma 4.4.

We turn back to the universal cover $\widetilde{\operatorname{Sal}}(\Gamma)$ of the Salvetti complex. For $\alpha \in A_{\Gamma}$, we set $\tilde{C}(\alpha)=\left\{(\alpha \tau(u), X) \mid X \in \mathcal{S}^{f}, u \in W\right.$ and $u$ is $(\emptyset, X)$-minimal $\}$. We restrict the ordering of $A_{\Gamma} \times \mathcal{S}^{f}$ to $\tilde{C}(\alpha)$, and we denote by $\Phi(\alpha) \subset \widetilde{\operatorname{Sal}}(\Gamma)$ the geometric realization of the derived complex of $\tilde{C}(\alpha)$.

Let $\alpha \in A_{\Gamma}$, and let $u W_{X} \in \mathcal{P}^{f}$. We can assume without loss of generality that $u$ is $(\emptyset, X)$-minimal. Then we set $f_{\alpha}\left(u W_{X}\right)=(\alpha \tau(u), X) \in \tilde{C}(\alpha)$.

Lemma 4.7. - Let $\alpha \in A_{\Gamma}$. Then the $\operatorname{map} f_{\alpha}: \mathcal{P}^{f} \rightarrow \tilde{C}(\alpha)$ is a poset isomorphism. In particular, it induces a homeomorphism $f_{\alpha}:\left|\left(\mathcal{P}^{f}\right)^{\prime}\right| \rightarrow$ $\Phi(\alpha)$. Hence, by Lemma 4.6, $\Phi(\alpha)$ is contractible.

Proof. - It is easily seen that $f_{\alpha}$ is bijective. Let $u W_{X}, v W_{Y} \in \mathcal{P}^{f}$. We assume without loss of generality that $u$ is $(\emptyset, X)$-minimal and $v$ is $(\emptyset, Y)$ minimal. Suppose that $u W_{X} \subset v W_{Y}$. Then $X \subset Y$ and $u \in v W_{Y}$. Let $u^{\prime} \in W_{Y}$ such that $u=v u^{\prime}$. Since $v$ is $(\emptyset, Y)$-minimal, we have $\lg (u)=$ $\lg (v)+\lg \left(u^{\prime}\right)$, thus $\tau(u)=\tau(v) \tau\left(u^{\prime}\right)$. Moreover, $u^{\prime}$ is $(\emptyset, X)$-minimal, since $u$ is. This implies that $(\alpha \tau(u), X)=\left(\alpha \tau(v) \tau\left(u^{\prime}\right), X\right) \preceq(\alpha \tau(v), Y)$.

Suppose that $(\alpha \tau(u), X) \preceq(\alpha \tau(v), Y)$. Then $X \subset Y$ and $\alpha \tau(u)$ can be written in the form $\alpha \tau(u)=\alpha \tau(v) \tau\left(u^{\prime}\right)$, where $u^{\prime} \in W_{Y}$ and $u^{\prime}$ is $(\emptyset, X)$ minimal. The latter equality implies that $u=v u^{\prime} \in v W_{Y}$, thus $u W_{X} \subset$ $v W_{Y}$.

For $n \in \mathbb{N}$, we set

$$
\widetilde{\mathrm{Sal}}^{(n)}(\Gamma)=\bigcup_{\alpha \in A_{\Gamma}^{+}, \lg (\alpha) \leqslant n} \Phi(\alpha) .
$$

Note that

$$
\widetilde{\mathrm{Sal}}^{+}(\Gamma)=\bigcup_{\alpha \in A_{\Gamma}^{+}} \Phi(\alpha)=\bigcup_{n=0}^{\infty} \widetilde{\mathrm{Sal}}^{(n)}(\Gamma)
$$

Lemma 4.8. - Let $n \in \mathbb{N}$, and let $\alpha, \beta \in A_{\Gamma}^{+}$such that $\alpha \neq \beta$ and $\lg (\alpha)=\lg (\beta)=n+1$. Then $\Phi(\alpha) \cap \Phi(\beta) \subset \widetilde{\operatorname{Sal}}^{(n)}(\Gamma)$.

Proof. - For $n \in \mathbb{N}$, we set

$$
\widetilde{\operatorname{Sal}}_{0}^{(n)}(\Gamma)=\bigcup_{\alpha \in A_{\Gamma}^{+}, \lg (\alpha) \leqslant n} \tilde{C}(\alpha)
$$

Since $\Phi(\alpha)=\left|\tilde{C}(\alpha)^{\prime}\right|$ and $\Phi(\beta)=\left|\tilde{C}(\beta)^{\prime}\right|$, we have

$$
\Phi(\alpha) \cap \Phi(\beta)=\left|(\tilde{C}(\alpha) \cap \tilde{C}(\beta))^{\prime}\right|
$$

Hence, in order to prove Lemma 4.8, it suffices to show that $\tilde{C}(\alpha) \cap \tilde{C}(\beta) \subset$ $\widetilde{\mathrm{Sal}_{0}}{ }^{(n)}(\Gamma)$.

Let $(\gamma, Z) \in \tilde{C}(\alpha) \cap \tilde{C}(\beta)$. There exist $u, v \in W$, both $(\emptyset, Z)$-minimal, such that $\gamma=\alpha \tau(u)=\beta \tau(v)$. Since $\tau(u) \preceq_{R} \gamma$ and $\tau(v) \preceq_{R} \gamma$, the element $\tau(u) \vee_{R} \tau(v)$ exists, and, by Proposition 2.12, there exists $w \in W$ such that $\tau(u) \vee_{R} \tau(v)=\tau(w)$.

Let $\mu \in A_{\Gamma}^{+}$such that $\tau(w)=\mu \tau(u)$. Set $u^{\prime}=\theta(\mu)$. Note that $w=$ $\theta(\tau(w))=u^{\prime} u$. We have

$$
\lg (w) \leqslant \lg \left(u^{\prime}\right)+\lg (u) \leqslant \lg (\mu)+\lg (\tau(u))=\lg (\tau(w))=\lg (w)
$$

thus $\mu=\tau\left(u^{\prime}\right)$ and $\lg (w)=\lg \left(u^{\prime}\right)+\lg (u)$. Similarly, there exists $v^{\prime} \in W$ such that $w=v^{\prime} v$ and $\lg (w)=\lg \left(v^{\prime}\right)+\lg (v)$. Note that this implies that $\tau(w)=\tau\left(u^{\prime}\right) \tau(u)=\tau\left(v^{\prime}\right) \tau(v)$.

Let $\gamma_{0} \in A_{\Gamma}^{+}$such that $\gamma=\gamma_{0} \tau(w)$. By left cancellation, we have $\alpha=$ $\gamma_{0} \tau\left(u^{\prime}\right)$ and $\beta=\gamma_{0} \tau\left(v^{\prime}\right)$. These two equalities imply that $\lg \left(\gamma_{0}\right) \leqslant n+1$. Moreover, if we had $\lg \left(\gamma_{0}\right)=n+1=\lg (\alpha)=\lg (\beta)$, then we would have $\gamma_{0}=\alpha=\beta$, which is not true. Hence, $\lg \left(\gamma_{0}\right) \leqslant n$. So, in order to prove that $(\gamma, Z) \in \widetilde{\operatorname{Sal}}_{0}^{(n)}(\Gamma)$, it suffices to show that $w$ is $(\emptyset, Z)$-minimal.

Suppose that $w$ is not $(\emptyset, Z)$-minimal. Then, by Proposition 2.9, there exists $s \in Z$ such that $\lg (w s)<\lg (w)$. Let $u=s_{1} \cdots s_{\ell}$ be a reduced expression of $u$, and let $u^{\prime}=t_{1} \cdots t_{k}$ be a reduced expression of $u^{\prime}$. Note that $t_{1} \cdots t_{k} s_{1} \cdots s_{\ell}$ is a reduced expression of $w=u^{\prime} u$. By Theorem 2.8, either there exists $i \in\{1, \ldots, \ell\}$ such that $w s=t_{1} \cdots t_{k} s_{1} \cdots \widehat{s_{i}} \cdots s_{\ell}$, or there exists $j \in\{1, \ldots, k\}$ such that $w s=t_{1} \cdots \widehat{t_{j}} \cdots t_{k} s_{1} \cdots s_{\ell}$. But, we cannot have $w s=t_{1} \cdots t_{k} s_{1} \cdots \widehat{s_{i}} \cdots s_{\ell}$, because $\lg (u s)=\lg (u)+1$ (since $u$ is $(\emptyset, Z)$-minimal), thus we have $w s=t_{1} \cdots \widehat{t_{j}} \cdots t_{k} s_{1} \cdots s_{\ell}$ for some $j \in\{1, \ldots, k\}$. Set $u^{\prime \prime}=t_{1} \cdots \widehat{t_{j}} \cdots t_{k}$. Then $w s=u^{\prime \prime} u$ and $\lg (w s)=$
$\lg \left(u^{\prime \prime}\right)+\lg (u)=\lg (w)-1$. In particular, $\tau(w s)=\tau\left(u^{\prime \prime}\right) \tau(u)$. Similarly, there exists $v^{\prime \prime} \in W$ such that $w s=v^{\prime \prime} v$ and $\lg (w s)=\lg \left(v^{\prime \prime}\right)+\lg (v)$ (hence, $\left.\tau(w s)=\tau\left(v^{\prime \prime}\right) \tau(v)\right)$. This contradicts the fact that $\tau(w)=\tau(u) \vee_{R} \tau(v)$, since $\lg (\tau(w s))<\lg (\tau(w))$, and, by the above, $\tau(u), \tau(v) \preceq_{R} \tau(w s)$.

For $\alpha \in A_{\Gamma}^{+}$, we set

$$
\operatorname{End}(\alpha)=\left\{s \in S \mid \sigma_{s} \preceq_{R} \alpha\right\} .
$$

Note that $\alpha$ is an upper bound of $\Sigma_{\operatorname{End}(\alpha)}$ for the relation $\preceq_{R}$, thus, by Proposition 2.12, we have $\operatorname{End}(\alpha) \in \mathcal{S}^{f}$.

Lemma 4.9. - Let $\alpha \in A_{\Gamma}^{+}$such that $\lg (\alpha)=n+1$. Set $X_{0}=\operatorname{End}(\alpha)$. Then

$$
\Phi(\alpha) \cap{\widetilde{\operatorname{Sal}^{(n)}}}^{(n)}(\Gamma)=f_{\alpha}\left(\left|\left(\mathcal{P}_{X_{0}}^{f}\right)^{\prime}\right|\right)
$$


Proof. - Since $\Phi(\alpha)=\left|\tilde{C}(\alpha)^{\prime}\right|$ and $\widetilde{\operatorname{Sal}^{(n)}}(\Gamma)=\left|\left({\widetilde{\operatorname{Sal}_{0}}}^{(n)}(\Gamma)\right)^{\prime}\right|$, we have

Hence, it suffices to show the following.

$$
\tilde{C}(\alpha) \cap \widetilde{\operatorname{Sal}}_{0}^{(n)}(\Gamma)=f_{\alpha}\left(\mathcal{P}_{X_{0}}^{f}\right)
$$

Let $u W_{X} \in \mathcal{P}_{X_{0}}^{f}$. As ever, we assume that $u$ is $(\emptyset, X)$-minimal. By definition, there exists $s \in X_{0}$ such that $\lg (s u)=\lg (u)+1$ and $s u$ is $(\emptyset, X)$-minimal. Since $X_{0}=\operatorname{End}(\alpha)$, we have $\sigma_{s} \preceq_{R} \alpha$, thus $\alpha$ can be written in the form $\alpha=\beta \sigma_{s}$, where $\beta \in A_{\Gamma}^{+}$. Since $\lg (s u)=\lg (u)+1$, we have $\tau(s u)=\sigma_{s} \tau(u)$, thus $\alpha \tau(u)=\beta \tau(s u)$, therefore $f_{\alpha}\left(u W_{X}\right)=$ $(\alpha \tau(u), X)=(\beta \tau(s u), X) \in \tilde{C}(\beta)$. On the other hand, $\lg (\beta)=n$, thus $f_{\alpha}\left(u W_{X}\right) \in \tilde{C}(\alpha) \cap \widetilde{\operatorname{Sal}_{0}^{(n)}}(\Gamma)$.

Let $(\gamma, Z) \in \tilde{C}(\alpha) \cap \widetilde{\operatorname{Sal}}_{0}^{(n)}(\Gamma)$. There exists $\beta \in A_{\Gamma}^{+}$such that $\lg (\beta) \leqslant n$ and $(\gamma, Z) \in \tilde{C}(\beta)$. There exist $u, v \in W$ such that $u$ and $v$ are $(\emptyset, Z)$ minimal and $\gamma=\alpha \tau(u)=\beta \tau(v)$. It is easily shown in the same way as in the proof of Lemma 4.8 that $\tau(u) \vee_{R} \tau(v)$ exists, that this element is of the form $\tau(w)$ with $w \in W$, that $w$ is $(\emptyset, Z)$-minimal, and that $w$ can be written in the form $w=u^{\prime} u=v^{\prime} v$ with $\lg (w)=\lg \left(u^{\prime}\right)+\lg (u)=\lg \left(v^{\prime}\right)+\lg (v)$. Note that, since $\lg (\beta)<\lg (\alpha)$ and $\alpha \tau(u)=\beta \tau(v)$, we have $\lg (u)<\lg (v)$, thus $u^{\prime} \neq 1$. We choose $s \in S$ such that $\lg \left(u^{\prime} s\right)=\lg \left(u^{\prime}\right)-1$. Set $u^{\prime \prime}=u^{\prime} s$. By
the above, $\tau\left(u^{\prime}\right)=\tau\left(u^{\prime \prime}\right) \sigma_{s}$. Let $\gamma_{0} \in A_{\Gamma}^{+}$such that $\gamma=\gamma_{0} \tau(w)$. We have $\alpha=\gamma_{0} \tau\left(u^{\prime}\right)=\gamma_{0} \tau\left(u^{\prime \prime}\right) \sigma_{s}$, thus $s \in X_{0}$. Finally, $\lg (s u)=\lg (u)+1$ (since $\left.\lg (w)=\lg \left(u^{\prime}\right)+\lg (u)\right)$ and $s u$ is $(\emptyset, Z)$-minimal (since $w$ is ( $(, Z)$-minimal), thus $u W_{Z} \in \mathcal{P}_{X_{0}}^{f}$. This shows that $(\gamma, Z)=f_{\alpha}\left(u W_{Z}\right) \in f_{\alpha}\left(\mathcal{P}_{X_{0}}^{f}\right)$.

Proof of Theorem 4.3. - We start by proving by induction on $n$ that $\widetilde{\text { Sal }}{ }^{(n)}(\Gamma)$ is contractible. If $n=0$, then $\widetilde{\operatorname{Sal}}^{(0)}(\Gamma)=\Phi(1)$, thus, by Lemma 4.7, $\widetilde{\mathrm{Sal}}^{(0)}(\Gamma)$ is contractible.

Now, we assume that $n \geqslant 0$ and $\widetilde{\mathrm{Sal}}^{(n)}(\Gamma)$ is contractible. Let $\alpha \in A_{\Gamma}^{+}$ such that $\lg (\alpha)=n+1$. By Lemma 4.7, $\Phi(\alpha)$ is contractible. Moreover, by Lemma 4.9, $\Phi(\alpha) \cap \widetilde{\text { Sal }}^{(n)}(\Gamma)$ is contractible. It follows that the embedding of
 is a deformation retract of $\Phi(\alpha)$ (see [32, Thm. 4.5]). We fix a deformation


We define a map

$$
h: \widetilde{\mathrm{Sal}}^{(n+1)}(\Gamma) \times[0,1] \rightarrow \widetilde{\mathrm{Sal}}^{(n+1)}
$$

as follows. Let $\alpha \in A_{\Gamma}^{+}$such that $\lg (\alpha) \leqslant n+1$. If $\lg (\alpha) \leqslant n$, we set $h(x, t)=$ $x$ for all $(x, t) \in \Phi(\alpha) \times[0,1]$. If $\lg (\alpha)=n+1$, we set $h(x, t)=h_{\alpha}(x, t)$ for all $(x, t) \in \Phi(\alpha) \times[0,1]$. Lemma 4.8 implies that $h$ is well-defined. It is clear from the above that $h$ is a deformation retraction of $\widetilde{\operatorname{Sal}}^{(n+1)}(\Gamma)$ onto $\widetilde{\text { Sal }}^{(n)}(\Gamma)$, thus $\widetilde{\text { Sal }}^{(n+1)}(\Gamma)$ is contractible as $\widetilde{\text { Sal }}^{(n)}(\Gamma)$ is.

Since

$$
\widetilde{\mathrm{Sal}}^{+}(\Gamma)=\bigcup_{n=0}^{\infty} \widetilde{\mathrm{Sal}}^{(n)}(\Gamma),
$$

we conclude by Theorem 2.1 that $\widetilde{\mathrm{Sal}^{+}}(\Gamma)$ is contractible.

## 4.3. $K(\pi, 1)$ problem for Artin groups of spherical type

Theorem 4.10 (Deligne [26]). - If $\Gamma$ is a spherical type Coxeter graph, then $\operatorname{Sal}(\Gamma)$ is an Eilenberg MacLane space.

Proof. - According to the statement of Theorem 2.13, we set $\Delta=\vee_{L} \Sigma$. We have the following chain of subcomplexes.

$$
\widetilde{\mathrm{Sal}}^{+}(\Gamma) \subset \Delta^{-1} \widetilde{\mathrm{Sal}}^{+}(\Gamma) \subset \cdots \subset \Delta^{-n} \widetilde{\mathrm{Sal}}^{+}(\Gamma) \subset \Delta^{-n-1} \widetilde{\mathrm{Sal}}^{+}(\Gamma) \subset \cdots
$$

$$
K(\pi, 1) \text { conjecture for Artin groups }
$$

The subcomplex $\Delta^{-n} \widetilde{\text { Sal }}^{+}(\Gamma)$ is contractible by Theorem 4.3, and $\cup_{n=0}^{\infty} \Delta^{-n} \widetilde{\operatorname{Sal}}^{+}(\Gamma)=\widetilde{\operatorname{Sal}}(\Gamma)$ by Theorem 2.13. We conclude by Theorem 2.1 that $\widetilde{\operatorname{Sal}}(\Gamma)$ is contractible.

## 5. Parabolic subgroups, FC type Artin groups, and generalizations

Let $\Gamma$ be a Coxeter graph, and let $\left(A_{\Gamma}, \Sigma\right)=(A, \Sigma)$ be its Artin system. For $X \subset S$, we set $\Sigma_{X}=\left\{\sigma_{s} \mid s \in X\right\}$, and we denote by $A_{X}$ the subgroup of $A$ generated by $\Sigma_{X}$. Such a subgroup is called standard parabolic subgroup of $A$. Recall that, for $X \subset S$, we set $M_{X}=\left(m_{s, t}\right)_{s, t \in X}$, where $M=\left(m_{s, t}\right)_{s, t \in S}$ is the Coxeter matrix of the Coxeter graph $\Gamma$, we denote by $\Gamma_{X}$ the Coxeter graph of $M_{X}$, and we denote by $W_{X}$ the subgroup of $W=W_{\Gamma}$ generated by $X$. By [3], the pair $\left(W_{X}, X\right)$ is the Coxeter system of $\Gamma_{X}$. The subgroup $W_{X}$ is called standard parabolic subgroup of $W$.

Let $T$ be a subset of $S$. Set $\mathcal{S}_{T}^{f}=\left\{X \in \mathcal{S}^{f} \mid X \subset T\right\}$. Observe that the inclusion $\left(W_{T} \times \mathcal{S}_{T}^{f}\right) \hookrightarrow\left(W \times \mathcal{S}^{f}\right)$ induces an embedding $\iota_{T}: \operatorname{Sal}\left(\Gamma_{T}\right) \hookrightarrow$ $\operatorname{Sal}(\Gamma)$ which is equivariant under the action of $W_{T}$. The starting point of the present section is the following theorem proved in [31]. It will be the key in the proofs of several results on standard parabolic subgroups and on some families of Artin groups.

Theorem 5.1 (Godelle, Paris [31]). - Let $T$ be a subset of S. Then the embedding $\iota_{T}: \operatorname{Sal}\left(\Gamma_{T}\right) \hookrightarrow \operatorname{Sal}(\Gamma)$ admits a retraction $\pi_{T}: \operatorname{Sal}(\Gamma) \rightarrow \operatorname{Sal}\left(\Gamma_{T}\right)$ which is equivariant under the action of $W_{T}$.

Proof. - It suffices to determine a function $\pi_{T}:\left(W \times \mathcal{S}^{f}\right) \rightarrow\left(W_{T} \times \mathcal{S}_{T}^{f}\right)$ that satisfies the following properties.

- $\pi_{T}(u, X)=(u, X)$ for all $(u, X) \in W_{T} \times \mathcal{S}_{T}^{f}$,
- $\pi_{T}$ is equivariant under (left) action of $W_{T}$,
- if $(u, X) \preceq(v, Y)$, then $\pi_{T}(u, X) \preceq \pi_{T}(v, Y)$.

Let $(u, X) \in W \times \mathcal{S}^{f}$. We write $u=u_{0} u_{1}$, where $u_{0} \in W_{T}$ and $u_{1}$ is $(T, \emptyset)$-minimal. Let $X_{0}=T \cap u_{1} X u_{1}^{-1}$. Then we set

$$
\pi_{T}(u, X)=\left(u_{0}, X_{0}\right)
$$

Note that, since $W_{X_{0}} \subset u_{1} W_{X} u_{1}^{-1}$, the group $W_{X_{0}}$ is finite, thus $X_{0} \in \mathcal{S}_{T}^{f}$.
It is easily seen that $\pi_{T}(u, X)=(u, X)$ for all $(u, X) \in W_{T} \times \mathcal{S}_{T}^{f}$, and that $\pi_{T}$ is equivariant under the action of $W_{T}$. So, it remains to show that,
if $(u, X),(v, Y) \in W \times \mathcal{S}^{f}$ are such that $(u, X) \preceq(v, Y)$, then $\pi_{T}(u, X) \preceq$ $\pi_{T}(v, Y)$.

Let $(u, X),(v, Y) \in W \times \mathcal{S}^{f}$ such that $(u, X) \preceq(v, Y)$. Set $u=u_{0} u_{1}$ and $v=v_{0} v_{1}$, where $u_{0}, v_{0} \in W_{T}$, and $u_{1}, v_{1}$ are $(T, \emptyset)$-minimal. Let $X_{0}=$ $T \cap u_{1} W_{X} u_{1}^{-1}$ and $Y_{0}=T \cap v_{1} W_{Y} v_{1}^{-1}$. Then $\pi_{T}(u, X)=\left(u_{0}, X_{0}\right)$ and $\pi_{T}(v, Y)=\left(v_{0}, Y_{0}\right)$. Let $w=v^{-1} u$, and let $w_{0}=v_{0}^{-1} u_{0}$. Since $(u, X) \preceq$ $(v, Y)$, we have $X \subset Y, w \in W_{Y}$, and $w$ is $(\emptyset, X)$-minimal. We should show that $X_{0} \subset Y_{0}, w_{0} \in W_{Y_{0}}$, and $w_{0}$ is $\left(\emptyset, X_{0}\right)$-minimal. We argue by induction on the length of $w$. It is easily checked that, if $w=1$, then $u_{0}=v_{0}$ (thus $\left.w_{0}=1\right), u_{1}=v_{1}$, and $X_{0} \subset Y_{0}$, thus $\pi_{T}(u, X) \preceq \pi_{T}(v, Y)$. So, we may assume that $\lg (w) \geqslant 1$ plus the induction hypothesis.

We write $w=s w^{\prime}$, where $s \in Y, w^{\prime} \in W_{Y}$, and $\lg \left(w^{\prime}\right)=\lg (w)-1$. Let $v^{\prime}=v s$. The element $\left(v^{\prime}\right)^{-1} u=w^{\prime}$ lies in $W_{Y}$ and is $(\emptyset, X)$-minimal (since $w$ is), thus $(u, X) \preceq\left(v^{\prime}, Y\right)$. Set $v^{\prime}=v_{0}^{\prime} v_{1}^{\prime}$, where $v_{0}^{\prime} \in W_{T}$ and $v_{1}^{\prime}$ is $(T, \emptyset)$ minimal, and set $Y_{0}^{\prime}=T \cap\left(v_{1}^{\prime}\right) W_{Y}\left(v_{1}^{\prime}\right)^{-1}$. By the induction hypothesis, we have $\left(u_{0}, X_{0}\right)=\pi_{T}(u, X) \preceq \pi_{T}\left(v^{\prime}, Y\right)=\left(v_{0}^{\prime}, Y_{0}^{\prime}\right)$. Set $w_{0}^{\prime}=\left(v_{0}^{\prime}\right)^{-1} u_{0}$. Then $X_{0} \subset Y_{0}^{\prime}, w_{0}^{\prime} \in W_{Y_{0}^{\prime}}$, and $w_{0}^{\prime}$ is $\left(\emptyset, X_{0}\right)$-minimal.

Suppose that $v_{1} s$ is $(T, \emptyset)$-minimal. Then $v_{0}^{\prime}=v_{0}$ and $v_{1}^{\prime}=v_{1} s$. Moreover, it is easily seen that, in that case, $Y_{0}=Y_{0}^{\prime}\left(\right.$ thus $\left.X_{0} \subset Y_{0}\right)$ and $w_{0}=w_{0}^{\prime}$ (thus $w_{0} \in W_{Y_{0}}$ and $w_{0}$ is $\left(\emptyset, X_{0}\right)$-minimal). Hence, $\pi_{T}(u, X) \preceq \pi_{T}(v, Y)$.

Suppose now that $v_{1} s$ is not $(T, \emptyset)$-minimal. We have $\lg \left(v_{1} s\right)>\lg \left(v_{1}\right)$, otherwise $v_{1} s$ would be $(T, \emptyset)$-minimal since $v_{1}$ is. Furthermore, by Proposition 2.9, there exists $t \in T$ such that $\lg \left(t v_{1} s\right)<\lg \left(v_{1} s\right)$. We also have $\lg \left(t v_{1}\right)>\lg \left(v_{1}\right)$, since $v_{1}$ is $(T, \emptyset)$-minimal. By Theorem 2.8, these inequalities imply that $t v_{1}=v_{1} s$. Then $v_{0}^{\prime}=v_{0} t, v_{1}^{\prime}=v_{1}$, thus $Y_{0}=Y_{0}^{\prime}$ and $w_{0}=t w_{0}^{\prime}$. A first consequence of this is that $X_{0} \subset Y_{0}=Y_{0}^{\prime}$ and $w_{0} \in W_{Y_{0}}$ (since $w_{0}^{\prime} \in W_{Y_{0}}$ and $t=v_{1} s v_{1}^{-1} \in T \cap v_{1} W_{Y} v_{1}^{-1}=Y_{0}$ ). It remains to prove that $w_{0}$ is $\left(\emptyset, X_{0}\right)$-minimal. Suppose not. Then we have $\lg \left(w_{0}\right)=\lg \left(t w_{0}^{\prime}\right)>\lg \left(w_{0}^{\prime}\right)$, otherwise $w_{0}$ would be $\left(\emptyset, X_{0}\right)$-minimal since $w_{0}^{\prime}$ is. By Proposition 2.9, there exists $x \in X_{0}$ such that $\lg \left(t w_{0}^{\prime} x\right)<\lg \left(t w_{0}^{\prime}\right)$. We also have $\lg \left(w_{0}^{\prime} x\right)>\lg \left(w_{0}^{\prime}\right)$ since $w_{0}^{\prime}$ is $\left(\emptyset, X_{0}\right)$-minimal. By Theorem 2.8, it follows that $t w_{0}^{\prime}=w_{0}^{\prime} x=w_{0}$. Hence,

$$
\begin{array}{cc} 
& x=\left(w_{0}^{\prime}\right)^{-1} t\left(w_{0}^{\prime}\right)=u_{0}^{-1}\left(v_{0}^{\prime}\right) t\left(v_{0}^{\prime}\right)^{-1} u_{0} \in W_{X_{0}}=W_{T} \cap u_{1} W_{X} u_{1}^{-1} \\
\Rightarrow & u^{-1} v_{0} t v_{0}^{-1} u=u^{-1} v s v^{-1} u=w^{-1} s w \in W_{X} \\
\Rightarrow & s w W_{X}=w^{\prime} W_{X}=w W_{X} .
\end{array}
$$

This contradicts the fact that $w$ is $(\emptyset, X)$-minimal (recall that $\lg \left(w^{\prime}\right)<$ $\lg (w))$. So, $w_{0}$ is $\left(\emptyset, X_{0}\right)$-minimal. We conclude that $\pi_{T}(u, X) \preceq \pi_{T}(v, Y)$.

$$
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$$

Let $\bar{\iota}_{T}: \overline{\operatorname{Sal}}\left(\Gamma_{X}\right)=\operatorname{Sal}\left(\Gamma_{X}\right) / W_{X} \rightarrow \overline{\operatorname{Sal}}(\Gamma)=\operatorname{Sal}(\Gamma) / W$ denote the map induced by $\iota_{T}: \operatorname{Sal}\left(\Gamma_{T}\right) \rightarrow \operatorname{Sal}(\Gamma)$.

Lemma 5.2.- Let $T \subset S$. Then $\bar{\iota}_{T}: \overline{\operatorname{Sal}}\left(\Gamma_{T}\right) \rightarrow \overline{\operatorname{Sal}}(\Gamma)$ is an embedding.
Proof. - Let $x, y$ be two points in $\operatorname{Sal}\left(\Gamma_{T}\right) \subset \operatorname{Sal}(\Gamma)$ that belong to the same $W$-orbit. Let $w \in W$ such that $y=w x$. The point $x$ (resp. $y$ ) lies in the interior of some cell $\mathbb{B}(u, X)$ (resp. $\mathbb{B}(v, Y))$ of $\operatorname{Sal}\left(\Gamma_{T}\right)$. Since $w$ sends cells to cells, we shall have $w \mathbb{B}(u, X)=\mathbb{B}(w u, X)=\mathbb{B}(v, Y)$, thus $X=Y$ and $v=w u$. Hence, $w=v u^{-1} \in W_{T}$ (since $\left.u, v \in W_{T}\right)$.

Consider the cellular decomposition of $\overline{\operatorname{Sal}}(\Gamma)$ described in Subsection 3.3. Let $T$ be a subset of $S$. Observe that, for all $X \in \mathcal{S}_{T}^{f}$, the map $\bar{\iota}_{T}$ sends the cell $\overline{\mathbb{B}}(X)$ of $\overline{\operatorname{Sal}}\left(\Gamma_{T}\right)$ homeomorphically to the cell $\overline{\mathbb{B}}(X)$ of $\overline{\operatorname{Sal}}(\Gamma)$. Observe also that, for all $s \in T$, the map $\bar{\iota}_{T}$ preserves the orientation of $\bar{a}_{s}=\overline{\mathbb{B}}(\{s\})$. Hence,

Lemma 5.3. - Let $T$ be a subset of $S$. Then the homomorphism $\left(\bar{\iota}_{T}\right)_{*}$ : $\pi_{1}\left(\overline{\operatorname{Sal}}\left(\Gamma_{T}\right), x_{0}\right)=A_{\Gamma_{T}} \rightarrow \pi_{1}\left(\overline{\operatorname{Sal}}(\Gamma), x_{0}\right)=A_{\Gamma}$ coincides with the natural homomorphism $A_{\Gamma_{T}} \rightarrow A_{\Gamma}$ which sends $\sigma_{s}$ to $\sigma_{s}$ for all $s \in T$.

Theorem 5.4 (Van der Lek [35]). - Let $T$ be a subset of $S$. Then the natural homomorphism $A_{\Gamma_{T}} \rightarrow A_{\Gamma}$ which sends $\sigma_{s}$ to $\sigma_{s}$ for all $s \in T$ is injective. In other words, the pair $\left(A_{T}, \Sigma_{T}\right)$ is an Artin system of $\Gamma_{T}$.

Proof. - We have the following commutative diagram, where the lines are exact sequences.

$$
\begin{array}{ccccccccc}
1 & \rightarrow & C A_{\Gamma_{T}} & \longrightarrow & A_{\Gamma_{T}} & \longrightarrow & W_{\Gamma_{T}} & \rightarrow & 1 \\
& & \downarrow & & \downarrow & & \downarrow & & \\
1 & \rightarrow & C A_{\Gamma} & \longrightarrow & A_{\Gamma} & \longrightarrow & W_{\Gamma} & \rightarrow & 1
\end{array}
$$

By Theorem 5.1, the homomorphism $C A_{\Gamma_{T}} \rightarrow C A_{\Gamma}$ has a retraction, thus it is injective. The homomorphism $W_{\Gamma_{T}} \rightarrow W_{\Gamma}$ is injective by [3]. We conclude by the five lemma that the homomorphism $A_{\Gamma_{T}} \rightarrow A_{\Gamma}$ is injective.

Theorem 5.5 (Godelle, Paris [31]). - Let $T$ be a subset of $S$. If $\operatorname{Sal}(\Gamma)$ is an Eilenberg MacLane space, then $\operatorname{Sal}\left(\Gamma_{T}\right)$ is also an Eilenberg MacLane space.

Proof. - By Theorem 5.1, for all $n \geqslant 1$, the homomorphism $\left(\iota_{T}\right)_{*}$ : $\pi_{n}\left(\operatorname{Sal}\left(\Gamma_{T}\right), x(1)\right) \rightarrow \pi_{n}(\operatorname{Sal}(\Gamma), x(1))$ has a retraction $\pi_{n}(\operatorname{Sal}(\Gamma), x(1)) \rightarrow$ $\pi_{n}\left(\operatorname{Sal}\left(\Gamma_{T}\right), x(1)\right)$, hence it is injective. Assume that $\operatorname{Sal}(\Gamma)$ is an Eilenberg MacLane space. Then $\pi_{n}(\operatorname{Sal}(\Gamma), x(1))=\{1\}$ for all $n \geqslant 2$, thus, by the
above, $\pi_{n}\left(\operatorname{Sal}\left(\Gamma_{T}\right), x(1)\right)=\{1\}$ for all $n \geqslant 2$, therefore $\operatorname{Sal}\left(\Gamma_{T}\right)$ is an Eilenberg MacLane space.

Theorem 5.6 (Ellis, Skldberg [28]). - Let $s, t \in S$ such that $m_{s, t}=\infty$. Set $T=S \backslash\{s\}$ and $R=S \backslash\{t\}$. If $\operatorname{Sal}\left(\Gamma_{T}\right)$ and $\operatorname{Sal}\left(\Gamma_{R}\right)$ are both Eilenberg MacLane spaces, then $\operatorname{Sal}(\Gamma)$ is an Eilenberg MacLane space.

Proof. - Let $X \in \mathcal{S}^{f}$. If $s \in X$, then $t \notin X$, thus $X \in \mathcal{S}_{R}^{f}$. Similarly, if $t \in X$, then $s \notin X$, thus $X \in \mathcal{S}_{T}^{f}$. Note that, if $s \notin X$ and $t \notin X$, then $X \in \mathcal{S}_{T \cap R}^{f}$. By Lemma 5.2, $\overline{\operatorname{Sal}}\left(\Gamma_{T}\right)$ and $\overline{\operatorname{Sal}}\left(\Gamma_{R}\right)$ are subcomplexes of $\overline{\operatorname{Sal}}(\Gamma)$. By the above, we have $\overline{\operatorname{Sal}}\left(\Gamma_{T}\right) \cup \overline{\operatorname{Sal}}\left(\Gamma_{R}\right)=\overline{\operatorname{Sal}}(\Gamma)$ and $\overline{\operatorname{Sal}}\left(\Gamma_{T}\right) \cap \overline{\operatorname{Sal}}\left(\Gamma_{R}\right)=\overline{\operatorname{Sal}}\left(\Gamma_{T \cap R}\right)$. By Lemma 5.3, the homomorphisms $\pi_{1}\left(\overline{\operatorname{Sal}}\left(\Gamma_{T \cap R}\right), x_{0}\right) \quad \rightarrow \quad \pi_{1}\left(\overline{\operatorname{Sal}}\left(\Gamma_{T}\right), x_{0}\right) \quad$ and $\quad \pi_{1}\left(\overline{\operatorname{Sal}}\left(\Gamma_{T \cap R}\right), x_{0}\right) \quad \rightarrow$ $\pi_{1}\left(\overline{\operatorname{Sal}}\left(\Gamma_{R}\right), x_{0}\right)$ are injective. The complexe $\overline{\operatorname{Sal}}\left(\Gamma_{T}\right)$ is an Eilenberg Maclane space, since $\operatorname{Sal}\left(\Gamma_{T}\right)$ is a covering of $\overline{\operatorname{Sal}}\left(\Gamma_{T}\right)$ and, by hypothesis, $\operatorname{Sal}\left(\Gamma_{T}\right)$ is an Eilenberg MacLane space. Similarly, $\overline{\operatorname{Sal}}\left(\Gamma_{R}\right)$ is an Eilenberg MacLane space. Furthermore, by applying Theorem 5.5 to $\Gamma_{T \cap R}$ and $\Gamma_{T}$ we get that $\operatorname{Sal}\left(\Gamma_{T \cap R}\right)$ is an Eilenberg MacLane space, thus $\overline{\operatorname{Sal}}\left(\Gamma_{T \cap R}\right)$ is an Eilenberg MacLane space. By Theorem 2.4, it follows that $\overline{\operatorname{Sal}}(\Gamma)$ is an Eilenberg MacLane space, thus $\operatorname{Sal}(\Gamma)$ is an Eilenberg MacLane space.

Recall that a subset $T$ of $S$ is said to be free of infinity if $m_{s, t} \neq \infty$ for all $s, t \in T$. We denote by $\mathcal{S}^{<\infty}$ the set of subsets of $S$ that are free of infinity. Note that $\mathcal{S}^{f} \subset \mathcal{S}^{<\infty}$. Recall also that $\Gamma$ is said to be of $F C$ type if $\mathcal{S}^{f}=\mathcal{S}^{<\infty}$.

Corollary 5.7 (Ellis, Sköldberg [28]). - If $\operatorname{Sal}\left(\Gamma_{T}\right)$ is an Eilenberg MacLane space for all $T \in \mathcal{S}^{<\infty}$, then $\operatorname{Sal}(\Gamma)$ is an Eilenberg MacLane space.

Proof. - We argue by induction on $|S|$. If $|S|=1$, then $S$ is free of infinity, thus $\operatorname{Sal}(\Gamma)=\operatorname{Sal}\left(\Gamma_{S}\right)$ is an Eilenberg MacLane space. More generally, if $S$ itself is free of infinity, then $\operatorname{Sal}(\Gamma)=\operatorname{Sal}\left(\Gamma_{S}\right)$ is an Eilenberg MacLane space. Assume that $|S| \geqslant 2$ and $S$ is not free of infinity, plus the induction hypothesis. Let $s, t \in S$ such that $m_{s, t}=\infty$. Set $T=S \backslash\{s\}$ and $R=S \backslash\{t\}$. By the induction hypothesis, $\operatorname{Sal}\left(\Gamma_{T}\right)$ and $\operatorname{Sal}\left(\Gamma_{R}\right)$ are Eilenberg MacLane spaces. By Theorem 5.6, it follows that $\operatorname{Sal}(\Gamma)$ is an Eilenberg MacLane space.

Corollary 5.8. - (Charney, Davis [13]). The complex $\operatorname{Sal}(\Gamma)$ is an Eilenberg MacLane space if $\Gamma$ is a Coxeter graph of FC type.

Proof. - By Theorem 4.10, $\operatorname{Sal}\left(\Gamma_{T}\right)$ is an Eilenberg MacLane space for all $T \in \mathcal{S}^{f}$. By definition, $\mathcal{S}^{f}=\mathcal{S}^{<\infty}$, thus, by Corollary 5.7, $\operatorname{Sal}(\Gamma)$ is an Eilenberg MacLane space.

## $K(\pi, 1)$ conjecture for Artin groups

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