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# LOCAL GALOIS GROUP OF IRREGULAR $q$-DIFFERENCE EQUATIONS 

by Virginie BUGEAUD

Abstract. - Relying on the normal forms of pure isoclinic modules with non integral slopes, due to van der Put and Reversat, we extend the isoformal analytic classification of Ramis, Sauloy and Zang made for the case of integral slopes. We obtain an analogue of Birkhoff-Guenther normal forms in the case of two slopes which are not integral. Computing Stokes operators in the case of two slopes, we prove a theorem of classification by the $H^{1}$. Moreover, we describe in a matricial form the formal Galois group when the denominator of the slopes is fixed. Finally, we prove a density theorem similar to that of Ramis and Sauloy to describe the Galois group.

Résumé. - Sur la base des travaux de van der Put et Reversat sur les formes normales des modules purs isoclines à pentes non entières, nous poursuivons la classification analytique locale des modules aux q-différences réalisée pour le cas des modules à pentes entières par Ramis, Sauloy et Zang. Nous obtenons un analoque des formes normales de Birkhoff-Guenther dans le cas à deux pentes non entières. En calculant les opérateurs de Stokes dans le cas à deux pentes, nous démontrons un théorème de classification par le $H^{1}$. De plus, nous décrivons le groupe de Galois sous forme matricielle dans le cas où le dénominateur des pentes est fixé. Enfin, nous démontrons un théorème de densité similaire à celui de Ramis et Sauloy pour décrire le groupe de Galois.

## Introduction

This article deals with linear $q$-difference equations. These are functional equations defined with an operator denoted by $\sigma_{q}$ which operates on complex functions by $\sigma_{q}(f(z))=f(q z)$. As in differential theory, a Newton polygon can be associated to a $q$-difference equation, and it gives rational slopes.

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Studying analytic linear $q$-difference equations is the same as studying the systems:

$$
Y(q z)=A(z) Y(z)
$$

where $A(z)$ is an invertible matrix with analytic coefficients, that is, in $K=\mathbb{C}(\{z\})$. In this article, we study pairs $\left(K^{n}, \Phi_{A}\right)$ which represent $q$ difference modules and where $\Phi_{A}: K^{n} \rightarrow K^{n}$ is a $\sigma_{q}$-linear automorphism of $K^{n}$ defined by $\Phi_{A}(X)=A^{-1} \sigma_{q}(X)$.

Birkhoff and Guenther in [1] said that any $q$-difference system is equivalent to a polynomial system, which means that the matrix $A$ has polynomial coefficients. It is easy to prove that a $q$-difference module with only one integral slope $\mu$ is equivalent to a module with matrix $A$ of the form $z^{\mu} C$ where $C \in \mathrm{GL}_{n}(\mathbb{C})$. This form, under some additional conditions, is called normal form.
van der Put and Reversat gave a normal form to any $q$-difference module with only one non integral slope, considering irreducible and indecomposable modules. As for $q$-difference module with several slopes, Ramis, Sauloy and Zhang found an explicit method to obtain a matrix with coefficients in $\mathbb{C}\left[z, z^{-1}\right]$. Nevertheless, it was only done when the slopes are integral. This form is called the Birkhoff-Guenther normal form. Local analytic classification, in the case of integral slopes, is partially built thanks to these normal forms.

Another aspect of $q$-difference equations is Galois theory. Many approaches exist to define the Galois group associated with a $q$-difference module (Picard-Vessiot theory by van der Put and Singer in [8], tannakian theory ...). The main difficulty compared to differential equations, lies in the fact that the constant field is the field of elliptic functions, so it is rather big: yet, one looks for classification and Galois theory over the complex numbers.

The approach of Sauloy in [14] is analytic and uses tannakian theory. In his article, Sauloy obtained a description of the local Galois group of $q$-difference equations with null slope. Later, Ramis and Sauloy deduced an explicit matricial description of the formal Galois group of $q$-difference equations with integral slopes.

Local analytic classification by Ramis, Sauloy and Zhang and the construction of Stokes operators enabled Ramis and Sauloy to study the local Galois group of $q$-difference equations with integral slopes. They obtained a Zariski dense subgroup of the local Galois group generated by the local formal Galois group and by Stokes operators associated to $q$-alien derivations.

In this article, we have tried to complete local analytic classification of $q$-difference modules and to compute Stokes operators in the case of non integral slopes. The case of two slopes is totally done. We also go on understanding local Galois theory: we obtain an explicit description of the local formal Galois group and a density theorem to describe the local Galois group in the case of non integral slopes. The case of three slopes or more is incomplete here, we comment on this at the beginning of Section 2.

## Contents

The complete description of normal forms associated with pure isoclinic modules with non integral slopes, by van der Put and Reversat in [7], is our starting point to extend a part of the results of [10], [11] and [12] about classification and Galois group. Note that van der Put and Reversat use Picard-Vessiot theory, while we follow a tannakian approach, so that our results in Galois theory are mostly independent of theirs.

In the first section, we introduce notations and definitions about $q$ difference modules. We define the Newton polygon and the slopes. We give a new, effective proof of the theorems of [7] which describe the normal forms of $q$-difference modules with a unique non integral slope. We also study the tensor product of two irreducible modules: we prove with an explicit isomorphism that a tensor product of two irreducible modules is a direct sum of irreducible modules. This result is one of the keys of the isoformal analytic classification in the case of two slopes not necessarily integral.

The second section deals with the analytic classification, it consists, as in [12], in describing the equivalence classes of modules which have the same graded module. We are looking for a Birkhoff-Guenther normal form for the case of two slopes. It exists when the slopes are integral for any number of slopes (see [12]). In the case of two slopes no necessarily integral, we prove that any class admits a representative in polynomial form and we obtain an isomorphism between the set of isoformal analytic classes and an explicit quotient of a polynomial space (Theorem 2.8).

In the third section, we want to compute Stokes operators. Like in the case of integral slopes, we start by establishing a classification by the $H^{1}$ of the vector bundle associated with a $q$-difference module (Theorem 3.5). The cocycles obtained to prove Theorem 3.5 enable us to construct Stokes operators associated with a module with slopes non necessarily integral.

The last section is devoted to Galois theory. Our approach is tannakian. In Theorem 4.1, we give a matricial description of the formal Galois group. The case of two slopes leads us to study also extensions of representations of the Galois group (Theorem 4.12). Finally, proving that our Stokes operators are Galoisian shows us the way to the density theorem. The whole Galois group is generated by the Stokes operators obtained by iteration of the operator $\sigma_{q}$ and by the formal Galois group (Theorem 4.30).

## 1. Definitions

### 1.1. Notations

Let $K:=\mathbb{C}(\{z\})=\mathbb{C}\{z\}\left[z^{-1}\right]$ be the field of convergent Laurent series, namely meromorphic germs at 0 , it is the field of fractions of $\mathbb{C}\{z\}$. Let $\hat{K}:=\mathbb{C} \llbracket z \rrbracket\left[z^{-1}\right]$ be the field of fractions of $\mathbb{C} \llbracket z \rrbracket$, the ring of formal power series.

We fix $q \in \mathbb{C}^{*}$ such that $|q|>1$, and we define the operator $\sigma_{q}$ by $\sigma_{q}(f(z))=f(q z)$, it is an automorphism of the field $K$ (and of $\hat{K}$ ). We define also $\mathcal{D}_{K, \sigma_{q}}:=K\left\langle\sigma_{q}, \sigma_{q}^{-1}\right\rangle$ the Ore ring of $q$-difference operators $\sum_{\text {finite }} a_{i} \sigma_{q}^{i}$. It has an algebra structure, characterized by a commutation relation: for all $x \in K$, for all $k \in \mathbb{Z}, \sigma_{q}^{k} \cdot x=\sigma_{q}^{k}(x) . \sigma_{q}^{k}$. The ring $\mathcal{D}_{K, \sigma_{q}}:=$ $K\left\langle\sigma_{q}, \sigma_{q}^{-1}\right\rangle$ is left euclidean (cf. [12]).

We denote by $E_{q}$ the elliptic curve $E_{q}:=\mathbb{C}^{*} / q^{\mathbb{Z}}$, the natural projection $\mathbb{C}^{*} \rightarrow E_{q}$ induces a bijection between the fundamental annulus $C_{q}:=$ $\left\{z \in \mathbb{C}^{*}|1 \leqslant|z|<|q|\}\right.$ and $E_{q}$.

For all $r \in \mathbb{N}^{*}$, let $\xi_{r}=e^{\frac{2 i \pi}{r}}$ be a primitive $r$ th root of unity in $\mathbb{C}$. We choose once and for all $\tau \in \mathbb{C}^{*}$ such that $q=e^{2 i \pi \tau}, \operatorname{Im} \tau<0$. Let $q_{r}=e^{\frac{2 i \pi \tau}{r}}$ be a $r$ th root of $q$, so that compatibility relations are satisfied: $q_{r}^{r}=q$ and $q_{r s}^{s}=q_{r}$.

## 1.2. $q$-difference modules, morphisms

General references for this subsection and the following (e.g. cyclic vector lemma, Newton polygon, fuchsian equations...) are $[13,16]$.

Definition 1.1. - A $q$-difference module $M$ over $\left(K, \sigma_{q}\right)$ is a pair $(V, \Phi)$ where $V$ is a $K$-vector space with finite dimension and $\Phi$ a $\sigma_{q^{-}}$ linear automorphism on $V$, which means, for all $a \in K$, and for all $X \in V$, $\Phi(a X)=\sigma_{q}(a) \Phi(X)$.

A morphism of $q$-difference modules $M=\left(V_{1}, \Phi_{1}\right) \rightarrow N=\left(V_{2}, \Phi_{2}\right)$ is a $K$-linear application $F: V_{1} \rightarrow V_{2}$ such that $\Phi_{2} \circ F=F \circ \Phi_{1}$.

By choosing a basis of the $K$-vector space $V$, a $q$-difference module $M$ is isomorphic to a pair $\left(K^{n}, \Phi_{A}\right)$ where:

$$
\Phi_{A}(X)=A^{-1} \sigma_{q}(X), \quad A \in \mathrm{GL}_{n}(K)
$$

A morphism from $\left(K^{n}, \Phi_{A}\right)$ to $\left(K^{p}, \Phi_{B}\right)$ is a matrix $F \in M_{p, n}(K)$ satisfying $\sigma_{q}(F) A=B F$. An isomorphism from $\left(K^{n}, \Phi_{A}\right)$ to $\left(K^{n}, \Phi_{B}\right)$ is a matrix $F \in \operatorname{GL}_{n}(K)$ such that $F[A]=B$, where we define $F[A]:=\sigma_{q}(F) A F^{-1}$.

Definition 1.2. - Let $M=(V, \Phi)$ be a $q$-difference module of rank $n$ and let $e$ be a vector of the $K$-vector space $V$. We say that $e$ is a cyclic vector if the family $\underline{e}=\left(e, \Phi(e), \ldots, \Phi^{n-1}(e)\right)$ is a basis of $V$.

By the cyclic vector lemma, every $q$-difference module $M=(V, \Phi)$ admits a cyclic vector $e$. By defining for all $x \in V,\left(\sum_{i=0}^{n} a_{i} \sigma_{q}^{i}\right) . x:=\sum_{i=0}^{n} a_{i} \Phi^{i}(x)$, then, every $q$-difference module is isomorphic to a module $\mathcal{D}_{K, \sigma_{q}} / \mathcal{D}_{K, \sigma_{q}} P$ where $P \in \mathcal{D}_{K, \sigma_{q}}$ is entire unitary; it is obtained by expressing $\Phi^{n}(e)$ as a combination of the $\Phi^{i}(e)$ for $i=0, \ldots, n-1$.

Let us define the Newton polygon associated with a $q$-difference module. The $z$-adic valuation of $K$ or $\hat{K}$ is denoted by $v$ and defined by: $v\left(\sum a_{n} z^{n}\right)=\min _{a_{n} \neq 0} n$ and $v(0)=-\infty$.

Definition 1.3. - The Newton polygon associated with the operator $P=\sum a_{i} \sigma_{q}^{i} \in \mathcal{D}_{K, \sigma_{q}}$ is the convex hull of $\left\{(i, j) \in \mathbb{Z} \times \mathbb{R} \mid j \geqslant v\left(a_{i}\right)\right\}$ in $\mathbb{R}^{2}$.

The lower boundary of the Newton polygon is made of $k$ vectors $\left(r_{i}, d_{i}\right) \in$ $\mathbb{N}^{*} \times \mathbb{Z}$ ordered from left to right, the $\mu_{i}=d_{i} / r_{i}$ are the slopes of these vectors. Necessarily $\mu_{i} \in \mathbb{Q}$ and $\mu_{1}<\cdots<\mu_{k}$. The Newton function associated with $P$ is defined by $r_{P}\left(\mu_{i}\right)=r_{i}$ and $r_{P}(\mu)=0$ otherwise.

By [12, Theorem 2.2.1], all unitary entire $P$ such that $M \cong \mathcal{D}_{K, \sigma_{q}} / \mathcal{D}_{K, \sigma_{q}} P$ have the same Newton function denoted by $r_{M}$.

As a consequence, we can associate with a $q$-difference module a set of slopes $S(M)=\left\{\mu_{1}, \ldots, \mu_{k}\right\}$.

A module with only one slope is said to be pure isoclinic and a module which is a direct sum of pure isoclinic modules is said to be pure. More particularly, a pure isoclinic module of slope 0 is called a fuchsian module. The equivalence of this definition with the classical one by Birkhoff is proved in [13, 16].

In the formal case (over $\hat{K}$ ), every $q$-difference module $M$ is isomorphic to $M_{0}=P_{1} \oplus \cdots \oplus P_{k}$ where for all $i=1, \ldots, k, P_{i}$ is pure isoclinic of slope $\mu_{i}$ and rank $r_{M}\left(\mu_{i}\right)$.

In the analytic case, according to the canonical filtration by slopes in [16], for all $q$-difference module $M$ such that $S(M)=\left\{\mu_{1}, \ldots, \mu_{k}\right\}$ and $\mu_{1}<$ $\cdots<\mu_{k}$, there exists unique submodules such that $\{0\} \subset M_{1} \subset \cdots \subset$ $M_{k}=M$, where for all $i=1, \ldots, k, P_{i}=M_{i} / M_{i-1}$ is pure isoclinic of slope $\mu_{i}$ and rank $r_{M}\left(\mu_{i}\right)$. We denoted by gr $M$, the graded module $P_{1} \oplus \cdots \oplus P_{k}$, this module is pure by definition. In fact, gr is a functor from the category of $q$-differences modules to the category of pure $q$-differences modules. This functor is exact, faithful and tensor compatible (cf. [16]).

### 1.3. Normal forms

According to [12, 2.2.2], a pure isoclinic module with integral slope $\mu$ is isomorphic to a module of the form $\left(K^{n}, \Phi_{z^{\mu} A}\right)$, where $A \in \mathrm{GL}_{n}(\mathbb{C})$ and $S p(A) \subset C_{q}(S p(A)$ is the spectrum of the matrix $A)$. The matrix $A$ is unique up to conjugation in $\mathrm{GL}_{n}(\mathbb{C})$. It is the normal form of the module $M$. In this section, we give normal forms associated with $q$-difference modules with non integral slopes. These results are due to van der Put and Reversat in [7], but, except for Theorem 1.10 which we copy directly, we give different proofs and a concrete description that will be needed afterwards.

### 1.3.1. Irreducible modules

Definition 1.4. - An irreducible $q$-difference module is a non trivial $q$-difference module which has no submodules except $\{0\}$ and itself. As a $\mathcal{D}_{K, \sigma_{q}}$-module, an irreducible module is simple.

Theorem 1.5 ([7, Proposition 1.3]). - For all irreducible $q$-difference module $M$ over $K$ (or $\hat{K}$ ), there are unique integers $d \in \mathbb{Z}, r \geqslant 1$ with $\operatorname{gcd}(d, r)=1$, and a unique $c \in \mathbb{C}^{*}, 1 \leqslant|c|<|q|$, such that:

$$
M \cong E(r, d, c):=\mathcal{D}_{K, \sigma_{q}} / \mathcal{D}_{K, \sigma_{q}}\left(\sigma_{q}^{r}-q^{\frac{-d(r-1)}{2}} c^{-1} z^{-d}\right)
$$

Remark 1.6. - From this theorem, an irreducible module of rank $r>1$ is pure isoclinic with slope $\mu=d / r$ such that $\operatorname{gcd}(r, d)=1$. Conversely, a module of rank $r>1$ and of slope $\mu=d / r$ such that $\operatorname{gcd}(r, d)=1$, is irreducible. So, it is isomorphic to some $E(r, d, c)$ which can be written $\left(K^{r}, \Phi_{B}\right)$, where $B$ is the following invertible matrix:

$$
B:=\left(\begin{array}{cccc}
0 & 1 & & 0 \\
\vdots & & \ddots & \\
0 & & & 1 \\
q^{\frac{d(r-1)}{2}} c z^{d} & 0 & \ldots & 0
\end{array}\right)
$$

For convenience, we will often denote $c$ by $b^{r} . E\left(r, d, b^{r}\right)$ depends on $b^{r}$ and not on the choice of $b$. By convention, if $r=1, E(1, d, c)=\left(K, \Phi_{c z^{d}}\right)$.

More generally, every module of rank $r$ and slope $d / r(\operatorname{gcd}(d, r)=1)$ will be denoted by $E(r, d, c)=\left(K^{r}, \Phi_{B}\right)$ with $c \in \mathbb{C}^{*}$ but no necessarily in $C_{q}$.

Lemma 1.7. - Let $d \in \mathbb{Z}^{*}, r \in \mathbb{N}^{*}$ such that $\operatorname{gcd}(d, r)=1$ and let $c \in \mathbb{C}^{*}$, there is an isomorphism of $q$-difference modules:

$$
E(r, d, c) \cong E(r, d, q c)
$$

Proof. - We identify $E(r, d, c)$ with $\left(K^{r}, \Phi_{B}\right)$ and we denote by $e=$ ${ }^{t}(1,0, \ldots, 0)$ the cyclic vector associated with $E(r, d, c)=\left(K^{r}, \Phi\right)$. We have $\Phi^{r}(e)=q^{\frac{-d(r-1)}{2}} c^{-1} z^{-d} e$. We take $z^{-u} \Phi^{v}(e)$ as a new cyclic vector where $u, v \in \mathbb{Z}$ are Bezout's coefficients such that $u r+v d=1$. Indeed,

$$
\Phi^{r}\left(z^{-u} \Phi^{v}(e)\right)=q^{-(u r+v d)} q^{\frac{-d(r-1)}{2}} c^{-1} z^{-d} z^{-u} \Phi^{v}(e)
$$

Remark 1.8. - We set $K_{r}:=K\left(z^{1 / r}\right)$, it is an extension of the field $K$, and the automorphism $\sigma_{q_{r}}$ extends $\sigma_{q}: \sigma_{q_{r}}\left(f\left(z^{\prime}\right)\right)=f\left(q_{r} z^{\prime}\right)$ where $z^{\prime}=$ $z^{1 / r}$. Then $\left(K_{r}, \sigma_{q_{r}}\right)$ is $q_{r}$-difference field and the slopes are calculated with the $z^{\prime}$-adic valuation associated with $K_{r}$. The operation of ramification on $M$ consists in defining the $q_{r}$-difference module $M^{\prime}=K_{r} \otimes M$, where if $M=(V, \Phi)$ then $M^{\prime}=\left(V^{\prime}, \Phi^{\prime}\right), V^{\prime}=K_{r} \otimes_{K} V$ and $\Phi^{\prime}=\sigma_{q_{r}} \otimes \Phi$. If $\mu_{i}$ are the slopes of $M$, the slopes of $M^{\prime}$ are $r \mu_{i}$. If $M$ is irreducible and $M \cong E(r, d, c)$, we choose $b \in \mathbb{C}^{*}$ such that $c=b^{r}$, a matrix $A$ such that $\left(M^{\prime}, \Phi_{M^{\prime}}\right) \cong\left(K_{r}^{r}, \Phi_{z^{d / r} A}\right)$ is:

$$
A:=\left(\begin{array}{cccc}
b & & & 0 \\
& \xi_{r} b & & \\
& & \ddots & \\
& & & \xi_{r}^{(r-1)} b
\end{array}\right)
$$

The matrix of the isomorphism $G$ over $K_{r}$ such that $\sigma_{q_{r}}(G) B=z^{d / r} A G$ is:

$$
G=\left(\begin{array}{ccccc}
1 & 1 & \ldots & & 1 \\
\xi_{r}^{-1} & \xi_{r}^{-2} & \ldots & & 1 \\
\xi_{r}^{-2} & \xi_{r}^{-4} & & \ldots & 1 \\
\vdots & & & & \vdots \\
\xi_{r}^{-(r-1)} & \xi_{r}^{-2(r-1)} & \ldots & & 1
\end{array}\right)\left(\begin{array}{ccccc}
g_{1} & & & & \\
& g_{2} & & 0 & \\
& & \ddots & & \\
& 0 & & \ddots & \\
& & & & g_{r}
\end{array}\right)
$$

where $g_{i}=q^{\frac{d(r-1)}{2}} b^{r-i} q_{r}^{\frac{d(i-1)(2 r-i)}{2}} q_{r}^{-\operatorname{id}(r-1)} z^{\frac{-d(i-1)}{r}}$. In fact, these equations stay valid if $d$ and $r$ are not coprime.

### 1.3.2. Indecomposable modules

Definition 1.9. - An indecomposable $q$-difference module over $\hat{K}$ or $K$, is a non trivial $q$-difference module which can not split into the direct sum of two $q$-difference submodules.

Theorem 1.10 ([7, Corollary 1.6]). - Let $M$ be a pure isoclinic indecomposable $q$-difference module over $K$ (or $\hat{K}$ ). There are unique integers $d \in \mathbb{Z}^{*}, r \geqslant 1$ and $m \geqslant 1$ such that $\operatorname{gcd}(d, r)=1$ and unique $c \in \mathbb{C}^{*}$ satisfying $1 \leqslant|c|<|q|$ such that:

$$
M \cong E(r, d, c) \otimes_{K} U_{m}
$$

$U_{m}$ is the unipotent $q$-difference module $\left(K^{m}, \Phi_{W_{m}}\right)$ (or over $\hat{K}$ ), where $W_{m} \in \mathrm{GL}_{m}(\mathbb{C})$ is the Jordan block of rank $m$ :

$$
W_{m}:=\left(\begin{array}{ccc}
1 & 1 & 0 \\
& \ddots & 1 \\
& 0 & 1
\end{array}\right)
$$

(For the definition of the tensor product, see 1.4).
Remark 1.11. - If $M$ is indecomposable over $\hat{K}$ then $M$ is automatically pure isoclinic because in the formal case, $M$ is a direct sum of its maximal pure isoclinic submodules.

Theorem 1.10 tells nothing about an indecomposable $q$-difference module with several slopes. The study of modules with several slopes will be done in Section 2. Nevertheless, a pure isoclinic module is a direct sum of indecomposable pure isoclinic modules, therefore we have a normal form for every pure isoclinic $q$-difference module.

### 1.4. Tensor product

The tensor product of two $q$-difference modules $M=(V, \Phi)$ and $N=$ $(W, \Psi)$ is $M \otimes N=\left(V \otimes_{K} W, \Phi \otimes \Psi\right)$ where $\Phi \otimes \Psi$ is the unique $\sigma_{q}$-linear automorphism of $V \otimes_{K} W$ such that $x \otimes y \mapsto \Phi(x) \otimes \Psi(y)$.

Convention. - Let us write $e_{1}, \ldots, e_{m}$ for the canonical basis of $K^{m}$ and $f_{1}, \ldots, f_{n}$ the one of $K^{n}$. The family $\left(e_{i} \otimes f_{j}\right)_{i, j}$ form a basis of $K^{m} \otimes$ $K^{n}$. We will use convention " $\hat{\otimes}$ " to identify $K^{m} \otimes K^{n}$ with $K^{m n}$.

It consists in taking basis $\widehat{\mathcal{C}}=\left(e_{1} \otimes f_{1}, e_{2} \otimes f_{1}, \ldots, e_{m} \otimes f_{1}, \ldots, e_{1} \otimes\right.$ $\left.f_{n}, \ldots, e_{m} \otimes f_{n}\right)$. Let $A=\left(a_{i, j}\right) \in M_{m}(K)$ and $B=\left(b_{i, j}\right) \in M_{n}(K)$ two
matrices. With this convention, tensor product of $A$ and $B$ is denoted by $A \hat{\otimes} B$ and we have:

$$
A \hat{\otimes} B=\left(\begin{array}{cccc}
A b_{1,1} & A b_{1,2} & & \\
A b_{2,1} & A b_{2,2} & \ddots & \\
\vdots & \vdots & & \\
A b_{n, 1} & & & A b_{n, n}
\end{array}\right)
$$

Lemma 1.12. - If $F, G$ are matrices in $M_{m, n}(K)$ then $A F B=G$ if, and only if, $\left(A \hat{\otimes}^{t} B\right) \hat{F}=\hat{G}$, where $\hat{F}$ is the vector ${ }^{t}\left(f_{1,1}, f_{2,1}, \ldots, f_{m, 1}, \ldots\right.$, $\left.f_{1, n}, \ldots, f_{m, n}\right)$.

Proof. - Straightforward computation left to the reader.
Let us have look at the tensor product of two irreducible modules. An irreducible $q$-difference module with an integral slope $\mu \in \mathbb{Z}$ is necessarily of rank one and of the form $\left(K, \Phi_{a z^{\mu}}\right)$. We saw that an irreducible module with non integral slope is of the form $E(r, d, c)$. We will give explicit formula for the tensor product of two irreducible modules. It is mentioned in [7, p. 681], we will give more details in 1.13 and 1.14.

Proposition 1.13. - The tensor product of an irreducible $q$-difference module with non integral slope $\frac{d}{r}$ and an irreducible module with integral slope $\mu \in \mathbb{Z}$, of rank one, is isomorphic to an irreducible $q$-difference module of slope $\frac{d+\mu r}{r}$ :

$$
E(r, d, c) \otimes\left(K, \Phi_{a z^{\mu}}\right) \cong E\left(r, d+\mu r, c a^{r}\right) ;
$$

this isomorphism is explicit.
Proof. - The matrix $G=\operatorname{diag}\left(1, a z^{\mu}, a z^{\mu} \sigma_{q}\left(a z^{\mu}\right), \ldots\right)$ realizes this isomorphism.

When the two irreducible modules have non integral slopes, we obtain a direct sum of irreducible modules with the same slope.

Proposition 1.14. - Let $E\left(r_{1}, d_{1}, b_{1}^{r_{1}}\right)$ and $E\left(r_{2}, d_{2}, b_{2}^{r_{2}}\right)$ be two irreducible $q$-difference modules. Let $p=\operatorname{gcd}\left(r_{1}, r_{2}\right), m=\operatorname{lcm}\left(r_{1}, r_{2}\right)$ and $d \in \mathbb{Z}, r \geqslant 1$ such that $\operatorname{gcd}(d, r)=1$ and $\frac{d_{1}}{r_{1}}+\frac{d_{2}}{r_{2}}=\frac{d}{r}$ and $k:=\frac{m}{r}$. We have an isomorphism of $q$-difference modules:

$$
E\left(r_{1}, d_{1}, b_{1}^{r_{1}}\right) \otimes E\left(r_{2}, d_{2}, b_{2}^{r_{2}}\right) \cong \bigoplus_{r=1}^{p / k} \bigoplus_{i=0}^{k-1} \bigoplus_{j=0}^{k-1} E\left(r, d, q_{k}^{i} \xi_{k}^{j}\left(b_{1} b_{2}\right)^{r}\right)
$$

Proof. - It is a consequence of the two following lemmas.

Lemma 1.15. - Let $E\left(r_{1}, d_{1}, c_{1}\right)$ and $E\left(r_{2}, d_{2}, c_{2}\right)$ two irreducible $q$ difference modules. Let $c_{1}=b_{1}^{r_{1}}$ and $c_{2}=b_{2}^{r_{2}}$. We have an explicit isomorphism of $q$-difference modules which does not depend on the choice of $b_{1}$ and $b_{2}$ :

$$
E\left(r_{1}, d_{1}, b_{1}^{r_{1}}\right) \otimes E\left(r_{2}, d_{2}, b_{2}^{r_{2}}\right) \cong \bigoplus_{i=0}^{p-1} \tilde{E}\left(m, t, q^{i u_{2} d_{1}}\left(b_{1} b_{2}\right)^{m}\right)
$$

where $p=\operatorname{gcd}\left(r_{1}, r_{2}\right), m=\operatorname{lcm}\left(r_{1}, r_{2}\right), r_{1}=p u_{1}, r_{2}=p u_{2}, t=u_{2} d_{1}+u_{1} d_{2}$.
$\tilde{E}\left(m, t, a_{i}^{m}\right)$ represents a $q$-difference module of rank $m$, of slope $\frac{t}{m}=$ $\frac{d_{1}}{r_{1}}+\frac{d_{2}}{r_{2}}$ and is equal to ( $K^{m}, \Phi_{A_{i}}$ ) where $A_{i}$ has the following form:

$$
A_{i}=\left(\begin{array}{cccc}
0 & 1 & & 0 \\
\vdots & & \ddots & \\
0 & & & 1 \\
a_{i}^{m} q^{\frac{t(m-1)}{2}} z^{t} & 0 & \ldots & 0
\end{array}\right) \text { where } a_{i}^{m}=q^{i u_{2} d_{1}}\left(b_{1} b_{2}\right)^{m}
$$

Remark 1.16. - The modules $\tilde{E}$ are not a priori irreducible and $t$ and $m$ are not coprime. This lemma introduces an asymmetry that we correct in the Proposition 1.14.

Proof. - Let $M_{i}:=E\left(r_{i}, d_{i}, b_{i}^{r_{i}}\right)=\left(K^{r_{i}}, \Phi_{i}\right)$ where $\Phi_{i}:=\Phi_{B_{i}}$. The vector $e={ }^{t}(1,0, \ldots, 0)$ of rank $r_{1}$ is a cyclic vector associated with $M_{1}$, indeed, $\underline{e}=\left(e, \Phi_{1}(e), \ldots, \Phi_{1}^{r_{1}-1}(e)\right)$ is a basis of $K^{r}$ and $\Phi_{1}^{r_{1}}(e)=$ $q^{\frac{-d_{1}\left(r_{1}-1\right)}{2}} b_{1}^{-r_{1}} z^{-d_{1}} e$. Thus $\Phi_{1}(\underline{e})=\underline{e} B_{1}^{-1}$. If we denote by $f$ the cyclic vector associated with $M_{2}$, we have $\Phi_{2}^{r_{2}}(f)=q^{\frac{-d_{2}\left(r_{2}-1\right)}{2}} b_{2}^{-r_{2}} z^{-d_{2}} f$.

We are looking for a basis of $K^{r_{1}} \otimes K^{r_{2}}$ formed with cyclic vectors for $\Phi=\Phi_{1} \otimes \Phi_{2}$. The vector $e \otimes f$ is not cyclic, indeed if $m=\operatorname{lcm}\left(r_{1}, r_{2}\right) \leqslant r_{1} r_{2}$, the family $\left(e \otimes f, \Phi(e \otimes f), \ldots, \Phi^{m-1}(e \otimes f)\right)$ is free over $K$ but if $m \neq r_{1} r_{2}$, it is not a basis. Let $p=\operatorname{gcd}\left(r_{1}, r_{2}\right)$, the family

$$
\begin{gathered}
e \otimes f, \Phi_{1}(e) \otimes \Phi_{2}(f), \ldots, \Phi_{1}^{m-1}(e) \otimes \Phi_{2}^{m-1}(f), \\
\Phi_{1}(e) \otimes f, \Phi_{1}^{2}(e) \otimes \Phi_{2}(f), \ldots, \Phi_{1}^{m}(e) \otimes \Phi_{2}^{m-1}(f), \\
\vdots \\
\Phi_{1}^{p-1}(e) \otimes f, \Phi_{1}^{p}(e) \otimes \Phi_{2}(f), \ldots, \Phi_{1}^{p-1+m-1}(e) \otimes \Phi_{2}^{m-1}(f)
\end{gathered}
$$

is a basis $\mathcal{B}$ of $K^{r_{1}} \otimes K^{r_{2}}$ which is then identified by $K^{r_{1} r_{2}}$, and the matrix of $\Phi$ has the wished form.

We have something better thanks to the following lemma which allows to see the modules $\tilde{E}$ as a direct sum of irreducible modules:

Lemma 1.17. - We have an explicit isomorphism of $q$-difference modules:

$$
\tilde{E}\left(m, t, a^{m}\right) \cong \bigoplus_{j=0}^{k-1} E\left(r, d, \xi_{k}^{j} a^{r}\right)
$$

where $\operatorname{gcd}(d, r)=1, m=k r$ and $\frac{t}{m}=\frac{d}{r}$.
Proof. - It is clear that the vector $e={ }^{t}(1,0, \ldots, 0)$ is cyclic for the module $\tilde{E}\left(m, t, a^{m}\right)=:\left(K^{m}, \Phi\right)$ that is $\left\{e, \Phi(e), \ldots, \Phi^{m-1}(e)\right\}$ is a basis of $K^{m}$ and $\Phi^{m}(e)=a^{-m} q^{\frac{-t(m-1)}{2}} z^{-t} e$.

We are looking for vectors $f_{0}, f_{1}, \ldots, f_{k-1}$ such that the family

$$
\left\{f_{0}, \Phi\left(f_{0}\right), \ldots, \Phi\left(f_{0}^{r-1}\right), \ldots, f_{k-1}, \ldots, \Phi^{r-1}\left(f_{k-1}\right)\right\}
$$

is a basis of $K^{m}$ and $\Phi^{r}\left(f_{j}\right)=\xi_{k}^{-j} a^{-r} q^{\frac{-d(r-1)}{2}} z^{-d} f_{j}$. We write

$$
f_{j}=a_{1(j)} e+a_{2(j)} \Phi^{r}(e)+\cdots+a_{k(j)} \Phi^{m-r}(e)
$$

and we verify that $a_{i(j)}=\xi_{k}^{i j} c_{i}$ with $c_{i}=a^{-m+i r} q^{\frac{-(k-i) d}{2} r(k+i-2)-1} z^{(i-1) d}$, is suitable. The transition matrix from the basis $\left\{e, \Phi(e), \ldots, \Phi^{m-1}(e)\right\}$ to $\left\{f_{0}, \Phi\left(f_{0}\right), \ldots, \Phi^{r-1}\left(f_{0}\right), \ldots, f_{k-1}, \ldots, \Phi^{r-1}\left(f_{k-1}\right)\right\}$ is the matrix of the isomorphism.

## 2. Isoformal analytic classification

In this section, we want to study the analytic classes of $q$-difference modules over $K$ whose graded module is fixed (we will define this notion later).

When slopes are integral, according to [12], it leads to the normal form of Birkhoff-Guenther ${ }^{(1)}$ and it gives an explicit matricial normal form for the representatives of the classes. Here, we choose the same approach allowing non integral slopes. We will use the same tool: an adapted $q$-Borel-Ramis transform and we obtain normal forms with polynomial coefficients. However, we are only able to treat the case of two slopes, when one or two slopes are not integral. Our method does not work with three slopes or more. Indeed, as shown by the computations in [15], upper levels involve nonlinear formulas for which I have found no equivalent in the case of non integral slopes.

[^0]
### 2.1. The space of isoformal analytic classes

We fix a class $M_{0}=P_{1} \oplus \cdots \oplus P_{k}$ where $P_{i}$ is pure isoclinic of slope $\mu_{i} \in \mathbb{Q}$ and of rank $r_{i} \in \mathbb{N}^{*}$. Moreover, we suppose $\mu_{1}<\cdots<\mu_{k}$. As $M_{0}$ is a direct sum of pure isoclinic $q$-difference module, the class $M_{0}$ can be identified with a formal class.

Definition 2.1 ([12]). - $\mathcal{F}\left(P_{1}, \ldots, P_{k}\right)$ is the set of equivalence classes of pairs $(M, u)$ with $M$ a $q$-difference module over $K$ and $u: \operatorname{gr} M \rightarrow M_{0}$ an isomorphism, where $(M, u) \sim\left(M^{\prime}, u^{\prime}\right)$ if there exists a morphism $f$ : $M \rightarrow M^{\prime}$ such that $u=u^{\prime} \circ \operatorname{gr} f$ and $f$ is automatically an isomorphism.

According to [12, Theorem 3.1.4], the set $\mathcal{F}\left(P_{1}, \ldots, P_{k}\right)$ is an affine space of dimension over $\mathbb{C} \sum_{i<j} r_{i} r_{j}\left(\mu_{j}-\mu_{i}\right)$.

In term of matrices, the fixed formal class is $M_{0}=\left(K^{n}, \Phi_{A_{0}}\right)$ and every class of $\mathcal{F}\left(P_{1}, \ldots, P_{k}\right)$ can be represented by $M_{U}=\left(K^{n}, \Phi_{A_{U}}\right)$ where

$$
\begin{align*}
& A_{0}=\left(\begin{array}{ccc}
B_{1} & & 0 \\
& \ddots & \\
0 & & B_{k}
\end{array}\right), \quad A_{U}=\left(\begin{array}{ccc}
B_{1} & & U_{i, j} \\
& \ddots & \\
0 & & B_{k}
\end{array}\right)  \tag{2.1}\\
& \forall 1 \leqslant i<j \leqslant k, \quad U_{i, j} \in M_{r_{i}, r_{j}}(K)
\end{align*}
$$

each matrice $B_{i} \in \mathrm{GL}_{r_{i}}(K)$ represents the pure isoclinic module $P_{i}=$ ( $K^{r_{i}}, \Phi_{B_{i}}$ ) of slope $\mu_{i}$ and rank $r_{i}$ (we generally denote $M_{r, s}(K)$ the space of $r \times s$ matrices over $K$ ).

We will denote by $\left[M_{U}\right]$ the class of the module $M_{U}$ in $\mathcal{F}\left(P_{1}, \ldots, P_{k}\right)$. A morphism respecting the graduation from $M_{U}$ to $M_{V}$ is a matrix:

$$
F=\left(\begin{array}{ccc}
I_{r_{1}} & & F_{i, j}  \tag{2.2}\\
& \ddots & \\
0 & & I_{r_{k}}
\end{array}\right) \quad \forall 1 \leqslant i<j \leqslant k, \quad F_{i, j} \in M_{r_{i}, r_{j}}(K)
$$

such that $\sigma_{q}(F) A_{U}=A_{V} F$. The set of matrices of the form (2.2) forms a unipotent algebraic subgroup of $\mathrm{GL}_{n}$ that we denote by $\mathfrak{S}_{r_{1}, \ldots, r_{k}}$.

Two modules $M_{U}$ and $M_{V}$ are equivalent if there exists an isomorphism $F \in \mathfrak{S}_{r_{1}, \ldots, r_{k}}(K)$ such that $F\left[A_{U}\right]=A_{V}$, in this case, we denote $M_{U} \sim M_{V}$ and $A_{U} \sim A_{V}$.

When the slopes are integral, $\mu_{i} \in \mathbb{Z}$, the matrices associated with $P_{i}$ have the form $B_{i}=z^{\mu_{i}} A_{i}, A_{i} \in \mathrm{GL}_{r_{i}}(\mathbb{C})$. According to Proposition 3.3.4 p. 40 of [12], a class of $\mathcal{F}\left(P_{1}, \ldots, P_{k}\right)$ admits a unique representative with
the associated matrix:

$$
A_{U}=\left(\begin{array}{cccc}
z^{\mu_{1}} A_{1} & & U_{i, j} \\
& \ddots & \\
0 & & z^{\mu_{k}} A_{k}
\end{array}\right) \forall 1 \leqslant i<j \leqslant k, \quad U_{i, j} \in M_{r_{i}, r_{j}}\left(\bigoplus_{l=\mu_{i}}^{\mu_{j}-1} \mathbb{C} z^{l}\right)
$$

This is called the normal form of Birkhoff-Guenther.

### 2.2. The case of two slopes: extensions

As we shall see, the space of isoformal analytic classes with two slopes is special because it is a vector space over $\mathbb{C}$. Moreover, thanks to the normal forms of pure isoclinic modules with integral slopes or not, we finally have to study only one case: $\mathcal{F}(E, \underline{1})$ in the above $E$ is an irreducible module.

Let $P_{1}$ and $P_{2}$ be two pure isoclinic $q$-difference modules with slopes $\mu_{1}<\mu_{2}$. The space $\mathcal{F}\left(P_{1}, P_{2}\right)$ is $\mathbb{C}$-vector space which can be identify with $\operatorname{Ext}\left(P_{2}, P_{1}\right)$, which is the $\mathbb{C}$-vector space of the extensions of the $q$-difference module $P_{2}$ by the $q$-difference module $P_{1}$ (cf. [12, Proposition 2.3.9 p. 25]; our Ext can be identified with the Ext ${ }^{1}$ space of homological algebra for $\mathcal{D}_{K, \sigma_{q}}$-modules, this allows us to use [3]).

Let $P_{1}=\left(V_{1}, \Phi_{1}\right)$ and $P_{2}=\left(V_{2}, \Phi_{2}\right)$ be two pure isoclinic $q$-differences modules of slopes $\mu_{1}<\mu_{2}$. An extension of $P_{2}$ by $P_{1}$ is an exact sequence of $q$-differences modules:

$$
0 \rightarrow P_{1} \rightarrow M \rightarrow P_{2} \rightarrow 0
$$

giving an exact sequence of $K$-vector spaces: $0 \rightarrow V_{1} \rightarrow V \rightarrow V_{2} \rightarrow 0$ where $M=(V, \Phi)$. The following diagram is commutative:


For $i=1,2, P_{i}$ is isomorphic to $\left(K^{n_{i}}, \Phi_{A_{i}}\right), A_{i} \in \mathrm{GL}_{n_{i}}(K)$, an extension of $P_{2}$ by $P_{1}$ is a module of the form $M_{U}=\left(K^{n_{1}+n_{2}}, \Phi_{A_{U}}\right)$ where:

$$
A_{U}=\left(\begin{array}{cc}
A_{1} & U \\
0 & A_{2}
\end{array}\right), \quad U \in M_{n_{1}, n_{2}}(K)
$$

We can easily see that $A_{U} \sim A_{V}$ if, and only if, $A_{0} \sim A_{V-U}$ :

$$
\begin{aligned}
A_{U} \sim A_{V} & \Leftrightarrow \exists F \in M_{n_{1}, n_{2}}(K), \sigma_{q}(F) A_{2}+U=A_{1} F+V \\
& \Leftrightarrow \exists F \in M_{n_{1}, n_{2}}(K), \sigma_{q}(F) A_{2}-A_{1} F=V-U .
\end{aligned}
$$

We notice that $\mathcal{F}\left(P_{1}, P_{2}\right)$ can be identified with the cokernel of $X \mapsto$ $\sigma_{q}(X) A_{2}-A_{1} X$ in $M_{n_{1}, n_{2}}(K)$ which is isomorphic to the cokernel of $X \mapsto \sigma_{q}(X)-A_{1} X A_{2}^{-1}$ in $M_{n_{1}, n_{2}}(K)$.

We have $\operatorname{Ext}\left(P_{2}, P_{1} \oplus P_{3}\right) \cong \operatorname{Ext}\left(P_{2}, P_{1}\right) \oplus \operatorname{Ext}\left(P_{2}, P_{3}\right)$ (cf. [12]) that gives the following isomorphism: $\mathcal{F}\left(P_{1} \oplus P_{3}, P_{2}\right) \cong \mathcal{F}\left(P_{1}, P_{2}\right) \oplus \mathcal{F}\left(P_{3}, P_{2}\right)$ which is defined by:

$$
\begin{equation*}
\left[M_{U}\right]=\left[\left(K^{n_{1}+n_{3}+n_{2}}, \Phi_{A_{U}}\right)\right] \mapsto\left(\left[M_{U_{1}}\right],\left[M_{U_{2}}\right]\right) \tag{2.3}
\end{equation*}
$$

where $M_{U_{1}}=\left(K^{n_{1}+n_{2}}, \Phi_{A_{U_{1}}}\right), M_{U_{2}}=\left(K^{n_{3}+n_{2}}, \Phi_{A_{U_{2}}}\right)$ and by identifying $P_{1}$ with $\left(K^{n_{1}}, \Phi_{B_{1}}\right)$ and $P_{3}$ with $\left(K^{n_{3}}, \Phi_{B_{3}}\right)$,

$$
\begin{array}{r}
A_{U}=\left(\begin{array}{ccc}
B_{1} & 0 & U_{1} \\
0 & B_{3} & U_{2} \\
0 & 0 & B_{2}
\end{array}\right), A_{U_{1}}=\left(\begin{array}{cc}
B_{1} & U_{1} \\
0 & B_{2}
\end{array}\right) A_{U_{2}}=\left(\begin{array}{cc}
B_{3} & U_{2} \\
0 & B_{2}
\end{array}\right) \\
U_{1} \in M_{n_{1}, n_{2}}(K), U_{2} \in M_{n_{3}, n_{2}}(K) .
\end{array}
$$

Moreover, $\operatorname{Ext}\left(P_{2}, P_{1}\right) \cong \operatorname{Ext}\left(\underline{1}, P_{2}^{\vee} \otimes P_{1}\right)(c f .[12])$, then we have an isomorphism: $\mathcal{F}\left(P_{1}, P_{2}\right) \cong \mathcal{F}\left(P_{1} \otimes P_{2}^{\vee}, \underline{1}\right)$ where $P_{2}^{\vee}$ is the dual of $P_{2}$. This isomorphism is defined by:

$$
\begin{equation*}
\left[M_{U}\right]=\left[\left(K^{n_{1}+n_{2}}, \Phi_{A_{U}}\right)\right] \mapsto\left[M_{U^{\prime}}^{\prime}\right]=\left[\left(K^{n_{1} n_{2}+1}, \Phi_{A_{U^{\prime}}^{\prime}}\right)\right] \tag{2.4}
\end{equation*}
$$

where,

$$
\begin{aligned}
& A_{U}=\left(\begin{array}{cc}
B_{1} & U \\
0 & B_{2}
\end{array}\right), U \in M_{n_{1}, n_{2}}(K) \\
& \quad \text { and } A_{U^{\prime}}^{\prime}=\left(\begin{array}{cc}
B_{1} \hat{\otimes} B_{2}^{\vee} & U^{\prime} \\
0 & 1
\end{array}\right), U^{\prime}=\widehat{U B_{2}^{-1}} \in M_{n_{1} n_{2}, 1}(K)
\end{aligned}
$$

It is well defined, indeed $M_{0}$ is equivalent to $M_{U}$ if, and only if, there exists $F \in M_{n_{1}, n_{2}}(K)$ such that:

$$
\begin{aligned}
\sigma_{q}(F) B_{2}=B_{1} F+U & \Leftrightarrow \sigma_{q}(F)=B_{1} F B_{2}^{-1}+U B_{2}^{-1} \\
& \Leftrightarrow \sigma_{q} \hat{F}=B_{1} \hat{\otimes} B_{2}^{\vee} \hat{F}+\widehat{U B_{2}^{-1}}
\end{aligned}
$$

where $B_{2}^{\vee}={ }^{t} B_{2}^{-1}$ is the matrix associated with $P_{2}^{\vee}$. The last equation means that $M_{0}^{\prime}$ is equivalent to $M_{U^{\prime}}^{\prime}$.

Proposition 2.2. - The module $M^{\prime}$ is a pullback:

$$
M^{\prime}=\left(M \otimes P_{2}^{\vee}\right) \times_{P_{2} \otimes P_{2}^{\vee}} \underline{1}
$$

Proof. - We have the following exact sequence:

$$
0 \rightarrow P_{1} \rightarrow M \rightarrow P_{2} \rightarrow 0
$$

By tensoring by $P_{2}^{\vee}$, it becomes (since tensoring is exact in this tannakian category):

$$
\begin{equation*}
0 \rightarrow P_{1} \otimes P_{2}^{\vee} \rightarrow M \otimes P_{2}^{\vee} \rightarrow P_{2} \otimes P_{2}^{\vee} \rightarrow 0 \tag{2.5}
\end{equation*}
$$

Let $M^{\prime \prime}=\left(M \otimes P_{2}^{\vee}\right) \times_{P_{2} \otimes P_{2}^{\vee}} \underline{1}$ (using the usual operator $\underline{1} \rightarrow P_{2} \otimes P_{2}^{\vee}$ of rigid categories); we have the following lemma:

Lemma 2.3. - The following diagram of exact sequences of $q$-difference modules is commutative:


Remark 2.4. - This a general lemma (see for example [12] or [3]). We give here an explicit matricial proof.

Proof of the lemma. - For convenience, we denote $P_{1}=\left(V_{1}, \Phi_{1}\right), P_{2}=$ $\left(V_{2}, \Phi_{2}\right)$. We have $M=\left(V_{1} \times V_{2}, \Phi_{u}\right)$ such that

$$
\Phi_{u}\left(x_{1}, x_{2}\right)=\left(\Phi_{1}\left(x_{1}\right)+u\left(x_{2}\right), \Phi_{2}\left(x_{2}\right)\right),
$$

$u \in \mathcal{L}_{\sigma_{q}}\left(V_{2}, V_{1}\right)$ (the set of the $\sigma_{q}$-linear maps from $V_{2}$ to $V_{1}$ ), with the point of view of matrices, $u$ corresponds to $-B_{1} U B_{2}^{-1} \sigma_{q}\left(\right.$ since $\left.\Phi_{U}=\left(A_{U}\right)^{-1} \sigma_{q}\right)$. From now, we identify $N \otimes P_{2}^{\vee}=\underline{\operatorname{Hom}}\left(P_{2}, N\right)$, where by definition, the internal Hom of $M=(V, \Phi)$ and $N=(W, \Psi)$, denoted by $\underline{\operatorname{Hom}}(M, N)$, is the $q$-difference module $\left(\mathcal{L}(V, W), T_{\Phi, \Psi}\right)$ where $T_{\Phi, \Psi}$ is the $\sigma_{q}$-linear automorphism defined by: $f \mapsto \Psi \circ f \circ \Phi^{-1}$.

The exact sequence of $q$-difference modules (2.5) becomes:

$$
0 \rightarrow \underline{\operatorname{Hom}}\left(P_{2}, P_{1}\right) \rightarrow \underline{\operatorname{Hom}}\left(P_{2}, M\right) \rightarrow \underline{\operatorname{Hom}}\left(P_{2}, P_{2}\right) \rightarrow 0 .
$$

Indeed, we have an exact sequence of the underlying $K$-vector spaces:

$$
0 \rightarrow \mathcal{L}\left(V_{2}, V_{1}\right) \rightarrow \mathcal{L}\left(V_{2}, V_{1}\right) \times \mathcal{L}\left(V_{2}, V_{2}\right) \rightarrow \mathcal{L}\left(V_{2}, V_{2}\right) \rightarrow 0
$$

with $\mathcal{L}\left(V_{2}, V_{1}\right)$ provided with the $\sigma_{q}$-linear automorphism $f \mapsto \Phi_{1} \circ f \circ \Phi_{2}^{-1}$, $\mathcal{L}\left(V_{2}, V_{2}\right)$ provided with the $\sigma_{q^{-}}$-linear automorphism $g \mapsto \Phi_{2} \circ g \circ \Phi_{2}^{-1}$ and $\mathcal{L}\left(V_{2}, V_{1}\right) \times \mathcal{L}\left(V_{2}, V_{2}\right)$ provided with the $\sigma_{q}$-linear automorphism
$(f, g) \mapsto \Psi_{u}(f, g)=\Phi_{u} \circ(f, g) \circ \Phi_{2}^{-1}=\left(\Phi_{1} \circ f \circ \Phi_{2}^{-1}+u \circ g \circ \Phi_{2}^{-1}, \Phi_{2} \circ g \circ \Phi_{2}^{-1}\right)$.
Therefore, the module $\underline{\operatorname{Hom}}\left(P_{2}, M\right)$ is an extension of $q$-difference modules $\underline{\operatorname{Hom}}\left(P_{2}, P_{2}\right)$ by $\underline{\operatorname{Hom}}\left(P_{2}, P_{1}\right)$ which corresponds to the element $g \mapsto$ $u \circ g \circ \Phi_{2}^{-1}$ of $\mathcal{L}_{\sigma_{q}}\left(\mathcal{L}\left(V_{2}, V_{2}\right), \mathcal{L}\left(V_{2}, V_{1}\right)\right)$.

According to [3] (Algebra, chapter X on homological algebra, p. 113), we have a morphism $\operatorname{Hom}(N, \tilde{M}) \times \operatorname{Ext}\left(\tilde{M}, \tilde{M}^{\prime}\right) \rightarrow \operatorname{Ext}\left(N, \tilde{M}^{\prime}\right)$. Replacing $N$ by $\underline{1}, \tilde{M}$ by $P_{2} \otimes P_{2}^{\vee}$ and $\tilde{M}^{\prime}$ by $P_{1} \otimes P_{2}^{\vee}$, we make the pullback with the morphism $\underline{1} \rightarrow \underline{\operatorname{Hom}}\left(P_{2}, P_{2}\right)$ and we obtain (keeping only the degree 0 terms of the Ext sequence):


As far as the underlying $K$-vector spaces are concerned, the second exact sequence of the diagram gives the exact sequence of $K$-vector spaces:

$$
0 \rightarrow \mathcal{L}\left(V_{2}, V_{1}\right) \rightarrow\left(\mathcal{L}\left(V_{2}, V_{1}\right) \times \mathcal{L}\left(V_{2}, V_{2}\right)\right) \times_{\mathcal{L}\left(V_{2}, V_{2}\right)} K \rightarrow K \rightarrow 0
$$

with $\mathcal{L}\left(V_{2}, V_{1}\right)$ provided with the $\sigma_{q}$-linear automorphism $f \mapsto \Phi_{1} \circ f \circ \Phi_{2}^{-1}$, $K$ provided with the $\sigma_{q}$-linear automorphism $\sigma_{q}$.

And yet, $\left(\mathcal{L}\left(V_{2}, V_{1}\right) \times \mathcal{L}\left(V_{2}, V_{2}\right)\right) \times_{\mathcal{L}\left(V_{2}, V_{2}\right)} K=\{(f, g, \lambda) \mid g=\lambda \operatorname{Id}\}=$ $\{(f, \lambda)\}$, so it is provided with the $\sigma_{q}$-linear automorphism $\Psi_{u} \times\left.\sigma_{q}\right|_{\{(f, \lambda)\}}$ :

$$
\left.(f, \lambda) \mapsto\left(\Phi_{1} \circ f \circ \Phi_{2}^{-1}+\sigma_{q}(\lambda) u \circ \Phi_{2}^{-1}\right), \sigma_{q}(\lambda)\right)
$$

The module $M^{\prime \prime}$ corresponds to the extension of $\underline{1}$ by $\left(\mathcal{L}\left(V_{2}, V_{1}\right), \Phi_{1} \otimes \Phi_{2}^{\vee}\right)$ defined by the element of $\mathcal{L}_{\sigma_{q}}\left(K, \mathcal{L}\left(V_{2}, V_{1}\right)\right), \lambda \mapsto \sigma_{q}(\lambda)\left(u \circ \Phi_{2}^{-1}\right)$. Notice that $u \circ \Phi_{2}^{-1}$ is associated with the matrix $-B_{1} U B_{2}^{-1} B_{2}=-B_{1} U$. This ends the proof of the lemma.

With the same notation as the lemma, $M^{\prime}$ is identified with the module $\left(\mathcal{L}\left(V_{2}, V_{1}\right) \times K, \Phi_{v}\right)$ where $\Phi_{v}(f, \lambda)=\left(\Phi_{1} \circ f \circ \Phi_{2}^{-1}+\sigma_{q}(\lambda) v, \sigma_{q}(\lambda)\right), v \in$ $\mathcal{L}_{\sigma_{q}}\left(K, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$, with a matricial point of view $v$ corresponds to $-B_{1} U \sigma_{q}$. It is exactly the module $M^{\prime}$ defined, as a consequence, there are the same modules. This ends the proof of the proposition.

A pure isoclinic module of slope $\mu \in \mathbb{Z}$ is isomorphic to a module of the form $\left(K^{n}, \Phi_{z^{\mu} A}\right)$, by Jordan's decomposition of $A$, it is isomorphic to a module of the form $\bigoplus_{i}\left(K, \Phi_{a_{i} z^{\mu}}\right) \otimes U_{m_{i}}$, where $a_{i} \in C_{q}$ is an eigenvalue of $A$.

A pure isoclinic module with non integral slope is a direct sum of indecomposable modules, so it is isomorphic to $\bigoplus_{i} E\left(r, d, c_{i}\right) \otimes U_{m_{i}}$. As a consequence, the study of $\mathcal{F}\left(P_{1}, P_{2}\right)$ amounts to the study of $\mathcal{F}\left(E_{1} \otimes U_{m_{1}}, E_{2} \otimes\right.$ $U_{m_{2}}$ ) where $E_{1}, E_{2}$ are irreducible with an integral slope or not.

According to the explicit isomorphism (2.4), $\mathcal{F}\left(E_{1} \otimes U_{m_{1}}, E_{2} \otimes U_{m_{2}}\right)$ is isomorphic to $\mathcal{F}\left(E_{1} \otimes E_{2}^{\vee} \otimes U_{m_{1}} \otimes U_{m_{2}}^{\vee}, \underline{1}\right)$. Moreover, $U_{m_{1}} \otimes U_{m_{2}}^{\vee}$ is isomorphic to a direct sum of unipotent modules (for details, see for instance [14]).

Thus, we have to study $\mathcal{F}\left(E_{1} \otimes E_{2}^{\vee} \otimes U_{m}, \underline{1}\right)$. And yet, in the Proposition 1.14, we have seen that the tensor product of two irreducible modules is isomorphic to a direct sum of irreducible modules. Finally, the only one case to study is $\mathcal{F}\left(E \otimes U_{m}, \underline{1}\right)$, where $E$ is an irreducible module with non integral slope.

$$
\text { 2.3. } \mathcal{F}(E, 1) \text { and } \mathcal{F}\left(E \otimes U_{m}, 1\right)
$$

We begin to study $\mathcal{F}\left(P_{1}, P_{2}\right)$ when the slope of $P_{1}$ is negative and non integral and the slope of $P_{2}$ is zero. According to the last paragraph, we just have to deal with $\mathcal{F}(E, \underline{1})$ where $E=E(r,-d, c)=\left(K^{r}, \Phi_{B}\right)$ is an irreducible module with non integral negative slope $\frac{-d}{r}$.

So, let $E=E(r,-d, c)$ be is an irreducible module with non integral slope $\mu=-d / r<0$ and of rank $r$, such that $E=\left(K^{r}, \Phi_{B}\right)$ we set $c^{\prime}=$ $q^{\frac{-d(r-1)}{2}} c \in \mathbb{C}^{*}$.

Remember that a class of $\mathcal{F}(E, \underline{1})$ admits a representative whose associated matrix has the following form (cf. (2.1)):

$$
A_{U}=\left(\begin{array}{cc}
B & U \\
0 & 1
\end{array}\right) \text { where } U={ }^{t}\left(u_{1}, \ldots, u_{r}\right) \in K^{r}
$$

In $[16,15]$, it is proved following Birkhoff and Guenther [1], that a class of $\mathcal{F}(E, \underline{1})$ admits at least a polynomial representative (that is to say $U$ has polynomial coefficients), in the following lemma, we give an effective way to find one. This representative is non unique contrary to the case of integral slopes. Indeed, the simplest non trivial example ( $E$ having rank 2 and slope $-1 / 2$ ) yields a space of classes of dimension 1 to be evenly distributed in $\mathbb{C}^{2}$, explaining the impossibility of a straight generalisation of Birkhoff-Guenther normal form.

Lemma 2.5 (cf. [12]). - Let $L^{\prime}$ be an operator of $\mathbb{C}(\{z\})$ with values in itself of the form $L^{\prime}=a z^{d} \sigma_{q}^{r}-1, a \in \mathbb{C}^{*}$ and $d, r>0$. Let $k \in \mathbb{Z}$ fixed, then we have:

$$
\mathbb{C}(\{z\})=\bigoplus_{l=k}^{k+d-1} \mathbb{C} z^{l} \oplus \operatorname{Im} L^{\prime}
$$

Remark 2.6. - Let us fix $k \in \mathbb{Z}$, we denote by $\pi_{r, d, k}$ the projection of $\mathbb{C}(\{z\})$ on $\bigoplus_{l=k}^{k+d-1} \mathbb{C} z^{l}$ parallel to $\operatorname{Im} L^{\prime}$. Thus, the equation $a z^{d} \sigma_{q}^{r}(f)-f=$ $\alpha$ has a solution in $\mathbb{C}(\{z\})$ if, and only if, $\pi_{r, d, k}(\alpha)=0$.

Let $V_{r, d}$ be the $\mathbb{C}$-vector space $\left(\sum_{l=0}^{d-1} \mathbb{C} z^{l}\right)^{r}$ of dimension $r d$.
Lemma 2.7. - The linear map from $V_{r, d}$ to $\mathcal{F}(E, \underline{1})$ defined by:

$$
U \in V_{r, d} \mapsto\left[M_{U}\right]
$$

is onto. So, every class of $\mathcal{F}(E, \underline{1})$ admits a representative (non unique) $M_{U}$ with $U \in V_{r, d}$. Such a representative can be given by the $\mathbb{C}$-linear map $\Pi_{r, d}: K^{r} \rightarrow V_{r, d}$ defined by:
$U=\left(u_{1}, \ldots, u_{r}\right) \mapsto\left(v_{1}, \ldots, v_{r}\right)$ such that $z^{d} \sigma_{q}^{r-i}\left(v_{i}\right)=\pi_{r, d, d}\left(z^{d} \sigma_{q}^{r-i}\left(u_{i}\right)\right)$, ( $\pi_{r, d, d}$ is the $\mathbb{C}$-linear defined in the Remark 2.6, and we choose here $k=d$ ).

Proof. - Let $M_{U}$ be a representative of a class of $\mathcal{F}(E, \underline{1})$ with matrix $A_{U}$, we write $U={ }^{t}\left(u_{1}, \ldots, u_{r}\right)$, then

$$
\begin{align*}
& A_{0} \sim A_{U} \Leftrightarrow \exists F={ }^{t}\left(f_{1}, \ldots, f_{n}\right) \in K^{r}, \sigma_{q} F=B F+U  \tag{2.7}\\
& \Leftrightarrow\left\{\begin{array}{c}
f_{2}=\sigma_{q}\left(f_{1}\right)-u_{1} \\
f_{3}=\sigma_{q}^{2}\left(f_{1}\right)-\left(\sigma_{q}\left(u_{1}\right)+u_{2}\right) \\
\vdots \\
f_{r}=\sigma_{q}^{r-1}\left(f_{1}\right)-\left(\sigma_{q}^{r-2}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{r-2}\right)+u_{r-1}\right) \\
\sigma_{q}^{r}\left(f_{1}\right)=c^{\prime} z^{-d} f_{1}+\sigma_{q}^{r-1}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{r-1}\right)+u_{r}
\end{array}\right. \tag{2.8}
\end{align*}
$$

We have to solve an equation of the type: $a z^{d} \sigma_{q}^{r}(f)-f=\alpha$, with $a=$ $c^{\prime-1} \in \mathbb{C}^{*}$ and

$$
\alpha=a z^{d}\left(\sigma_{q}^{r-1}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{r-1}\right)+u_{r}\right) .
$$

According to Lemma 2.5, for a fixed $k=d \in \mathbb{Z}$, this equation have a solution in $K$ if, and only if, $\pi_{r, d, d}(\alpha) \in \bigoplus_{l=d}^{d+d-1} \mathbb{C} z^{l}=0$. Let

$$
z^{d} \sigma_{q}^{(r-i)}\left(v_{i}\right)=\left(\pi_{r, d, d}\left(z^{d} \sigma_{q}^{r-i}\left(u_{i}\right)\right)\right),
$$

we have $\pi_{r, d, d}\left(z^{d} \sigma_{q}^{r-i}\left(v_{i}\right)-z^{d} \sigma_{q}^{r-i}\left(u_{i}\right)\right)=0$. Thus, the equations $a z^{d} \sigma_{q}^{r}\left(g_{i}\right)-g_{i}=z^{d} \sigma_{q}^{r-i}\left(v_{i}\right)-z^{d} \sigma_{q}^{r-i}\left(u_{i}\right)$ admit a solution $g_{i}$ in $K$. Let $f=g_{1}+\cdots+g_{r}$.

With the same system, replacing $U$ by $V-U$, then $A_{0} \sim A_{V-U}$ so $A_{U} \sim A_{V}$ with $V \in V_{r, d}$.

Theorem 2.8. - The $\mathbb{C}$-linear map $\varphi$ from $V_{r, d}$ to $\sum_{l=0}^{d-1} \mathbb{C} z^{l}$ defined by

$$
\varphi\left(\left(u_{1}, \ldots, u_{r}\right)\right)=\sum_{j=1}^{r} \sigma^{r-j}\left(u_{j}\right)
$$

induces an isomorphism of $\mathbb{C}$-vector spaces:

$$
\mathcal{F}(E, \underline{1}) \cong \frac{V_{r, d}}{K e r \varphi} \cong \operatorname{Im} \varphi \cong \sum_{l=0}^{d-1} \mathbb{C} z^{l}
$$

The dimension of $\mathcal{F}(E, \underline{1})$ is known to be equal to $d$, we find it again in this theorem, which can be summarized by the following commutative diagram:


Proof. - According to the Lemma 2.7, we can suppose that a class of $\mathcal{F}(E, \underline{1})$ is represented by $M_{U}$ with $U \in V_{r, d}$.

Thanks to system (2.8) of the previous proof, we now have $\alpha=$ $a z^{d}\left(\sigma_{q}^{r-1}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{r-1}\right)+u_{r}\right)$ which is in $\bigoplus_{l=d}^{d+d-1} \mathbb{C} z^{l}$, so the equation $a z^{d} \sigma_{q}^{r}(f)-f=\alpha$ admits a convergent solution if, and only if, $\alpha=0$, it is equivalent to $\varphi(U)=\sigma_{q}^{r-1}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{r-1}\right)+u_{r}=0$. As a consequence, the map from $\mathcal{F}(E, \underline{1})$ to $\sum_{l=0}^{d-1} \mathbb{C} z^{l}$ is injective. To prove the bijectivity, we can use the dimension or see that the antecedent of $u \in \sum_{l=0}^{d-1} \mathbb{C} z^{l}$ is the class $\left[M_{U}\right]$ where $U={ }^{t}(0, \ldots, 0, u)$, because $\left[M_{U}\right] \mapsto \varphi(U)=u$.

Remark 2.9. - According to the proof, the coefficients of a morphism $F$ verifying $\sigma_{q}(F)-B F=U$ with $U \in V_{r, d}$ are in $V_{r, d}$, because we have $f_{1}=0$ and for all $i>1$,

$$
f_{i}=-\left(\sigma_{q}^{i-2}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{i-2}\right)+u_{i-1}\right) .
$$

Thanks to this theorem, we can choose the matrix of a representative of a class of $\mathcal{F}(E, \underline{1})$, of the form $A_{U}$ where $U={ }^{t}\left(u_{1}, \ldots, u_{r}\right)$ has polynomial coefficients in $\mathbb{C}[z]_{d-1}$. In other word, such a $q$-difference module is in the same class as $A_{0}$ if, and only if, $\varphi\left(\left(u_{1}, \ldots, u_{r}\right)\right)=0$.

From this result, we can achieve the study of $\mathcal{F}\left(E_{1}, E_{2}\right)$ when $E_{1}$ and $E_{2}$ are irreducible. It remains now to study $\mathcal{F}\left(E \otimes U_{m}, \underline{1}\right)$.

Lemma 2.10. - Every class of $\mathcal{F}\left(E \otimes U_{m}, \underline{1}\right)$ admits a representative $M_{U}$ such that $U \in V_{r, d}^{m}$.

Proof. - With the convention $\hat{\otimes}$ defined in 1.4, a module $M_{U}$ representing a class of $\mathcal{F}\left(E \otimes U_{m}, \underline{1}\right)$ has a matrix of the form:

$$
A_{U}=\left(\begin{array}{ccccc}
B & B & & 0 & U_{1} \\
0 & \ddots & \ddots & & \vdots \\
\vdots & & B & B & U_{m-1} \\
0 & \ldots & 0 & B & U_{m} \\
0 & & & 0 & 1
\end{array}\right)
$$

Thus, $A_{0} \sim A_{U}$ if, and only if, there exists $F=\left(F_{1}, \ldots, F_{m}\right) \in\left(K^{r}\right)^{m}$, such that

$$
\begin{aligned}
\left(\begin{array}{c}
\sigma_{q}\left(F_{1}\right) \\
\vdots \\
\sigma_{q}\left(F_{m-1}\right) \\
\sigma_{q}\left(F_{m}\right)
\end{array}\right)= & \left(\begin{array}{cccc}
B & B & & 0 \\
0 & B & \ddots & \\
& & \ddots & B \\
0 & & 0 & B
\end{array}\right)\left(\begin{array}{c}
F_{1} \\
\vdots \\
F_{m-1} \\
F_{m}
\end{array}\right)+\left(\begin{array}{c}
U_{1} \\
\vdots \\
U_{m-1} \\
U_{m}
\end{array}\right) \\
& \Leftrightarrow\left\{\begin{array}{c}
\sigma_{q}\left(F_{1}\right)=B F_{1}+B F_{2}+U_{1} \\
\sigma_{q}\left(F_{2}\right)=B F_{2}+B F_{3}+U_{2} \\
\vdots \\
\sigma_{q}\left(F_{m-1}\right)=B F_{m-1}+B F_{m}+U_{m-1} \\
\sigma_{q}\left(F_{m}\right)=B F_{m}+U_{m}
\end{array}\right.
\end{aligned}
$$

With the notations of Lemma 2.7, we put:

- $V_{m}=\Pi_{r, d}\left(U_{m}\right)$ then there exists $F_{m} \in K^{r}$ such that $\sigma_{q}\left(F_{m}\right)=$ $B F_{m}+V_{m}-U_{m}$;
- $V_{m-1}=\Pi_{r, d}\left(B F_{m}+U_{m-1}\right)$ then there exists $F_{m-1} \in K^{r}$ such that $\sigma_{q}\left(F_{m-1}\right)=B F_{m-1}+V_{m-1}-\left(B F_{m}+U_{m-1}\right) \ldots$
Therefore by induction, we obtain the lemma.
Let us suppose now that $U \in V_{r, d}^{m}$. We have $A_{0} \sim A_{U}$ that implies $\varphi\left(U_{m}\right)=0$ and according to the Remark 2.9, the morphism $F_{m}$ such that $\sigma_{q}\left(F_{m}\right)=B F_{m}+U_{m}$ is explicitly known and depends on $U_{m}$, it has also his coefficients in $V_{r, d}$, and $B F_{m}$ too. Indeed, $B F_{m}=-\Psi\left(U_{m}\right)$ where $\Psi$ is
the following map:
$\Psi\left(U_{m}\right)=\left(\begin{array}{c}u_{1} \\ \sigma_{q}\left(u_{1}\right)+u_{2} \\ \vdots \\ \sigma_{q}^{r-2}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{r-2}\right)+u_{r-1} \\ \varphi\left(U_{m}\right)\end{array}\right)$ and $U_{m}={ }^{t}\left(u_{1}, \ldots, u_{r}\right)$.
So $A_{0} \sim A_{U}$ implies $\varphi\left(U_{m}\right)=0$ and $\varphi\left(-\Psi\left(U_{m}\right)+U_{m-1}\right)$. By induction, we prove that $A_{0} \sim A_{U}$ implies $F_{1}, \ldots, F_{m} \in V_{r, d}$ and $\varphi\left(U_{m}\right)=0$, for all $i=1, \ldots m-1, \varphi\left(B F_{m-i+1}+U_{m-i}\right)=0$. We obtain the following theorem:

Theorem 2.11. - The $\mathbb{C}$-linear map $\psi$ from $\left(K^{r}\right)^{m}$ to $\left(\sum_{l=0}^{d-1} \mathbb{C} z^{l}\right)^{m}$ defined by:

$$
U=\left(U_{1}, \ldots, U_{m}\right) \in\left(V_{r, d}\right)^{m} \mapsto \psi(U)=\left(\varphi\left(S_{1}\right), \ldots, \varphi\left(S_{m}\right)\right)
$$

where
$S_{i}=(-1)^{i} \Psi^{m-i}\left(U_{m}\right)+(-1)^{i-1} \Psi^{m-i-1}\left(U_{m-1}\right)+\cdots-\Psi\left(U_{m-i+1}\right)+U_{m-i}$ induces an isomorphism between $\mathcal{F}\left(E \otimes U_{m}, \underline{1}\right)$ and $\left(\sum_{l=0}^{d-1} \mathbb{C} z^{l}\right)^{m}$, which, to a class $\left[M_{U}\right]$ with $U \in V_{r, d}^{m}$, associates $\psi(U)$.

Proof. - From the previous paragraph, it is injective and because of the dimension, it is bijective.

This theorem is summarized by the following commutative diagram:


## 3. $H^{1}$ and Stokes operators

In [12], the space of isoformal classes is shown (in the case of an arbitrary number of integral slopes) to be isomorphic to the first cohomology group of some sheaf of unipotent groups over the elliptic curve $E_{q}$ ( $q$-analogue of the theorem of Birkhoff-Malgrange-Sibuya). We do the same here for arbitrary slopes (not necessarily integral) but restricting to the case of two slopes. Then, the sheaf of groups is a vector bundle $\mathcal{F}_{E}$ (it will be defined precisely just before Theorem 3.5).

### 3.1. Some notations

The discrete $q$-spiral of $a \in \mathbb{C}^{*}$ is $[a ; q]:=a q^{\mathbb{Z}}$, every point of $[a ; q]$ has the same image by the canonical projection $\pi: \mathbb{C}^{*} \rightarrow E_{q}$. Similarly, for all $r \in \mathbb{N}^{*}$, the $q^{r}$-spiral will be $\left[a ; q^{r}\right]:=a q^{r \mathbb{Z}}$.

We define the Theta function $\theta_{q^{r}, c}, c \in \mathbb{C}^{*}$. It is an analytic solution on $\mathbb{C}^{*}$ of the equation $\sigma_{q}^{r}(\theta)=\frac{z}{c} \theta$ and is equal to:

$$
\theta_{q^{r}, c}(z)=\sum_{n \in \mathbb{Z}} q^{r \frac{-n(n+1)}{2}}\left(\frac{z}{c}\right)^{n}
$$

The Jacobi's triple product formula gives:

$$
\theta_{q^{r}, c}(z)=\prod_{n \geqslant 1}\left(1-q^{-r n}\right) \prod_{n \geqslant 1}\left(1+q^{-r n} \frac{z}{c}\right) \prod_{n \geqslant 0}\left(1+q^{-r n}\left(\frac{z}{c}\right)^{-1}\right) .
$$

The function $\theta_{q^{r}, c}$ has simple zeroes all located on the $q$-spiral $\left[-c ; q^{r}\right]$.
Moreover, for all $d \in \mathbb{N}^{*}, \theta_{q^{r}, c}^{d}$ is solution of $\sigma_{q}^{r}(\theta)=\left(\frac{z}{c}\right)^{d} \theta$ and its zeros are located on $\left[-c ; q^{r}\right]$ and are of multiplicity $d$.

### 3.2. Stokes operators in the case of two slopes

Let us take $E=E\left(r,-d, b^{r}\right)$ an irreducible $q$-difference module of slope $-d / r<0$, we have $E=\left(K^{r}, \Phi_{B}\right)$ where

$$
B=\left(\begin{array}{cccc}
0 & 1 & & 0 \\
\vdots & & \ddots & \\
0 & & & 1 \\
b^{\prime} z^{-d} & 0 & \ldots & 0
\end{array}\right) \text { where } b^{\prime}=q^{\frac{-d(r-1)}{2}} b^{r} \in \mathbb{C}^{*}
$$

In this section, we want to prove that $\mathcal{F}(E, \underline{1})$ and $H^{1}\left(E_{q}, \mathcal{F}_{E}\right)$ (the sheaf $\mathcal{F}_{E}$ is defined just before Theorem 3.5) are isomorphic. Therefore, we are going to construct privileged cocycles with poles on $E_{q^{r}}$ but not on $E_{q}$ as for the case of integral slopes in [15]. Here $M_{0}=\left(K^{r+1}, \Phi_{A_{0}}\right)$ and a class of $\mathcal{F}(E, \underline{1})$ is represented by a module $M_{U}=\left(K^{r+1}, \Phi_{A_{U}}\right)$ where:

$$
A_{0}=\left(\begin{array}{ll}
B & 0 \\
0 & 1
\end{array}\right) \text { and } A_{U}=\left(\begin{array}{cc}
B & U \\
0 & 1
\end{array}\right) U \in\left(\mathbb{C}[z]_{d-1}\right)^{r}
$$

Indeed, we may and will suppose $U \in\left(\mathbb{C}[z]_{d-1}\right)^{r}$ thanks to Lemma 2.7 in all this part.

We are looking for an isomorphism, more precisely a matrix, between the $q$-difference modules $\left(K^{r+1}, \Phi_{A_{0}}\right)$ and $\left(K^{r+1}, \Phi_{A_{U}}\right)$. We want that isomorphism to have a matrix of the form $\mathfrak{S}_{r, 1}$ :

$$
\left(\begin{array}{cc}
I_{r} & F \\
0 & 1
\end{array}\right)
$$

with $\sigma_{q}(F)-B F=U$.
In the general case, there exists a unique formal morphism $\hat{F}$ satisfying this equation but, a priori, the modules associated to the matrices $A_{0}$ and $A_{U}$ are not in the same analytic class, therefore $\hat{F}$ has not its coefficients in $K$. We shall be looking for $F$ meromorphic on $\mathbb{C}^{*}$.

We denote by $\overline{\bar{c}}$ the class of $c \in \mathbb{C}^{*}$ in $E_{q^{r}}$ and write $\mathcal{O}\left(\mathbb{C}^{*}\right)$ the set of holomorphic functions over $\mathbb{C}^{*}$.

Proposition 3.1. - Let $\Sigma\left(A_{0}\right)=\left\{c \in \mathbb{C}^{*} \mid \exists n \in \mathbb{Z}, c^{d}=b^{r} q^{\frac{-d(r-1)}{2}} q^{r n}\right\}$ modulo $q^{r}$, the set $\Sigma\left(A_{0}\right)$ is finite.

For all $U \in\left(\mathbb{C}[z]_{d-1}\right)^{r}$, for all $\overline{\bar{c}} \in E_{q^{r}} \backslash \Sigma\left(A_{0}\right)$ (the notation is defined hereafter), there exists a unique vector of meromorphic functions $\tilde{F}_{\overline{\bar{c}}}$ over $\mathbb{C}^{*}, \tilde{F}_{\overline{\bar{c}}}={ }^{t}\left(f_{1}, \ldots, f_{r}\right)$, such that the poles of $f_{i}$ are the $q^{r}$-spiral $\left[-c q^{-i+1} ; q^{r}\right]$, of multiplicity $\leqslant d$ and such that $\sigma_{q}\left(\tilde{F}_{\overline{\bar{c}}}\right)-B \tilde{F}_{\overline{\bar{c}}}=U$.

Proof. - We look for $F$ with meromorphic coefficients on $\mathbb{C}^{*}$ such that $\sigma_{q}(F)-B F=U$. By setting conditions on poles using Theta functions, we would like to obtain uniqueness of a such $F$.

Let $F=T^{-1} G$ such that $G \in\left(\mathcal{O}\left(\mathbb{C}^{*}\right)\right)^{r}$ and $T \in \mathrm{GL}_{r}\left(\mathcal{O}\left(\mathbb{C}^{*}\right)\right)$ is the diagonal matrix:

$$
T=\left(\begin{array}{ccc}
\theta_{1} & & 0 \\
& \ddots & \\
0 & & \theta_{r}
\end{array}\right), F=\left(\begin{array}{c}
g_{1} / \theta_{1} \\
\vdots \\
g_{r} / \theta_{r}
\end{array}\right)
$$

We have $\sigma_{q}(F)-B F=U \Leftrightarrow \sigma_{q}(G)-T[B] G=\sigma_{q}(T) U$.
Let us denote $A=T[B]$ and let $G=\sum_{n \in \mathbb{Z}} G_{n} z^{n}$, and $V=\sigma_{q}(T) U=$ $\sum_{n \in \mathbb{Z}} V_{n} z^{n}$ then:

$$
\begin{aligned}
\sigma_{q}(G)-A G=V & \Leftrightarrow \forall n \in \mathbb{Z}, q^{n} G_{n}-A G_{n}=V_{n} \\
& \Leftrightarrow \forall n \in \mathbb{Z}, G_{n}=\left(q^{n} I_{r}-A\right)^{-1} V_{n}
\end{aligned}
$$

and,

$$
A=T[B]=\sigma_{q}(T) B T^{-1}=\left(\begin{array}{cccc}
0 & \frac{\sigma_{q}\left(\theta_{1}\right)}{\theta_{2}} & 0 & \\
& & \ddots & 0 \\
0 & & & \frac{\sigma_{q}\left(\theta_{r-1}\right)}{\theta_{r}} \\
b^{\prime} z^{-d \frac{\sigma_{q}\left(\theta_{r}\right)}{\theta_{1}}} & 0 & \cdots & 0
\end{array}\right)
$$

We choose $A$ of the following form:

$$
\left(\begin{array}{cccc}
0 & 1 & 0 & \\
\vdots & & \ddots & \\
0 & & & 1 \\
c^{\prime} & 0 & \ldots & 0
\end{array}\right), \quad c^{\prime} \in \mathbb{C}^{*}
$$

Its eigenvalues are the $r$ th roots of $c^{\prime}$. Therefore, $G$ is unique if, and only if, for all $n \in \mathbb{Z}, c^{\prime} \neq q^{r n}$. Now, we have to determine $\theta_{i}$ satisfying:

$$
\left\{\begin{array}{c}
\theta_{2}=\sigma_{q}\left(\theta_{1}\right) \\
\theta_{3}=\sigma_{q}^{2}\left(\theta_{1}\right) \\
\vdots \\
\sigma_{q}^{r}\left(\theta_{1}\right)=c^{\prime} b^{\prime-1} z^{d} \theta_{1}
\end{array}\right.
$$

Let $c \in \mathbb{C}^{*}$, we put $c^{\prime}=b^{\prime} c^{-d}$ and $\theta_{1}=\left(\theta_{q^{r}, c}\right)^{d}$. The zeroes of $\theta_{1}$ have multiplicity $d$ and are the $q^{r}$-spiral $\left[-c ; q^{r}\right]$. The Jacobi's triple product formula gives

$$
\begin{aligned}
\theta_{i+1} & =\sigma_{q}^{i}\left(\theta_{q^{r}, c}^{d}(z)\right) \\
& =\prod_{n \geqslant 1}\left(1-q^{-r n}\right)^{d} \prod_{n \geqslant 1}\left(1+q^{-r n} q^{i} \frac{z}{c}\right)^{d} \prod_{n \geqslant 0}\left(1+q^{-r n} q^{-i}\left(\frac{z}{c}\right)^{-1}\right)^{d}
\end{aligned}
$$

so that the zeroes of $\theta_{i}$ have multiplicity $d$ and are the $q^{r}$-spiral $\left[-c q^{-i+1} ; q^{r}\right]$.

Then, we put $\tilde{F}_{c}=T^{-1} G$. For the chosen matrix $T, F$ exists and is unique on condition that for all $n \in \mathbb{Z}, c^{d} \neq b^{\prime} q^{r n}$.

In order to finish, we need to verify that our computation of $\tilde{F}_{c}$ depends only on $\overline{\bar{c}}$, that is $\tilde{F}_{c}=\tilde{F}_{c q^{r}}$. Writing $G={ }^{t}\left(g_{1}, \ldots, g_{r}\right), U={ }^{t}\left(u_{1}, \ldots, u_{r}\right)$,
we have:

$$
\begin{align*}
\sigma_{q}(G)-A G=\sigma_{q}(T) U & \Leftrightarrow\left\{\begin{array}{c}
\sigma_{q}\left(g_{1}\right)-g_{2}=\sigma_{q}\left(\theta_{1}\right) u_{1} \\
\sigma_{q}\left(g_{2}\right)-g_{3}=\sigma_{q}\left(\theta_{2}\right) u_{2} \\
\vdots \\
\sigma_{q}\left(g_{r}\right)-c^{\prime} g_{1}=\sigma_{q}\left(\theta_{r}\right) u_{r}
\end{array}\right.  \tag{3.1}\\
& \Leftrightarrow\left\{\begin{array}{c}
g_{2}=\sigma_{q}\left(g_{1}\right)-\sigma_{q}\left(\theta_{1}\right) u_{1} \\
g_{3}=\sigma_{q}^{2}\left(g_{1}\right)-\sigma_{q}^{2}\left(\theta_{1}\right)\left(\sigma_{q}\left(u_{1}\right)+u_{2}\right) \\
\vdots \\
\sigma_{q}^{r}\left(g_{1}\right)=c^{\prime} g_{1}+\sigma_{q}^{r}\left(\theta_{1}\right) \varphi(U),
\end{array}\right.
\end{align*}
$$

where $\varphi(U)=\sigma_{q}^{r-1}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{r-1}\right)+u_{r}$ is the map defined in Theorem 2.8.

We replace $c$ by $c q^{r}$, let $\theta_{1}^{\prime}=\left(\theta_{q^{r}, c q^{r}}\right)^{d}$ and $\theta_{i}^{\prime}=\sigma_{q}^{i-1}\left(\theta_{1}^{\prime}\right)$. We remark thanks to the Jacobi's triple product formula that:

$$
\theta_{1}^{\prime}=\left(\theta_{q^{r}, c q^{r}}\right)^{d}=\left(q^{r}\left(\frac{z}{c}\right)^{-1} \theta_{q_{r}, c}\right)^{d}=q^{r d}\left(\frac{z}{c}\right)^{-d} \theta_{1}
$$

As $c$ is replaced by $c q^{r}, c^{\prime}$ is replaced by $c^{\prime} q^{-r d}$. If $\tilde{F}_{c q^{r}}=T^{\prime-1} G^{\prime}$, the equation verified by $g_{1}^{\prime}$ is:

$$
\begin{aligned}
\sigma_{q}^{r}\left(g_{1}^{\prime}\right)=c^{\prime} q^{-r d} & g_{1}^{\prime}+\sigma_{q}^{r}\left(\theta_{1}^{\prime}\right) \varphi(U) \\
& \Leftrightarrow \sigma_{q}^{r}\left(g_{1}^{\prime}\right)=c^{\prime} q^{-r d} g_{1}^{\prime}+c^{d} z^{-d} \sigma_{q}^{r}\left(\theta_{1}\right) \varphi(U) \\
& \Leftrightarrow \sigma_{q}^{r}\left(q^{-r d}\left(\frac{z}{c}\right)^{d} g_{1}^{\prime}\right)=c^{\prime} q^{-r d}\left(\frac{z}{c}\right)^{d} g_{1}^{\prime}+\sigma_{q}^{r}\left(\theta_{1}\right) \varphi(U)
\end{aligned}
$$

And yet, $g_{1}$ is the unique solution on $\mathbb{C}^{*}$ of $\sigma_{q}^{r}\left(g_{1}\right)=c^{\prime} g_{1}+\sigma_{q}^{r}\left(\theta_{1}\right) \varphi(U)$, so $g_{1}=q^{-r d}\left(\frac{z}{c}\right)^{d} g_{1}^{\prime}$. We easily verify that $\frac{g_{i}}{\theta_{i}}=\frac{g_{i}^{\prime}}{\theta_{i}}$, so $\tilde{F}_{c}=\tilde{F}_{c q^{r}}$.

Remark 3.2. - We notice the apparition of the elliptic curve $E_{q^{r}}$ instead of $E_{q}$. Nevertheless, $\tilde{F}_{\overline{\bar{c}}}$ does not have a unique pole $\overline{\overline{-c}}$, every coordinate of $\tilde{F}_{\overline{\bar{c}}}$ has poles $\overline{\overline{-c q^{-i+1}}}$.

Remark 3.3. - The hypothesis $U \in\left(\mathbb{C}[z]_{d-1}\right)^{r}$, can be weakened in this proposition. Indeed, it is sufficient that $U \in K^{r}$ to obtain existence and uniqueness of $F$.

Remark 3.4. - In the proof of Proposition 3.1, the last equality $\tilde{F}_{c}=$ $\tilde{F}_{c q^{r}}$ can also be justified without any calculation because the two members satisfy the same constraint of uniqueness.

Let $\tilde{F}_{\overline{\bar{c}} \overline{\bar{c}}^{\prime}}\left(A_{U}\right)=\tilde{F}_{\bar{c}^{\prime}}-\tilde{F}_{\overline{\bar{c}}}={ }^{t}\left(f_{\overline{\bar{c}}, \overline{\bar{c}}^{\prime}}, \sigma_{q}\left(f_{\overline{\bar{c}}, \overline{\bar{c}}^{\prime}}\right), \ldots, \sigma_{q}^{r-1}\left(f_{\overline{\bar{c}, \overline{c^{\prime}}}}\right)\right)$ where $f_{\overline{\bar{c}}, \overline{\bar{c}^{\prime}}}=$ $f_{\overline{\bar{c}}^{\prime}}-f_{\overline{\bar{c}}}$ satisfy this equation:

$$
\sigma_{q}^{r}\left(f_{\overline{\bar{c}}}\right)-b^{r} q^{-d(r-1) / 2} z^{-d} f_{\overline{\bar{c}}}=\varphi(U)
$$

$\varphi$ is the map defined in Theorem 2.8. The poles of $\tilde{F}_{\overline{\bar{c}}, \overline{\bar{c}}^{\prime}}\left(A_{U}\right)$ are located on $E_{q}$ and correspond to $\overline{-c}, \overline{-c^{\prime}}$. The function $\tilde{F}_{\overline{\bar{c}}, \bar{c}^{\prime}}\left(A_{U}\right)$ satisfies $\sigma_{q}\left(\tilde{F}_{\overline{\bar{c}, \bar{c}^{\prime}}}\right)-$ $B \tilde{F}_{\overline{\bar{c}} \overline{\bar{c}}^{\prime}}=0$.

Let $M=\left(K^{n}, \Phi_{A}\right)$ be a $q$-difference module in normal form, the holomorphic vector bundle on $E_{q}$ associated with $M$ is defined by:

$$
\mathcal{F}_{M}=\frac{\mathbb{C}^{*} \times \mathbb{C}^{n}}{(z, X) \sim(q z, A(z) X)} \longrightarrow E_{q}
$$

As a sheaf, it associates to every open set $V \subset E_{q}$ the space of holomorphic solutions over $\pi^{-1}(V) \subset \mathbb{C}^{*}$ of the $q$-difference system $Y(q z)=A(z) Y(z)$, or rather their germs near 0 (cf. [17]).

The functions $\tilde{F}_{\overline{\bar{c}}, \bar{c}^{\prime}}\left(A_{U}\right)$ are sections of the vector bundle $\mathcal{F}_{E}$ on the open sets $V_{\bar{c}, \bar{c}^{\prime}}=E_{q} \backslash\left\{\overline{-c}, \overline{-c^{\prime}}\right\}$.

Theorem 3.5. - There is an isomorphism of $\mathbb{C}$-vector spaces:

$$
\mathcal{F}(E, \underline{1}) \cong H^{1}\left(E_{q}, \mathcal{F}_{E}\right)
$$

induced by:

$$
M_{U}=\left(K^{r+1}, \Phi_{A_{U}}\right) \mapsto\left(\tilde{F}_{\overline{\bar{c}}, \overline{\bar{c}}^{\prime}}\left(A_{U}\right)\right) .
$$

Proof. - According to the previous proposition, for all $\overline{\bar{c}}, \overline{\bar{c}}^{\prime} \in E_{q^{r}} \backslash$ $\Sigma\left(A_{0}\right)$, we can associate with each matrix $A_{U}, U \in\left(\mathbb{C}[z]_{d-1}\right)^{r}$, a unique vector of holomorphic functions on $V_{\bar{c}, \bar{c}^{\prime}}$, denoted by $\tilde{F}_{\overline{\bar{c}}, \bar{c}^{\prime}}\left(A_{U}\right)$. First, let us prove that the $\tilde{F}_{\overline{\bar{c}}, \bar{c}^{\prime}}\left(A_{U}\right)$ depends only on the class of $M_{U}$ in $\mathcal{F}(E, \underline{1})$. Let $U^{\prime} \in \mathbb{C}[z]_{d-1}$ such that $\left[M_{U}\right]=\left[M_{U^{\prime}}\right]$, that is, thanks to the Theorem 2.8, $\varphi(U)=\varphi\left(U^{\prime}\right)$ and there exists an isomorphism $H \in \mathfrak{S}_{r, 1}(K)$ between $M_{U}$ and $M_{U^{\prime}}$. By Proposition 3.1, the uniqueness of $\tilde{F}_{\overline{\bar{c}}}\left(A_{U}\right)$ and $\tilde{F}_{\bar{c}^{\prime}}\left(A_{U^{\prime}}\right)$ gives us the following commutative diagram:

where

$$
\tilde{S}_{\overline{\bar{c}}} \hat{F}\left(A_{U}\right)=\left(\begin{array}{cc}
I_{r} & \tilde{F}_{\overline{\bar{c}}}\left(A_{U}\right) \\
0 & 1
\end{array}\right) \text { and } \tilde{S}_{\overline{\bar{c}}} \hat{F}\left(A_{U^{\prime}}\right)=\left(\begin{array}{cc}
I_{r} & \tilde{F}_{\overline{\bar{c}}}\left(A_{U^{\prime}}\right) \\
0 & 1
\end{array}\right)
$$

As a consequence, we easily see that $\tilde{F}_{\overline{\bar{c}}, \overline{\bar{c}}^{\prime}}\left(A_{U}\right)=\tilde{F}_{\overline{\bar{c}}, \overline{\bar{c}}^{\prime}}\left(A_{U^{\prime}}\right)$.
The map $\left[M_{U}\right] \mapsto \tilde{F}_{\overline{\bar{c}}, \bar{c}^{\prime}}\left(A_{U}\right)$ is well defined and induces a map:

$$
\alpha: \mathcal{F}(E, \underline{1}) \rightarrow Z^{1}\left(\mathcal{U}^{\prime}, \mathcal{F}_{E}\right)
$$

where $\mathcal{U}^{\prime}$ is a covering of $E_{q}$ that we are going to describe. We have $q^{r \mathbb{Z}} \subset$ $q^{\mathbb{Z}}$ hence an onto map $p: E_{q^{r}} \rightarrow E_{q}$ such that the following diagram is commutative:

$\pi_{1}$ and $\pi_{r}$ being the canonical projections. We set:

$$
W_{\overline{\bar{c}}}=E_{q} \backslash p(\{\overline{\bar{c}}\})
$$

It is an open set of $E_{q}$ and in fact $W_{\overline{\bar{c}}}=V_{\bar{c}}$. Thus $\tilde{F}_{\overline{\bar{c}}}$ is holomorphic on $W_{\overline{\bar{c}}}$. Putting:

$$
\mathcal{U}^{\prime}=\bigcup_{\bar{c} \in E_{q^{r}} \backslash \Sigma\left(A_{0}\right)} W_{\overline{\bar{c}}},
$$

we obtain an open covering of $E_{q}$. The map $\alpha: \mathcal{F}(E, \underline{1}) \rightarrow Z^{1}\left(\mathcal{U}^{\prime}, \mathcal{F}_{E}\right)$ is well defined and $\mathbb{C}$-linear, It is easy to see that $\tilde{F}_{\overline{\bar{c}}, \bar{c}^{\prime}}\left(A_{U+U^{\prime}}\right)=\tilde{F}_{\overline{\bar{c}}, \overline{\bar{c}}^{\prime}}\left(A_{U}\right)+$ $\tilde{F}_{\overline{\bar{c}}, \bar{c}^{\prime}}\left(A_{U^{\prime}}\right)$ and $\tilde{F}_{\overline{\bar{c}}, \overline{\bar{c}}^{\prime}}(\lambda U)=\lambda \tilde{F}_{\overline{\bar{c}}, \overline{\bar{c}}^{\prime}}(U)$ for all $\lambda \in \mathbb{C}$.

The map $\alpha$ is injective. Indeed, let us suppose that $\tilde{F}_{\overline{\bar{c}}, \bar{c}^{\prime}}(U)=0$ and show that $\left[M_{U}\right]=\left[M_{0}\right]$. We have $\tilde{F}_{\overline{\bar{c}}, \bar{c}^{\prime}}(U)=0 \Leftrightarrow \tilde{F}_{\overline{\bar{c}}}=\tilde{F}_{\overline{\bar{c}}^{\prime}}$. So, if $\overline{\bar{c}} \neq \overline{\bar{c}}^{\prime}, \tilde{F}_{\overline{\bar{c}}}$ and $\tilde{F}_{\bar{c}^{\prime}}$ have no poles on $\mathbb{C}^{*}$. Thus, we have an holomorphic function $F$ on $\mathbb{C}^{*}$ such that $\sigma_{q}(F)-B F=U$. The following lemma shows that necessarily if $F$ is meromorphic at 0 so that the morphism $\left(\begin{array}{cc}I_{r} & F \\ 0 & 1\end{array}\right)$ is an isomorphism over $K$ from $M_{0}$ to $M_{U}$, hence $\left[M_{U}\right]=\left[M_{0}\right]$.

Lemma 3.6. - A holomorphic solution on $\mathbb{C}^{*}$ of the equation $\sigma_{q}(F)$ $B F=U$ is automatically meromorphic on $\mathbb{C}$.

Proof of the lemma. - We write $F={ }^{t}\left(f_{1}, \ldots, f_{r}\right)$ then

$$
\begin{aligned}
\sigma_{q}(F)- & B F=U \\
& \Leftrightarrow\left\{\begin{array}{c}
f_{2}=\sigma_{q}\left(f_{1}\right)-u_{1} \\
\vdots \\
f_{r}=\sigma_{q}^{r-1}\left(f_{1}\right)-\left(\sigma_{q}^{r-2}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{r-2}\right)+u_{r-1}\right) \\
\sigma_{q}^{r}\left(f_{1}\right)=b^{\prime} z^{-d} f_{1}+\sigma_{q}^{r-1}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{r-1}\right)+u_{r} .
\end{array}\right.
\end{aligned}
$$

If $f_{1}=\sum_{n \in \mathbb{Z}} a_{n} z^{n}$ and $\varphi(U)=\sigma_{q}^{r-1}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{r-1}\right)+u_{r}=\sum_{k=0}^{d-1} v_{n} z^{n}$, the last equation is equivalent to $q^{r n} a_{n}=b^{\prime} a_{n+d}+v_{n}$ for all $n \in \mathbb{Z}$.

When $n<0$ the equation becomes $q^{r n} a_{n}=b^{\prime} a_{n+d}$. We denote by $s_{n}$ the rest of the euclidean division of $n$ by $d, n=-k_{n} d+s_{n}\left(k_{n} \geqslant 0\right)$. Then

$$
a_{n}=b^{\prime} q^{-r n} a_{n+d}=b^{\prime k_{n}} q^{-r\left(k_{n} n+\frac{k_{n}\left(k_{n}-1\right) d}{2}\right)} a_{s_{n}} .
$$

When $n$ tends to $-\infty, a_{n}$ is of order $q^{r n^{2}}$ so there is divergence. Necessarily, $a_{n}=0$ when $n \ll 0$.

In the same way, we see that the map $\bar{\alpha}: \mathcal{F}(E, \underline{1}) \rightarrow H^{1}\left(\mathcal{U}^{\prime}, \mathcal{F}_{E}\right)$ is $\mathbb{C}$-linear and injective. Indeed, the cohomology class of $\tilde{F}_{\overline{\bar{c}}, \overline{\bar{c}}^{\prime}}\left(A_{U}\right)$ is zero if $\tilde{F}_{\overline{\bar{c}}, \bar{c}^{\prime}}\left(A_{U}\right)=X_{\overline{\bar{c}}^{\prime}}-X_{\overline{\bar{c}}}$ with $X_{\overline{\bar{c}}}$ and $X_{\overline{\bar{c}}^{\prime}}$ holomorphic sections on $W_{\overline{\bar{c}}}$ and $W_{\overline{\bar{c}}^{\prime}}$; the argument is the same as the one to prove that $\alpha$ is injective.

Since in Cech cohomology, $H^{1}\left(\mathcal{U}^{\prime}, \mathcal{F}_{E}\right)$ embeds into the direct limit $H^{1}\left(E_{q}, \mathcal{F}_{E}\right) . \bar{\alpha}$ induces a map from $\mathcal{F}(E, \underline{1})$ to $H^{1}\left(E_{q}, \mathcal{F}_{E}\right)$ that is $\mathbb{C}$ linear and injective. Because of the dimension, it is an isomorphism. Indeed, we know by the general theory in [12] that $\operatorname{dim}_{\mathbb{C}} \mathcal{F}(E, \underline{1})=d$ and $\operatorname{dim}_{\mathbb{C}} H^{1}\left(E_{q}, \mathcal{F}_{E}\right)=d$; this uses the results on holomorphic vector bundles from [5, p. 64].

These results given in Proposition 3.1 and Theorem 3.5 can be generalized for an indecomposable module of the form $M=E \otimes U_{m}$. With the convention $\hat{\otimes}, M$ has an associated matrix $C$ of rank $m r$ :

$$
C=\left(\begin{array}{cccc}
B & B & & 0 \\
& \ddots & \ddots & \\
& & B & B \\
0 & & & B
\end{array}\right)
$$

Putting

$$
A_{U}=\left(\begin{array}{cc}
C & U \\
0 & 1
\end{array}\right), \quad U=\left(\begin{array}{c}
U_{1} \\
\vdots \\
U_{m}
\end{array}\right), \quad U_{i} \in\left(\mathbb{C}[z]_{d-1}\right)^{r}
$$

and writing $A_{0}$ the matrix associated with the graded module (i.e. $U=0$ ), we have the following proposition.

Proposition 3.7. - For all $U \in\left(\mathbb{C}[z]_{d-1}\right)^{n}$, for all $\overline{\bar{c}} \in E_{q^{r}} \backslash \Sigma\left(A_{0}\right)$, there exists a unique vector of meromorphic functions $\tilde{F}_{\overline{\bar{c}}}=\left(F_{i}\right)_{i=1 \ldots m}$ on $\mathbb{C}^{*}, F_{i}={ }^{t}\left(f_{1, i}, \ldots, f_{r, i}\right)$, such that the poles of $f_{k, i}$ are the $q^{r}$-spiral $\left[-c q^{-i+1} ; q^{r}\right]$, of multiplicity $\leqslant d$ and $\tilde{F}_{\overline{\bar{c}}}$ satisfies $\sigma_{q}\left(\tilde{F}_{\overline{\bar{c}}}\right)-B \tilde{F}_{\overline{\bar{c}}}=U$. The set $\Sigma\left(A_{0}\right)$ is equal to $\left\{c \in \mathbb{C}^{*} \mid \exists n \in \mathbb{Z}, c^{d}=b^{r} q^{\frac{-d(r-1)}{2}} q^{r n}\right\}$ modulo $q^{r}$ and is finite.

Proof. - The proof is the same as the case $\mathcal{F}(E, \underline{1})$ by putting $F=$ $T^{\prime-1} G$ where

$$
T^{\prime}=\left(\begin{array}{ccc}
T & & 0 \\
& \ddots & \\
0 & & T
\end{array}\right) \text { and } T^{\prime}[C]=\left(\begin{array}{cccc}
T[B] & T[B] & & 0 \\
& \ddots & \ddots & \\
& & T[B] & T[B] \\
0 & & & T[B]
\end{array}\right)
$$

This matrix is fuchsian and

$$
\sigma_{q}(F)-C F=U \Leftrightarrow \sigma_{q}(G)-T^{\prime}[C] G=\sigma_{q}\left(T^{\prime}\right) U
$$

In the next paragraph, we generalize the previous calculations to a $q$ difference module with two slopes non necessarily integral. We are guided in the same way as the study of $\mathcal{F}\left(P_{1}, P_{2}\right)$ by the isomorphism $\mathcal{F}\left(P_{1}, P_{2}\right) \cong$ $\mathcal{F}\left(P_{1} \otimes P_{2}^{\vee}, \underline{1}\right)$ given by the formula (2.4).

We suppose that $E_{1}$ and $E_{2}$ are two irreducible modules of slopes $\mu_{1}<\mu_{2}$ and their associated matrices are $B_{1}$ and $B_{2}$, one of them can have an integral slope. We look for a meromorphic isomorphism on $\mathbb{C}^{*}$ between the $q$-difference modules $\left(K^{r_{1}+r_{2}}, \Phi_{A_{0}}\right)$ and $\left(K^{r_{1}+r_{2}}, \Phi_{A_{U}}\right)$ where:

$$
A_{0}=\left(\begin{array}{cc}
B_{1} & 0 \\
0 & B_{2}
\end{array}\right) \quad \text { and } \quad A_{U}=\left(\begin{array}{cc}
B_{1} & U \\
0 & B_{2}
\end{array}\right), U \in M_{r_{1}, r_{2}}(K)
$$

and the matrix of the isomorphism has the following form: $\left(\begin{array}{cc}I_{r_{1}} & F \\ 0 & I_{r_{2}}\end{array}\right) \in$ $\mathfrak{S}_{r_{1}, r_{2}}$ satisfying $\sigma_{q}(F) B_{2}-B_{1} F=U$. But,

$$
\sigma_{q}(F) B_{2}-B_{1} F=U \Leftrightarrow \sigma_{q}(\hat{F})-B_{1} \hat{\otimes} B_{2}^{\vee} \hat{F}=\widehat{U B_{2}^{-1}}
$$

So, it is equivalent to look for $F$ such that $\sigma_{q}(F)-B_{1} \hat{\otimes} B_{2}^{\vee} F=U^{\prime}$, $U^{\prime}=\widehat{U B_{2}^{-1}}$. Let $M^{\prime}=\left(K^{r_{1} r_{2}+1}, \Phi_{A_{U^{\prime}}^{\prime}}\right)$ where:

$$
A_{U^{\prime}}^{\prime}=\left(\begin{array}{cc}
B_{1} \hat{\otimes} B_{2}^{\vee} & U^{\prime} \\
0 & 1
\end{array}\right), \quad U^{\prime}=\widehat{U B_{2}^{-1}}
$$

$B_{1} \hat{\otimes} B_{2}^{\vee}$ is associated with the module $E_{1} \otimes E_{2}^{\vee}$, according to Proposition 1.14, this module is isomorphic to a direct sum of irreducible $q$ difference modules of rank $r$ and slope $\frac{-d}{r}$. Then, there exists an isomorphism of $q$-difference modules $P$ (given by the proposition) such that $E_{1} \otimes E_{2}^{\vee}$ is isomorphic to a module with a matrix which is diagonal by blocks written $B$. The blocks are matrices $B_{i, j, l}, i, j=0, \ldots, k-1$ and $l=1, \ldots, \frac{p}{k}$ associated with irreducible modules $E\left(r,-d, b_{i, j}\right), b_{i, j}=q_{k}^{i} \xi_{r}^{j}\left(b_{1} b_{2}^{-1}\right)^{r}$, so, for all $i, j$, there are $p / k$ identical blocks $B_{i, j, l}$. We have $\sigma_{q}(P) B_{1} \hat{\otimes} B_{2}^{\vee}=$ $B P$.

Let $M^{\prime \prime}=\left(K^{r_{1} r_{2}+1}, \Phi_{A_{U^{\prime \prime}}^{\prime \prime}}\right)$ where $\sigma_{q}\left(P^{\prime}\right) A_{U^{\prime}}^{\prime}=A_{U^{\prime \prime}}^{\prime \prime} P^{\prime}$,

$$
P^{\prime}=\left(\begin{array}{ll}
P & 0 \\
0 & 1
\end{array}\right) \quad \text { and } \quad A_{U^{\prime \prime}}^{\prime \prime}=\left(\begin{array}{cc}
B & U^{\prime \prime} \\
0 & 1
\end{array}\right)
$$

We denote by $U^{\prime \prime}=\left(U_{i, j, l}^{\prime \prime}\right)_{i, j, l}$ and $A_{0}^{\prime \prime}$ is the matrix of the graded module $M^{\prime \prime}$ corresponding to $U^{\prime \prime}=0$. We apply Proposition 3.1, to each block $B_{i, j, l}$ associated with the vector $U_{i, j, l}^{\prime \prime} \in K^{r}$ (cf. Remark 3.3), for all $\overline{\bar{c}} \in$ $E_{q^{r}} \backslash \Sigma\left(A_{0}^{\prime \prime}\right)$, there exists a unique vector of meromorphic functions on $\mathbb{C}^{*}$, $\tilde{F}_{\overline{\bar{c}}(i, j, l)}$ satisfying the polar conditions of Proposition 3.1 and such that $\sigma_{q}\left(\tilde{F}_{\overline{\bar{c}},(i, j, l)}\right)-B_{i, j, l} \tilde{F}_{\overline{\bar{c}},(i, j, l)}=U_{i, j, l}^{\prime \prime}$. The set $\Sigma\left(A_{0}^{\prime \prime}\right)$ is equal to $\left\{c \in \mathbb{C}^{*} \mid\right.$ $\left.\exists n \in \mathbb{Z}, \exists i, j \in\{0, \ldots, k-1\}, c^{d}=b_{i, j} q^{\frac{-d(r-1)}{2}} q^{r n}\right\}$ modulo $q^{r}$ and it is finite.

We denote by $\tilde{F}_{\overline{\bar{c}}}\left(A_{U^{\prime \prime}}^{\prime \prime}\right)=\left(\tilde{F}_{\overline{\bar{c}},(i, j, l)}\right)$ the vector we obtain by concatenating the vectors corresponding to the blocks $(i, j, l)$ and satisfying the polar conditions of Proposition 3.1. So, let $\tilde{F}_{\bar{c}}\left(A_{U^{\prime}}^{\prime}\right)=P^{-1} \tilde{F}_{\bar{c}}\left(A_{U^{\prime \prime}}^{\prime \prime}\right)$. Thus, we define $\tilde{F}_{\bar{c}}\left(A_{U}\right)$ by:

$$
\widehat{\tilde{F}_{\overline{\bar{c}}}\left(A_{U}\right)}=\tilde{F}_{\overline{\bar{c}}}\left(A_{U^{\prime}}^{\prime}\right)=P^{-1} \tilde{F}_{\overline{\bar{c}}}\left(A_{U^{\prime \prime}}^{\prime \prime}\right)
$$

This latter verifies $\sigma_{q}\left(\tilde{F}_{\overline{\bar{c}}}\left(A_{U}\right)\right) B_{2}=B_{1} \tilde{F}_{\overline{\bar{c}}}\left(A_{U}\right)+U$ and is meromorphic on $\mathbb{C}^{*}$, it satisfies the polar conditions denoted by $(*)$ imposed by those of $\tilde{F}_{\bar{c},(i, j, l)}$. Putting $\Sigma\left(A_{0}\right):=\Sigma\left(A_{0}^{\prime \prime}\right)$, we have the following proposition:

Proposition 3.8. - For all $U \in M_{r_{1}, r_{2}}(K)$, for all $\overline{\bar{c}} \in E_{q^{r}} \backslash \Sigma\left(A_{0}\right)$ there exists a unique matrix $\tilde{F}_{\overline{\bar{c}}}\left(A_{U}\right)$ of rank $r_{1} \times r_{2}$ with meromorphic coefficients on $\mathbb{C}^{*}$ and satisfying the polar conditions $(*)$, such that $\sigma_{q}(F) B_{2}=$ $B_{1} F+U$.

Then, we obtain a meromorphic isomorphism on $\mathbb{C}^{*}$ from the module $\left(K^{r_{1}+r_{2}}, \Phi_{A_{0}}\right)$ to the module $\left(K^{r_{1}+r_{2}}, \Phi_{A_{U}}\right)$, that we denote $\tilde{S}_{\bar{c}} \hat{F}\left(A_{U}\right)=$ $\left(\begin{array}{cc}I_{r_{1}} & \tilde{F}_{\overline{\bar{c}}}\left(A_{U}\right) \\ 0 & I_{r_{2}}\end{array}\right)$.

We denote also $\tilde{F}_{\overline{\bar{c}}, \overline{\bar{c}}^{\prime}}\left(A_{U}\right)=\tilde{F}_{\bar{c}^{\prime}}\left(A_{U}\right)-\tilde{F}_{\overline{\bar{c}}}\left(A_{U}\right)$, so the Stokes operators associated with the module ( $K^{r_{1}+r_{2}}, \Phi_{A_{U}}$ ) are the meromorphic automorphisms of $\left(K^{r_{1}+r_{2}}, \Phi_{A_{0}}\right)$ :

$$
\tilde{S}_{\overline{\bar{c}}, \overline{c^{\prime}}} \hat{F}\left(A_{U}\right)=\left(\begin{array}{cc}
I_{r_{1}} & \tilde{F}_{\overline{\bar{c}}, \overline{\bar{c}}^{\prime}}\left(A_{U}\right) \\
0 & I_{r_{2}}
\end{array}\right), \quad \overline{\bar{c}}, \overline{\bar{c}}^{\prime} \in E_{q^{r}} \backslash \Sigma\left(A_{0}\right) .
$$

This proposition can be generalized for all modules with two slopes where at least one is non integral but we don't give the details because the calculations become unreadable but are explicit.

We are able to compute the Stokes operators associated with a $q$-difference module with two slopes. These Stokes operators don't have
galoisian properties yet, they only express an ambiguity of summation. Nevertheless, we will prove in the next section that they are galoisian.

## 4. Local Galois theory

In this section, we shall give a more concrete description of the results of van der Put and Reversat on the formal Galois group [7], then apply them as well as our results on Stokes operators to the description of the local analytic Galois group in the case of two slopes.

### 4.1. Formal Galois group

Let $q^{\prime} \in \mathbb{C}^{*},\left|q^{\prime}\right|>1,\left(K^{\prime}, \sigma_{q^{\prime}}\right)$ is a $q^{\prime}$-difference field such that $\left(K^{\prime}, \sigma_{q^{\prime}}\right)=$ $\left(K, \sigma_{q}\right)$ or $\left(K_{r}, \sigma_{q_{r}}\right)$ or $\left(K, \sigma_{q^{r}}\right)$. We will denote by:

- $\mathcal{E}_{p}\left(K^{\prime}, q^{\prime}\right)$ : the category of pure $q^{\prime}$-difference modules over $K^{\prime}$.
- $\mathcal{E}_{f}\left(K^{\prime}, q^{\prime}\right)$ : the category of pure $q^{\prime}$-difference modules of slope equal to 0 over $K^{\prime}$ (i-e fuchsian modules)
- $\mathcal{E}_{p, r}\left(K^{\prime}, q^{\prime}\right), r \in \mathbb{N}^{*}$ : the category of pure $q^{\prime}$-difference modules over $K^{\prime}$ of slopes $\frac{k}{r}$ for some $k \in \mathbb{Z}$.
If $r=1$, it is the category of pure $q^{\prime}$-difference modules with integral slopes. When it is not specified, $\mathcal{E}_{p}$, respectively $\mathcal{E}_{p, r}$ denote the category $\mathcal{E}_{p}(K, q)$, respectively $\mathcal{E}_{p, r}(K, q)$. These categories are $\mathbb{C}$-linear rigid abelian tensor categories (see [4]).

From now on, the pure isoclinic $q$-difference modules are supposed to be in normal form, in particular, their associated matrices have their coefficients in $\mathbb{C}\left[z, z^{-1}\right]$ (see paragraph 1.3).

Let $\left(K^{\prime}, \sigma_{q^{\prime}}\right)$ be $\left(K, \sigma_{q}\right)$. Let $z_{0} \in \mathbb{C}^{*}$, and $\omega_{z_{0}}$ be the fiber functor from the category $\mathcal{E}_{p}$ to the category of the $\mathbb{C}$-vector spaces of finite dimension, defined in [9] by:

$$
\begin{array}{rlll}
\omega_{z_{0}}: & \rightarrow \operatorname{Vect}_{\mathbb{C}}^{f} \\
& \rightsquigarrow \mathbb{C}^{n} \\
\left(K^{n}, \Phi_{A}\right) & \rightsquigarrow & F\left(z_{0}\right)
\end{array}
$$

This fiber functor turns $\mathcal{E}_{p}$ into a neutral tannakian category and allows one to define the tannakian Galois groups associated with the previous categories over $\left(K, \sigma_{q}\right)$.

The Galois group associated with the category $\mathcal{E}_{p}$ is the group of $\otimes$ compatible automorphisms of the fiber functor $\omega_{z_{0}}$ and we denote it by $G_{p}:=\operatorname{Aut}^{\otimes}\left(\omega_{z_{0}}\right)$.

The categories, $\mathcal{E}_{f}$, respectively $\mathcal{E}_{p, r}, r>0$, are full rigid abelian tensor subcategories of $\mathcal{E}_{p}$, and the fiber functor $\omega_{z_{0}}$ can be restricted to those tannakian categories. Their Galois group are defined by $G_{f}=\operatorname{Aut}^{\otimes}\left(\omega_{z_{0}} \mid \mathcal{E}_{f}\right)$ respectively, $G_{p, r}=\operatorname{Aut}^{\otimes}\left(\omega_{z_{0}} \mid \mathcal{E}_{p, r}\right)$. If we have to precise, we will denote $G_{p}(K, q), G_{f}(K, q)$ and $G_{p, r}(K, q)$. As $\mathcal{E}_{f}$ and $\mathcal{E}_{p, r}$ are full subcategories of $\mathcal{E}_{p}$ and $\mathcal{E}_{f}$ is a full subcategory of $\mathcal{E}_{p, r}$, according to [4, Proposition 2.21] the following group morphisms are onto (for details, see [15, 12]):

$$
G_{p} \rightarrow G_{f}, \quad G_{p} \rightarrow G_{p, r} \quad \text { and } \quad G_{p, r} \rightarrow G_{f}
$$

From now on, a pure $q$-difference module will always be a pair $\left(K^{n}, \Phi_{A}\right)$, where $A$ is a matrix in $\mathrm{GL}_{n}\left(\mathbb{C}\left[z, z^{-1}\right]\right)$ in normal form. Instead of writing $\varphi(M)$, we make reference to the matrix in normal form writing $\varphi(A)$. Thus, an element $\varphi$ of the Galois group is determined by the $\varphi(A), A$ being the matrix associated with the module (cf. [14, 1.1.2] for more details).

Our goal is to describe explicitly the matrices $\varphi(A)$ for all matrices $A$ in normal form.

As far as integral slopes are concerned, the formal Galois group is described explicitly in [14] and [9]:

$$
G_{p, 1}=\mathbb{C}^{*} \times \overbrace{E_{q}^{\vee} \times \mathbb{C}}^{G_{f}}
$$

where $E_{q}^{\vee}:=\operatorname{Hom}_{\mathrm{gr}}\left(E_{q}, \mathbb{C}^{*}\right)$ denote the morphisms of "abstract" group from $E_{q}$ to $\mathbb{C}^{*}$.

For a module $M=\left(K^{n}, \Phi_{z^{\mu} A}\right)$ where $A \in \mathrm{GL}_{n}(\mathbb{C})$, an element $\varphi=$ $(t, \gamma, \lambda) \in G_{p, 1}$ acts in the following way:

$$
\varphi(A)=t^{\mu} \gamma\left(A_{s}\right) A_{u}^{\lambda}
$$

where $t \in \mathbb{C}^{*}, \mu \in \mathbb{Z}$ is the slope of $M, \lambda \in \mathbb{C}, A=A_{s} A_{u}$ is the multiplicative Dunford decomposition, $A_{s}$ is the semisimple part and $A_{u}$ the unipotent part. Let us define $\gamma\left(A_{s}\right)$ : if $A_{s}=P \operatorname{diag}\left(a_{1}, \ldots, a_{n}\right) P^{-1}, P \in$ $\operatorname{GL}_{n}(\mathbb{C}), a_{i} \in \mathbb{C}^{*}$ then $\gamma\left(A_{s}\right)=P \operatorname{diag}\left(\gamma\left(a_{1}\right), \ldots, \gamma\left(a_{n}\right)\right) P^{-1}$ (it does not depend on diagonalisation).

As $A_{u}$ is a unipotent matrix $A_{u}^{\lambda}=\sum_{k \geqslant 0}\binom{\lambda}{k}\left(A_{u}-I_{n}\right)^{k}$ is well-defined.
Now, we want to describe the formal Galois group of $q$-difference modules with non integral slopes. Let us fix the denominator of the slopes $r \in \mathbb{N}^{*}$, let $z_{0, r}$ be a $r$ th root of $z_{0}$. We want to describe the Galois group $G_{p, r}$
associated with the category $\mathcal{E}_{p, r}$ of pure $q$-difference modules of slopes $\frac{k}{r}, k \in \mathbb{Z}$.

After Theorem 1.10, an element of the category $\mathcal{E}_{p, r}$ is a direct sum of indecomposable modules $E(s, t, c) \otimes U_{m}$ of slope $\frac{k}{r}=\frac{t m}{s m}$ and modules with integral slopes. For all $\varphi \in G_{p, r}$, we have $\varphi\left(E(s, t, c) \otimes U_{m}\right)=\varphi(E(s, t, c)) \otimes$ $\varphi\left(U_{m}\right)$.

And if $s$ divides $r$, then the inclusion $i_{r, s}$ of the categories $\mathcal{E}_{p, s} \subset \mathcal{E}_{p, r}$ induces an onto morphism $i_{r, s}^{*}$ of the associated Galois group: $G_{p, r} \rightarrow G_{p, s}$, so that for all $\varphi \in G_{p, r}, \varphi(E(s, t, c))=i_{r, s}^{*}(\varphi)(E(s, t, c))$.

As a consequence, to study the image of the matrix associated with a module of $\mathcal{E}_{p, r}$ by an element of the Galois group, it is sufficient to study the image $\varphi(A), \varphi \in G_{p, r}$, where $A$ is associated with $E\left(r, d, a^{r}\right)$, an irreducible $q$-difference module of slope $\frac{d}{r}\left(a \in \mathbb{C}^{*}, \operatorname{gcd}(d, r)=1\right)$ :

$$
A=\left(\begin{array}{cccc}
0 & 1 & & \\
\vdots & & \ddots & \\
0 & & & 1 \\
a^{r} q^{\frac{d(r-1)}{2}} z^{d} & 0 & \ldots & 0
\end{array}\right) \in \mathrm{GL}_{r}(\mathbb{C})
$$

The category $\mathcal{E}_{p, 1}$ is a full subcategory of $\mathcal{E}_{p, r}$, we denote by $i$ this inclusion. There is a morphism of groups $i^{*}: G_{p, r} \rightarrow G_{p, 1}$ (restriction to a subcategory) such that $i^{*}(\varphi)(B)=\varphi(B)$ for all matrices $B$ with integral slope (these are at the same time in $E_{p, r}$ and $E_{p, 1}$ ). As we know how to describe the action of the Galois group on a module with integral slopes, we try to be in this case to describe $\varphi(A)$. Then, we obtain the following theorem.

We recall from Section 1, Subsection 1.1 that $\xi_{r}=e^{\frac{2 i \pi}{r}}$, a primitive $r$ th root of unity in $\mathbb{C}$, and that $q_{r}=e^{\frac{2 i \pi \tau}{r}}$, a $r$ th root of $q=e^{2 i \pi \tau}$.

Theorem 4.1. - Let $\varphi \in G_{p, r}$. Then there exists $t \in \mathbb{C}^{*}, \gamma \in E_{q}^{\vee}$ and $\lambda \in \mathbb{C}$ such that $\varphi=(t, \gamma, \lambda)$ and $i^{*}(\varphi)=\left(t^{r}, \gamma, \lambda\right)$. Moreover, if $A$ is the matrix in normal form which is associated with an irreducible module $E\left(r, d, a^{r}\right)$, there exists a matrix $G_{a, d}\left(z_{0, r}\right) \in \mathrm{GL}_{r}(\mathbb{C})$ such that:
$\varphi(A)=G_{a, d}^{-1}\left(z_{0, r}\right) t^{d} \gamma(a) \gamma\left(T_{r}\right) G_{a, d}\left(z_{0, r}\right)\left(\begin{array}{cccc}1 & & & 0 \\ & \gamma\left(q_{r}\right) & & \\ & & \ddots & \\ 0 & & & \gamma\left(q_{r}\right)^{(r-1)}\end{array}\right)^{d}$
and

$$
\begin{gathered}
G_{a, d}\left(z_{0, r}\right)=\operatorname{diag}\left(1, \alpha_{0}, \alpha_{0} \alpha_{1}, \ldots, \alpha_{0} \ldots \alpha_{r-2}\right), \quad \alpha_{j}=a^{-1} q_{r}^{-j d} z_{0, r}^{-d} \\
T_{r}=\left(\begin{array}{ccc}
0 & 1 \\
0 & \ddots & 1 \\
1 & \ldots & 0
\end{array}\right) \in \mathrm{GL}_{r}(\mathbb{C})
\end{gathered}
$$

Remark 4.2. - The action of $\lambda$ is on the unipotent part, it is described in the course of the proof.

Remark 4.3. - It is easy to see that $t$ depends only on $\varphi$, we have $\varphi(z)=t$, and $\varphi(A)$ depends only on $a^{r}$. The matrix $G_{a, d}\left(z_{0, r}\right)$ depends only on $A$.

## Remark 4.4.

(1) The matrix $T_{r}$ is conjugate to the diagonal matrix $\operatorname{diag}\left(1, \xi_{r}, \ldots\right.$, $\left.\xi_{r}^{r-1}\right)$, we have $T_{r}=V^{-1} \operatorname{diag}\left(1, \xi_{r}, \ldots, \xi_{r}^{r-1}\right) V$ where $V$ is the Vandermonde matrix:

$$
V=\left(\begin{array}{ccccc}
1 & 1 & \ldots & 1 & 1 \\
\xi_{r}^{-1} & \xi_{r}^{-2} & & \xi_{r}^{-(r-1)} & \vdots \\
\xi_{r}^{-2} & \xi_{r}^{-4} & & \xi_{r}^{-2(r-1)} & \vdots \\
\vdots & \vdots & & \vdots & \vdots \\
\xi_{r}^{-(r-1)} & \xi_{r}^{-2(r-1)} & \ldots & \xi_{r}^{-(r-1)^{2}} & 1
\end{array}\right) .
$$

(2) For all $\gamma \in E_{q}^{\vee}, \gamma\left(q_{r}\right)^{r}=1$ and $\gamma\left(\xi_{r}\right)^{r}=1$, so $\gamma\left(q_{r}\right)$ and $\gamma\left(\xi_{r}\right)$ are $r$ th roots of unity. In particular, if $\gamma\left(\xi_{r}\right)=\xi_{r}^{k}$, then $\gamma\left(T_{r}\right)=T_{r}^{k}$.

Proof. - The category $\mathcal{E}_{f}$ is a full subcategory of $\mathcal{E}_{p, r}$, we denote by $j$ this inclusion. Then, we have a morphism of groups $j^{*}: G_{p, r} \rightarrow G_{f}$ (restriction to a subcategory) such that $j^{*}(\varphi)(B)=\varphi(B)$ for all fuchsian matrices $B$.

We consider another irreducible module $E\left(r, r-d, b^{r}\right)$ of slope $1-\frac{d}{r}$ and associated matrix $B$. The tensor product adds the slopes so, $E\left(r, d, a^{r}\right) \otimes$ $E\left(r, r-d, b^{r}\right)$ has its slope equal to 1 and we can notice that

$$
\underbrace{E\left(r, d, a^{r}\right) \otimes \cdots \otimes E\left(r, d, a^{r}\right)}_{r \text { times }}
$$

is of slope $d$, that is to say, we have two ways to obtain integral slopes.
We use the convention $\hat{\otimes}$ for the tensor product of matrices and to simplify notations, it will be denoted by $\otimes$.

Study of the non fuchsian part. - Let $\varphi \in \operatorname{Ker}\left(j^{*}\right)$ be an element of the Galois group $G_{p, r}$ which is trivial on the fuchsian part. As $E\left(r, d, a^{r}\right) \otimes$ $E\left(r, r-d, b^{r}\right)$ is of slope 1 , it is isomorphic as a $q$-difference module over $K($ and $\hat{K})$ to a module $\left(K^{r^{2}}, \Phi_{z C}\right), C \in \mathrm{GL}_{r^{2}}(\mathbb{C})$. Hence, $\varphi(A) \otimes \varphi(B)$ is similar to $\varphi(z C)$. Putting $\varphi(z)=t^{r}, t \in \mathbb{C}^{*}$, we have:

$$
\varphi(A) \otimes \varphi(B)=t^{r} I_{r^{2}}
$$

if we identify $K^{r} \otimes K^{r}$ with $K^{r^{2}}$ taking for basis $\left\{e \otimes f, \Phi_{A}(e) \otimes f, \ldots\right.$, $\left.\Phi_{A}^{r-1}(e) \otimes f, e \otimes \Phi_{B}(f), \Phi_{A}(e) \otimes \Phi_{B}(f), \ldots\right\}$ (basis of convention $\hat{\otimes}$ ) ; e being the cyclic vector of $A$ and $f$ the cyclic vector of $B$, here $e$ and $f$ are the first vector of the canonical basis of $K^{r}$.

Necessarily $\varphi(A)$ and $\varphi(B)$ have to be diagonal.
Writing $\varphi(A)=\operatorname{diag}\left(a_{1}, \ldots, a_{r}\right)$ and $\varphi(B)=\operatorname{diag}\left(b_{1}, \ldots, b_{r}\right)$ then,

$$
\begin{aligned}
\varphi(A) \otimes \varphi(B) & =\left(\begin{array}{lll}
a_{1} & & 0 \\
& \ddots & \\
0 & & a_{r}
\end{array}\right) \otimes\left(\begin{array}{lll}
b_{1} & & 0 \\
& \ddots & \\
0 & & b_{r}
\end{array}\right) \\
& =\left(\begin{array}{cccc}
a_{1} b_{1} & & & 0 \\
& a_{2} b_{1} & & \\
& & & \ddots \\
0 & & & a_{r} b_{r}
\end{array}\right)=t^{r} I_{r^{2}}
\end{aligned}
$$

Consequently $\varphi(A) \otimes \varphi(B)=t^{r}\left(\alpha I_{r}\right) \otimes\left(\frac{1}{\alpha} I_{r}\right), \alpha \in \mathbb{C}^{*}$. So $\varphi(A)=a_{1} I_{r}$ and $\varphi(B)=b_{1} I_{r}$ such that $a_{1} b_{1}=t^{r}$.

As

$$
\overbrace{\varphi(A) \otimes \cdots \otimes \varphi(A)}^{r \text { times }}=t^{r d} I_{r^{r}}
$$

then $a_{1}^{r} I_{r^{r}}=t^{r d} I_{r^{r}}$, so $a_{1}=\left(\xi_{r}^{l} t\right)^{d}, l \in\{0, \ldots, r-1\}$ and $b_{1}=\left(\xi_{r}^{l^{\prime}} t\right)^{r-d}$.
As $a_{1} b_{1}=t^{r}$, we have $l=l^{\prime}$ so: $\varphi(A)=\left(\alpha_{d} t\right)^{d} I_{r}$ and $\varphi(B)=\left(\alpha_{d} t\right)^{r-d} I_{r}$ where $\alpha_{d}$ is a $r$ th root of 1 . The root $\alpha_{d}$ might depend on $d$ and $\varphi$. Let us prove that $\alpha_{d}$ depends only on $\varphi$. Let $d$ and $d^{\prime}$ be two integers coprime to $r$ (so $\operatorname{gcd}\left(d d^{\prime}, r\right)=1$ ), let $A_{d}$ be the matrix of $E\left(r, d, a^{r}\right)$ and $A_{d^{\prime}}$ the matrix of $E\left(r, d^{\prime}, a^{\prime r}\right)$ :

$$
\begin{aligned}
& \underbrace{\varphi\left(A_{d}\right) \otimes \cdots \otimes \varphi\left(A_{d}\right) \otimes \underbrace{\varphi\left(A_{d^{\prime}}\right) \otimes \cdots \otimes \varphi\left(A_{d^{\prime}}\right)}_{d \text { times }}}_{r-d^{\prime} \text { times }} \\
& \qquad=\left(\alpha_{d} t\right)^{d\left(r-d^{\prime}\right)} \times\left(\alpha_{d^{\prime}} t\right)^{d d^{\prime}} I=\alpha_{d}^{-d d^{\prime}} \times \alpha_{d^{\prime}}^{d d^{\prime}} t^{r d} I \\
& \\
& \quad \Rightarrow\left(\alpha_{d}^{-1} \alpha_{d^{\prime}}\right)^{d d^{\prime}}=1 \Rightarrow \alpha_{d}=\alpha_{d^{\prime}}
\end{aligned}
$$

Even if we have to change $t$ in $\alpha t$, we have:

$$
\text { if } \varphi \in \operatorname{Ker} j^{*}, \text { then } \varphi(A)=t^{d} I_{r}
$$

Study of the fuchsian part. - In the previous part, we studied the effect of the slopes on an element of the Galois group. We used the tensor product of two irreducible module to have an integral slope. With the same method, we study the effect of the fuchsian part. Let us recall some facts about the tensor product.

According to Lemma 1.15, there is an explicit matrix $P$ such that:

$$
\begin{array}{r}
A \otimes B=\sigma_{q}(P)\left(\begin{array}{lll}
C_{1} & & 0 \\
& \ddots & \\
0 & & C_{r}
\end{array}\right) P^{-1}, \text { and } C_{j}=\left(\begin{array}{ccc}
0 & 1 & \\
& \ddots & 1 \\
\tilde{c_{j}} & & 0
\end{array}\right) \\
\text { where } \tilde{c_{j}}
\end{array}=q^{\frac{r(r-1)}{2}}(a b)^{r} q^{(j-1) d} z^{r} .
$$

and $P$ is equal to:

where $a^{\prime}=\left(a^{r} q^{\frac{d(r-1)}{2}} z^{d}\right)^{-1}$ and the blocks have size $r$.
Let $\varphi \in G_{p, r}$, it is sufficient to study the image by $\varphi \in G_{p, r}$ of the blocks $C_{j}$. The matrix $C_{j}$ represents a module of slope 1 so we have to find an isomorphism with a matrix of the form $z A, A \in \mathrm{GL}_{r}(\mathbb{C})$. In fact, we have:

$$
C_{j}=\left(\begin{array}{ccc}
0 & 1 & \\
& \ddots & 1 \\
\tilde{c}_{j} & & 0
\end{array}\right)=\sigma_{q}\left(Q_{j}\right)^{-1} z\left(\begin{array}{cccc}
c_{j} & 0 & & 0 \\
0 & c_{j} \xi_{r} & \ddots & \\
& \ddots & \ddots & 0 \\
0 & & 0 & c_{j} \xi_{r}^{r-1}
\end{array}\right) Q_{j}
$$

where

$$
Q_{j}=\underbrace{\left(\begin{array}{ccccc}
1 & 1 & \ldots & 1 & 1 \\
\xi_{r}^{-1} & \xi_{r}^{-2} & & \xi_{r}^{-(r-1)} & \vdots \\
\xi_{r}^{-2} & \xi_{r}^{-4} & & \xi_{r}^{-2(r-1)} & \vdots \\
\vdots & \vdots & & \vdots & \vdots \\
\xi_{r}^{-(r-1)} & \xi_{r}^{-2(r-1)} & \ldots & \xi_{r}^{-(r-1)^{2}} & 1
\end{array}\right)}_{V} \underbrace{\left(\begin{array}{cccc}
g_{1}^{(j)} & 0 & & 0 \\
0 & g_{2}^{(j)} & \ddots & \\
& \ddots & \ddots & 0 \\
0 & & 0 & g_{r}^{(j)}
\end{array}\right)}_{G_{j}}
$$

and $g_{i}^{(j)}=c_{j}^{r-i} q^{\frac{r(r-1)}{2}} q^{-i(r-1)} q^{r-1} \ldots q^{r-i+1} z^{-(i-1)}$, cf. Remark 1.8. By restriction to $\mathcal{E}_{p, 1}, i^{*}(\varphi)=\left(t^{r}, \gamma, \lambda\right), t^{r} \in \mathbb{C}^{*}, \gamma \in \operatorname{Hom}_{\mathrm{gr}}\left(E_{q}, \mathbb{C}^{*}\right), \lambda \in \mathbb{C}$. So:

$$
\varphi\left(C_{j}\right)=Q_{j}\left(z_{0}\right)^{-1} \quad t^{r} \gamma\left(c_{j}\right)\left(\begin{array}{cccc}
1 & 0 & & 0 \\
0 & \gamma\left(\xi_{r}\right) & \ddots & \\
& \ddots & \ddots & 0 \\
0 & & 0 & \gamma\left(\xi_{r}\right)^{r-1}
\end{array}\right) Q_{j}\left(z_{0}\right)
$$

To continue, we need to explicit $Q_{j}^{-1}$ and thanks to the following lemma, the inverse of the matrix of Vandermonde $V$ is:

$$
V^{-1}=\frac{1}{r}\left(\begin{array}{ccccc}
1 & \xi_{r} & \xi_{r}^{2} & \ldots & \xi_{r}^{(r-1)} \\
1 & \xi_{r}^{2} & \xi_{r}^{4} & \ldots & \xi_{r}^{2(r-1)} \\
\vdots & & & & \vdots \\
1 & \xi_{r}^{(r-1)} & \xi_{r}^{2(r-1)} & \ldots & \xi_{r}^{(r-1)^{2}} \\
1 & 1 & 1 & \ldots & 1
\end{array}\right)
$$

Lemma 4.5. - Let $\xi_{r}$ be a primitive $r$ th root of unity, $\xi_{r}=e^{2 i \pi / r}$, and let $k \in \mathbb{Z}$ then:

$$
\sum_{j=1}^{r}\left(\xi_{r}^{k}\right)^{j}= \begin{cases}0 & \text { si } k \neq 0 \quad \bmod r \\ r & \text { otherwise }\end{cases}
$$

Proof. - For all $s \in \mathbb{N}^{*}$, the sum of $s$ th roots of unity is equal to zero.
Thus,

$$
\varphi\left(C_{j}\right)=t^{r} \gamma\left(c_{j}\right) G_{j}\left(z_{0}\right)^{-1} V^{-1}\left(\begin{array}{cccc}
1 & 0 & & 0 \\
0 & \gamma\left(\xi_{r}\right) & \ddots & \\
& \ddots & \ddots & 0 \\
0 & & 0 & \gamma\left(\xi_{r}\right)^{r-1}
\end{array}\right) V G_{j}\left(z_{0}\right)
$$

and, $V^{-1} \operatorname{diag}\left(1, \gamma\left(\xi_{r}\right), \ldots, \gamma\left(\xi_{r}\right)^{r-1}\right) V=\left(\frac{1}{r} \sum_{l=0}^{r-1}\left(\xi_{r}^{-(j-i)} \gamma\left(\xi_{r}\right)\right)^{l}\right)_{1 \leqslant i, j \leqslant r}$.
We have $\gamma\left(\xi_{r}\right)^{r}=1$ so $\gamma\left(\xi_{r}\right)$ is a $r$ th root of unity, there exists $k \in$ $\{0, \ldots, r-1\}$ such that $\gamma\left(\xi_{r}\right)=\xi_{r}^{k}$. According to Lemma 4.5, we can easily describe this product: $\varphi\left(C_{j}\right)=t^{r} \gamma\left(c_{j}\right) G_{j}\left(z_{0}\right)^{-1} T_{r}^{k} G_{j}\left(z_{0}\right)$ where

$$
T_{r}=\left(\begin{array}{ccc}
0 & 1 & \\
& \ddots & 1 \\
1 & & 0
\end{array}\right)=V^{-1}\left(\begin{array}{cccc}
1 & 0 & & 0 \\
0 & \xi_{r} & \ddots & \\
& \ddots & \ddots & 0 \\
0 & & 0 & \xi_{r}^{r-1}
\end{array}\right) V
$$

Moreover $\gamma\left(T_{r}\right)=T_{r}^{k}$ so $\varphi\left(C_{j}\right)=t^{r} \gamma\left(c_{j}\right) G_{j}\left(z_{0}\right)^{-1} \gamma\left(T_{r}\right) G_{j}\left(z_{0}\right)$.
Now, we have:

$$
\varphi(A \otimes B)=P\left(z_{0}\right)\left(\begin{array}{ccc}
\varphi\left(C_{1}\right) & & \\
& \ddots & \\
& & \varphi\left(C_{r}\right)
\end{array}\right) P\left(z_{0}\right)^{-1}
$$

$$
=t^{r} \gamma(a b) P\left(z_{0}\right) G\left(z_{0}\right)^{-1}\left(\begin{array}{ccc}
\gamma\left(T_{r}\right) & & 0 \\
& \gamma\left(q_{r}\right)^{d} \gamma\left(T_{r}\right) & \\
& \ddots & \\
0 & & \gamma\left(q_{r}\right)^{d(r-1)} \gamma\left(T_{r}\right)
\end{array}\right) G\left(z_{0}\right) P\left(z_{0}\right)^{-1} .
$$

$G\left(z_{0}\right)$ is the diagonal matrix with diagonal blocks $G_{j}\left(z_{0}\right) j=1, \ldots, r$. We set $G^{\prime}\left(z_{0}\right)=$
where $g_{i}^{(j)}:=g_{i}^{(j)}\left(z_{0}\right), a^{\prime}:=a^{\prime}\left(z_{0}\right), \sigma_{q}^{l}\left(a^{\prime}\right):=a^{\prime}\left(q^{l} z_{0}\right)$ by abusing the notation,

$$
g_{i}^{(j)}=(a b)^{r-i} q_{r}^{(j-1) d(r-i)} q^{\frac{r(r-1)}{2}} q^{-i(r-1)} q^{r-1} \ldots q^{r-i+1} z_{0}^{-(i-1)}
$$

Writing $\gamma\left(T_{r}\right)=\left(j_{i, j}\right)_{1 \leqslant i, j \leqslant r}$, we obtain

$$
\varphi(A \otimes B)=t^{r} \gamma(a) \gamma(b) G^{\prime}\left(z_{0}\right) H G^{\prime}\left(z_{0}\right)^{-1}
$$

where $H$ is described in Figure 4.1.
A tensor product appears in the structure of this matrix:

$$
H=\gamma\left(T_{r}\right)\left(\begin{array}{cccc}
1 & & & 0 \\
& \gamma\left(q_{r}\right) & & \\
& & \ddots & \\
0 & & & \gamma\left(q_{r}\right)^{(r-1)}
\end{array}\right)^{d} \otimes \gamma\left(T_{r}\right)\left(\begin{array}{cccc}
1 & & & 0 \\
& \gamma\left(q_{r}\right) & & \\
& & \ddots & \\
0 & & & \gamma\left(q_{r}\right)^{(r-1)}
\end{array}\right)^{r-d}
$$

Thus,

$$
\begin{aligned}
\varphi(A \otimes B)=t^{r} \gamma(a) \gamma(b) & G^{\prime}\left(z_{0}\right) \gamma\left(T_{r}\right) \otimes \gamma\left(T_{r}\right) G^{\prime}\left(z_{0}\right)^{-1} \\
& \times\left(\begin{array}{ccc}
1 & & 0 \\
& \gamma\left(q_{r}\right) & \\
& & \ddots \\
0 & & \gamma\left(q_{r}\right)^{(r-1)}
\end{array}\right)^{d}\left(\begin{array}{ccc}
1 & & 0 \\
& \gamma\left(q_{r}\right) & \\
\\
& & \ddots \\
0 & & \gamma\left(q_{r}\right)^{(r-1)}
\end{array}\right)^{r-d}
\end{aligned}
$$

( $G^{\prime}\left(z_{0}\right)$ being diagonal, it commutes with the other diagonal matrices).
We have to find two matrices $U$ and $V$ such that:

$$
\left(\begin{array}{ccc}
0 & u_{2} & \\
& \ddots & u_{r} \\
u_{1} & & 0
\end{array}\right) \otimes\left(\begin{array}{ccc}
0 & v_{2} & \\
& \ddots & v_{r} \\
v_{1} & & 0
\end{array}\right)=G^{\prime}\left(z_{0}\right) T_{r} \otimes T_{r} G^{\prime}\left(z_{0}\right)^{-1} .
$$

We notice that

$$
\frac{g_{i}^{(j)}}{g_{k}^{(j)}}=(a b)^{k-i} q_{r}^{(j-1)(k-i)} q^{\frac{(k-i)(k+i-3)}{2}} z_{0}^{k-i}
$$

Then we have:

$$
\begin{aligned}
& u_{1} v_{1}=(a b)^{r-1} q^{\frac{(r-1)(r-2)}{2}} z_{0}^{r-1}, \\
& u_{2} v_{1}=a^{-1} b^{r-1} q_{r}^{d(r-1)} q^{\frac{(r-1)(r-2)}{2}} q^{\frac{-d(r-1)}{2}} z_{0}^{r-d-1}, \\
& u_{j} v_{1}=a^{-1} b^{r-1} q_{r}^{d(j-1)(r-1)} q^{\frac{(r-1)(r-2)}{2}} q^{\frac{-d(r-1)}{2}} q^{-(j-2) d} z_{0}^{r-d-1}, \\
& u_{r} v_{1}=a^{-1} b^{r-1} q_{r}^{d(r-1)^{2}} q^{\frac{(r-1)(r-2)}{2}} q^{\frac{-d(r-1)}{2}} q^{-(r-2) d} z_{0}^{r-d-1}, \\
& u_{1} v_{2}=a^{r-1} b^{-1} q_{r}^{-d(r-1)} q^{\frac{d(r-1)}{2}} z_{0}^{d-1} \\
& u_{2} v_{2}=(a b)^{-1} z_{0}^{-1} \\
& u_{j} v_{2}=(a b)^{-1} q_{r}^{-d(j-2)} z_{0}^{-1} \\
& u_{r} v_{2}=(a b)^{-1} q_{r}^{-d(r-2)} z_{0}^{-1} \cdots
\end{aligned}
$$



Figure 4.1.

Let $z_{0, r}$ be the $r$ th root of $z_{0}$ that we choose to begin, there exists $\alpha_{(d)} \in$ $\mathbb{C}^{*}$ such that:

$$
\begin{array}{ll}
u_{1}=\alpha_{(d)} a^{r-1} q_{r}^{\frac{d(r-1)(r-2)}{2}} z_{0, r}^{d(r-1)}, & v_{1}=\alpha_{(d)}^{-1} b^{r-1} q_{r}^{\frac{(r-d)(r-1)(r-2)}{2}} z_{0, r}^{(r-d)(r-1)}, \\
u_{2}=\alpha_{(d)} a^{-1} z_{0, r}^{-d}, & v_{2}=\alpha_{(d)}^{-1} b^{-1} z_{0, r}^{-(r-d)}, \\
u_{j}=\alpha_{(d)} a^{-1} q_{r}^{-d(j-2)} z_{0, r}^{-d}, & v_{j}=\alpha_{(d)}^{-1} b^{-1} q_{r}^{-(r-d)(j-2)} z_{0, r}^{-(r-d)}, \\
u_{r}=\alpha_{(d)} a^{-1} q_{r}^{-d(r-2)} z_{0, r}^{-d}, & v_{r}=\alpha_{(d)}^{-1} b^{-1} q_{r}^{-(r-d)(r-2)} z_{0, r}^{-(r-d)} .
\end{array}
$$

In fact, we have:

$$
\varphi(A)=t^{d} \alpha_{(d)} \gamma(a)\left(\begin{array}{cccc}
0 & \alpha_{0}^{-1} & & \\
0 & & \ddots & \\
0 & & & \alpha_{r-2}^{-1} \\
\alpha_{0} \alpha_{1} \ldots \alpha_{r-2} & 0 & \ldots & 0
\end{array}\right)^{k}
$$

$$
\times\left(\begin{array}{cccc}
1 & & & 0 \\
& \gamma\left(q_{r}\right) & & \\
& & \ddots & \\
0 & & & \gamma\left(q_{r}\right)^{(r-1)}
\end{array}\right)^{d}
$$

where $\alpha_{j}=a q_{r}^{j d} z_{0, r}^{d}$ and $\gamma\left(T_{r}\right)=T_{r}^{l}$. In the same way as the first part, we prove that $\alpha_{(d)}$ depends only on $d$ and $\varphi$, and that $\alpha_{(d)}=\alpha_{(1)}^{d}$ is $r$ th root of 1 . Even if we change $t$ in $\alpha_{(1)} t$, we can consider $\alpha_{(d)}=1$.

And if we set:

$$
G_{a, d}\left(z_{0, r}\right)=\left(\begin{array}{lllll}
1 & & & & \\
& \alpha_{0} & & & \\
& & \alpha_{0} \alpha_{1} & & \\
& & & \ddots & \\
& & & & \alpha_{0} \alpha_{1} \ldots \alpha_{r-2}
\end{array}\right)^{-1}
$$

we obtain the formula of Theorem 4.1.
Thus, an element of the Galois group $G_{p, r}$ is a triple $\varphi=(t, \gamma, \lambda)$ where $t \in \mathbb{C}^{*}, \gamma \in E_{q}^{\vee}, \lambda \in \mathbb{C}, \lambda$ acting on the unipotent part $U_{m}$.

The group law is given by $(t, \gamma, \lambda)\left(t^{\prime}, \gamma^{\prime}, \lambda^{\prime}\right)=\left(t t^{\prime} \gamma\left(q_{r}\right)^{-k^{\prime}}, \gamma \gamma^{\prime}, \lambda+\lambda^{\prime}\right)$ because the matrices $T_{r}$ and $\operatorname{diag}\left(1, \gamma\left(q_{r}\right), \ldots\right)$ don't commute.

As $\gamma\left(q_{r}\right)$ is $r$ th root of the unity, we have $\gamma\left(q_{r}\right)^{k^{\prime}}=\gamma^{\prime}\left(\gamma\left(q_{r}\right)\right)$ (which is the composition $\gamma^{\prime} \circ \gamma$ but not the multiplication in $\left.E_{q}^{\vee}\right)$. We set $\varepsilon_{r}\left(\gamma, \gamma^{\prime}\right)=$ $\frac{1}{\gamma^{\prime}\left(\gamma\left(q_{r}\right)\right)}=\xi_{r}^{-l k^{\prime}}$ if $\gamma\left(q_{r}\right)=\xi_{r}^{l}$ and $\gamma^{\prime}\left(\xi_{r}\right)=\xi_{r}^{k^{\prime}}$. So, the group law is:

$$
(t, \gamma, \lambda)\left(t^{\prime}, \gamma^{\prime}, \lambda^{\prime}\right)=\left(t t^{\prime} \varepsilon_{r}\left(\gamma, \gamma^{\prime}\right), \gamma \gamma^{\prime}, \lambda+\lambda^{\prime}\right)
$$

We easily verify that the group law is associative, as $\varepsilon_{r}$ satisfies the following property (and the symmetric property):

$$
\varepsilon_{r}\left(\gamma \gamma^{\prime}, \gamma^{\prime \prime}\right)=\varepsilon_{r}\left(\gamma, \gamma^{\prime \prime}\right) \varepsilon_{r}\left(\gamma^{\prime}, \gamma^{\prime \prime}\right)
$$

In fact, $\varepsilon_{r}: E_{q}^{\vee} \times E_{q}^{\vee} \rightarrow \mu_{r}$ is bilinear, $\mu_{r}$ denoting the group of the $r$ th roots of the unity.

Proposition 4.6. - The group $\mathbb{C}^{*}$ is central in $G_{p, r}$ and we have: $G_{p, r}=H_{r} \times \mathbb{C}$ where

$$
1 \rightarrow \mathbb{C}^{*} \xrightarrow{u} H_{r} \xrightarrow{v} E_{q}^{\vee} \rightarrow 1, \quad u(t)=(t, 1), v((t, \gamma))=\gamma
$$

is a central extension.
Proof. - We easily verify that $(t, \gamma)\left(t^{\prime}, 1\right)=\left(t^{\prime}, 1\right)(t, \gamma)$.
Remark 4.7. - The extension $1 \rightarrow \mathbb{C}^{*} \rightarrow H_{r} \rightarrow E_{q}^{\vee} \rightarrow 1$ is central but the exact sequence does not split. Indeed, to choose a section $s: E_{q}^{\vee} \rightarrow H_{r}$ such that $v \circ s=\operatorname{Id}_{E_{q}^{\vee}}$, the only possibility is to put $s(\gamma)=(1, \gamma)$, but it is not a morphism of groups because $(1, \gamma)\left(1, \gamma^{\prime}\right)=\left(\varepsilon_{r}\left(\gamma, \gamma^{\prime}\right), \gamma \gamma^{\prime}\right)$.

Let $r, s \in \mathbb{N}^{*}$, if $r$ divides $s$ then $\mathcal{E}_{p, r}$ is a full subcategory of $\mathcal{E}_{p, s}$. Thanks to Proposition 2.21 of [4], we have the onto morphisms of groups:

$$
\varphi_{r, s}: G_{p, s} \rightarrow G_{p, r}, \varphi_{r, s}(t, \gamma, \lambda)=\left(t^{s / r}, \gamma, \lambda\right)
$$

Proposition 4.8. - The universal formal Galois group is then $G_{p}=$ $H \times \mathbb{C}$ where $H=\underset{\leftrightarrows}{\lim } H_{r}$ and

$$
1 \rightarrow \mathbb{Q}^{\vee} \rightarrow H \rightarrow E_{q}^{\vee} \rightarrow 1
$$

is a central extension. The morphisms $\varphi_{r}: G_{p} \rightarrow G_{p, r}$ are $\varphi_{r}(\alpha, \gamma, \lambda)=$ $\left(\alpha\left(\frac{1}{r}\right), \gamma, \lambda\right)$.

An element of $G_{p}$ is a triple $(\alpha, \gamma, \lambda), \alpha \in \mathbb{Q}^{\vee}, \gamma \in E_{q}^{\vee}$ and $\lambda \in \mathbb{C}$. The group law is:

$$
(\alpha, \gamma, \lambda)\left(\alpha^{\prime}, \gamma^{\prime}, \lambda^{\prime}\right)=\left(\alpha \alpha^{\prime} \varepsilon\left(\gamma, \gamma^{\prime}\right), \gamma \gamma^{\prime}, \lambda+\lambda^{\prime}\right)
$$

where $\varepsilon: E_{q}^{\vee} \times E_{q}^{\vee} \rightarrow \mathbb{Q}^{\vee}$ is a morphism of groups such that $r \in \mathbb{N}^{*}$, $\varepsilon\left(\gamma, \gamma^{\prime}\right)\left(\frac{1}{r}\right)=\varepsilon_{r}\left(\gamma, \gamma^{\prime}\right)$.

Proof. - To prove Proposition 4.8, we need the two following lemmas.
Lemma 4.9. $-\underset{\leftarrow}{\lim }\left(H_{r} \times \mathbb{C}\right)=\lim _{\rightleftarrows}\left(H_{r}\right) \times \mathbb{C}$.

Lemma 4.10. - If we consider $\mathbb{C}^{*}$ with the following projective system: let $r, s \in \mathbb{N}^{*}$, if $r$ divides $s$, we put:

$$
\begin{aligned}
\rho_{r, s}: \mathbb{C}_{s}^{*} & \rightarrow \mathbb{C}_{r}^{*} \\
t & \mapsto t^{s / r} .
\end{aligned}
$$

Then $\lim _{\Longleftarrow}\left(\mathbb{C}_{r}^{*}\right)=\mathbb{Q}^{\vee}$.
The proofs of the lemmas are left to the reader.
For all $r \in \mathbb{N}^{*}$, we have the following exact sequence:

$$
1 \rightarrow \mathbb{C}^{*} \rightarrow H_{r} \rightarrow E_{q}^{\vee} \rightarrow 0
$$

Let us consider the following morphism of groups:

$$
\begin{aligned}
\varepsilon: E_{q}^{\vee} \times E_{q}^{\vee} & \rightarrow \mathbb{Q}^{\vee} \\
\left(\gamma, \gamma^{\prime}\right) & \mapsto \varepsilon\left(\gamma, \gamma^{\prime}\right),
\end{aligned}
$$

where $\varepsilon\left(\gamma, \gamma^{\prime}\right): \mathbb{Q} \rightarrow \mathbb{C}^{*}$ is a group morphism defined for all $r \in \mathbb{N}^{*}$ by $\varepsilon\left(\gamma, \gamma^{\prime}\right)\left(\frac{1}{r}\right)=\varepsilon_{r}\left(\gamma, \gamma^{\prime}\right)$.

So, we have $G_{p}=\lim _{\rightleftarrows}\left(H_{r}\right) \times \mathbb{C}$. One puts $H=\underset{\longleftarrow}{\lim } H_{r}$. We have:

$$
H=\left\{\begin{array}{l|l}
(\alpha, \gamma) \in \mathbb{Q}^{\vee} \times E_{q}^{\vee} & \begin{array}{c}
\forall \alpha, \alpha^{\prime} \in \mathbb{Q}^{\vee}, \forall \gamma, \gamma^{\prime} \in E_{q}^{\vee} \\
(\alpha, \gamma)\left(\alpha^{\prime}, \gamma^{\prime}\right)=\left(\alpha \alpha^{\prime} \varepsilon\left(\gamma, \gamma^{\prime}\right), \gamma \gamma^{\prime}\right)
\end{array}
\end{array}\right\}
$$

with the morphisms:

$$
\begin{aligned}
\psi_{r}: \quad H & \rightarrow H_{r} \\
(\alpha, \gamma) & \mapsto\left(\alpha\left(\frac{1}{r}\right), \gamma\right)
\end{aligned}
$$

that satisfy $\varphi_{r, s \mid} \circ \psi_{s}=\psi_{r}$.
As a consequence, we have the following diagram of exact sequences:

$\rho_{r}: \mathbb{Q}^{\vee} \rightarrow \mathbb{C}^{*}$ is defined by $\alpha \mapsto \alpha\left(\frac{1}{r}\right)$. These extensions are central.
We find the same result as van der Put and Reversat obtained by the Picard-Vessiot theory

### 4.2. Galois group

Let $\left(K^{\prime}, \sigma_{q^{\prime}}\right)$ be a $q^{\prime}$-difference field, $\left(K^{\prime}, \sigma_{q^{\prime}}\right)=\left(K, \sigma_{q}\right),\left(K_{r}, \sigma_{q_{r}}\right)$ or $\left(K, \sigma_{q^{r}}\right)$, we denote by:

- $\mathcal{E}\left(K^{\prime}, q^{\prime}\right)$ : the category of $q^{\prime}$-difference modules over $K^{\prime}$. If $\left(K^{\prime}, \sigma_{q^{\prime}}\right)=$ $\left(K, \sigma_{q}\right)$, we simply denote it by $\mathcal{E}$.
- $\mathcal{E}_{r}\left(K^{\prime}, q^{\prime}\right), r \in \mathbb{N}^{*}$ : the category of $q^{\prime}$-difference modules over $K^{\prime}$ of slopes $\frac{k}{r}, k \in \mathbb{Z}$ and over $\left(K, \sigma_{q}\right)$, we simply denote it by $\mathcal{E}_{r}$.
Every $q$-difference module admits a unique graded module. The functor gr from $\mathcal{E}$ to $\mathcal{E}_{p}$ (cf. [16]) associates with a $q$-difference module $M$ its graded module and with a morphism of $q$-difference modules its graded morphism. It is faithful, exact and tensor compatible.

We can consider that an element of $\mathcal{E}$ has a matrix in standard form:

$$
A_{U}=\left(\begin{array}{ccc}
A_{1} & & U_{i, j} \\
& \ddots & \\
0 & & A_{s}
\end{array}\right)
$$

where $A_{i}$ is the matrix of a pure isoclinic module in normal form. According to the Section $2, U_{i, j}$ are matrices with coefficients in $\mathbb{C}\left[z, z^{-1}\right]$.

We defined on $\mathcal{E}_{p}$, the functor $\omega_{z_{0}}$. Now, we define the functor $\hat{\omega}_{z_{0}}:=$ $\omega_{z_{0}} \circ \mathrm{gr}$ on $\mathcal{E}$. It is a fiber functor on $\mathcal{E}$. The category $\mathcal{E}$ provided with this fiber functor is tannakian. Let $G:=\operatorname{Aut}^{\otimes}\left(\hat{\omega}_{z_{0}}\right)$ be its Galois group. On the other hand, $\mathcal{E}_{p}$ is a subcategory of $\mathcal{E}$, if we denote by $i$ this inclusion, $\mathrm{gr} \circ i=\mathrm{id}$ and by tannakian duality, we have:

$$
G \underset{\mathrm{gr}^{*}}{\stackrel{i^{*}}{\rightleftarrows}} G_{p} \quad \text { and } \quad i^{*} \circ \mathrm{gr}^{*}=\mathrm{id}
$$

Let $S=$ Ker $i^{*}$ be the Stokes group (whose elements are trivial on pure modules), we obtain a split exact sequence:

$$
1 \rightarrow S \rightarrow G \rightarrow G_{p} \rightarrow 1
$$

Thus, the Galois group $G$ is the semi direct product of $S$ by $G_{p}, G=S \rtimes G_{p}$. The group $G_{p}$ acts by conjugation on the elements of $S$ : we will set for all $g_{0} \in G_{p}$ and $s \in S, s^{g_{0}}=g_{0} s g_{0}^{-1} \in S$.

For all $r \in \mathbb{N}^{*}$, the functor $\hat{\omega}_{z_{0}}$ restricts to the rigid abelian tensor subcategories $\mathcal{E}_{r}$ and the inclusion $i$ restricts too: $\mathcal{E}_{p, r} \subset \mathcal{E}_{r}$, as a consequence, we can define: $G_{r}:=\operatorname{Aut}^{\otimes}\left(\hat{\omega}_{z_{0}} \mid \mathcal{E}_{r}\right)$ the Galois group of the tannakian category $\mathcal{E}_{r}$ and $S_{r}=\operatorname{Ker}\left(\left.i^{*}\right|_{G_{r}}\right)$, the exact sequence of groups
$1 \rightarrow S_{r} \rightarrow G_{r} \rightarrow G_{p, r} \rightarrow 1$ is also split. We have the following commutative diagram:


The functor also restricts to the tannakian category which is generated by an object $M$ of $\mathcal{E}$, in this case, we will denote the previous groups by $S_{M}$, $G_{M}$ and $G_{p, M}$ and we have the split exact sequence of algebraic groups:

$$
1 \rightarrow S_{M} \rightarrow G_{M} \rightarrow G_{p, M} \rightarrow 1
$$

By tannakian theory, every tannakian category is equivalent to the category of rational representations of its Galois group. With an object $M$ of $\mathcal{E}$, we can associate the representation $\rho_{M}: G \rightarrow \operatorname{GL}\left(\hat{\omega}_{z_{0}}(M)\right), \varphi \mapsto \varphi(M)$. The group $G_{M}$ is identified to the algebraic subgroup $\operatorname{Im} \rho_{M}=G(M)=$ $\left\{\varphi(M) \mid \varphi \in G_{M}\right\}$ of $\operatorname{GL}\left(\hat{\omega}_{z_{0}}(M)\right)$.

### 4.3. Extensions of representations

We consider $\mathcal{C}$ the tannakian category generated by $q$-difference modules with two slopes whose graded module is fixed. Precisely, we fix $M_{0}=$ $\left(K^{n_{1}+n_{2}}, \Phi_{A_{0}}\right)$ which is a pure module with two slopes such that:

$$
A_{0}=\left(\begin{array}{cc}
A_{1} & 0 \\
0 & A_{2}
\end{array}\right)
$$

The modules $\left(K^{n_{1}}, \Phi_{A_{1}}\right)$ and $\left(K^{n_{2}}, \Phi_{A_{2}}\right)$ are pure isoclinic of slopes $\mu_{1}<\mu_{2}$. The category $\mathcal{C}$ is generated by the $q$-difference modules $M=$ $\left(K^{n_{1}+n_{2}}, \Phi_{A_{U}}\right)$ where:

$$
A_{U}=\left(\begin{array}{cc}
A_{1} & U \\
0 & A_{2}
\end{array}\right) \quad U \in M_{n_{1}, n_{2}}(K)
$$

Abusing the notation, a matrix denotes its associated module. Thus, for all $U \in M_{n_{1}, n_{2}}(K)$, we have an exact sequence of $q$-difference modules:

$$
0 \rightarrow A_{1} \rightarrow A_{U} \rightarrow A_{2} \rightarrow 0
$$

To simplify, we set $\omega:=\omega_{z_{0}}$ and $\hat{\omega}=\omega \circ \mathrm{gr}$, and here $G$ is the Galois group of the category $\mathcal{C}$ obtained by restriction of the functor $\hat{\omega}, S$ is the Stokes group and $G_{0}$ the Galois group of $\left\langle M_{0}\right\rangle$, which is also the formal Galois
group associated to the category $\mathcal{C}$. The following split exact sequence of groups is still true:

$$
1 \rightarrow S \rightarrow G \rightarrow G_{0} \rightarrow 1
$$

For the properties of vector groups used in the following, see $[2, \S 1.2]$ or [6].

Proposition 4.11. - The Stokes group of the category $\mathcal{C}$ is a vector group, that is to say, pro-unipotent and commutative.

Proof. - Let $N$ be an object of $\mathcal{C},\langle N\rangle$ is a full subcategory of $\mathcal{C}$, then there is an onto morphism of groups $j_{N}^{*}: G \rightarrow G_{N}$ and $N^{\prime}>N$ if there is an onto morphism of algebraic groups $j_{N, N^{\prime}}^{*}: G_{N^{\prime}} \rightarrow G_{N}$. The following diagram is commutative:


In the basic case $M=\left(K^{n_{1}+n_{2}}, \Phi_{A_{U}}\right)$, the Stokes group $S_{M}$ is isomorphic to the algebraic subgroup $\mathfrak{S}_{n_{1}, n_{2}}(\mathbb{C})$ of $\mathrm{GL}_{n_{1}+n_{2}}(\mathbb{C})$ (defined in Section 2.1), so $S_{M}$ is a vector space. Generally,

$$
S=\lim _{\check{ }} S_{N}
$$

for the projective system: $N^{\prime}>N$, if there exists $X$ such that $N^{\prime}=N \oplus X$, and by restriction, there is a linear morphism $j_{N, N^{\prime}}^{*}: S_{N^{\prime}} \rightarrow S_{N}$.

According to [4], $G=\lim _{\gtrless} G_{N}$, for all $N, S_{N}$ is a subgroup of $G_{N}$ and the morphisms $j_{N, N^{\prime}}^{*}$ restrict to $S$. Therefore, $S=\varliminf_{\longleftarrow} S_{N}$ is a commutative proalgebraic subgroup and it is pro-unipotent.

For $i=1,2$, let $V_{i}$ denote the $\mathbb{C}$-vector space $\hat{\omega}\left(A_{i}\right)$. Let $\rho_{1}: G \rightarrow \operatorname{GL}\left(V_{1}\right)$ be the representation of the group $G$ associated with $A_{1}$ and $\rho_{2}: G \rightarrow$ $\mathrm{GL}\left(V_{2}\right)$ the representation associated with $A_{2}$. If we denote by $\rho$ the representation of $G$ associated with $A_{U}$, the following sequence of representations is exact:

$$
0 \rightarrow \rho_{1} \rightarrow \rho \rightarrow \rho_{2} \rightarrow 0
$$

We have:

$$
\rho(g)=\left(\begin{array}{cc}
\rho_{1}(g) & \alpha(g) \\
0 & \rho_{2}(g)
\end{array}\right)
$$

where $\alpha$ is a map $G \rightarrow \mathcal{L}\left(V_{2}, V_{1}\right)$ such that $\rho$ is a representation of group, which means that $\alpha$ verifies:

$$
\begin{equation*}
\forall g, g^{\prime} \in G, \alpha\left(g g^{\prime}\right)=\rho_{1}(g) \alpha\left(g^{\prime}\right)+\alpha(g) \rho_{2}\left(g^{\prime}\right) \tag{4.1}
\end{equation*}
$$

Theorem 4.12. - There is an isomorphism of $\mathbb{C}$-vector spaces:

$$
\operatorname{Ext}\left(\rho_{2}, \rho_{1}\right) \xrightarrow{\sim} \mathcal{L}_{G_{0}}\left(S, \mathcal{L}\left(V_{2}, V_{1}\right)\right)
$$

Here, the group $G_{0}$ acts on $S$ and on $\left.\mathcal{L}\left(V_{2}, V_{1}\right)\right)$ which are $G_{0}$-modules.
We define the $\mathbb{C}$-vector space $\mathcal{L}_{G_{0}}\left(S, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$ to be the set of linear maps $\alpha$ from $S$ to $\mathcal{L}\left(V_{2}, V_{1}\right)$ such that for all $g_{0} \in G_{0}, \alpha\left(s^{g_{0}}\right)=$ $\rho_{1}\left(g_{0}\right) \alpha(s) \rho_{2}\left(g_{0}\right)^{-1}$ where $s^{g_{0}}:=g_{0} s g_{0}^{-1}$.

Remark 4.13. - Let us notice the analogy with the Corollary 5.11 of [7], the authors obtain a similar result with a Picard-Vessiot theory.

Proof. - The group $G$ acts on $\mathcal{L}\left(V_{2}, V_{1}\right)$ in the following way:

$$
\forall g \in G, \forall A \in \mathcal{L}\left(V_{2}, V_{1}\right), \quad g \cdot A:=\rho_{1}(g) A \rho_{2}(g)^{-1}
$$

We define $H^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$ as the quotient

$$
Z^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right) / B^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right)
$$

where $Z^{1}$ is the set of cocycles and $B^{1}$ the set of coboundaries, they are defined by:

$$
\begin{aligned}
& Z^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right)=\left\{f: G \rightarrow \mathcal{L}\left(V_{2}, V_{1}\right) \left\lvert\, \begin{array}{l}
\forall g, g^{\prime} \in G, \\
f\left(g g^{\prime}\right)=g \cdot f\left(g^{\prime}\right)+f(g)
\end{array}\right.\right\} \\
& B^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right)=\left\{f \in Z^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right) \left\lvert\, \begin{array}{r}
\exists A \in \mathcal{L}\left(V_{2}, V_{1}\right), \forall g \in G \\
f(g)=g \cdot A-A
\end{array}\right.\right\}
\end{aligned}
$$

and all $f$ in $Z^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$ and $B^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$ are rational.
Every matrix $A_{U}$ gives a representation of the group $G, \rho: G \rightarrow$ $\operatorname{GL}\left(V_{1} \times V_{2}\right)$ :

$$
\rho(g)=\left(\begin{array}{cc}
\rho_{1}(g) & \alpha(g) \\
0 & \rho_{2}(g)
\end{array}\right) .
$$

We put for all $g \in G, Z_{\rho}(g)=\alpha(g) \rho_{2}(g)^{-1}$. Then, $Z_{\rho}$ is a cocycle of dimension 1 for the cohomology of the group $G$ with values in $\mathcal{L}\left(V_{2}, V_{1}\right)$. Indeed,

$$
\begin{aligned}
& d Z_{\rho}\left(g g^{\prime}\right) \\
& =g \cdot Z_{\rho}\left(g^{\prime}\right)-Z_{\rho}\left(g g^{\prime}\right)+Z_{\rho}(g) \\
& =\rho_{1}(g) \alpha\left(g^{\prime}\right) \rho_{2}\left(g g^{\prime}\right)^{-1}-\alpha\left(g g^{\prime}\right) \rho_{2}\left(g g^{\prime}\right)^{-1}+\alpha(g) \rho_{2}(g)^{-1} \\
& =\rho_{1}(g) \alpha\left(g^{\prime}\right) \rho_{2}\left(g g^{\prime}\right)^{-1}-\rho_{1}(g) \alpha\left(g^{\prime}\right) \rho_{2}\left(g g^{\prime}\right)^{-1}-\alpha(g) \rho_{2}(g)^{-1}+\alpha(g) \rho_{2}(g)^{-1} \\
& =0
\end{aligned}
$$

As a consequence, $Z_{\rho} \in Z^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$. Let $B$ be a coboundary, there exists $A \in \mathcal{L}\left(V_{2}, V_{1}\right)$ such that for all $g \in G, B(g)=g . A-A$. So, $Z_{\rho}$ and $Z_{\rho^{\prime}}$ are in the same cohomology class if, and only if,

$$
\begin{aligned}
\forall g \in G, \quad Z_{\rho}(g)= & Z_{\rho^{\prime}}(g)+g \cdot A-A \\
& \Leftrightarrow \alpha(g)=\alpha^{\prime}(g)+\rho_{1}(g) A-A \rho_{2}(g) \\
& \Leftrightarrow \rho(g)=\left(\begin{array}{cc}
\operatorname{Id} & -A \\
0 & \mathrm{Id}
\end{array}\right)\left(\begin{array}{cc}
\rho_{1}(g) & \alpha^{\prime}(g) \\
0 & \rho_{2}(g)
\end{array}\right)\left(\begin{array}{cc}
\operatorname{Id} & A \\
0 & \mathrm{Id}
\end{array}\right),
\end{aligned}
$$

that is to say, the representation $\rho$ is isomorphic to the representation $\rho^{\prime}$, they have the same class in $\operatorname{Ext}\left(\rho_{2}, \rho_{1}\right)$. We prove in the same way that $\left[Z_{\rho}\right]=0$ if, and only if, $\rho$ is in the class of $\rho_{1} \oplus \rho_{2}$. Thus, we obtain an well defined injective map:

$$
\operatorname{Ext}\left(\rho_{2}, \rho_{1}\right) \rightarrow H^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right), \rho \mapsto\left[Z_{\rho}\right]
$$

This is a bijection because if $Z$ is a cocycle, we set for all $g \in G, \alpha(g):=$ $Z(g) \rho_{2}(g)$ and $\alpha$ is in $\mathcal{L}\left(V_{2}, V_{1}\right)$. As $Z$ is a cocycle $\alpha$ satisfies the property (4.1), so $\rho$ defined by

$$
\rho(g)=\left(\begin{array}{cc}
\rho_{1}(g) & \alpha(g) \\
0 & \rho_{2}(g)
\end{array}\right)
$$

is a representation of the group $G$ in $\operatorname{Ext}\left(\rho_{2}, \rho_{1}\right)$. We have constructed a bijection of sets:

$$
\begin{equation*}
\operatorname{Ext}\left(\rho_{2}, \rho_{1}\right) \xrightarrow{\sim} H^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right) \tag{4.2}
\end{equation*}
$$

There is left to prove:
(1) $H^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right) \cong \mathcal{L}_{G_{0}}\left(S, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$,
(2) the previous bijection (4.2) is a linear isomorphism.

Lemma 4.14. - $H^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right) \cong \mathcal{L}_{G_{0}}\left(S, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$ by $\left[Z_{\rho}\right] \mapsto Z_{\rho_{\mid S}}$.
Proof of Lemma 4.14. - Let $g \in G$, we can write $g=s g_{0}$ where $s \in S$ and $g_{0} \in G_{0}$ because $G=S \rtimes G_{0}$. Let $Z$ be a cocycle of $Z^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$, we have:

$$
Z(g)=Z\left(s g_{0}\right)=s . Z\left(g_{0}\right)+Z(s)=\rho_{1}(s) Z\left(g_{0}\right) \rho_{2}(s)^{-1}+Z(s)
$$

But $\rho_{i}(s)=s\left(A_{i}\right)=\mathrm{Id}$ for $i=1,2$ because $A_{i}$ is a matrix of a pure isoclinic module. Thus, $Z(g)=Z\left(g_{0}\right)+Z(s)$ and a coboundary for $S$ is necessarily zero because $B(s)=s . A-A=A-A=0$.

We have $H^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right) \subset H^{1}\left(G_{0}, \mathcal{L}\left(V_{2}, V_{1}\right)\right) \times \mathcal{L}_{G_{0}}\left(S, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$ defined by $[Z] \mapsto\left(\left[Z_{\mid G_{0}}\right], Z_{\mid S}\right)$. Indeed for all $s \in S$, we have $Z\left(s^{g_{0}}\right)=$
$\rho_{1}\left(g_{0}\right) Z(s) \rho_{2}\left(g_{0}\right)^{-1}$ so $Z_{\mid S}$ is in $\mathcal{L}_{G_{0}}\left(S, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$. We have a well defined and injective map.

Let us prove that $H^{1}\left(G_{0}, \mathcal{L}\left(V_{2}, V_{1}\right)\right)=0$. Let $Z^{\prime}$ be a cocycle in $Z^{1}\left(G_{0}, \mathcal{L}\left(V_{2}, V_{1}\right)\right)=0, Z^{\prime}$ gives a rational representation of $G_{0}$ :

$$
\rho: G_{0} \rightarrow \mathrm{GL}\left(V_{1} \times V_{2}\right), g_{0} \mapsto\left(\begin{array}{cc}
1 & Z^{\prime}\left(g_{0}\right) \\
0 & 1
\end{array}\right)\left(\begin{array}{cc}
\rho_{1}(g) & 0 \\
0 & \rho_{2}(g)
\end{array}\right)
$$

such that the sequence of representations of $G_{0}, 1 \rightarrow \rho_{1} \rightarrow \rho \rightarrow \rho_{2} \rightarrow 1$ is exact. By tannakian duality, the category of rational representations of $G_{0}$ is equivalent to the category $\left\langle M_{0}\right\rangle$. This exact sequence corresponds to the exact sequence in $\left\langle M_{0}\right\rangle: 1 \rightarrow M_{1} \rightarrow M \rightarrow M_{2} \rightarrow 1$. Necessarily, $M=M_{1} \oplus M_{2}$ since $\left\langle M_{0}\right\rangle$ has only pure modules and $M_{1}$ and $M_{2}$ have not the same slope. Thus, we have $\rho=\rho_{1} \oplus \rho_{2}$ and $Z_{\rho}\left(g_{0}\right)=Z^{\prime}\left(g_{0}\right)=0$.

If $g=s g_{0}$, and $Z \in H^{1}\left(G, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$, then $Z(g)=Z(s)$. The map described by the lemma is injective. It is onto: we put $\alpha \in \mathcal{L}_{G_{0}}\left(S, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$, for all $g \in G, g=s g_{0}, Z(g)=Z\left(s g_{0}\right):=\alpha(s), Z$ is a cocycle, indeed:

$$
\begin{aligned}
Z\left(g g^{\prime}\right)=Z\left(s g_{0} s^{\prime} g_{0}^{\prime}\right)=Z\left(s s^{\prime g_{0}} g_{0} g_{0}^{\prime}\right)=\alpha\left(s s^{\prime g_{0}}\right) & =\alpha(s)+g_{0} \cdot \alpha\left(s^{\prime}\right) \\
& =Z(g)+g \cdot Z\left(g^{\prime}\right)
\end{aligned}
$$

To finish the proof of the theorem, we have to prove that the bijection between $\operatorname{Ext}\left(\rho_{2}, \rho_{1}\right)$ and $\mathcal{L}_{G_{0}}\left(S, \mathcal{L}\left(V_{2}, V_{1}\right)\right)$ is a linear isomorphism.

The structure of $\mathbb{C}$-vector space of $\operatorname{Ext}\left(\rho_{2}, \rho_{1}\right)$ is described in [12] at Section A. 4 (for the extensions of modules). An element of $\operatorname{Ext}\left(\rho_{2}, \rho_{1}\right)$ is a representation of $G$ of the form:

$$
\rho: G \rightarrow \mathrm{GL}(V), \quad \forall g \in G, \rho(g)=\left(\begin{array}{cc}
\rho_{1}(g) & \alpha(g) \\
0 & \rho_{2}(g)
\end{array}\right)
$$

addition is given by:

$$
\rho+\rho^{\prime}: g \mapsto\left(\begin{array}{cc}
\rho_{1}(g) & \alpha(g)+\alpha^{\prime}(g) \\
0 & \rho_{2}(g)
\end{array}\right)
$$

the identity element is the representation $\rho_{1} \oplus \rho_{2}$ where for all $g \in G$, $\alpha(g)=0$. And scalar multiplication by $\lambda \in \mathbb{C}$ is defined by:

$$
\lambda \rho: g \mapsto\left(\begin{array}{cc}
\rho_{1}(g) & \lambda \alpha(g) \\
0 & \rho_{2}(g)
\end{array}\right) .
$$

Our map:

$$
\kappa: \operatorname{Ext}\left(\rho_{2}, \rho_{1}\right) \rightarrow \mathcal{L}_{G_{0}}\left(S, \mathcal{L}\left(V_{2}, V_{1}\right)\right),\left.\rho \mapsto Z_{\rho}\right|_{S}=\left.\alpha\right|_{S}
$$

is $\mathbb{C}$-linear and bijective.

Remark 4.15. - The theory of [18, Chapter VII] can be extended to the context of algebraic groups and rational maps. The Theorem 4.12 is then a particular case of the sequence of inflation restriction of [18, Chapter VII p. 126]. Indeed, by setting $A=\mathcal{L}\left(V_{2}, V_{1}\right)$, we have the following exact sequence:

$$
0 \rightarrow H^{1}\left(G / S, A^{S}\right) \rightarrow H^{1}(G, A) \rightarrow H^{1}(S, A)^{G_{0}} \rightarrow H^{2}(G / S, A)
$$

induced by $S \subset G$ and $i^{*}: G \rightarrow G_{0}$.
But the action of $S$ on $A$ is trivial, as a consequence $A^{S}=A$ and $H^{1}(S, A)$ is $\operatorname{Hom}(S, A)$, thus $H^{1}(S, A)^{G_{0}}=\mathcal{L}_{G_{0}}(S, A)$. In fact, we have:

$$
0 \rightarrow H^{1}\left(G_{0}, A\right) \rightarrow H^{1}(G, A) \rightarrow \mathcal{L}_{G_{0}}(S, A) \rightarrow 0
$$

The map $H^{1}(G, A) \rightarrow \mathcal{L}_{G_{0}}(S, A)$ is onto by the Lemma 4.14, we proved by hand but not using the fact $H^{2}=0$, the principal argument is $G=S \rtimes G_{0}$. By tannakian theory, we prove that $H^{1}\left(G_{0}, A\right)$ is zero.
4.3.1. Link between the Galois group of an element of $\mathcal{F}\left(P_{1}, P_{2}\right)$ and its corresponding element in $\mathcal{F}\left(P_{1} \otimes P_{2}^{\vee}, 1\right)$

If $P_{1}=\left(K^{n_{1}}, \Phi_{A_{1}}\right)$ and $P_{2}=\left(K^{n_{2}}, \Phi_{A_{2}}\right)$ are two pure isoclinic modules of slopes $\mu_{1}<\mu_{2}$, we saw that $\mathcal{F}\left(P_{1}, P_{2}\right)$ and $\mathcal{F}\left(P_{1} \otimes P_{2}^{\vee}, \underline{1}\right)$ are isomorphic (Theorem 2.4). If we take a representative of a class of $\mathcal{F}\left(P_{1}, P_{2}\right), M=$ $\left(K^{n_{1}+n_{2}}, \Phi_{A_{U}}\right)$ with:

$$
A_{U}=\left(\begin{array}{cc}
A_{1} & U \\
0 & A_{2}
\end{array}\right)
$$

and the corresponding element in $\mathcal{F}\left(P_{1} \otimes P_{2}^{\vee}, 1\right)$ is $M^{\prime}=\left(K^{r_{1} r_{2}+1}, \Phi_{A_{U^{\prime}}^{\prime}}\right)$ where:

$$
A_{U^{\prime}}^{\prime}=\left(\begin{array}{cc}
B_{1} \widehat{\otimes} B_{2}^{\vee} & U^{\prime} \\
0 & 1
\end{array}\right) \quad U^{\prime}=\widehat{U B_{2}^{-1}}
$$

Now we shall describe the relationship between their Galois groups.
According to Proposition 2.2 established during the study of $\mathcal{F}\left(P_{1}, P_{2}\right)$, the module $M^{\prime}$ is a pullback, we have:

$$
M^{\prime}=\left(M \otimes P_{2}^{\vee}\right) \times_{P_{2} \otimes P_{2}^{\vee}} \underline{1}
$$

There is an equivalence of categories between the category of $q$-difference modules and the category of the rational representations of the Galois group, so we study the pullback of the associated representations.

We follow the scheme of Proposition 2.2. We denote by $W_{1}=\hat{\omega}_{z_{0}}\left(P_{1}\right)$ and $W_{2}=\hat{\omega}_{z_{0}}\left(P_{2}\right)$ the vector spaces associated with $P_{1}$ and $P_{2}$. The representations of the Galois group of $P_{1}$ and $P_{2}$ are $\rho_{1}: G \rightarrow \operatorname{GL}\left(W_{1}\right)$ and $\rho_{2}$ : $G \rightarrow \mathrm{GL}\left(W_{2}\right)$.

The representation which is associated with $M$ is an extension of $\rho_{2}$ by $\rho_{1}$, we denote it by: $\rho_{v}: G \rightarrow \mathrm{GL}\left(W_{1} \times W_{2}\right)$ such that for all $\left(x_{1}, x_{2}\right) \in W_{1} \times W_{2}$, $\rho_{v}(g)\left(x_{1}, x_{2}\right)=\left(\rho_{1}(g)\left(x_{1}\right)+v(g)\left(x_{2}\right), \rho_{2}(g)\left(x_{2}\right)\right)$, where $v: G \rightarrow \mathcal{L}\left(W_{2}, W_{1}\right)$ satisfies:

$$
\forall g, g^{\prime} \in G, v\left(g g^{\prime}\right)=\rho_{1}(g) v\left(g^{\prime}\right)+v(g) \rho_{2}\left(g^{\prime}\right)
$$

We have an exact sequence of representations:

$$
0 \rightarrow \rho_{1} \rightarrow \rho_{v} \rightarrow \rho_{2} \rightarrow 0
$$

by identifying $\rho \otimes \rho_{2}^{\vee}$ with $\operatorname{Hom}\left(\rho_{2}, \rho\right)$, we have the exact sequence

$$
0 \rightarrow \underline{\operatorname{Hom}}\left(\rho_{2}, \rho_{1}\right) \rightarrow \underline{\operatorname{Hom}}\left(\rho_{2}, \rho_{v}\right) \rightarrow \underline{\operatorname{Hom}}\left(\rho_{2}, \rho_{2}\right) \rightarrow 0
$$

where $\underline{\operatorname{Hom}}\left(\rho_{2}, \rho_{1}\right)$ corresponds to the representation $G \rightarrow \mathcal{L}\left(W_{2}, W_{1}\right)$ such that $g \mapsto\left(p \in \mathcal{L}\left(W_{2}, W_{1}\right) \mapsto \rho_{1}(g) \circ p \circ \rho_{2}(g)^{-1}\right) ; \underline{\operatorname{Hom}}\left(\rho_{2}, \rho_{2}\right)$ corresponds to the representation $G \rightarrow \mathcal{L}\left(W_{2}, W_{2}\right)$ such that $g \mapsto\left(q \in \mathcal{L}\left(W_{2}, W_{2}\right) \mapsto\right.$ $\left.\rho_{2}(g) \circ q \circ \rho_{2}(g)^{-1}\right)$ and $\underline{\operatorname{Hom}}\left(\rho_{2}, \rho_{v}\right)$ corresponds to the representation $G \rightarrow$ $\mathcal{L}\left(W_{2}, W_{1}\right) \times \mathcal{L}\left(W_{2}, W_{2}\right)$ such that
$g \mapsto\left((p, q) \mapsto\left(\rho_{1}(g) \circ p \circ \rho_{2}(g)^{-1}+v(g) \circ q \circ \rho_{2}(g)^{-1}, \rho_{2}(g) \circ q \circ \rho_{2}(g)^{-1}\right)\right)$.
We make the pullback by $\underline{1} \rightarrow \underline{\operatorname{Hom}}\left(\rho_{2}, \rho_{2}\right)$ where $\underline{1}$ is the trivial representation and this morphism is described by $\mathbb{C} \rightarrow \mathcal{L}\left(W_{2}, W_{2}\right), \lambda \mapsto \lambda \mathrm{Id}$. Then, we obtain a representation

$$
G \rightarrow\left(\mathcal{L}\left(W_{2}, W_{1}\right) \times \mathcal{L}\left(W_{2}, W_{2}\right)\right) \times_{\mathcal{L}\left(W_{2}, W_{2}\right)} \mathbb{C}
$$

defined by:

$$
g \mapsto\left((p, \lambda) \mapsto\left(\rho_{1}(g) \circ p \circ \rho_{2}(g)^{-1}+\lambda v(g) \circ \rho_{2}(g)^{-1}, \lambda\right)\right)
$$

$$
\text { by identifying } q=\lambda \operatorname{Id} \text {. }
$$

So, we have:

$$
G(M)=\left\{\rho_{v}(g)=\left(\begin{array}{cc}
\rho_{1}(g) & v(g) \\
0 & \rho_{2}(g)
\end{array}\right)\right\}
$$

and

$$
G\left(M^{\prime}\right)=\left\{\left(\begin{array}{cc}
\left(\rho_{1} \otimes \rho_{2}^{\vee}\right)(g) & V(g) \\
0 & 1
\end{array}\right)\right\}
$$

where

$$
\left.\left(\rho_{1} \otimes \rho_{2}^{\vee}\right)(g)\right)(p)=\rho_{1}(g) \circ p \circ \rho_{2}(g)^{-1}
$$

where $V(g) \in \mathcal{L}\left(W_{2}, W_{1}\right)$ and $V(g)(p)=v(g) \circ p \circ \rho_{2}(g)^{-1}$.

As far as the Stokes groups are concerned, we have:

$$
\begin{aligned}
S(M) & =\left\{\left(\begin{array}{cc}
\operatorname{Id}_{W_{1}} & v(s) \\
0 & \mathrm{Id}_{W_{2}}
\end{array}\right), s \in S\right\}, \\
S\left(M^{\prime}\right) & =\left\{\left(\begin{array}{cc}
\operatorname{Id}_{\mathcal{L}\left(W_{2}, W_{1}\right)} & V(s) \\
0 & 1
\end{array}\right), s \in S\right\}
\end{aligned}
$$

and $V(s)$ is identified with $v(s)$ through the identification of $\mathcal{L}\left(W_{2}, W_{1}\right)$ with $W_{1} \otimes W_{2}^{\vee}$. We obtain the following proposition:

Proposition 4.16. - The isomorphism of $\mathbb{C}$-vector spaces which identifies $M_{r_{1}, r_{2}}(\mathbb{C})$ and $M_{r_{1} r_{2}, 1}(\mathbb{C})$ induces the isomorphism:

$$
S(M) \cong S\left(M^{\prime}\right)
$$

### 4.3.2. The functor $\mathrm{it}_{r}$

There are many processes to make the slopes of a $q$-difference module integral, we could use ramification as in [7]. To compute the Stokes operators in Section 3, we did not use ramification. An iteration process appears in the calculations and we will see that is a way to have integral slopes.

Let $r \in \mathbb{N}^{*}$, we work on the category $\mathcal{E}_{r}(K, q)$. We define the functor iteration of order $r$, denoted by it ${ }_{r}$. It is a functor from the category $\mathcal{E}_{r}(K, q)$ to the category $\mathcal{E}_{1}\left(K, q^{r}\right)$ :

$$
\begin{aligned}
\mathrm{it}_{r}: \quad \mathcal{E}_{r}(K, q) & \rightarrow \mathcal{E}_{1}\left(K, q^{r}\right) \\
M=\left(K^{n}, \Phi_{A}\right) & \rightsquigarrow \mathrm{it}_{r}(M)=\left(K^{n}, \Phi_{A}^{r}\right) \\
F: M \rightarrow N & \rightsquigarrow F: \mathrm{it}_{r}(M) \rightarrow \mathrm{it}_{r}(N) .
\end{aligned}
$$

Remark 4.17. - In fact, $\Phi_{A}^{r}=\Phi_{\sigma_{q}^{r-1}(A) \ldots \sigma_{q}(A) A}$ and the morphisms are invariant by it ${ }_{r}$ because:

$$
\Phi_{B} \circ F=F \circ \Phi_{A} \Rightarrow \Phi_{B}^{r} \circ F=F \circ \Phi_{A}^{r} .
$$

Lemma 4.18. - The functor $\mathrm{it}_{r}$ makes the slopes of modules in $\mathcal{E}_{r}(K, q)$ integral.

Proof. - The functor $\mathrm{it}_{r}$ multiplies the slopes by $r$.
Proposition 4.19. - The functor it $_{r}$ is exact, faithful and tensor compatible.

We notice that $\left.\hat{\omega}_{z_{0}}\right|_{\mathcal{E}_{r}(K, q)}=\left.\hat{\omega}_{z_{0}}\right|_{\mathcal{E}_{1}\left(K, q^{r}\right)} \circ$ it $_{r}$, by tannakian duality, we obtain the following commutative diagram:


Remark 4.20. - The morphism $\mathrm{it}_{r}^{*}$ is not a closed immersion, for example, the module $\left(K, \Phi_{z}\right)$ of $\mathcal{E}_{r}(K, q)$ cannot be a $\operatorname{it}_{r}\left(K, \Phi_{a}\right)$ : otherwise $z=\sigma_{q}^{r-1}(a) \ldots \sigma_{q}(a) a$ but it is not possible in $K$.

Nevertheless, $\mathrm{it}_{r}^{*}\left(S_{1}\left(K, q^{r}\right)\right)$ is a subgroup of $S_{r}(K, q)$. As a consequence, if we find a morphism $F: \operatorname{gr}\left(A_{U}\right) \rightarrow \operatorname{gr}\left(A_{U}\right)$ such that $F\left(z_{0}\right) \in$ $S_{1}\left(K, q^{r}\right)\left(\mathrm{it}_{r}\left(A_{U}\right)\right)$ then $F\left(z_{0}\right) \in S_{r}(K, q)\left(A_{U}\right)$. We will see in the next paragraph, that this argument enables us to show that our Stokes operators are galoisian.

### 4.3.3. Stokes operators for two slopes

According to [17],the Stokes operators for a module $M=\left(K^{n}, \Phi_{A_{U}}\right)$ with integral slopes are for all $\bar{c}, \bar{d} \notin \Sigma\left(A_{0}\right)$ the meromorphic morphisms over $\mathbb{C}^{*}, S_{\bar{c}, \bar{d}} \hat{F}\left(A_{U}\right)$ and their poles are the $q$-spirals $[-c ; q]$ and $[-d ; q]$. We fix $c_{0} \notin \Sigma\left(A_{0}\right) \cup\left\{\overline{\bar{z}}_{0}\right\}$ and we put as $\sigma_{q^{r}}$-modules:

$$
\forall \bar{c} \in E_{q}, \quad \dot{\Delta}_{\bar{c}}\left(A_{U}\right):=\operatorname{Res}_{\bar{d}=\bar{c}} \log S_{\bar{c}_{0}, \bar{d}} \hat{F}\left(A_{U}\right)\left(z_{0}\right)
$$

The $\dot{\Delta}_{\bar{c}}$ are called the $q$-alien derivations (see the introduction of [9] for the explanation of the analogy). According to [9], the $q$-alien derivation are "Lie-like" morphisms of the Lie algebra $\mathfrak{s}_{1}$ of $S_{1}$.

When the slopes are not integral, we introduced similar notations for Stokes operators in the case of two slopes: $\tilde{S}_{\overline{\bar{c}}, \overline{\bar{d}}} F\left(A_{U}\right)$ is the Stokes operator, it is a meromorphic automorphism over $\mathbb{C}^{*}$ of $A_{0}$, its poles are, for $i=$ $0, \ldots, r$, the $q^{r}$-spirals $\left[-c q^{-i+1} ; q^{r}\right]$ and $\left[-d q^{-i+1} ; q^{r}\right]$. And $\tilde{\Delta}_{\bar{c}}\left(A_{U}\right):=$ $\operatorname{Res}_{\overline{\bar{d}}=\overline{\bar{c}}} \log \tilde{S}_{\bar{c}_{0}, \bar{d}} \hat{F}\left(A_{U}\right)\left(z_{0}\right)$ is the residue in $\overline{\bar{c}} \in \Sigma\left(A_{0}\right)$.

One non integral slope and one null slope. - Let $M=\left(K^{r+1}, \Phi_{A_{U}}\right)$ be a $q$-difference module whose graded module is $E\left(r,-d, b^{r}\right) \oplus \underline{1}$, the matrix $A_{U}$ has the following form:

$$
A_{U}=\left(\begin{array}{cc}
B & U \\
0 & 1
\end{array}\right), \quad B:=\left(\begin{array}{cccc}
0 & 1 & & 0 \\
\vdots & & \ddots & \\
0 & & & 1 \\
b^{\prime} z^{-d} & 0 & \ldots & 0
\end{array}\right)
$$

where $b^{\prime}=q^{\frac{-d(r-1)}{2}} b^{r} \in \mathbb{C}^{*}$.
Let $h_{l}=\left(1, \gamma_{l}, 0\right), l \in \mathbb{Z}$, be elements of the formal Galois group $G_{p, r}$, $\gamma_{l} \in E_{q}^{\vee}$. We suppose $\gamma_{0}=1$, the trivial morphism. Moreover, we have $\mathbb{C}^{*}=U \times q^{\mathbb{R}}$ ( $U$ is the set of complex numbers of module 1 ), we define $\gamma_{1} \in E_{q}^{\vee}$ such that $\gamma_{1}$ is trivial over $U$ and for all $x \in \mathbb{R}, \gamma_{1}\left(q^{x}\right)=e^{2 i \pi x}$. In particular, $\gamma_{1}\left(\xi_{r}\right)=1$ and $\gamma_{1}\left(q_{r}\right)=\xi_{r}$.

Finally, we define for $l \geqslant 2, \gamma_{l}=\left(\gamma_{1}\right)^{l}$, that is for all $c \in E_{q}, \gamma_{l}(c):=$ $\left(\gamma_{1}(c)\right)^{l}$. We notice that for all $l \in \mathbb{Z}, \gamma_{l}\left(q_{r}\right)=\xi_{r}^{l}$ and for all $l, l^{\prime} \in \mathbb{Z}$, $\gamma_{l} \gamma_{l^{\prime}}=\gamma_{l+l^{\prime}}$.

For all $\overline{\bar{c}} \in E_{q^{r}} \backslash \Sigma\left(A_{0}\right)$, we find a meromorphic isomorphism on $\mathbb{C}^{*}$ from $M_{0}$ to $M$ denoted by:

$$
\tilde{S}_{\bar{c}} \hat{F}\left(A_{U}\right)=\left(\begin{array}{cc}
I_{r} & \tilde{F}_{\bar{c}}\left(A_{U}\right) \\
0 & 1
\end{array}\right)
$$

The map $c \in \mathbb{C}^{*} \mapsto \tilde{F}_{\overline{\bar{c}}_{0}, \bar{c}}\left(A_{U}\right)\left(z_{0}\right)$ is meromorphic on $\mathbb{C}^{*}$ and the poles are $\Sigma\left(A_{0}\right)$. Thus the residues $\tilde{\Delta}_{\overline{\bar{c}}}\left(A_{U}\right)=\operatorname{Res}{ }_{\overline{\bar{d}}=\overline{\bar{c}}} \log \tilde{S}_{\overline{\bar{d}}} \hat{F}\left(A_{U}\right)$ are such that:

$$
\tilde{\Delta}_{\overline{\bar{c}}}\left(A_{U}\right)=\left(\begin{array}{cc}
0 & \operatorname{Res}_{\overline{\bar{d}}=\overline{\bar{c}}} \tilde{F}_{\overline{\bar{d}}}\left(A_{U}\right) \\
0 & 0
\end{array}\right) .
$$

And for the $q^{r}$-difference module with integral slopes and matrix it ${ }_{r}\left(A_{U}\right)$, we have, for all $\overline{\bar{c}} \in E_{q^{r}} \backslash \Sigma\left(\mathrm{it}_{r}\left(A_{0}\right)\right)$,

$$
S_{\bar{c}} \hat{F}\left(\mathrm{it}_{r}\left(A_{U}\right)\right)=\left(\begin{array}{cc}
I_{r} & F_{\overline{\bar{c}}}\left(\mathrm{it}_{r}\left(A_{U}\right)\right) \\
0 & 1
\end{array}\right)
$$

and for all $\overline{\bar{c}} \in \Sigma\left(\mathrm{it}_{r}\left(A_{0}\right)\right)$,

$$
\dot{\Delta}_{\overline{\bar{c}}}\left(\mathrm{it}_{r}\left(A_{U}\right)\right)=\left(\begin{array}{cc}
0 & \operatorname{Res}_{\overline{\bar{d}}=\overline{\bar{c}}} F_{\overline{\bar{d}}}\left(\mathrm{it}_{r}\left(A_{U}\right)\right) \\
0 & 0
\end{array}\right) .
$$

Proposition 4.21. - For all $\overline{\bar{c}} \in E_{q^{r}} \backslash \Sigma\left(\mathrm{it}_{r}\left(A_{0}\right)\right)$,

$$
\tilde{F}_{\overline{\bar{c}}}\left(A_{U}\right)=\sum_{j=0}^{r-1} \sum_{l=0}^{r-1} \frac{1}{r} \frac{\gamma_{l}\left(q_{r}^{d j}\right)}{\gamma_{l}(b)} h_{l}(B) F_{\overline{\overline{c_{j}}}}\left(\mathrm{it}_{r}\left(A_{U}\right)\right),
$$

where $c_{j}:=c q^{-j}$.

Proof. - We remember that $\tilde{F}_{\overline{\bar{c}}}\left(A_{U}\right)={ }^{t}\left(f_{1}, \ldots, f_{r}\right)$ satisfies the following system (cf. system (2.8)):

$$
\left\{\begin{aligned}
f_{2} & =\sigma_{q}\left(f_{1}\right)-u_{1} \\
f_{3} & =\sigma_{q}^{2}\left(f_{1}\right)-\left(\sigma_{q}\left(u_{1}\right)+u_{2}\right) \\
& \vdots \\
f_{r} & =\sigma_{q}^{r-1}\left(f_{1}\right)-\left(\sigma_{q}^{r-2}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{r-2}\right)+u_{r-1}\right) \\
\sigma_{q}^{r}\left(f_{1}\right) & =b^{\prime} z^{-d} f_{1}+\sigma_{q}^{r-1}\left(u_{1}\right)+\cdots+\sigma_{q}\left(u_{r-1}\right)+u_{r}
\end{aligned}\right.
$$

and $f_{1}=\frac{g}{\theta_{q^{r}, c}^{d}}$ with $g$ holomorphic on $\mathbb{C}^{*}$.
We have

$$
\mathrm{it}_{r}(B)=z^{-d}\left(\begin{array}{cccc}
b^{\prime} & 0 & \cdots & 0 \\
0 & b^{\prime} q^{-d} & \ddots & \vdots \\
\vdots & \ddots & \ddots & 0 \\
0 & \cdots & 0 & b^{\prime} q^{-(r-1) d}
\end{array}\right)
$$

and
$\mathrm{it}_{r}\left(A_{U}\right)=\left(\begin{array}{cc}\mathrm{it}_{r}(B) & V \\ 0 & 1\end{array}\right), \quad V=\sum_{k=0}^{r-2} \sigma_{q}^{r-1}(B) \ldots \sigma_{q}^{k+1}(B) \sigma_{q}^{k}(U)+\sigma_{q}^{r-1}(U)$.
We have $\Sigma\left(\operatorname{it}_{r}\left(A_{U}\right)\right)=\left\{c \in \mathbb{C}^{*} \mid \exists i=0, \ldots, r-1, c^{d}=b^{\prime} q^{-\mathrm{id}}\right\} \bmod q^{r}$. Moreover, we easily verify that

$$
\sigma_{q}(F)-B F=U \Rightarrow \sigma_{q}^{r}(F)-\mathrm{it}_{r}(B) F=V
$$

Let us write, $F_{\overline{\bar{c}}}\left(\mathrm{it}_{r}\left(A_{U}\right)\right)={ }^{t}\left(f_{1, \overline{\bar{c}}}, f_{2, \overline{\bar{c}}}, \ldots, f_{r, \overline{\bar{c}}}\right)$, by the uniqueness of the $f_{i, \overline{\bar{c}}}$, we notice that:

$$
f_{1}=f_{1, \bar{c}}, f_{2}=f_{2, \overline{\bar{c}}}, \ldots, f_{r}=f_{r, \overline{\bar{c}}} \overline{r_{r-1}}
$$

Thus,
$\tilde{F}_{\overline{\bar{c}}}\left(A_{U}\right)=E_{1,1} F_{\overline{\bar{c}}}\left(\mathrm{it}_{r}\left(A_{U}\right)\right)+E_{2,2} F_{\overline{\overline{c_{1}}}}\left(\mathrm{it}_{r}\left(A_{U}\right)\right)+\cdots+E_{r, r} F_{\overline{\overline{c_{r-1}}}}\left(\mathrm{it}_{r}\left(A_{U}\right)\right)$, where $E_{i, j}$ is the elementary matrix with zeroes everywhere except at the place $(i, j)$.

According to Lemma 4.5:

$$
\sum_{l=0}^{r-1} \frac{1}{r} \gamma_{l}\left(q_{r}^{d j}\right)\left(\begin{array}{cccc}
1 & 0 & \cdots & 0 \\
0 & \gamma_{l}\left(q_{r}\right)^{-d} & \ddots & \vdots \\
\vdots & \ddots & \ddots & 0 \\
0 & \cdots & 0 & \gamma_{l}\left(q_{r}\right)^{-(r-1) d}
\end{array}\right)=E_{j+1, j+1}
$$

As

$$
h_{l}(B)=\gamma_{l}(b)\left(\begin{array}{cccc}
1 & 0 & \cdots & 0 \\
0 & \gamma_{l}\left(q_{r}\right)^{-d} & \ddots & \vdots \\
\vdots & \ddots & \ddots & 0 \\
0 & \ldots & 0 & \gamma_{l}\left(q_{r}\right)^{-(r-1) d}
\end{array}\right)
$$

we obtain the formula.
Lemma 4.22. - The only vector spaces which are stable under $G_{p}\left(E\left(r,-d, b^{r}\right)\right)$ are $\{0\}$ and $\mathbb{C}^{r}$.

Proof. - Let us suppose that $X={ }^{t}\left(x_{1}, x_{2}, \ldots, x_{r}\right) \in \mathfrak{s}(M) \subset \mathbb{C}^{r}$ then for all $l \in\{0, \ldots, r-1\}$,

$$
\left(\begin{array}{cccc}
1 & & & \\
& \xi_{r}^{l} & & \\
& & \ddots & \\
& & & \xi_{r}^{l(r-1)}
\end{array}\right)\left(\begin{array}{c}
x_{1} \\
x_{2} \\
\vdots \\
x_{r}
\end{array}\right)=\left(\begin{array}{c}
x_{1} \\
\xi_{r}^{l} x_{2} \\
\vdots \\
\xi_{r}^{(r-1) l} x_{r}
\end{array}\right) \in \mathfrak{s}(M)
$$

because $r$ and $d$ are coprime ( $\xi_{r}^{d}$ is a primitive $r$ th root of the unity).
According to Lemma 4.5, for all $j \in\{0, \ldots, r-1\}$ we have:

$$
\sum_{j=0}^{r-1} \xi_{r}^{r-j l}\left(\begin{array}{c}
x_{1} \\
\xi_{r}^{l} x_{2} \\
\vdots \\
\xi_{r}^{(r-1) l} x_{r}
\end{array}\right)=\left(\begin{array}{c}
0 \\
\vdots \\
0 \\
r x_{j+1} \\
0 \\
\vdots \\
0
\end{array}\right) \in \mathfrak{s}(M)
$$

And thanks to the permutation matrices

$$
\left(\begin{array}{cccc}
0 & \alpha_{0}^{-1} & & \\
\vdots & & \ddots & \\
0 & & & \alpha_{r-2}^{-1} \\
\alpha_{0} \ldots \alpha_{r-2} & & & 0
\end{array}\right)^{k}
$$

for all $k \in\{1, \ldots, r\}$, we have $x_{j} E_{k} \in \mathfrak{s}(M)$ where $E_{k}$ is the elementary vector whose coordinates are equal to zero except the $k$ th which is 1 .

As a conclusion, if there exists $X \neq 0$ in $\mathfrak{s}(M)$ then $\mathfrak{s}(M)=\mathbb{C}^{r}$.
We can extend the previous lemma to the case of an arbitrary indecomposable module.

Lemma 4.23. - The vector spaces which are stable by $G_{p}\left(E\left(r,-d, b^{r}\right) \otimes\right.$ $\left.U_{m}\right)$ are $\{0\}$ and $\mathbb{C}^{r m}$.

Proof. - An element of $G_{p}\left(E\left(r,-d, b^{r}\right) \otimes U_{m}\right)$ is a matrix $C \otimes W_{m}^{\lambda}$ where $C$ is in $G_{p}\left(E\left(r,-d, b^{r}\right)\right)$ and $\lambda \in \mathbb{C}$. Let $V$ be a vector space stable by $G_{p}\left(E\left(r,-d, b^{r}\right) \otimes U_{m}\right)$ and $X \in V$ such that

$$
X=\left(\begin{array}{c}
X_{1} \\
\vdots \\
X_{m}
\end{array}\right) \in \mathbb{C}^{r m}, X_{i} \in \mathbb{C}^{r} .
$$

Let us take $\lambda=0$. Then,

$$
C \otimes I_{m} X=\left(\begin{array}{c}
C X_{1} \\
\vdots \\
C X_{m}
\end{array}\right) \in V .
$$

As in the previous proof, we show that for $j=1, \ldots, r$,

$$
\left(\begin{array}{c}
E_{j, j} X_{1} \\
\vdots \\
E_{j, j} X_{m}
\end{array}\right) \in V
$$

Let us take $\lambda=1$, then,

$$
\left(\begin{array}{c}
E_{j, j} X_{1}+E_{j, j} X_{2} \\
\vdots \\
E_{j, j} X_{m}
\end{array}\right) \in V
$$

We prove the following by induction: for all $k=1, \ldots, m$,

$$
\left(\begin{array}{c}
E_{j, j} X_{k} \\
\vdots \\
E_{j, j} X_{m} \\
0 \\
\vdots \\
0
\end{array}\right) \in V
$$

Consequently, for all $j$, for all $x \in \mathbb{C}$

$$
\left(\begin{array}{c}
E_{j} x \\
0 \\
\vdots \\
\vdots \\
0
\end{array}\right) \in V \text { and }\left(\begin{array}{c}
\vdots \\
0 \\
E_{j} x \\
0 \\
\vdots
\end{array}\right) \in V
$$

By the permutation matrices, $X=0$ is the unique vector of $V$ or $V=$ $\mathbb{C}^{r m}$.

Proposition 4.24. - For all $\overline{\bar{c}} \in E_{q^{r}} \backslash\left(\Sigma\left(\mathrm{it}_{r}\left(A_{0}\right)\right) \cup\left\{\overline{\bar{z}}_{0}\right\}\right)$,

$$
\tilde{\Delta}_{\overline{\bar{c}}}\left(A_{U}\right)=\sum_{j=0}^{r-1} \sum_{l=0}^{r-1} \frac{1}{r} \frac{\gamma_{l}\left(q_{r}^{d j}\right)}{\gamma_{l}(b)} h_{l}\left(A_{0}\right) \cdot \dot{\Delta}_{\overline{c q^{-j}}}\left(\mathrm{it}_{r}\left(A_{U}\right)\right) \in \mathfrak{s}(M) .
$$

Proof. - It is a consequence of the Proposition 4.21 with $z=z_{0}$ and taking the residue in $\overline{\bar{c}}$, and because $S_{\overline{\bar{c}}, \overline{\bar{d}}} \hat{F}\left(\mathrm{it}_{r}\left(A_{U}\right)\right) \in S(M)$.

Remark 4.25. - This formula remains the same if we replace $A_{U}$ by the matrix in standard form $\left(\begin{array}{cc}1 & V \\ 0 & B^{\vee}\end{array}\right), V=-U B^{\vee}$, of the dual of $M$.

Any object of the tannakian category generated by the $q$-difference module $M$, denoted by $\langle M\rangle$, belongs in particular to the category $\mathcal{E}_{r}(K)$, so the functor $\mathrm{it}_{r}$ makes the slopes integral. Thus, we can define for any object $N=\left(K^{n}, \Phi_{A}\right)$ of $\langle M\rangle$, an element of the Lie algebra $\mathfrak{s}(N)$ :

$$
\begin{aligned}
\forall \overline{\bar{c}} \in E_{q^{r}} \backslash & \left(\Sigma\left(\mathrm{it}_{r}(\operatorname{gr} A)\right) \cup\left\{\overline{\bar{z}}_{0}\right\}\right), \\
& \tilde{\Delta}_{\bar{c}}(A):=\sum_{j=0}^{r-1} \sum_{l=0}^{r-1} \frac{1}{r} \frac{\gamma_{l}\left(q_{r}^{d j}\right)}{\gamma_{l}(b)} h_{l}(\operatorname{gr} A) \cdot \dot{\Delta} \overline{\overline{c q^{-j}}}\left(\mathrm{it}_{r}(A)\right) \in \mathfrak{s}(N) .
\end{aligned}
$$

Proposition 4.26. - The operators $\tilde{\Delta}_{\bar{c}}$ are "Lie-like" morphisms, in the Lie algebra $\mathfrak{s}_{M}$. Moreover,

$$
\tilde{\Delta}_{\bar{c}}(\cdot):=\sum_{j=0}^{r-1} \sum_{l=0}^{r-1} \frac{1}{r} \frac{\gamma_{l}\left(q_{r}^{d j}\right)}{\gamma_{l}(b)} h_{l} \cdot \dot{\Delta} \overline{\overline{c q^{-j}}}\left(\mathrm{it}_{r}(\cdot)\right)
$$

and we have the inversion formula:

$$
\dot{\Delta}_{\bar{c}}\left(\mathrm{it}_{r}(\cdot)\right)=\sum_{j=0}^{r-1} \sum_{l=0}^{r-1} \frac{1}{r} \frac{\gamma_{l}\left(q_{r}^{d j}\right)}{\gamma_{l}(b)} h_{l} \cdot \tilde{\Delta} \overline{\overline{q^{j}}}(\cdot)
$$

Remark 4.27. - I have no conceptual explanation for the complicated calculations that follow, nor for the apparent "self-duality" in the above formulas.

Proof. - The operators $\dot{\Delta}_{\overline{c q^{-j}}}\left(\mathrm{it}_{r}(\cdot)\right)$ are "Lie-like" morphisms, in the Lie algebra $\mathfrak{s}_{M}$, that is to say

$$
\dot{\Delta} \overline{\overline{c q^{-j}}}\left(\mathrm{it}_{r}(A \otimes B)\right)=\dot{\dot{\Delta}_{\overline{c q^{-j}}}}\left(\mathrm{it}_{r}(A)\right) \otimes 1+1 \otimes \dot{\dot{\Delta}_{\overline{c q^{-j}}}}\left(\mathrm{it}_{r}(B)\right) .
$$

The formula linking $\tilde{\Delta}_{\overline{\bar{c}}}(\cdot)$ and $\dot{\Delta}_{\overline{\overline{q q^{-j}}}}\left(\mathrm{it}_{r}(\cdot)\right)$ is linear so the morphisms $\tilde{\Delta}_{\overline{\bar{c}}}(\cdot)$ are "Lie-like" morphisms in the Lie algebra $\mathfrak{s}_{M}$.

Let us prove the inversion formula:

$$
\begin{aligned}
& \sum_{j^{\prime}=0}^{r-1} \sum_{l^{\prime}=0}^{r-1} \frac{1}{r} \frac{\gamma_{l^{\prime}}\left(q_{r}^{d j^{\prime}}\right)}{\gamma_{l^{\prime}}(b)} h_{l^{\prime}} \cdot \tilde{\Delta} \overline{c q^{j^{\prime}}}(\cdot) \\
& =\sum_{j^{\prime} 0}^{r-1} \sum_{l^{\prime}=0}^{r-1} \frac{1}{r} \frac{\gamma_{l^{\prime}}\left(q_{r}^{d j^{\prime}}\right)}{\gamma_{l^{\prime}}(b)} h_{l^{\prime}} . \sum_{j=0}^{r-1} \sum_{l=0}^{r-1} \frac{1}{r} \frac{\gamma_{l}\left(q_{r}^{d j}\right)}{\gamma_{l}(b)} h_{l} \cdot \dot{\Delta} \underset{c q^{j^{\prime}-j}}{ }\left(\mathrm{it}_{r}(\cdot)\right) \\
& =\sum_{j=0}^{r-1} \sum_{j^{\prime}=0}^{r-1} \frac{1}{r^{2}} \sum_{l=0}^{r-1} \sum_{l^{\prime}=0}^{r-1} \frac{\gamma_{l}\left(q_{r}^{d j}\right) \gamma_{l^{\prime}}\left(q_{r}^{d j^{\prime}}\right)}{\gamma_{l+l^{\prime}}(b)} h_{l} h_{l^{\prime}} \cdot \dot{\overline{\Delta q^{j^{\prime}-j}}}\left(\mathrm{it}_{r}(\cdot)\right) \\
& =\sum_{j=0}^{r-1} \sum_{j^{\prime}=0}^{r-1} \frac{1}{r^{2}}\left(\sum_{k=0}^{r-1} \sum_{l=0}^{k} \frac{\gamma_{l}\left(q_{r}^{d j}\right) \gamma_{k-l}\left(q_{r}^{d j^{\prime}}\right)}{\gamma_{k}(b)} h_{k}\right. \\
& \left.+\sum_{k=r}^{2 r-2} \sum_{l=k-r+1}^{r-1} \frac{\gamma_{l}\left(q_{r}^{d j}\right) \gamma_{k-l}\left(q_{r}^{d j^{\prime}}\right)}{\gamma_{k}(b)} h_{k}\right) \cdot \dot{\Delta} \overline{c q^{j^{\prime}-j}}\left(\mathrm{it}_{r}(\cdot)\right) \\
& =\sum_{j=0}^{r-1} \sum_{j^{\prime}=0}^{r-1} \frac{1}{r^{2}}\left(\sum_{k=0}^{r-1} \sum_{l=0}^{k} \frac{\gamma_{l}\left(q_{r}^{d j}\right) \gamma_{k-l}\left(q_{r}^{d j^{\prime}}\right)}{\gamma_{k}(b)} h_{k}\right. \\
& \left.+\sum_{k=0}^{r-1} \sum_{l=k+1}^{r-1} \frac{\gamma_{l}\left(q_{r}^{d j}\right) \gamma_{k-l}\left(q_{r}^{d j^{\prime}}\right)}{\gamma_{k}(b)} h_{k}\right) \cdot \dot{\overline{c q j^{j^{\prime}-j}}}\left(\mathrm{it}_{r}(\cdot)\right) \\
& \text { because } h_{k}\left(A_{0}\right)=h_{k-r}\left(A_{0}\right) \\
& =\sum_{j=0}^{r-1} \sum_{j^{\prime}=0}^{r-1} \frac{1}{r^{2}}\left(\sum_{k=0}^{r-1} \sum_{l=0}^{r-1} \frac{\gamma_{l}\left(q_{r}^{d j}\right) \gamma_{k-l}\left(q_{r}^{d j^{\prime}}\right)}{\gamma_{k}(b)} h_{k}\right) \cdot \dot{\overline{c q^{j^{\prime}-j}}} \overline{\left.\mathrm{it}_{r}(\cdot)\right)} \\
& =\sum_{j=0}^{r-1} \sum_{j^{\prime}=0}^{r-1} \frac{1}{r^{2}}\left(\sum_{k=0}^{r-1} \frac{\gamma_{k}\left(q_{r}^{d j^{\prime}}\right)}{\gamma_{k}(b)} \sum_{l=0}^{r-1} \gamma_{l}\left(q_{r}^{d\left(j-j^{\prime}\right)}\right) h_{k}\right) \cdot \dot{\overline{c q^{j^{\prime}-j}}}\left(\mathrm{it}_{r}(\cdot)\right)
\end{aligned}
$$

$$
\begin{aligned}
= & \sum_{j=0}^{r-1} \frac{1}{r}\left(\sum_{k=0}^{r-1} \frac{\gamma_{k}\left(q_{r}^{d j}\right)}{\gamma_{k}(b)} h_{k}\right) \dot{\Delta}_{\overline{\bar{c}}}\left(\mathrm{it}_{r}(\cdot)\right) \\
& \quad \text { because } \sum_{l=0}^{r-1} \gamma_{l}\left(q_{r}^{d\left(j-j^{\prime}\right)}\right)=0 \\
\quad & \quad \text { even if } j=j^{\prime} \text { according to Lemma 4.5 } \\
= & \sum_{k=0}^{r-1} \frac{1}{r} \frac{1}{\gamma_{k}(b)}\left(\sum_{j=0}^{r-1} \gamma_{k}\left(q_{r}^{d j}\right)\right) h_{k} \cdot \dot{\Delta}_{\overline{\bar{c}}}\left(\mathrm{it}_{r}(\cdot)\right) \\
= & \dot{\Delta}_{\overline{\bar{c}}}\left(\mathrm{it}_{r}(\cdot)\right) \quad \text { because } \sum_{j=0}^{r-1} \gamma_{k}\left(q_{r}^{d j}\right)=0 \text { except for } k=0
\end{aligned}
$$

In the previous section, we computed the Stokes operators for a module with two non integral slopes, of the form $M=\left(K^{r_{1}+r_{2}}, \Phi_{A_{U}}\right)$, where:

$$
A_{U}=\left(\begin{array}{cc}
B_{1} & U \\
0 & B_{2}
\end{array}\right)
$$

and for $i=1,2, B_{i}$ is the matrix associated with the irreducible module $E\left(r_{i}, d_{i}, b_{i}^{r}\right)$ of rank $r_{i}$ and slope $\frac{d_{i}}{r_{i}}$ such that $\frac{d_{1}}{r_{1}}<\frac{d_{2}}{r_{2}}$. We notice that it was equivalent to compute those of the module $M^{\prime}=\left(K^{r_{1} r_{2}+1}, \Phi_{A_{U^{\prime}}^{\prime}}\right)$ where:

$$
A_{U^{\prime}}^{\prime}=\left(\begin{array}{cc}
B_{1} \widehat{\otimes} B_{2}^{\vee} & U^{\prime} \\
0 & 1
\end{array}\right) \quad U^{\prime}=\widehat{U B_{2}^{-1}}
$$

We saw in Proposition 4.16 that $S(M)$ and $S\left(M^{\prime}\right)$ can be identified, consequently, we just have to prove the Stokes operators associated with $M^{\prime}$ are galoisian.

We can generalize the previous results to the module $M^{\prime}$ whose graded module is $E\left(r_{1}, d_{1}, b_{1}^{r_{1}}\right) \otimes E\left(r_{2},-d_{2}, b_{2}^{-r_{2}}\right) \oplus \underline{1}$. According to Proposition 1.14, formula are nearly the same. We obtain the following corollary:

Corollary 4.28. - The Stokes operators of the Galois group of a module with two non integral slopes are galoisian.

The residues $\tilde{\Delta}_{\bar{c}}\left(A_{U}\right)$ are in the Lie algebra $\mathfrak{s}(M)$. It will give us generators of the Stokes group associated with the module $M$.

### 4.4. Density theorem

In the case of integral slopes, Ramis and Sauloy proved the following theorem:

Theorem 4.29 ([10, Theorem 3.5]). - The formal Galois group $G_{p, 1}$ and the Stokes subgroup associated with $q$-alien derivations $\dot{\Delta}$ generate a Zariski dense subgroup of the Galois group of $q$-difference modules with integral slopes $G_{1}$.

Here, we generalize this theorem to the Galois group $G_{p}$ taking inspiration from the results of the previous paragraph, where the analogue of the $q$-alien derivations seems to be the $\dot{\Delta}_{\bar{c}} \circ \mathrm{it}_{r}$.

Theorem 4.30. - Let $r \in \mathbb{N}^{*}$. The subgroup of $S_{r}(K, q)$ associated with the residues $\dot{\Delta}_{\overline{\bar{c}}} \circ \mathrm{it}_{r}$ and the formal Galois group $G_{p, r}(K, q)$ generate a Zariski-dense subgroup of $G_{r}(K, q)$.

Remark 4.31. - If $r=1$, we recover Theorem 4.29.
Proof. - We use a density theorem of Chevalley, the same as the proof of Theorem 3.5 of [10], it may be formulated by:

Theorem. - Let $H$ be a subgroup of $G_{r}(K, q)$. For $H$ to generate Zariski-dense subgroup of $G_{r}(K, q)$, it is sufficient that for each object $M$ of $\mathcal{E}_{r}(K, q)$ and each line $D$ of $\hat{\omega}_{z_{0}}(M)$ invariant under the action of each element of $H$, then $D$ is invariant under the action of $G_{r}(K, q)$.

We take $H=G_{p, r}(K, q) \times \exp \left(\left\{\dot{\Delta}_{\overline{\bar{c}}} \circ \operatorname{it}_{r} \mid c \in \mathbb{C}^{*}\right\}\right)$. Let $\left(K^{n}, \Phi_{A_{U}}\right)$ be an object of $\mathcal{E}_{r}(K, q)$. Thanks to the canonical filtration by the slopes, we may suppose that $A_{U}$ has the following form:

$$
A_{U}=\left(\begin{array}{cccc}
A_{1} & & & \\
& A_{2} & & U_{i, j} \\
0 & & \ddots & \\
& & & A_{s}
\end{array}\right)
$$

the matrices $A_{i}$ correspond to pure isoclinic modules of slopes $k_{i} / r, k_{i} \in \mathbb{Z}$, such that $k_{1}<k_{2}<\cdots<k_{s}$. The matrix of the associated graded module is $A_{0}$.

Let $D$ be a line of $\hat{\omega}_{z_{0}}(M)=\mathbb{C}^{n}$ and $X$ a generator of this line, we write it by blocks:

$$
X=\left(\begin{array}{c}
X_{1} \\
\vdots \\
X_{s}
\end{array}\right)
$$

The line $D$ is supposed to be invariant under the action of $G_{p, r}(K, q)$, which means that for each matrix $B \in G_{p, r}(K, q), B X$ and $X$ are colinear.

To be invariant by $\dot{\Delta}_{\bar{c}} \circ \mathrm{it}_{r}$ means that $\dot{\Delta}_{\overline{\bar{c}}} \circ \mathrm{it}_{r}\left(A_{U}\right) X=0$ because $\dot{\Delta}_{\overline{\bar{c}}} \circ \mathrm{it}_{r}$ is in the Lie algebra of $S(M)$. We have to prove that $D \in \mathfrak{s}_{r}(K, q)$, $D(M) X=0$.

The slopes are distinct, the action of $\mathbb{C}^{*}$ of the formal Galois group implies that only one $X_{i}$ corresponding to a unique slope $\mu_{i}$ is non zero. Indeed,for all $t \in \mathbb{C}^{*}$,

$$
\left(\begin{array}{c}
t^{k_{1}} X_{1} \\
\vdots \\
t^{k_{s}} X_{s}
\end{array}\right)
$$

must be colinear to $X$.
We proved in Lemma 4.23 that the vector spaces stabilized by the formal Galois group of an indecomposable module of rank $n$ and of non integral slope are $\{0\}$ and $\mathbb{C}^{n}$. A module with non inegral slopes is a direct sum of indecomposable modules, the same proof shows that if $\mu_{i}$ is non integral then $X_{i}=0$. In this case, we are done.

On the other hand, if $\mu_{i}$ is integral, then $A_{i}=z^{\mu_{i}} A_{i}^{\prime}$, Ramis and Sauloy proved in [10, Lemma 2.2] that $X_{i}$ is an eigenvector of $A_{i}^{\prime}$. Then, there exists $\lambda$ an eigenvalue of $A_{i}^{\prime}$ such that $A_{0} X=\lambda z^{\mu_{i}} X$.

We may suppose that $i=s$ because if we denote by $M^{\prime}$ the submodule of $M$ whose slopes are smaller than $k_{i} / r$ and of rank $n^{\prime}=n_{1}+\cdots+$ $n_{i}$, the inclusion given by the matrix Inc $=\binom{I_{n^{\prime}}}{0}$ is a morphism of $q$ difference module. By functoriality, the vector $X^{\prime}=\operatorname{Inc} X$ and the matrix $A^{\prime}$ corresponding to $M^{\prime}$ verify the same hypothesis as $X$ and $A_{U}$.

Then, we have an analytic morphism:

$$
\lambda z^{\mu_{s}} \xrightarrow{X} A_{0} .
$$

Moreover, there exists a unique formal morphism tangent to identity $\hat{F}$ : $A_{0} \rightarrow A_{U}$ (that is to say in $\mathfrak{S}_{n_{1}, \ldots, n_{s}}(\hat{K})$ ), hence a formal morphism $G=$ $\hat{F} X: \lambda z^{\mu_{s}} \rightarrow A_{U}$. If we prove that this morphism is analytic then we will have the following commutative diagram for all $D \in S$ :

where $G_{0}$ is the graded morphism associated with $G$. But $D\left(\lambda z^{\mu_{s}}\right)=0$ because the module is pure, as a consequence $D\left(A_{U}\right) X=0$.

Now, we just have to prove that $G=\hat{F} X$ is analytic. By hypothesis $\dot{\Delta}_{\bar{c}} \mathrm{oit}_{r}\left(A_{U}\right) X=0$. The functor it ${ }_{r}$ does not change morphisms, by applying
it on $G$ we have:

$$
\mathrm{it}_{r}\left(\lambda z^{\mu_{s}}\right) \xrightarrow{X} \mathrm{it}_{r}\left(A_{0}\right) \xrightarrow{\hat{F}} \mathrm{it}_{r}\left(A_{U}\right)
$$

Now, the slopes are integral and we have the same hypothesis as Lemma 3.6 of [10]. This lemma shows that $G$ is an analytic morphism.

Corollary 4.32. - Let $M=\left(K^{n}, \Phi_{A_{U}}\right)$, with $A_{U}=\left(\begin{array}{cc}B_{1} & U \\ 0 & B_{2}\end{array}\right)$ where for $i=1,2, B_{i}$ is the matrix associated with the irreducible module $E\left(r_{i}, d_{i}, b_{i}^{r}\right)$. The $\tilde{\Delta}_{\bar{c}}$ and their conjugates by the action of the formal Galois group $G_{p, M}$ generate a Zariski-dense Lie subalgebra of $\mathfrak{s}_{M}$.

Proof. - It is a consequence of the previous theorem and Proposition 4.26.

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[^0]:    ${ }^{(1)}$ These authors also use a cohomological description inspired by the theorem of Birkhoff-Malgrange-Sibuya, we shall follow that method in Section 3 for two arbitrary slopes.

