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## Instability of standing waves for the generalized Davey-Stewartson system

by

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ABSTRACT. – In this paper we study the instability of standing wave  $u_\omega(t, x) = e^{i\omega t} \varphi_\omega(x)$  for the following equation:

$$iu_t + \Delta u + a|u|^{p-1}u + E_1(|u|^2)u = 0, \quad t \geq 0, \quad x \in \mathbb{R}^n,$$

where  $a > 0$ ,  $1 < p < 1 + 4/(n-2)$  and  $n = 2$  or  $3$ . We prove that if  $p \geq 1 + 4/n$ , then  $u_\omega$  is unstable for any  $\omega \in (0, \infty)$ . This is an extension of the previous result due to Cipolatti [4], who proved that if  $p \geq 3$ , then  $u_\omega$  is unstable for any  $\omega \in (0, \infty)$ . We show a different criterion of instability from that in [4], which can cover the case of  $1 + 4/3 \leq p < 3$  for  $n = 3$ . Furthermore, we prove that if  $n = 3$  and  $1 < p < 1 + 4/3$ , then there exists  $\omega_0 = \omega_0(a, p) > 0$  such that  $u_\omega$  is unstable for any  $\omega \in (\omega_0, \infty)$ .

RÉSUMÉ. – Dans cet article on étudie l'instabilité de la solution  $u_\omega(t, x) = e^{i\omega t} \varphi_\omega(x)$  pour l'équation suivante :

$$iu_t + \Delta u + a|u|^{p-1}u + E_1(|u|^2)u = 0, \quad t \geq 0, \quad x \in \mathbb{R}^n,$$

où  $a > 0$ ,  $1 < p < 1 + 4/(n-2)$  et  $n = 2$  ou  $3$ . On prouve que si  $p \geq 1 + 4/n$ ,  $u_\omega$  est instable pour tout  $\omega \in (0, \infty)$ . C'est une extension du résultat précédent par Cipolatti [4], qui prouva que si  $p \geq 3$ ,  $u_\omega$  est instable pour tout  $\omega \in (0, \infty)$ . On montre un critère d'instabilité différente de celui de [4], qui peut couvrir le cas de  $1 + 4/3 \leq p < 3$  pour  $n = 3$ . En outre, on prouve que si  $n = 3$  et  $1 < p < 1 + 4/3$ , il existe  $\omega_0 = \omega_0(a, p) > 0$  telle que  $u_\omega$  est instable pour tout  $\omega \in (\omega_0, \infty)$ .

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## 1. INTRODUCTION AND RESULTS

In the present paper we consider the instability of standing waves for the following nonlinear Schrödinger equation:

$$iu_t + \Delta u + a |u|^{p-1} u + E_1(|u|^2) u = 0, \quad t \geq 0, \quad x \in \mathbb{R}^n, \quad (1.1)$$

where  $a > 0$ ,  $1 < p < 1 + 4/(n-2)$ ,  $n = 2$  or  $3$  and  $E_1$  is the singular integral operator with symbol  $\sigma_1(\xi) = \xi_1^2/|\xi|^2$ ,  $\xi \in \mathbb{R}^n$ .

The equation (1.1) has its origin in fluid mechanics where, for  $n = 2$  and  $p = 3$ , it describes the evolution of weakly nonlinear water waves that travel predominantly in one direction. More precisely, (1.1) is the  $n$ -dimensional extension of the generalized Davey-Stewartson system in the elliptic-elliptic case, namely

$$\left. \begin{aligned} iu_t + \lambda u_{xx} + u_{yy} + a |u|^{p-1} u + uv_x &= 0, \\ v_{xx} + \mu v_{yy} &= (|u|^2)_x, \end{aligned} \right\}$$

where  $\lambda, \mu > 0$  (see [5]).

By a standing wave, we mean a solution of (1.1) with the form

$$u(t, x) = e^{i\omega t} \varphi_\omega(x),$$

where  $\omega > 0$  and  $\varphi_\omega$  is a ground state of the following stationary problem:

$$\left. \begin{aligned} -\Delta \psi + \omega \psi - a |\psi|^{p-1} \psi - E_1(|\psi|^2) \psi &= 0, \quad x \in \mathbb{R}^n, \\ \psi \in H^1(\mathbb{R}^n), \quad \psi \neq 0. \end{aligned} \right\} \quad (1.2_\omega)$$

DEFINITION 1. – We define the following notations.

$$S_\omega(v) = \frac{1}{2} |\nabla v|_2^2 + \frac{\omega}{2} |v|_2^2 - \frac{a}{p+1} |v|_{p+1}^{p+1} - \frac{1}{4} \int |v|^2 E_1(|v|^2) dx,$$

$\chi_\omega$  = the set of solutions for (1.2 $_\omega$ )

$$= \{\psi \in H^1(\mathbb{R}^n) : S'_\omega(\psi) = 0, \quad \psi \neq 0\},$$

$\mathcal{G}_\omega$  = the set of ground states for (1.2 $_\omega$ )

$$= \{\varphi \in \chi_\omega : S_\omega(\varphi) \leq S_\omega(\psi) \text{ for all } \psi \in \chi_\omega\},$$

$$(\tau_y v)(x) = v(x-y), \quad v \in H^1(\mathbb{R}^n), \quad x, y \in \mathbb{R}^n.$$

*Remark 1.* – Cipolatti [3] showed that if  $a > 0$ ,  $1 < p < 1 + 4/(n-2)$  and  $n = 2$  or  $3$ , then  $\mathcal{G}_\omega$  is not empty for any  $\omega \in (0, \infty)$ .

DEFINITION 2. – We shall say that the standing wave  $u_\omega(t) = e^{i\omega t} \varphi_\omega$  is *stable* if for any  $\varepsilon > 0$  there exists  $\delta > 0$  with the following property:

If  $u_0 \in H^1(\mathbb{R}^n)$  and the solution  $u(t)$  of (1.1) with  $u(0) = u_0$  satisfies  $\|u_0 - \varphi_\omega\|_{H^1} < \delta$ , then

$$\sup_{0 \leq t < \infty} \inf_{\theta \in \mathbb{R}, y \in \mathbb{R}^n} \|u(t) - e^{i\theta} \tau_y \varphi_\omega\|_{H^1} < \varepsilon.$$

Otherwise,  $u_\omega$  is said to be *unstable*.

*Remark 2.* – The unique local existence of  $H^1$  solution for (1.1) was established by Ghidaglia and Saut [6]: If  $a > 0$ ,  $1 < p < 1 + 4/(n - 2)$  and  $n = 2$  or  $3$ , then for any  $u_0 \in H^1(\mathbb{R}^n)$  there exist  $T > 0$  and a unique solution  $u(\cdot) \in C([0, T]; H^1(\mathbb{R}^n))$  of (1.1) with  $u(0) = u_0$ . Furthermore,  $u(t)$  satisfies:

$$|u(t)|_2 = |u_0|_2, \tag{1.3}$$

$$\mathcal{E}(u(t)) = \mathcal{E}(u_0), \tag{1.4}$$

for all  $t \in [0, T]$ , where  $\mathcal{E}$  is defined on  $H^1(\mathbb{R}^n)$  by

$$\mathcal{E}(v) = \frac{1}{2} |\nabla v|_2^2 - \frac{a}{p+1} |v|_{p+1}^{p+1} - \frac{1}{4} \int |v|^2 E_1(|v|^2) dx.$$

Cipolatti [4] has proved that if  $a > 0$ ,  $3 \leq p < 1 + 4/(n - 2)$  and  $n = 2$  or  $3$ , then the standing wave  $e^{i\omega t} \varphi_\omega$  is unstable for any  $\omega \in (0, \infty)$ . He has applied a sufficient condition for the instability essentially due to Gonçalves Ribeiro [7], and has constructed the unstable flow by using the Pohozaev multiplier  $x \cdot \nabla \varphi_\omega$ . For  $p \geq 3$ , the sufficient condition of instability in [4] is satisfied. On the other hand, under the assumption that the ground state of (1.2 $_\omega$ ) is unique, up to a translation and a phase change, the author [8] showed that if  $a > 0$ ,  $1 < p < 1 + 4/n$  and  $n = 2$  or  $3$ , then there exists a sequence  $(\omega_k)$  such that  $\omega_k > 0$ ,  $\omega_k \rightarrow 0$  and  $e^{i\omega_k t} \varphi_{\omega_k}$  is stable. When  $n = 3$ , the result due to Cipolatti [4] is not optimal, that is, we obtain the following results.

**THEOREM 1.** – *If  $a > 0$ ,  $1 + 4/n \leq p < 1 + 4/(n - 2)$  and  $n = 2$  or  $3$ , then the standing wave  $e^{i\omega t} \varphi_\omega$  is unstable for any  $\omega \in (0, \infty)$ .*

**THEOREM 2.** – *If  $a > 0$ ,  $n = 3$  and  $1 < p < 1 + 4/3$ , then there exists  $\omega_0 = \omega_0(a, p) > 0$  such that  $e^{i\omega t} \varphi_\omega$  is unstable for any  $\omega \in (\omega_0, \infty)$ .*

*Remark 3.* – As stated above, if  $a > 0$ ,  $1 < p < 1 + 4/n$  and  $n = 2$  or  $3$ , then there exist stable standing waves for  $\omega$  close to 0 (see [8]). Thus, it is natural that the exponent  $p = 1 + 4/n$  should appear in Theorems 1 and 2.

*Remark 4.* – The exponent  $p = 1 + 4/n$  is the critical one for the case of the single power nonlinearity:

$$iu_t + \Delta u + |u|^{p-1} u = 0, \quad t \geq 0, \quad x \in \mathbb{R}^n.$$

That is, it is well known that if  $1 < p < 1 + 4/n$ , then all standing waves are stable, and if  $1 + 4/n \leq p < 1 + 4/(n - 2)$ , then all standing waves are unstable (see [1], [2], [10]).

This paper is organized as follows. In Section 2 we first state Theorem 3, which gives a sufficient condition for the instability. Next we prove Theorems 1 and 2 by using Theorem 3. In Section 3 we give the proof of Theorem 3. We should mention that the proof of Theorem 3 is based on the ideas of Shatah and Strauss [9]. In particular, see Section 4 in [9]. In the proof of Theorem 3, we give the unstable direction explicitly by using the scaling  $\varphi_\omega^\lambda(x) = \lambda^{n/2} \varphi_\omega(\lambda x)$ ,  $\lambda > 0$ , which associates with the pseudo-conformal identity [see (3.4) in Section 3]. In the proof of Theorem 1, we can easily check our sufficient condition  $\partial_\lambda^2 \mathcal{E}(\varphi_\omega^\lambda)|_{\lambda=1} < 0$  by a simple computation. This enables us to remove the restriction of  $p \geq 3$  for  $n = 3$ , which was assumed in the paper [4] by Cipolatti. In the proof of Theorem 2, we compare the norms of the ground states with the case of  $a = 0$  in (1.1) by using the variational characterization of the ground states [see Lemma 1 in Section 2]. For the case of  $a = 0$ , we can use the scaling argument and can estimate the norms of the ground states [see (2.11) and under (2.14)]. The analogous method has been used in [8] to show the existence of the stable standing waves.

In what follows, we omit the integral variables with respect to the spatial variable  $x$ , and we omit the integral region when it is the whole space  $\mathbb{R}^n$ . We denote the norms of  $L^q(\mathbb{R}^n)$  and  $H^1(\mathbb{R}^n)$  by  $|\cdot|_q$  and  $\|\cdot\|_{H^1}$ , respectively.

## 2. PROOF OF THEOREMS 1 AND 2

In this section we prove Theorems 1 and 2 by using the following Theorem 3, which will be proved in the next section.

**THEOREM 3.** – *Suppose that  $a > 0$ ,  $1 < p < 1 + 4/(n - 2)$  and  $n = 2$  or  $3$ . If  $\partial_\lambda^2 \mathcal{E}(\varphi_\omega^\lambda)|_{\lambda=1} < 0$ , then the standing wave  $e^{i\omega t} \varphi_\omega$  is unstable, where  $v^\lambda(x) = \lambda^{n/2} v(\lambda x)$ ,  $\lambda > 0$ .*

*Proof of Theorem 1.* – A simple computation shows

$$\begin{aligned} \mathcal{E}(\varphi_\omega^\lambda) &= \frac{\lambda^2}{2} |\nabla \varphi_\omega|_2^2 - \frac{a}{p+1} \lambda^{\frac{n}{2}(p-1)} |\varphi_\omega|_{p+1}^{p+1} \\ &\quad - \frac{1}{4} \lambda^n \int |\varphi_\omega|^2 E_1(|\varphi_\omega|^2) dx, \end{aligned} \quad (2.1)$$

$$\begin{aligned} \partial_\lambda \mathcal{E}(\varphi_\omega^\lambda)|_{\lambda=1} &= |\nabla \varphi_\omega|_2^2 - \frac{n(p-1)}{2(p+1)} a |\varphi_\omega|_{p+1}^{p+1} \\ &\quad - \frac{n}{4} \int |\varphi_\omega|^2 E_1(|\varphi_\omega|^2) dx, \end{aligned} \tag{2.2}$$

$$\begin{aligned} \partial_\lambda^2 \mathcal{E}(\varphi_\omega^\lambda)|_{\lambda=1} &= |\nabla \varphi_\omega|_2^2 - \frac{n(p-1)}{2(p+1)} \left(\frac{n}{2}(p-1) - 1\right) a |\varphi_\omega|_{p+1}^{p+1} \\ &\quad - \frac{n}{4}(n-1) \int |\varphi_\omega|^2 E_1(|\varphi_\omega|^2) dx. \end{aligned} \tag{2.3}$$

Here, we have used the fact that  $E_1(v(\lambda \cdot))(x) = E_1(v)(\lambda x)$ ,  $\lambda > 0$  (see [3], Lemma 2.1). Since  $|\varphi_\omega^\lambda|_2 = |\varphi_\omega|_2$  and  $\varphi_\omega \in \chi_\omega$ , we have

$$\partial_\lambda \mathcal{E}(\varphi_\omega^\lambda)|_{\lambda=1} = \partial_\lambda S_\omega(\varphi_\omega^\lambda)|_{\lambda=1} = \langle S'_\omega(\varphi_\omega), \partial_\lambda \varphi_\omega^\lambda|_{\lambda=1} \rangle = 0. \tag{2.4}$$

Substituting (2.2) and (2.4) into (2.3), we have

$$\begin{aligned} \partial_\lambda^2 \mathcal{E}(\varphi_\omega^\lambda)|_{\lambda=1} &= \left(\frac{n}{2}\right)^2 \frac{p-1}{p+1} \left(1 + \frac{4}{n} - p\right) a |\varphi_\omega|_{p+1}^{p+1} \\ &\quad + \frac{n}{4}(2-n) \int |\varphi_\omega|^2 E_1(|\varphi_\omega|^2) dx. \end{aligned} \tag{2.5}$$

From the definition of  $E_1$  and the Parseval identity, we have

$$\begin{aligned} \int |\varphi_\omega|^2 E_1(|\varphi_\omega|^2) dx &= \int |\varphi_\omega|^2 \mathcal{F}^{-1} \sigma_1(\xi) \mathcal{F}(|\varphi_\omega|^2) dx \\ &= \int \sigma_1(\xi) |\mathcal{F}(|\varphi_\omega|^2)|^2 d\xi > 0, \end{aligned}$$

where  $\mathcal{F}$  is the Fourier transform on  $\mathbb{R}^n$ . Therefore, from (2.5), we have

$$\partial_\lambda^2 \mathcal{E}(\varphi_\omega^\lambda)|_{\lambda=1} < 0, \tag{2.6}$$

if  $n = 2$  and  $p > 1 + 4/n$  or  $n = 3$  and  $p \geq 1 + 4/n$ . The proof follows from (2.6) and Theorem 3, except the case  $n = 2$  and  $p = 1 + 4/n$ . For this special case, see Proposition 3.16 in [4].  $\square$

Before giving the proof of Theorem 2, we make some preparations.

DEFINITION 3. – For any  $v \in H^1(\mathbb{R}^n)$ , we define that

$$\begin{aligned} K_\omega(v) &= S_\omega(v) - \frac{1}{n} |\nabla v|_2^2 \\ &= \left(\frac{1}{2} - \frac{1}{n}\right) |\nabla v|_2^2 + \frac{\omega}{2} |v|_2^2 \\ &\quad - \frac{a}{p+1} |v|_{p+1}^{p+1} - \frac{1}{4} \int |v|^2 E_1(|v|^2) dx, \\ P(v) &= |\nabla v|_2^2 - \frac{n(p-1)}{2(p+1)} a |v|_{p+1}^{p+1} - \frac{n}{4} \int |v|^2 E_1(|v|^2) dx. \end{aligned}$$

Remark 5. – The functional  $K_\omega$  is called the Pohozaev functional. Since  $K_\omega(v) = \frac{1}{n} \partial_\lambda S_\omega(v(\cdot/\lambda))|_{\lambda=1}$  for  $v \in H^1(\mathbb{R}^n)$ , we have  $K_\omega(\psi) = 0$  for  $\psi \in \chi_\omega$ . Moreover, from (2.2), we have  $P(v) = \partial_\lambda \mathcal{E}(v^\lambda)|_{\lambda=1}$  for  $v \in H^1(\mathbb{R}^n)$ . The functional  $P$  is closely related to the pseudo-conformal conservation law [see, e.g., (3.4) in Section 3].

LEMMA 1. – Assume that  $a > 0$ ,  $1 < p < 1 + 4/(n-2)$  and  $n = 2$  or  $3$ .

(1) If  $v \in H^1(\mathbb{R}^n)$  satisfies  $K_\omega(v) < 0$ , then there exists  $\tilde{v} \in H^1(\mathbb{R}^n)$  such that  $K_\omega(\tilde{v}) = 0$ ,  $\tilde{v} \neq 0$  and  $|\nabla \tilde{v}|_2 < |\nabla v|_2$ ,

(2)  $K_\omega(\varphi_\omega) = 0$  and

$$|\nabla \varphi_\omega|_2^2 = \inf \{ |\nabla v|_2^2 : v \in H^1(\mathbb{R}^n), v \neq 0, K_\omega(v) = 0 \},$$

(3)  $S_\omega(\varphi_\omega) = \inf \{ S_\omega(v) : v \in H^1(\mathbb{R}^n), |\nabla v|_2 = |\nabla \varphi_\omega|_2 \}$ .

Proof. – (1) Let  $K_\omega(v) < 0$ . For any  $\eta > 0$ , we have

$$\begin{aligned} K_\omega(\eta v) &= \left(\frac{1}{2} - \frac{1}{n}\right) \eta^2 |\nabla v|_2^2 + \frac{\omega}{2} \eta^2 |v|_2^2 - \frac{a}{p+1} \eta^{p+1} |v|_{p+1}^{p+1} \\ &\quad - \frac{1}{4} \eta^4 \int |v|^2 E_1(|v|^2) dx. \end{aligned}$$

Thus, we have  $K_\omega(\eta v) > 0$  for  $\eta$  small enough. Therefore, there exists  $\eta_0 \in (0, 1)$  such that  $K_\omega(\eta_0 v) = 0$ . Taking  $\tilde{v} = \eta_0 v$ , we have  $|\nabla \tilde{v}|_2 = \eta_0 |\nabla v|_2 < |\nabla v|_2$ . This implies (1).

(2) See Lemma 2.1 in [8].

(3) Consider any  $v \in H^1(\mathbb{R}^n)$  such that  $|\nabla v|_2 = |\nabla \varphi_\omega|_2$ .

Then, it follows from (1) and (2) that  $K_\omega(v) \geq 0$ . Thus, we have

$$S_\omega(v) = \frac{1}{n} |\nabla v|_2^2 + K_\omega(v) \geq \frac{1}{n} |\nabla \varphi_\omega|_2^2 = S_\omega(\varphi_\omega),$$

which implies (3).  $\square$

*Remark 6.* – We note that even if there are many distinct ground states, we have

$$|\nabla \varphi_\omega^{(1)}|_2^2 = n S_\omega(\varphi_\omega^{(1)}) = n S_\omega(\varphi_\omega^{(2)}) = |\nabla \varphi_\omega^{(2)}|_2^2, \varphi_\omega^{(1)}, \varphi_\omega^{(2)} \in \mathcal{G}_\omega.$$

*Proof of Theorem 2.* – Let  $a > 0$ ,  $n = 3$  and  $1 < p < 1 + 4/3$ .

From (2.5), we have  $\partial_\lambda^2 \mathcal{E}(\varphi_\omega^\lambda)|_{\lambda=1} < 0$ , provided that

$$\frac{|\varphi_\omega|_{p+1}^{p+1}}{\int |\varphi_\omega|^2 E_1(|\varphi_\omega|^2) dx} < \frac{p+1}{3(p-1)(1+4/3-p)a}. \tag{2.7}$$

If we have

$$\lim_{\omega \rightarrow \infty} \frac{|\varphi_\omega|_{p+1}^{p+1}}{\int |\varphi_\omega|^2 E_1(|\varphi_\omega|^2) dx} = 0, \tag{2.8}$$

then there exists  $\omega_0 = \omega_0(a, p) > 0$  such that (2.7) holds for any  $\omega \in (\omega_0, \infty)$ . Thus, the proof follows from Theorem 3. Therefore, it is enough to show (2.8). Let  $\tilde{\varphi}_\omega$  be a ground state of

$$-\Delta \psi + \omega \psi - E_1(|\psi|^2) \psi = 0, \quad x \in \mathbb{R}^n, \tag{2.9}$$

and let

$$\tilde{K}_\omega(v) = \frac{1}{6} |\nabla v|_2^2 + \frac{\omega}{2} |v|_2^2 - \frac{1}{4} \int |v|^2 E_1(|v|^2) dx.$$

From Lemma 1 (1) and (2), we have

$$K_\omega(\tilde{\varphi}_\omega) < \tilde{K}_\omega(\tilde{\varphi}_\omega) = 0 \quad \text{and} \quad |\nabla \varphi_\omega|_2^2 < |\nabla \tilde{\varphi}_\omega|_2^2. \tag{2.10}$$

We set  $\tilde{\varphi}(x) = (1/\sqrt{\omega}) \tilde{\varphi}_\omega(x/\sqrt{\omega})$ . Then,  $\tilde{\varphi}$  is a ground state of (2.9) with  $\omega = 1$ . If we put  $d_1 = |\nabla \tilde{\varphi}|_2^2$ , from Remark 6, we have  $d_1 = |\nabla \varphi|_2^2$  for all ground states  $\varphi$  of (2.9) with  $\omega = 1$ . By the change of variables, we also have  $|\nabla \tilde{\varphi}_\omega|_2^2 = d_1 \sqrt{\omega}$ . Therefore, from (2.10), we obtain

$$|\nabla \varphi_\omega|_2^2 \leq d_1 \sqrt{\omega} \quad \text{for any } \omega \in (0, \infty). \tag{2.11}$$



From the definition of  $P$  and (2.4), we have  $P(\varphi_\omega) = 0$ , which together with (2.11) implies

$$|\varphi_\omega|_{p+1}^{p+1} + \int |\varphi_\omega|^2 E_1(|\varphi_\omega|^2) dx \leq C_1 \sqrt{\omega}, \quad \omega \in (0, \infty), \quad (2.12)$$

for some  $C_1 = C_1(a, p) > 0$ .

Also, from  $K_\omega(\varphi_\omega) = 0$  and (2.12), we have

$$\frac{\omega}{2} |\varphi_\omega|_2^2 \leq \frac{a}{p+1} |\varphi_\omega|_{p+1}^{p+1} + \frac{1}{4} \int |\varphi_\omega|^2 E_1(|\varphi_\omega|^2) dx \leq C_2 \sqrt{\omega},$$

$$\omega \in (0, \infty),$$

for some  $C_2 = C_2(a, p) > 0$ .

Thus, we have

$$|\varphi_\omega|_2^2 \leq 2C_2 \omega^{-1/2}, \quad \omega \in (0, \infty). \quad (2.13)$$

Next, we shall estimate  $|\nabla \varphi_\omega|_2^2$  from below. Let  $\hat{\varphi}_\omega$  be a ground state of

$$-\Delta \psi + \omega \psi - 2E_1(|\psi|^2)\psi = 0, \quad x \in \mathbb{R}^n,$$

and let

$$\hat{K}_\omega(v) = \frac{1}{6} |\nabla v|_2^2 + \frac{\omega}{2} |v|_2^2 - \frac{1}{2} \int |v|^2 E_1(|v|^2) dx.$$

If we have

$$\frac{2a}{p+1} |\varphi_\omega|_{p+1}^{p+1} < \frac{1}{6} |\nabla \varphi_\omega|_2^2 + \frac{\omega}{2} |\varphi_\omega|_2^2, \quad \omega > \omega_1, \quad (2.14)$$

for some  $\omega_1 > 0$ , then we obtain  $\hat{K}_\omega(\varphi_\omega) < 2K_\omega(\varphi_\omega)$ , for  $\omega > \omega_1$ , and in the same way as (2.11) we can also show that  $d_2 \sqrt{\omega} \leq |\nabla \varphi_\omega|_2^2$  for  $\omega > \omega_1$ , where  $d_2 = |\nabla \hat{\varphi}_1|_2^2$ . In fact, from the Gagliardo and Nirenberg inequality, we have

$$\int |\varphi_\omega|^{p+1} dx \leq \int |\varphi_\omega|^{2+4/3} dx + \int |\varphi_\omega|^2 dx$$

$$\leq C \left( \int |\varphi_\omega|^2 dx \right)^{2/3} \int |\nabla \varphi_\omega|^2 dx + \int |\varphi_\omega|^2 dx, \quad (2.15)$$

for some  $C > 0$ . It follows from (2.13) and (2.15) that there exists  $\omega_1 = \omega_1(a, p) > 0$  such that (2.14) holds for any  $\omega \in (\omega_1, \infty)$ .

Therefore, we have

$$d_2 \sqrt{\omega} \leq |\nabla \varphi_\omega|_2^2, \quad \omega \in (\omega_1, \infty). \tag{2.16}$$

Furthermore, from (2.11), (2.13) and (2.15), we have

$$|\varphi_\omega|_{\frac{p+1}{p+1}}^{p+1} \leq C_3 (\omega^{-1/3} \cdot \omega^{1/2} + \omega^{-1/2}) \leq C_4 \omega^{1/6}, \quad \omega \in (\omega_2, \infty), \tag{2.17}$$

where positive constants  $\omega_2$ ,  $C_3$  and  $C_4$  depend only on  $a$  and  $p$ .

Also, from (2.16), (2.17) and  $P(\varphi_\omega) = 0$ , we have

$$\begin{aligned} \frac{3}{4} \int |\varphi_\omega|^2 E_1(|\varphi_\omega|^2) dx &= |\nabla \varphi_\omega|_2^2 - \frac{3(p-1)}{2(p+1)} a |\varphi_\omega|_{\frac{p+1}{p+1}}^{p+1} \\ &\geq C_5 \omega^{1/2} - C_6 \omega^{1/6} \geq C_7 \omega^{1/2}, \quad \omega \in (\omega_3, \infty), \end{aligned} \tag{2.18}$$

where positive constants  $\omega_3$ ,  $C_5$ ,  $C_6$  and  $C_7$  depend only on  $a$  and  $p$ .

From (2.17) and (2.18), we have

$$\frac{|\varphi_\omega|_{\frac{p+1}{p+1}}^{p+1}}{\int |\varphi_\omega|^2 E_1(|\varphi_\omega|^2) dx} \leq C_8 \omega^{-1/3}, \quad \omega \in (\omega_3, \infty),$$

for some  $C_8 = C_8(a, p) > 0$ , which implies (2.8).  $\square$

### 3. PROOF OF THEOREM 3

In this section we first prepare three lemmas and next prove Theorem 3. Throughout this section, we assume that  $a > 0$ ,  $1 < p < 1 + 4/(n - 2)$  and  $n = 2$  or  $3$ . Moreover, since we fix the parameter  $\omega$ , we drop the subscript  $\omega$ . Thus, we write  $\varphi$  for  $\varphi_\omega$ ,  $S$  for  $S_\omega$ , and so on.

LEMMA 2. – For any  $\varepsilon > 0$ , there exists  $\delta > 0$  and a mapping

$$\begin{aligned} \lambda : N_\varepsilon(\varphi) &\rightarrow (1 - \delta, 1 + \delta) \\ \text{such that } |\nabla v^\lambda|_2 &= |\nabla \varphi|_2 \quad \text{for } v \in N_\varepsilon(\varphi), \end{aligned}$$

where  $N_\varepsilon(\varphi) = \{v \in H^1(\mathbb{R}^n) : \inf_{\theta \in \mathbb{R}, y \in \mathbb{R}^n} \|v - e^{i\theta} \tau_y \varphi\|_{H^1} < \varepsilon\}$ .

Proof. – Since  $|\nabla v^\lambda|_2 = \lambda |\nabla v|_2$  for any  $\lambda > 0$  and  $v \in H^1(\mathbb{R}^n)$ , it suffices to take  $\lambda(v) = |\nabla \varphi|_2 / |\nabla v|_2$ .  $\square$

LEMMA 3. – If  $\partial_\lambda^2 \mathcal{E}(\varphi^\lambda)|_{\lambda=1} < 0$ , then there exist  $\varepsilon_1, \delta_1 > 0$  with the following property: for any  $v \in N_{\varepsilon_1}(\varphi)$  satisfying  $|v|_2 = |\varphi|_2$ , there exists  $\lambda(v) \in (1 - \delta_1, 1 + \delta_1)$  such that  $\mathcal{E}(\varphi) \leq \mathcal{E}(v) + (\lambda(v) - 1)P(v)$ , where  $P$  is defined as in Definition 3.

*Proof.* – From the assumption  $\partial_\lambda^2 \mathcal{E}(\varphi^\lambda)|_{\lambda=1} < 0$  and the continuity of  $\partial_\lambda^2 \mathcal{E}(v^\lambda)$  in  $\lambda$  and  $v$ , there exist  $\varepsilon_1, \delta_1 > 0$  such that  $\partial_\lambda^2 \mathcal{E}(v^\lambda)| < 0$  for any  $\lambda \in (1 - \delta_1, 1 + \delta_1)$  and  $v \in N_{\varepsilon_1}(\varphi)$ . Since  $\partial_\lambda \mathcal{E}(v^\lambda)|_{\lambda=1} = P(v)$ , the Taylor expansion at  $\lambda = 1$  gives

$$\mathcal{E}(v^\lambda) \leq \mathcal{E}(v) + (\lambda - 1)P(v), \quad \lambda \in (1 - \delta_1, 1 + \delta_1), \quad v \in N_{\varepsilon_1}(\varphi). \quad (3.1)$$

From Lemma 2, if we take  $\varepsilon_1$  small enough, for any  $v \in N_{\varepsilon_1}(\varphi)$ , there exists  $\lambda(v) \in (1 - \delta_1, 1 + \delta_1)$  such that  $|\nabla v^{\lambda(v)}|_2 = |\nabla \varphi|_2$ . Furthermore, from Lemma 1 (3), if  $|v|_2 = |\varphi|_2$ , we have

$$\mathcal{E}(v^{\lambda(v)}) = S(v^{\lambda(v)}) - \frac{\omega}{2} |v^{\lambda(v)}|_2^2 \geq S(\varphi) - \frac{\omega}{2} |\varphi|_2^2 = \mathcal{E}(\varphi). \quad (3.2)$$

Therefore, from (3.1) and (3.2), we have

$$\mathcal{E}(\varphi) \leq \mathcal{E}(v) + (\lambda(v) - 1)P(v)$$

for any  $v \in N_{\varepsilon_1}(\varphi)$  satisfying  $|v|_2 = |\varphi|_2$ .  $\square$

DEFINITION 4. – Put

$$\mathcal{A} = \{v \in N_{\varepsilon_1}(\varphi) : \mathcal{E}(v) < \mathcal{E}(\varphi), |v|_2 = |\varphi|_2, P(v) < 0\},$$

and for any  $u_0 \in N_{\varepsilon_1}(\varphi)$ , we define the exit time from  $N_{\varepsilon_1}(\varphi)$  as follows:

$$T(u_0) = \sup \{T > 0 : u(t) \in N_{\varepsilon_1}(\varphi), 0 \leq t \leq T\},$$

where  $u(t)$  is the solution of (1.1) with  $u(0) = u_0$ .

LEMMA 4. – If  $\partial_\lambda^2 \mathcal{E}(\varphi^\lambda)|_{\lambda=1} < 0$ , then for any  $u_0 \in \mathcal{A}$  there exists  $\delta_0 = \delta_0(u_0) > 0$  such that  $P(u(t)) \leq -\delta_0$  for  $0 \leq t < T(u_0)$ .

*Proof.* – Take  $u_0 \in \mathcal{A}$  and put  $\delta_2 = \mathcal{E}(\varphi) - \mathcal{E}(u_0) > 0$ . From Lemma 3 and the conservation laws (1.3) and (1.4), we have

$$\delta_2 \leq (\lambda(u(t)) - 1)P(u(t)), \quad 0 \leq t < T(u_0). \quad (3.3)$$

Thus, we have  $P(u(t)) \neq 0$  for  $0 \leq t < T(u_0)$ . Since the mapping  $t \mapsto P(u(t))$  is continuous and  $P(u_0) < 0$ , we have  $P(u(t)) < 0$  for  $0 \leq t < T(u_0)$ . Therefore, from Lemma 3 and (3.3), we have

$$-P(u(t)) \geq \frac{\delta_2}{1 - \lambda(u(t))} \geq \frac{\delta_2}{\delta_1}, \quad 0 \leq t < T(u_0).$$

Hence, putting  $\delta_0 = \delta_2/\delta_1$ , we have

$$P(u(t)) \leq -\delta_0 \quad \text{for } 0 \leq t < T(u_0). \quad \square$$

*Proof of Theorem 3.* – Since  $\partial_\lambda \mathcal{E}(\varphi^\lambda)|_{\lambda=1} = 0$ ,  $\partial_\lambda^2 \mathcal{E}(\varphi^\lambda)|_{\lambda=1} < 0$  and  $P(\varphi^\lambda) = \lambda \partial_\lambda \mathcal{E}(\varphi^\lambda)$ , we have  $\mathcal{E}(\varphi^\lambda) < \mathcal{E}(\varphi)$  and  $P(\varphi^\lambda) < 0$  for  $\lambda > 1$  sufficiently close to 1. Furthermore, since  $|\varphi^\lambda|_2 = |\varphi|_2$  and  $\lim_{\lambda \rightarrow 1} \|\varphi^\lambda - \varphi\|_{H^1} = 0$ , we have  $\varphi^\lambda \in \mathcal{A}$  for  $\lambda > 1$  sufficiently close to 1.

Since it follows from Theorem 2.4 in [3] that  $\int |x|^2 |\varphi^\lambda(x)|^2 dx < \infty$ , we have

$$\frac{d^2}{dt^2} \int |x|^2 |u_\lambda(t, x)|^2 dx = 8P(u_\lambda(t)), \quad 0 \leq t < T(\varphi^\lambda), \quad (3.4)$$

where  $u_\lambda(t)$  is the solution of (1.1) with  $u_\lambda(0) = \varphi^\lambda$ . From Lemma 4, there exists  $\delta_\lambda > 0$  such that

$$P(u_\lambda(t)) \leq -\delta_\lambda, \quad 0 \leq t < T(\varphi^\lambda). \quad (3.5)$$

Hence, from (3.4) and (3.5), we can conclude that  $T(\varphi^\lambda) < \infty$ .

Since  $\lim_{\lambda \rightarrow 1} \|\varphi^\lambda - \varphi\|_{H^1} = 0$ , the proof is completed.  $\square$

*Remark 7.* – Cipolatti also showed in [3] the existence of ground states of  $(1.2_\omega)$  in the case when  $a < 0$ ,  $1 < p \leq 3$  and  $n = 2$  or  $3$ , and proved in [4] that all standing waves are unstable in that case. We note that our proof is applicable to that case.

*Remark 8.* – It is an open problem whether the above  $u_\lambda$  blows up in finite time or not. For the case of local nonlinearity, see Berestycki and Cazenave [1].

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