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## H. Airault <br> P. MALLIAVIN <br> Some heat operators on $\mathbb{P}\left(\mathbb{R}^{d}\right)$

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# SOME HEAT OPERATORS ON $\mathbb{P}\left(\mathbb{R}^{d}\right)$ 

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#### Abstract

To a diffusion on $R^{n}$, we associate a heat equation on the path space $P\left(R^{n}\right)$ of continuous maps defined on $[0,1]$ with values in $R^{n}$. The heat operator is obtained by taking the sum of the square of twisted derivatives with respect to an orthonormal basis of the Cameron-Martin space. We give the expression of this heat operator when it acts on cylindrical functions defined on the Wiener space. Résumé . A une diffusion sur $R^{n}$, on associe une équation de la chaleur sur $P\left(R^{n}\right)$, l'espace des applications continues, définies sur $[0,1]$ à valeurs dans $R^{n}$. L'opérateur de la chaleur est construit en prenant la somme des carrés des dérivées amorties par rapport à une base de l'espace de Cameron-Martin. On exprime cet opérateur de la chaleur sur les fonctions cylindriques définies sur l'espace de Wiener.


## §0: Introduction

Let $\Omega=P\left(R^{n}\right)$ be the Wiener space of continuous maps from $[0,1]$ with values in $R^{n}$ and let $I: \omega \rightarrow x(\omega)$ be a map from $\Omega$ to itself. We assume that, for any $\tau \in[0,1]$, the map $\omega \rightarrow x_{\tau}(\omega)$ is differentiable on the Wiener space and that it is adapted. Given the heat operator $A$ on the Wiener space $P\left(R^{n}\right)$ [See [2]], we construct a new operator $\tilde{A}$. The operator $\tilde{A}$ is the image of the operator $A$ through the map $I$, and satisfy the identity

$$
\begin{equation*}
A(f o I)=(\tilde{A} f) o I \tag{0.1}
\end{equation*}
$$

This allows to obtain a heat equation associated to the map $I$. The operator $\tilde{A}$ is obtained by taking the sum of the square of twisted derivatives with respect to a basis $\left(e_{k}, \alpha\right)_{k \geq 0,1 \leq \alpha \leq n}$ of the Cameron-Martin space of the Wiener space. We express the operator $\tilde{A}$ when it is applied to cylindrical functions defined on the Wiener space $P\left(R^{n}\right)$. The identity (0.1) extends to the Wiener space the elementary following computation: Let $A=\frac{d^{2}}{d x^{2}}$ be the derivative of order 2 on $R$, viewed as the infinitesimal generator of the brownian diffusion on $R$, and let $\phi$ be a differentiable homeomorphism of $R$; then $A(f \circ \phi)=(\tilde{A} f) \circ \phi$ holds where

$$
\begin{equation*}
\tilde{A}=\left(\phi^{\prime}\left[\phi^{-1}(x)\right]\right)^{2} \frac{d^{2}}{d x^{2}}+\phi^{\prime \prime}\left(\phi^{-1}(x)\right) \frac{d}{d x} \tag{0.2}
\end{equation*}
$$

is the infinitesimal generator of a new diffusion on $R$. We explicit the computations when the map $I$ is the Ito map associated to the diffusion on $R^{n}$

$$
\begin{equation*}
d x(\tau)=d \omega(\tau)+b(x(\tau)) d \tau \tag{0.3}
\end{equation*}
$$

This method extends when $I$ is a map from $P\left(R^{n}\right)$ to $P(M)$ the path space of a Riemannian manifold $M$; it allows to obtain new diffusions on the space $P(M)$. See [3] for further developments related to this subject.

## §1 Notations and definitions

Let $\omega$ be the brownian on $R^{n}$, and consider the diffusion given by the stochastic differential equation (0.3) where $b$ is a differentiable map from $R^{n}$ to $R^{n}$. We denote by

$$
\begin{equation*}
I: \omega \rightarrow x(\omega) \tag{1.1}
\end{equation*}
$$

the Ito map and let

$$
\begin{equation*}
g_{t}: \omega \rightarrow \sqrt{t} \omega \tag{1.2}
\end{equation*}
$$

be the dilation on $P\left(R^{n}\right)$. The evaluation map $\varphi_{\tau}$ at $\tau$ is given by

$$
\varphi_{\tau}(\omega)=\omega_{\tau}
$$

and we put

$$
\begin{equation*}
\tilde{\varphi}_{\tau}=\varphi_{\tau} O I \tag{1.3}
\end{equation*}
$$

We denote by $\mu$ the Wiener measure on $\Omega=C\left([0,1], R^{n}\right)$ and let $\nu_{t}=\left(\operatorname{Iog}_{t}\right) * \mu$ be the image of the Wiener measure $\mu$ by the map Iog $_{t}$. The Cameron-Martin space $H$ is the set of differentiable functions $h$ in $L^{2}([0,1] ; R)$ such that $\int_{0}^{1} h^{\prime}(s)^{2} d s<+\infty$. We consider for a basis of the Cameron-Martin space $H$, the functions defined by

$$
\begin{equation*}
e_{k, \alpha}(\tau)=\sqrt{2} \frac{\sin (k \pi \tau)}{k \pi} \otimes \varepsilon_{\alpha} \tag{1.4}
\end{equation*}
$$

with $k \geq 1$ and

$$
e_{0, \alpha}(\tau)=\tau \otimes \varepsilon_{\alpha}
$$

where $\left(\varepsilon_{\alpha}\right)_{\alpha=1, \ldots, n}$ is a basis of $R^{n}$. We shall write

$$
\begin{gathered}
e_{k}(\tau)=\sqrt{2} \frac{\sin (k \pi \tau)}{k \pi} \\
e_{0}(\tau)=\tau
\end{gathered}
$$

Let $h$ be an element of the Cameron-Martin space $H$ and let $f: \Omega \rightarrow R^{n}$. We let

$$
\begin{equation*}
D_{h} f(\omega)=\left.\frac{d}{d \varepsilon}\right|_{\varepsilon=0} f(\omega+\varepsilon h) \tag{1.5}
\end{equation*}
$$

For $s \in[0,1]$, we define $D_{s} f(\omega)$ such that

$$
\begin{equation*}
D_{h} f(\omega)=\int_{0}^{1} D_{s} f(\omega) h^{\prime}(s) d s \tag{1.6}
\end{equation*}
$$

Let

$$
\begin{equation*}
\nabla f(\omega)(s)=\int_{0}^{s} D_{u} f(\omega) d u \tag{1.7}
\end{equation*}
$$

On the Cameron-Martin space $H$, denote ( | ) $)_{H}$ the scalar product given by $\left(h_{1} \mid h_{2}\right)_{H}=$ $\int_{0}^{1} h_{1}^{\prime}(s) h_{2}^{\prime}(s) d s$. We have

$$
\begin{equation*}
D_{h}(\omega)=(h \mid \nabla f(\omega)) \tag{1.8}
\end{equation*}
$$

and for $f_{1}$ and $f_{2}$ defined on $\Omega$ with real values, we have

$$
\begin{equation*}
\left(\nabla f_{1}(\omega) \mid \nabla f_{2}(\omega)\right)=\int_{0}^{1} D_{s} f_{1}(\omega) D_{s} f_{2}(\omega) d s \tag{1.9}
\end{equation*}
$$

## §2 Twisting and intertwinning identities

Let $b^{\prime}$ be the Jacobian map of $b$ and let $h$ in the Cameron-Martin space; we put

$$
\begin{equation*}
\beta(\tau)(\omega)=\int_{0}^{\tau} \exp \left[\int_{s}^{\tau} b^{\prime}\left(\omega_{u}\right) d u\right] h^{\prime}(s) d s \tag{2.1}
\end{equation*}
$$

Definition 2.1. We call $\beta(\tau)$ the twisted vector field associated to the element $h$ through the diffusion (0.3).

We denote $\beta^{\prime}(\tau)=\frac{d}{d \tau} \beta(\tau)$ the derivative of $\beta$ as a function of $\tau$. By (2.1), we have

$$
\begin{equation*}
\beta^{\prime}(\tau)(\omega)=h^{\prime}(\tau)+b^{\prime}\left(\omega_{\tau}\right) \beta(\tau)(\omega) \tag{2.2}
\end{equation*}
$$

and

$$
\beta(0)(\omega)=0
$$

Lemma 2.1. Assume that $\beta$ and $h$ are related by (2.1), then the derivative of the evaluation map (1.3) is

$$
\begin{equation*}
D_{h} \tilde{\varphi}_{\tau}(\omega)=\beta(\tau)(I \omega) \tag{2.3}
\end{equation*}
$$

proof. Let $h \in H$; from (1.2) and (0.3), the function

$$
y^{\epsilon}(\tau)(\omega)=\tilde{\varphi}_{\tau}(\omega+\epsilon h)
$$

is solution of the stochastic equation

$$
\begin{equation*}
d y^{\epsilon}(\tau)(\omega)=d \omega(\tau)+\epsilon h^{\prime}(\tau) d \tau+b\left(y^{\epsilon}(\tau)(\omega)\right) d \tau \tag{2.4}
\end{equation*}
$$

Taking the derivative with respect to $\epsilon$, we obtain that

$$
z(\tau)(\omega)=\frac{d}{d \epsilon}_{\mid \epsilon=0} y^{\epsilon}(\tau)(\omega)
$$

satisfies

$$
d z(\tau)(\omega)=h^{\prime}(\tau) d \tau+b^{\prime}(x(\tau)(\omega)) z(\tau) d \tau
$$

and

$$
z(0)(\omega)=0
$$

By (2.2), we obtain the identity (2.3).
Corollary. We have

$$
\begin{equation*}
D_{s} x(\tau)(\omega)=\exp \left[\int_{s}^{\tau} b^{\prime}(x(u)(\omega))\right] d u \tag{2.5}
\end{equation*}
$$

proof. $D_{s} x(\tau)(\omega)$ means $D_{s} \tilde{\varphi}_{\tau}(\omega)$ Thus, by (2.3) and (1.6), we have

$$
\begin{equation*}
\beta(\tau)(I \omega)=\int_{0}^{\tau} D_{s} x_{\tau}(\omega) h^{\prime}(s) d s \tag{2.6}
\end{equation*}
$$

Then, we use (2.1).
Remark: If we denote $\varphi_{\tau}(\omega)=\omega_{\tau}$ then (2.6) can be written

$$
\begin{equation*}
\beta(\tau)(\omega)=\left(\left(\nabla\left(\varphi_{\tau} o I\right)\left(I^{-1}(\omega) \mid h\right)_{H}\right.\right. \tag{2.7}
\end{equation*}
$$

Definition 2.2. We let

$$
\begin{equation*}
D_{\beta} f(\omega)=\frac{d}{d \varepsilon}_{\mid \varepsilon=0} f(\omega+\varepsilon \beta(\omega)) \tag{2.8}
\end{equation*}
$$

Lemma 2.2. If $\beta$ is the twisted vector field related to $h$ through (2.1), the following intertwinning relation holds

$$
\begin{equation*}
D_{h}(f o I)(\omega)=\left(D_{\beta} f\right)(I \omega) \tag{2.9}
\end{equation*}
$$

proof.

$$
\begin{equation*}
D_{h}(f o I)(\omega)=\frac{d}{d \varepsilon}_{\mid \varepsilon=0}(f o I)(\omega+\varepsilon h) \tag{2.10}
\end{equation*}
$$

We verify (2.9) when $f=\psi o \varphi_{\tau}$ where $\varphi_{\tau}(\omega)=\omega_{\tau}$ and $\psi: R^{n} \rightarrow R$. For the solution $y^{\epsilon}(\tau)$ of (2.4), we have

$$
\begin{equation*}
(f o I)(\omega+\epsilon h)=\psi\left(y^{\epsilon}(\tau)\right) \tag{2.11}
\end{equation*}
$$

We deduce that

$$
\begin{equation*}
\frac{d}{d \varepsilon}_{\left.\right|_{\epsilon=0}} \psi\left(y^{\epsilon}(\tau)\right)=\psi^{\prime}\left(x_{\tau}\right) \beta(\tau)(I \omega) \tag{2.12}
\end{equation*}
$$

On the other hand

$$
\begin{equation*}
\left(D_{\beta} f\right)(\omega)=\psi^{\prime}(\omega(\tau)) \beta(\tau)(\omega) \tag{2.13}
\end{equation*}
$$

By comparison of (2.13) and (2.12), we get (2.9).
Remark that (2.3) is the particular case of (2.9) when $f=\varphi_{\tau}$.
Definition 2.3. When $h$ and $\beta$ are related through (2.1), we define the twisted derivative $\tilde{D}_{h} f$ by

$$
\begin{equation*}
\tilde{D}_{h} f(\omega)=D_{\beta} f(\omega) \tag{2.14}
\end{equation*}
$$

Lemma 2.3. We have

$$
\begin{equation*}
\left(\tilde{D}_{h}^{2} f\right)(I \omega)=D_{h}^{2}(f o I)(\omega) \tag{2.15}
\end{equation*}
$$

proof. From (2.14) and (2.9), we get

$$
\begin{equation*}
\left(\tilde{D}_{h} f\right)(I \omega)=D_{h}(f o I)(\omega) \tag{2.16}
\end{equation*}
$$

and

$$
\begin{gathered}
\tilde{D}_{h}\left(\tilde{D}_{h} f\right)(I \omega)=D_{h}\left(\left(\tilde{D}_{h} f\right) o I\right)(\omega) \\
=D_{h}\left(D_{h}(f o I)\right)(\omega)
\end{gathered}
$$

Thus, we obtain (2.15).

## §3 Heat operators on the space $P\left(R^{n}\right)$

We shall construct the heat operator on $P\left(R^{n}\right)$ using the Ito map.
Definition 3.1. Let $e_{k, \alpha}$ given by (1.4) and let $D_{e_{k, \alpha}}$ the derivation in the direction $e_{k, \alpha}$ (See (1.5)), we define the second order operator

$$
\begin{equation*}
A=\sum_{k \geq 0} \sum_{1 \leq \alpha \leq n} D_{e_{k, \alpha}}^{2} \tag{3.1}
\end{equation*}
$$

The operator $A$ on $P\left(R^{n}\right)$ does not depend on the basis of the Cameron-Martin space; See [2].

Definition 3.2. Let $\tilde{D}_{e_{k, \alpha}}$ be the twisted derivation, we define the twisted operator $\tilde{A}$ by

$$
\begin{equation*}
\tilde{A}=\sum_{k \geq 0} \sum_{1 \leq \alpha \leq n} \tilde{D}_{e_{k, \alpha}}^{2} \tag{3.2}
\end{equation*}
$$

We verify that the definition (3.2) for the operator $\tilde{A}$ on $P\left(R^{n}\right)$ does not depend on the basis of the Cameron-Martin space.

Lemma 3.1. We have

$$
\begin{equation*}
A(f o I)=(\tilde{A} f) o I \tag{3.3}
\end{equation*}
$$

proof. This is a consequence of (2.15), (3.1) and (3.2).
We shall see in $\S 4$ that $\tilde{A}$ corresponds to a change of variables on the Wiener space analoguous to the elementary one (0.2) on $R$.

Definition 3.3. We denote by $\mu$ the Wiener measure on $\Omega=C\left([0,1], R^{n}\right)$ and let

$$
\begin{equation*}
\nu_{t}=\left(\operatorname{Iog}_{t}\right) * \mu \tag{3.4}
\end{equation*}
$$

the image of the Wiener measure $\mu$ through the map Iog $_{t}$. See (1.2).
Theorem 3.1. Let $f$ be a regular function from $P\left(R^{n}\right)$ to $R$. We have

$$
\begin{equation*}
\frac{\partial}{\partial t} \int f(\omega) d \nu_{t}(\omega)=\int \tilde{A} f(\omega) d \nu_{t}(\omega) \tag{3.5}
\end{equation*}
$$

proof. We verify (3.4) when $f(\omega)=\psi\left(\omega_{\tau_{1}}, \dot{\omega}_{\tau_{2}}\right)$ and $\psi: R^{n} \rightarrow R$. In this case, we have

$$
\begin{aligned}
& \int f(\omega) d \nu_{t}(\omega)=\int f\left(\operatorname{Iog}_{t}(\omega)\right) d \mu(\omega) \\
& =\int \psi\left(x_{\tau_{1}}(\sqrt{t} \omega), x_{\tau_{2}}(\sqrt{t} \omega)\right) d \mu(\omega)
\end{aligned}
$$

From the heat equation related to the brownian motion on $P\left(R^{n}\right)$, we know (see [2]) that

$$
\begin{equation*}
\frac{\partial}{\partial t} \int(f o I)\left(g_{t}(\omega)\right) d \mu(\omega)=\int A(f o I)\left(g_{t}(\omega)\right) d \mu(\omega) \tag{3.6}
\end{equation*}
$$

From (3.6) and (3.3), we deduce (3.5).
§4 Expression of the twisted Laplacian $\tilde{A}$ on cylindrical functions
Notation. Let $p_{i}: R^{n} \rightarrow R$ be the projection on the $i$ component; we denote

$$
x^{i}(\tau)=p_{i} \alpha \tilde{\varphi}_{\tau}
$$

and $x(\tau)=\left(x^{1}(\tau), x^{2}(\tau), \ldots, x^{n}(\tau)\right)$. We put $\nabla x^{i}(\tau)=\nabla\left(p_{i} o \tilde{\varphi}_{\tau}\right)$.
From (1.9), we have

$$
\begin{equation*}
\left(\nabla x^{i}(\tau) \mid \nabla x^{j}(\tau)\right)_{H}=\int_{0}^{\tau} D_{s} x^{i}(\tau) D_{s} x^{j}(\tau) d s \tag{4.1}
\end{equation*}
$$

Theorem 4.1. Let $\psi: R^{n} \rightarrow R$ and $\varphi_{\tau}(\omega)=\omega_{\tau}$. We have

$$
\begin{equation*}
\tilde{A}\left(\psi o \varphi_{\tau}\right)=\sum_{1 \leq i \leq n} \sum_{1 \leq j \leq n}\left(\nabla x^{i}(\tau) \mid \nabla x^{j}(\tau)\right)_{H}\left(I^{-1} \omega\right) \frac{\partial^{2} \psi}{\partial x_{i} \partial x_{j}}\left(\omega_{\tau}\right)+A\left(x^{i}(\tau)\right)\left(I^{-1} \omega\right) \frac{\partial \psi}{\partial x_{i}}\left(\omega_{\tau}\right) \tag{4.2}
\end{equation*}
$$

The proof of (4.2) will result from the following lemmas and definitions.
Remark: If we take a $\Phi=\left(\Phi_{1}, \Phi_{2}, \ldots, \Phi_{n}\right)$ to be a differentiable homeomorphism of $R^{n}$ and let

$$
\Delta=\sum_{1 \leq i \leq n} \frac{\partial^{2}}{\partial x_{i}{ }^{2}}
$$

to be the usual Laplacian on $R^{n}$, we have, for $F: R^{n} \rightarrow R$

$$
\Delta(F o \Phi)=(\tilde{\Delta} F) o \Phi
$$

with

$$
\tilde{\Delta}=\sum_{i, j}\left(\nabla \Phi_{i} \mid \nabla \Phi_{j}\right)\left(\Phi^{-1}(x)\right) \frac{\partial^{2}}{\partial x_{i} \partial x_{j}}+\sum_{1 \leq i \leq n}\left(\Delta \Phi_{i}\right)\left(\Phi^{-1}(x)\right) \frac{\partial}{\partial x_{i}}
$$

The theorem 4.1 is an extension of this remark to the Wiener space.
Definition 4.1. Let

$$
\begin{equation*}
M(s, \tau)(\omega)=\exp \left[\int_{s}^{\tau} b^{\prime}\left(\omega_{u}\right) d u\right] \tag{4.3}
\end{equation*}
$$

From (2.5), we see that

$$
\begin{equation*}
M(s, \tau)(I \omega)=D_{s} x(\tau)(\omega) \tag{4.4}
\end{equation*}
$$

Lemma 4.2. We assume that we have a one dimensional diffusion, i.e. $n=1$ in (0.3). For $k \geq 1$, let

$$
\begin{equation*}
\beta_{k}(\tau)(\omega)=\int_{0}^{\tau} M(s, \tau)(\omega) \sqrt{2} \cos (k \pi s) d s \tag{4.5}
\end{equation*}
$$

and

$$
\begin{equation*}
\beta_{o}(\tau)(\omega)=\int_{0}^{\tau} M(s, \tau)(\omega) d s \tag{4.6}
\end{equation*}
$$

We have

$$
\begin{equation*}
\sum_{k \geq 0} \beta_{k}(\tau)^{2}(\omega)=\int_{0}^{\tau} \exp \left[2 \int_{s}^{\tau} b^{\prime}\left(\omega_{u}\right) d u\right] d s \tag{4.7}
\end{equation*}
$$

proof. For fixed $\tau$, let $g$ be the even function which is periodic, of period 2 and given by

$$
\begin{equation*}
g(s)=1_{s \leq \tau} \exp \left[\int_{s}^{\tau} b^{\prime}\left(\omega_{u}\right) d u\right] \tag{4.8}
\end{equation*}
$$

Its development in Fourier series, for $s \leq \tau$ is equal to

$$
\begin{equation*}
\beta_{0}(\tau)+\sum_{k \geq 1} 2 \beta_{k}(\tau) \cos (k \pi s)=g(s) \tag{4.9}
\end{equation*}
$$

From Parseval's identities, we obtain

$$
\begin{equation*}
2 \int_{0}^{1} g(s)^{2} d s=2 \sum_{k \geq 0} \beta_{k}(\tau)^{2} \tag{4.10}
\end{equation*}
$$

This proves (4.7).
Lemma 4.3. The line vectors of the matrix $M(s, \tau)(I \omega)$ are the vectors $D_{s} x^{i}(\tau)(\omega)$. See (4.4). For $n=1$, we get

$$
\begin{equation*}
\sum_{k \geq 0} \beta_{k}(\tau)^{2}(I \omega)=|\nabla x(\tau)(\omega)|_{H}^{2} \tag{4.11}
\end{equation*}
$$

proof.
By (3.1), we have

$$
\begin{equation*}
D_{h} \tilde{\varphi}_{\tau}(\omega)=\int_{0}^{\tau} \exp \left[\int_{s}^{\tau} b^{\prime}\left(x_{u}\right) d u\right] h^{\prime}(s) d s \tag{4.12}
\end{equation*}
$$

thus, from (2.5), we get

$$
\begin{equation*}
D_{s} \tilde{\varphi}_{r}(\omega)=\exp \left[\int_{s}^{\tau} b^{\prime}\left(x_{u}\right) d u\right] 1_{s \leq \tau} \tag{4.13}
\end{equation*}
$$

This proves the first assertion. Then, we deduce (4.11) from (4.7) and (1.9).

Proposition 4.4. The second order term in $\tilde{A}\left(\psi o \varphi_{\tau}\right)$ is given by

$$
\begin{equation*}
\left(\nabla x^{i}(\tau) \mid \nabla x^{j}(\tau)\right)_{H}\left(I^{-1} \omega\right) \frac{\partial^{2} \varphi}{\partial x_{i} \partial x_{j}}\left(\omega_{\tau}\right) \tag{4.14}
\end{equation*}
$$

proof. We have to calculate $D_{\beta}^{2}\left(\psi o \varphi_{\tau}\right)$, taking care that

$$
\beta(\tau)(\omega)=\int_{0}^{\tau} \exp \left[\int_{s}^{\tau} b^{\prime}\left(\omega_{u}\right) d u\right] h^{\prime}(s) d s
$$

depends on $\omega$ when the gradient of $b$ is not constant. We have

$$
\begin{equation*}
D_{\beta}\left(\psi \omega \varphi_{\tau}\right)(\omega)=\psi^{\prime}\left(\omega_{\tau}\right) \beta(\tau)(\omega) \tag{4.15}
\end{equation*}
$$

and

$$
\begin{equation*}
D_{\beta}^{2}\left(\psi o \varphi_{\tau}\right)(\omega)=\psi^{\prime \prime}\left(\omega_{\tau}\right)[\beta(\tau)(\omega), \beta(\tau)(\omega)]+\psi^{\prime}\left(\omega_{\tau}\right) D_{\beta}[\beta(\tau)(\omega)] \tag{4.16}
\end{equation*}
$$

We obtain (4.14) from (4.11), (4.16) and (3.2) as follows: Let

$$
\begin{gathered}
\beta_{k, \alpha}(\tau)(\omega)=\int_{0}^{\tau} \exp \left[\int_{s}^{\tau} b^{\prime}\left(\omega_{u}\right) d u\right] e_{k, \alpha}^{\prime}(s) d s \\
=\int_{0}^{\tau} e_{k}^{\prime}(s) \exp \left[\int_{s}^{\tau} b^{\prime}\left(\omega_{u}\right) d u\right]\left(\epsilon_{\alpha}\right) d s \\
=\int_{0}^{\tau} e_{k}^{\prime}(s) M(s, \tau)\left(\epsilon_{\alpha}\right) d s
\end{gathered}
$$

See (4.3). We put

$$
M(s, \tau)\left(\epsilon_{\alpha}\right)=\sum_{j} A_{\alpha}^{j}(s, \tau)\left(\epsilon_{j}\right)
$$

We obtain

$$
\beta_{k, \alpha}(\tau)(\omega)=\sum_{1 \leq j \leq n} \int_{0}^{\tau} e_{k}^{\prime}(s) A_{\alpha}^{j}(s, \tau) d s\left(\epsilon_{j}\right)
$$

We denote

$$
\begin{equation*}
{ }_{k} B_{\alpha}^{j}(\tau)=\int_{0}^{\tau} e_{k}^{\prime}(s) A_{\alpha}^{j}(s, \tau) d s \tag{4.17}
\end{equation*}
$$

We have

$$
\begin{gathered}
\sum_{\alpha=1}^{n} \psi^{\prime \prime}\left(\omega_{\tau}\right)\left[\beta_{k, \alpha}(\tau)(\omega), \beta_{k, \alpha}(\tau)(\omega)\right] \\
=\sum_{\alpha=1}^{n} \sum_{j_{1}=1, j_{2}=1}^{n}\left[{ }_{k} B_{\alpha}^{j_{1}}(\tau)_{k} B_{\alpha}^{j_{2}}(\tau)\right] \psi^{\prime \prime}\left(\omega_{\tau}\right)\left(\epsilon_{j_{1}}, \epsilon_{j_{2}}\right)
\end{gathered}
$$

$$
=\sum_{j_{1}, j_{2}}\left[\sum_{\alpha=1}^{n}\left[{ }_{k} B_{\alpha}^{j_{1}}(\tau)_{k} B_{\alpha}^{j_{2}}(\tau)\right] \frac{\partial^{2} \psi}{\partial x_{j_{1}} \partial x_{j_{2}}}\left(\omega_{r}\right)\right.
$$

On the other hand,

$$
\left(\nabla x^{j_{1}}(\tau) \mid \nabla x^{j_{2}}(\tau)\right)_{H}=\sum_{\alpha=1}^{n} \sum_{k \geq 0}\left[k B_{\alpha}^{j_{1}}(\tau)_{k} B_{\alpha}^{j_{2}}(\tau)\right]
$$

This proves (4.14).
We shall now evaluate the first order term on cylindrical functions.
Lemma 4.5. Let $\beta_{k}(\tau)(\omega)$ and $\beta_{o}(\tau)(\omega)$ given by (4.5)-(4.6) and $n=1$, we have

$$
\begin{equation*}
\sum_{k \geq 0} D_{\beta_{k}}\left[\beta_{k}(\tau)(\omega)\right]=\int_{0}^{\tau} M(s, \tau) \int_{s}^{\tau} M(s, \alpha) b^{\prime \prime}\left(\omega_{\alpha}\right) d \alpha \tag{4.18}
\end{equation*}
$$

proof. By (2.2), we have

$$
\begin{equation*}
\beta(\tau)(\omega+\varepsilon \beta(\omega))=\int_{0}^{\tau} \exp \left[\int_{s}^{\tau} b^{\prime}\left(\omega_{u}+\epsilon \beta(u)(\omega)\right) d u\right] h^{\prime}(s) d s \tag{4.19}
\end{equation*}
$$

We deduce

$$
\begin{gather*}
\left.\frac{d}{d \varepsilon} \right\rvert\, \varepsilon=0 \\
=\int_{0}^{\tau} M(\tau, \tau)(\omega) \int_{s}^{\tau} b^{\prime \prime}\left(\omega_{\alpha}\right) \beta(\alpha)(\omega) h^{\prime}(s) d \alpha d s \\
=\int_{0}^{\tau} M(s, \tau)(\omega) \int_{s}^{\tau} b^{\prime \prime}\left(\omega_{\alpha}\right) \int_{0}^{\alpha} M(u, \alpha) h^{\prime}(u) h^{\prime}(s) d u d s \\
=\int_{0}^{\tau} M(s, \tau)(\omega) h^{\prime}(s) d s \int_{0}^{\tau} h^{\prime}(u) \int_{s u p(u, s)}^{\tau} b^{\prime \prime}\left(\omega_{\alpha}\right) M(u, \alpha) d \alpha d u \tag{4.20}
\end{gather*}
$$

where, at the second step, we have replaced $\beta(\alpha)$ by its expression (2.1). We have to evaluate the sum

$$
\begin{equation*}
J=\sum_{k \geq 0} e_{k}^{\prime}(s) \int_{0}^{\tau} e_{k}^{\prime}(v) g_{s}(v) d v \tag{4.21}
\end{equation*}
$$

where

$$
\begin{equation*}
g_{s}(v)=\int_{s u p(s, v)}^{\tau} M(v, \alpha) b^{\prime \prime}\left(\omega_{\alpha}\right) d \alpha \tag{4.22}
\end{equation*}
$$

$J$ is the sum of the Fourier series of $g$ at the point $v=s$. We deduce (4.18).

Proposition 4.6. Let $A$ be the Laplacian (3.1). The first order term in (4.2) is given by

$$
\begin{equation*}
A\left(x^{i}(\tau)\right)\left(I^{-1} \omega\right) \frac{\partial \psi}{\partial x_{i}}\left(\omega_{\tau}\right) \tag{4.23}
\end{equation*}
$$

proof. We do the proof when $n=1$. We calculate

$$
\begin{equation*}
\sum_{k} D_{e_{k}}^{2} x(\tau)(\omega) \tag{4.24}
\end{equation*}
$$

We have

$$
D_{h} x(\tau)(\omega)=\int_{0}^{\tau} \exp \left[\int_{s}^{\tau} b^{\prime}\left(x_{u}(\omega)\right) d u\right] h^{\prime}(s) d s
$$

and

$$
\begin{gather*}
D_{h}^{2} x(\tau)(\omega)=\left.\frac{d}{d \varepsilon}\right|_{\mid \varepsilon=0} D_{h} x(\tau)(\omega+\varepsilon h) \\
=\int_{0}^{\tau} d s \quad M(s, \tau)(I \omega) h^{\prime}(s) \int_{s}^{\tau} d u \quad b^{\prime \prime}\left(x_{u}(\omega)\right) \int_{0}^{\tau} d \gamma \quad M(\gamma, u)(I \omega) h^{\prime}(\gamma) \tag{4.25}
\end{gather*}
$$

After changing the order of integration in (4.25), we calculate the sum (4.24) as the sum of a Fourier series. We obtain that the sum (4.24) is equal to

$$
\begin{equation*}
\int_{0}^{\tau} M(s, \tau)(I \omega) \int_{s}^{\tau} M(s, u)(I \omega) b^{\prime \prime}\left(x_{u}(\omega)\right) d u d s \tag{4.26}
\end{equation*}
$$

We compare with (4.18) and it yields (4.23).

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