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On Analyticity in Homogeneous First Order Partial Differential Equations.

HANS LEWY (*)

1. – Let α_1 , α_2 , s be independent real variables and x, y, u real C^1 -functions of these near the origin, satisfying

(1)
$$\frac{\partial(x, y, u)}{\partial(\alpha_1, \alpha_2, s)} = 0$$

and

(2)
$$rac{\partial(x,\,y)}{\partial(lpha_1,\,lpha_2)}
eq 0 \;, \qquad rac{\partial x}{\partial s}
eq 0 \;.$$

An arbitrary C^1 -function u = f(x, y) satisfies (1). We investigate conditions such that f is analytic in x and y.

THEOREM 1. If x, y, u satisfy (1) and (2) and

$$\begin{vmatrix} x_s & y_s & (y_s/x_s)_s \\ x_{\alpha_1} & y_{\alpha_1} & (y_s/x_s)_{\alpha_1} \\ x_{\alpha_2} & y_{\alpha_2} & (y_s/x_s)_{\alpha_2} \end{vmatrix} \neq 0$$

and if x, y, u can be extended as holomorphic functions of s+it, $|t| < t_0$, which remain C^1 in α_1 , α_2 , s, t, then u = f(x, y) where f is analytic in x and y.

PROOF. We first establish that near the α_1, α_2, s, t -origin the map

$$\alpha_1 \alpha_2, s, t \rightarrow x, y$$

is one-one for $t \neq 0$.

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Put

$$x = x_0 + x_s(s+it) + \frac{1}{2}x_{ss}(s+it)^2 + \dots$$
$$y = y_0 + y_s(s+it) + \frac{1}{2}y_{ss}(s+it)^2 + \dots$$

where

$$x_0 = x(\alpha_1, \alpha_2, 0), \quad x_s = \frac{\partial x}{\partial s}(\alpha_1, \alpha_2, 0), \ldots$$

An application of Cauchy's integral formula shows the coefficients of the above power series to be C^1 -functions of α_1 , α_2 . The imaginary parts of x and y are of the form tP(s,t) where P(s,t) is a convergent power series in s and t. It follows from (2) that for $t \neq 0$

$$\frac{\operatorname{Im} y}{\operatorname{Im} x} = \frac{y_s + y_{ss} s + \dots}{x_s + x_{ss} s + \dots} = \frac{y_s}{x_s} + s \frac{y_{ss} x_s - x_s y_{ss}}{x_s^2} + \dots,$$

a power series in s and t.

Hence near $s=t=\alpha_1=\alpha_2=0$,

$$J = \frac{\partial (\operatorname{Re} x, \operatorname{Re} y, \operatorname{Im} x, \operatorname{Im} y/\operatorname{Im} x)}{\partial (s, t, \alpha_{1}, \alpha_{2})} =$$

$$= \begin{vmatrix} x_{s} & y_{s} & 0 & \frac{y_{ss}x_{s} - x_{s}y_{ss}}{x_{s}^{2}} \\ 0 & 0 & x_{s} & 0 \\ x_{\alpha_{1}} & y_{\alpha_{1}} & 0 & \left(\frac{y_{s}}{x_{s}}\right)_{\alpha_{1}} \\ x_{\alpha_{2}} & y_{\alpha_{3}} & 0 & \left(\frac{y_{s}}{x_{s}}\right)_{\alpha_{2}} \end{vmatrix} + \dots = - \begin{vmatrix} x_{s} & y_{s} & (y_{s}|x_{s})_{s} \\ x_{\alpha_{1}} & y_{\alpha_{1}} & (y_{s}|x_{s})_{\alpha_{1}} \\ x_{\alpha_{2}} & y_{\alpha_{2}} & (y_{s}|x_{s})_{\alpha_{2}} \end{vmatrix} \cdot x_{s} + \dots$$

where the omitted terms are of degree $\geqslant 1$ in s, t.

By (2) and (3), $J \neq 0$ near the origin. Accordingly

$$s, t, \alpha_1, \alpha_2 \to \operatorname{Re} x$$
, $\operatorname{Re} y$, $\operatorname{Im} x$, $\frac{\operatorname{Im} y}{\operatorname{Im} x}$

is one-one, if Im y/Im x is defined by continuity also for Im x=0; Im x=0 coincides with t=0 by (2). Now the map

$$\operatorname{Re} x$$
, $\operatorname{Re} y$, $\operatorname{Im} x$, $\frac{\operatorname{Im} y}{\operatorname{Im} x} \to \operatorname{Re} x$, $\operatorname{Re} y$, $\operatorname{Im} x$, $\operatorname{Im} y$

is one-one as long as $\operatorname{Im} x \neq 0$. Hence the part of an open neighborhood of the s, t, α_1, α_2 -origin for which $t \neq 0$ is in one-one correspondence with a certain open set of $\operatorname{Re} x$, $\operatorname{Re} y$, $\operatorname{Im} x$, $\operatorname{Im} y$ -space with $\operatorname{Im} x \neq 0$; and the Jacobian $\partial(x, y, \overline{x}, \overline{y})/\partial(\alpha_1, \alpha_2, s, t) \neq 0$ there.

Now consider for $t \neq 0$ the form

$$\omega = du \wedge dx \wedge dy \wedge d\bar{y} .$$

We have

$$\begin{split} \omega &= \frac{\partial u}{\partial \overline{x}} d\overline{x} \wedge dx \wedge dy \wedge d\overline{y} \\ &= \frac{\partial (u, x, y, \overline{y})}{\partial (\alpha_1, \alpha_2, s, t)} d\alpha_1 \wedge d\alpha_2 \wedge ds \wedge dt \\ &= \left(+ \frac{\partial (u, x, y)}{\partial (\alpha_1, \alpha_2, s)} \frac{\partial \overline{y}}{\partial t} - \frac{\partial (u, x, y)}{\partial (\alpha_1, \alpha_2, t)} \frac{\partial \overline{y}}{\partial s} + \frac{\partial (u, x, y)}{\partial (\alpha_1, s, t)} \frac{\partial \overline{y}}{\partial \alpha_2} - \frac{\partial (u, x, y)}{\partial (\alpha_2, s, t)} \frac{\partial \overline{y}}{\partial \alpha_1} \right) \\ &= 0 & d\alpha_1 \wedge d\alpha_2 \wedge ds \wedge dt \end{split}$$

since by assumption (1) holds and u, x, y are all holomorphic in s + it, i.e. satisfy $\partial u/\partial t = i(\partial u/\partial s), \ldots, \partial y/\partial t = i(\partial y/\partial s)$, and the first derivatives with respect to α_1, α_2 are also holomorphic in s + it. As $J \neq 0$ in $t \neq 0$ we conclude

$$\frac{\partial u}{\partial \overline{x}} = 0 \quad \text{for } t \neq 0.$$

Similarly, $\partial u/\partial \bar{y} = 0$ for $t \neq 0$. Hence u = f(x, y) in $t \neq 0$ with f holomorphic for $\operatorname{Im} x \neq 0$. As $\operatorname{Im} x \to 0$ we have $t \to 0$, $\operatorname{Im} y \to 0$ and u, x, y tend to their values for t = 0 uniformly on compact sets of α_1, α_2, s . This implies that f(x, y) with x, y real is the limit of f(x, y) as x, y tend from complex to real values. Moreover that part of the neighborhood of the origin of the x, y-space which is image of a neighborhood of the origin of α_1, α_2, s, t certainly contains the Cartesian product of

$$|\operatorname{Re} x| < \varepsilon$$
, $|\operatorname{Re} y| < \varepsilon$

with

$$0
eq |{
m Im}\,x| < arepsilon\,, \quad \left|rac{{
m Im}\,y}{{
m Im}\,x} - rac{y_s}{x_s}
ight| < arepsilon$$

with $\varepsilon > 0$ and small, i.e. the products of a square E of the Rex, Rey-plane with an open «cone» W of the Imx, Imy-plane (truncated by Im $x = \varepsilon$), vertex at (0,0), and with its negative, -W. Therefore we may apply the local version of the edge-of-the-wedge theorem [1] which tells that f(x,y) is holomorphic also for real x,y,y.

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2. – Theorem 1 contains the special case when $x = \alpha_1$, $y = \alpha_2$ for s = 0. We then have $u(\alpha_1, \alpha_2, 0) = f(\alpha_1, \alpha_2)$ with analytic f.

Note that (1) (with the aid of (2)) can be formulated thus: x, y, u are solutions of

$$\frac{\partial v}{\partial s} = A_1 \frac{\partial v}{\partial \alpha_1} + A_2 \frac{\partial v}{\partial \alpha_2}$$

with

$$A_1 = rac{\partial(x,y)}{\partial(s_1,lpha_2)} / rac{\partial(x,y)}{\partial(lpha_1,lpha_2)}, \qquad A_2 = rac{\partial(x,y)}{\partial(lpha_1,s)} / rac{\partial(x,y)}{\partial(lpha_1,lpha_2)}.$$

This suggests the following corollary of Theorem 1.

THEOREM 2. Let $A_1(\alpha_1, \alpha_2, s)$, $A_2(\alpha_1, \alpha_2, s)$ be real valued analytic functions of α_1 , α_2 , s, extensible holomorphically as functions of s+it, $|t| < t_0$. Let v be a C^1 -solution of (4) which can be extended to a C^1 -function of s+it, α_1 , α_2 , holomorphic in s+it for $|t| < t_0$. Then v is holomorphic in all three variables α_1 , α_2 , s, provided $A_1(\partial A_2/\partial s) - A_2(\partial A_1/\partial s) \neq 0$.

PROOF. There exist by Cauchy-Kovalewski two solutions x, y of (4) which reduce to $x = \alpha_1$, $y = \alpha_2$ for s = 0. We find for s = 0, if w.l.o.g., $A_1 = \frac{\partial x}{\partial s} \neq 0$,

$$\begin{split} \frac{\partial x}{\partial \alpha_1} &= 1 \;, \quad \frac{\partial x}{\partial \alpha_2} = 0 \;, \quad \frac{\partial y}{\partial \alpha_1} = 0 \;, \quad \frac{\partial y}{\partial \alpha_2} = 1 \;, \quad \frac{\partial x}{\partial s} = A_1 \;, \quad \frac{\partial y}{\partial s} = A_2 \;, \\ \frac{\partial^2 x}{\partial s^2} &= \frac{\partial A_1}{\partial s} + \sum_{2}^{1} A_1 \frac{\partial A_1}{\partial \alpha_1} \;, \quad \frac{\partial^2 y}{\partial s^2} = \frac{\partial A_2}{\partial s} + \sum_{1}^{2} A_1 \frac{\partial A_2}{\partial \alpha_1} \end{split}$$

so that (3) becomes for s=0

$$\begin{vmatrix} x_s & y_s & \left(\frac{y_s}{x_s}\right)_s \\ x_{\alpha_1} & y_{\alpha_1} & \left(\frac{y_s}{x_s}\right)_{\alpha_1} \end{vmatrix} = x_s^{-2} \begin{vmatrix} A_1 & A_2 & y_{ss}A_1 - x_{ss}A_2 \\ 1 & 0 & A_1(A_2)_{\alpha_1} - A_2(A_1)_{\alpha_1} \\ 0 & 1 & A_1(A_2)_{\alpha_2} - A_2(A_1)_{\alpha_2} \end{vmatrix} = \\ x_{\alpha_1} & y_{\alpha_2} & \left(\frac{y_s}{x_s}\right)_{\alpha_2} \end{vmatrix} \cdot = x_s^{-2} \left(A_1 \frac{\partial A_2}{\partial s} - A_2 \frac{\partial A_1}{\partial s}\right) \neq 0$$

so that Theorem 1 applies. Hence v is a holomorphic function of x, y which

in turn are analytic in α_1 , α_2 , s as Cauchy-Kowalevski solutions of (4). Thus v is holomorphic in α_1 , α_2 , s, q.e.d.

Dr. T. KAWAI has kindly communicated to the A. how to deduce Theorem 2 as a special case of a general analyticity Theorem to be found in [2].

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