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## A GENERALIZED MARKOV DECISION PROCESS (\*)

by Gary J. KOEHLER <sup>(1)</sup>

*Abstract. — In this paper we present a generalized Markov decision process that subsumes the traditional discounted, infinite horizon, finite state and action Markov decision process, Veinott's discounted decision processes, and Koehler's generalization of these two problem classes.*

*Résumé. — Nous présentons dans cet article un processus de Markov généralisé qui englobe le processus de décision markovien actualisé à l'horizon infini, avec état et action finis; les processus de décision actualisés de Veinott; et la généralisation de Koehler de ces deux classes de problèmes.*

### 1. INTRODUCTION

In this paper we explore the extension of results obtained in [2] to a broader class of problems. The author's motivation is as follows. Many practical large-scale linear programs in energy and food allocation modelling can be easily partitioned to the form

$$\left. \begin{array}{l} \text{Max } c'x \\ \text{S.T.} \\ Bx = b \\ Ex = d \\ x \geq 0 \end{array} \right\} \quad (1.1)$$

where  $b \geq 0$ ,  $B$  is essentially Leontief (to be defined later), and  $Bx = b$  accounts for most of the constraints. Programs having Leontief constraint sets can be solved without inversion [2] and procedures taking advantage of this fact in solving (1.1) are of interest. In this paper we explore the results obtained in [2] on Leontief Systems and extend these to use on essentially Leontief Systems.

In the interest of brevity we borrow heavily from [2] in notation and preliminary results.

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## 2. PROBLEM STATEMENT

Consider the problem

$$\left. \begin{array}{l} \text{Max } c'x \\ \text{S.T.} \\ Bx = b \\ x \geq 0 \end{array} \right\} \quad (2.1)$$

where  $B$  is an  $m \times k$  essentially Leontief matrix and  $b \geq 0$ . An essentially Leontief matrix is a pre-Leontief matrix [4]—a matrix having at most one positive element per column—where, additionally, there is an  $x \geq 0$  such that  $Ax > 0$ . We assume the following:

### Assumption A

Problem 2.1 has a bounded objective and the columns of  $B$  are scaled so that the positive elements of  $B$  are not greater than one.

Let  $A_i \subseteq \{1, 2, \dots, n\}$  for  $i = 1, \dots, m$  such that if  $B_{ij} > 0$  then  $j \in A_i$  and  $\bigcup_i A_i = \{1, 2, \dots, n\}$ . Note that each  $A_i \neq \emptyset$  since  $Bx > 0$  for some

$x \geq 0$ . Let  $\Delta = \prod_{i=1}^m A_i$ . For  $\delta \in \Delta$  let  $B^\delta$  be the corresponding submatrix of  $B$  and let  $Q^\delta = I - B^\delta$  and  $P_\delta = (Q^\delta)'$ . Here  $P_\delta \geq 0$ .

From [1,4] there is some  $\delta^* \in \Delta$  such that:

1.  $v^* = [(B^{\delta^*})']^{-1} c^{\delta^*}$  solves the dual to (2.1);
2.  $\rho(P_{\delta^*}) < 1$ , where  $\rho(P)$  is the spectral radius of the square matrix  $P$ .

Let

$$\mathcal{L}_\delta(v) = P_\delta v + c^\delta$$

and

$$\mathcal{L}(v) = \max_{\delta \in \Delta} \mathcal{L}_\delta(v).$$

Both operators are isotone. Define

$$F = \{v : v = \mathcal{L}(v)\} \quad \text{and} \quad C = \left\{v : \lim_{n \rightarrow \infty} \mathcal{L}^n(v) = v^*\right\}.$$

Note that  $v^* \in F$  and  $v^* \in C$ . Finally, denote the dual feasible set of (2.1) as

$$D = \{v : (I - P_\delta)v \geq c^\delta, \delta \in \Delta\}.$$

Consider the following four conditions:

1.  $P_\delta \geq 0, \quad \delta \in \Delta;$  (2.2)
2.  $\rho(P_\delta) < 1$  for all  $\delta \in \Delta;$
3.  $D \neq \emptyset;$
4.  $I - P_\delta$  has a positive diagonal for each  $\delta \in \Delta.$

These conditions hold for discounted (semi-) Markov decisions and the discounted processes of Veinott [3]. Under these conditions  $C = R^m$ . In Koehler [2] condition 2 was relaxed to yield

$$2. \rho(P_\delta) < 1 \text{ for some } \delta \in \Delta. \quad (2.3)$$

1, 3 and 4 as in (2.2).

Here  $C \neq R^m$  in general. In this paper we further relax (2.2) to

$$1, 2 \text{ and } 3 \text{ as in } (2.3). \quad (2.4)$$

Drop 4.

Some properties of  $\mathcal{L}(\cdot)$  and  $C$  which were discovered in [2] which also hold for (2.4) are summarized below. Refer to [2] for notation.

PROPOSITION 2.5.

1.  $\liminf_{n \rightarrow \infty} \mathcal{L}^n(v) \geq v^*$  for all  $v \in R^m$ .
2.  $L(C) \subseteq C$ .
3.  $C$  is convex.
4. If  $F = [v^*]$ , then  $L(D) \subseteq C$ . In addition, if for some  $d > 0$   $P_\delta d \leq d$  for all  $\delta \in \Delta$ , then  $C = R^m$ .
5. If  $\rho(P_\delta) \leq 1$  for all  $\delta \in \Delta$  and  $c^\delta \notin \text{range}(I - P_\delta)$  whenever  $\rho(P_\delta) = 1$ , then  $F = \{v^*\}$ .
6. Assume that  $C = R^m$ . Then for every  $\delta \in \Delta$ ,  $\rho(P_\delta) \leq 1$  and for  $\delta$  having  $\rho(P_\delta) = 1$  there exists no  $v \in R^m$  such that  $v \leq P_\delta v + c^\delta$ .

Notice that the isotonicity of  $\mathcal{L}(\cdot)$  and  $L(v^*) \subseteq C$  give an easily satisfied sufficient condition for picking a point,  $v^0$ , of  $C$ . That is, let  $v^0 = -Me$  where  $M \gg 0$  and  $e$  is an  $m$  vector of ones.

3. SPECTRAL PROPERTIES OF THE  $P_\delta$ 's AND GEOMETRIC PROPERTIES OF  $D$

In this section we extend almost all of the properties found in [2] which relate the spectral radii of the  $P_\delta$ 's to boundedness of  $D$  and the property that it has a non-empty interior. From [2] we have:

PROPOSITION 3.1: Consider the following properties of the  $\rho(P_\delta)$ 's and  $D$ :

- (a) For some  $d > 0$ ,  $P_\delta d \leq d$  for all  $\delta \in \Delta$ .
- (b)  $\rho(P_\delta) \leq 1$  for all  $\delta \in \Delta$ .
- (c)  $D$  is unbounded from above.
- (d) For some  $d \geq 0$ ,  $P_\delta d \leq d$  for all  $\delta \in \Delta$ .

Then (a)  $\rightarrow$  (b)  $\rightarrow$  (c)  $\Leftrightarrow$  (d).

In [2] it was shown, under the conditions given in (2.3), that if  $D$  has a non-empty interior then  $\rho(P_\delta) = 1$  implies  $c^\delta \notin \text{range}(I - P_\delta)$ . This is no longer the case under the conditions in (2.4). For example, let

$$B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$c' = (-2 \quad 2 \quad 0)$$

$D$  has a non-empty interior yet for  $\delta = (3,2)$  we have  $P_\delta = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$ ,  $\rho(P_\delta) = 1$  and  $c^\delta = \begin{pmatrix} 0 \\ 2 \end{pmatrix} \in \text{range}(I - P_\delta)$ .

The following results from [2] can be established under the conditions of (2.4).

THEOREM 3.2: Suppose for some  $d > 0$ ,  $P_\delta d \leq d$  for every  $\delta \in \Delta$  and if  $\rho(P_\delta) = 1$  then  $c^\delta \notin \text{range}(I - P_\delta)$ . Then  $D$  has a non-empty interior.

*Proof:* Suppose  $B_j \leq 0$ . Then  $B_j = e_i - (-B_j + e_i)$ . For some  $\delta$  the  $i$ -th row of  $P_\delta$  looks like  $(e_i - B_j)'$ . Thus  $(e_i - B_j)' d \leq d_i$  by the first part of our premise for some  $d > 0$ . Thus  $d_i - B_j' d \leq d_i$  or  $0 \leq B_j' d$ . However,  $B_j' d < 0$ .

Thus  $B_j \leq 0$  implies  $B_j = 0$ .

Let  $B_j = 0$  and  $\delta$  be a decision using  $\delta^*$  except in the state where  $B_j$  may be used. It is readily demonstrated that  $\rho(P_\delta) = 1$ . So  $c^\delta \notin \text{range}(I - P_\delta)$  implies that  $c_j < 0$  since otherwise  $v^*$  would give  $c^\delta$ .

Thus we may restrict our attention to just those columns of  $B$  having a positive element and proceed to use the proof of Theorem 4.3 in [2] to get the desired result.  $\square$

Notice that under the conditions of Theorem 3.2  $F = \{v^*\}$  [see Prop. 2.5, No. (5)].

#### 4. THE IRREDUCIBLE CASE

Refer to [2] for appropriate definitions. In this section we assume:

##### Assumption B

$B$  of problem (2.3) is not permutable to an essentially dynamic Leontief matrix.

Assumption B can be tested by discarding each non-positive column of  $B$  and using the procedures mentioned in [2] on the remaining matrix.

LEMMA 4.1: *If Assumption B holds,  $d \geq 0$  and  $P_\delta d \leq d$  for every  $\delta \in \Delta$ , then  $d > 0$  and  $B_j \leq 0$  implies  $B_j = 0$ .*

*Proof:* Without loss of generality we may partition  $B$  as  $B = (B_1, B_2)$  with  $B_2 \leq 0$  and  $B_1$  Leontief. Then  $d'(B_1, B_2) \geq 0$  gives that  $d'B_2 = 0$ . From [2] (Lemma 5.1)  $d'B_1 \geq 0$  and  $B_1$  not dynamic Leontief gives that  $d > 0$ . Hence,  $d'B_2 = 0$  implies  $B_2 = 0$ .  $\square$

From the Proposition 3.1 and Lemma 4.1 we get the following.

PROPOSITION 4.2: *If Assumption B holds, then the following are equivalent:*

- (a)  $D$  is unbounded from above;
- (b)  $P_\delta d \leq d$  for some  $d > 0$ ;
- (c)  $\rho(P_\delta) \leq 1$  for all  $\delta \in \Delta$ .

Finally, pulling together several of the above results, we get:

THEOREM 4.3: *If Assumption B holds, then consider the following:*

- (a)  $C = R^m$ ;
- (b)  $\rho(P_\delta) \leq 1$  for all  $\delta \in \Delta$  and  $c^\delta \notin \text{range}(I - P_\delta)$  whenever  $\rho(P_\delta) = 1$ ;
- (c)  $D$  is unbounded from above and has a non-empty interior.

Then (a)  $\Leftrightarrow$  (b)  $\rightarrow$  (c).

*Proof:* (a)  $\rightarrow$  (b): This follows from Proposition 2.5 part (6).

(b)  $\rightarrow$  (a): From Proposition 2.5 part (5) we have  $F = \{v^*\}$ . From Proposition 3.1 and Lemma 4.1 there is a  $d > 0$  such that  $P_\delta d \leq d$  for all  $\delta \in \Delta$ . Thus from Proposition 2.5 part (4) we have that  $C = R^m$ .

(b)  $\rightarrow$  (c): As in the previous part of the proof we have some  $d > 0$  such that  $P_\delta d \leq d$  for all  $\delta \in \Delta$ . By Proposition 3.1  $D$  is unbounded from above. The rest follows from Proposition 4.2 and Theorem 3.2.  $\square$

We cannot complete the implication in this theorem as can be seen by the following example. Let

$$B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

$$c' = (1 \quad 1 \quad 0)$$

Here  $D$  has a non-empty interior and  $D$  has a positive direction of recession ( $d' = (1,1)$ ) but

$$\left\{ \begin{pmatrix} 1 \\ \alpha \end{pmatrix}, \begin{pmatrix} \alpha \\ 1 \end{pmatrix} : \alpha \geq 1 \right\} \subseteq F,$$

which implies  $C \neq R^m$ .

Theorem 4.3 can be relaxed to complete the implications. This is done below.

**THEOREM 4.4:** *If Assumption B holds and if  $B_j = 0$  implies that  $c_j < 0$ , then the conditions (a), (b), and (c) of Theorem 4.3 are equivalent.*

*Proof:* From Theorem 4.3 we have (a)  $\Leftrightarrow$  (b)  $\rightarrow$  (c).

(c)  $\rightarrow$  (a): If  $D$  is unbounded from above then from Proposition 3.1 and Lemma 4.1 there is a  $d > 0$  such that  $P_\delta d \leq d$  for all  $\delta \in \Delta$  and  $B_j \leq 0$  implies  $B_j = 0$ . By Proposition 4.2,  $\rho(P_\delta) \leq 1$  for all  $\delta \in \Delta$ . Suppose  $\rho(P_\delta) = 1$  for some  $\delta \in \Delta$ . From Theorem 4.3 of [2]  $c^\delta \notin \text{range}(I - P_\delta)$  if some row has no positive element since then this row is a vector of zeroes and the corresponding element of  $c^\delta$  is negative by assumption. Thus  $c^\delta \notin \text{range}(I - P_\delta)$ . The rest follows from Proposition 2.5 parts (5) and (4).  $\square$

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