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A Principle Involving the Variation of the Metric Tensor in a Stationary Space-Time of General Relativity.

LUCIANO BATTALIA (*)

SUMMARY - Within general relativity we introduce a variational principle, involving the variation of the metric tensor in a stationary spacetime, and concerning the equilibrium of an elastic body capable of couple stresses but not of heat conduction.

1. Introduction.

In this work we consider an elastic body C capable of couple stresses but not of heat conduction and we assume absence of electromagnetic phenomena.

Basing ourselves on a certain variational theorem involving the variation of the space-time metric, firstly formulated by Taub in [4] and extended by Schöpf and Bressan to the non-polar and polar cases respectively — cf. [3] and [2]—, we introduce a variational principle concerning the rest of a body C of the type above.

More in detail we prove that if C_3 is a certain 3-dimensional region of a stationary spacetime S_4 , the equilibrium of the body C , in the stationary frame (x) , is physically possible if and only if the functional

$$J = \int_{C_3} (R + 16\pi hc^{-4} \varrho) \sqrt{-g} dC_3,$$

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is stationary with respect to certain variations of the metric, where R is the bicontracted Riemann tensor, h Cavendish's constant, c the velocity of light in vacuum and ρ the proper actual density of matter energy.

This theorem is an analogue of the relativistic variational principle proved in [1].

2. Preliminaries.

We follow the theory of continuous media in general relativity constructed by Bressan, cf. [2] (cf. also [1] and the references therein).

Let C be a continuous body and \mathcal{F} a process physically possible for C in a space-time S_4 of general relativity. We shall consider only regular motions for C , e.g. without slidings and splittings; hence C can be regarded as a collection of material points.

By (x) we denote an admissible frame; by $g_{\alpha\beta} = g_{\alpha\beta}(x^\alpha)$ ⁽¹⁾ the metric tensor corresponding to \mathcal{F} ; by $u^\alpha[A^\alpha]$ the four velocity [acceleration] of C at the event point \mathcal{E} .

Then we consider a particular process \mathcal{F}^* physically possible for the universe containing C , the world-tube W_C^* of C in \mathcal{F}^* and an admissible frame (y) . We call S_3^* the intersection of W_C^* with the hypersurface $y^0 = 0$. We use the co-ordinate y^L of the intersection of S_3^* with the world line of the point P^* of C as L -th material co-ordinate ⁽²⁾.

We represent the arbitrary (regular) motion of C in the system of co-ordinates (x) by means of the functions

$$(1) \quad x^\alpha = \hat{x}^\alpha(t, y^1, y^2, y^3),$$

where t is an arbitrary time parameter.

If $T^{::}$ is a double tensor field associated to the event point x^α and the material point y^L , we shall denote by $T^{::},_e$ the ordinary partial derivative, by $T^{::},_e$ the covariant derivative and by $T^{::}|_M$ the lagrangian spatial derivative based on the map (1) and introduced by Bressan.

We are interested in an elastic body C capable of couple stress but not of heat conduction and we shall always assume that electromagnetic phenomena are absent.

⁽¹⁾ Greek and Latin indices run over 0, 1, 2, 3 and 1, 2, 3 respectively.

⁽²⁾ Capital and lower case letters represent material and space-time indices respectively.

We call ϱ the proper actual density of total internal energy, $X^{\alpha\beta}$ the stress tensor, $m^{\alpha\beta\gamma}$ the couple stress tensor and we shall assume as total energy tensor ⁽³⁾

$$(2) \quad \mathfrak{U}^{\alpha\beta} = \varrho u^\alpha u^\beta + X^{(\alpha\beta)} + 2m^{(\alpha\lambda\beta)}/_\lambda + 2v^{(\alpha}u^{\beta)},$$

where

$$v^\alpha = 2m^{(\alpha\varrho\sigma)}u_{\varrho/\sigma}.$$

This assumption is proved to be physically acceptable in the case considered here (cf. [2]).

3. A theorem concerning the variation of the metric tensor in S_4 .

We always consider a body C of the type specified above and we suppose assigned in S_4 the motion (1) of C and the metric tensor $g_{\alpha\beta} = g_{\alpha\beta}(x)$ ⁽⁴⁾.

We take into account a bounded 4-dimensional domain C_4 of S_4 , where the motion of C is of class $C^{(2)}$ and we call $\mathcal{F}C_4$ its boundary oriented outwards. Furthermore let $\delta g_{\alpha\beta}$ be an arbitrary variation of $g_{\alpha\beta}$, of class $C^{(2)}$ in C_4 and such that

$$(3) \quad \delta g_{\alpha\beta} = 0 = \delta g_{\alpha\beta,\gamma} \quad \text{on } \mathcal{F}C_4.$$

Consider the functional

$$(4) \quad I = \int_{C_4} (R + 16\pi\hbar c^{-4}\varrho) \sqrt{-g} dC_4.$$

In [2] it is proved that for every variation $\delta g_{\alpha\beta}$ of the aforementioned type we have

$$(5) \quad \delta \int_{C_4} (R + 16\pi\hbar c^{-4}\varrho) \sqrt{-g} dC_4 = - \int_{C_4} (A^{\alpha\beta} + 8\pi\hbar c^{-4}\mathfrak{U}^{\alpha\beta}) \delta g_{\alpha\beta} \sqrt{-g} dC_4.$$

⁽³⁾ We use the notations $2T_{(\alpha\beta)} = T_{\alpha\beta} + T_{\beta\alpha}$; $2T_{[\alpha\beta]} = T_{\alpha\beta} - T_{\beta\alpha}$.

⁽⁴⁾ For the constitutive equations of an elastic body C capable of couple stresses in the absence of heat conduction an electromagnetic phenomena see [1].

4. A variational principle concerning equilibrium in a stationary frame.

Let now S_4 be stationary and (x) a stationary frame. The metric tensor, that we always consider as assigned in S_4 , satisfies

$$(6) \quad g_{\alpha\beta,0} = 0 .$$

We call C_3 the intersection of the world tube W_C of C with the hypersurface $x_0 = 0$.

We identify the arbitrary parameter in the equations (1) of the motion with x^0 and denote by $x^r = \chi^r(y^L)$ the configuration of C in C_3 . We consider the following motion of C :

$$(7) \quad \begin{cases} x^0 = t \\ x^r = x^r(t, y^L) = \chi^r(y^L) , \end{cases}$$

hence C is in equilibrium with respect to (x) .

Consider an arbitrary variation $\delta_3 g_{\alpha\beta} = \delta_3 g_{\alpha\beta}(x^1, x^2, x^3)$ of $g_{\alpha\beta}$ on C_3 , of class $C^{(2)}$ and such that

$$(8) \quad \delta_3 g_{\alpha\beta} = 0 = \delta_3 g_{\alpha\beta,\gamma} \quad \text{on } \mathcal{F}C_3 \quad (a, \beta = 0, 1, 2, 3) .$$

Consider the functional

$$(9) \quad J = \int_{C_3} (R + 16\pi h c^{-4} \rho) \sqrt{-g} dC_3 .$$

We shall prove that the rest (7) of the body C , with respect to the stationary frame (x) , is physically possible if and only if

$$(10) \quad \delta_3 J = 0$$

for every variation of $g_{\alpha\beta}$ of the aforementioned type.

Let a be a real positive number. We consider the following subsets of W_C

$$\begin{aligned} C_4 &= \{P \in W_C \mid |x^0| \leq a + 1\} , & C_4^a &= \{P \in W_C \mid |x^0| \leq a\} , \\ C_4^+ &= \{P \in W_C \mid a \leq x^0 \leq a + 1\} , & C_4^- &= \{P \in W_C \mid -(a + 1) \leq x^0 \leq -a\} , \end{aligned}$$

where by x^0 we mean the co-ordinates of the point P of S_4 .

Let then $\varphi(\xi)$ be an arbitrary function of the real variable ξ , of class $C^{(2)}$ in $[0, 1]$ and such that

$$(11) \quad \begin{cases} \varphi(1) = \varphi'(1) = \varphi'(0) = \varphi''(0) = 0 \\ \varphi(0) = 1 \\ \int_0^1 \varphi(\xi) d\xi = 0 . \end{cases}$$

Consider the following variation $\delta g_{\alpha\beta}(x_0, x^1, x^2, x^3)$ in C_4

$$(12) \quad \delta g_{\alpha\beta} = \begin{cases} \delta_3 g_{\alpha\beta}(x^1, x^2, x^3) & \text{in } C_4^a \\ \varphi(x_0 - a) \delta_3 g_{\alpha\beta} & \text{in } C_4^+ \\ \varphi(-x_0 - a) \delta_3 g_{\alpha\beta} & \text{in } C_4^- . \end{cases}$$

On the basis of (11) this variation is of class $C^{(2)}$ in C_4 and satisfies the conditions

$$(13) \quad \delta g_{\alpha\beta} = 0 = \delta g_{\alpha\beta,\gamma} \quad \text{on } \mathcal{F}C_4 .$$

Hence the variational theorem enounced in the previous paragraph can be applied:

$$(14) \quad \delta \int_{C_4} (R + 16\pi hc^{-4} \rho) \sqrt{-g} dC_4 = - \int_{C_4} (A^{\alpha\beta} + 8\pi hc^{-4} \mathcal{U}^{\alpha\beta}) \delta g_{\alpha\beta} \sqrt{-g} dC_4 .$$

The stationarity of spacetime and the equations (7) of equilibrium imply that $g_{\alpha\beta}$, R , $\mathcal{U}_{\alpha\beta,\rho}$ do not depend on x^0 .

We have

$$\begin{aligned} \delta \int_{C_4^+} R \sqrt{-g} dC_4 &= \int_{C_4^+} \frac{\partial R \sqrt{-g}}{\partial g_{\alpha\beta}} \delta g_{\alpha\beta} dC_4 = \int_{C_4^+} \frac{\partial R \sqrt{-g}}{\partial g_{\alpha\beta}} \varphi(x^0 - a) \delta_3 g_{\alpha\beta} dC_4 = \\ &= \int_{C_4^+} \frac{\partial R \sqrt{-g}}{\partial g_{\alpha\beta}} \delta_3 g_{\alpha\beta} dC_3 \int_a^{a+1} \varphi(x^0 - a) dx^0 = 0 , \end{aligned}$$

and analogously

$$\delta \int_{C_4^+} \varrho \sqrt{-g} dC_4 = 0 .$$

Furthermore in the same way we prove that

$$\delta \int_{C_4^-} R \sqrt{-g} dC_4 = 0 = \delta \int_{C_4^-} \varrho \sqrt{-g} dC_4 .$$

Hence

$$(15) \quad \delta \int_{C_4^+} (R + 16\pi\hbar c^{-4} \varrho) \sqrt{-g} dC_4 = 0 = \delta \int_{C_4^-} (R + 16\pi\hbar c^{-4} \varrho) \sqrt{-g} dC_4 .$$

Furthermore

$$(16) \quad \int_{C_4^a} (R + 16\pi\hbar c^{-4} \varrho) \sqrt{-g} dC_4 = \\ = \int_{-a}^a dx^0 \int_{C_3} (R + 16\pi\hbar c^{-4} \varrho) \sqrt{-g} dC_3 = 2a \int_{C_3} (R + 16\pi\hbar c^{-4} \varrho) \sqrt{-g} dC_3 .$$

From (15) and (16) we have

$$(17) \quad \delta \int_{C_4} (R + 16\pi\hbar c^{-4} \varrho) \sqrt{-g} dC_4 = 2a \delta \int_{C_3} (R + 16\pi\hbar c^{-4} \varrho) \sqrt{-g} dC_3$$

for the variation $\delta g_{\alpha\beta}$ and $\delta_3 g_{\alpha\beta}$ above.

We also have

$$(18) \quad \int_{C_4^+} (A^{\alpha\beta} + 8\pi\hbar c^{-4} \mathcal{U}^{\alpha\beta}) \delta g_{\alpha\beta} \sqrt{-g} dC_4 = \\ = \int_{C_4^+} (A^{\alpha\beta} + 8\pi\hbar c^{-4} \mathcal{U}^{\alpha\beta}) \varphi(x^0 - a) \delta_3 g_{\alpha\beta} \sqrt{-g} dC_4 = \\ = \int_{C_3} (A^{\alpha\beta} + 8\pi\hbar c^{-4} \mathcal{U}^{\alpha\beta}) \delta_3 g_{\alpha\beta} \sqrt{-g} dC_3 \int_a^{a+1} \varphi(x^0 - a) dx^0 = 0 .$$

and analogously

$$(19) \quad \int_{C_4^-} (A^{\alpha\beta} + 8\pi\hbar c^{-4} \mathcal{U}^{\alpha\beta}) \delta g_{\alpha\beta} \sqrt{-g} dC_4 = 0 .$$

Furthermore

$$\begin{aligned}
 (20) \quad \int_{C_4^a} (A^{\alpha\beta} + 8\pi\hbar c^{-4} \mathcal{U}^{\alpha\beta}) \delta g_{\alpha\beta} \sqrt{-g} dC_4 &= \\
 &= \int_{C_3} (A^{\alpha\beta} + 8\pi\hbar c^{-4} \mathcal{U}^{\alpha\beta}) \delta_3 g_{\alpha\beta} \sqrt{-g} dC_3 \int_{-a}^a dx^0 = \\
 &= 2a \int_{C_3} (A^{\alpha\beta} + 8\pi\hbar c^{-4} \mathcal{U}^{\alpha\beta}) \delta_3 g_{\alpha\beta} \sqrt{-g} dC_3 .
 \end{aligned}$$

From (14), (17), (18), (19), (20) we deduce

$$(21) \quad \delta_3 \int_{C_3} (R + 16\pi\hbar c^{-4} \varrho) \sqrt{-g} dC_3 = - \int_{C_3} (A^{\alpha\beta} + 8\pi\hbar c^{-4} \mathcal{U}^{\alpha\beta}) \delta_3 g_{\alpha\beta} \sqrt{-g} dC_3$$

for the variations $\delta_3 g_{\alpha\beta}$ specified above.

From (21) it follows that the variational condition $\delta_3 J = 0$ is equivalent to the validity, in C_3 , of the gravitational equations for C : $A^{\alpha\beta} + 8\pi\hbar c^{-4} \mathcal{U}^{\alpha\beta} = 0$ ($\alpha, \beta = 0, 1, 2, 3$). If we remember that $\varrho, R, A^{\alpha\beta}, \mathcal{U}^{\alpha\beta}$ do not depend on x^0 , we can conclude that the variational condition $\delta_3 J = 0$ is equivalent to the validity of the gravitational equations for C in the whole world tube W_C . This proves the theorem.

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